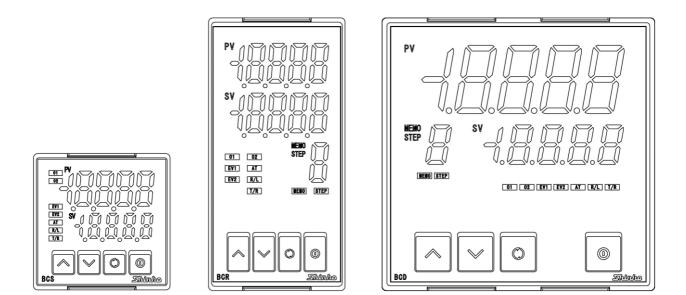
# DIGITAL INDICATING CONTROLLER BCx2 INSTRUCTION MANUAL





## Preface

Thank you for purchasing our digital indicating controller BCx2. This manual contains instructions for the mounting, functions, operations and notes when operating the BCx2. To prevent accidents arising from the misuse of this controller, please ensure the operator receives this manual.

Abbreviation	Term
PV	Process variable
SV	Desired value
MV	Manipulated variable
DV	Deviation
OUT1	Control output OUT1
OUT2	Control output OUT2
AT	Auto-tuning

### Abbreviations used in this manual

### Characters used in this manual

Indication	-{	Ω	1	Ē	ī,	Ч	5	5	7	8	9	Ľ	F
Number, °C/°F	-1	0	1	2	3	4	5	6	7	8	9	°C	°F
Indication	R	Ь	Ē	ď	E	F	5	Н	- {	1	F	Ľ	Ē
Alphabet	А	В	С	D	Ш	F	G	Н	I	J	к	L	М
Indication	п	Ø	Ρ	9	r	5	[	Ц	Н	Ļ.	U i	Ч	111
Alphabet	Ν	0	Ρ	Q	R	S	Т	U	V	W	Х	Y	Ζ

### Notes

- This instrument should be used in accordance with the specifications described in the manual. If it is not used according to the specifications, it may malfunction or cause a fire.
- Be sure to follow the warnings, cautions and notices. If they are not observed, serious injury or malfunction may occur.
- The contents of this instruction manual are subject to change without notice.
- Care has been taken to ensure that the contents of this instruction manual are correct, but if there are any doubts, mistakes or questions, please inform our sales department.
- Measures must be taken to ensure that the operator cannot touch power terminals or other high voltage sections.
- Any unauthorized transfer or copying of this document, in part or in whole, is prohibited.
- Shinko Technos Co., Ltd. is not liable for any damage or secondary damage(s) incurred as a result of using this product, including any indirect damage.

## Safety Precautions (Be sure to read these precautions before using our products.)

The safety precautions are classified into categories: "Warning" and "Caution". Depending on circumstances, procedures indicated by  $\triangle$  Caution may cause serious results, so be sure to follow the directions for usage.



Procedures which may lead to dangerous conditions and cause death or serious injury, if not carried out properly.

# ▲ Caution

Procedures which may lead to dangerous conditions and cause superficial to medium injury or physical damage or may degrade or damage the product, if not carried out properly.

# \land Warning

- To prevent an electrical shock or fire, only Shinko or other qualified service personnel may handle the inner assembly.
- To prevent an electrical shock, fire or damage to the instrument, parts replacement may only be undertaken by Shinko or other qualified service personnel.

# 

- To ensure safe and correct use, thoroughly read and understand this manual before using this instrument.
- This instrument is intended to be used for industrial machinery, machine tools and measuring equipment. Verify correct usage after purpose-of-use consultation with our agency or main office. (Never use this instrument for medical purposes with which human lives are involved.)
- External protection devices such as protective equipment against excessive temperature rise, etc. must be installed, as malfunction of this product could result in serious damage to the system or injury to personnel. Proper periodic maintenance is also required.
- This instrument must be used under the conditions and environment described in this manual. Shinko Technos Co., Ltd. does not accept liability for any injury, loss of life or damage occurring due to the instrument being used under conditions not otherwise stated in this manual.

### Caution with respect to Export Trade Control Ordinance

To avoid this instrument from being used as a component in, or as being utilized in the manufacture of weapons of mass destruction (i.e. military applications, military equipment, etc.), please investigate the end users and the final use of this instrument. In the case of resale, ensure that this instrument is not illegally exported.

## 1. Installation Precautions

## 🗥 Caution

This instrument is intended to be used under the following environmental conditions (IEC61010-1): Overvoltage category II, Pollution degree 2

Ensure the mounting location corresponds to the following conditions:

A minimum of dust, and an absence of corrosive gases

- No flammable, explosive gases
- No mechanical vibrations or shocks
- No exposure to direct sunlight, an ambient temperature of -10 to 55<sup>°</sup>C (14 to 131<sup>°</sup>F) that does not change rapidly, and no icing
- An ambient non-condensing humidity of 35 to 85%RH
- No large capacity electromagnetic switches or cables through which large current is flowing
- No water, oil or chemicals or where the vapors of these substances can come into direct contact with the unit
- Take note that the ambient temperature of this unit not the ambient temperature of the control panel must not exceed 55°C (131°F) if mounted through the face of a control panel, otherwise the life of electronic components (especially electrolytic capacitors) may be shortened.
- Note Avoid setting this instrument directly on or near flammable material even though the case of this instrument is made of flame-resistant resin.

# 2. Wiring Precautions

## ▲ Caution

- Do not leave wire remnants in the instrument, as they could cause a fire or malfunction.
- Use the solderless terminal with an insulation sleeve in which the M3 screw fits when wiring the instrument.
- The terminal block of this instrument is designed to be wired from the left side. The lead wire must be inserted from the left side of the terminal, and fastened with the terminal screw.
- Tighten the terminal screw using the specified torque. If excessive force is applied to the screw when tightening, the terminal screw or case may be damaged.
- Do not pull or bend the lead wire on the terminal side when wiring or after wiring, as it could cause malfunction.
- When using a terminal cover for the BCS2, pass terminal wires numbered 7 to 12 into the holes of the terminal cover.

• This instrument does not have a built-in power switch, circuit breaker and fuse. It is necessary to install a-power switch, circuit breaker and fuse near the controller. (Recommended fuse: Time-lag fuse, rated voltage 250 V AC, rated current 2 A)

- For a 24 V AC/DC power source, do not confuse polarity when using direct current (DC).
- Do not apply a commercial power source to the sensor which is connected to the input terminal nor allow the power source to come into contact with the sensor.
- Use a thermocouple and compensating lead wire according to the sensor input specifications of this controller.
- Use the 3-wire RTD according to the sensor input specifications of this controller.
- For DC voltage input, (+) side input terminal number of 0 to 5 V DC, 1 to 5 V DC, 0 to 10 V DC differs from that of 0 to 1 V DC.

Model	Terminal Number	
BCS2	<sup>(9)</sup> : (+) side of 0 to 5 V DC, 1 to 5 V DC, 0 to 10 V DC	
	(10): (+) side of 0 to 1 V DC	
BCR2, BCD2	<sup>(21)</sup> : (+) side of 0 to 5 V DC, 1 to 5 V DC, 0 to 10 V DC	
	<sup>22</sup> : (+) side of 0 to 1 V DC	

• When using a relay contact output type, externally use a relay according to the capacity of the load to protect the built-in relay contact.

• When wiring, keep input wires (thermocouple, RTD, etc.) away from AC sources or load wires.

## 3. Operation and Maintenance Precautions

## **Caution**

- It is recommended that AT be performed on the trial run.
- Do not touch live terminals. This may cause electrical shock or problems in operation.
- Turn the power supply to the instrument OFF when retightening the terminal or cleaning. Working on or touching the terminal with the power switched ON may result in severe injury or death due to electrical shock.
- Use a soft, dry cloth when cleaning the instrument.
   (Alcohol based substances may tarnish or deface the unit.)
- As the display section is vulnerable, do not strike or scratch it with a hard object or put pressure on it.

### Contents

### Page

1. Model	Ũ
1.1 Model	7
1.2 How to Read the Model Label	8
2. Names and Functions of Sections	9
3. Mounting to the Control Panel	
3.1 External Dimensions (Scale: mm)	12
3.2 Panel Cutout (Scale: mm)	
3.3 CT (Current Transformer) External Dimensions (Scale: mm)	
3.4 Mounting to, and Removal from, the Control Panel	
3.4.1 How to Mount the Unit	16
3.4.2 How to Remove the Mounting Frame and Unit	
4. Wiring	
4.1 Terminal Arrangement	
4.2 Lead Wire Solderless Terminal	
4.3 Terminal Cover	
4.4 Wiring	
4.4.1 Power Supply	23
4.4.2 Control Output OUT1, OUT2	
4.4.3 Input	
4.4.4 Event Output 1, Event Output 2	
4.4.5 Insulated Power Output	
4.4.6 CT Input	
4.4.7 Serial Communication	
4.4.8 Event Input	
4.4.9 External Setting Input	
4.4.10 Transmission Output	
5. Outline of Key Operation and Each Mode	00
5.1 Key Operation	31
5.2 Modes	
5.3 Basic Operation after Power-ON	
6. Initial Setting	
6.1 Example of Initial Setting	
6.2 Initial Setting Mode	
7. Settings	10
7.1 Main Setting Mode	53
7.2 Sub Setting Mode	
7.3 Engineering Mode	
8. Operation and Settings of Standard Functions	01
8.1 Selecting an input type	78
8.2 Selecting PID Control or ON/OFF Control	
8.3 Selecting Direct/Reverse Action	
8.4 Performing Fixed Value Control	
8.5 Setting PID Constants (by Performing AT)	
8.6 Performing Auto-reset	
8.7 Performing Program Control	
8.8 Event Output EV1 Allocation	
8.9 Indicating MV, Remaining Time (Program Control)	
8.10 Items to be Initialized by Changing Settings	
erre iteme to be initialized by enaliging oottinge	00

### 9. Attached Function

9.1 Input Value Correction	- 97
9.2 Set Value Lock	- 99
9.3 Control Output OFF Function	100
9.4 Switching Auto/Manual Control (Auto/Manual Control Function)	
9.5 Using as a Converter	
9.5.1 Selecting Converter Function	103
9.5.2 Fine Adjustment of Converter Output (4 to 20 mA DC)	104
9.5.3 Setting Example of Converter	
9.6 Clearing Data	106
10. Action Explanation	
10.1 OUT1 Action	
10.2 OUT1 ON/OFF Control Action	-
10.3 Heater Burnout Alarm Action	
10.4 Alarm Action	
10.5 OUT2 (Heating/Cooling Control) Action	
10.6 OUT2 (Heating/Cooling Control) Action (When Setting Dead Band) -	112
10.7 OUT2 (Heating/Cooling Control) Action (When Setting Overlap Band)-	113
11. Specifications	
11.1 Standard Specifications	
11.2 Optional Specifications	124
12. Troubleshooting	
12.1 Indication	
12.2 Key Operation	
12.3 Control	129
13. Character Table	
13.1 Error Code	
13.2 Run Mode	
13.3 Monitor Mode	-
13.4 Initial Setting Mode	
13.5 Main Setting Mode	
13.6 Sub Setting Mode	
13.7 Engineering Mode	
14 Key Operation Flowchart	149

## 1. Model

### 1.1 Model

	B C 2										
	BCS2						48 x 4	48 x 68 n	nm (W x H x D) (Depth of control panel interior: 60)		
Size	BCR2						48 x 9	8 x 96 x 68 mm (W x H x D) (Depth of control panel interior: 60)			
	BCD2						96 x 9	96 x 68 n	nm (W x H x D) (Depth of control panel interior: 60)		
Control	outout	R					Relay	Relay contact: 1a			
Control OUT1	ουιραι	S					Non-	contact v	oltage (for SSR drive) 12 V DC±15%		
0011		А					Direc	t current:	: 4 to 20 mA DC		
Power s	supply		0				100 t	o 240 V A	AC (Standard)		
voltage			1				24 V	AC/DC			
Input				0			Multi-	range (*	1)		
					0			No Opt	ion 1 needed.		
Ontion	1 (+0)				1		EV2	EV2 Event output EV2 (*3)			
Option 1		+	ion )		2		DS	DS Heating/Cooling control output OUT2, Non-contact voltage			
Choose	e only one	ε ορι	.1011.)		3		DA	DA Heating/Cooling control output OUT2, Direct current			
					4		P24	P24 Insulated power output			
						0			No Option 2 needed.		
						1	C5W	(20A)	Event input (2 points) (*4) + Serial communication		
									+ Heater burnout alarm (20A) (*5)		
				2	C5W	(100A)	Event input (2 points) (*4) + Serial communication				
									+ Heater burnout alarm (100A) (*5)		
						3	EIW	(20A)	Event input (2 points) +		
Ontion	0 (*0)								Heater burnout alarm (20A) (*5)		
Option 2	e only one	o ont	ion )			4	EIW	(100A)	Event input (2 points) +		
Choose		e opi							Heater burnout alarm (100A) (*5)		
						5	EIT		Event input (2 points) (*6)+		
									External setting input + Transmission output		
						6	C5		Serial communication		
						7	W (20	DA)	Heater burnout alarm (20 A) (*5)		
						8	W (10	00A)	Heater burnout alarm (100 A) (*5)		
						9	EI		Event input (2 points)		

(\*1) Thermocouple, RTD, Direct current and DC voltage can be selected by keypad.

(\*2) Only one option can be selected from Option 1 and Option 2 respectively.

(\*3) Event output EV1 is standard.

The following outputs can be selected in [Event output EV1/EV2 allocation] by keypad:

Alarm output (12 alarm types and No alarm action), Heater burnout alarm output, Loop break alarm output, Time signal output, Output during AT, Pattern end output, Output by communication command, Heating/Cooling control output OUT2 (for EV2 option only).

For Event output EV1/EV2, Heater burnout alarm output and Output by communication command are available when C5W, EIW, C5 or W option is ordered.

(\*4) For the BCS2, Event input (2 points) is not available.

(\*5) For Direct current output type, Heater burnout alarm does not work.

(\*6) For the BCS2, 1 point of Event input is available.

#### 1.2 How to Read the Model Label

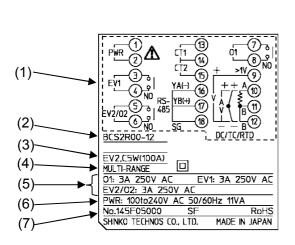
The model label is attached to the right side of the case.

#### BCS2

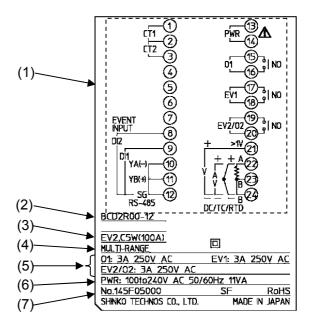
(e.g.) BCS2R00-12

### BCR2, BCD2

(e.g.) BCD2R00-12



(Fig. 1.2-1)



(Fig. 1.2-2)

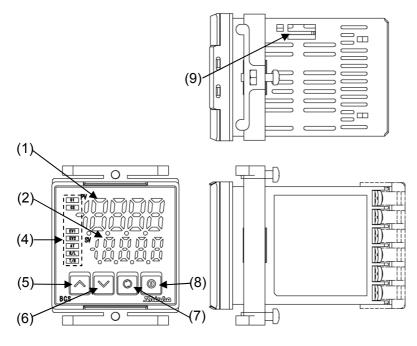
No.	Description	Example
(1)	Terminal arrangement	BCS2R00-12, BCD2R00-12 (*1)
(2)	Model	BCS2R00-12, BCD2R00-12
(3)	Option	EV2 (Event output EV2)
		C5W(100A) [Serial communication + Heater burnout
		alarm (100 A)] (*2)
(4)	Input	MULTI-RANGE (Multi-range input)
(5)	Control output, Event output	O1: 3 A 250 V AC (Control output OUT1)
		EV1: 3 A 250 V AC (Event output EV1)
		EV2: 3 A 250 V AC (Event output EV2)
(6)	Power supply voltage,	100 to 240 V AC 50/60 Hz,
	Power consumption	11 VA
(7)	Serial number	No. 145F05000

(\*1) Terminal arrangement diagram differs depending on the model.

(\*2) For Heater burnout alarm output (C5W, EIW, W options), CT rated current is entered in bracket ( ).

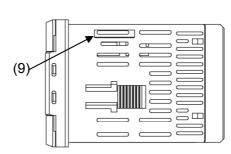
## 2. Names and Functions of Sections

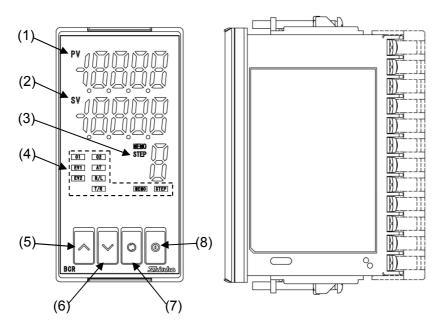
BCS2



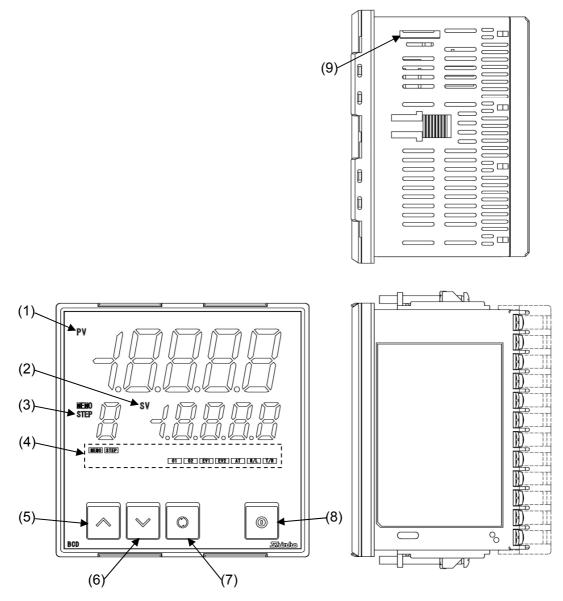
(Fig. 2-1)

BCR2





(Fig. 2-2)



(Fig. 2-3)

### Display

Display							
No.	Name		Description				
(1)	PV Display	Indicates PV.					
		Indicates setting	g characters in each setting mode.				
(2)	SV Display	Indicates SV.					
		Indicates set da	ata in each setting mode.				
		In Monitor mode	e, indicated contents differ depending on the model as				
		follows.	follows.				
		Model	Model Indicated Contents				
		BCS2	Indicates MV, Remaining time (Program control), Step				
			number (Program control) or Set value memory number				
			(Fixed value control).				
		BCR2, BCD2	BCR2, BCD2 Indicates MV or Remaining time (Program control).				
(3)	MEMO/STEP	Indicates Set va	Indicates Set value memory number (Fixed value control) or Step number				
	Display	(Program contro	ol). (For BCR2, BCD2)				

### **Action Indicators**

No.	Name	Description
(4)	O1 (Green)	Lit when control output OUT1 is ON.
		For direct current output type, flashes corresponding to the MV in 125 ms
		cycles.
	O2 (Yellow)	Lit when control output OUT2 (EV2, DS options) is ON.
		For direct current output type (DA option), flashes corresponding to the MV
		in 125 ms cycles.
	EV1 (Red)	Lit when Event output 1 is ON.
	EV2 (Red)	Lit when Event output 2 (EV2 option) is ON.
		Unlit if $\Box \mathcal{G} \ \mathcal{I} \mathcal{G}$ (Heating/Cooling control relay contact output) is selected in
		[Event output EV2 allocation].
	AT (Yellow)	Flashes while AT, 'AT on startup' or Auto-reset is performing.
	R/L (Yellow)	Lit during Remote action, selected in [Remote/Local] (EIT option).
	T/R (Yellow)	Lit during Serial communication (C5W, C5 options) TX (transmitting) output.
	MEMO	Lit when Set value memory number (Fixed value control) is indicated.
	(Yellow)	(For BCR2, BCD2)
	STEP (Green)	Lit when a step number (Program control) is indicated. (For BCR2, BCD2)

Key

ey							
No.	Name	I	Description				
(5)	UP key	Increases the numeric value.					
		By pressing this key for 1 secon	d during Program control, the performing				
		step is interrupted, proceeding to	o the beginning of the next step. (Advance				
		function)					
(6)	DOWN key	Decreases the numeric value.					
(7)	MODE key	Switches a setting mode, and registers the set data.					
		By pressing this key for 3 seconds during RUN mode, the unit enters					
		Monitor mode.					
(8)	OUT/OFF key	By pressing the <sup>(()</sup> ) key for approx. 1 second, one of the following items					
		selected in [OUT/OFF key function] is activated.					
		OUT/OFF Key Function	Description				
		Control output OFF function	Turns control output ON or OFF.				
		Auto/Manual control	Switches the Auto/Manual control.				
		Program control	Starts/Stops the Program control.				
			· · · · · · · · · · · · · · · · · · ·				

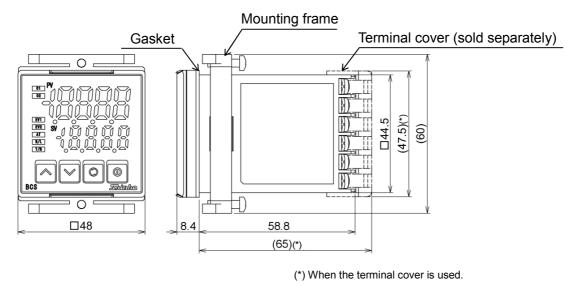
### **Console Connector**

No.	Name	Description
(9)	Console	By connecting the tool cable (CMD-001, sold separately), the following
	connector	operations can be conducted from an external computer using the Console
		software SWC-BCx01M.
		<ul> <li>Reading and setting of SV, PID and various set values</li> </ul>
		<ul> <li>Reading of PV and action status</li> </ul>
		Function change

## 3. Mounting to the Control Panel

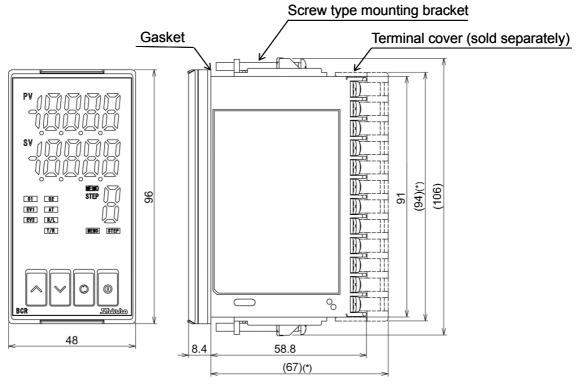
3.1 External Dimensions (Scale: mm)

#### BCS2



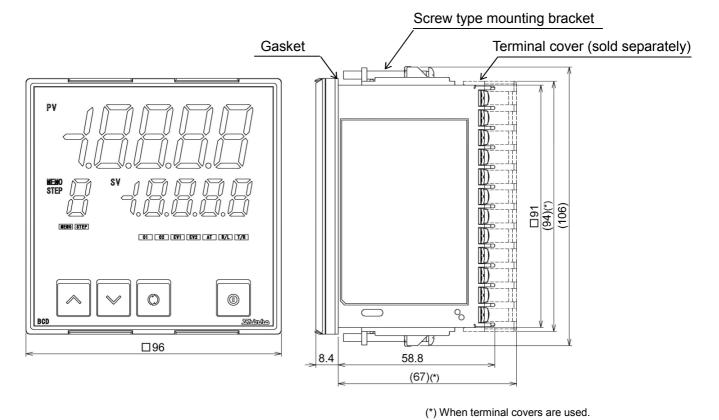
(Fig. 3.1-1)

BCR2



(\*) When the terminal cover is used.

(Fig. 3.1-2)

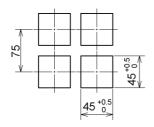


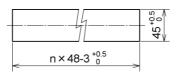
(Fig. 3.1-3)

## \land Caution

If lateral close mounting is used for the controller, IP66 specification (Drip-proof/Dust-proof) may be compromised, and all warranties will be invalidated.

### BCS2

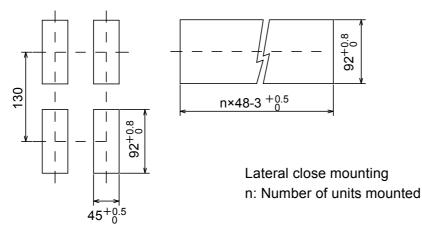




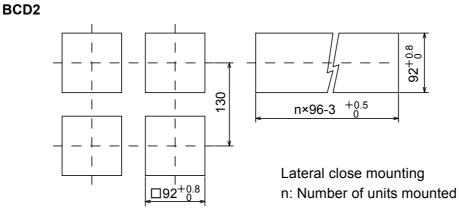
Lateral close mounting n: Number of units mounted



BCR2





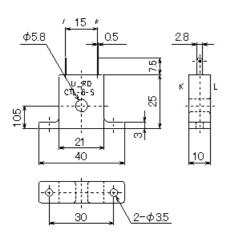


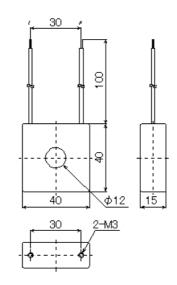


### 3.3 CT (Current Transformer) External Dimensions (Scale: mm)

CTL-6S (for 20 A)

CTL-12-S36-10L1U (for 100 A)





(Fig. 3.3-1)

## ▲ Caution

As the mounting frame of the BCS2 is made of resin, do not use excessive force while tightening screws, or the mounting frame could be damaged. Tighten screws with one rotation upon the screw tips touching the panel.

The torque is 0.05 to 0.06 N•m.

For the BCR2, BCD2, the torque should be 0.1 N•m.

### 3.4.1 How to Mount the Unit

### BCS2

Mount the controller vertically to the flat, rigid panel to ensure it adheres to the Drip-proof/Dust-proof specification (IP66).

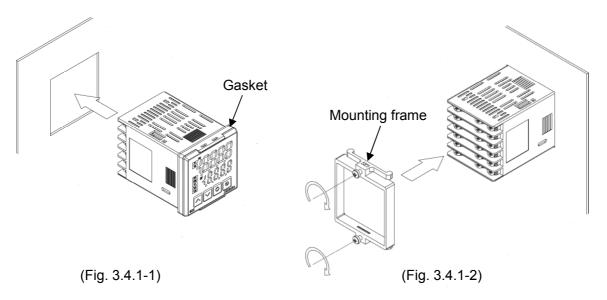
If the lateral close mounting is used for the controller, IP66 specification (Drip-proof/Dust-proof) may be compromised, and all warranties will be invalidated.

Mountable panel thickness: 1 to 5 mm

(1) Insert the controller from the front side of the control panel. (Fig. 3.4.1-1)

If the Drip-proof/Dust-proof specification (IP66) is not necessary, the gasket may be removed (please keep in mind the warranty is void if gasket is removed).

(2) Insert the mounting frame until it comes into contact with the panel, and fasten with screws. Tighten screws with one rotation upon the screw tips touching the panel. (Fig. 3.4.1-2) The torque is 0.05 to 0.06 N•m.



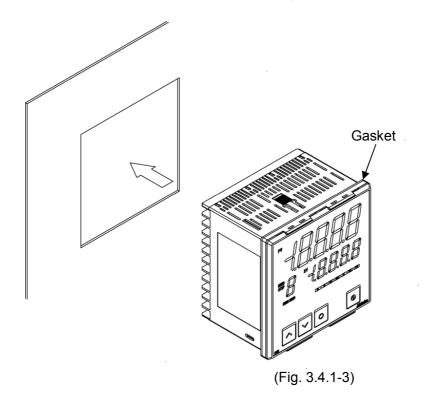
#### BCR2, BCD2

Mount the controller vertically to the flat, rigid panel to ensure it adheres to the Drip-proof/Dust-proof specification (IP66).

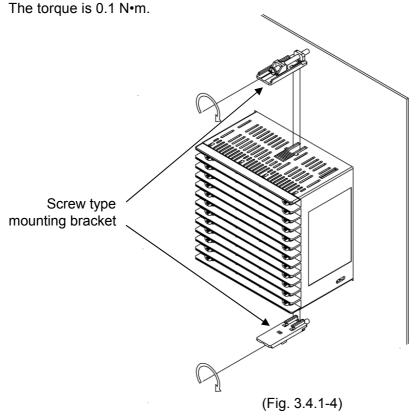
If the lateral close mounting is used for the controller, IP66 specification (Drip-proof/Dust-proof) may be compromised, and all warranties will be invalidated. Mountable panel thickness: 1 to 7 mm

(1) Insert the controller from the front side of the control panel. (Fig. 3.4.1-3)

If the Drip-proof/Dust-proof specification (IP66) is not necessary, the gasket may be removed. (Please keep in mind the warranty is void if gasket is removed).



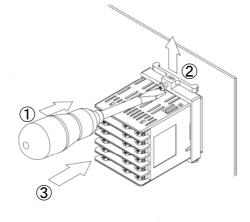
(2) Attach the mounting brackets by the holes at the top and bottom of the case, and secure the controller in place with the screws.



### 3.4.2 How to Remove the Mounting Frame and Unit

### BCS2 (Fig. 3.4.2-1)

- (1) Turn the power to the unit OFF, and disconnect all wires before removing the mounting frame.
- (2) Insert a flat blade screwdriver between the mounting frame and unit ().
- (3) Slowly push the frame upward using the screwdriver (<sup>2</sup>), while pushing the unit toward the panel (<sup>3</sup>).
- (4) Repeat step (2) and slowly push the frame downward using the screwdriver for the other side. The frame can be removed little by little by repeating these steps.



(Fig. 3.4.2-1)

### BCR2, BCD2

- (1) Turn the power to the unit OFF, and disconnect all wires before removing the unit.
- (2) Loosen the screws of the mounting brackets, and remove the mounting brackets.
- (3) Pull the unit out from the front of the control panel.

# 4. Wiring

# \land Warning

Turn the power supply to the instrument off before wiring or checking.

Working on or touching the terminal with the power switched on may result in severe injury or death due to electrical shock.

# \land Caution

- Do not leave wire remnants in the instrument, as they could cause a fire or malfunction.
- Use the solderless terminal with an insulation sleeve in which the M3 screw fits when wiring the instrument.
- The terminal block of this instrument is designed to be wired from the left side. The lead wire must be inserted from the left side of the terminal, and fastened with the terminal screw.
- Tighten the terminal screw using the specified torque. If excessive force is applied to the screw when tightening, the terminal screw or case may be damaged.
- Do not pull or bend the lead wire on the terminal side when wiring or after wiring, as it could cause malfunction.
- When using a terminal cover for the BCS2, pass terminal wires numbered 7 to 12 into the holes of the terminal cover.
- This instrument does not have a built-in power switch, circuit breaker and fuse. It is necessary to install a power switch, circuit breaker and fuse near the controller. (Recommended fuse: Time-lag fuse, rated voltage 250 V AC, rated current 2 A)
- For a 24 V AC/DC power source, do not confuse polarity when using direct current (DC).
- Do not apply a commercial power source to the sensor which is connected to the input terminal nor allow the power source to come into contact with the sensor.
- Use a thermocouple and compensating lead wire according to the sensor input specifications of this controller.
- Use the 3-wire RTD according to the sensor input specifications of this controller.
- For DC voltage input, (+) side input terminal number of 0 to 5 V DC, 1 to 5 V DC, 0 to 10 V DC differs from that of 0 to 1 V DC.

Model	Terminal Number
BCS2	<sup>(9)</sup> : (+) side of 0 to 5 V DC, 1 to 5 V DC, 0 to 10 V DC
	<sup>(1)</sup> : (+) side of 0 to 1 V DC
BCR2, BCD2	②: (+) side of 0 to 5 V DC, 1 to 5 V DC, 0 to 10 V DC
	22: (+) side of 0 to 1 V DC

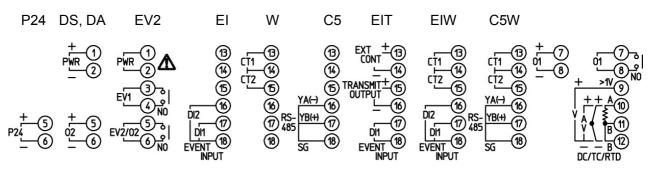
• When using a relay contact output type, externally use a relay according to the capacity of the load to protect the built-in relay contact.

• When wiring, keep input wires (thermocouple, RTD, etc.) away from AC sources or load wires.

### 4.1 Terminal Arrangement

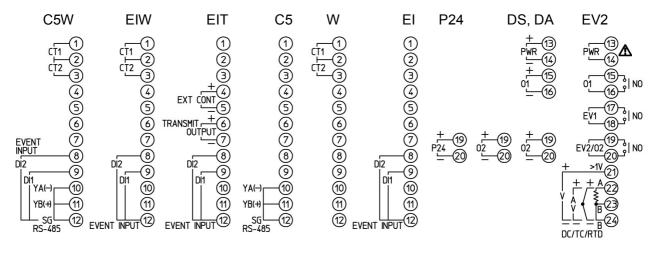
Terminal arrangement of the BCS2, BCR2, BCD2 differs depending on the options as follows.

BCS2



(Fig. 4.1-1)

BCR2, BCD2



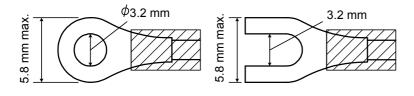
(Fig. 4.1-2)

Terminal		Description
PWR	100 to 240 V AC or 24 V AC/DC	
(Power supply)	For a 24 V AC/DC power source, do not confuse polarity when using	
	direct current (DC).	
EV1	Event output E\	/1
EV2	Event output E\	/2 (EV2 option)
O2	Control output C	DUT2 (EV2, DS, DA options)
P24	24 V DC insulat	ed power output (P24 option)
01	Control output C	DUT1
RTD	RTD input	
ТС	Thermocouple i	nput
DC	Direct current, I	DC voltage inputs
	-	e input, (+) side input terminal number of 0 to 5 V DC, 1 to
	5 V DC, 0 to 1	0 V DC differs from that of 0 to 1 V DC.
	Model	Terminal Number
	BCS2	(9): + side of 0 to 5 V DC, 1 to 5 V DC, 0 to 10 V DC
		10: + side of 0 to 1 V DC
	BCR2, BCD2	(1): + side of 0 to 5 V DC, 1 to 5 V DC, 0 to 10 V DC
		<sup>22</sup> : + side of 0 to 1 V DC
CT1	CT input 1 (C5W)	· · · · ·
CT2	CT input 2 (C5W, EIW, W options)	
RS-485	Serial communication RS-485 (C5W, C5 options)	
EVENT INPUT	Event input DI1 (BCS2: EIW, EIT, EI options,	
	BCR2/BCD2: C5W, EIW, EIT, EI options)	
	Event input DI2 (BCS2: EIW, EI options,	
	BCR2/BCD2: C5W, EIW, EIT, EI options)	
EXT CONT	External setting input (EIT option)	
TRANSMIT OUTPUT	Transmission of	utput (EIT option)

### 4.2 Lead Wire Solderless Terminal

Use a solderless terminal with an insulation sleeve in which an M3 screw fits as shown below. The torque should be 0.63 N-m.

Solderless Terminal	Manufacturer	Model	Tightening Torque
Vturo	Nichifu Terminal Industries Co., Ltd.	TMEV1.25Y-3	
Y-type	Japan Solderless Terminal MFG Co., Ltd.	VD1.25-B3A	0.02 Norm
	Nichifu Terminal Industries Co., Ltd.	TMEV1.25-3	0.63 N•m
Ring-type	Japan Solderless Terminal MFG Co., Ltd.	V1.25-3	

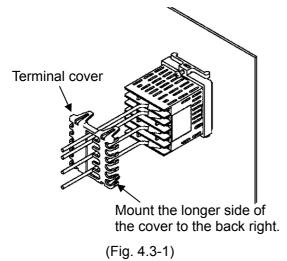


(Fig. 4.2-1)

### 4.3 Terminal Cover

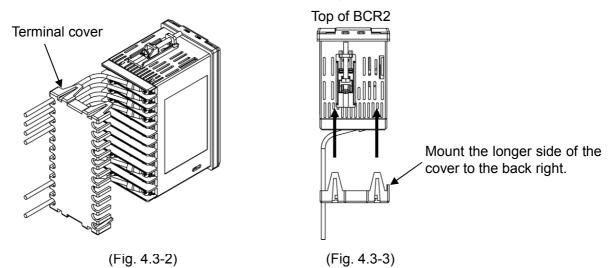
### BCS2

When using a terminal cover (sold separately), make sure the longer side is on the back right side of the case. Pass the wires from terminals 7 to 12 into the holes of the terminal cover.



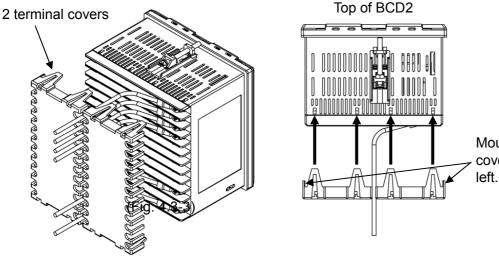
### BCR2

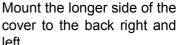
When using a terminal cover (sold separately), make sure the longer side is on the back right side of the case. Pass the wires from terminals 13 to 24 through the left side of the terminal cover.



### BCD2

When using terminal covers (sold separately), make sure the longer side is on the back right and left sides of the case. Pass the wires from terminals 13 to 24 through between covers.





(Fig. 4.3-4)



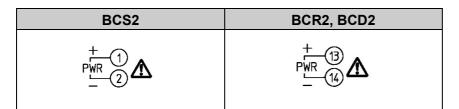
### 4.4 Wiring

For the terminal arrangement, refer to Section '4.1 Terminal Arrangement' (p.20).

### 4.4.1 Power Supply

Power supply voltage is 100 to 240 V AC or 24 V AC/DC.

For a 24 V AC/DC power source, ensure polarity is correct when using direct current (DC).



### 4.4.2 Control Output OUT1, OUT2

When EV2, DS or DA option is ordered, control output OUT2 is available. Specifications of Control output OUT1, OUT2 are shown below.

