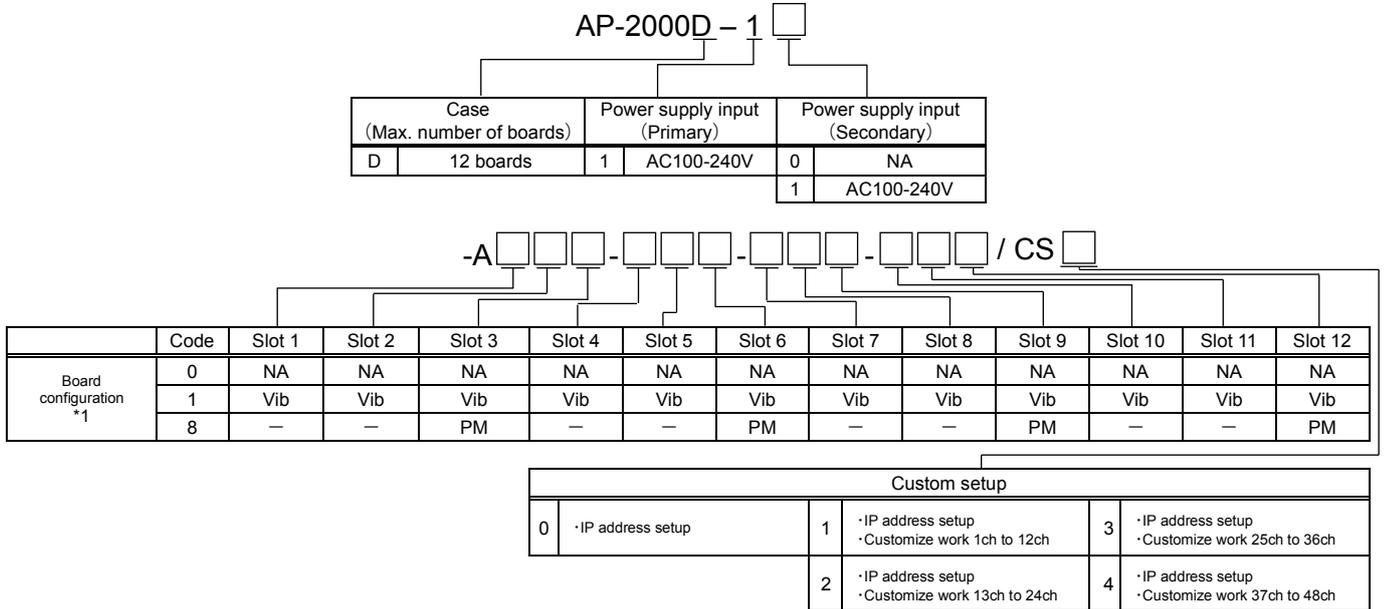
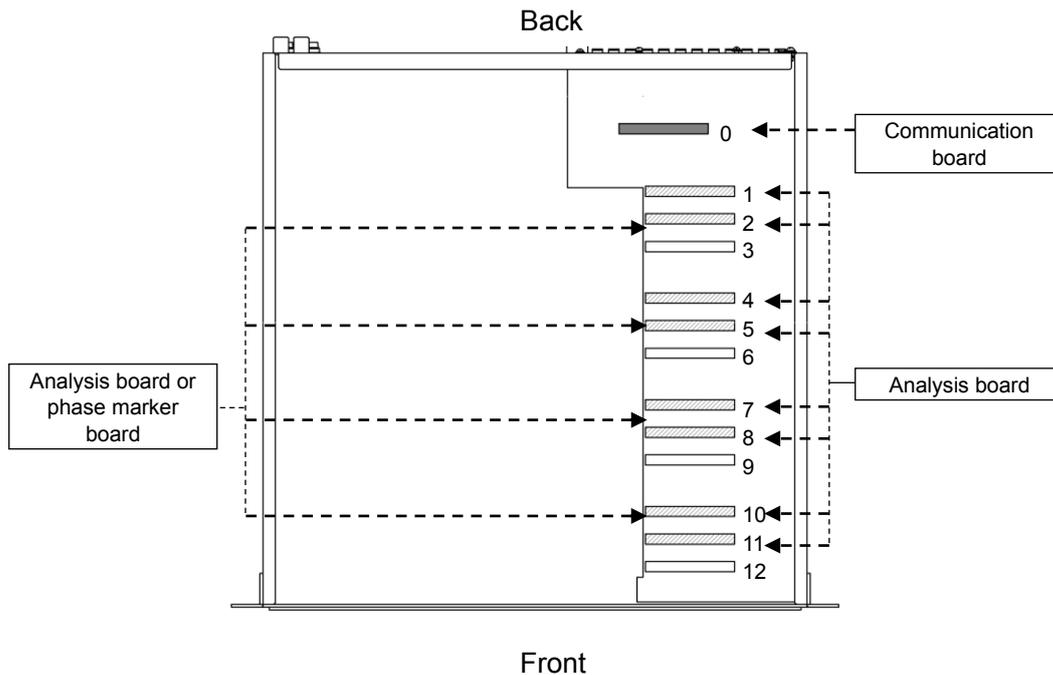