Relay contact	1a
	Control capacity: 3 A 250 V AC (resistive load),
	1 A 250 V AC (inductive load $\cos\phi$ =0.4)
	Electrical life: 100,000 cycles
	Minimum applicable load: 10 mA 5 V DC
Non-contact voltage	12 V DC±15%
(for SSR drive)	Max. 40 mA (short circuit protected)
Direct current	4 to 20 mA DC
	Load resistance: Max. 550 $\Omega$

E	BCS2	BCF	2, BCD2
Relay contact	Non-contact voltage, Direct current	Relay contact	Non-contact voltage, Direct current
EV2/02 6 NO	+ 02 - 6	01_15_1 NO	+(15) 01(16)
010  8N0	+7 018	EV2/02	+(19) 02(20)

Number of Shinko SSR units when connected in parallel (for Non-contact voltage output):

- SA-400 series: 5 units
- SA-500 series: 2 units

### 4.4.3 Input

Each input wiring is shown below.

For DC voltage input, (+) side input terminal number of 0 to 5 V DC, 1 to 5 V DC, 0 to 10 V DC differs from that of 0 to 1 V DC.

BCS2			
Thermocouple	RTD	Direct current, DC voltage (0 to 1 V)	DC voltage (0 to 5 V, 1 to 5 V, 0 to 10 V)
			+ () () () () () () () () () ()

BCR2, BCD2			
Thermocouple	RTD	Direct current, DC voltage (0 to 1 V)	DC voltage (0 to 5 V, 1 to 5 V, 0 to 10 V)
+22 (23) -24 ΤΓ		+22 4 2 1 2 0 0	+ 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2

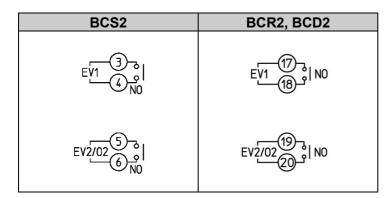
### 4.4.4 Event Output 1, Event Output 2

Event output EV1 is a standard feature.

If EV2 option is ordered, Event output EV2 is available.

Specifications of Event output 1 and Event output 2 are shown below.

1	
Relay contact	1a
	Control capacity: 3 A 250 V AC (resistive load)
	1 A 250 V AC (inductive load $\cos\phi$ =0.4)
	Electrical life: 100,000 cycles
	Minimum applicable load: 10 mA 5 V DC



### 4.4.5 Insulated Power Output

If P24 option is ordered, the Insulated power output is available.

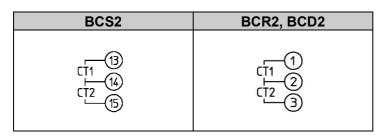
Specifications of Insulated power output are shown below.

Output voltage	24±3 V DC (at load current 30 mA DC)
Ripple voltage	Within 200 mV DC (at load current 30 mA DC)
Max load current	30 mA DC

BCS2	BCR2, BCD2
+5	+(9)
P246	P24(2)

### 4.4.6 CT Input

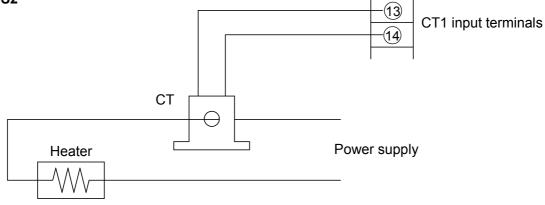
CT input is available when Heater burnout alarm (C5W, EIW, W options) is ordered. **Cannot be used for detecting heater current under phase control.** 



Use the CT (current transformer) provided, and pass one lead wire of the heater circuit into the hole of the CT. (Fig. 4.4.6-1)

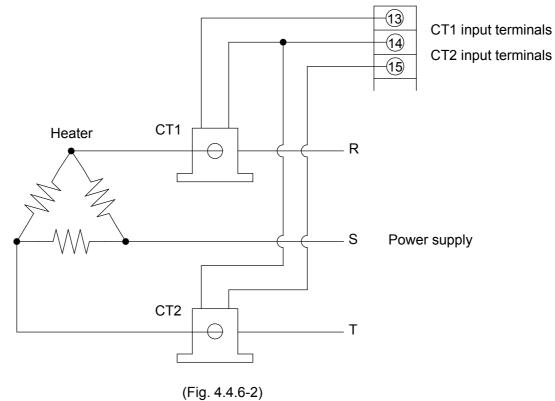
When wiring, keep the CT wire away from AC sources or load wires to avoid the external interference.



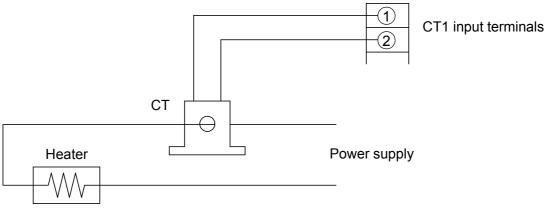


(Fig. 4.4.6-1)

If using 3-phase, pass any 2 lead wires of R, S, T into the CT, and connect them to CT1 ( $^{(3-4)}$ ) and CT2 ( $^{(4)-(5)}$ ) terminals. (Fig. 4.4.6-2)

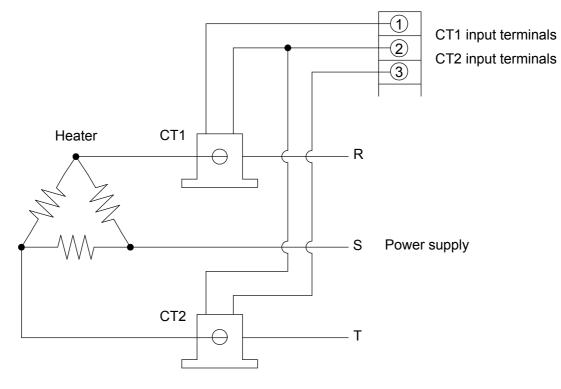


26



(Fig. 4.4.6-3)

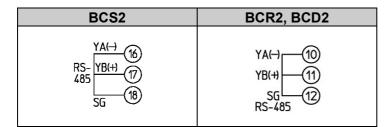
If using 3-phase, pass any 2 lead wires of R, S, T into the CT, and connect them to CT1 (1-2) and CT2 (2-3) terminals. (Fig. 4.4.6-4)



(Fig. 4.4.6-4)

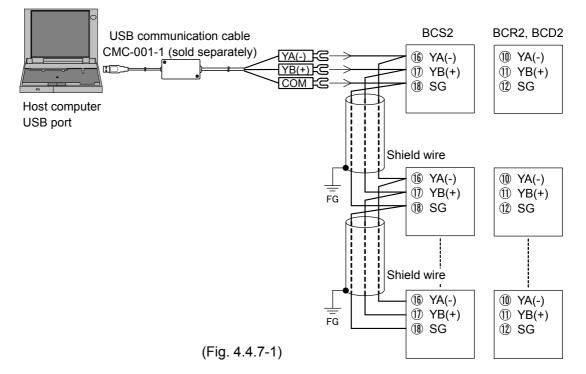
#### 4.4.7 Serial Communication

If the C5W or C5 option is ordered, Serial communication is available.

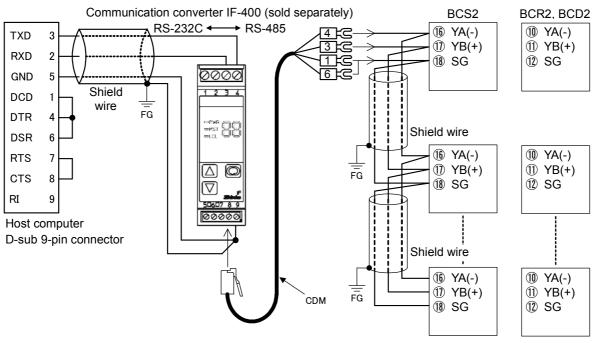


#### (1) Serial Communication

#### When using USB communication cable CMC-001-1 (sold separately)



#### • When using communication converter IF-400 (sold separately)



(Fig. 4.4.7-2)

### (2) Set value digital transmission

By connecting to Shinko programmable controllers [PC-900 or PCD-33A with the SVTC (Set value digital transmission) option], digital SV via the SVTC command can be received from programmable controllers.

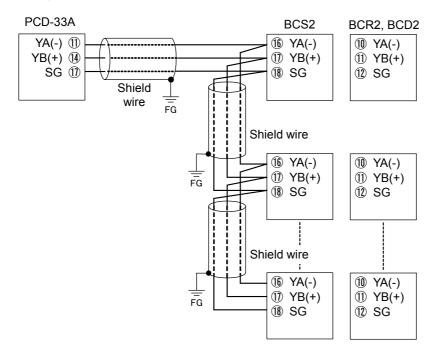
### Wiring

For the PC-900, connect YA (-) to YA (-), YB (+) to YB (+), COM (PC-900) to SG (BCx2) terminal respectively.

For the PCD-33A, connect YA (-) to YA (-), YB (+) to YB (+), SG to SG terminal respectively. Up to 31 units of the BCS2 or BCR2 or BCD2 can be connected.

The following shows a connection example of PCD-33A and BCS2, BCR2, BCD2. (Fig. 4.4.7-3)

### Wiring example of PCD-33A and BCx2



(Fig. 4.4.7-3)

### Shield wire

Connect only one end of the shield to the FG terminal to avoid a ground loop. If both ends of the shield wire are connected to the FG terminal, the circuit will be closed, resulting in a ground loop. This may cause noise. Be sure to ground the FG terminal.

Recommended cable: OTSC-VB 2PX0.5SQ (made by Onamba Co., Ltd.) or equivalent (Use a twisted pair cable.)

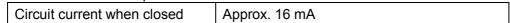
### 4.4.8 Event Input

Event Input DI1 is available for the BCS2 with Event input (EIW, EIT, EI options). Event Input DI1 is available for the BCR2, BCD2 with Serial communication (C5W option) or Event input (EIW, EIT, EI options).

Event Input DI2 is available for the BCS2 with Event input (EIW, EI options).

Event Input DI2 is available for the BCR2, BCD2 with Serial communication (C5W option) or Event input (EIW, EIT, EI options).

Specifications of Event input are shown below.



B	BCS2	
EIW (20A), EIW (100A), EI	EIT	EIW (20A), EIW (100A), EIT, EI
DI2 DI2 DI1 EVENT INPUT	DI1 EVENT INPUT	DI2 9 DI1 10 11 EVENT INPUT 12

### 4.4.9 External Setting Input

If the EIT option is ordered, External setting input is available.

Specifications of External setting input are shown below.

Setting signal	Direct current 4 to 20 mA DC
Allowable input	50 mA DC max.
Input impedance	50 Ω max.
Input sampling period	125 ms

BCS2	BCR2, BCD2

### 4.4.10 Transmission Output

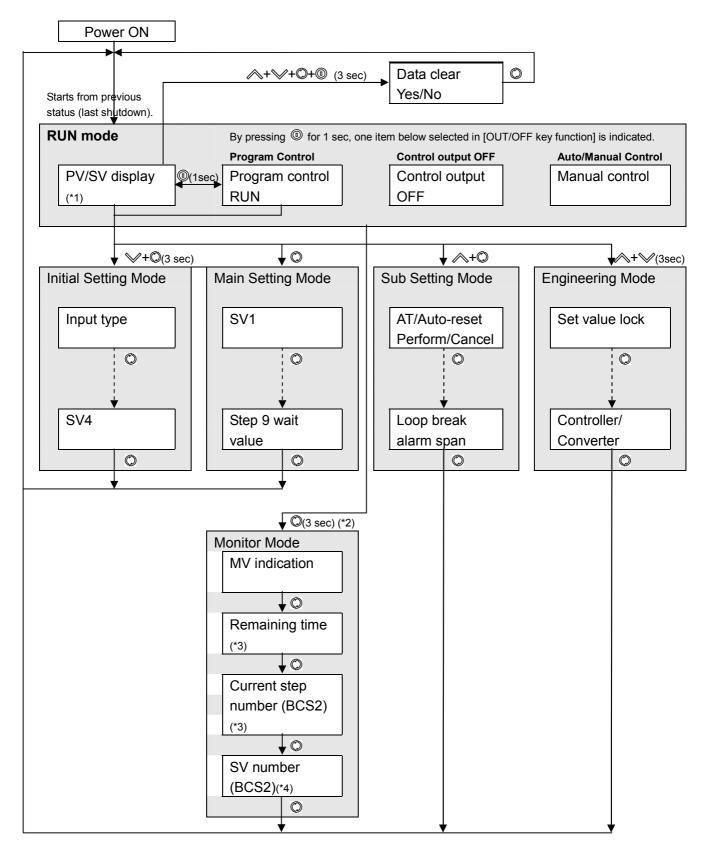
If the EIT option is ordered, Transmission output is available. Specifications of Transmission output are shown below.

Resolution	12000		
Output	4 to 20 mA DC		
	Load resistance: Max 550 $\Omega$		
Output accuracy	Within $\pm 0.3\%$ of Transmission output span		

BCS2	BCR2, BCD2
	TRANSMIT

## 5. Outline of Key Operation and Each Mode

5.1 Key Operation



(\*1) If 'Program control' is selected in [OUT/OFF key function], the unit enters Standby mode (program control waiting).

- (\*2) The unit cannot proceed to Monitor mode if it is in Standby of program control.
- (\*3) Available only when 'Program control' is selected in [OUT/OFF key function].
- (\*4) Not available if 'Program control' is selected in [OUT/OFF key function].

- $\forall$ + $\bigcirc$  (3 sec): Press and hold the  $\forall$ ,  $\bigcirc$  keys (in that order) together for approx. 3 sec.
- $\wedge$ + $\mathbb{O}$ : Press and hold the  $\wedge$ ,  $\mathbb{O}$  keys (in that order) together.
- $\wedge$ + $\vee$  (3 sec): Press and hold the  $\wedge$ ,  $\vee$  keys (in that order) together for approx. 3 sec.
- Set (or select) each item with the  $\wedge$  or  $\vee$  key, and register the value with the  $\mathbb O$  key.
- ♥<sup>©</sup>: If the <sup>©</sup> key is pressed, the unit will proceed to the next setting item, illustrated by an arrow. Pressing the <sup>®</sup> key moves back to the previous item.
- To revert to RUN mode, press and hold the  ${igodot}$  key for approx. 3 sec while in any mode.
- To revert to RUN mode, press and hold the 0 key for approx. 3 sec while in any mode.
- If 'Control output OFF function' is selected in [OUT/OFF key function], the unit will enter Control output OFF status.
- If 'Auto/Manual control' is selected in [OUT/OFF key function], the unit will enter Manual control status.

If 'Program control' is selected in [OUT/OFF key function], the unit will enter 'Program control RUN' or Standby mode.

Mode	Description			
RUN mode	When power is turned ON, the unit enters RUN mode.			
	The PV Display indicates PV, and the SV Display indicates SV.			
	Control starts from previous status (last shutdown).			
	By pressing the <sup>(i)</sup> key for approx. 1 sec, one of the following functions			
	selected in [OUT/OFF key function] is activated.			
	OUT/OFF Key	Description		
	Control output OF	<sup>=</sup> function	Turns the control output ON or OFF.	
	Auto/Manual control		Switches the Auto/Manual control.	
	Program control		Starts/Stops the Program control.	
Monitor mode	By pressing the $ \mathbb{O} $	key for approx.	3 sec in RUN mode, the unit enters Monitor	
	mode. The PV Dis	olay indicates P	V, and the SV Display indicates MV.	
	Every time the Ø k	key is pressed, t	he following is indicated.	
	Indicated contents	differ dependin	g on the model.	
	Model		Indicated Contents	
	BCS2	Indicates MV,	Remaining time (Program control), Step	
		number (Prog	ram control) or Set value memory number	
		(Fixed value c	ontrol).	
	BCR2, BCD2	Indicates MV or Remaining time (Program control).		
Initial setting mode	By pressing the $$	' and © keys (	n that order) together for approx. 3 sec in	
	RUN mode, the uni	t enters Initial se	tting mode.	
	The following items	can be set.		
	Input type, Scalin	ig high limit/low l	imit, Event output EV1/EV2 (EV2 option)	
	allocation, Event	input DI1/DI2 a	llocation (*), SV1, etc.	
Main setting mode	By pressing the O	key in RUN mo	de, the unit enters Main setting mode.	
	SV can be set.			
	If 'Program control	' is selected in [	OUT/OFF key function], SV, Time and Wait	
	value for Steps 1 to	o 9 can be set.		
	If 'Set value memo	ory number' is se	elected in [Event input DI1/DI2 allocation]	
	(*), SV1 to SV4 can be set.			
Sub setting mode	By pressing the ∧	and 🔘 keys (	n that order) together in RUN mode, the unit	
	enters Sub setting r	node.		
	The following items	can be set.		
	AT Perform, P, I	, D, Direct/Reve	erse action, Event output EV1/EV2 (EV2	
	option), etc.			
Engineering mode				
	RUN mode, the uni		-	
	The following items	can be set.		
	-		DI2 allocation (*), Event output EV1/EV2	
		-	correction, PV filter time constant, Program	
	control, OUT/OFF key function, Controller/Converter, etc.			
) Event input DI1 allocation: BCS2 with EIW EIT EL ontions BCR2/BCD2 with C5W EIW EIT EL ontions)				

(\*) Event input DI1 allocation: BCS2 with EIW, EIT, EI options, Event input DI2 allocation: BCS2 with EIW, EI options, BCR2/BCD2 with C5W, EIW, EIT, EI options)

### 5.3 Basic Operation after Power-ON

After the unit is mounted to the control panel and wiring is completed, operate the unit following the procedure below.

### (1) Turn the power supply to the unit ON

After the power is turned ON, the PV Display indicates the input type, and the SV Display indicates the Input range high limit value (for thermocouple, RTD inputs) or Scaling high limit value (for DC voltage, current inputs) for approximately 3 seconds. (Table 5.3-1)

During this time, all outputs and the indicators are in OFF status.

Control will then start, indicating the PV on the PV Display and SV on the SV Display. While the control output OFF function is working, the PV Display indicates [aFF...]. Indication differs depending on the selection in [Indication when control output OFF].

Concor Input	°(	С	°F		
Sensor Input	PV Display	SV Display	PV Display	SV Display	
К	£	1370	EEEF	2498	
	E	4888	E .F	7520	
J	JIIIE	1000	JEEF	1832	
R		1760	~	3200	
S	500C	1760	<b>५</b> []][/	3200	
В	6C	1820	<b>ь</b>	3308	
E	E	<i>□800</i>	E	1472	
Т	$r \square . r$	4888	ſШ.F	7520	
N	- <u></u>	1300	n E F	2372	
PL-Ⅱ	PLZE	1390	PL 2F	2534	
C(W/Re5-26)	c IIIC	23 (5	<i>د</i> ۶	4 /99	
Pt100	PF E	8500	PT F	1562.0	
JPt100	JPF.E	5000	JPF.F	932.0	
Pt100	PFEE	<u>850</u>	PFEF	1562	
JPt100	JPEE	<u> </u>	JPEF	<u> </u>	
4 to 20 mA DC	420R				
0 to 20 mA DC	020R	Scaling high limit value			
0 to 1 V DC	$D\square$ /B				
0 to 5 V DC	D S B				
1 to 5 V DC	/□5 <i>8</i>				
0 to 10 V DC	0 108				

(Table 5.3-1)

When power is turned ON, and any errors are found, the following error codes are indicated on the PV Display.

To cancel the error code, press the  $\bigcirc$  key.

Error Code	Error Contents		
E-0 /	Non-volatile IC memory is defective.		
E-02	Data writing (in non-volatile IC memory) error when power failure occurs.		

### (2) Enter each value.

Refer to Sections '6. Initial Setting' (p.37) to '8. Operation and Settings of Standard Functions' (p.96):

Enter each value: Input type, Control action (PID control, ON/OFF control, etc), Direct/Reverse action, SV, PID constants, Event output EV1 allocation, etc.

### (3) Turn the load circuit power ON

Control starts, so as to reach, and then maintain the control target at the SV.

### Error codes during operation

If errors occur during operation, error codes below are indicated on the PV Display.

Error Code	Error Contents
e-05	PV has exceeded Input range high limit value (scaling high limit value for DC
	voltage, current inputs).
E-05	PV has dropped below Input range low limit value (scaling low limit value for DC
	voltage, current inputs).
8-07	Input burnout, or PV has exceeded the Indication range and Control range.
Er 10	Hardware malfunction

#### **Indication Range and Control Range**

Input Type	Indication Range and Control Range			
Thermocouple	[Input range low limit – 50°C (100°F)] to [Input range high limit + 50°C (100°F)]			
RTD	[Input range low limit – Input span x 1%] to [Input range high limit + $50^{\circ}$ C (100°F)]			
DC voltage,	[Scaling low limit value – Scaling span x 1%] to			
Direct current	[Scaling high limit value + Scaling span x 10%]			

### Input error (Overscale, Underscale)

Overscale occurs if PV has exceeded Input range high limit value (Scaling high limit value for DC voltage, current inputs). PV and error code [ $\mathcal{E} = \mathcal{D} \mathcal{D}$ ] are indicated on the PV Display alternately.

Underscale occurs if PV has dropped below Input range low limit value (Scaling low limit value for DC voltage, current inputs). PV and error code [ $\mathcal{E} = \overline{\mathcal{D}}\overline{\mathcal{E}}$ ] are indicated on the PV Display alternately.

For manual control, the preset MV is output.

### Burnout

If PV has exceeded Indication range and Control range, [---] and [E - D] are alternately indicated on the PV Display.

If PV has dropped below Indication range and Control range, [- - -] and  $[\mathcal{E} \cap \mathcal{Q}]$  are alternately indicated on the PV Display.

If thermocouple or RTD input is burnt out, or if DC voltage (0 to 1 V DC) input is disconnected, [---] and [E = 0] are alternately indicated on the PV Display.

If DC voltage or current input is disconnected:

For 4 to 20 mA DC, 1 to 5 V DC inputs, the PV Display indicates [---] and  $[\xi \neg \overline{\beta}]$  alternately. For 0 to 20 mA DC, 0 to 5 V DC and 0 to 10 V DC inputs, the PV Display indicates the value corresponding with 0 mA DC or 0 V DC input.

OUT1 and OUT2 are turned OFF (OUT1/OUT2 low limit value for Direct current output). For manual control, the preset MV is output.

If Alarm, Heater burnout alarm or Loop break alarm is selected in [Event output EV1/EV2 allocation], Event output will be turned ON under the alarm active conditions.

Burnout is enabled even in standby (program control waiting) mode in Program control

[Output status when input errors occur] can be used only for controllers using Direct current and voltage inputs, and Direct current output.

		Output Status			
Output status when input	Contents, Indication	OUT1		OUT2	
		Direct (Cooling)	Reverse (Heating)	Direct (Cooling)	Reverse (Heating)
errors occur		action	action	action	action
on	Indicates [] and [ <i>E - D 7</i> ]	ON (20mA) or OUT1 high limit value (*) OFF (4mA) or	OFF (4mA) or OUT1 low limit	OFF or OUT2 low	ON or OUT2 high limit value (*) OFF or
₽FF□	alternately.	OUT1 low limit value	value	limit value	OUT2 low limit value
on	Indicates [ ] and [E ー ロ 기] alternately.	OFF (4mA) or OUT1 low limit value	ON (20mA) or OUT1 high limit value (*)	ON or OUT2 high limit value (*)	OFF or OUT2 low limit value
₀FF□			OFF (4mA) or OUT1 low limit value	OFF or OUT2 low limit value	

Output status differs depending on selection in [Output status when input errors occur].

(\*) Outputs a value between OFF (4mA) and ON (20mA) or between OUT1 (or OUT2) low limit value and OUT1 (or OUT2) high limit value, depending on deviation.

# 6. Initial Setting

Setup (setting the Input type, Event output allocation, SV, etc.) should be done before using this controller, according to the user's conditions. Perform setup in Initial setting mode.

Setting items in Initial setting mode are shown in (Table 6.1).

If the user's specification is the same as the factory default value of this instrument, or if user's instrument has already been installed in a system, initial settings are not necessary. Proceed to Section '7. Settings' (p.53).

(Table 6.1)	
Setting Items in Initial Setting Mode	Factory Default
Input type	K -200 to 1370℃
Scaling high limit	1370℃
Scaling low limit	<b>-200</b> ℃
Decimal point place	No decimal point
Event output EV1 allocation	No event
EV1 alarm value 0 Enabled/Disabled	Disabled
EV1 alarm value	<b>0</b> ℃
EV1 high limit alarm value	0°C
EV1 alarm hysteresis	1.0℃
EV1 alarm delay time	0 sec
EV1 alarm Energized/De-energized	Energized
Event output EV2 allocation (EV2 option)	No event
EV2 alarm value 0 Enabled/Disabled (EV2 option)	Disabled
EV2 alarm value (EV2 option)	0°C
EV2 high limit alarm value (EV2 option)	0°C
EV2 alarm hysteresis (EV2 option)	1.0℃
EV2 alarm delay time (EV2 option)	0 sec
EV2 alarm Energized/De-energized (EV2 option)	Energized
Heater burnout alarm 1 value (C5W, EIW, W options)	0.0 A
Heater burnout alarm 2 value (C5W, EIW, W options)	0.0 A
Loop break alarm time	0 minutes
Loop break alarm span	0°C
Event input DI1 allocation	No event
(BCS2: EIW, EIT, EI options, BCR2/BCD2: C5W, EIW, EIT, EI options)	
Event input DI2 allocation	No event
(BCS2: EIW, EI options, BCR2/BCD2: C5W, EIW, EIT, EI options)	
External setting input high limit (EIT option)	<b>1370</b> ℃
External setting input low limit (EIT option)	<b>-200</b> ℃
Transmission output type (EIT option)	PV transmission
Transmission output high limit (EIT option)	1370℃
Transmission output low limit (EIT option)	-200℃
SV1	0°C
SV2 (BCS2: EIW, EIT, EI options, BCR2/BCD2: C5W, EIW, EIT, EI options)	<b>0</b> °C
SV3 (BCS2: EIW, EI option, BCR2/BCD2: C5W, EIW, EIT, EI options)	0°C
SV4 (BCS2: EIW, EI option, BCR2/BCD2: C5W, EIW, EIT, EI options)	<b>0</b> ℃

37

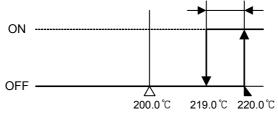
## 6.1 Example of Initial Setting

(e.g.) BCS2R00-00

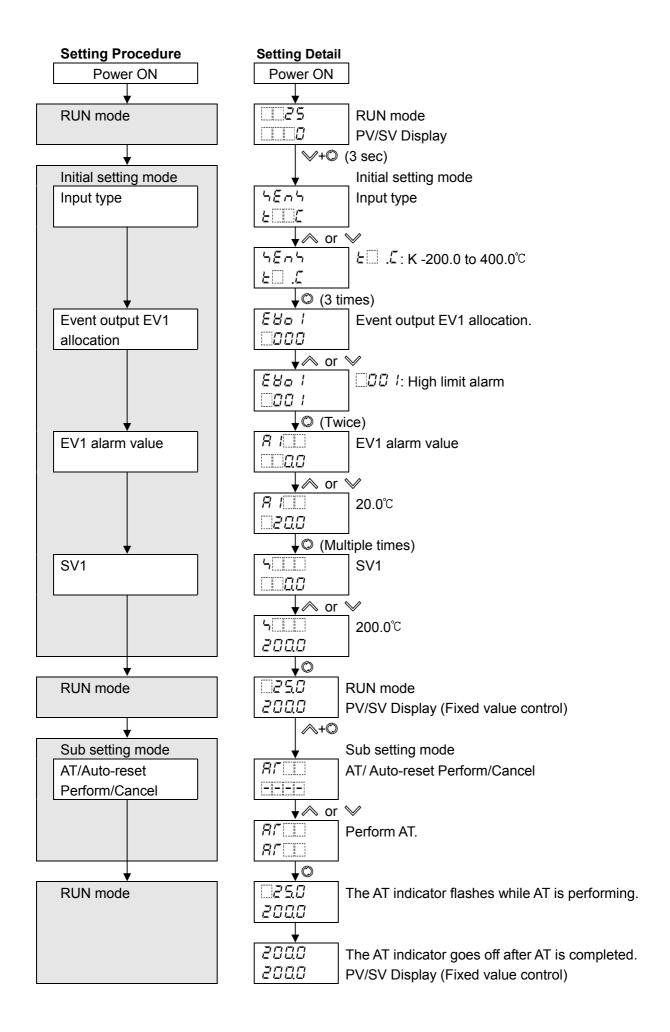
Initial Setting Items	Example
Input type	К -200.0 to 400.0°С
Event output EV1 allocation	High limit alarm
EV1 alarm value	20.0°C (Deviation setting from SV)
SV	200.0°C (Fixed value control)

PID control is performed. PID constants are calculated by performing AT.

# Alarm action



(Fig. 6.1-1)



#### 6.2 Initial Setting Mode

To enter Initial setting mode, press and hold the  $\bigvee$  and  $\bigcirc$  keys (in that order) for 3 seconds in RUN mode. To set (or select) each setting item, use the  $\wedge$  or  $\vee$  key. To register each setting item, press the <sup>(C)</sup> key.

Explanation of setting item:

- Upper left: PV Display: Indicates setting characters.
- Lower left: SV Display: Indicates factory default.
- Right side: Indicates the setting item, explanation of its function, and setting range (or selection item).

Setting charac	cters Setting item name, function, setting range (or selection item)
5En5	Input type
E	• Selects an input type from thermocouple (10 types), RTD (2 types), Direct current
	(2 types) and DC voltage (4 types), and the unit °C/°F.

Factory default value

Characters, Factory Default	Setting Item, Function, Setting Range						
5575 2005	<ul> <li>Input type</li> <li>Selects an input type from thermocouple (10 types), RTD (2 types), Direct current (2 types) and DC voltage (4 type), and the unit °C/F.</li> <li>When changing the input from DC voltage to other inputs, remove the sensor connected to this controller first, then change the input. If the input is changed with the sensor connected, the input circuit may break.</li> <li>When changing an input type, refer to Section "8.10 Items to be Initialized by Changing Settings" (p.96).</li> </ul>						
	• Selection item: └───└──└── K -200 to 1370°C	E	K -328 to 2498°F				
	<i>Е</i> . <i>Г</i> К -200.0 to 400.0℃	E□.F	K -328.0 to 752.0°F				
	⊿	J	J -328 to 1832°F				
	∠ R 0 to 1760℃	r[]]F	R 32 to 3200°F				
	հ⊒⊑ Տ 0 to 1760℃	B       0 to 1820℃       b       F       B       32 to 3308°F         E       -200 to 800℃       E       -328 to 1472°F         T       -200.0 to 400.0℃       Γ       .F       T       -328.0 to 752.0°F					
	N200 to 1300℃	PL-Ⅱ         0 to 1390°C         PL-I         32 to 2534°F           C(W/Re5-26)         0 to 2315°C         c □□F         C(W/Re5-26)         32 to 4199					
	· · · · · · · · · · · · · · · · · · ·						
	<i>₽Г . L</i> Pt100 -200.0 to 850.0°C	PF F	Pt100 -328.0 to1562.0°F				
	<i>J₽Г.</i> JPt100 -200.0 to 500.0℃	JPF,F	JPt100 -328.0 to 932.0°F				
	<i>₽Г</i> Pt100 -200 to 850℃		Pt100 -328 to 1562°F				
	<i>JP</i> Г <i>⊆</i> JPt100 -200 to 500°C	JPEF	JPt100 -328 to 932°F				
	<u> イビロ将</u> 4 to 20 mA DC -2000 to 10000	_					
	0 to 20 mA DC -2000 to 10000						
	□□ 18 0 to 1 V DC -2000 to 10000						
	□ 5 H 0 to 5 V DC -2000 to 10000						
	/ 5 H 1 to 5 V DC -2000 to 10000						
	□ I□ B 0 to 10 V DC -2000 to 10000						
45LH	Scaling high limit						
סרבו	Sets scaling high limit value.						
	<ul> <li>Setting range: Scaling low limit value to Input range high limit value DC voltage, current inputs: -2000 to 10000 (*1)</li> </ul>						
(*4) The surface service of the	placement of the decimal point follows the selection						

Characters, Factory Default	Setting Item, Function, Setting Range				
55LL	Scaling low limit				
-200		aling low limit value.			
	Setting r	<ul> <li>Setting range: Input range low limit value to Scaling high limit value DC voltage, current inputs: -2000 to 10000 (*1)</li> </ul>			
dP	Decimal	point place			
<u> </u>		decimal point place.			
	Selectio				
		No decimal point			
	0	1 digit after decimal point			
	0	2 digits after decimal point			
	0000	3 digits after decimal point			
	Available or	nly for DC voltage and current inputs			
E80 I		tput EV1 allocation			
		Event output EV1 from the Event Outp			
		nanging Event output EV1, refer to Sec	tion "8.10 Items to be Initialized by		
	•	Changes" (p.96).			
	Selectio				
		tput Allocation Table			
		No event			
		Alarm output, High limit alarm			
		Alarm output, Low limit alarm			
		Alarm output, High/Low limits alarm			
	<u> </u>	Alarm output, High/Low limits independent alarm			
	005	Alarm output, High/Low limit range			
		alarm			
	005				
	ר ס ס	Alarm output, Process high alarm			
	008	Alarm output, Process low alarm			
	009	Alarm output, High limit with standby alarm			
	0 10	Alarm output, Low limit with standby alarm			
		Alarm output, High/Low limits with standby alarm			
	0 IZ	Alarm output, High/Low limits with standby independent alarm			
	<u>□0</u> /3	Heater burnout alarm output			
	<u>□</u> 0 /4	Loop break alarm output			
	⊡0 /S	Time signal output	Turns OFF or ON during Program control, by setting OFF and ON times within the step set in [Step number].		
	0 15	Output during AT	Turns ON during AT.		
	רו ס	Pattern end output	Turns ON when Program control ends, and remains ON until turned OFF by pressing the <sup>(1)</sup> key.		
	0 <i>18</i>	Output by communication command	Turns OFF or ON by communication command 00E4H during Serial communication. B0 EV1 output 0: OFF 1: ON B1 EV2 output 0: OFF 1: ON		

Characters,					
Factory Default	Setting Item, Function, Setting Range				
R IER	EV1 alarm value 0 Enabled/Disabled				
	• When EV1 alarm value is 0 (zero), alarm action can be Enabled or Disabled.				
· · · · · · · · · · · · · · · · · · ·	Selection item:				
	Stabled				
		High limit alarm) to $\Box \Box \Box \Box \Box$ (Alarm output, High/Low limit range			
	independent alarm), $\Box DDS$ (Alarm output, High limit with standby alarm) to $\Box D$ 12 (Alarm output,				
		ent alarm) are selected in [Event output EV1 allocation].			
<i>A</i> /	EV1 alarm value				
<i>0</i>	Sets EV1 alarm value.				
	EV1 alarm value matches EV	1 low limit alarm value in the following cases:			
	[[] [[[[[[[[[[[] [[[[[[[[[[[] 대대 (대	/Low limits independent alarm), $\Box \Box \Box \Box \Xi \overline{\Sigma}$ (Alarm			
	output, High/Low limit range	independent alarm), or $\Box \Box \ / c$ (Alarm output,			
	High/Low limits with standby	vindependent alarm) is selected in [Event output EV1			
	allocation].				
	Setting range:				
	High limit alarm	-(Input span) to Input span °C (°F) (*1) (*2)			
	Low limit alarm	-(Input span) to Input span °C (°F) (*1) (*2)			
	High/Low limits alarm	0 to Input span °C (°F) (*1) (*2)			
	High/Low limits independent 0 to Input span °C (°F) (*1) (*2)				
	alarm				
	High/Low limit range alarm	0 to Input span °C (°F) (*1) (*2)			
	High/Low limit range	0 to Input span °C (°F) (*1) (*2)			
	independent alarm				
	Process high alarm	Input range low limit to Input range high limit (*1) (*3)			
	Process low alarm	Input range low limit to Input range high limit (*1) (*3)			
	High limit with standby alarm	-(Input span) to Input span °C (°F) (*1) (*2)			
	Low limit with standby alarm	-(Input span) to Input span °C (°F) (*1) (*2)			
	High/Low limits with standby	0 to Input span °C (°F) (*1) (*2)			
	alarm				
	High/Low limits with standby	0 to Input span °C (°F) (*1) (*2)			
	independent alarm				
	Available when any alarm from $\Box \Box \Box \Box$	(Alarm output, High limit alarm) to $\Box \mathcal{G} \not \mathcal{Z}$ (Alarm output, High/Low			
·····		is selected in [Event output EV1 allocation].			
	EV1 high limit alarm value				
	Sets EV1 high limit alarm value.				
	This value is available only for the following cases.				
		/Low limits independent alarm), $\Box\Box\Box\Delta$ (Alarm			
		independent alarm), or $\Box \Box \ \dot{L} \ \dot{L}$ (Alarm output,			
		r independent alarm) is selected in [Event output EV1			
	allocation].	o of Γ)/(1 clorm volue			
	Setting range: Same as those	e or Evil alarm value			

(\*2) For DC voltage, current inputs, the input span is the same as the scaling span.

(\*3) For DC voltage, current inputs, input range low (or high) limit value is the same as scaling low (or high) limit value.