Model Code / Additional Spec. Code (Specify only when additional spec. is required.)



- *1 The maximum number of input channels on an analysis board (vibration/process signal input) or a phase marker board is 4.
- NA: No board is installed in this slot. (Enter "0" to specify vacant slot.)
- Vib: Analysis board (vibration/process signal input) is installed in this slot. (Enter "1" to specify.)
- PM: Phase marker board is installed in this slot. (Enter "8" to specify.)
- About Phase marker board implementation
- A phase marker board cannot be installed in slot 3 if slots 1 and 2 are not installed.
 - A phase marker board cannot be installed in slot 6 if slots 4 and 5 are not installed.
 - A phase marker board cannot be installed in slot 9 if slots 7 and 8 are not installed.
- : This slot does not support phase marker board.



Specifications

INPUT

ANALYSIS BOARD (VIBRATION SIGNAL INPUT)²

- Number of inputs : 4 channels
- Installation : 12 boards max. ^{*3}
- Input voltage range : -25 V to +25 V
(Accuracy guaranteed : -20 V to +20 V)
(vibration signal input)
1 V to 5 V, 0 V to 5 V, 0 V to 10 V
(process signal input)^{*4}
- Input impedance : 50 kΩ (approx.)
- Signal input connector (40 pin)
- Matching plug : N361J040AU (Otax)
- Matching hood : N360C040B (Otax)
- or
- Matching plug and hood : 1473381-1 (TE)

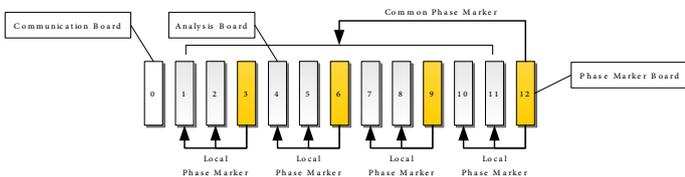
- ^{*2} By changing the setting, it can enter the mode to measure process (voltage) signals.
- ^{*3} Total inputs and number of boards installed
Total inputs (vibration) = Number of analysis boards X 4
Note:
Number of analysis boards + Number of phase marker boards ≤ 12
- ^{*4} When you are using current input (4 to 20 mA), use a reference resistor to convert it to voltage before inputting.
- ^{*5} Always disable OK alarm when using integrator in critical mode.

PHASE MARKER BOARD (PHASE MARKER SIGNAL INPUT)

- Number of inputs : 4 channels
- Installation : 4 boards max. ^{*6}
- Input voltage range : -25 V to +25 V
- Min. pulse width : 50μsec
- Trigger mode : Auto/Manual
- Input impedance : 50 kΩ (approx.)
- Practical rotation speed range : 60 rpm to 60,000 rpm ^{*7}
- Signal input connector (40 pin)
- Matching plug : N361J040AU (Otax)
- Matching hood : N360C040B (Otax)
- or
- Matching plug and hood : 1473381-1 (TE)

^{*6} Slot description

| Slots for phase marker boards | Slots to which the phase marker signals can be allocated |
|-------------------------------|--|
| 3 | 1, 2 |
| 6 | 4, 5 |
| 9 | 7, 8 |
| 12 | 1 to 11 |



- ^{*7} Transient can be measured up to 15,000 rpm.
- As this input circuit is not single-ended type, isolation between the channels is not provided.

OUTPUT

- Transducer power supply :
Piezoelectric transducer : +24VDC/4mA (constant current)

SYNCHRONOUS WAVEFORM DATA ACQUISITION

- Number of FFT lines : 400/800/1600 lines
- Number of sampling : 32/64/128 samples per revolution
- Sampling frequency : 51.2 kHz (max.)
- Data collection interval : 10 seconds (min.)

ASYNCHRONOUS WAVEFORM DATA ACQUISITION

- Number of FFT lines : 400/800/1600 lines
- Sampling frequency : 51.2 kHz (max.)
- Data collection interval : 10 seconds (min.)

TREND DATA ACQUISITION

- Item (vibration signal input) : Please refer to the below.
- Item (process signal input) ^{*8} : Measurement value
- Collection interval : 1 second (min. under normal condition),
or 0.1 second (for 20 seconds before alarm, for 10 seconds after alarm under high-speed acquisition mode)

- ^{*8} Under process signal measurement mode, the data is processed by a moving average of 0.1 sec, which is equivalent to frequency response of 5 Hz (-3 dB).

ANALYSIS MODE

Each analysis board can be set to "Critical" mode or "BOP" mode, depending on the application. Available data varies depending on the mode.

| | Critical mode | BOP mode |
|-------------------------------|--|---|
| Application | For analysis of transient operation of large rotating machinery. | For analysis of rated rotation of balance of plant equipment. |
| Phase Marker | Required for synchronous sampling of input signal waveform. | Not required. |
| Trend data calculation method | Calculated from synchronous waveform. | Calculated from asynchronous waveform. |
| Available trend data. | Rotor speed GAP Amplitude (Overall, 0.5X, 1X, 2X, Not-1X, nX1 to nX4 ⁹ , fX1, fX2 ¹⁰ , S _{(p-p) max}) Phase (0.5X, 1X, 2X, nX1 to nX4 ^{9,11}) | Rotor speed ¹² GAP Amplitude (Overall, 0.5X, 1X, 2X, Not-1X, nX1 to nX4 ⁹ , fX1, fX2 ¹⁰) |
| Available waveform data | synchronous waveform, asynchronous waveform | asynchronous waveform |