Characters, Factory Default	Setting Item, Function, Setting Range
RIHY	EV1 alarm hysteresis
	Sets EV1 alarm hysteresis.
	• Setting range: 0.1 to 1000.0℃ (°F),
	DC voltage, current inputs: 1 to 10000 (*1)
	Available when any alarm from $\Box \mathcal{G} \mathcal{G}$ / (Alarm output, High limit alarm) to $\Box \mathcal{G}$ / $\mathcal{E}$ (Alarm output, High/Low
	limits with standby independent alarm) is selected in [Event output EV1 allocation].
R 189	EV1 alarm delay time
	Sets EV1 alarm action delay time.
	When setting time has elapsed after the input enters the alarm output range, the
	alarm is activated.
	Setting range: 0 to 10000 seconds
	Available when any alarm from $\Box G G$ / (Alarm output, High limit alarm) to $\Box G$ /2 (Alarm output, High/Low
	limits with standby independent alarm) is selected in [Event output EV1 allocation].
RILA	EV1 alarm Energized/De-energized
noñL	<ul> <li>Selects Energized/De-energized status for EV1 alarm.</li> </ul>
	(Refer to 'EV1/EV2 Energized/De-energized' on p.50.)
	Selection item:
	nand Energized
	ー E ビー De-energized
	Available when any alarm from $\Box \Box \Box \Box$ $l$ (Alarm output, High limit alarm) to $\Box \Box$ $l c$ (Alarm output, High/Low
_	limits with standby independent alarm) is selected in [Event output EV1 allocation].
/~~ /~	TS1 output step number
[]]]] /	Sets the step number at which Time signal output TS1 will be turned OFF or ON
	during Program control.
	(Refer to 'Time Signal Output' on p.52.)
	Setting range: 1 to 9
	Available only when $\Box G / S$ (Time signal output) is selected in [Event output EV1 allocation].
55 IF	TS1 OFF time
0000	Sets Time signal output TS1 OFF time.
	(Refer to 'Time Signal Output' on p.52.)
	• Setting range: 00:00 to 99:59 (*4)
	Available only when $\Box G / S$ (Time signal output) is selected in [Event output EV1 allocation].
[5]]	TS1 ON time
0000	Sets Time signal output TS1 ON time.
	(Refer to 'Time Signal Output' on p.52.)
	• Setting range: 00:00 to 99:59 (*4)
	Available only when $\Box G$ /5 (Time signal output) is selected in [Event output EV1 allocation].
(*1)The placement of th	ne decimal point follows the selection.

(\*4) Time unit follows the selection from [Step time unit].

Characters, Factory Default		Setting Item, Function, Setting Range			
EBo2	Event output EV2 allocation				
000	Selects Event output EV2 from the Event Output Allocation Table below.				
		hanging Event output EV2, refer to Sec			
		ig Settings" (p.96).			
	<ul> <li>Selectio</li> </ul>	n item:			
	Event Ou	Itput Allocation Table			
	$\Box 000$	No event			
	00 I	Alarm output, High limit alarm			
	002	Alarm output, Low limit alarm			
	003	Alarm output, High/Low limits alarm			
	004	Alarm output, High/Low limits			
		independent alarm			
	005	Alarm output, High/Low limit range alarm			
	005	Alarm output, High/Low limit range			
		independent alarm			
	C 0 0 1	Alarm output, Process high alarm			
	008	Alarm output, Process low alarm			
	003	Alarm output, High limit with standby alarm			
	0 10	Alarm output, Low limit with standby alarm			
	<i>□0 ; ;</i>	Alarm output, High/Low limits with standby alarm			
	0 IZ	Alarm output, High/Low limits with standby independent alarm			
	<u> </u>	Heater burnout alarm output			
	<u> </u>	Loop break alarm output			
	0 IS	Time signal output	Turns OFF or ON during Program control, by setting OFF and ON times within the step set in [Step		
			number].		
	0 16	Output during AT	Turns ON during AT.		
	רו ס	Pattern end output	Turns ON when Program control ends, and remains ON until turned OFF by pressing the <sup>(IIII</sup> ) key.		
	0 18	Output by communication command	Turns OFF or ON by communication command 00E4H during Serial communication. B0 EV1 output 0: OFF 1: ON B1 EV2 output 0: OFF 1: ON		
	0 19	Heating/Cooling control	Works as Control output OUT2		
	taand "	relay contact output	(Heating/Cooling control).		
	Available o	nly when Event output EV2 (EV2 option) is ordered			
8258 no	EV2 aları	<b>m value 0 Enabled/Disabled</b> V2 alarm value is 0 (zero), alarm action			
	- o	Disabled			
	9E 4	Enabled			
	Available only when Event output EV2 (EV2 option) is ordered. Available when $\Box \Box \Box \Box \downarrow$ (Alarm output, High limit alarm) to $\Box \Box \Box \Box \Xi$ (Alarm output, High/Low limit range				
	independent alarm), $\Box \Box \Box \Box$ (Alarm output, High limit alarm) to $\Box \Box \Box \Box \Box$ (Alarm output, High/Low limit range High/Low limits with standby independent alarm) are selected in [Event output EV2 allocation].				

Characters,	Setting	Item, Function, Setting Range			
Factory Default	EV2 alarm value				
	• Sets EV2 alarm value.				
1	EV2 alarm value matches EV2 low limit alarm value in the following cases:				
		Low limits independent alarm), $\Box \Box \Box \Box \Box $ (Alarm output,			
		ident alarm), or $\Box \mathcal{Q} \not\models \mathcal{Z}$ (Alarm output, High/Low limits			
		, <b>.</b>			
	with standby independent alarm) is selected in [Event output EV2 allocation]. <ul> <li>Setting range:</li> </ul>				
	High limit alarm	-(Input span) to Input span °C (°F) (*1) (*2)			
	Low limit alarm	-(Input span) to Input span $^{\circ}$ (°F) (*1) (*2)			
	High/Low limits alarm	0 to Input span °C (°F) (*1) (*2)			
	High/Low limits independent	0 to Input span $^{\circ}C$ (°F) (*1) (*2)			
	alarm				
	High/Low limit range alarm	0 to Input span ℃ (°F) (*1) (*2)			
	High/Low limit range	0 to Input span °C (°F) (*1) (*2)			
	independent alarm				
	Process high alarm	Input range low limit to Input range high limit (*1) (*3)			
	Process low alarm	Input range low limit to Input range high limit (*1) (*3)			
	High limit with standby alarm	-(Input span) to Input span °C (°F) (*1) (*2)			
	Low limit with standby alarm	-(Input span) to Input span °C (°F) (*1) (*2)			
	High/Low limits with standby       0 to Input span °C (°F) (*1) (*2)         High/Low limits with standby       0 to Input span °C (°F) (*1) (*2)         independent alarm       0 to Input span °C (°F) (*1) (*2)         Available only when Event output EV2 (EV2 option) is ordered.       0 to limit clean) to 100 / 70 / 70 (0 cm output limit clean) to 100 / 70 / 70 / 70 / 70 / 70 / 70 / 70				
	Available when any alarm from $\square \square \square \square \square$ (Alarm output, High limit alarm) to $\square \square \square \square \square$ (Alarm output, High/Low limits with standby independent alarm) is selected in [Event output EV2 allocation].				
R2H	EV2 high limit alarm value				
	Sets EV2 high limit alarm value.				
	This value is available only for the following cases:				
	□□□□디너 (Alarm output, High/	Low limits independent alarm), $\Box \Box \Box \Box B$ (Alarm output,			
	High/Low limit range indeper	ndent alarm), or $\Box \mathcal{Q} \not \in$ (Alarm output, High/Low limits			
	with standby independent ala	arm) is selected in [Event output EV2 allocation].			
	<ul> <li>Setting range: Same as those</li> </ul>	e of EV2 alarm value			
	Available only when Event output EV2	(EV2 option) is ordered.			
RSHR	EV2 alarm hysteresis				
	Sets EV2 alarm hysteresis.				
	• Setting range: 0.1 to 1000.0°				
	DC voltage, current inputs: 1				
	Available only when Event output EV2 Available when any alarm from $\Box \Box \Box$	(EV2 option) is ordered. (Alarm output, High limit alarm) to $\Box a / c$ (Alarm output, High/Low			
	limits with standby independent alarm) is selected in [Event output EV2 allocation].				
RSAA	EV2 alarm delay time				
<i>0</i>	Sets EV2 alarm action delay				
	•	ed after the input enters the alarm output range, the			
	alarm is activated.				
	<ul> <li>Setting range: 0 to 10000 set Available only when Event output EV2</li> </ul>				
		(Evz option) is ordered. (Alarm output, High limit alarm) to $\Box a / c$ (Alarm output, High/Low			
	2	is selected in [Event output EV2 allocation].			
(*1) The placement of t	the decimal point follows the selection.				

(\*2) For DC voltage, current inputs, the input span is the same as the scaling span.

(\*3) For DC voltage, current inputs, input range low (or high) limit value is the same as scaling low (or high) limit value.

Characters,	Softing Hom Europhics Softing Dense				
Factory Default	Setting Item, Function, Setting Range				
RZLA	EV2 alarm Energized/De-energized				
noñL	Selects Energized/De-energized status for EV2 alarm.				
	(Refer to '	EV1/EV2 Energized/De-energized' on p.50.)			
	<ul> <li>Selection</li> </ul>	item:			
	noñL	Energized			
	-E84	De-energized			
	Available only when Event output EV2 (EV2 option) is ordered.				
	Available whe	n any alarm from $\Box BB$ / (Alarm output, High limit alarm) to $\Box B$ /2 (Alarm output, High/Low			
	limits with star	ndby independent alarm) is selected in [Event output EV2 allocation].			
F424	TS2 output	t step number			
[]][]] <i>1</i>	<ul> <li>Sets the s</li> </ul>	tep number at which Time signal output TS2 will be turned OFF or ON			
	during Pro	gram control.			
	(Refer to '	Time Signal Output' on p.52.)			
	<ul> <li>Setting rail</li> </ul>	nge: 1 to 9			
	Available only	when $\Box 3$ /5 (Time signal output) is selected in [Event output EV2 allocation].			
F42F	TS2 OFF time				
0000	Sets Time signal output TS2 OFF time.				
	(Refer to 'Time Signal Output' on p.52.)				
	• Setting range: 00:00 to 99:59 (*4)				
	Available only when $\Box \mathcal{G}$ /5 (Time signal output) is selected in [Event output EV2 allocation].				
F420	TS2 ON time				
0000	<ul> <li>Sets Time</li> </ul>	signal output TS2 ON time.			
	(Refer to '	Time Signal Output' on p.52.)			
	<ul> <li>Setting rail</li> </ul>	nge: 00:00 to 99:59 (*4)			
	Available only	when $\Box\Box$ /5 (Time signal output) is selected in [Event output EV2 allocation].			
H /	Heater bur	nout alarm 1 value			
	<ul> <li>Sets the h</li> </ul>	eater current value for Heater burnout alarm 1.			
H I and CT1 current	Character	s $H$ / and CT1 current value are alternately indicated on the PV			
value are alternately	Display.				
indicated on the PV	When OUT1 is ON, the CT1 current value is updated.				
Display.	When OU	T1 is OFF, the unit memorizes the previous value when OUT1 was ON.			
	Upon retu	rning to set limits, the alarm will stop.			
	<ul> <li>Setting rail</li> </ul>	nge:			
	20 A: 0.0 f	to 20.0 A			
	100 A: 0.0	to 100.0 A			
	Setting to	0.0 disables the alarm.			
	Not available	for the Direct current output type.			
	Available whe	en Heater burnout alarm (C5W, EIW, W options) is ordered.			

(\*4) Time unit follows the selection from [Step time unit].

Characters, Factory Default	Setting Item, Function, Setting Range					
	Heater bu	Irnout alarm 2 value	•			
	Sets the heater current value for Heater burnout alarm 2.					
		e only when using 3-p				
H⋛ and CT2				Itomotoly india	ated on the PV Display.	
current value are				•	aleu un line PV Display.	
alternately		UT1 is ON, the CT2 o		-		
indicated on the		When OUT1 is OFF, the unit memorizes the previous value when OUT1 was ON.				
PV Display.		urning to set limits, th	ie alarm will sto	ρ.		
	0	Setting range:				
		to 20.0 A				
		0 to 100.0 A				
	_	0.0 disables the ala				
		e for the Direct current outp	51			
		ly when Heater burnout ala	rm (C5W, EIW, W op	otions) is ordered.		
	-	ak alarm time				
<i>0</i>		time to assess the Lo	•	1.		
		Loop Break Alarm' o	-			
	-	ange: 0 to 200 minute				
1 5 11	-	0 (zero) disables the	e alarm.			
LP_H	•	ak alarm span				
<i>0</i>		temperature to asses	•	ak alarm.		
		Loop Break Alarm' of	•	°C (°D)		
	-	ange: 0 to 150°C (°F)		C (F)		
		ge, current inputs: 0 t				
J <del>,</del> , , , , ,		0 (zero) disables the	e alarm.			
E81 1	-	ut DI1 allocation				
<b>000</b>		Event input DI1 from	•	cation lable.		
	•	'Event Input' on p.51	.)			
	Selection					
	Event Inp	ut Allocation Table				
		Event input	Input ON	Input OFF	Remarks	
		function	(Closed)	(Open)		
		No event				
		Set value memory				
	002	Control ON/OFF	Control OFF	Control ON	Control output OFF function	
	003	Direct/Reverse	Direct action	Reverse	Always effective	
		action		action		
	004	Preset output 1	Preset	Usual	If sensor is burnt out,	
		ON/OFF	output	control	the unit maintains	
					control with the	
	preset MV.					
	005	Preset output 2	Preset	Usual	The unit maintains	
		ON/OFF	output	control	control with the	
					preset MV.	
	005	Auto/Manual	Manual	Automatic	Effective when	
		control	control	control	Auto/Manual control	
					is selected in [OUT/	
					OFF key function].	

Characters, Factory Default	Setting Item, Function, Setting Range				
		Event input function	Input ON (Closed)	Input OFF (Open)	Remarks
	С007	Remote/Local	Remote	Local	Effective when External setting input (EIT option) is ordered.
	008	Program control RUN/STOP	RUN	STOP	Level action when power is turned on
	003	Program control Holding/Not holding	Holding	Not holding	Level action when power is turned on
	0 0	Program control Advance function	Advance function	Usual control	
		Integral action Holding vailable only when Event ir	Integral action Holding	Usual integral action	Control continues with the integral value being held.
					input (EIW, EIT, EI options) is
E812	<ul> <li>Event input DI2 allocation</li> <li>Selects Event input DI2 from Event Input Allocation Table. (Refer to 'Event Input' on p.51)</li> <li>Selection item: Same as those of Event input DI1 allocation</li> <li>For BCS2, available only when Event input (EIW, EI option) is ordered.</li> <li>For BCR2/BCD2, available when Serial communication (C5W option) or Event input (EIW, EIT, EI options) is</li> </ul>				
-FLH 1370	<ul> <li>ordered.</li> <li>External setting input high limit</li> <li>Sets External setting input high limit value. This value corresponds to 20 mA in Direct current input.</li> <li>Setting range: External setting input low limit to Input range high limit (*1) Available only when External setting input (EIT option) is ordered.</li> </ul>				
-FLL -200	<ul> <li>External setting input low limit</li> <li>Sets External setting input low limit value.</li> <li>This value corresponds to 4 mA in Direct current input.</li> <li>Setting range: Input range low limit to External setting input high limit (*1) Available only when External setting input (EIT option) is ordered.</li> </ul>				
Ггоч Р8	・Selects t ・When ch Initialized ・Selection アビー ンゼー ー	sion output type ransmission output ty anging transmission by Changing Settin item: PV transmission SV transmission MV transmission DV transmission	output type, re gs" (p.96).		3.10 Items to be

Characters, Factory Default	:	Setting Item, Function, Setting Range	
TELH	Transmission output high limit		
1370	Sets the Transmission output high limit value.		
	This value correponds to 20 mA in DC current output.		
	Setting range:		
	PV, SV transmission	Transmission output low limit to Input range high limit value	
		DC voltage, current inputs: -2000 to 10000	
	MV transmission	Transmission output low limit to 105.0%	
	DV transmission	Transmission output low limit to Scaling span (*1)	
	Available only when Transm	ission output (EIT option) is ordered.	
THLL	Transmission output		
-200	Sets the Transmissio	n output low limit value.	
	This value correpond	s to 4 mA in DC current output.	
	Selection item:	·	
	PV, SV transmission	Input range low limit to Transmission output high limit value	
		DC voltage, current inputs: -2000 to 10000	
	MV transmission	-5.0% to Transmission output high limit value	
	DV transmission	-Scaling span to Transmission output high limit value (*1)	
	Available only when Transm	ission output (EIT option) is ordered.	
<b>4</b>	SV1		
<i>0</i>	Sets SV1.		
	<ul> <li>Setting range: Scalin</li> </ul>	g low limit to Scaling high limit (*1)	
	Available when Control outp	ut OFF function or Auto/Manual control is selected in [OUT/OFF key function].	
4 <i>2</i>	SV2		
	Sets SV2.		
	<ul> <li>Setting range: Scalin</li> </ul>	g low limit to Scaling high limit (*1)	
	Available for the following ca	ases:	
		function or Auto/Manual control is selected in [OUT/OFF key function].	
		IW, EIT, EI options) is ordered. ommunication (C5W option) or Event input (EIW, EIT, EI options) is ordered.	
		memory) is selected in [Event input DI1/DI2 allocation].	
<i>└┐∃</i>	SV3		
	Sets SV3.		
	<ul> <li>Setting range: Scalin</li> </ul>	g low limit to Scaling high limit (*1)	
	Available for the following ca	ases:	
		function or Auto/Manual control is selected in [OUT/OFF key function].	
	For BCS2, Event input (E     For BCR2/BCD2, Serial c	IW, EI options) is ordered. ommunication (C5W option) or Event input (EIW, EIT, EI options) is ordered.	
		memory) is selected in [Event input D1/D12 allocation].	
<u> </u>	SV4		
<i>0</i>	Sets SV4.		
	Setting range: Scalin	g low limit to Scaling high limit (*1)	
	Available for the following ca	ases:	
		function or Auto/Manual control is selected in [OUT/OFF key function].	
	For BCS2, Event input (E     For BCR2/BCD2, Serial c	IW, EI options) is ordered ormunication (C5W option) or Event input (EIW, EIT, EI options) is ordered.	
		memory) is selected in [Event input DI1/DI2 allocation].	
(*1) The placement of t	he decimal point follows the se		

#### [EV1/EV2 Energized/De-energized]

When cacile (Energized) is selected, Event output 1 or 2 is conductive (ON) while the EV1/EV2 indicator is lit.

Event output 1 or 2 is not conductive (OFF) while the EV1/EV2 indicator is not lit.

When  $\neg \xi \exists \neg$  (De-energized) is selected, Event output 1 or 2 is not conductive (OFF) while the EV1/EV2 indicator is lit.

Event output 1 or 2 is conductive (ON) while the EV1/EV2 indicator is not lit.

# High limit alarm (when Energized is set) High limit alarm (when De-energized is set) ON OFF $\xrightarrow{EV1 \text{ hysteresis}}_{SV + EV1 \text{ value}}$ OFF $\xrightarrow{EV1 \text{ hysteresis}}_{SV + EV1 \text{ value}}$ OFF $\xrightarrow{EV1 \text{ hysteresis}}_{SV + EV1 \text{ value}}$ (Fig. 6.2-1) (Fig. 6.2-2)

EV1 value and EV1 hysteresis represent EV1 alarm value and EV1 alarm hysteresis respectively. For EV2, read "EV2" for "EV1".

#### [Loop Break Alarm]

#### When the control action is Reverse (Heating) control:

- If the PV does not **reach** the Loop break alarm span setting within the time allotted to assess the Loop break alarm (after the MV has reached 100% or the OUT high limit value), the alarm will be activated.
- Likewise, if the PV does not **drop to** the Loop break alarm span setting within the time allotted to assess the Loop break alarm (after the MV has reached 0% or the OUT low limit value), the alarm will be activated.

#### When the control action is Direct (Cooling) control:

- If the PV does not **drop to** the Loop break alarm span setting within the time allotted to assess the Loop break alarm (after the MV has reached 100% or the OUT high limit value), the alarm will be activated.
- Likewise, if the PV does not **reach** the Loop break alarm span setting within the time allotted to assess the Loop break alarm (after the MV has reached 0% or the OUT low limit value), the alarm will be activated.
- If Serial communication (C5W, C5 options) is ordered, status can be read by reading Status flag 1.

## [Event Input]

• If  $\Box \Box \Box \Box \Box \downarrow$  (Set value memory) is selected, the set value memory number will be as follows.

When only Event input DI1 is selected.

Set value memory number	SV1	SV2
DI1	Open	Closed

When only Event input DI2 is selected.

Set value memory number	SV1	SV2
DI2	Open	Closed

When both Event inputs DI1, DI2 are selected.

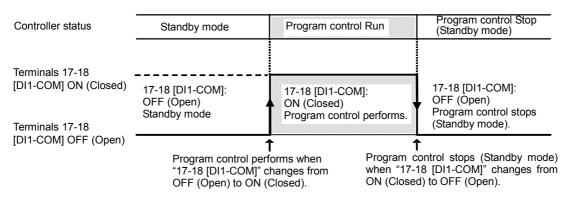
Set value memory number	SV1	SV2	SV3	SV4
DI1	Open	Closed	Open	Closed
DI2	Open	Open	Closed	Closed

- Preset value of  $\Box \Box \Box \Box \Box \Box$  (Preset output 1 ON/OFF) and  $\Box \Box \Box \Box \Box \Box$  (Preset output 2 ON/OFF) can be set in [OUT1, OUT2 MV preset value] in Engineering mode (p.77).
- If  $\Box \Box \Box \Box \Box$  (Preset output 2 ON/OFF) is selected in [Event input DI1 allocation], and  $\Box \Box \Box \Box$  (Auto/Manual control) is selected in Event input DI2 allocation, and if DI1-COM and DI2-COM terminals are turned ON (Closed) simultaneously, then Preset output 2 will be given priority, and control starts with the MV set in [OUT1/OUT2 MV preset value (p.77)] in Engineering mode. In this case, control will be switched to manual control, and MV cannot be changed via keypad.

• Signal edge action from OFF to ON / ON to OFF is engaged.

If  $\Box \Box \Box \Box \Box \Box B$  (Program control RUN/STOP) is selected in [Event input DI1 allocation], the following action will be performed.

However, only when power is turned ON, Level action is engaged - which follows the input status [ON (Closed) or OFF (Open)] of Event input DI1.



(Fig. 6.2-3)

- OR calculation [if any one is ON (closed), the function activates] begins if the same functions except DD / (Set value memory) have been selected in [Event input DI1/DI2 allocation]. If any terminals DI1-COM or DI2-COM is ON (closed), the function activates.
- If any function except  $\Box \Box \Box \Box \Box$  (Program control Advance function) is selected in [Event input DI1/DI2 allocation], Level action is engaged when power is turned ON which follows the input status [ON (Closed) or OFF (Open)] of Event input DI1/DI2.

#### [Time Signal Output]

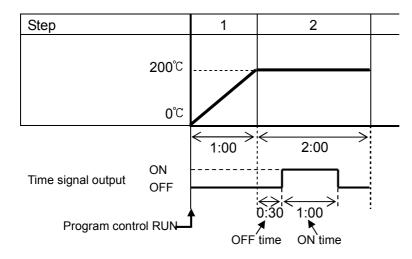
Time signal output activates during Time signal output ON time within the step (number). Time signal output ON time follows Time signal output OFF time after the program control starts.

The following program pattern shows that the temperature rises to  $200^{\circ}$  for 1 hour, and stays at  $200^{\circ}$  for 2 hours after Program control starts.

Step	1	2
Step SV	<b>200</b> ℃	<b>200</b> ℃
Step time	1:00	2:00

Time signal output (Fig. 6.2-4) is shown when set as follows.

- TS1/TS2 output step number: 2
- TS1/TS2 OFF time: 0:30
- TS1/TS2 ON time: 1:00





Time signal output is effective within the step set in [TS1/TS2 output step number]. For example, if TS1/TS2 ON time is set to "2:00" at the above, Time signal output is turned OFF at the moment when Step 2 is completed.

# 7. Settings

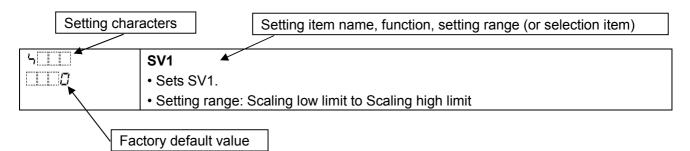
In this section, Main setting, Sub setting and Engineering modes will be explained.

### 7.1 Main Setting Mode

To enter Main setting mode, press the  $\bigcirc$  key in RUN mode. Use the  $\land$  or  $\checkmark$  key for settings (or selections). To register the set data, use the  $\bigcirc$  key.

Explanation of setting items:

- Upper left: PV Display: Indicates setting characters.
- Lower left: SV Display: Indicates factory default value.
- Right side: Indicates the setting item, explanation of its function and setting range (or selection item).



Characters, Factory Default	Setting Item, Function, Setting Range
4( <u></u>	SV1
	Sets SV1.
	Corresponds to [SV1] in Initial setting mode.
	If Program control is selected in [OUT/OFF key function], this will become Step 1
	SV.
	Setting range: Scaling low limit to Scaling high limit (*1)
ſ <u>□</u> _ /	Step 1 time
00.00	Sets Step 1 time.
	• Setting range:, or 00:00 to 99:59
	If is set, Step 1 time will be held, and Fixed value control will be performed
	using Step 1 SV.
	Available only when Program control is selected in [OUT/OFF key function].
J=_ /	Step 1 wait value
	Sets Step 1 wait value.
	Setting range: 0 to 20% of the input span
	DC voltage, current inputs: 0 to 20% of scaling span (*1)
	Setting the value to 0 disables this Wait function.
	Available only when Program control is selected in [OUT/OFF key function].

Characters, Factory Default	Setting Item, Function, Setting Range
42000	SV2
	• Sets SV2.
tan dan dan dan dan dan dan dan dan dan d	Corresponds to [SV2] in Initial setting mode.
	If Program control is selected in [OUT/OFF key function], this will become Step 2
	SV.
	Setting range: Scaling low limit to Scaling high limit (*1)
	Available for the following cases:
	When Program control is selected in [OUT/OFF key function]
	For BCS2, Event input (EIW, EIT, EI options) is ordered
	• For BCR2/BCD2, Serial communication (C5W option) or Event input (EIW, EIT, EI options) is ordered.
rn.a	When      GG / (Set value memory) is selected in [Event input DI1/DI2 allocation].      Step 2 time
0000	Sets Step 2 time.
	• Setting range:, or 00:00 to 99:59
	If is set, Step 2 time will be held, and Fixed value control will be performed
	using Step 2 SV.
	Available only when Program control is selected in [OUT/OFF key function].
<u> </u>	Step 2 wait value
<b></b>	Sets Step 2 wait value.
	Setting range: 0 to 20% of the input span
	DC voltage, current inputs: 0 to 20% of scaling span (*1)
	Setting the value to 0 disables Wait function.
	Available only when Program control is selected in [OUT/OFF key function].
5 <i>3</i>	SV3
<b></b> <i>0</i>	• Sets SV3.
	Corresponds to [SV3] in Initial setting mode.
	If Program control is selected in [OUT/OFF key function], this will become Step 3
	SV.
	Setting range: Scaling low limit to Scaling high limit (*1)
	Available for the following cases:
	When Program control is selected in [OUT/OFF key function]
	<ul> <li>For BCS2, Event input (EIW, EI options) is ordered</li> <li>For BCR2/BCD2, Serial communication (C5W option) or Event input (EIW, EIT, EI options) is ordered.</li> </ul>
	• When $\Box D I / (Set value memory) is selected in [Event input DI1/DI2 allocation].$
ГЭ	Step 3 time
0000	Sets Step 3 time.
	• Setting range: [-]-]-], or 00:00 to 99:59
	If EEEE is set, Step 3 time will be held, and Fixed value control will be performed
	using Step 3 SV.
	Available only when Program control is selected in [OUT/OFF key function].
JEL 3	Step 3 wait value
	• Sets Step 3 wait value.
	Setting range: 0 to 20% of the input span
	DC voltage, current inputs: 0 to 20% of scaling span (*1)
	Setting the value to 0 disables Wait function.
	Available only when Program control is selected in [OUT/OFF key function].
(*1) The placement of t	the decimal point follows the selection.

Characters,	Setting Item, Function, Setting Range
Factory Default	
54 <u></u>	SV4
	• Sets SV4.
	Corresponds to [SV4] in Initial setting mode.
	If Program control is selected in [OUT/OFF key function], this will become Step 4
	SV.
	Setting range: Scaling low limit to Scaling high limit (*1)
	Available for the following cases:
	When Program control is selected in [OUT/OFF key function]     For BCS2, Event input (EIW, EI options) is ordered
	<ul> <li>For BCR2/BCD2, Serial communication (C5W option) or Event input (EIW, EIT, EI options) is ordered.</li> </ul>
	When DD / (Set value memory) is selected in [Event input DI1/DI2 allocation].
Г <u> </u>	Step 4 time
0000	Sets Step 4 time.
	• Setting range:, or 00:00 to 99:59
	If is set, Step 4 time will be held, and Fixed value control will be performed
	using Step 4 SV.
	Available only when Program control is selected in [OUT/OFF key function].
J4	Step 4 wait value
	Sets Step 4 wait value.
	Setting range: 0 to 20% of the input span
	DC voltage, current inputs: 0 to 20% of scaling span (*1)
	Setting the value to 0 disables Wait function.
45	Available only when Program control is selected in [OUT/OFF key function].
	Step 5 SV
······································	• Sets Step 5 SV.
	Setting range: Scaling low limit to Scaling high limit (*1)
<i>T</i> S	Available only when Program control is selected in [OUT/OFF key function]. Step 5 time
0000	Sets Step 5 time.
	• Setting range:, or 00:00 to 99:59
	If is set, Step 5 time will be held, and Fixed value control will be performed
	using Step 5 SV.
	Available only when Program control is selected in [OUT/OFF key function].
<i>J</i> 5	Step 5 wait value
	Sets Step 5 wait value.
	Setting range: 0 to 20% of the input span
	DC voltage, current inputs: 0 to 20% of scaling span (*1)
	Setting the value to 0 disables Wait function.
	Available only when Program control is selected in [OUT/OFF key function].
	the decimal point follows the selection

Characters, Factory Default	Setting Item, Function, Setting Range
55 C	Step 6 SV
	Sets Step 6 SV.
	Setting range: Scaling low limit to Scaling high limit (*1)
	Available only when Program control is selected in [OUT/OFF key function].
ГШ_Б	Step 6 time
0000	Sets Step 6 time.
	• Setting range:, or 00:00 to 99:59
	If is set, Step 6 time will be held, and Fixed value control will be performed
	using Step 6 SV.
	Available only when Program control is selected in [OUT/OFF key function].
J _ 5	Step 6 wait value
	Sets Step 6 wait value.
	Setting range: 0 to 20% of the input span
	DC voltage, current inputs: 0 to 20% of scaling span (*1)
	Setting the value to 0 disables Wait function.
	Available only when Program control is selected in [OUT/OFF key function].
ら 7[[]]]	Step 7 SV
	Sets Step 7 SV.
	<ul> <li>Setting range: Scaling low limit to Scaling high limit (*1)</li> </ul>
	Available only when Program control is selected in [OUT/OFF key function].
<del>7</del> _ [] ۲	Step 7 time
0000	Sets Step 7 time.
	• Setting range:, or 00:00 to 99:59
	If is set, Step 7 time will be held, and Fixed value control will be performed
	using Step 7 SV.
	Available only when Program control is selected in [OUT/OFF key function].
	Step 7 wait value
	Sets Step 7 wait value.
	Setting range: 0 to 20% of the input span
	DC voltage, current inputs: 0 to 20% of scaling span (*1)
	Setting the value to 0 disables Wait function.
	Available only when Program control is selected in [OUT/OFF key function].

Characters, Factory Default	Setting Item, Function, Setting Range
<i>ら8</i>	Step 8 SV
	Sets Step 8 SV.
	Setting range: Scaling low limit to Scaling high limit (*1)
	Available only when Program control is selected in [OUT/OFF key function].
ſ <u></u> _8	Step 8 time
0000	Sets Step 8 time.
	• Setting range: [-]-]-], or 00:00 to 99:59
	If is set, Step 8 time will be held, and Fixed value control will be performed
	using Step 8 SV.
	Available only when Program control is selected in [OUT/OFF key function].
J8	Step 8 wait value
<u> </u>	Sets Step 8 wait value.
	Setting range: 0 to 20% of the input span
	DC voltage, current inputs: 0 to 20% of scaling span (*1)
	Setting the value to 0 disables Wait function.
	Available only when Program control is selected in [OUT/OFF key function].
5 <i>9</i>	Step 9 SV
	Sets Step 9 SV.
	<ul> <li>Setting range: Scaling low limit to Scaling high limit (*1)</li> </ul>
	Available only when Program control is selected in [OUT/OFF key function].
/ <u> </u>	Step 9 time
00.00	Sets Step 9 time.
	• Setting range: [-]-]-], or 00:00 to 99:59
	If is set, Step 9 time will be held, and Fixed value control will be performed
	using Step 9 SV.
	Available only when Program control is selected in [OUT/OFF key function].
<u> </u>	Step 9 wait value
	Sets Step 9 wait value.
	Setting range: 0 to 20% of the input span
	DC voltage, current inputs: 0 to 20% of scaling span (*1)
	Setting the value to 0 disables Wait function.
	Available only when Program control is selected in [OUT/OFF key function].

#### 7.2 Sub Setting Mode

To enter Sub setting mode, press the  $\land$  and  $\bigcirc$  keys (in that order) together in RUN mode. Use the  $\land$  or  $\checkmark$  key for settings (or selections).

To register the set data, use the  $\ensuremath{\mathbb{O}}$  key.

Explanation of setting items:

- Upper left: PV Display: Indicates setting characters.
- Lower left: SV Display: Indicates factory default value.
- Right side: Indicates the setting item, explanation of its function and setting range (or selection item).

Setting characters		Setting item name, function, setting range (or selection item)
AL	AT/Auto-reset P	erform/Cancel
	Selects AT or 'A	T on startup' Perform/Cancel in PID control, or Auto-reset
	Perform/Cancel	in P or PD control.

Factory default value

Characters, Factory Default	Setting Item, Function, Setting Range		
RE	AT/Auto-reset Perform/Cancel		
	Selects AT or 'AT on startup' Perform/Cancel in PID control action, or Auto-reset		
	Perform/Cancel in P or PD control action.		
	Refer to Sections '8.5 Setting PID Constants (by Performing AT)' (p. 82), and		
	'8.6 Performing Auto-reset' (p. 85).		
	Selection item:		
	AT/AT on startup/Auto-reset Cancel		
	AT Perform		
	려도 'AT on startup' Perform		
	ー っ と Auto-reset Perform		
	Not available for ON/OFF control or PI control.		
P	OUT1 proportional band		
III 10	Sets OUT1 proportional band.		
	• Setting range: 0 to Input span ℃ (°F)		
	DC voltage, current inputs: 0.0 to 1000.0%		
	OUT1 becomes ON/OFF control when set to 0 or 0.0.		
/	Integral time		
200	Sets the integral time.		
	Auto-reset can be performed when PD is control action $(I = 0)$ .		
	Setting range: 0 to 3600 seconds		
	Setting the value to 0 disables integral action.		
	Not available if OUT1 is in ON/OFF control.		
	Derivative time		
	Sets the derivative time.		
	Setting range: 0 to 1800 seconds     Setting the value to 0 dischlor derivative exting		
	Setting the value to 0 disables derivative action.		
	Not available if OUT1 is in ON/OFF control.		

Characters,	Setting Itom Function Setting Bange
Factory Default	Setting Item, Function, Setting Range
Ar J	ARW
	Sets ARW (anti-reset windup).
	Setting range: 0 to 100%
	Available only for PID control.
- <i>5</i> E F	Manual reset
	Sets the reset value manually.
	Setting range: ±Proportional band value
	If a value larger than 100.0% is set in [OUT1 proportional band], the setting range
	will be ±100.0.
	Available for P and PD controls.
<b>د</b>	OUT1 proportional cycle
<b>0</b>	Sets proportional cycle for OUT1.
Factory default: Relay contact	For relay contact output, if the proportional cycle time is decreased, the frequency
output: 30 sec.	of the relay action increases, and the life of the relay contact is shortened.
Non-contact	Setting range: 0.5, or 1 to 120 seconds
voltage output: 3 sec.	Not available for Direct current output type, or if OUT1 is in ON/OFF control.
<i>НУ</i> Ч	OUT1 ON/OFF hysteresis
	Sets ON/OFF hysteresis for OUT1.
	• Setting range: 0.1 to 1000.0°C (°F),
	DC voltage, current inputs: 1 to 10000 (*1)
	Available only when OUT1 is in ON/OFF control.
oLH	OUT1 high limit
🗆 <i>100</i>	Sets OUT1 high limit value.
	Setting range: OUT1 low limit value to 100%
	(Direct current output type: OUT1 low limit value to 105%)
	Not available if OUT1 is in ON/OFF control.
oll	OUT1 low limit
<u> </u>	Sets OUT1 low limit value.
	Setting range: 0% to OUT1 high limit value
	(Direct current output type: -5% to OUT1 high limit value)
	Not available if OUT1 is in ON/OFF control.
or AF	OUT1 rate-of-change
<i>0</i>	<ul> <li>Sets changing value of OUT1 MV for 1 second.</li> </ul>
	See 'OUT1 rate-of-change' on p. 63.
	Setting range: 0 to 100 %/second
	Setting the value to 0 disables this function.
	Not available if OUT1 is in ON/OFF control.

Characters,			
Factory Default	Setting Item, Function, Setting Range		
cRcT	OUT2 cooling method		
81 r	<ul> <li>Selects OUT2 cooling method from air, oil or water cooling.</li> </ul>		
	OUT2 proportional band		
	Air cooling		
	Oil cooling		
	Water cooling		
	SV SV		
	(Fig. 7.2-1)		
	Selection item:		
	Air cooling (linear characteristics)		
	□ Coll cooling (1.5th power of the linear characteristics)		
	<i>ū</i> 用F□ Water cooling (2nd power of the linear characteristics)		
	Available when Event output EV2 (EV2 option) or Heating/Cooling control (DS, DA options) is ordered.		
	Not available if OUT2 is in ON/OFF control.		
P_6	OUT2 proportional band		
(III) <i>10</i>	<ul> <li>Sets the proportional band for OUT2.</li> </ul>		
	• Setting range: 0 to Input span °C (°F)		
	DC voltage, current inputs: 0.0 to 1000.0%		
	If the proportional band is set to 0 or 0.0, OUT2 becomes ON/OFF control, and the		
	item selected in [OUT2 cooling method] will be disabled.		
	Available when Event output EV2 (EV2 option) or Heating/Cooling control (DS, DA options) is ordered.		
<u></u> 5	OUT2 proportional cycle		
<b></b> 30	Sets proportional cycle for OUT2.		
Factory default:	For relay contact output, if the proportional cycle time is decreased, the frequency		
EV2(*2): 30 sec.	of the relay action increases, and the life of the relay contact is shortened.		
DS: 3 sec.	Setting range: 0.5, or 1 to 120 seconds		
	Available when Event output EV2 (EV2 option) or Heating/Cooling control (DS, DA options) is ordered.		
	Not available for Direct current output type, or if OUT2 is in ON/OFF control.		
<i>Н</i> УЧБ	OUT2 ON/OFF hysteresis		
	Sets ON/OFF hysteresis for OUT2.		
	• Setting range: 0.1 to 1000.0°C (°F),		
	DC voltage, current inputs: 1 to 10000 (*1)		
	Available when Event output EV2 (EV2 option) or Heating/Cooling control (DS, DA options) is ordered.		
oLH6	OUT2 high limit		
🗆 <i>100</i>	Sets OUT2 high limit value.		
	Setting range: OUT2 low limit value to 100%		
	(Direct current output type: OUT2 low limit value to 105%)		
	Available when Event output EV2 (EV2 option) or Heating/Cooling control (DS, DA options) is ordered.		
(*1) The placement of t	he decimal point follows the selection.		

(\*2) When  $\square \mathcal{O}$  / $\mathcal{G}$  (Heating/Cooling control relay contact output) is selected in [Event output EV2 allocation]}.

Characters,	Setting Item, Function, Setting Range			
Factory Default	OUT2 low limit			
	Sets OUT2 low limit value.			
·····	Setting range: 0% to OUT2 h	igh limit value		
	(Direct current output type: -5% to OUT2 high limit value)			
	Available when Event output EV2 (EV2 option) or Heating/Cooling control (DS, DA options) is ordered.			
db	Overlap/Dead band			
<i>0</i>	<ul> <li>Sets the overlap band or dear</li> </ul>	d band for OUT1 and OUT2.		
	+ Set value: Dead band			
	<ul> <li>Set value: Overlap band</li> </ul>			
	• Setting range: -200.0 to 200.0	°C (°F),		
	DC voltage, current inputs: -2	2000 to 2000 (*1)		
	Available when Event output EV2 (EV2	2 option) or Heating/Cooling control (DS, DA options) is ordered.		
conf	Direct/Reverse action			
неяг		ing) or Direct (Cooling) control action.		
	HERF Reverse (Heatin			
	cool Direct (Cooling)	action		
	EV1 alarm value			
	<ul> <li>Sets EV1 alarm value.</li> </ul>			
	Corresponds to [EV1 alarm value] in Initial setting mode.			
		1 low limit alarm value in the following cases:		
	$\Box \Box \Box \Box \forall$ (Alarm output, High/Low limits independent alarm), $\Box \Box \Box \Box \delta$ (Alarm			
	output, High/Low limit range independent alarm), or $\Box \Box \not = i$ (Alarm output,			
	High/Low limits with standby independent alarm) is selected in [Event output EV1			
	allocation].  • Setting range:			
	High limit alarm	-(Input span) to Input span °C (°F) (*1) (*2)		
	Low limit alarm	-(Input span) to input span $\circ$ (1) (1) (2)		
	High/Low limits alarm	0 to Input span °C (°F) (*1) (*2)		
	High/Low limits independent	0 to Input span °C (°F) (*1) (*2)		
	alarm			
	High/Low limit range alarm	0 to Input span ℃ (°F) (*1) (*2)		
	High/Low limit range	0 to Input span °C (°F) (*1) (*2)		
	independent alarm			
	Process high alarm	Input range low limit to Input range high limit (*1) (*3)		
	Process low alarm	Input range low limit to Input range high limit (*1) (*3)		
	High limit with standby alarm	-(Input span) to Input span °C (°F) (*1) (*2)		
	Low limit with standby alarm	-(Input span) to Input span °C (°F) (*1) (*2)		
	High/Low limits with standby	0 to Input span ℃ (°F) (*1) (*2)		
	alarm			
	High/Low limits with standby	0 to Input span °C (°F) (*1) (*2)		
	independent alarm			
	Available when any alarm from $\Box \Box \Box$ .	(Alarm output, High limit alarm) to $\Box \mathcal{G} \not \mathcal{L}$ (Alarm output, High/Low		
	limits with standby independent alarm)	is selected in [Event output EV1 allocation].		

(\*1) The placement of the decimal point follows the selection.(\*2) For DC voltage, current inputs, the input span is the same as the scaling span.

(\*3) For DC voltage, current inputs, input range low (or high) limit value is the same as scaling low (or high) limit value.

Characters,			
Factory Default	Setting Item, Function, Setting Range		
R IH	EV1 high limit alarm value		
<i>0</i>	Sets EV1 high limit alarm value.		
	This value is available only for the following cases:		
	$\Box\Box\Box\Box$ (Alarm output, High/Low limits independent alarm), $\Box\Box\Box\Box$ (Alarm		
	output, High/Low limit range independent alarm), or $\Box \Box J J c$ (Alarm output,		
	High/Low limits with standby independent alarm) is selected in [Event output EV1		
	allocation].		
	Corresponds to [EV1 high limit alarm value] in Initial setting mode.		
	Setting range: Same as those of EV1 alarm value		
82	EV2 alarm value		
	Sets EV2 alarm value.		
	Corresponds to [EV2 alarm value] in Initial setting mode.		
	EV2 alarm value matches EV2 low limit alarm value in the following cases:		
	$\Box \Box \Box \Box \Box \downarrow 4$ (Alarm output, High/Low limits independent alarm), $\Box \Box \Box \Box \Box \Box$ (Alarm		
	output, High/Low limit range independent alarm), or $\Box D   l  \vec{c} $ (Alarm output		
	High/Low limits with standby independent alarm) is selected in [Event output EV2		
	allocation].		
	Setting range: Same as those of EV1 alarm value		
	Available only when $\Box \Box \Box \Box I$ (Alarm output, High limit alarm) to $\Box \Box I I I$ (Alarm output, High/Low limits with		
······	standby independent alarm) is selected in [Event output EV2 allocation].		
R2H	EV2 high limit alarm value		
	Sets EV2 high limit alarm value.		
	This value is available only for the following cases:		
	$\Box \Box \Box \Box \Box \downarrow$ (Alarm output, High/Low limits independent alarm), $\Box \Box \Box \Box \Box$ (Alarm		
	output, High/Low limit range independent alarm), or $\Box J \downarrow \vec{c}'$ (Alarm output,		
	High/Low limits with standby independent alarm) is selected in [Event output EV2		
	allocation].		
	Corresponds to [EV2 high limit alarm value] in Initial setting mode.		
	Setting range: Same as those of EV1 alarm value		
H I	Heater burnout alarm 1 value		
	• Sets the heater current value for Heater burnout alarm 1.		
H I and CT1	Corresponds to [Heater burnout alarm 1 value] in Initial setting mode.		
current value are	Characters <i>H</i> / and CT1 current value are indicated alternately on the PV Display.		
alternately	When OUT1 is ON, the CT1 current value is updated.		
indicated on the	When OUT1 is OFF, the unit memorizes the previous value when OUT1 was ON.		
PV Display.	Upon returning to set limits, the alarm will stop.		
	Setting range:     20.0 A: 0.0 to 20.0 A		
	100.0 A: 0.0 to 100.0 A		
	Setting to 0.0 disables the alarm.		
	Not available for direct current output type.		
	Available only when Heater burnout alarm (C5W, EIW, W options) is ordered.		

Characters,	Sotting Itom Eurotion Sotting Pango
Factory Default	Setting Item, Function, Setting Range
H2 and CT2 current value are alternately indicated on the PV Display.	<ul> <li>Heater burnout alarm 2 value</li> <li>Sets the heater current value for Heater burnout alarm 2. Available only when using 3-phase. Corresponds to [Heater burnout alarm 2 value] in Initial setting mode. Characters He<sup>2</sup> and CT2 current value are indicated alternately on the PV Display.</li> <li>When OUT1 is ON, the CT2 current value is updated.</li> <li>When OUT1 is OFF, the unit memorizes the previous value when OUT1 was ON. Upon returning to set limits, the alarm will stop.</li> <li>Setting range: 20.0 A: 0.0 to 20.0 A 100.0 A: 0.0 to 100.0 A Setting to 0.0 disables the alarm. Not available for direct current output type.</li> </ul>
	<ul> <li>Available only when Heater burnout alarm (C5W, EIW, W options) is ordered.</li> <li>Loop break alarm time <ul> <li>Sets the time to assess the Loop break alarm.</li> <li>Corresponds to [Loop break alarm time] in Initial setting mode.</li> <li>Refer to 'Loop Break Alarm' on p.50.</li> <li>Setting range: 0 to 200 minutes</li> <li>Setting to 0 (zero) disables the alarm.</li> </ul> </li> </ul>
LP_H []]]0	<ul> <li>Loop break alarm span</li> <li>Sets the temperature to assess the Loop break alarm. Corresponds to [Loop Break alarm span] in Initial setting mode. Refer to 'Loop Break Alarm' on p.50.</li> <li>Setting range: 0 to 150°C (°F), 0.0 to 150.0°C (°F) DC voltage, current inputs: 0 to 1500 (*1) Setting to 0 (zero) disables the alarm.</li> </ul>

 $(\ensuremath{^\star 1})$  The placement of the decimal point follows the selection.

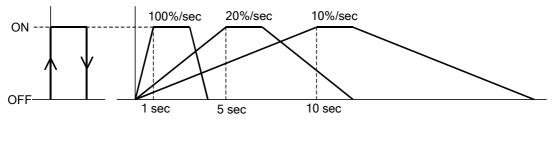
#### [OUT1 rate-of-change]

For Heating control, if PV is lower than SV, the output is generally turned from OFF to ON as shown in (Fig. 7.2-2).

If OUT1 rate-of-change is set, the output can be changed by the rate-of-change (Fig. 7.2-3).

This control is suitable for high temperature heaters (which are made from molybdenum, tungsten or platinum, etc., and used at approx. 1500 to  $1800^{\circ}$ C) which are easily burnt out from turning on electricity rapidly.

Usual output
 Output when Output rate-of-change is set



(Fig. 7.2-2) (Fig. 7.2-3)

#### 7.3 Engineering Mode

To enter Engineering mode, press and hold the  $\wedge$  and  $\vee$  keys (in that order) together for 3 seconds in RUN mode.

Use the  $\land$  or  $\checkmark$  key for settings (or selections).

To register the set data, use the  $\bigcirc$  key.

Explanation of setting items:

- Upper left: PV Display: Indicates setting characters.
- Lower left: SV Display: Indicates factory default value.
- Right side: Indicates the setting item, explanation of its function and setting range (or selection item).

Setting chara	cters Setting item name, function, setting range (or selection item)		
Lock	Set value lock		
	Locks the set values to prevent setting errors.		
	The setting item to be locked depends on the selection.		

Factory default value

Characters, Factory Default	Setting Item, Function, Setting Range			
Loct	Set value lock			
	Locks t	he set va	lues to prevent setting errors.	
	The se	tting item	to be locked depends on the select	tion.
	Selecti	on item:		
			Change via Keypad	Change via Software Communication
		Unlock	All set values can be changed.	All set values can be
	Loc I	Lock 1	None of the set values can be changed.	changed.
	Loc2	Lock 2	In Fixed value control, only SV and Alarm value can be changed. In Program control, Step SV, Step time and Alarm value can be changed.	
	Loc∃	Lock 3	All set values can be changed.	Setting items – except Input
	Loc4	Lock 4	None of the set values can be changed.	type, Controller/Converter – can be changed temporarily
	Loc5	Lock 5	In Fixed value control, only SV and Alarm value can be changed. In Program control, Step SV,	via software communication. However, if power is turned ON again, the setting values
			Step time and Alarm value can be changed.	revert to the values before Lock 3, 4 or 5 was selected.

Characters, Factory Default	Setting Item, Function, Setting Range					
EBI I	Event input DI1 allocation					
000	Selects Event input DI1 from the Event Input Allocation Table.					
		onds to [Event inpu	•			
	Selection		· · · · · · · · · · · · · · · · · · ·			
	Event In	put Allocation Tab	le			
		Event input Input ON Input OFF			Develo	
		function	(Closed)	(Open)	Remarks	
	$\Box 000$	No event				
	00 I	Set value memory				
	002	Control ON/OFF	Control OFF	Control ON	Control output OFF	
					function	
	003 E 00	Direct/Reverse	Direct action	Reverse	Always effective	
		action		action		
	004	Preset output 1	Preset output	Usual control	If sensor is burnt	
		ON/OFF			out, the unit	
					maintains control	
					with the preset MV.	
	005	Preset output 2	Preset output	Usual control	The unit maintains	
		ON/OFF			control with the	
	005				preset MV.	
	<u> </u>	Auto/Manual	Manual	Automatic	Effective when	
		control	control	control	Auto/Manual control	
					is selected in [OUT/ OFF key function].	
	- DO	Remote/Local	Remote	Local	Effective when	
		Remote/Local	Remote	LUCAI	External setting	
					input (EIT option) is	
					ordered.	
	008	Program control	RUN	STOP	Level action when	
		RUN/STOP			power is turned on	
	009	Program control	Holding	Not holding	Level action when	
		Holding/Not			power is turned on	
		holding				
	<i>□0 10</i>	Program control Advance function	Advance function	Usual control		
		Integral action	Integral action	Usual	Control continues	
		holding	holding	integral action	with the integral	
					value being held.	
	For BCS2, available only when Event input (EIW, EIT, EI options) is ordered. For BCR2/BCD2, available when Serial communication (C5W option) or Event input (EIW, EIT, EI ordered.					
E81 2		put DI2 allocation				
000	Selects Event input DI2 from the Event Input Allocation Table.					
	Corresponds to [Event input DI2 allocation] in Initial setting mode.					
	Selection item: Same as Event input DI1 allocation					
	For BCS2, available only when Event input (EIW, EI options) is ordered. For BCR2/BCD2, available when Serial communication (C5W option) or Event input (EIW, EIT, EI options)					
					put (EIW, EIT, EI options) is	
<u> </u>	ordered.					

Characters,	Setting Item, Function, Setting Range			
Factory Default		Setting item, runction, S	eung Kange	
E8o /	Event output EV1 allocation			
	Selects	Event output EV1 from the Event Outp	ut Allocation Table below.	
	Corresponds to [Event output EV1 allocation] in Initial setting mode.			
	When changing Event output EV1 allocation, refer to Section "8.10 Items to be			
	Initialize	d by Changing Settings" (p.96).		
	Selection item:			
		tput Allocation Table		
		No event		
	00 I	Alarm output, High limit alarm		
	002	Alarm output, Low limit alarm		
	<i>□003</i>	Alarm output, High/Low limits alarm		
	004	Alarm output, High/Low limits		
		independent alarm		
	005	Alarm output, High/Low limit range		
		alarm		
	005	Alarm output, High/Low limit range		
		independent alarm		
	007	Alarm output, Process high alarm		
		Alarm output, Process low alarm		
	009	Alarm output, High limit with standby		
	0 10	Alarm output, Low limit with standby		
	□0 ; ;	Alarm output, High/Low limits with standby alarm		
	<u> </u>	Alarm output, High/Low limits		
		with standby independent alarm		
		Heater burnout alarm output		
	014	Loop break alarm output		
	0 /5	Time signal output	Turns OFF or ON during Program	
			control, by setting OFF and ON	
			times within the step set in [Step	
	0 15	Output during AT	number]. Turns ON during AT.	
		Pattern end output	Turns ON when Program control	
			ends, and remains ON until turned	
			OFF by pressing the <sup>®</sup> key.	
	0 18	Output by communication	Turns OFF or ON by communication	
		command	command 00E4H during Serial	
			communication.	
			B0 EV1 output 0: OFF	
			1: ON	
			B1 EV2 output 0: OFF	
			1: ON	
		m value 0 Enabled/Disabled		
~o[]]]		V1 alarm value is 0 (zero), alarm action		
	-	onds to [EV1 alarm value 0 Enabled/Di	sabled in initial setting mode.	
	Selectio			
		Disabled		
		Enabled	305 (Alorm output Lliph/Low limit reaso	
	Available when $\Box \Box \Box \Box I$ (Alarm output, High limit alarm) to $\Box \Box \Box \Box \Box E$ (Alarm output, High/Low independent alarm), $\Box \Box \Box \Box S$ (Alarm output, High limit with standby alarm) to $\Box \Box I Z$ (Alarm			
	-	in [Event output EV1 allocation].		

Characters, Factory Default	Setting	Setting Item, Function, Setting Range		
R /	EV1 alarm value			
	Sets EV1 alarm value.			
	Corresponds to [EV1 alarm value] in Initial setting mode.			
	EV1 alarm value matches EV1 low limit alarm value in the following cases:			
		h/Low limits independent alarm), $\Box D D B$ (Alarm		
	output, High/Low limit rang	e independent alarm), or $\Box \mathcal{I} \not \in$ (Alarm output,		
	High/Low limits with standby independent alarm) is selected in [Event output EV1			
	allocation].			
	Setting range:			
	High limit alarm	-(Input span) to Input span °C (°F) (*1) (*2)		
	Low limit alarm	-(Input span) to Input span °C (°F) (*1) (*2)		
	High/Low limits alarm	0 to Input span <sup>°</sup> C ( <sup>°</sup> F) (*1) (*2)		
	High/Low limits independent	0 to Input span ℃ (°F) (*1) (*2)		
	alarm			
	High/Low limit range alarm	0 to Input span ℃ (°F) (*1) (*2)		
	High/Low limit range	0 to Input span <sup>°</sup> C (°F) (*1) (*2)		
	independent alarm			
	Process high alarm	Input range low limit to Input range high limit (*1) (*3)		
	Process low alarm Input range low limit to Input range high limit (*1) (*3)			
	High limit with standby alarm-(Input span) to Input span $^{\circ}C$ ( $^{\circ}F$ ) (*1) (*2)			
	Low limit with standby alarm -(Input span) to Input span °C (°F) (*1) (*2)			
	High/Low limits with standby 0 to Input span °C (°F) (*1) (*2)			
	alarm High/Low limits with standby 0 to Input span °C (°F) (*1) (*2)			
	independent alarm			
	Available when any alarm from $\Box \Box \Box$	/ (Alarm output, High limit alarm) to $\Box \mathcal{G} \not\models$ (Alarm output, High/Low		
	limits with standby independent alarm	is selected in [Event output EV1 allocation].		
R IH	EV1 high limit alarm value			
<i>D</i>	<ul> <li>Sets EV1 high limit alarm va</li> </ul>	lue.		
	This value is available only for	or the following cases:		
	· · · · ·	h/Low limits independent alarm), $\Box \Box \Box \Box \Xi E$ (Alarm		
		le independent alarm), $\Box \Box ~ l \stackrel{\sim}{_{\sim}} $ (Alarm output,		
	High/Low limits with stand	by independent alarm) is selected in [Event output EV1		
	allocation].			
		nit alarm value] in Initial setting mode.		
	Setting range: Same as those of EV1 alarm value			
A IHY	EV1 alarm hysteresis			
	• Sets EV1 alarm hysteresis.			
		nysteresis] in Initial setting mode.		
	• Setting range: 0.1 to 1000.0°			
	DC voltage, current inputs: 1			
		$l$ (Alarm output, High limit alarm) to $\Box \mathcal{I} \ l \mathcal{I}$ (Alarm output, High/Low		
	limits with standby independent alarm) he decimal point follows the selection.	is selected in [Event output EV1 allocation].		

(\*1) The placement of the decimal point follows the selection.(\*2) For DC voltage, current inputs, the input span is the same as the scaling span.

(\*3) For DC voltage, current inputs, input range low (or high) limit value is the same as scaling low (or high) limit value.

Characters, Factory Default	Setting Item, Function, Setting Range			
8 139	EV1 alarm delay time			
<i>D</i>	Sets EV1 al	arm action delay time.		
		s to [EV1 alarm delay time] in Initial setting mode.		
		g time has elapsed after the input enters the alarm output range, the		
	alarm is acti			
	• •	e: 0 to 10000 seconds		
		any alarm from $\Box \Box \Box \Box$ / (Alarm output, High limit alarm) to $\Box \Box$ /2 (Alarm output, High/Low		
		by independent alarm) is selected in [Event output EV1 allocation].		
A ILA		nergized/De-energized		
noñL		rgized/De-energized status for EV1 alarm.		
	-	s to [EV1 alarm Energized/De-energized] in Initial setting mode.		
	•	/1/EV2 Energized/De-energized' on p.50.)		
	Selection ite			
	noñL	Energized		
	-685	De-energized		
	Available when a	any alarm from $\Box DD$ / (Alarm output, High limit alarm) to $\Box D$ /2 (Alarm output, High/Low		
	limits with stand	by independent alarm) is selected in [Event output EV1 allocation].		
<u>, , , , , , , , , , , , , , , , , , , </u>	TS1 output s	step number		
		p number for which Time signal output TS1 is turned OFF or ON		
	during Prog	ram control.		
	-	s to [TS1 output step number] in Initial setting mode.		
	<ul> <li>Setting range</li> </ul>	je: 1 to 9		
		hen $\Box \mathcal{G}$ /5 (Time signal output) is selected in [Event output EV1 allocation].		
	TS1 OFF tim	-		
0000	<ul> <li>Sets Time s</li> </ul>	ignal output TS1 OFF time.		
	-	Corresponds to [TS1 OFF time] in Initial setting mode.		
	• Setting range: 00:00 to 99:59 (*4)			
	Available only when $\Box G / S$ (Time signal output) is selected in [Event output EV1 allocation].			
F5 10	TS1 ON time			
0000	Sets Time s	ignal output TS1 ON time.		
	Correspond	s to [TS1 ON time] in Initial setting mode.		
	Setting range	ge: 00:00 to 99:59 (*4)		
	Available only w	hen $\Box \mathcal{C}$ /5 (Time signal output) is selected in [Event output EV1 allocation].		
(*4) Time unit follows th	e selection from IS	e selection from [Step time unit].		

Characters, Factory Default	Setting Item, Function, Setting Range				
E802	Event output EV2 allocation				
000		Event output EV2 from the Event Outp	ut Allocation Table below.		
	Corresponds to [Event output EV2 allocation] in Initial setting mode.				
	• When changing Event output EV2, refer to Section "8.10 Items to be Initialized				
		ging Settings" (p.96).			
	Selection item:				
	Event Ou				
	000	No event			
	001	Alarm output, High limit alarm			
	002	Alarm output, Low limit alarm			
	003	Alarm output, High/Low limits alarm			
	004	Alarm output, High/Low limits			
		independent alarm			
	005	Alarm output, High/Low limit range			
		alarm			
	005	Alarm output, High/Low limit range			
		independent alarm			
	ר סס	Alarm output, Process high alarm			
	008	Alarm output, Process low alarm			
	009	Alarm output, High limit with			
		standby alarm			
	0 10	Alarm output, Low limit with			
		standby alarm			
		Alarm output, High/Low limits			
		with standby alarm			
	0 IZ	Alarm output, High/Low limits			
	0 13	with standby independent alarm Heater burnout alarm output			
		Loop break alarm output			
		Time signal output	Turns OFF or ON during Program control, by setting OFF and ON		
			times within the step set in [Step		
			number].		
	0 15		1		
		Output during AT Pattern end output	Turns ON during AT. Turns ON when Program control		
			ends, and remains ON until turned		
			OFF by pressing the   key.		
	0 18	Output by communication	Turns OFF or ON by communication		
		command	command 00E4H during Serial		
		Command	communication.		
			B0 EV1 output 0: OFF		
			1: ON		
			B1 EV2 output 0: OFF		
			1: ON		
	0 19	Heating/Cooling control	Works as Control output OUT2		
	hand the second second	relay contact output	(Heating/Cooling control).		
	Available o	nly when Event output EV2 (EV2 option) is ordered			

Characters,	Setting Item, Function, Setting Range		
Factory Default			
R2IR no[]]	<ul> <li>EV2 alarm value 0 Enabled/Disabled</li> <li>When EV2 alarm value is 0 (zero), alarm action can be Enabled or Disabled. Corresponds to [EV2 alarm value 0 Enabled/Disabled] in Initial setting mode.</li> <li>Selection item:</li> </ul>		
	Stabled		
	Available only when Event output EV2 (EV2 option) is ordered. Available when $\Box \Box \Box \Box I$ (Alarm output, High limit alarm) to $\Box \Box \Box \Box \Box I$ (Alarm output, High/Low limit range independent alarm), $\Box \Box \Box \Box I$ (Alarm output, High limit with standby alarm) to $\Box \Box I I$ (Alarm output, High/Low limits with standby independent alarm) are selected in [Event output EV2 allocation].		
82	EV2 alarm value		
	<ul> <li>Sets EV2 alarm value.</li> </ul>	Sets EV2 alarm value.	
	Corresponds to [EV2 alarm value] in Initial setting mode.		
	EV2 alarm value matches EV2 low limit alarm value in the following cases: $\Box D D \forall$ (Alarm output, High/Low limits independent alarm), $\Box D D \delta$ (Alarm output, High/Low limit range independent alarm), or $\Box D \forall d$ (Alarm output, High/Low limits with standby independent alarm) is selected in [Event output EV2 allocation].		
	Setting range:		
	High limit alarm	-(Input span) to Input span °C (°F) (*1) (*2)	
	Low limit alarm	-(Input span) to Input span $\ ^{\circ}C \ (^{\circ}F) \ (^{\ast}1) \ (^{\ast}2)$	
	High/Low limits alarm	0 to Input span °C (°F) (*1) (*2)	
	High/Low limits independent alarm	0 to Input span °C (°F) (*1) (*2)	
	High/Low limit range alarm	0 to Input span °C (°F) (*1) (*2)	
	High/Low limit range	0 to Input span ℃ (°F) (*1) (*2)	
	independent alarm		
	Process high alarm	Input range low limit to Input range high limit (*1) (*3)	
	Process low alarm	Input range low limit to Input range high limit (*1) (*3)	
	High limit with standby alarm	-(Input span) to Input span °C (°F) (*1) (*2)	
	Low limit with standby alarm	-(Input span) to Input span °C (°F) (*1) (*2)	
	High/Low limits with standby alarm	0 to Input span ℃ (°F) (*1) (*2)	
	High/Low limits with standby independent alarm	0 to Input span ℃ (°F) (*1) (*2)	
	-	<sup>1</sup> /2 (EV2 option) is ordered. <sup>1</sup> / (Alarm output, High limit alarm) to $\Box a / c$ (Alarm output, High/Low n) is selected in [Event output EV2 allocation].	
82H0	<ul><li>EV2 high limit alarm value</li><li>Sets EV2 high limit alarm value.</li></ul>		
kan ada ana dana di Santa	This value is available only for the following cases:		
	$\Box \Box \Box \Box \Box \downarrow A$ (Alarm output, High/Low limits independent alarm), $\Box \Box \Box \Box \Box \Box$ (Alarm output, High/Low limit range independent alarm), or $\Box \Box \downarrow Z$ (Alarm output, High/Low limits with standby independent alarm) is selected in [Event output EV2]		
	allocation].		
	<ul> <li>Corresponds to [EV2 high limit alarm value] in Initial setting mode.</li> <li>Setting range: Same as those of EV2 alarm value</li> </ul>		
	<ul> <li>Setting range: Same as thos Available only when Event output EV2</li> </ul>		
	,	· · · /	

(\*2) For DC voltage, current inputs, the input span is the same as the scaling span.

(\*3) For DC voltage, current inputs, input range low (or high) limit value is the same as scaling low (or high) limit value.

Characters,	Setting Item, Function, Setting Range		
Factory Default 유근유달	EV/O slavna hustana sia		
	EV2 alarm hysteresis		
(	• Sets EV2 alarm hysteresis.		
	Corresponds to [EV2 alarm hysteresis] in Initial setting mode. • Setting range: 0.1 to 1000.0°C (°F), DC voltage, current inputs: 1 to 10000 (*1)		
	Available only when Event output EV2 (EV2 option) is ordered.		
	Available when any alarm from $\Box \Box \Box \Box l$ (Alarm output, High limit alarm) to $\Box \Box l l l c$ (Alarm output, High/Low		
	limits with standby independent alarm) is selected in [Event output EV2 allocation].		
8249	EV2 alarm delay time		
	Sets EV2 alarm action delay time.		
	Corresponds to [EV2 alarm delay time] in Initial setting mode.		
	When setting time has elapsed after the input enters the alarm output range, the		
	alarm is activated.		
	Setting range: 0 to 10000 seconds     Available only when Event output EV2 (EV2 option) is ordered.		
	Available when any alarm from $\Box \Box \Box \Box$ / (Alarm output, High limit alarm) to $\Box \Box \Box$ /2 (Alarm output, High/Low		
, , , , , ,	limits with standby independent alarm) is selected in [Event output EV2 allocation].		
RELA	EV2 alarm Energized/De-energized		
noñL	<ul> <li>Selects Energized/De-energized status for EV2 alarm.</li> </ul>		
	Corresponds to [EV2 alarm Energized/De-energized] in Initial setting mode.		
	Refer to 'EV1/EV2 Energized/De-energized' (p.50).		
	Selection item:		
	nont Energized		
	ーEBト De-energized		
	Available only when Event output EV2 (EV2 option) is ordered.         Available when any alarm from $\Box \Box \Box I$ (Alarm output, High limit alarm) to $\Box \Box I I$ (Alarm output, High/Low		
	limits with standby independent alarm) is selected in [Event output EV2 allocation].		
1424	TS2 output step number		
[]]]] /	<ul> <li>Sets the step number for which Time signal output TS2 is turned OFF or ON</li> </ul>		
	during Program control.		
	Corresponds to [TS2 output step number] in Initial setting mode.		
	Setting range: 1 to 9		
	Available only when $\Box B$ /5 (Time signal output) is selected in [Event output EV2 allocation].		
F 42F	TS2 OFF time		
0000	Sets Time signal output TS2 OFF time.		
	Corresponds to [TS2 OFF time] in Initial setting mode.		
	• Setting range: 00:00 to 99:59 (*4)		
	Available only when $\Box 2$ /5 (Time signal output) is selected in [Event output EV2 allocation].		
[42a	TS2 ON time		
0000	Sets Time signal output TS2 ON time.		
	Corresponds to [TS2 ON time] in Initial setting mode.		
	• Setting range: 00:00 to 99:59 (*4)		
	Available only when $\Box a$ /5 (Time signal output) is selected in [Event output EV2 allocation].		
(*1) The placement of t	the decimal point follows the selection.		

(\*1) The placement of the decimal point follows the selection. (\*4) Time unit follows the selection from [Step time unit].

Characters, Factory Default		Setting Item, Function, Setting Range	
50E	Sensor correction coefficient		
1000	Sets sensor correction coefficient.		
	Sets slope of input value from a sensor.		
	PV after sensor correction= Current PV x (Sensor correction coefficient) +		
	(Sensor correction value)		
	Refer to Section '9.1 Input Value Correction' (p. 97).		
	• Setting range: -10.000 to 10.000		
50	Sensor correction		
	This corrects the input value from the sensor.		
	When a sensor cannot be set at the exact location where control is desired, the		
	sensor-measured temperature may deviate from the temperature in the controlled		
	location. When using plural controllers, sometimes the measured temperatures do not		
	concur due to differences in sensor accuracy or dispersion of load capacities. In such a		
	case, the control can be set at the desired temperature by adjusting the input value of		
	sensors.		
	PV after sensor correction= Current PV x (Sensor correction coefficient) + (Sensor correction value)		
	Refer to Section '9.1 Input Value Correction' (p.97).		
	• Setting range: -1000.0 to $1000.0^{\circ}$ C (°F)		
	DC voltage, current inputs: -10000 to 10000 (*1)		
FILT	PV filter time constant		
	Sets PV filter time constant.		
	If the value is set too high, it affects control results due to the delay of response.		
	Setting ran	Setting range: 0.0 to 10.0 seconds	
674L	Communication protocol		
noñL	Selects communication protocol.		
		Selection item:	
	noñL	Shinko protocol	
	ñodR	Modbus ASCII	
	ñadr	Modbus RTU	
	Available only	when Serial communication (C5W, C5 options) is ordered.	
cñno	Instrument number		
		strument number.	
	The instrument numbers should be set one by one when multiple instruments are		
	connected in Serial communication, otherwise communication is impossible.		
	Setting range: 0 to 95		
(+4) The share (-5)	Available only when Serial communication (C5W, C5 options) is ordered. he decimal point follows the selection.		

 $(\ensuremath{^\star 1})$  The placement of the decimal point follows the selection.

Proceeding       Communication speed $2\bar{n}5P$ Selects a communication speed equal to that of the host computer. $355$ 9600 bps $352$ 1920 bps $354$ 38400 bps         Available only when Serial communication (C5W, C5 options) is ordered. $c\bar{n}5f$ Data bit/Parity $354$ Selects data bit and parity. $5$ Selects data bit and parity.       Selection item: $8\bar{n}an$ 8 bits/No parity $3can$ 8 bits/No parity $3can$ 8 bits/Vo parity $8\bar{c}dn$ 8 bits/Cdd $7add$ 7 bits/No parity $8cdn$ 8 bits/Odd $7add$ 7 bits/Odd         Available only when Serial communication (C5W, C5 options) is ordered. $c\bar{n}5f$ Selects the stop bit. $5$ Selects the stop bit.       Selects the stop bit. $5$ Selects the stop bit.       Selection item: $11$ 1 bit $12$ 2 bits $4$ vailable only when Serial communication (C5W, C5 options) is ordered. $c\bar{n}5f$ 1 bit $12$ 2 bits $4$ valiable only when Ser	Characters,	Setting Item, Function, Setting Range		
95       • Selects a communication speed equal to that of the host computer.         95       9600 bps         192       19200 bps         384       38400 bps         Available only when Serial communication (C5W, C5 options) is ordered.         2587       Data bit/Parity         * Selection item:       *         8 non       8 bits/No parity         * Selection item:       *         8 non       8 bits/No parity         * Selection item:       *         8 non       8 bits/No parity         * Selection item:       *         8 non       8 bits/No parity         * Selection item:       *         8 non       7 bits/No parity         8 50 non       8 bits/Obd         * non       7 bits/No parity         8 add       8 bits/Odd         * add       8 bits/Odd         * add       7 bits/Odd         Available only when Serial communication (C5W, C5 options) is ordered.         * Selection item:       *	Factory Default			
$ \begin{array}{c c c c c c c c c c c c c c c c c c c $		-		
35       9600 bps         192       19200 bps         384       38400 bps         Available only when Serial communication (C5W, C5 options) is ordered.         CAFF       Data bit/Parity         Selects data bit and parity.         • Selection item:         Baan       8 bits/No parity         7.nan       7 bits/No parity         8.25 Un       8 bits/Even         7.6 Un       7 bits/No parity         8.25 Un       8 bits/Odd         7.add       7 bits/Odd         Available only when Serial communication (C5W, C5 options) is ordered.         CANT       Selects the stop bit.         • Selection item:       • Selection item:         11       1 bit         12.2       2 bits         Available only when Serial communication (C5W, C5 options) is ordered.         CANT       • Selects the stop bit.         • Selection item:       • Selection item:         11       1 bit         12.2       2 bits         Available only when Serial communication (C5W, C5 options) is ordered.         CANT       • Response delay time         • Response from the controller can be delayed after receiving command from the host computer.				
192       19200 bps         384       38400 bps         Available only when Serial communication (C5W, C5 options) is ordered.         2587       Data bit/Parity         3584       Selects data bit and parity.         Selection item:       Selection item:         Selection item:       Selects data bits/No parity         7.nan       7 bits/No parity         8 bits/No parity       Selection item:         Selection item:       Selection item:         Selection item:       Selection item:         7.nan       7 bits/No parity         SEB:       8 bits/Odd         7.add       7 bits/Even         Sedd       8 bits/Odd         7.add       7 bits/Odd         Available only when Serial communication (C5W, C5 options) is ordered.         Selection item:       Selection item:         11       1 bit         122       2 bits         Available only when Serial communication (C5W, C5 options) is ordered.         Section item:       Section item:         112       1 bit         122       2 bits         Available only when Serial communication (C5W, C5 options) is ordered.         Section item:       Section item:         122				
ごろちい       38400 bps         Available only when Serial communication (C5W, C5 options) is ordered.         Data bit/Parity         'Selects data bit and parity.         ·Selects data bit and parity.         ·Selection item:         Bran       8 bits/No parity         'Trans       7 bits/No parity         'Trans       7 bits/No parity         'Trans       7 bits/No parity         'Trans       7 bits/Even         Badd       8 bits/Leven         'Tadd       7 bits/Odd         Available only when Serial communication (C5W, C5 options) is ordered.         Stop bit       · Selects the stop bit.         · Selection item:       · Selection item:         '''       ''''         '''       ''''         '''       '''         '''       '''         '''       '''         '''       '''         '''       '''         '''       '''         '''       '''         '''       '''         '''       ''''         '''       ''''         '''       ''''         '''       ''''         ''''       ''''''' <t< th=""><th></th><th></th><th>•</th></t<>			•	
Available only when Serial communication (C5W, C5 options) is ordered.         こうちて         フを出っ         フを出っ         Selects data bit and parity.         Selection item:         日本のの         日本のの         Bits/No parity         フロのの         フレのの         フロのの         フレのの         フロのの         フレのの         Stop bit         Selects the stop bit.         Selection item:         コレック         シレック <td< th=""><th></th><th></th><th></th></td<>				
C ホ ら ら い い い い い い い い い い い い い い い い い			•	
기を出っ       • Selects data bit and parity.         ・ Selection item:         日本のの       8 bits/No parity         ブルロの       7 bits/No parity         夏を見か       8 bits/Even         ブを見か       7 bits/Even         夏を見か       7 bits/Even         夏を見か       7 bits/Odd         ブロログ       7 bits/Odd         インallable only when Serial communication (C5W, C5 options) is ordered.         ミージン       Selection item:         ゴログ       1 bit         ゴログ       1 bit         ゴログ       2 bits         Available only when Serial communication (C5W, C5 options) is ordered.         Cガdゲ       Response delay time         ・ Response from the controller can be delayed after receiving command from the host computer.	_ = = = = =	-		
Selection item:     Bnon 8 bits/No parity     Inon 7 bits/No parity     Response delay time     Response from the controller can be delayed after receiving command from the host computer.			-	
Bnon       8 bits/No parity         Inon       7 bits/No parity         BEBn       8 bits/Even         IEBn       7 bits/Even         Bodd       8 bits/Odd         Idd       7 bits/Odd         Available only when Serial communication (C5W, C5 options) is ordered.         Stop bit       • Selects the stop bit.         • Selects the stop bit.       • Selection item:         IIII       1 bit         IIIII       2 bits         Available only when Serial communication (C5W, C5 options) is ordered.         Response delay time         • Response delay time         • Response from the controller can be delayed after receiving command from the host computer.				
ブロロロ       7 bits/No parity         夏を出口       8 bits/Even         ブを出口       7 bits/Even         夏点点点       8 bits/Odd         ブロ点点       7 bits/Odd         Available only when Serial communication (C5W, C5 options) is ordered.         Stop bit       • Selects the stop bit.         • Selection item:       • Selection item:         □□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□				
$3 E B n$ 8 bits/Even $7 E B n$ 7 bits/Even $3 a d d$ 8 bits/Odd $7 a d d$ 7 bits/Odd         Available only when Serial communication (C5W, C5 options) is ordered. $2 n h^{7}$ Stop bit         • Selects the stop bit.       • Selection item: $1 h h^{7}$ 1 h h $2 h h^{7}$ 2 bits         Available only when Serial communication (C5W, C5 options) is ordered. $2 h h^{7}$ 1 h h $4 h h^{7}$ 1 h h $4 h h^{7}$			· · ·	
ブミゼホ       7 bits/Even         渇っぱぱ       8 bits/Odd         ブっぱぱ       7 bits/Odd         イャailable only when Serial communication (C5W, C5 options) is ordered.         シボッド       Stop bit         ・ Selects the stop bit.         ・ Selection item:         ゴーゴ       1 bit         ゴーゴ       1 bit         ゴーゴ       2 bits         Available only when Serial communication (C5W, C5 options) is ordered.         アンボッド       1 bit         ゴーゴ       2 bits         Available only when Serial communication (C5W, C5 options) is ordered.         アンボッド       Response delay time         ・ Response from the controller can be delayed after receiving command from the host computer.				
超点点点       8 bits/Odd         ブロ点点点       7 bits/Odd         Available only when Serial communication (C5W, C5 options) is ordered.         Stop bit         · Selects the stop bit.         · Selection item:         · Response delay time         · Response from the controller can be delayed after receiving command from the host computer.				
idd       7 bits/Odd         Available only when Serial communication (C5W, C5 options) is ordered.         Stop bit         • Selects the stop bit.         • Selection item:         idd         iddd         idddd         idddddddd         iddddddddddddddddddddddddddddddddddd				
Available only when Serial communication (C5W, C5 options) is ordered.         ここうご         Stop bit         • Selects the stop bit.         • Selection item:         □□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□				
こうう「       Stop bit         · Selects the stop bit.         · Selection item:         · Selection item:         · · · · · · · · · · · · · · · · · · ·				
· Selects the stop bit.         · Selection item:         · Available only when Serial communication (C5W, C5 options) is ordered.         · Response delay time         · Response from the controller can be delayed after receiving command from the host computer.	-, ,-		when Serial communication (C5W, C5 options) is ordered.	
<ul> <li>Selection item:</li> <li>1 bit</li> <li>2 bits</li> <li>Available only when Serial communication (C5W, C5 options) is ordered.</li> </ul> Response delay time <ul> <li>Response from the controller can be delayed after receiving command from the host computer.</li> </ul>		•		
こここ!       1 bit         こここ!       2 bits         Available only when Serial communication (C5W, C5 options) is ordered.         Available only when Serial communication (C5W, C5 options) is ordered.         Response delay time         ・Response from the controller can be delayed after receiving command from the host computer.		•		
Image: Constraint of the controller can be delayed after receiving command from the host computer.				
Available only when Serial communication (C5W, C5 options) is ordered.         ここうゴゴ       Response delay time         ・Response from the controller can be delayed after receiving command from the host computer.				
Cond H       Response delay time         • Response from the controller can be delayed after receiving command from the host computer.				
• Response from the controller can be delayed after receiving command from the host computer.				
host computer.		•	•	
		•	, ,	
If Response delay time is changed via software communication, the changed delay		•		
		-		
time will be reflected immediately.				
Setting range: 0 to 1000 ms		•	-	
		Available only when Serial communication (C5W, C5 options) is ordered.		
		SVTC bias		
	······································	Control desired value (SV) adds SVTC bias value to the value received by the		
SVTC command.				
• Setting range: ±20% of the input span		-		
DC voltage, current inputs: ±20% of the scaling span (*1)		J		
Available when Shinko protocol is selected in [Communication protocol].				
	-535	Available when Serial communication (C5W, C5 options) is ordered.		
Selects Remote (Remote operation) or Local (keypad operation) setting of the SV.		Remote/Local  • Selects Remote (Remote operation) or Local (keypad operation) setting of the SV		
Selection item:				
rEnt Remote				
Available only when External setting input (EIT option) is ordered.				