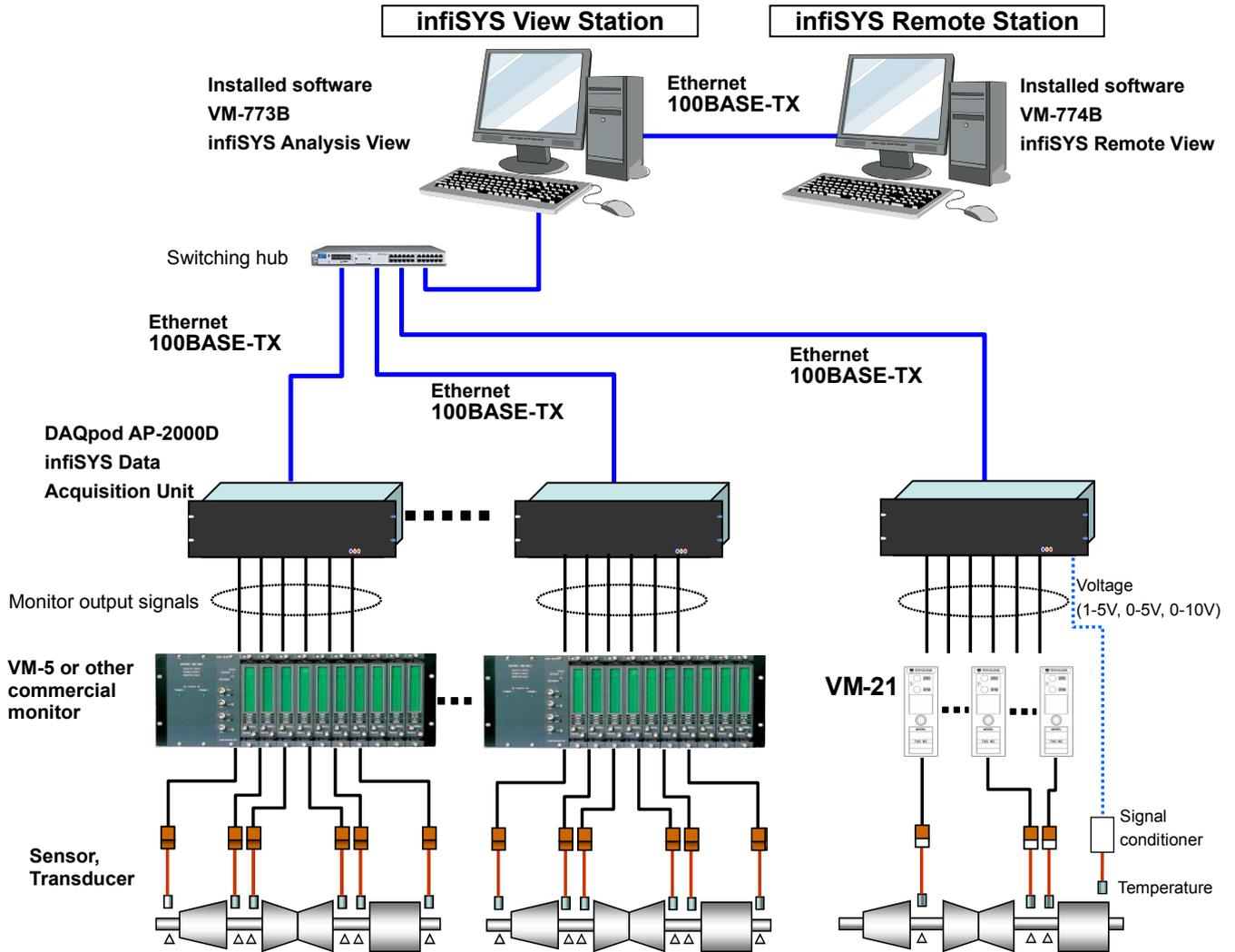
- ^{*9} Vibration amplitude and phase angle at n times rotation synchronous frequency. (n = 0.01 to 10.00 in 0.01 increments)
- ^{*10} Vibration amplitude at specified frequency component (f). (f = 0.01 to 20,000.00 Hz in 0.01 Hz increments)
- ^{*11} Phase mark is available only during displacement vibration measurement.
- ^{*12} Rotor speed is provided only when phase mark input is available.

ANALYSIS ACCURACY

- Vibration amplitude accuracy : Overall, 0.5X, 1X, 2X, nX(n=0.01 to 10.00), Not-1X : ±3% Max. of F.S. at 25°C
±5% Max. of F.S. at 0°C to 65°C
(for machine speed less than 30,000 r/min)
- S_{(p-p) max} : ±5% Max. of F.S. at 25°C
±7% Max. of F.S. at 0°C to 65°C
- Phase accuracy : 0.5X, 1X, 2X : ±3 deg of rdg. at 25°C
±6 deg of rdg. at 0°C to 65°C
- Process signal accuracy ^{*13} : ± 1% of F.S. at 25°C
± 2% of F.S. at 0°C~65°C

- ^{*13} With current input, the accuracy of the standard resistor is not included.

System Configuration



OTHERS