(\*1) The placement of the decimal point follows the selection.

Characters, Factory Default		Setting Item, Function, Setting Range	
- Г L H	External setting inpu	t high limit	
סרבו	Sets External setting input high limit value.		
	Ŭ	nds to 20 mA in Direct current input.)	
	· ·	nal setting input low limit to Input range high limit	
		al setting input (EIT option) is ordered.	
FFLL	External setting inpu	t low limit	
-200	Sets External setting	input low limit value.	
	(This value correspor	nds to 4 mA in Direct current input.)	
	Setting range: Input	range low limit to External setting input high limit	
	Available only when Externa	al setting input (EIT option) is ordered.	
-5_6	Remote bias		
	<ul> <li>During remote action</li> </ul>	, SV includes the remote bias value.	
	Setting range: ±20%		
	DC voltage, current ir	nputs: $\pm 20\%$ of the scaling span (*1)	
	Available only when Externa	Il setting input (EIT option) is ordered.	
[- <u>a</u> 5	Transmission output		
PB	Selects the transmiss		
	•••	smission output type, refer to Section "8.10 Items to be	
	Initialized by Changi	ng Settings" (p.96).	
	Selection item:		
	PU transr		
	SV transr		
	<i>売</i> と MV transi		
	러닝 DV transr		
ГгЦН		hission output (EIT option) is ordered.	
1370	Transmission output	n output high limit value.	
		ds to 20 mA in Direct current output.)	
	Setting range:		
	PV, SV transmission	Transmission output low limit to Input range high limit value	
	MV transmission	Transmission output low limit to 105.0%	
	DV transmission	Transmission output low limit to Scaling span (*1)	
		ission output (EIT option) is ordered.	
[-LL	Transmission output low limit		
-200	-	n output low limit value.	
	(This value correpon	ds to 4 mA in Direct current output.)	
	Setting range:		
	PV, SV transmission	Input range low limit to Transmission output high limit value	
	MV transmission	-5.0% to Transmission output high limit value	
	DV transmission	-Scaling span to Transmission output high limit value (*1)	
	Available only when Transm	ission output (EIT option) is ordered.	
	Step time unit		
āl n	Selects the Step time unit for the Program control.		
	Selection item:		
		Minutes	
	<u> '-Εc</u> Minute	s:Seconds	
	Available only when Program	n control is selected in [OUT/OFF key function].	

 $(^{\star}1)$  The placement of the decimal point follows the selection.

Characters, Factory Default	Setting Item, Function, Setting Range	
PrEF	Power restore action	
45 <i>6</i> 2	• Selects the program status if a power failure occurs mid-program and it is restored.	
	Selection item:	
	Stops after power is restored.	
	Continues (resumes) after power is restored.	
	HoLd Suspends (on hold) after power is restored.	
	Available only when Program control is selected in [OUT/OFF key function].	
5_58	Program start temperature	
0	Sets the step temperature when Program control starts.	
	Setting range: Scaling low limit value to Scaling high limit value (*1)	
	Available only when Program control is selected in [OUT/OFF key function].	
5_56	Program control start type	
P B C C C	Selects the Program control start type.	
	Selection item:	
	PV start	
	PBr PVR start	
	らど start	
	Available only when Program control is selected in [OUT/OFF key function].	
-886	Number of repetitions	
<i>0</i>	Sets the number of repetitions for Program control.	
	Setting range: 0 to 10000 times	
	Available only when Program control is selected in [OUT/OFF key function].	
-855	SV Rise/Fall rate start type	
585F	• When control output is turned from OFF to ON, or switched from Manual to	
	Automatic control, SV start or PV start can be selected for SV rise rate or fall rate	
	action.	
	• When power is turned ON, PV start is adopted for SV Rise/Fall rate action,	
	regardless of the selected type.	
	Selection item:	
	<u> ちおちに</u> SV start	
	PB57 PV start	
- 85 U	SV rise rate	
	• Sets SV rise rate (rising value for 1 minute).	
	When the SV is adjusted, it approaches the new SV by the preset rate-of-change (°C/min, °F/min).	
	When the power is turned on, the control starts from the PV, and approaches the	
	SV by the rate-of-change ( $^{\circ}$ /min, $^{\circ}$ F/min).	
	• Setting range: 0 to 10000 °C/min (°F/min)	
	Thermocouple, RTD inputs with a decimal point: 0.0 to 1000.0 °C/min (°F/min)	
	DC voltage, current inputs: 0 to 10000/min	
	Setting to 0 or 0.0 disables this function.	

 $(^{\star}1)$  The placement of the decimal point follows the selection.

Characters,	Setting Item, Function, Setting Range		
Factory Default	SV fall rate		
······	• Sets SV fall rate (falling value for 1 minute).		
	When the SV is adjusted, it approaches the new SV by the preset rate-of-change $\binom{C}{2}$ (min $\frac{C}{2}$ (min). When the neuron is turned on the central starts from the DV and		
	(°C/min, °F/min). When the power is turned on, the control starts from the PV and $(^{\circ}C/min)$ (°C/min) °F/min)		
	approaches the SV by the rate-of-change (°C/min, °F/min).		
	• Setting range: 0 to 10000 °C/min (°F/min)		
	Thermocouple, RTD inputs with a decimal point: 0.0 to 1000.0 °C/min (°F/min)		
	DC voltage, current inputs: 0 to 10000/min		
1771 J J (~~~)	Setting to 0 or 0.0 disables this function.		
P58 cc	Indication when control output OFF		
off	Selects the indication when control output is OFF.		
	Selection item:		
	OFF indication		
	RoFF No indication		
	PV indication		
	PBBL PV indication + Any Alarm active		
86_6	AT bias		
	Sets bias value for the AT.		
	AT point is automatically determined by the deviation between PV and SV.		
	Refer to Section '8.5 Setting PID Constants (by performing AT)' (p.82).		
	• Setting range: 0 to 50°C (0 to 100°F) or		
	0.0 to 50.0°℃ (0.0 to 100.0°F)		
	Available only for PID control.		
	Not available for DC voltage, current inputs		
8615	AT gain		
	• Sets proportional band ratio calculated by performing AT or 'AT on startup'.		
	Setting range: 0.1 to 10.0 times		
EeUF	Output status when input errors occur		
off	Selects the output status when input errors occur.		
	Selection item:		
	Output OFF		
	Output ON		
	Available for Direct current and voltage inputs, and Direct current output.		
ARAU	OUT/OFF key function		
oFF	Selects OUT/OFF key function.		
	Selection item:		
	Control output OFF function		
	- Ā吊っ U Auto/Manual control		
	Profa Program control		
	Auto/Manual after power interruption		
RUFa	• When the power to the controller is turned ON, selects whether the unit starts using		
	Automatic control or Manual control.		
	Selection item:		
	Automatic control       Automatic control		
	Available only when Auto/Manual control is selected in [OUT/OFF key function].		

Characters, Factory Default		Setting Item, Function, Setting Range	
FI AE	Indication time		
00.00	Sets time from no operation status until Displays are switched off.		
	Displays relig	ght by pressing any key while Displays are unlit.	
	When input e	error (Overscale, Underscale) or burnout has occurred, Displays are	
	lit, and error	codes are displayed.	
	If errors are	cancelled, Displays are unlit after indication time has passed again.	
	<ul> <li>Setting range</li> </ul>	e: 00:00 to 60:00 (Minutes:Seconds)	
	When set to	00:00, Displays remain ON.	
P47 (	OUT1 MV pre	set value	
	<ul> <li>If 'Preset out</li> </ul>	put 1 ON/OFF' or 'Preset output 2 ON/OFF' is selected in [Event	
	input allocati	on], OUT1 MV can be set.	
	Preset outp	ut 1 ON/OFF:	
	If sensor is MV.	burnt out during Event Input ON, control is performed with the preset	
		ut 2 ON/OFF:	
	-	t input is ON, control is performed with the preset MV.	
		e: 0.0 to 100.0% (Direct current output: -5.0 to 105.0%)	
	For BCS2, available only when Event input (EIW, EIT, EI options) is ordered.		
	For BCR2/BCD2, ordered.	available when Serial communication (C5W option) or Event input (EIW, EIT, EI options) is	
PSEZ	OUT2 MV pre	set value	
	-	put 1 ON/OFF' or 'Preset output 2 ON/OFF' is selected in [Event	
		on], OUT2 MV can be set.	
	-	ut 1 ON/OFF:	
	If sensor is	burnt out during Event Input ON, control is performed with the preset	
	<ul> <li>MV.</li> <li>Preset output 2 ON/OFF:</li> <li>When Event input is ON, control is performed with the preset MV.</li> <li>Setting range: 0.0 to 100.0% (Direct current output: -5.0 to 105.0%)</li> <li>Available for the following cases:</li> <li>For BCS2, Event output EV2 (EV2 option), Heating/Cooling control (DS, DA) or Event input (EIW, EIT, EI options) is ordered.</li> <li>For BCR2/BCD2, Event output EV2 (EV2 option), Heating/Cooling control (DS, DA), Serial communication</li> </ul>		
	,	r Event input (EIW, EIT, EI options) is ordered.	
FUnc	• When $\Box I I I$ (Heating/Cooling control relay contact output) is selected in [Event output EV2 allocation].		
cofr	Selects either controller or converter function.		
	Selection ite		
		Controller	
	en 8F	Converter	
	Available only wh	en OUT1 is Direct current output.	

# 8. Operation and Settings of Standard Functions

#### 8.1 Selecting an input type

Select an input type in [Input type] in Initial setting mode.

#### Selection item:

Selection item	•		
E	K -200 to 1370 ℃	E	K -328 to 2498 °F
E	K -200.0 to 400.0 °C	E□ .F	K -328.0 to 752.0 °F
	J -200 to 1000 ℃	J	J -328 to 1832 °F
- []][[	R 0 to 1760 ℃	r[]]F	R 32 to 3200 °F
500 C	S 0 to 1760 °C	'	S 32 to 3200 °F
<u>ь</u>	B 0 to 1820 °C	6F	B 32 to 3308 °F
E	E -200 to 800 ℃	E	E -328 to 1472 °F
E	T -200.0 to 400.0 ℃	ГШ , <b>F</b>	T -328.0 to 752.0 °F
	N -200 to 1300 ℃	n F	N -328 to 2372 °F
PLZE	PL-Ⅱ 0 to 1390 °C	PLZE	PL-Ⅱ 32 to 2534 °F
c	C(W/Re5-26) 0 to 2315 ℃	c F	C(W/Re5-26) 32 to 4199 °F
PF E	Pt100 -200.0 to 850.0 ℃	PF F	Pt100 -328.0 to 1562.0 °F
JPF.E	JPt100 -200.0 to 500.0 ℃	JPEE	JPt100 -328.0 to 932.0 °F
Priic	Pt100 -200 to 850 ℃	PTEF	Pt100 -328 to 1562 °F
JPFE	JPt100 -200 to 500 ℃	JPEE	JPt100 -328 to 932 °F
4208	4 to 20 mA DC -2000 to 10000		
020A	0 to 20 mA DC -2000 to 10000		
0 IB	0 to 1 V DC -2000 to 10000		
0058	0 to 5 V DC -2000 to 10000		
/ <u></u> 58	1 to 5 V DC -2000 to 10000		
0 108	0 to 10 V DC -2000 to 10000		

Factory default value is K -200 to 1370℃.

# (Example) Selecting K -200.0 to 400.0℃

Power ON	
↓	
2s	RUN mode
	PV/SV Display
<b>↓</b>	3 sec)
4874	Initial setting mode
E	Input type
v ∧ or √	×
5875	<i>上</i> . <i>L</i> : к -200.0 to 400.0℃
E .C	
<b>↓</b> © (Muli	tiple times) or © (3 sec)
25	RUN mode
0	PV/SV Display

#### 8.2 Selecting PID Control or ON/OFF Control

Selects PID or ON/OFF control action.

Select PID or ON/OFF control action in [OUT1 proportional band] in Sub setting mode. If 'OUT1 proportional band' is set to 0 (zero), the unit performs ON/OFF control action. Factory default value is PID control.

#### **PID control**

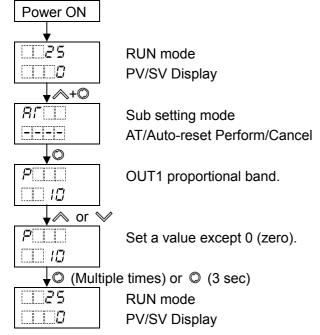
Proportional (P) action suppresses overshoot and hunting, Integral (I) action corrects offset, and Derivative (D) action converges rapid temperature change due to disturbance in shorter time. Optimum values of P, I, D, ARW for PID control can be automatically set by performing AT.

#### **ON/OFF** control

When PV is lower than the SV, the control output is turned ON, and if PV exceeds the SV, the control output is turned OFF.

Overshoot, undershoot and hunting are generated in ON/OFF control action.

#### (Example) Selecting PID control



- P control action: When [Integral time] and [Derivative time] are set to 0 (zero).
- PD control action: When [Integral time] is set to 0 (zero).
- PI control action: When [Derivative time] is set to 0 (zero).

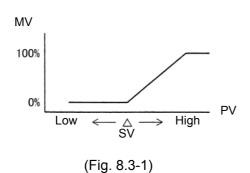
#### 8.3 Selecting Direct/Reverse Action

Selects Direct or Reverse control action.

Select Direct or Reverse control action in [Direct/Reverse action] in Sub setting mode. Factory default value is Reverse action.

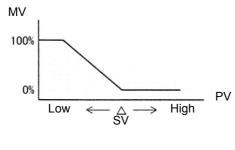
#### **Direct action**

In Direct action, MV is increased when PV is higher than SV (positive deviation). Refrigerators, etc. perform Direct action.



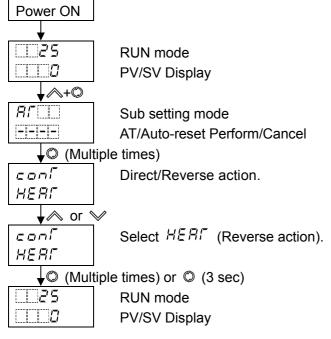
#### **Reverse** action

In Reverse action, MV is increased when SV is higher than PV (negative deviation). Electric furnaces, etc. perform Reverse action.





#### (Example) Selecting Reverse action



#### 8.4 Performing Fixed Value Control

Fixed value control is a typical temperature control action, which reduces deviation from a single SV by comparing with PV. To perform Fixed value control, set the SV.

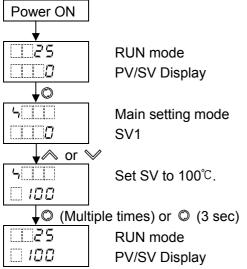
There are 2 ways to set the SV.

- Set the SV in [SV1] in Initial setting mode.
- Set the SV in [SV1] in Main setting mode.

Setting item [SV1] in Initial setting mode corresponds to [SV1] in Main setting mode. Therefore, if one SV1 is changed, the other SV1 will also be changed.

Factory default value is 0 (zero).

### (Example) Setting SV to 100℃



Now, settings are complete.

## **⚠** Notice

- Perform the AT during the trial run.
- During the AT, none of the setting items can be set.
- If power failure occurs during the AT, the AT stops.
- If AT is cancelled during the process, P, I, D and ARW values revert to the values before AT was performed.
- AT will be forced to stop if it has not been completed within 4 hours.
- Sometimes the AT process will not fluctuate if AT is performed at or near room temperature. Therefore AT might not finish normally.

To set PID constants, perform AT.

There are 2 types of AT.

#### (1) Usual AT

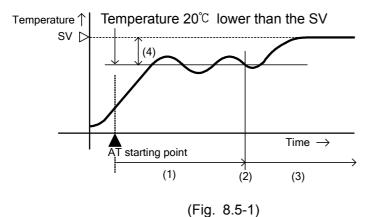
In order to set each value of P, I, D and ARW automatically, the AT process should be made to fluctuate to obtain an optimal value.

For DC voltage, current inputs, the AT process will fluctuate around the SV for conditions of [A], [B] and [C] below.

One of 3 types of fluctuation below is automatically selected depending on the deviation between SV and PV.

#### [A] If there is a large difference between the SV and PV as the temperature is rising

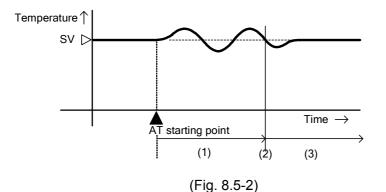
When AT bias is set to  $20^{\circ}$ C, the AT process will fluctuate at the temperature  $20^{\circ}$ C lower than the SV.



- (1) Calculating PID constants
- (2) PID constants calculated
- (3) Controlled by the PID constants set by AT.
- (4) AT bias value (Factory default: 20℃)

#### [B] When the control is stable

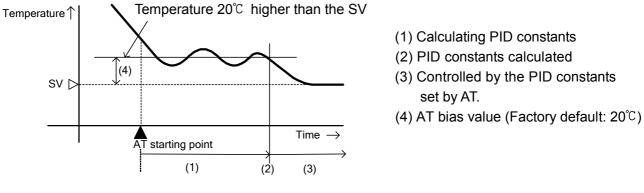
The AT process will fluctuate around the SV.



- (1) Calculating PID constants
- (2) PID constants calculated
- (3) Controlled by the PID constants set by AT.

#### [C] If there is a large difference between the SV and PV as the temperature is falling

When AT bias is set to 20°C, the AT process will fluctuate at the temperature 20°C higher than the SV.



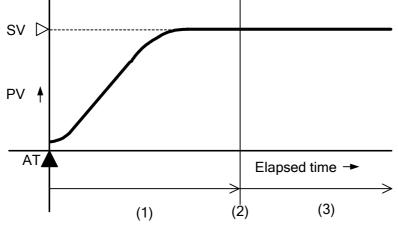
(Fig. 8.5-3)

#### (2) AT on Startup

When usual AT cannot be performed normally due to temperature interference, P, I, D and ARW values can be calculated only when temperature is rising.

As the selected [AT on startup Perform] is internally memorized, 'AT on startup' is performed whenever the power is turned ON.

To stop 'AT on startup', select 'AT/AT on startup/Auto-reset Cancel' in [AT/Auto-reset Perform/Cancel].



- (1) Calculating AT (from startup, until PV is stabilized at SV)
- (2) PID constants calculated
- (3) Controls with PID constants set by 'AT on startup'

(Fig. 8.5-4)

#### [Conditions of Performing 'AT on startup']

• When starting 'AT on startup', if deviation between PV and SV exceeds the proportional band by 2 times or more, 'AT on startup' will perform.

When power is turned ON (\*), or when the unit reverts to RUN mode after canceling control output OFF, 'AT on startup' performs.

Even after 'AT on startup' is successfully finished, 'AT on startup' has been still selected in [AT/Auto-reset Perform/Cancel].

When power is turned ON again, or when the unit reverts to RUN mode by cancelling Control output OFF, 'AT on startup' performs again under the above performance conditions.

To stop 'AT on startup', select 'AT/AT on startup/Auto-reset Cancel' in [AT/Auto-reset Perform/Cancel]. (\*) For Fixed value control, 'AT on startup' can be performed when power is turned ON. It cannot be performed for Program control. However, if PV slope and delay time cannot be measured normally for P, I, D calculation, the error code below will be indicated on the PV Display, and automatically 'AT on startup' will stop. If an error has occurred, P, I, D and ARW values revert to the previous value at which 'AT on startup' is performed.

Error Code	Error Contents
6-20	PV slope and delay time cannot be measured normally for P, I, D calculation.

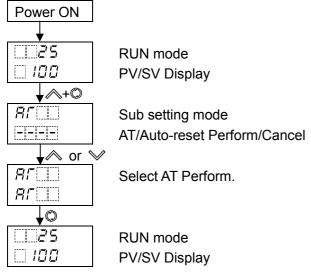
To cancel the error code, press the  $\bigcirc$  key.

If 'AT on startup' is performed or stopped, the error code will be cancelled.

#### [Conditions of Cancelling 'AT on startup']

- When Control output OFF is enabled
- When input is burnt out
- When deviation between SV and PV is not within 2°C or is not within 2% of proportional band (even though the set integral time has exceeded when the control is stable)

#### (Example) Performing Usual AT



Now, selection is complete.

The AT indicator flashes while AT is performing.

After AT is complete, the AT indicator goes off, and control is performed using PID constants calculated by the AT.

If AT does not finish after 4 hours, the error code below will be indicated on the PV Display, and AT will automatically stop.

Error Code	Error Contents
8-20	If AT or 'AT on startup' does not finish after 4 hours.

To cancel the error code, press the  $\bigcirc$  key.

The error code will be cancelled in the following cases.

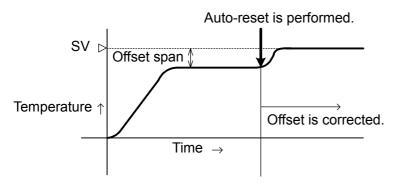
- When Control output OFF function is enabled
- When Program control is stopped and the unit reverts to the Standby (Program control waiting) mode.
- When 'Control output OFF function' or 'Auto/Manual control' is selected in [OUT/OFF key function].
- When 'AT/AT on startup/Auto-reset Cancel' is selected in [AT/Auto-reset Perform/Cancel].

## \Lambda Notice

- Auto-reset is cancelled in approximately 4 minutes. It cannot be cancelled while performing this function.
- If input is burnt out, Auto-reset will be forced to stop.

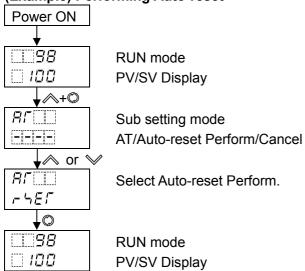
Auto-reset is performed to correct the offset at the point at which PV indication is stabilized within the proportional band during the PD control. Since the corrected value is internally memorized, it is not necessary to perform the Auto-reset again as long as the process is the same.

However, when OUT1 proportional band (P) is set to 0 or 0.0, the corrected value is cleared to 0 (zero).





#### (Example) Performing Auto-reset



Now, selection is complete.

The AT indicator flashes while Auto-reset is performing.

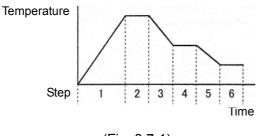
Auto-reset is completed in approximately 4 minutes.

After Auto-reset is complete, the AT indicator goes off, and control is performed using the offset corrected value.

#### 8.7 Performing Program Control

In Program control, SV changes as time elapses, and PV is controlled to order to reach each SV. SV and time can be set for every step, and a maximum of 9 steps can be repeatedly controlled. SV can be set as (Fig. 8.7-1).

(e.g.) Program control of electric furnaces in ceramic manufacture, food machinery, etc.



(Fig. 8.7-1)

Major functions of Program control are shown below.

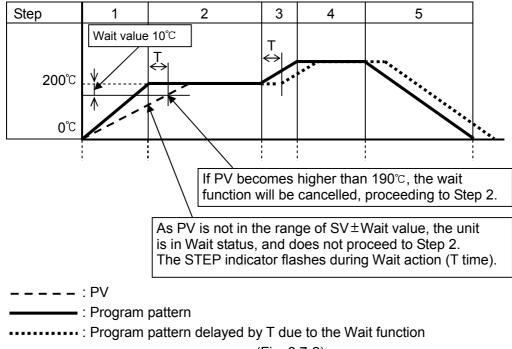
Number of patterns and steps: 1 pattern; 9 steps

#### [Wait function]

While Program control is running, the program does not proceed to the next step until the deviation between PV and SV enters  $SV \pm Wait$  value at the end of step. The PV Display flashes while the Wait function is working.

The Wait function is cancelled on the condition that:

- When program pattern is rising: PV is higher than SV- Wait value
- When program pattern is falling: PV is lower than SV+ Wait value



(Fig. 8.7-2)

#### Program control Holding/Not holding

During Program control, progress of current step is suspended, and then Fixed value control is performed using the SV from the point of suspension. Program control Holding/Not holding can be selected in [Event input DI1/DI2 allocation].

#### Advance function

Interrupts current step while Program control is running, and proceeds to the beginning of the next step.

By pressing the  $\land$  key for approx. 1 second during Program control, Advance function initiates. Select this function in [Event input DI1/DI2 allocation].

#### Pattern end output

If Pattern end output is selected in [Event output EV1/EV2 allocation], pattern end output is turned ON after Program control is finished, and the SV Display flashes  $P_{c} \mathcal{E} \cap d$ .

By pressing the <sup>(IIII</sup>) key for approx. 1 second, pattern end output is turned OFF, and the unit enters Standby mode.

#### Step time unit

Step time unit can be selected: Hours:Minutes, Minutes:Seconds Factory default value is Hours:Minutes.

#### Power Restore Action (Program control after power is restored)

If power fails during Program control, selects a status after the power is restored. Factory default value is 'Stops after power is restored'.

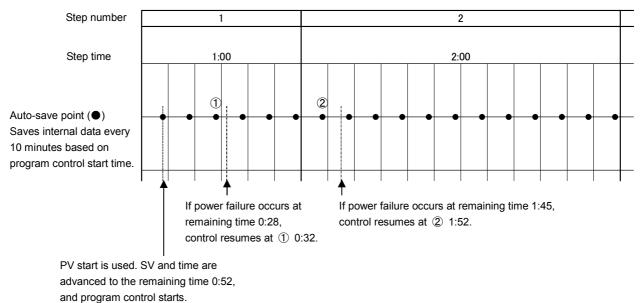
Power Restore Action	Description
Stops after power is restored.	Stops Program control, and returns to Standby (Program control waiting) mode.
Continues after power is restored. (*)	Continues (resumes) Program control.
Suspends after power is restored. (*)	Suspends (on hold) current program, and performs Fixed value control using the SV from the point of suspension. Pressing the <sup>(IIIIIIIIIIIIIIIIIIIIIIIIIIIIIIIIIIII</sup>

(\*) Progressing time error when power is restored: 10 minutes

This controller saves internal status every 10 minutes after Program control starts.

Internal status is also saved when step is changed.

When power is restored, the unit starts from the last auto-save point.



(Fig. 8.7-3)

#### Program start temperature

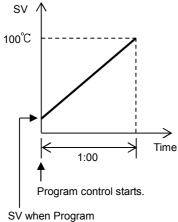
When Program control starts, it starts from the value set in [Program start temperature]. Factory default value is  $0^{\circ}$ C.

#### Program control start type

One type can be selected: PV start, PVR start, SV start. Factory default value is PV start.

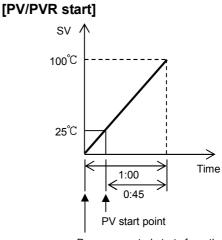
Program control start type	Description
PV start	When Program control starts, the SV and step time are advanced to the PV,
	then Program control starts.
	However, if [Program start temperature] at the time of Program control start is
	higher than the PV (when PV start is initiated), then Program control will start
	from the SV set in [Program start temperature].
PVR start	In pattern repeating, the SV and step time are advanced to the PV, then the
	Program control starts.
SV start	Program control starts from the SV which has been set in [Program start
	temperature].





SV when Program control starts

(Fig. 8.7-4)



Program control starts from the PV start point (measured value  $25^{\circ}C$ ).

(Fig. 8.7-5)

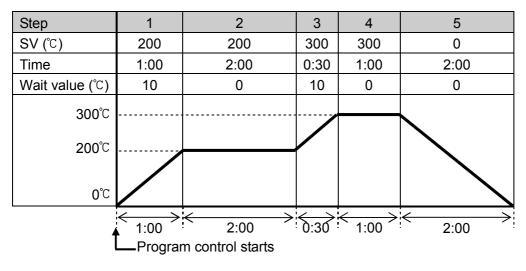
#### **Repeat function**

When Program control is finished, control can be repeated from Step 1. The user determines the number of repetitions. Factory default value is 0 (zero). Select 'Program control' in [OUT/OFF key function] in Engineering mode. Factory default value is Control output OFF function.

Set the following items in Engineering mode:

Step time unit, Power restore action, Program start temperature, Program control start type, Number of repetitions

Program pattern can be set in Main setting mode.



#### Example of program pattern setting



In the above program pattern, control is performed at each step as follows.

Step 1: The SV gradually rises to  $200^{\circ}$  for 1 hour.

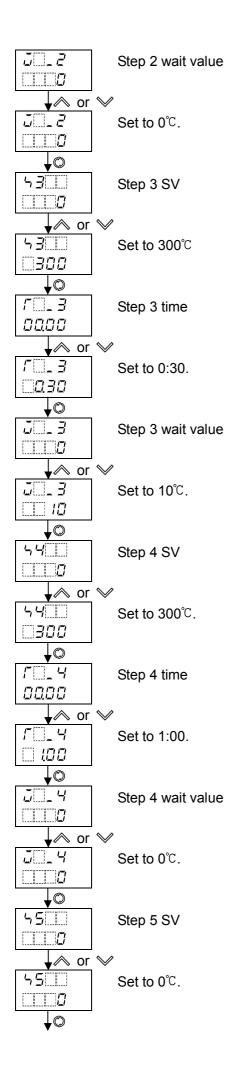
When step ends, Wait function works so that control cannot proceed to the next step until PV reaches  $190^{\circ}$ C when step ends.

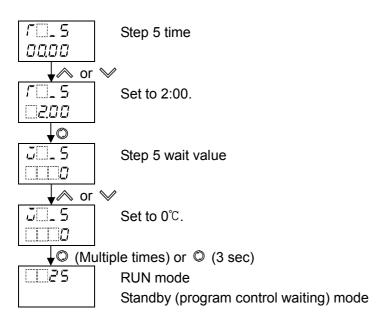
- Step 2: Fixed value control is performed to keep SV at 200<sup>℃</sup> for 2 hours.
- Step 3: Control is performed so that the SV gradually rises to 300°C for 30 minutes. When step is finished, Wait function works so that control cannot proceed to the next step until PV reaches 290°C.
- Step 4: Fixed value control is performed to keep SV at 300°C for 1 hour.

Step 5: Control is performed so that the SV gradually falls to  $0^{\circ}$  for 2 hours.

## (Example) Selecting Program control and Setting program pattern of (Fig. 8.7-6)

Power ON	
$\downarrow$	
25	RUN mode
<u> </u>	
	PV/SV Display
(3	sec)
Lock	Engineering mode
	Set value lock
é (Multiple	
· · · · · · · · · · · · · · · · · · ·	
787U	OUT/OFF key function
oFF	
↓ ∧ or ∨	
ARAU	Select 🗁 – 🛛 🖓 (Program control).
Proū	
	e times) or 🔘 (3 sec)
25	RUN mode
	Standby (Program control waiting)
↓ ©	
	Main potting mode
	Main setting mode
	Step 1 SV
↓ ∧ or ∨	
4	Set to 200℃.
200	
	Step 1 time
0000	
v or √	
	Set to 1:00.
	Set to 1.00.
<b>↓</b> ©	
J	Step 1 wait value
↓ ∧ or ∨	
	Set to 10℃.
EE 10	
↓Ø	
ц,э́т	Step 2 SV
	0.00 2 0 1
1	
v or ₩	
52000	Set to 200℃.
200	
	Otom O time
	Step 2 time
0000	
Γ	Set to 2:00.
200	
<b>↓</b> ©	





Now, selection is complete.

#### **Program control RUN**

To perform Program control, press and hold the <sup>(iiii</sup>) key for approx. 1 second in Standby (program control waiting) mode.

Program control starts using the start type selected in [Program control start type]. While Wait function is working, the PV Display flashes.

#### **Program control STOP**

To stop Program control, press and hold the (1) key for approx. 1 second during Program control. Program control will stop, and the unit will revert to Standby (Program control waiting) mode.

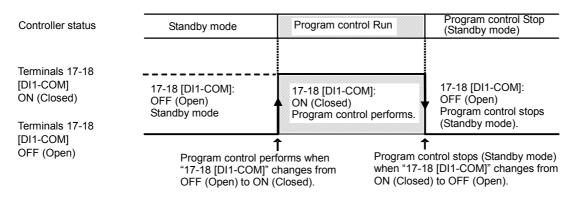
#### Proceeding to the next step during Program control (Advance function)

By pressing the  $\wedge$  key for approx. 1 second during Program control, the performing step is interrupted, proceeding to the next step. (Advance function) While Wait function is working, the Wait function is cancelled, and proceeds to the next step.

If  $\Box \Box \Box \Box B$  (Program control RUN/STOP)' is selected in [Event input DI1 allocation], Program control RUN/STOP can be switched by terminals 17-18 [DI1-COM]:

Signal edge action from OFF to ON / ON to OFF is engaged.

However, for the action when power is turned ON, Level action [ON (Closed) or OFF (Open)] is engaged.



#### 8.8 Event Output EV1 Allocation

Selects Event output EV1 allocation.

There are 2 methods in selection of Event output EV1 allocation.

- Select in [Event output EV1 allocation] in Initial setting mode.
- Select in [Event output EV1 allocation] in Engineering mode.

Setting item [Event output EV1 allocation] in Initial setting mode corresponds to [Event output EV1 allocation] in Engineering mode.

Therefore, if one [Event output EV1 allocation] is changed, the other [Event output EV1 allocation] will also be changed.

Factory default value is No event.

#### Selection item:

000	No event	
00 I	Alarm output, High limit alarm	
500	Alarm output, Low limit alarm	
003	Alarm output, High/Low limits alarm	
004	Alarm output, High/Low limits independent alarm	
005	Alarm output, High/Low limit range alarm	
005	Alarm output, High/Low limit range independent alarm	
007	Alarm output, Process high alarm	
008	Alarm output, Process low alarm	
009	Alarm output, High limit with standby alarm	
0 10	Alarm output, Low limit with standby alarm	
<u> </u>	Alarm output, High/Low limits with standby alarm	
0 IZ	Alarm output, High/Low limits with standby independent alarm	
<i>□0 13</i>	Heater burnout alarm output	
Ш <i>0 1</i> Ч	Loop break alarm output	
<i>□0                                    </i>	Time signal output	Turns OFF or ON during Program control, by setting OFF and ON times within the step set in [Step number].
0 15	Output during AT	Turns ON during AT.
רו ם	Pattern end output	Turns ON when Program control ends, and remains ON until turned OFF by pressing the <sup>(1)</sup> key.
0 18	Output by communication command	Turns OFF or ON by communication command 00E4H during Serial communication. B0 EV1 output 0: OFF 1: ON B1 EV2 output 0: OFF
		1: ON

## (Example) Selecting High limit alarm, and setting EV1 alarm value to $20^\circ\!\!\mathbb{C}$

Power ON	
25	RUN mode
<i>D</i>	PV/SV Display
<b>↓</b> ∀+© (3	3 sec)
4824	Initial setting mode
E	Input type
<b>√</b> © (3 tim	es)
E8o (	Event output EV1 allocation
0	
🔜 🖌 🗸 🗸	/
E8a I	Select $\Box \Box \Box \Box \downarrow$ (High limit alarm).
(2 tim	es)
<i>A (</i>	EV1 alarm value
🚽 📥 or 🔌	/
<i>A</i> /	Set to 20℃.
<b>↓</b> © (Multi	ple times) or 🛇 (3 sec)
25	RUN mode
	PV/SV Display

Now, settings are complete.

#### 8.9 Indicating MV, Remaining Time (Program Control)

In Fixed value control and Program control, MV and remaining time are indicated.

To indicate MV, press and hold the  $\,$  key for approx. 3 seconds on the PV/SV Display.

The unit enters Monitor mode, and indicates MV.

While MV is indicating, the decimal point flashes.

While in Standby (Program control waiting) mode of Program control, the unit cannot move to Monitor mode.

In Monitor mode, the following contents are switched every time the <sup>O</sup> key is pressed.

Model	Indicated Contents			
BCS2	Fixed value control Indicates MV, Set value memory number (in that order).			
	Program control	Indicates MV, Remaining time, Step number (in that order).		
BCR2, BCD2	Fixed value control Indicates only MV. (*)			
	Program control Indicates MV, Remaining time (in that order). (*)			

(\*) For the BCR2, BCD2, Set value memory number (Fixed value control) and step number (Program control) are indicated on the MEMO/STEP Display.

#### Indicating MV, Remaining time

Power ON	
$\checkmark$	
	RUN mode
00	PV/SV Display
<b>↓</b> © (3 sec)	
001	Monitor mode
7.2	Indicates MV. (e.g.) MV: 7.2% (Decimal point flashes.)
<b>↓</b> Ø	
00	Remaining time (Program control RUN)
00.30	(e.g.) Remaining time 0:30
<b>↓</b> Ø	
001	Step number (Program control RUN) (BCS2)
57 _ 1	(e.g.) Step 1
<b>↓</b> Ø	
00	Set value memory number (Fixed value control) (BCS2)
4 <i>82</i>	(e.g.) Set value memory number 2
<b>↓</b> Ø	
	RUN mode
🗆 <i>100</i>	PV/SV Display

## 8.10 Items to be Initialized by Changing Settings

If settings are changed, the following items will be initialized.

- •: Initialized
- X: Not initialized

Setting item to be Item changed to be Initialized	Input Type	Event output EV1 allocation	Event output EV2 allocation	Transmission output
SV1 to SV9	•	Х	Х	Х
Steps 1 to 9 wait value	•	Х	Х	Х
AT bias	•	Х	Х	Х
OUT1 proportional band	●	Х	Х	Х
Manual reset	٠	Х	Х	Х
SV rise rate	۲	Х	Х	Х
SV fall rate	●	Х	Х	Х
Scaling high limit	۲	Х	Х	Х
Scaling low limit	●	Х	Х	Х
Program start temperature	٠	Х	Х	Х
EV1 alarm value	•	•	Х	Х
EV1 high limit alarm value	•	•	Х	Х
Loop break alarm time	۲	Х	Х	Х
Loop break alarm span	۲	Х	Х	Х
SVTC bias	٠	Х	Х	Х
Remote bias	٠	Х	Х	Х
EV2 alarm value	•	Х	•	Х
EV2 high limit alarm value	•	Х	•	Х
Transmission output high limit	۲	Х	Х	•
(Except MV transmission)				
Transmission output low limit	۲	Х	Х	•
(Except MV transmission)				
OUT2 proportional band	•	Х	Х	Х
EV1 alarm value 0 Enabled/Disabled	Х	•	Х	Х
EV1 alarm hysteresis	Х	•	Х	Х
EV1 alarm delay time	Х	•	Х	Х
EV1 alarm Energized/De-energized	Х	•	Х	Х
EV2 alarm value 0 Enabled/Disabled	Х	Х	•	Х
EV2 alarm hysteresis	Х	Х	•	Х
EV2 alarm delay time	Х	Х	•	Х
EV2 alarm Energized/De-energized	Х	X	•	Х
Sensor correction coefficient	•	Х	Х	Х
Sensor correction value	•	Х	Х	Х
External setting input high limit	•	Х	Х	Х
External setting input low limit	•	Х	Х	Х

## 9. Attached Function

#### 9.1 Input Value Correction

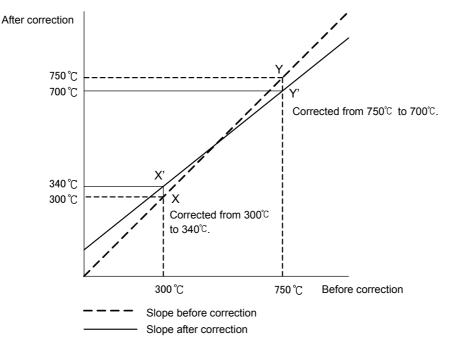
Input value can be corrected in [Sensor correction coefficient] and [Sensor correction] in Engineering mode.

- In [Sensor correction coefficient], set the slope of temperature change.
- In [Sensor correction], set the difference between temperatures before correction and after correction.

PV after input correction is expressed with the following formula.

PV after input correction = Current PV x Sensor correction coefficient + (Sensor correction value)

The following shows an example of input value correction using 'Sensor correction coefficient' and 'Sensor correction value'.



(Fig.9.1-1)

- (1) Select any 2 points of PV to be corrected, and determine the PV after correction.
   PV before correction: 300°C → PV after correction: 340°C
   PV before correction: 750°C → PV after correction: 700°C
- (2) Calculate Sensor correction coefficient from Step (1). (Y' - X') / (Y - X) = (700 - 340) / (750 - 300) = 0.8
- (3) Enter a PV value of 300°C using an mV generator or dial resistor.
- (4) Set Step (2) value as a Sensor correction coefficient.
- (5) Read the PV.

240°C will be indicated.

- (6) Calculate the sensor correction value.
   Calculate the difference between 'PV after correction' and Step (5) PV.
   340°C 240°C = 100°C
- (7) Set Step (6) value as a Sensor correction value.
- (8) Enter an electromotive force or resistance value equivalent to 750°C using an mV generator or dial resistor.
- (9) Read the PV, and confirm that  $700^{\circ}$ C is indicated.

## (Example) Setting Sensor correction coefficient to 0.800, and Sensor correction to 100.0 $^\circ C$

Power ON	
¥	
001	RUN mode
🗆 <i>100</i>	PV/SV Display
<b>↓</b> ∧+ ∨ (3	sec)
Lock	Engineering mode
	Set value lock
↓© (Multip	le times)
50E	Sensor correction coefficient.
1000	
v ∧ or √	
40E	Set to 0.800.
<i>a800</i>	
<b>↓</b> Ø	
50 <sup>1</sup>	Sensor correction
v ∧ or √	
50	Set to 100.0℃.
1000	
↓© (Multip	le times) or 🔘 (3 sec)
	RUN mode
🗆 <i>100</i>	PV/SV Display
·	

Now, settings are complete.

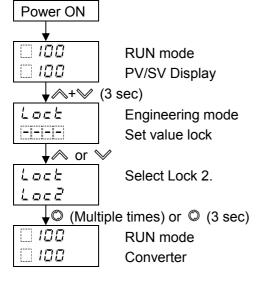
#### 9.2 Set Value Lock

Locks the set values to prevent setting errors. Make a selection in [Set value lock] in Engineering mode.

Selection Item	Change via Keypad	Change via Software Communication
Unlock	All set values can be changed.	All set values can be changed.
Lock 1	None of the set values can be changed.	
Lock 2	In Fixed value control, only SV and	
	Alarm value can be changed.	
	In Program control, Step SV, Step time	
	and Alarm value can be changed.	
Lock 3	All set values can be changed.	Setting items – except Input type,
Lock 4	None of the set values can be changed.	Controller/Converter – can be changed
Lock 5	In Fixed value control, only SV and	temporarily via software communication.
	Alarm value can be changed.	However, if power is turned ON again,
	In Program control, Step SV, Step time	the setting values revert to the values
	and Alarm value can be changed.	before Lock 3, 4 or 5 was selected.

The setting item t	a ha laakad	donondo on	the coloction
The setting item i	o pe lockeu	uepenus on	the selection.
· · · · · · · · · · · · · · · · · · ·			

#### (Example) Selecting Lock 2



### 9.3 Control Output OFF Function

The control action and output of an instrument (or instruments) can be turned OFF without turning OFF their power supplies using this function.

Select 'Control output OFF function' in [OUT/OFF key function] in Engineering mode. Factory default value is Control output OFF function.

# (Example) Selecting 'Control output OFF function', and 'PV indication' in [Indication when control output OFF]

00	
Power ON	
<b>—</b>	
2S	RUN mode
🗆 <i>100</i>	PV/SV Display
<b>↓</b> ∧+∨ (	(3 sec)
Lock	Engineering mode
	Set value lock
, (Mult	iple times)
P 4 8	Indication when control output OFF
oFF	
🖌 🔿 or 🔌	
P 4 8	Select PB (PV indication).
<i>P 8</i>	
↓© (Mult	iple times)
ARAU	OUT/OFF key function
oFF	
v ∧ vr	
AR-U	Select
oFF	
<b>↓</b> © (Mult	iple times) or 🔘 (3 sec)
25	RUN mode
🗌 <i>100</i>	PV/SV Display

Now, selection is complete.

To turn the control output OFF, press the <sup>(iiii)</sup> key for approximately 1 second on the PV/SV Display. PV is indicated on the PV Display. Indication differs depending on the selection in [Indication when control output OFF].

Once the control output OFF function is enabled, the function cannot be cancelled even if the power to the instrument is turned OFF and ON again.

To cancel the function, press the <sup>(iii)</sup> key again for approx. 1 second.

25	RUN mode	(1 sec)	25	Control output OFF
	PV/SV Display		[Unlit]	

## 9.4 Switching Auto/Manual Control (Auto/Manual Control Function)

Control action can be switched from automatic to manual and vice versa. When power to the controller is turned ON, Automatic or Manual control is selectable.

Select 'Auto/Manual control' in [OUT/OFF key function] in Engineering mode. Factory default value is Control output OFF function.

Select 'Automatic control' or 'Manual control' in [Auto/Manual after power interruption] in Engineering mode.

Factory default value is Automatic control.

## (Example) Selecting 'Auto/Manual control ', and 'Manual control' after power interruption

Power ON	
<b>•</b>	
2s	RUN mode
	PV/SV Display
<b>↓</b> ∧+∨	(3 sec)
Loct	Engineering mode
	Set value lock
↓© (Muli	tiple times)
AR-U	OUT/OFF key function
oFF	
	×
ARAU	Select 주문고문 (Auto/Manual control).
AR-U	
<b>↓</b> Ø	
- A- S	Auto/Manual after power interruption
RUFa	
√∧ or ≦	×
- A- S	Select 주문고날 (Manual control).
⊼8n∐	
↓© (Muli	tiple times) or 🔘 (3 sec)
25	RUN mode
100	PV/SV Display

Now, selection is complete.

By pressing the <sup>(iii)</sup> key in PV/SV Display for approx. 1 second, Auto/Manual control function can be switched.

If control action is switched from automatic to manual and vice versa, balanceless-bumpless function works to prevent a sudden change in the MV.

When automatic control is switched to manual control, MV flashes on the SV Display.

The MV on the SV Display can be increased or decreased by pressing the  $\,$  or  $\,$  v key.

Data is saved 1 second after MV is changed, and manual control is performed.

When power is turned ON after interruption, control resumes using the previously saved MV (if manual control is selected in [Auto/Manual after power interruption]).

However, if  $\square \square \square \square \square \square$  (Auto/Manual control) is selected in [Event input DI1/DI2 allocation], then Event input status has priority.

By pressing the <sup>®</sup> key again for approx. 1 second, the unit reverts to automatic control.

00 III III III III III III III III III	RUN mode PV/SV Display		MV flashes (Manual control). MV increases/decreases with
	(Automatic control)		\land or 🛇 key.

#### 9.5 Using as a Converter

## **I** Caution

• Input/Output response time of this instrument is approx. 1 second.

When using as a converter, the converter input will be 1 sec slower due to the response time. (In such cases please use a converter with input time slower than the response time above.)

This instrument can be used as a simplified converter.

Converts each input value (thermocouple, RTD, DC voltage and current inputs) to '4 to 20 mA DC', and outputs it.

When OUT1 is Direct current output, the controller can be used as a converter.

Select 'Converter' in [Controller/Converter] in Engineering mode. Factory default value is Controller.

When this instrument is switched from controller to converter, values in the table below (Table 9.5-1) are automatically set. The SV Display turns blank.

When this instrument is switched from converter to controller, the PV Display indicates  $\frac{1}{2} \sigma \frac{1}{2}$  for 1 second, and factory default values are set.

(Table 9.5-1)

Setting Item	Set Value (or Selection)		
SV1 (*1)	Scaling low limit value		
SV2 (*1)	Scaling low limit value		
(BCS2: EIW, EIT, EI options,			
BCR2/BCD2: C5W, EIW, EIT, EI options)	Scaling low limit value		
SV3 (*1) (BCS2: EIW, EI options,			
BCR2/BCD2: C5W, EIW, EIT, EI options)			
SV4 (*1)	Scaling low limit value		
(BCS2: EIW, EI options,			
BCR2/BCD2: C5W, EIW, EIT, EI options) AT/Auto-reset Perform/Cancel (*2)	AT/AT on startup/Auto-reset Cancel		
	· ·		
OUT1 proportional band (*1)	Input span		
Integral time	0		
Derivative time	0		
Reset	0 (Reset value, calculated by Auto-reset function)		
OUT1 high limit	100		
OUT1 low limit	0		
OUT1 rate-of-change	0		
OUT2 proportional band (*1)	Input span		
Direct/Reverse action	Direct action		
EV1/EV2 alarm value 0 Enabled/Disabled	Disabled		
EV1/EV2 alarm value	0 or Input range low limit value (Scaling low limit value)		
EV1/EV2 high limit alarm value	0 or Input range low limit value (Scaling low limit value)		
EV1/EV2 alarm hysteresis	1.0		
EV1/EV2 alarm delay time	0		
EV1/EV2 alarm Energized/De-energized	Energized		
Loop break alarm time	0		
Loop break alarm span	0		
Event input DI1 allocation	No event		
(BCS2: EIW, EIT, EI options,			
BCR2/BCD2: C5W, EIW, EIT, EI options)	No event		
Event input DI2 allocation (BCS2: EIW, EI options,			
BCR2/BCD2: C5W, EIW, EIT, EI options)			

Setting Item	Set Value (or Selection)		
Event output EV1 allocation	No event		
Event output EV2 allocation	No event		
(EV2 option)			
Remote/Local	Local		
(EIT option)			
Transmission output type	PV transmission		
(EIT option)			
Transmission output high limit	Input range high limit		
(EIT option)			
Transmission output low limit	Input range low limit		
(EIT option)			
SV rise rate	0		
SV fall rate	0		
OUT/OFF key function	Control output OFF function		

(\*1) When input range is changed while this instrument is used as a converter, SV1 to SV4, OUT1 and OUT2 proportional bands will be automatically set to values corresponding to the input range.

(\*2) If "AT on startup" is successfully completed and "AT on startup Perform" has been still selected, "AT on startup" will be stopped (AT/ AT on startup/Auto-reset Cancel).

#### 9.5.1 Selecting Converter Function

Power ON	
<b>↓</b>	
25	RUN mode
	PV/SV Display
<b>∀</b> +©	(3 sec)
4E24	Initial setting mode
E	Input type
<b>↓</b> ©	Select an input type with the \land or 📎 key.
SELH	Scaling high limit
סרבו	Set a 100% output value which is indicated on the PV Display, using the 🙈 or
<b>↓</b> Ø	₩ key.
55LL	Scaling low limit
-200	Set a 0% output value which is indicated on the PV Display, using the 📣 or 📎
	key.
(Μι	ultiple times or 3 sec)
25	RUN mode
	PV/SV Display
<u></u>	(3 sec)
Loct	Engineering mode
	Set value lock
(Μι	ultiple times)
FUnc	Controller/Converter
enFr	Available only when OUT1 is direct current output type.
↓ ∧ or	$\sim$
FUnc	Select こっぱご (Converter).
en 8F	
<b>↓</b> ©	
25	RUN mode
[Unlit]	Converter

### 9.5.2 Converter Output Fine Adjustment (4 to 20 mA DC)

4 to 20 mA DC will be output corresponding to the input from Scaling low limit to Scaling high limit. Fine adjustment range: 1/Scaling span

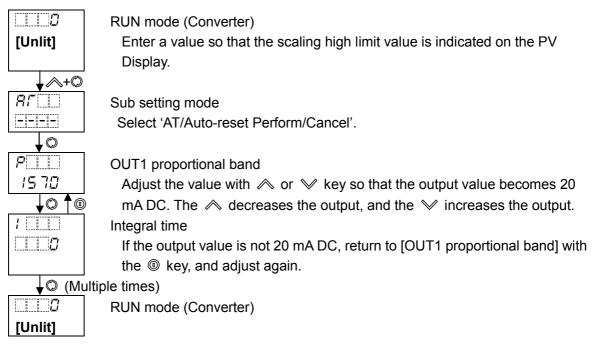
### Fine Adjustment Method for Converter Output

Be sure to perform Zero side first in fine adjustment of converter output. Perform Zero side adjustment in [Manual reset]. Perform Span side adjustment in [OUT1 proportional band].

### (1) Adjust Zero side.

<i>D</i>	RUN mode (Converter)
[Unlit]	Enter a value so that the scaling low limit value is indicated on the PV Display.
<b>+</b> ⊘	
86	Sub setting mode
	Select 'AT/Auto-reset Perform/Cancel'.
↓© (Mι	ultiple times)
- <i>5</i> E F	Manual reset
	Adjust a value with the \land or $ arsigma $ key so that the output value becomes
	4 mA DC. The $\wedge$ decreases the output, and the $\vee$ increases the output.
o L H	OUT1 high limit
🗆 <i>100</i>	If the output value is not 4 mA DC, return to [Manual reset] with the $ @ $ key,
	and adjust again.
<b>↓</b> © (Μι	ultiple times)
	RUN mode (Converter)
[Unlit]	

#### (2) Adjust Span side.



#### (3) Repeat (1) and (2) until the correct value is output.

#### 9.5.3 Converter Setting Example

# When the input is any other value except 4 to 20 mA DC Input and output conditions:

Input: 6 to 14 mA DC (Indication: 30.0 to 130.0), Output: 4 to 20 mA DC

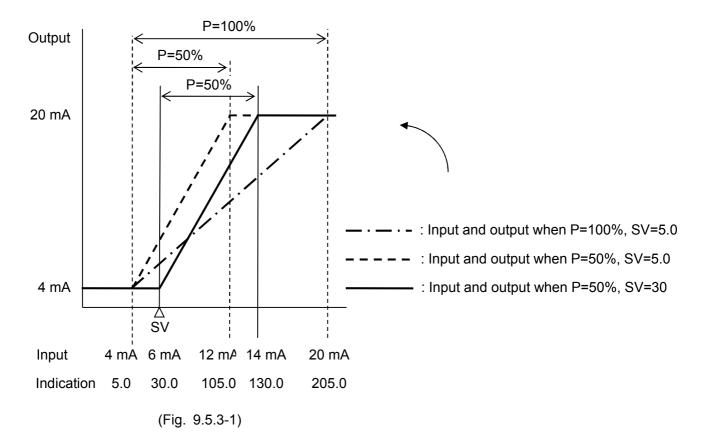
#### Setting method

#### (1) Calculating Scaling high and low limit values of 4 to 20 mA DC

Indication value per mA DC:  $(130.0 - 30.0) \div (14 - 6) = 100 \div 8 = 12.5$ Scaling high limit value: $130.0 + (20 - 14) \times 12.5 = 205.0$ Scaling low limit value $30.0 - (6 - 4) \times 12.5 = 5.0$ 

- (2) Calculating OUT1 Proportional band of 6 to 14 mA DC (Slope setting) OUT1 Proportional band (P) =  $\{(14 - 6) \div (20 - 4)\} \times 100 = 0.5 \times 100 = 50$  (%)
- (3) Calculating SV (desired value) so that 4 mA DC output can be obtained from 6 mA DC input (Parallel shift setting)

 $SV = \{(6-4) \times 12.5\} + 5.0$  (Scaling low limit) = 30.0



#### Input, Output and Indication

#### 9.6 Clearing Data

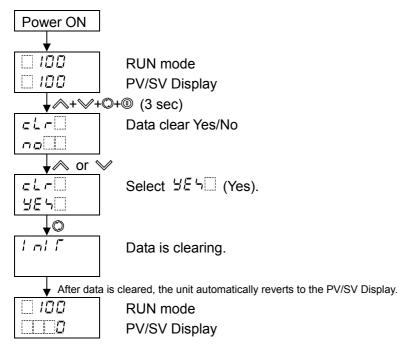
If data is cleared, data will revert to factory default values.

To clear data, press and hold *∧*, *∨*, *©*, *⊚* (in that order) together for approx. 3 seconds on the PV/SV Display.

The unit enters [Data clear Yes/No] mode.

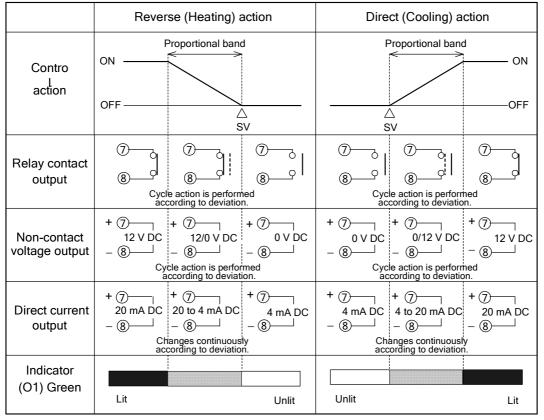
Select 'Yes', and press the  $\bigcirc$  key. Data will be cleared. While data is clearing,  $l = l \int c$  is indicated on the PV Display.

#### Executing data clear



# **10. Action Explanation**

## 10.1 OUT1 Action



: Turns ON (lit) or OFF (unlit).

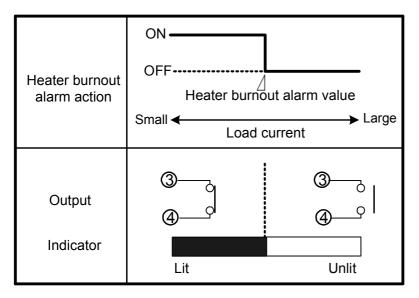
OUT1 terminal numbers of the BCR2, BCD2: 15, 16

## 10.2 OUT1 ON/OFF Control Action

	Reverse (Heating) action		Direct (Cooling) action		
Contro L action			Hysteresis		
	OFF SV		OFF △ SV		
Relay contact output	@	⑦ ⑧)	<i>ଆ</i> ଞ_ୁ		ر ک س
Non-contact voltage output	+ ⑦ 12 V DC - ⑧	+ ⑦ 0 V DC - ⑧	+ ⑦ 0 V DC _ ⑧		+ 7) 12 V DC - 8)
Direct current output	+ ⑦ 20 mA DC - ⑧	+ ⑦ 4 mA DC - ⑧	+ ⑦ 4 mA DC - ⑧		+⑦ 20 mA DC - ⑧
Indicator (O1) Green	Lit	Unlit	Unlit		Lit

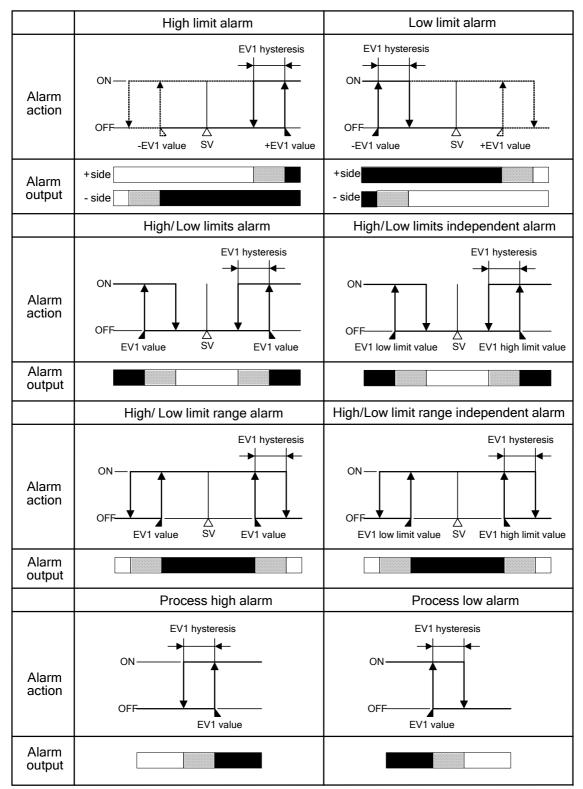
: Turns ON (lit) or OFF (unlit).

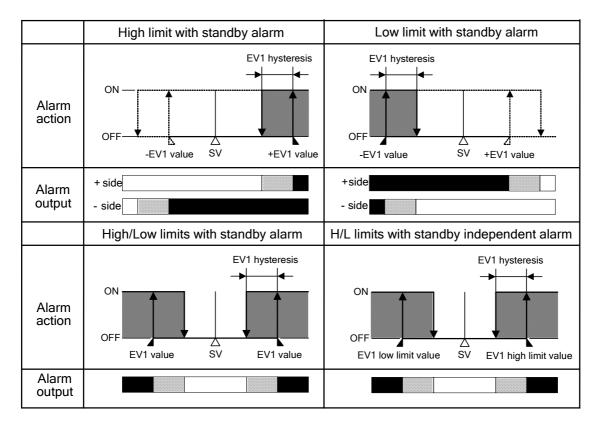
OUT1 terminal numbers of the BCR2, BCD2: 15, 16



BCS2: Event output 1 terminal numbers: 3, 4Event output 2 terminal numbers: 5, 6BCR2, BCD2: Event output 1 terminal numbers: 17, 18Event output 2 terminal numbers: 19, 20

### **10.4 Alarm Action**





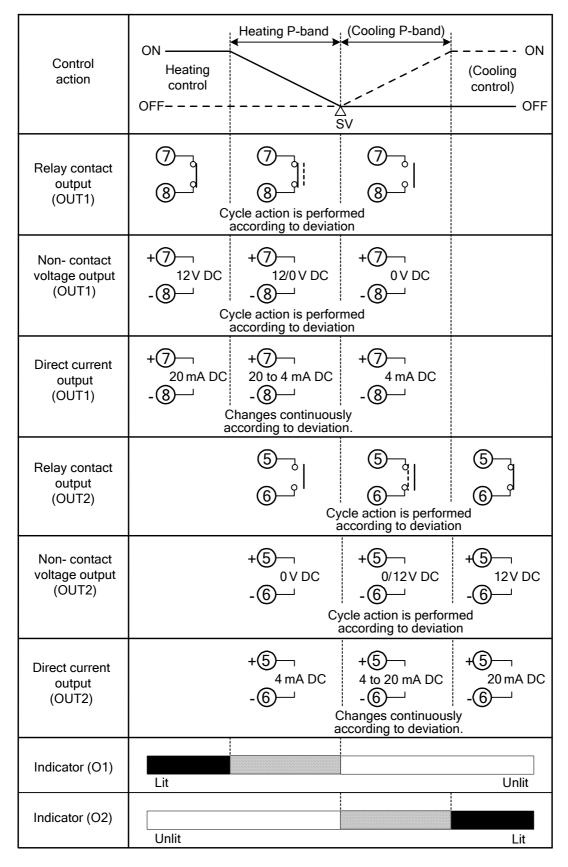
: Event output 1 terminals 3 and 4: ON (closed).

- : Event output 1 terminals 3 and 4: ON (closed) or OFF (open).
- : Event output 1 terminals 3 and 4: OFF (open).
- : Alarm output is in Standby.
- EV1 value, EV1 high limit value, and EV1 hysteresis represent EV1 alarm value, EV1 high limit alarm value and EV1 alarm hysteresis respectively. For EV2, read "EV2" for "EV1".
- EV1 indicator lights when Event output 1 terminals 3 and 4 are ON, and goes off when their output terminals 3 and 4 are OFF.

EV2 indicator lights when Event output 2 terminals 5 and 6 are ON, and goes off when their output terminals 5 and 6 are OFF.

BCR2, BCD2: Event output 1 terminal numbers: 17, 18
 Event output 2 terminal numbers: 19, 20

### 10.5 OUT2 (Heating/Cooling Control) Action



: Turns ON (lit) or OFF (unlit).

----: Represents Cooling control action.

### 10.6 OUT2 (Heating/Cooling Control) Action (When Setting Dead Band)

		Heating P-band	Dead band	(Cooling P-band)		
Control action	ON Heating control	-rouning - surre	( ) )		(Cooling Control)	ON OFF
	0FF <b></b>	∆ S\				UFF
Relay contact output (OUT1)	() () ()	Cycle action is perfor according to deviat	() () () () () () () () () () () () () (			
Non- contact voltage output (OUT1)	+⑦ 12 V DC -⑧ ℃	+⑦ 12/0 V DC -⑧ vcle action is perform according to deviatio	+⑦ 0 V DC -⑧ ned			
Direct current output (OUT1)	+⑦ 20 mA DC -⑧ Cl ac	+⑦ 20 to 4 mA DC -⑧ nanges continuously cording to deviation.	+⑦ 4 mA DC -⑧			
Relay contact output (OUT2)			چ مے دیر	5 6 le action is performe cording to deviation	5-, 6- <sup>4</sup>	]
Non- contact voltage output (OUT2)			+5 0 V DC -6 Cyc	+5 0/12 V DC -6 de action is performation	+5 12V -6	DC
Direct current output (OUT2)			+5 4 mA DC -6 A	+5 4 to 20 mA DC -6 Changes continuous	+5 20 m/ -6	A DC
Indicator (O1)	Lit				Unlit	
Indicator (O2)	Unlit				Li	it



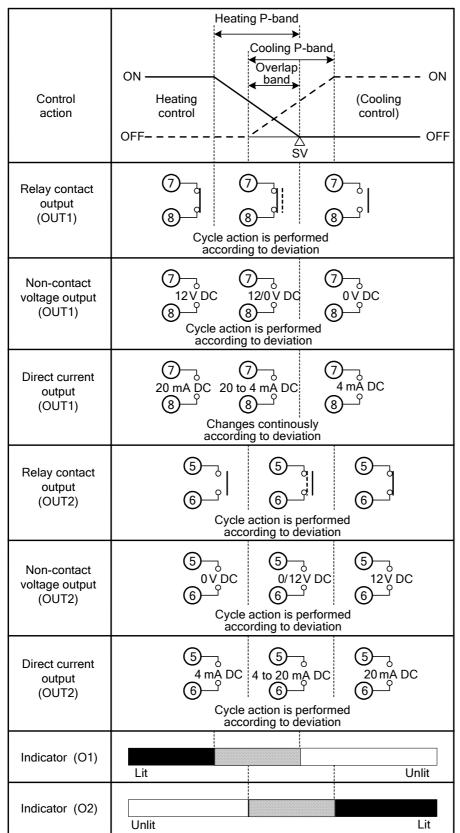
\_

: Turns ON (lit) or OFF (unlit).

- : Represents Heating control action.

---: Represents Cooling control action.

### 10.7 OUT2 (Heating/Cooling Control) Action (When Setting Overlap Band)



: Alternates between ON (lit) and OFF (unlit).

- : Represents Heating control action.

---: Represents Cooling control action.

# **11. Specifications** 11.1 Standard Specifications

### Rating

Rated scale		Input	Scale	Range	Resolution
			-200 to 1370 ℃	-328 to 2498 °F	1 °C(°F)
		К	-200.0 to 400.0 ℃	-328.0 to 752.0 °F	0.1 °C(°F)
		J	-200 to 1000 ℃	-328 to 1832 °F	1 °C(°F)
		R	0 to 1760 ℃	32 to 3200 °F	1 °C(°F)
		S	0 to 1760 ℃	32 to 3200 °F	1 ℃(°F)
		В	0 to 1820 ℃	32 to 3308 °F	1 ℃(°F)
		E	-200 to 800 ℃	-328 to 1472 °F	1 ℃(°F)
		Т	-200.0 to 400.0 ℃	-328.0 to 752.0 °F	0.1 ℃(°F)
		N	-200 to 1300 ℃	-328 to 2372 °F	1 ℃(°F)
		PL-Ⅱ	0 to 1390 ℃	32 to 2534 °F	1 ℃(°F)
		C(W/Re5-26)	0 to 2315 ℃	<b>32</b> to 4199 °F	1 ℃(°F)
		, , , ,	-200.0 to 850.0 ℃	-328.0 to 1562.0 °F	0.1 °C(°F)
		Pt100	-200 to 850 ℃	-328 to 1562 °F	1 ℃(°F)
			-200.0 to 500.0 ℃	-328.0 to 932.0 °F	0.1 ℃(°F)
		JPt100	-200 to 500 ℃	-328 to 932 °F	1 ℃(°F)
		4 to 20 mA		0 10000 (*)	1
		0 to 20 mA	-2000 to	0 10000 (*)	1
		0 to 1 V			1
		0 to 5 V -2000 to 10000 (*) 1		1	
		1 to 5 V -2000 to 10000 (*) 1			
		0 to 10 V -2000 to 10000 (*) 1		1	
		(*) Scaling and de	cimal point place selection	n are possible.	
Input	Thermocouple	K, J, R, S, B, E, T, N, PL-II, C(W/Re5-26)			
·		External resis	stance: 100 Ω max.		
		However, for	B input, External resist	stance: 40 Ω max.	
	RTD	Pt100, JPt100	3-wire type		
		Allowable inp	ut lead wire resistanc	e: 10 Ω max. per wire	
	Direct current	0 to 20 mA DC,			
		Input impeda			
			ut current: 50 mA max	Χ.	
	DC voltage	0 to 1 V DC			
		Input impedance: $1 M\Omega$ min.			
			Allowable input voltage: 5 V DC max.		
		-	Allowable signal source resistance: 2 kΩ max. 0 to 5 V DC, 1 to 5 V DC, 0 to 10 V DC		
			Input impedance: 100 kΩ min. Allowable input voltage: 15 V DC max.		
			nal source resistance		
Power	BC 2 00-	100 to 240 V A			
supply voltage	BC 2 10-	24 V AC/DC 5			
Allowable	BC 200-	85 to 264 V AC			
voltage fluctuation	BC□2□10-□□	20 to 28 V AC/DC			

### **General Structure**

General Structu					
External	BCS2		nm (W x H x D) (Depth of control panel interior: 60 mm)		
dimensions	BCR2		nm (W x H x D) (Depth of control panel interior: 60 mm)		
	BCD2	96 x 96 x 68 mm (W x H x D) (Depth of control panel interior: 60 mm)			
Mounting	Mounting				
Case		Flame-resistant resin, Black			
Front panel	Front panel		Membrane sheet		
Drip-proof/Dust-	proof	Front panel: IP66, Rear case: IP20, Terminal section: IP00			
Standards	EN	EN61010-1 (Pollution degree 2, Overvoltage category $II$ )			
Indication	PV Display	Indicates PV.			
structure		7-segment Red LED display			
		BCS2	Character size: 12.4 x 5.8 mm (H x W)		
		BCR2	Character size: 14 x 5.8 mm (H x W)		
		BCD2	Character size: 24 x 11 mm (H x W)		
	SV Display	Indicates SV.			
		7-segment Gr	een LED display		
		BCS2	Character size: 8.8 x 3.9 mm (H x W)		
		BCR2	Character size: 14 x 5.8 mm (H x W)		
		BCD2	Character size: 14 x 7 mm (H x W)		
	MEMO/STEP	Indicates Set	value memory number (Fixed value control) or Step		
	Display	number (Prog	ram control).		
	(BCR2,	7-segment Green LED display			
	BCD2)	BCR2	Character size: 14 x 5.8 mm (H x W)		
		BCD2	Character size: 14 x 7 mm (H x W)		
	Action	O1 (Green)	Lit when control output OUT1 is ON.		
	indicators		For direct current output type, flashes corresponding		
			to the MV in 125 ms cycles.		
		O2 (Yellow)	Lit when control output OUT2 (EV2, DS, DA options) is ON.		
			For direct current output type (DA option), flashes		
			corresponding to the MV in 125 ms cycles.		
		EV1 (Red)	Lit when Event output 1 is ON.		
		EV2 (Red)	Lit when Event output 2 (EV2 option) is ON.		
			Unlit if $\square \square \ / \square$ (Heating/Cooling control relay contact		
			output) is selected in [Event output EV2 allocation].		
		AT (Yellow)	Flashes while AT, 'AT on startup' or Auto-reset is		
			performing.		
		R/L (Yellow)	Lit during Remote action from Remote/Local		
			switching (EIT option).		
		T/R (Yellow)	Lit during Serial communication (C5W, C5 options) TX		
			(transmitting) output.		
		MEMO	Lit when Set value memory number (Fixed value		
		(Yellow)	control) is indicated.		
			(BCR2, BCD2)		
		STEP	Lit when a step number (Program control) is indicated.		
		(Green)	(BCR2, BCD2)		
1					

Terminal arrangement	Refer to 'Terminal arrangement'. (p.20)
Console connector	By connecting to the tool cable (CMD-001, sold separately), the
	following operations can be conducted from an external computer using
	the Console software SWC-BCx01M.
	<ul> <li>Reading and setting of SV, PID and various set values</li> </ul>
	Reading of PV and action status     Function change

### Setting Structure

octaing out				
Function	UP key	Increases the numeric value.		
key		By pressing this key for 1 second during Program control, the performing		
		step is interrupted, proceeding to the beginning of the next step.		
		(Advance function)		
	DOWN key	Decreases the numeric value.		
	MODE key	Selects a setting mode, or registers the set data.		
		By pressing this key for 3 seconds during RUN mode, the unit enters		
		Monitor mode.		
	OUT/OFF key	The following function can be selected in [OUT/OFF key function].		
		Selection Item Action		
		Control output OFF function Turns the control output ON or OFF.		
		Auto/Manual control Switches the Auto/Manual control.		
		Program control	Starts/Stops the Program control.	

### **Indication Performance**

Basic accuracy		At ambient temperature 23 $^{\circ}$ C (for a single unit mounting)
	Thermocouple	Within $\pm 0.2\%$ of each input span $\pm 1$ digit
		However R, S inputs, 0 to 200°C (32 to 392°F): Within $\pm 6$ °C (12°F)
		B input, 0 to $300^{\circ}$ C (0 to $572^{\circ}$ F): Accuracy is not guaranteed.
		K, J, E, T, N inputs, Less than 0°C (32°F): Within $\pm 0.4\%$ of input
		span±1 digit
	RTD	Within $\pm 0.1\%$ of each input span $\pm 1$ digit
	Direct current, DC voltage	Within $\pm 0.2\%$ of each input span $\pm 1$ digit
Effect of ambient temperature		Within 50 ppm/℃ of each input span
Input sampling period		125 ms
Time accur	асу	Within $\pm 1.0\%$ of setting time

### **Control Performance**

Control ac	tion	PID control (with AT function)	
		PI control: When derivative time is set to 0	
		<ul> <li>PD control (with Auto-reset, Manual reset function):</li> </ul>	
		When integral time is set to 0	
		<ul> <li>P control (with Auto-reset, Manual reset function):</li> </ul>	
		When derivative and integral times are set to 0.	
		ON/OFF control: When proportional band is set to 0 (or 0.0)	
	OUT1	Thermocouple, RTD inputs without decimal point: 0 to Input span	
	proportional	Thermocouple, RTD inputs with decimal point: 0.0 to Input span	
	band	Direct current, voltage inputs: 0.0 to 1000.0%	
	Integral time	0 to 3600 sec	
	Derivative time	0 to 1800 sec	
OUT1 propor-		0.5, or 1 to 120 sec	
	tional cycle		
	ARW	0 to 100%	

	Manual reset	±Proportional band value
		•
	OUT1 ON/OFF	Thermocouple, RTD inputs: 0.1 to 1000.0°C(°F)
	hysteresis	Direct current, voltage inputs: 1 to 10000 (The placement of the decimal
		point follows the selection.)
	OUT1 high limit,	0 to 100% (Direct current: -5 to 105%)
	OUT1 low limit	
Control	Relay contact	Control capacity: 3 A 250 V AC (resistive load)
output	1a	1 A 250 V AC (inductive load $\cos\phi$ =0.4)
		Electrical life: 100,000 cycles
		Minimum applicable load: 10 mA 5 V DC
	Non-contact	12 V DC±15%
	voltage (For SSR drive)	Max 40 mA (short circuit protected)
	Direct current	4 to 20 mA DC
		Resolution: 12000
		Load resistance: Max 550 $\Omega$

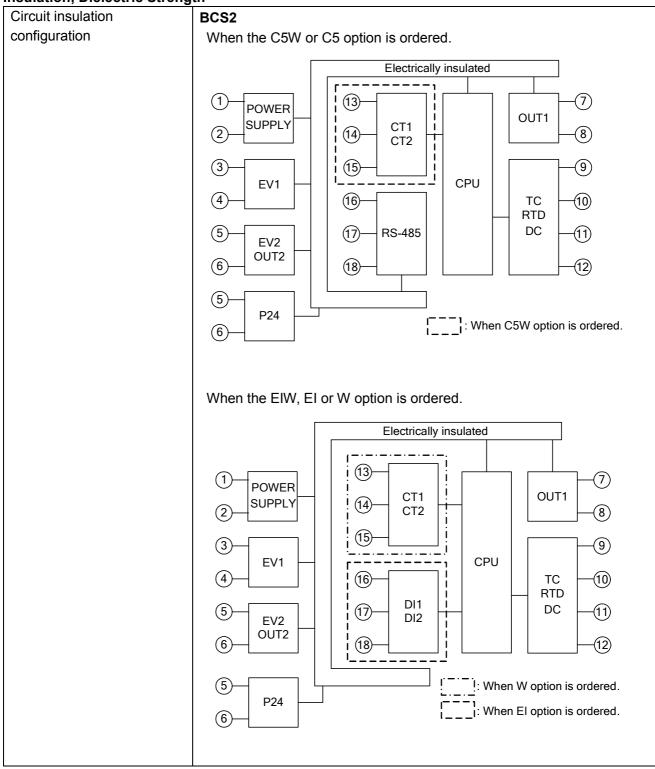
### **Standard Function**

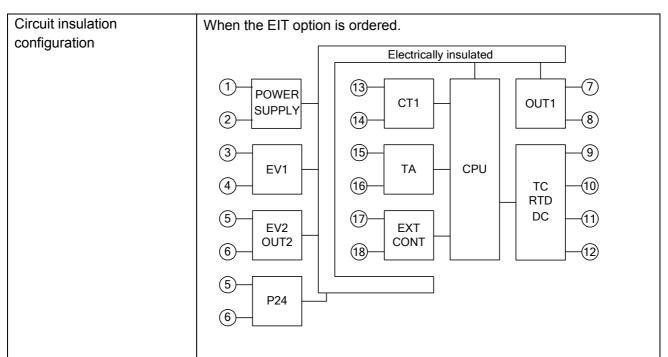
Standard F			
EV1 output		The output is turned ON or OFF depending on the conditions selected in	
		[Event output EV1 allocation].	
		Relay contact 1a Control capacity: 3 A 250 V AC (resistive load)	
		1 A 250 V AC (inductive load $\cos\phi$ =0.4)	
		Electrical life: 100,000 cycles	
		Minimum applicable load: 10 mA 5 V DC	
Alarm action	on	When an alarm type and Energized action are selected in [Event output	
		EV1 allocation] or [Event output EV2 allocation]: The alarm action point	
		is set by ±deviation from the SV (excluding Process alarm) and if PV	
		goes outside the range, alarm output is turned ON or OFF (High/Low	
		limit range alarm).	
		When De-energized action is selected, alarm is activated conversely.	
	Туре	High limit alarm, Low limit alarm, High/Low limits alarm, High/Low limits	
		independent alarm, High/Low limit range alarm, High/Low limit range	
		independent alarm, Process high alarm, Process low alarm, High limit	
		with standby alarm, Low limit with standby alarm, High/Low limits with	
		standby alarm, High/Low limits with standby independent alarm.	
		Energized/De-energized action are applied to the above alarms, totaling	
		24 alarm types. No alarm action can also be selected.	
	Action	ON/OFF action	
	Hysteresis	Thermocouple, RTD inputs: 0.1 to 1000.0°C (°F)	
		Direct current, voltage inputs: 1 to 10000 (The placement of the decimal point follows the selection.)	
	Output	EV1, EV2 outputs for which Alarm output (001 to 012) is selected in	
		[Event output EV1/EV2 allocation].	
	Alarm value 0	If 'Enabled' is selected in [Alarm value 0 Enabled/Disabled], the	
	Enabled/	following alarm type activates even if alarm value is set to 0 (zero).	
	Disabled	High limit alarm, Low limit alarm, High/Low limits alarm, High/Low limits	
		independent alarm, High/Low limit range alarm, High/Low limit range	
		independent alarm, High limit with standby alarm, Low limit with standby	
		alarm, High/Low limits with standby alarm, High/Low limits with standby	
		independent alarm.	
l oon hreal	k alarm	Detects heater burnout, sensor burnout and actuator trouble.	
Loop break alarm		EV1 or EV2 output for which Loop break alarm (014) is selected in	
		[Event output EV1/EV2 allocation].	
		· · ·	

Simplified converter function	be used as a convertor by actin	troller/Converter], this instrument can
TUTICUOT	be used as a converter, by settin Setting Item	Values or Selection
	SV1	Scaling low limit value
	SV2	Scaling low limit value
	(BCS2: EIW, EIT, EI options,	
	BCR2/BCD2: C5W, EIW, EIT, EI options,	
	SV3 (EIW option)	Scaling low limit value
	(BCS2: EIW, EI options,	
	BCR2/BCD2: C5W, EIW, EIT, EI options)	
	SV4 (EIW option)	Scaling low limit value
	(BCS2: EIW, EI options,	
	BCR2/BCD2: C5W, EIW, EIT, EI options)	
	AT/Auto-reset Perform/Cancel	AT/AT on startup/Auto-reset Cancel
	OUT1 proportional band	Input span
	Integral time	0
	Derivative time	0
	Reset	0 (Reset value, calculated by Auto-reset function)
	OUT2 proportional band	Input span
	EV1/EV2 alarm value 0	Disabled
	Enabled/Disabled	
	EV1/EV2 alarm value	0 or Input range low limit value (Scalin low limit value)
	EV1/EV2 high limit alarm value	0 or Input range low limit value (Scalin low limit value)
	EV1/EV2 alarm hysteresis	1.0
	EV1/EV2 alarm delay time	0
	EV1/EV2 alarm Energized/	Energized
	De-energized	
	Loop break alarm time	0
	Loop break alarm span	0
	Direct/Reverse control	Direct control
	OUT/OFF key function	Control output OFF function
	Event input DI1 allocation	000: No event
	(BCS2: EIW, EIT, EI options,	
	BCR2/BCD2: C5W, EIW, EIT, EI options)	
	Event input DI2 allocation	000: No event
	(BCS2: EIW, EI option,	
	BCR2/BCD2: C5W, EIW, EIT, EI options)	
	Event output EV1 allocation	000: No event
	Event output EV2 allocation	000: No event
	(EV2 option)	
	Remote/Local	Local
	(EIT option)	-
	Transmission output type	PV transmission
	(EIT option) Transmission output high limit	Input range high limit

Transmission output low limit	Input range low limit
(EIT option)	
SV rise rate	0
SV fall rate	0
OUT1 high limit	100
OUT1 low limit	0
OUT1 rate-of-change	0
4 to 20 mA DC	
Load resistance: Max 550 $\Omega$	

### Insulation, Dielectric Strength

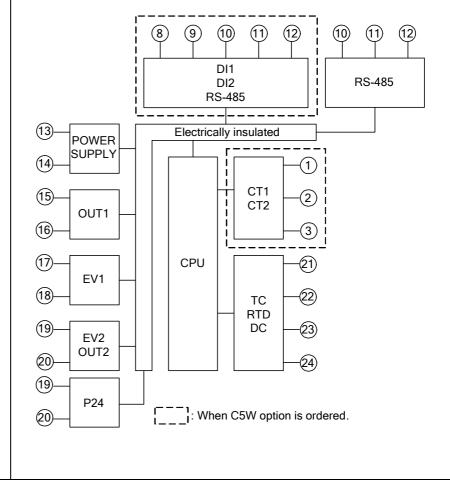


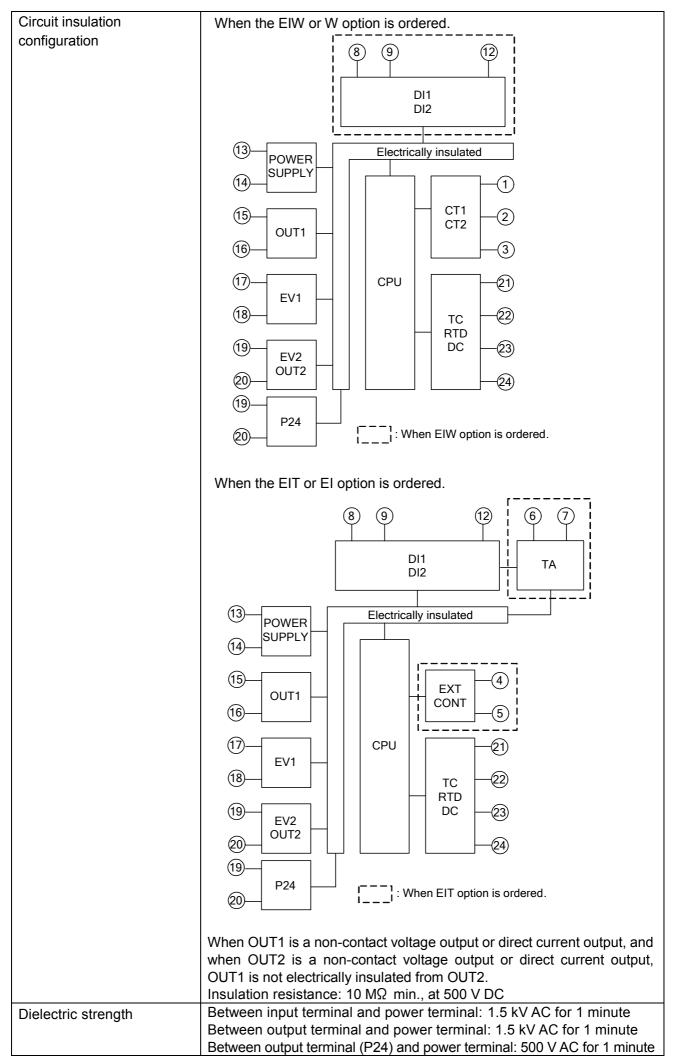


When OUT1 is a non-contact voltage output or direct current output, and when OUT2 is a non-contact voltage output or direct current output, OUT1 is not electrically insulated from OUT2. Insulation resistance: 10 M $\Omega$  min., at 500 V DC

### BCR2, BCD2

When the C5W or C5 option is ordered.





Power consumption		100 to 240 V AC	Approx. 8 VA max. (When the maximum number of options are added: Approx. 11 VA max.)	
		24 V AC	Approx. 5 VA max. (When the maximum number of options are added: Approx. 8 VA max.)	
		24 V DC	Approx. 5 W max. (When the maximum number of options are added: Approx. 8 W max.)	
Rush curren	t	100 to 240 V AC	Max. 14 to 34 A	
		24 V AC	Max. 34 A	
		24 V DC	Max. 34 A	
Ambient tem	perature	-10 to 55℃ (Non-o	-10 to 55°C (Non-condensing, No icing)	
Ambient hur	nidity	35 to 85%RH (Non-condensing)		
Weight	BCS2	Approx. 110 g		
	BCR2	Approx. 160 g	Approx. 160 g	
	BCD2	Approx. 220 g		
Accessories	included	Mounting frame: 1 piece (BCS2)		
		Screw type mounting bracket: 1 set (BCR2, BCD2)		
		Instruction manual (excerpt): 1 copy		
Accessories	sold	Terminal cover		
separately		CT (Current transformer):		
		CTL-6S (For Heater burnout alarm 20 A)		
		CTL-12-S36-10L1U (For Heater burnout alarm 100 A)		
		Tool cable CMD-001		
Environmental specification		RoHS directive compliant		

### Attached Functions

Attached Fi	unctions			
Sensor correction coefficient		Sets slope of input value from a sensor.		
Sensor cor	rection	Corrects the input value from a sensor.		
Set value lo	ock	Locks the set values to prevent setting errors.		
Auto/Manu	al control	Switches Auto/Manual control.		
switching		In Manual control, sets MV with the \land or 📎 key.		
SV ramp fu	inction	When the SV is adjusted, it approaches the new SV by the preset		
		rate-of-change. Set SV rise rate and SV fall rate respectively.		
SV Rise/Fa	all rate start type	When control output is turned from OFF to ON, or switched from Manual		
		to Automatic control, SV start or PV start can be selected for SV rise rate		
		or SV fall rate action.		
Program co	ontrol	1 pattern; 9 steps		
Power failu countermea	-	The setting data is backed up in the non-volatile IC memory.		
Self-diagno	osis	The CPU is monitored by a watchdog timer, and if an abnormal status		
		occurs, the controller is switched to warm-up status, turning all outputs OFF.		
Automatic of	cold junction	This detects the temperature at the connecting terminal between the		
temperatur	e compensation	thermocouple and the instrument, and always maintains it at the same		
		status as if the reference junction location temperature was at $0^{\circ}$ C (32°F).		
Indication	Thermocouple	[Input range low limit value - 50°C (100°F)] to		
range,		[Input range high limit value + 50℃ (100°F)]		
Control	RTD	[Input range low limit value – (Input span x 1%)] to		
range		[Input range high limit value + 50°C (100°F)]		
	DC voltage,	[Scaling low limit value – (Scaling span x 1%)] to		
	Direct current	[Scaling high limit value + Scaling span x 10%]		

Input orror						I (0 II	
Input error	Over	scale			0 0	value (Scaling	high limit value for
				/oltage, current i	• •		
					alternately indicate		ispiay.
					he preset MV is ou		
	Unde	erscale				limit value (Sca	aling low limit value
				C voltage, curre	• •		
					alternately indicate		isplay.
_			⊢or I	Manual control, t	he preset MV is ou	itput.	
Burnout						_	
If PV has alternate		eded Indic	ation	range, Control ra	ange, the PV Displa	ay indicates [	¯ ¯] and [ <i>E − Ū ¯</i> ]
If PV has [ <i>∃ ר ם </i> ]]			Indica	ation range, Con	trol range, the PV	Display indicate	es [ ] and
			DC vo	ltage (0 to 1 V D	C) input is burnt ou	t or disconnect	ed, the PV Display
	-			] alternately.	, <b>.</b>		
	-			s disconnected:			
	-		•		Display indicates [	] and [E	<i>⊢ ت</i> ] alternately.
				•	DC inputs, the PV I		
				or 0 V DC input.	-		
		-		•	2 low limit value for	Direct ourroot	
				MV is output.		Direct current	oulpul type).
					lorm is colocted in	Event output E	(1/E)/2 allocation]
							V1/EV2 allocation],
	•				active conditions.		
In Progra	am cor	itrol, Burno	out is	enabled even in	standby (program	control waiting	) mode.
		•		-	used only for contr	ollers using Dir	ect current and
voltage ir							
For manu	ual cor	ntrol, the p	reset	MV is output.	Outputs	status	
For manu Output s	ual cor status	ntrol, the p Conter	reset	MV is output.	Output s	0	UT2
For manu	ual cor status put	ntrol, the p	reset nts	MV is output. O Direct(Cooling)	UT1 Reverse(Heating)	O Direct(Cooling)	Reverse(Heating)
For manu Output s when inp	ual cor status put	ntrol, the p Conter and Indicati	reset nts on	MV is output. O Direct(Cooling) action	UT1 Reverse(Heating) action	0	Reverse(Heating) action
For manu Output s when inp errors oc	status put ccur	ntrol, the p Conter and	reset nts on	MV is output. O Direct(Cooling) action ON (20mA) or	UT1 Reverse(Heating) action	O Direct(Cooling) action	Reverse(Heating) action ON or
For manu Output s when inp	status put ccur	ntrol, the p Conter and Indicati	reset nts on	MV is output. O Direct(Cooling) action ON (20mA) or OUT1 high limit value (*)	UT1 Reverse(Heating) action OFF (4mA) or	O Direct(Cooling) action	Reverse(Heating) action ON or OUT2 high limit value (*)
For manu Output s when inp errors of	tatus put ccur	ntrol, the p Conter and Indicati Indicates [] and	reset nts on	MV is output. O Direct(Cooling) action ON (20mA) or OUT1 high limit value (*) OFF (4mA) or	UT1 Reverse(Heating) action OFF (4mA) or OUT1 low limit	O Direct(Cooling) action OFF or OUT2 low	Reverse(Heating) action ON or OUT2 high limit value (*) OFF or
For manu Output s when inp errors oc	tatus put ccur	ntrol, the p Conter and Indication Indicates [ ] and [E – [] ]]	reset nts on	MV is output. O Direct(Cooling) action ON (20mA) or OUT1 high limit value (*) OFF (4mA) or OUT1 low	UT1 Reverse(Heating) action OFF (4mA) or	O Direct(Cooling) action	Reverse(Heating) action ON or OUT2 high limit value (*) OFF or OUT2 low
For manu Output s when inp errors of	tatus put ccur	ntrol, the p Conter and Indication Indicates [ ] and [ミーロ 7] alternate	reset nts on ly.	MV is output. O Direct(Cooling) action ON (20mA) or OUT1 high limit value (*) OFF (4mA) or	UT1 Reverse(Heating) action OFF (4mA) or OUT1 low limit value	O Direct(Cooling) action OFF or OUT2 low limit value	Reverse(Heating) action ON or OUT2 high limit value (*) OFF or
For manu Output s when inp errors oc	tatus put ccur	Indicates	reset nts on ly.	MV is output. O Direct(Cooling) action ON (20mA) or OUT1 high limit value (*) OFF (4mA) or OUT1 low limit value	UT1 Reverse(Heating) action OFF (4mA) or OUT1 low limit value ON (20mA) or	O Direct(Cooling) action OFF or OUT2 low	Reverse(Heating) action ON or OUT2 high limit value (*) OFF or OUT2 low limit value
For manu Output s when inp errors of	tatus put ccur	Indicates	reset nts on ly.	MV is output. O Direct(Cooling) action ON (20mA) or OUT1 high limit value (*) OFF (4mA) or OUT1 low limit value OFF (4mA) or	UT1 Reverse(Heating) action OFF (4mA) or OUT1 low limit value ON (20mA) or OUT1 high limit value (*)	O Direct(Cooling) action OFF or OUT2 low limit value ON or OUT2 high limit value (*)	Reverse(Heating) action ON or OUT2 high limit value (*) OFF or OUT2 low limit value OFF or
For manu Output s when inp errors oc on of FF	itatus put ccur	htrol, the p Conter and Indicates $\begin{bmatrix} - & - \\ - & - \end{bmatrix}$ and $\begin{bmatrix} E - & 0 \\ 7 \end{bmatrix}$ alternate	reset nts on ly.	MV is output. O Direct(Cooling) action ON (20mA) or OUT1 high limit value (*) OFF (4mA) or OUT1 low limit value OFF (4mA) or OUT1 low	UT1 Reverse(Heating) action OFF (4mA) or OUT1 low limit value ON (20mA) or OUT1 high limit value (*) OFF (4mA) or	O Direct(Cooling) action OFF or OUT2 low limit value ON or OUT2 high limit value (*) OFF or	Reverse(Heating) action ON or OUT2 high limit value (*) OFF or OUT2 low limit value OFF or OUT2 low
For manu Output s when inp errors oc	itatus put ccur	htrol, the p Conter and Indicates $\begin{bmatrix} - & - \\ - & - \end{bmatrix}$ and $\begin{bmatrix} E - & T \end{bmatrix}$ alternate Indicates $\begin{bmatrix} - & - \\ - & - \end{bmatrix}$ and $\begin{bmatrix} E - & T \end{bmatrix}$	reset nts on ly.	MV is output. O Direct(Cooling) action ON (20mA) or OUT1 high limit value (*) OFF (4mA) or OUT1 low limit value OFF (4mA) or	UT1 Reverse(Heating) action OFF (4mA) or OUT1 low limit value ON (20mA) or OUT1 high limit value (*) OFF (4mA) or OUT1 low limit	O Direct(Cooling) action OFF or OUT2 low limit value ON or OUT2 high limit value (*) OFF or OUT2 low	Reverse(Heating) action ON or OUT2 high limit value (*) OFF or OUT2 low limit value OFF or
For manu Output s when inp errors oc o F F		htrol, the p Conter and Indicates $\begin{bmatrix} - & - \\ - & - \end{bmatrix}$ alternate $\begin{bmatrix} E - & - \\ - & - \end{bmatrix}$ and $\begin{bmatrix} E - & - \\ - & - \end{bmatrix}$ and $\begin{bmatrix} E - & - \\ - & - \end{bmatrix}$ alternate	reset nts on ly.	MV is output. O Direct(Cooling) action ON (20mA) or OUT1 high limit value (*) OFF (4mA) or OUT1 low limit value OFF (4mA) or OUT1 low limit value	UT1 Reverse(Heating) action OFF (4mA) or OUT1 low limit value ON (20mA) or OUT1 high limit value (*) OFF (4mA) or OUT1 low limit value	O Direct(Cooling) action OFF or OUT2 low limit value ON or OUT2 high limit value (*) OFF or OUT2 low limit value	Reverse(Heating) action ON or OUT2 high limit value (*) OFF or OUT2 low limit value OFF or OUT2 low limit value
For manu Output s when inp errors oc D T D F C T (*) Outputs a	a value b	htrol, the p Conter and Indicates $\begin{bmatrix} - & - \\ - & - \end{bmatrix}$ alternate $\begin{bmatrix} - & - & - \end{bmatrix}$ alternate etween OFF	ly.	MV is output. O Direct(Cooling) action ON (20mA) or OUT1 high limit value (*) OFF (4mA) or OUT1 low limit value OFF (4mA) or OUT1 low limit value	UT1 Reverse(Heating) action OFF (4mA) or OUT1 low limit value ON (20mA) or OUT1 high limit value (*) OFF (4mA) or OUT1 low limit	O Direct(Cooling) action OFF or OUT2 low limit value ON or OUT2 high limit value (*) OFF or OUT2 low limit value	Reverse(Heating) action ON or OUT2 high limit value (*) OFF or OUT2 low limit value OFF or OUT2 low limit value
For manu Output s when inp errors oc DFF DF C (*) Outputs a limit value	ial cor status put ccur	htrol, the p Conter and Indicates $\begin{bmatrix} - & - & - \\ - & - & - \end{bmatrix}$ alternate Indicates $\begin{bmatrix} - & - & - & - \\ - & - & - & - \end{bmatrix}$ alternate etween OFF ding on devia	ly. (4mA) :	MV is output. O Direct(Cooling) action ON (20mA) or OUT1 high limit value (*) OFF (4mA) or OUT1 low limit value OFF (4mA) or OUT1 low limit value	UT1 Reverse(Heating) action OFF (4mA) or OUT1 low limit value ON (20mA) or OUT1 high limit value (*) OFF (4mA) or OUT1 low limit value tween OUT1 (or OUT2)	O Direct(Cooling) action OFF or OUT2 low limit value ON or OUT2 high limit value (*) OFF or OUT2 low limit value low limit value and o	Reverse(Heating) action ON or OUT2 high limit value (*) OFF or OUT2 low limit value OFF or OUT2 low limit value
For manu Output s when inp errors oc D T D F C T (*) Outputs a	ial cor status put ccur	htrol, the p Conter and Indicates $\begin{bmatrix} - & - & - \\ - & - & - \end{bmatrix}$ alternate Indicates $\begin{bmatrix} - & - & - & - \\ - & - & - & - \end{bmatrix}$ alternate etween OFF ding on devia	ly. (4mA) attion.	MV is output. O Direct(Cooling) action ON (20mA) or OUT1 high limit value (*) OFF (4mA) or OUT1 low limit value OFF (4mA) or OUT1 low limit value and ON (20mA) or be	UT1 Reverse(Heating) action OFF (4mA) or OUT1 low limit value ON (20mA) or OUT1 high limit value (*) OFF (4mA) or OUT1 low limit value tween OUT1 (or OUT2)	O Direct(Cooling) action OFF or OUT2 low limit value ON or OUT2 high limit value (*) OFF or OUT2 low limit value low limit value and o ent is turned of	Reverse(Heating) action ON or OUT2 high limit value (*) OFF or OUT2 low limit value OFF or OUT2 low limit value
For manu Output s when inp errors oc DFF DF C (*) Outputs a limit value	ial cor status put ccur	htrol, the p Conter and Indicates $\begin{bmatrix} - & - & - \\ - & - & - \end{bmatrix}$ alternate Indicates $\begin{bmatrix} - & - & - & - \\ - & - & - & - \end{bmatrix}$ alternate etween OFF ding on devia	ly. (4mA) attor. After	MV is output. O Direct(Cooling) action ON (20mA) or OUT1 high limit value (*) OFF (4mA) or OUT1 low limit value OFF (4mA) or OUT1 low limit value and ON (20mA) or be the power sup sates the input ty	UT1 Reverse(Heating) action OFF (4mA) or OUT1 low limit value ON (20mA) or OUT1 high limit value (*) OFF (4mA) or OUT1 low limit value tween OUT1 (or OUT2)	O Direct(Cooling) action OFF or OUT2 low limit value ON or OUT2 high limit value (*) OFF or OUT2 low limit value low limit value and o ent is turned o ay indicates in	Reverse(Heating) action ON or OUT2 high limit value (*) OFF or OUT2 low limit value OFF or OUT2 low limit value DUT1 (or OUT2) high
For manu Output s when inp errors oc DFF DF C (*) Outputs a limit value	ial cor status put ccur	htrol, the p Conter and Indicates $\begin{bmatrix} - & - & - \\ - & - & - \end{bmatrix}$ alternate Indicates $\begin{bmatrix} - & - & - & - \\ - & - & - & - \end{bmatrix}$ alternate etween OFF ding on devia	ly. (4mA) attion. After indicu	MV is output. O Direct(Cooling) action ON (20mA) or OUT1 high limit value (*) OFF (4mA) or OUT1 low limit value OFF (4mA) or OUT1 low limit value and ON (20mA) or be the power sup cates the input ty e (for thermocou	UT1 Reverse(Heating) action OFF (4mA) or OUT1 low limit value ON (20mA) or OUT1 high limit value (*) OFF (4mA) or OUT1 low limit value tween OUT1 (or OUT2) ply to the instrum ype, and SV Displa ple, RTD inputs) o	O Direct(Cooling) action OFF or OUT2 low limit value ON or OUT2 high limit value (*) OFF or OUT2 low limit value low limit value and o ent is turned o ay indicates inp r scaling high li	Reverse(Heating) action ON or OUT2 high limit value (*) OFF or OUT2 low limit value OFF or OUT2 low limit value DUT1 (or OUT2) high DUT1 (or OUT2) high
For manu Output s when inp errors of D T D T D T C F C (*) Outputs a limit value Warm-up inc	ial cor status put ccur	htrol, the p Conter and Indicates $\begin{bmatrix} - & - & - \\ - & - & - \end{bmatrix}$ alternate Indicates $\begin{bmatrix} - & - & - & - \\ - & - & - & - \end{bmatrix}$ alternate etween OFF ding on devia	ly. (4mA) ; attion. After indic value	MV is output. O Direct(Cooling) action ON (20mA) or OUT1 high limit value (*) OFF (4mA) or OUT1 low limit value OFF (4mA) or OUT1 low limit value and ON (20mA) or be the power sup cates the input ty e (for thermocou	UT1 Reverse(Heating) action OFF (4mA) or OUT1 low limit value ON (20mA) or OUT1 high limit value (*) OFF (4mA) or OUT1 low limit value tween OUT1 (or OUT2) ply to the instrum vpe, and SV Displa ple, RTD inputs) of nputs) for approxim	O Direct(Cooling) action OFF or OUT2 low limit value ON or OUT2 high limit value (*) OFF or OUT2 low limit value low limit value and o ent is turned o ay indicates in r scaling high lin nately 3 second	Reverse(Heating) action         ON or         OUT2 high         limit value (*)         OFF or         OUT2 low         limit value         OUT1 (or OUT2) high
For manu Output s when inp errors of D T D T (*) Outputs a limit value Warm-up inc	a value b e, depen	htrol, the p Conter and Indicates $\begin{bmatrix} - & - & - \\ - & - & - \end{bmatrix}$ alternate Indicates $\begin{bmatrix} - & - & - & - \\ - & - & - & - \end{bmatrix}$ alternate etween OFF ding on devia	ly. (4mA) attor value curre By	MV is output. O Direct(Cooling) action ON (20mA) or OUT1 high limit value (*) OFF (4mA) or OUT1 low limit value OFF (4mA) or OUT1 low limit value and ON (20mA) or be the power sup cates the input ty e (for thermocou ent and voltage in connecting to t	UT1 Reverse(Heating) action OFF (4mA) or OUT1 low limit value ON (20mA) or OUT1 high limit value (*) OFF (4mA) or OUT1 low limit value tween OUT1 (or OUT2) oply to the instrum (pe, and SV Displa ple, RTD inputs) of nputs) for approxim he tool cable (CI	OFF or OUT2 low limit value ON or OUT2 high limit value (*) OFF or OUT2 low limit value (*) OFF or OUT2 low limit value low limit value and of ent is turned of ay indicates input second mately 3 second MD-001, sold	Reverse(Heating) action         ON or OUT2 high limit value (*)         OFF or OUT2 low limit value         OUT1 (or OUT2) high         OUT1 (or OUT2) high limit value (for Direct ls. separately) to the
For manu Output s when inp errors of D T D T D T C F C (*) Outputs a limit value Warm-up inc	a value b e, depen	htrol, the p Conter and Indicates $\begin{bmatrix} - & - & - \\ - & - & - \end{bmatrix}$ alternate Indicates $\begin{bmatrix} - & - & - & - \\ - & - & - & - \end{bmatrix}$ alternate etween OFF ding on devia	ly. (4mA) attor value curre By cons	MV is output. O Direct(Cooling) action ON (20mA) or OUT1 high limit value (*) OFF (4mA) or OUT1 low limit value OFF (4mA) or OUT1 low limit value or OUT1 low limit value or output low limit value limit value or output low limit value or output low limit value limit value or output low limit value or or or or or or or or or or	UT1 Reverse(Heating) action OFF (4mA) or OUT1 low limit value ON (20mA) or OUT1 high limit value (*) OFF (4mA) or OUT1 low limit value tween OUT1 (or OUT2) oply to the instrum ype, and SV Displa ple, RTD inputs) of nputs) for approxin he tool cable (Cl the following operation	OFF or OUT2 low limit value ON or OUT2 high limit value (*) OFF or OUT2 low limit value (*) OFF or OUT2 low limit value low limit value adv indicates in r scaling high lin nately 3 second VD-001, sold ations can be of	Reverse(Heating) action         ON or OUT2 high limit value (*)         OFF or OUT2 low limit value         OFF or OUT2 low limit value         OFF or OUT2 low limit value         OUT1 (or OUT2) high         DUT1 (or OUT2) high limit value         DUT1 (or OUT2) high limit value         OUT1 (or OUT2) high         DUT1 (or OUT2) high limit value (for Direct ls.         separately) to the conducted from an
For manu Output s when inp errors of D T D T (*) Outputs a limit value Warm-up inc	a value b e, depen	htrol, the p Conter and Indicates $\begin{bmatrix} - & - & - \\ - & - & - \end{bmatrix}$ alternate Indicates $\begin{bmatrix} - & - & - & - \\ - & - & - & - \end{bmatrix}$ alternate etween OFF ding on devia	ly. (4mA) attion. After indic value cons exte	MV is output. O Direct(Cooling) action ON (20mA) or OUT1 high limit value (*) OFF (4mA) or OUT1 low limit value OFF (4mA) or OUT1 low limit value and ON (20mA) or be the power sup cates the input ty e (for thermocou ent and voltage in connecting to t sole connector, for ernal computer, u	UT1 Reverse(Heating) action OFF (4mA) or OUT1 low limit value ON (20mA) or OUT1 high limit value (*) OFF (4mA) or OUT1 low limit value tween OUT1 (or OUT2) oply to the instrum ype, and SV Displa ple, RTD inputs) of nputs) for approxim he tool cable (Cl the following opera- sing the Console s	OFF or OUT2 low limit value ON or OUT2 high limit value (*) OFF or OUT2 low limit value (*) OFF or OUT2 low limit value low limit value and ( ent is turned of ay indicates in r scaling high lin nately 3 second MD-001, sold ations can be of software SWC-F	Reverse(Heating) action         ON or OUT2 high limit value (*)         OFF or OUT2 low limit value         OUT1 (or OUT2) high         Dutt (or OUT2) high         Dutt (or OUT2) high         Dutt ange high limit mit value (for Direct ls.         separately) to the conducted from an BCx01M.
For manu Output s when inp errors of D T D T (*) Outputs a limit value Warm-up inc	a value b e, depen	htrol, the p Conter and Indicates $\begin{bmatrix} - & - & - \\ - & - & - \end{bmatrix}$ alternate Indicates $\begin{bmatrix} - & - & - & - \\ - & - & - & - \end{bmatrix}$ alternate etween OFF ding on devia	ly. (4mA) : ition. After indic value curre By cons exte Con	MV is output. O Direct(Cooling) action ON (20mA) or OUT1 high limit value (*) OFF (4mA) or OUT1 low limit value OFF (4mA) or OUT1 low limit value or OUT1 low limit value or outf 1 low limit value or or be or or outf 1 low limit value or be or or be or or be or or be or or be or or computer, u sole communication	UT1 Reverse(Heating) action OFF (4mA) or OUT1 low limit value ON (20mA) or OUT1 high limit value (*) OFF (4mA) or OUT1 low limit value tween OUT1 (or OUT2) oply to the instrum ype, and SV Displa ple, RTD inputs) of nputs) for approxim he tool cable (Cl the following opera- sing the Console s	OFF or OUT2 low limit value ON or OUT2 high limit value (*) OFF or OUT2 low limit value (*) OFF or OUT2 low limit value low limit value and ( ent is turned of ay indicates in r scaling high lin nately 3 second MD-001, sold ations can be of software SWC-F	Reverse(Heating) action         ON or OUT2 high limit value (*)         OFF or OUT2 low limit value         OFF or OUT2 low limit value         OFF or OUT2 low limit value         OUT1 (or OUT2) high         DUT1 (or OUT2) high limit value         DUT1 (or OUT2) high limit value         OUT1 (or OUT2) high         DUT1 (or OUT2) high limit value (for Direct ls. separately) to the conducted from an
For manu Output s when inp errors of D T D T (*) Outputs a limit value Warm-up inc	a value b e, depen	htrol, the p Conter and Indicates $\begin{bmatrix} - & - & - \\ - & - & - \end{bmatrix}$ alternate Indicates $\begin{bmatrix} - & - & - & - \\ - & - & - & - \end{bmatrix}$ alternate etween OFF ding on devia	ly. (4mA) : ation. After indic value cons exte Con be u	MV is output. O Direct(Cooling) action ON (20mA) or OUT1 high limit value (*) OFF (4mA) or OUT1 low limit value OFF (4mA) or OUT1 low limit value or OUT1 low limit value and ON (20mA) or be the power sup cates the input ty e (for thermocou ent and voltage in connecting to t sole connector, the production of the sole communication of the sole communication of the sole communication of the or and together.	UT1 Reverse(Heating) action OFF (4mA) or OUT1 low limit value ON (20mA) or OUT1 high limit value (*) OFF (4mA) or OUT1 low limit value tween OUT1 (or OUT2) oply to the instrum (pe, and SV Displa ple, RTD inputs) of nputs) for approxim he tool cable (Cl the following opera- sing the Console so this and Serial con	OFF or OUT2 low limit value ON or OUT2 high limit value (*) OFF or OUT2 low limit value (*) OFF or OUT2 low limit value low limit value and of ent is turned of ay indicates input r scaling high limit nately 3 second MD-001, sold ations can be of software SWC-Emmunication (O	Reverse(Heating) action         ON or OUT2 high limit value (*)         OFF or OUT2 low limit value         OUT1 (or OUT2) high         DUT1 (or OUT2) high         Dut range high limit mit value (for Direct ls.         separately) to the conducted from an BCx01M.         C5W option) cannot
For manu Output s when inp errors of D T D T (*) Outputs a limit value Warm-up inc	a value b e, depen	htrol, the p Conter and Indicates $\begin{bmatrix} - & - & - \\ - & - & - \end{bmatrix}$ alternate Indicates $\begin{bmatrix} - & - & - & - \\ - & - & - & - \end{bmatrix}$ alternate etween OFF ding on devia	ly. (4mA) is (4mA) is (4mA) is atton. After indic value cons exte Con be u (1) F	MV is output. O Direct(Cooling) action ON (20mA) or OUT1 high limit value (*) OFF (4mA) or OUT1 low limit value OFF (4mA) or OUT1 low limit value OFF (4mA) or OUT1 low limit value or output low limit value output low limit value connecting to t sole connector, f output low limit computer, u sole communication lised together. Reading and setti	UT1 Reverse(Heating) action OFF (4mA) or OUT1 low limit value ON (20mA) or OUT1 high limit value (*) OFF (4mA) or OUT1 low limit value (*) OFF (4mA) or OUT1 low limit value tween OUT1 (or OUT2) oply to the instrum ype, and SV Displa ple, RTD inputs) of nputs) for approxin he tool cable (Cl the following opera- sing the Console s ation and Serial con-	OFF or OUT2 low limit value ON or OUT2 high limit value (*) OFF or OUT2 low limit value (*) OFF or OUT2 low limit value low limit value and of ent is turned of ay indicates input r scaling high limit nately 3 second MD-001, sold ations can be of software SWC-Emmunication (O	Reverse(Heating) action         ON or OUT2 high limit value (*)         OFF or OUT2 low limit value         OUT1 (or OUT2) high         DUT1 (or OUT2) high         Dut range high limit mit value (for Direct ls.         separately) to the conducted from an BCx01M.         C5W option) cannot
For manu Output s when inp errors of D T D T (*) Outputs a limit value Warm-up inc	a value b e, depen	htrol, the p Conter and Indicates $\begin{bmatrix} - & - & - \\ - & - & - \end{bmatrix}$ alternate Indicates $\begin{bmatrix} - & - & - & - \\ - & - & - & - \end{bmatrix}$ alternate etween OFF ding on devia	ly. ly. ly. (4mA) : idion. After indic value cons exte Con be u (1) F (2) F	MV is output. O Direct(Cooling) action ON (20mA) or OUT1 high limit value (*) OFF (4mA) or OUT1 low limit value OFF (4mA) or OUT1 low limit value or OUT1 low limit value and ON (20mA) or be the power sup cates the input ty e (for thermocou ent and voltage in connecting to t sole connector, for reading and setti Reading of PV ar	UT1 Reverse(Heating) action OFF (4mA) or OUT1 low limit value ON (20mA) or OUT1 high limit value (*) OFF (4mA) or OUT1 low limit value (*) OFF (4mA) or OUT1 low limit value tween OUT1 (or OUT2) oply to the instrum ype, and SV Displa ple, RTD inputs) of nputs) for approxin he tool cable (Cl the following opera- sing the Console s ation and Serial con-	OFF or OUT2 low limit value ON or OUT2 high limit value (*) OFF or OUT2 low limit value (*) OFF or OUT2 low limit value low limit value and of ent is turned of ay indicates input r scaling high limit nately 3 second MD-001, sold ations can be of software SWC-Emmunication (O	Reverse(Heating) action         ON or OUT2 high limit value (*)         OFF or OUT2 low limit value         OUT1 (or OUT2) high         DUT1 (or OUT2) high         Dut range high limit mit value (for Direct ls.         separately) to the conducted from an BCx01M.         C5W option) cannot
For manu Output s when inp errors of D D D F F (*) Outputs a limit value Warm-up inc	a value b e, depen	htrol, the p Conter and Indicates $\begin{bmatrix} - & - & - \\ - & - & - \end{bmatrix}$ alternate Indicates $\begin{bmatrix} - & - & - & - \\ - & - & - & - \end{bmatrix}$ alternate etween OFF ding on devia	Iy. Iy. Iy. (4mA) : indic value cons exte Con be u (1) F (2) F (3) F	MV is output. O Direct(Cooling) action ON (20mA) or OUT1 high limit value (*) OFF (4mA) or OUT1 low limit value OFF (4mA) or OUT1 low limit value OFF (4mA) or OUT1 low limit value or output low limit value output low limit value connecting to t sole connector, for sole communication sole communication lised together. Reading and setting	UT1 Reverse(Heating) action OFF (4mA) or OUT1 low limit value ON (20mA) or OUT1 high limit value (*) OFF (4mA) or OUT1 low limit value (*) OFF (4mA) or OUT1 low limit value tween OUT1 (or OUT2) oply to the instrum (pe, and SV Displa ple, RTD inputs) of nputs) for approxim he tool cable (Cl the following opera- sing the Console s ation and Serial con- ing of SV, PID and ad action status	OFF or OUT2 low limit value ON or OUT2 high limit value (*) OFF or OUT2 low limit value (*) OFF or OUT2 low limit value low limit value and of ent is turned of ay indicates input r scaling high limit nately 3 second MD-001, sold ations can be of software SWC-Emmunication (O	Reverse(Heating) action         ON or OUT2 high limit value (*)         OFF or OUT2 low limit value         OUT1 (or OUT2) high         DUT1 (or OUT2) high         Dut range high limit mit value (for Direct ls.         separately) to the conducted from an BCx01M.         C5W option) cannot

### **11.2 Optional Specifications**

2 Optional Specifications				
Event input	2 points of Event input (BCS2: 1 point for EIT option) can be applied.			
BCS2: EIW, EIT, EI options	Any Event selected in [Event input DI1/DI2 allocation] will be performed			
BCR2/BCD2: C5W, EIW,	depending on the DI1/DI2 input ON (Closed) or OFF (Open) status.			
EIT, EI options	Circuit current when Closed: Approx. 16 mA			
Event output	Output will be turned ON or OFF depending on the Event conditions			
(EV2 option)	selected in [Event output EV2 allocation].			
( · )	Relay contact, 1a			
	Control capacity: 3 A 250 V AC (resistive load)			
	$1 \text{ A } 250 \text{ V AC}$ (inductive load, $\cos\phi=0.4$ )			
	Electric life: 100,000 cycles			
	Minimum applicable load: 10 mA 5 V DC			
Heater burnout alarm	Monitors heater current with CT (current transformer), and detects burnout.			
(C5W, EIW, W options)	EV1/EV2 output, for which Heater burnout alarm is selected in [Event output			
	· · · ·			
	EV1/EV2 allocation], will be turned ON or OFF.			
	This alarm is also activated when the input is burnt out.			
	Rated current: 20 A, 100 A (Must be specified when ordering.)			
	Single-phase: Detects burnout with CT1 input.			
	3-phase: Detects burnout with CT1 and CT2 inputs.			
	Setting accuracy: Within $\pm 5\%$ of the rated value			
Heating/Cooling control	Performs Heating/Cooling control.			
(DS, DA, EV2 options)	(Specifications of Heating side are the same as those of OUT1.)			
	OUT2 proportional band:			
	Thermocouple, RTD inputs without decimal point: 0 to Input span			
	Thermocouple, RTD inputs with decimal point: 0.0 to Input span			
	DC voltage, current inputs: 0.0 to 1000.0%			
	OUT2 integral time: Same as OUT1 integral time			
	OUT2 derivative time: Same as OUT1 derivative time			
	OUT2 proportional cycle: 0.5, or 1 or 120 seconds			
	Overlap/Dead band setting range:			
	Thermocouple, RTD inputs: -200.0 to 200.0°C (°F)			
	DC voltage, current inputs: -2000 to 2000 (The placement of the decimal			
	point follows the selection.)			
	OUT2 ON/OFF hysteresis:			
	Thermocouple, RTD inputs: 0.1 to 1000.0℃ (°F)			
	DC voltage, current inputs: 1 to 10000 (The placement of the decimal point			
	follows the selection.)			
	OUT2 high limit: 0 to 100% (Direct current: -5 to 105%)			
	OUT2 low limit: 0 to 100% (Direct current: -5 to 105%)			
	OUT2 cooling method			
	One cooling method can be selected from Air cooling (linear			
	characteristics), Oil cooling (1.5th power of the linear characteristics)			
	and Water cooling (2nd power of the linear characteristics) by keypad			
	operation.			
	Cooling output (OUT2):			
	Control capacity: 3 A 250 V AC (resistive load)			
	1 A 250 V AC (inductive load, $\cos\phi$ =0.4)			
	Electric life: 100,000 cycles			
	Non-contact voltage (for SSR drive) (DS): 12 V DC±15%,			
	Max. 40 mA (short circuit protected)			
	Resolution: 12000			
	<ul> <li>Relay contact 1a (EV2)</li> <li>Control capacity: 3 A 250 V AC (resistive load)</li> <li>1 A 250 V AC (inductive load, cos¢=0.4)</li> <li>Electric life: 100,000 cycles</li> <li>Non-contact voltage (for SSR drive) (DS): 12 V DC±15%,</li> <li>Max. 40 mA (short circuit protected)</li> <li>Direct current (DA): 4 to 20 mA DC</li> </ul>			

Carial as remained to the	The fellowing as a	rations are be	mind and function and a	tornal commuter		
Serial communication	The following operations can be carried out from an external computer.					
(C5W, C5 options)	Serial communication and Console communication cannot be used					
	together.					
	· ,	•	PID values and variou	us set values		
	(2) Reading of the	PV and action sta	atus			
	(3) Function chang	je				
	Cable length: Max	x 1.2 km, Cable r	esistance: Within 50	$\Omega$ (Terminators are		
	not	necessary, but if	used, use 120 $\Omega$ or	more on both		
	not necessary, but if used, use 120 $\Omega$ or more on both sides.)					
	Communication li	,				
			ex communication			
			p synchronization			
	-		0/38400 bps (Select	ahle hy keynad)		
		•	Odd, No parity (Sele	,		
	-			ciable by Keypau)		
	Stop bit: 1 bit, 2 b	•				
	Communication p	•	protocol/Modbus ASC	II/MODDUS RIU		
		(Selecta	ble by keypad)			
	Data format:					
	Communication	Shinko	Modbus ASCII	Modbus RTU		
	protocol	protocol				
	Start bit	1	1	1		
	Data bit	7	7 or 8	8		
	Parity	Yes (Even)	Yes (Even, Odd), No parity	Yes (Even, Odd), No parity		
	Stop bit	1	1 or 2	1 or 2		
	Number of conne	ctable units: Max	timum 31 units to 1 h	ost computer		
	Communication e	error detection: Pa	arity, checksum (Shir	nko protocol),		
			odbus ASCII), CRC-	• •		
	Digital external se	·	,			
	•	•	programmable contr	rollers		
	-	33A with SVTC o				
External setting input			remote bias value.			
(EIT option)		0 0	Terriole blas value.			
	Not available for F	-				
	Setting signal: 4 to 20 mA DC					
	Allowable input: 50 mA DC max.					
	Input impedance: 50 $\Omega$ max.					
	Input sampling pe					
Transmission output	Converting the va	lue (PV, SV, MV	or DV transmission)	) to analog signal		
(EIT option)	every 125 ms, ou	tputs the value ir	n current or voltage.			
	Outputs Transmission output low limit value if Transmission output high					
	limit and low limit value are the same.					
	Resolution: 12000					
	Output: 4 to 20 mA DC (Load resistance: Maximum 550 $\Omega$ )					
		•	of Transmission outp	,		
Inculated power output			· · · · · · · · · · · · · · · · · · ·			
Insulated power output	Output voltage: 24±3 V DC (when load current is 30 mA DC)					
(P24 option)			(when load current is	s 30 mA DC)		
	Max. load current:	30 mA DC				

## 12. Troubleshooting

If any malfunctions occur, refer to the following items after checking that power is being supplied to the controller.

### 12.1 Indication

Problem	Possible Cause	Solution
[ <i>E ー 囗 「</i> ] is indicated on the PV Display.	Internal non-volatile IC memory is defective.	Cancel the error code by pressing the © key, and perform data clearing. (p.106) If the problem is not still solved, contact our agency or us.
$[E - \Box \overline{E}]$ is indicated on the PV Display.	Data writing (in non-volatile IC memory) error when power failure occurs.	Cancel the error code by pressing the $\bigcirc$ key, and perform data clearing. (p.106)
PV and [ <i>E ー ロ</i> 与] are alternately indicated on the PV Display.	Overscale. PV has exceeded Input range high limit value (scaling high limit value for DC voltage, current inputs).	Check the input signal source.
PV and $[E - GB]$ are alternately indicated on the PV Display.	Underscale. PV has dropped below Input range low limit value (scaling low limit value for DC voltage, current inputs).	Check the input signal source and wiring of input terminals.
[ ̄ ̄ ̄]and [ <i>E ー ロ ヿ</i> ] are alternately indicated	PV has exceeded the Indication range and Control range.	Check the input signal source.
on the PV Display.	Burnout of thermocouple, RTD or disconnection of DC voltage (0 to 1 V DC)	Replace each sensor. How to check whether the sensor is burnt out [Thermocouple] If the input terminals of the instrument are shorted, and if a value around room temperature is indicated, the instrument is likely to be operating normally, however, the sensor may be burnt out. [RTD] If approx. 100 $\Omega$ of resistance is connected to the input terminals between A-B of the instrument and between B-B is shorted, and if a value around 0°C (32°F) is indicated, the instrument is likely to be operating normally, however, the sensor may be burnt out. [DC voltage (0 to 1 V DC)] If the input terminals of the instrument are shorted, and if a scaling low limit value is indicated, the instrument is likely to be operating normally, however, the signal wire may be disconnected.
	Check whether the input terminals of thermocouple, RTD or DC voltage (0 to 1 V DC) are securely mounted to the instrument input terminals.	Connect the sensor terminals to the instrument input terminals securely.

Problem	Possible Cause	Solution
[] and	PV has dropped below the	Check the input signal source and wiring of input
[ <i>E – 🛛 -</i> ] are	Indication range and Control	terminals.
alternately indicated	range.	
on the PV Display.	Check whether input signal wire for DC voltage (1 to 5 V DC) or Direct current (4 to 20 mA DC) is disconnected.	How to check whether the input signal wire is disconnected [DC voltage (1 to 5 V DC)] If the input to the input terminals of the instrument is 1 V DC and if a scaling low limit value is indicated, the instrument is likely to be operating normally, however, the signal wire may be disconnected. [Direct current (4 to 20 mA DC)] If the input to the input terminals of the instrument is 4 mA DC and if a scaling low limit value is
		indicated, the instrument is likely to be operating normally, however, the signal wire may be disconnected.
	Check whether input signal wire for DC voltage (1 to 5 V DC) or current (4 to 20 mA DC) is securely connected to the instrument input terminals.	Connect the input signal wire to the terminals of this instrument securely.
	Check if polarity of thermo- couple or compensating lead wire is correct. Check whether codes (A, B, B) of RTD agree with the instrument terminals.	Wire them correctly.
$[\underline{\mathcal{E}} \vdash \underline{\mathcal{U}}]$ is indicated on the PV Display.	Hardware malfunction	Contact our agency or us.
[ <i>¤FF</i> ], nothing or PV is indicated on the PV Display.	Control output OFF function is enabled.	Press the <sup>(iii)</sup> key for approx. 1 second to cancel the function.
The indication of PV Display is irregular or unstable.	Check whether sensor input or temperature unit (°C or °F) is correct.	Select the sensor input and temperature unit (°C or °F) correctly.
	Sensor correction coefficient or Sensor correction value is unsuitable.	Set them to suitable values.
	Check whether the specification of the sensor is correct.	Use a sensor with appropriate specifications.
	AC leaks into the sensor circuit.	Use an ungrounded type sensor.
	There may be equipment that interferes with or makes noise near the instrument.	Keep the instrument clear of any potentially disruptive equipment.

Problem	Possible Cause	Solution
The PV Display keeps indicating the value set in [Scaling low limit].	Check whether the input signal wire for DC voltage (0 to 5 V DC, 0 to 10 V DC) and Direct current (0 to 20 mA DC) is disconnected.	Check the input signal wires of DC voltage (0 to 5 V DC, 0 to 10 V DC) and Direct current (0 to 20 mA DC). How to check whether the input signal wire is disconnected [DC voltage (0 to 5 V DC, 0 to 10 V DC)] If the input to the input terminal of this controller is 1 V DC, and if a value (converted value from scaling high, low limit setting) corresponding to 1 V DC is indicated, the controller is likely to be operating normally, however, the input signal wire may be disconnected. [Direct current (0 to 20 mA DC)] If the input to the input terminal of this controller is 4 mA DC, and if a value (converted value from scaling high, low limit setting) corresponding to 4 mA DC is indicated, the controller is likely to be operating normally, however, the input signal wire
	Check whether the input terminals for DC voltage (0 to 5 V DC, 0 to 10 V DC) or Direct current (0 to 20 mA DC) are securely connected to the instrument input terminals.	Connect the input terminals of DC voltage and current to the input terminals of this instrument securely.

### 12.2 Key Operation

Problem	Possible Cause	Solution
None of the set	Set value lock (Lock 1 or	Release the lock in [Set value lock].
values can be set.	Lock 4) is selected.	
	AT, 'AT on startup' or	If AT or 'AT on startup' is performing, cancel AT or
	Auto-reset is performing.	'AT on startup'.
		Please wait until Auto-reset is finished.
		(It takes approximately 4 minutes until Auto-reset is finished.)
Only SV and Alarm	Set value lock (Lock 2 or	Release the lock in [Set value lock].
value can be set.	Lock 5) is selected.	
Other settings are		
impossible.		
The setting	Scaling high or low limit value	Set it to a suitable value.
indication does not	may be set at the point where	
change in the input	the value does not change.	
range, and new		
values are unable to		
be set.		

### 12.3 Control

Problem	Possible Cause	Solution
Temperature does	Sensor is out of order.	Replace the sensor.
not rise.		•
not nse.	Check whether the sensor or	Ensure that the sensor or control output terminals
	control output terminals are	are mounted to the instrument input terminals
	securely mounted to the	securely.
	instrument input terminals.	
	Check whether the wiring of	Wire them correctly.
	sensor or control output	
	terminals is correct.	
The control output	OUT1 or OUT2 low limit value	Set it to a suitable value.
remains in an ON	is set to 100% or higher.	
status.		
The control output	OUT1 or OUT2 high limit	Set it to a suitable value.
remains in an OFF	value is set to 0% or less.	
status.		
$[\mathcal{E} - \mathcal{E} \mathcal{G}]$ is indicated	AT or 'AT on startup' has not	Set P, I, D and ARW values manually
on the PV Display.	been completed even if	
	approx. 4 hours have elapsed	
	since AT or 'AT on startup'	
	started.	
	For 'AT on startup', PV slope	
	and delay time cannot be	
	measured normally for P, I, D	
	calculation.	

For all other malfunctions, please contact our main office or dealers.

## 13. Character Table

### 13.1 Error Code

Error codes are indicated on the PV Display.

Error Code	Error Contents
E-0 /	Internal non-volatile IC memory is defective.
E-02	Data writing (in non-volatile IC memory) error when power failure occurs.
6-05	PV has exceeded Input range high limit value (Scaling high limit value for DC
	voltage, current inputs).
E-05	PV has dropped below Input range low limit value (Scaling low limit value for DC
	voltage, current inputs).
E-07	Input burnout or disconnection.
	Input value is outside of the Indication range and control range.
Er 10	Hardware malfunction
E-20	AT or 'AT on startup' has not been completed even if approx. 4 hours have
	elapsed since AT or 'AT on startup' started.
	For 'AT on startup', PV slope and delay time cannot be measured normally for P,
	I, D calculation.

### 13.2 Run Mode

Character	Indicated Item Name
oFF	Control output OFF
	Manual control
🗆 <i>10</i> ,5	(MV flashes.)

### 13.3 Monitor Mode

The PV Display indicates PV, and the SV Display indicates setting item value.

Character	Indicated Item Name
<i>2</i> 5	MV
[MV]	(Decimal point flashes.)
2s	Remaining time is indicated (When Program control is performing)
[Remaining time]	
2s	Current step number indicated (When Program control is performing) (BCS2)
[Step number]	<b>トニ / to トニ 当</b>
<i>2</i> 5	SV number indicated (BCS2)
[Memory number]	<i>ら出 1</i> □ to <i>ら出 4</i> □

### 13.4 Initial Setting Mode

The PV Display indicates setting characters, and the SV Display indicates factory default value.

Characters,	Setting Item, Setting Range							
Factory Default		Setting item, Se	Rang Kar	ige				
4874	Input type							
E	EIIIIC	K -200 to 1370 °C	E	K -328 to 2498 °F				
	£ 🗌 .Ľ	K -200.0 to 400.0 °C	E□ .F	K -328.0 to 752.0 °F				
	<u>کا اللہ</u>	J -200 to 1000 ℃	J	J -328 to 1832 °F				
	۲۲	R 0 to 1760 ℃	r[]][]F	R 32 to 3200 °F				
	<u>ר</u>	S 0 to 1760 ℃	5F	S 32 to 3200 °F				
	6 <u></u> C	B 0 to 1820 ℃	ЬШF	B 32 to 3308 °F				
	EIIIIC	E -200 to 800 ℃	E	E -328 to 1472 °F				
	ГШ .С	T -200.0 to 400.0 ℃	ГП ,F	T -328.0 to 752.0 °F				
	n	N -200 to 1300 ℃	n EF	N -328 to 2372 °F				
	PLZE	PL-Ⅱ 0 to 1390 °C	PL2F	PL-Ⅱ 32 to 2534 °F				
	۲۲	C(W/Re5-26) 0 to 2315 ℃	c DF	C(W/Re5-26) 32 to 4199 °F				
	PF j	Pt100 -200.0 to 850.0 ℃	PF F	Pt100 -328.0 to 1562.0 °F				
	JPF.E	JPt100 -200.0 to 500.0 ℃	JPEF	JPt100 -328.0 to 932.0 °F				
	Prot	Pt100 -200 to 850 ℃	PTEF	Pt100 -328 to 1562 °F				
	JPFE	JPt100 -200 to 500 ℃	JPEE	JPt100 -328 to 932 °F				
	4208	4 to 20 mA DC -2000 to 10000						
	020A	0 to 20 mA DC -2000 to 10000						
	0 18	0 to 1 V DC -2000 to 10000						
	0058	0 to 5 V DC -2000 to 10000						
	<i>I</i> ∏58	1 to 5 V DC -2000 to 10000						
	0 108	0 to 10 V DC -2000 to 10000						
55LH	Scaling hig	gh limit						
סרבו	Setting ra	ange: Scaling low limit value to in	nput rang	e high limit value				
		DC voltage, current inputs	: -2000 to	10000 (*1)				
45 <u>6</u>	Scaling lov							
-200	Setting ra	ange: Input range low limit value	•	5 0				
		DC voltage, current inputs:	: -2000 to	10000 (*1)				
dP	Decimal po	-						
		No decimal point						
		1 digit after decimal point						
		2 digits after decimal point						
	0.000	3 digits after decimal point						

(\*1) The placement of the decimal point follows the selection.

Characters, Factory Default	Setting Item, Setting Range						
E8a I	Event outp	out EV1 allocation	1				
000	[Event Output Allocation Table]						
	000	No event					
	00 i	Alarm output, Hig	gh limit alarm				
	002	Alarm output, Lov	w limit alarm				
	003	Alarm output, Hig	gh/Low limits alarm				
	004	Alarm output, Hig	gh/Low limits independent alarm				
	005	Alarm output, High/Low limit range alarm					
	005	Alarm output, Hig	gh/Low limit range independent alarm				
	007	Alarm output, Pro	ocess high alarm				
	008	Alarm output, Pro					
	009		gh limit with standby alarm				
	0 10		w limit with standby alarm				
		-	gh/Low limits with standby alarm				
	012		gh/Low limits with standby independent				
		alarm					
	<u> </u>	Heater burnout a	larm output				
	014	Loop break alarm output					
	0 15	Time signal output					
	0 15	Output during AT					
	CI 0 17	Pattern end output					
	0 18	Output by communication command					
R IER	EV1 alarm	value 0 Enabled/					
	no	Disabled					
	467	Enabled					
R (	EV1 alarm	/1 alarm value					
	High limit a		-(Input span) to Input span $^{\circ}C$ ( $^{\circ}F$ ) (*1) (*2	)			
	Low limit al		-(Input span) to Input span °C (°F) (*1) (*2				
	High/Low li		0 to Input span °C (°F) (*1) (*2)	/			
		mits independent	0 to Input span $^{\circ}C$ ( $^{\circ}F$ ) (*1) (*2)				
	alarm						
		mit range alarm	0 to Input span °℃ (°F) (*1) (*2)				
	High/Low li		0 to Input span $^{\circ}C$ ( <sup>°</sup> F) (*1) (*2)				
	independer	•					
	Process hig		Input range low limit to Input range high	limit (*1) (*3)			
	Process Iov		Input range low limit to input range high limit (*1) (*3)				
		ith standby alarm	-(Input span) to Input span $^{\circ}C$ ( $^{\circ}F$ ) (*1) (*2)				
	-	ith standby alarm	-(input span) to input span $^{\circ}$ (°F) (*1) (*2)				
		mits with standby	0 to Input span $^{\circ}$ (°F) (*1) (*2)	1			
	alarm	inito with standby					
		mits with standby	0 to Input span ℃ (°F) (*1) (*2)				
	-	-					
8 IH	independent alarm       EV1 high limit alarm value						
	-		e of EV1 alarm value				
	-	lows the selection					

(\*2) For DC voltage, current inputs, the input span is the same as the scaling span.

(\*3) For DC voltage, current inputs, input range low (or high) limit value is the same as scaling low (or high) limit value.

Characters,	Setting Kem Setting Dange							
Factory Default		Setting Item, Setting Range						
R IHY	EV1 alarm	hysteresis						
	Setting range: 0.1 to 1000.0°C(°F),							
	DC voltag	DC voltage, current inputs: 1 to 10000 (*1)						
A 144	EV1 alarm	•						
	Setting ra	Setting range: 0 to 10000 seconds						
RILA		EV1 alarm Energized/De-energized						
noñl	noñL	Energized						
	-685	De-energized						
/~ /~	TS1 output	t step number						
1	Setting ra	ange: 1 to 9						
F5 1F	TS1 OFF ti	me						
0000	Setting ra	ange: 00:00 to 99:59 (*4)						
15 lo	TS1 ON tin	10						
0000	Setting ra	ange: 00:00 to 99:59 (*4)						
E802	•	out EV2 allocation						
		utput Allocation Table]						
	000	No event						
	<i>00 i</i>	Alarm output, High limit alarm						
	002	Alarm output, Low limit alarm						
	<u> </u>	Alarm output, High/Low limits alarm						
	004	Alarm output, High/Low limits independent alarm						
	00s	Alarm output, High/Low limit range alarm						
	005	Alarm output, High/Low limit range independent alarm						
	007	Alarm output, Process high alarm						
	$\Box 008$	Alarm output, Process low alarm						
	009	Alarm output, High limit with standby alarm						
	0 10	Alarm output, Low limit with standby alarm						
	$\Box 0$ / /	Alarm output, High/Low limits with standby alarm						
	0 IZ	Alarm output, High/Low limits with standby independent						
		alarm						
		Heater burnout alarm output						
		Loop break alarm output						
		Time signal output						
		Output during AT						
		Pattern end output						
		Output by communication command						
	0 19	Heating/Cooling control relay contact output						
REER		value 0 Enabled/Disabled						
~o[]]]	no	Disabled						
	9E 4 🗌	Enabled						

(\*4) Time unit follows the selection from [Step time unit].

Characters,	6.4	ting Itom Cotting Dongo			
Factory Default	Set	tting Item, Setting Range			
R2[]]]	EV2 alarm value				
	High limit alarm	-(Input span) to Input span °C (°F) (*1) (*2)			
	Low limit alarm	-(Input span) to Input span °C (°F) (*1) (*2)			
	High/Low limits alarm	0 to Input span °C (°F) (*1) (*2)			
	High/Low limits independent	0 to Input span ℃ (°F) (*1) (*2)			
	alarm				
	High/Low limit range alarm	0 to Input span °C (°F) (*1) (*2)			
	High/Low limit range	0 to Input span °C (°F) (*1) (*2)			
	independent alarm				
	Process high alarm	Input range low limit to Input range high limit (*1) (*3)			
	Process low alarm	Input range low limit to Input range high limit (*1) (*3)			
	High limit with standby alarm	-(Input span) to Input span °C (°F) (*1) (*2)			
	Low limit with standby alarm	-(Input span) to Input span °C (°F) (*1) (*2)			
	High/Low limits with standby	0 to Input span °C (°F) (*1) (*2)			
	alarm				
	High/Low limits with standby	0 to Input span °C (°F) (*1) (*2)			
	independent alarm				
R2H	EV2 high limit alarm value				
<u> </u>	Setting range: Same as tho	se of EV2 alarm value			
RSHA	EV2 alarm hysteresis				
	Setting range: 0.1 to 1000.0	Ĵ℃ (°F),			
	DC voltage, o	current inputs: 1 to 10000 (*1)			
8239	EV2 alarm delay time				
	Setting range: 0 to 10000 s	econds			
RZLA	EV2 alarm Energized/De-ene	rgized			
noñL	oant Energized				
	<i>ー ᢄ Ყ</i> 与 De-energized				
1424	TS2 output step number				
1	Setting range: 1 to 9				
F428	TS2 OFF time				
0000	Setting range: 00:00 to 99:5	59 (*4)			
1420	TS2 ON time				
0000	Setting range: 00:00 to 99:5	59 (*4)			
H I	Heater burnout alarm 1 valu	le			
	Setting range:				
H I and CT1 current	20 A: 0.0 to 20.0 A				
value are alternately indicated on the PV Display.	100 A: 0.0 to 100.0 A				
H2	Heater burnout alarm 2 valu	e			
	Setting range:	-			
HE and CT2 current	20 A: 0.0 to 20.0 A				
value are alternately	100 A: 0.0 to 100.0 A				
indicated on the PV Display.	decimal point follows the selection				

(\*2) For DC voltage, current inputs, the input span is the same as the scaling span.

(\*3) For DC voltage, current inputs, input range low (or high) limit value is the same as scaling low (or high) limit value.

(\*4) Time unit follows the selection from [Step time unit].

Characters,	Setting Item, Setting Range								
Factory Default	Loon brea	k alarm timo							
	Loop break alarm time Setting range: 0 to 200 minutes								
LP_H	Loop break alarm span								
	-	•	0 0 to 150 0℃ (°F	)					
kan sa da sa da sa da <b>sa s</b> a da <b>sa s</b> a da <b>sa sa da sa sa</b>	ootting t	Setting range: 0 to 150°C (°F), or 0.0 to 150.0°C (°F) DC voltage, current inputs: 0 to 1500 (*1)							
EBI I	Event input DI1 allocation								
<i>000</i>	-	[Event Input Allocation Table]							
	-	Event input	Input ON	Input OFF					
		function	(Closed)	(Open)					
	000	No event							
	00 I	Set value memory							
	002	Control ON/OFF	Control OFF	Control ON					
	003	Direct/Reverse action	Direct action	Reverse action					
	ШООЧ	Preset output 1 ON/OFF	Preset output	Usual control					
	005	Preset output 2 ON/OFF	Preset output	Usual control					
	005	Auto/Manual control	Manual	Automatic					
			control	control					
	C 0 0 7	Remote/Local	Remote	Local					
	008	Program control RUN/STOP	RUN	STOP					
	009	Program control Holding/Not holding	Holding	Not holding					
	0 10	Program control	Advance	Usual control					
		Advance function	function						
	□0	Integral action	Integral action	Usual					
		Holding	Holding	integral action					
<u> </u>	-	t DI2 allocation							
		item: Same as those of	Event input DI1 a	allocation					
$-\Gamma L H$		etting input high limit							
סרבו	•	ange: External setting inp	out low limit to Inp	out range high limit	(*1)				
FFLL		etting input low limit							
-200	Setting ra	ange: Input range low lim	nit to External set	ting input high limit	(*1)				
5-04		ion output type							
PB	P8	PV transmission							
	<u> </u>	SV transmission							
	- <i></i>	MV transmission							
	d V	DV transmission							

Characters, Factory Default		Setting Item, Setting Range				
ГЕЦН	Transmission output high limit					
1370	PV, SV transmission	Transmission output low limit to Input range high limit				
		DC voltage, current inputs: -2000 to 10000				
	MV transmission	Transmission output low limit to 105.0%				
	DV transmission	Transmission output low limit to Scaling span (*1)				
FFLL	Transmission output lo	w limit				
-200	PV, SV transmission	Input range low limit to Transmission output high limit				
		DC voltage, current inputs: -2000 to 10000				
	MV transmission	-5.0% to Transmission output high limit value				
	DV transmission	-Scaling span to Transmission output high limit value (*1)				
<b>5</b>	SV1					
	Setting range: Scaling	low limit to Scaling high limit (*1)				
<i>∽2</i>	SV2					
	Setting range: Scaling	low limit to Scaling high limit (*1)				
<i>ゝ∃</i>	SV3					
	Setting range: Scaling low limit to Scaling high limit (*1)					
<u>чч</u>	SV4					
	Setting range: Scaling	low limit to Scaling high limit (*1)				

### 13.5 Main Setting Mode

The PV Display indicates setting characters, and the SV Display indicates factory default value.

Characters,	Sotting Itom Sotting Bongo
Factory Default	Setting Item, Setting Range
<b>५</b> []]]]	SV1
	Setting range: Scaling low limit to Scaling high limit (*1)
	Step 1 time
0000	Setting range:, or 00:00 to 99:59
	Step 1 wait value
	Setting range: 0 to 20% of the input span
	DC voltage, current inputs: 0 to 20% of scaling span (*1)
52000	SV2
	Setting range: Scaling low limit to Scaling high limit (*1)
r=_2	Step 2 time
00.00	Setting range:, or 00:00 to 99:59
J	Step 2 wait value
	Setting range: 0 to 20% of the input span
	DC voltage, current inputs: 0 to 20% of scaling span (*1)
<b>ЧЭ</b>	SV3
	Setting range: Scaling low limit to Scaling high limit (*1)
Γ	Step 3 time
0000	Setting range:, or 00:00 to 99:59
<u> </u>	Step 3 wait value
	Setting range: 0 to 20% of the input span
	DC voltage, current inputs: 0 to 20% of scaling span (*1)
<u>५</u> Ч	SV4
	Setting range: Scaling low limit to Scaling high limit (*1)
ГШ_Ч	Step 4 time
00.00	Setting range:, or 00:00 to 99:59
<u>Б</u> Ч	Step 4 wait value
	Setting range: 0 to 20% of the input span
	DC voltage, current inputs: 0 to 20% of scaling span (*1)
55	Step 5 SV
	Setting range: Scaling low limit to Scaling high limit (*1)
/ 🗆 _ S	Step 5 time
00.00	Setting range:, or 00:00 to 99:59
JOL S	Step 5 wait value
	Setting range: 0 to 20% of the input span
	DC voltage, current inputs: 0 to 20% of scaling span (*1)
5 <u>5</u>	Step 6 SV
	Setting range: Scaling low limit to Scaling high limit (*1)
ГШ_В	Step 6 time
00.00	Setting range:, or 00:00 to 99:59
J	Step 6 wait value
	Setting range: 0 to 20% of the input span
	DC voltage, current inputs: 0 to 20% of scaling span (*1)
(*1) The placement of the	

 $(^{\star}1)$  The placement of the decimal point follows the selection.

Characters, Factory Default	Setting Item, Setting Range
└ <b>╮</b> ७([]]]	Step 7 SV
	Setting range: Scaling low limit to Scaling high limit (*1)
[ T	Step 7 time
0000	Setting range:, or 00:00 to 99:59
<i>I</i> . 7	Step 7 wait value
	Setting range: 0 to 20% of the input span
	DC voltage, current inputs: 0 to 20% of scaling span (*1)
<i>ч8</i>	Step 8 SV
	Setting range: Scaling low limit to Scaling high limit (*1)
ГШ_ <i>В</i>	Step 8 time
0000	Setting range:, or 00:00 to 99:59
J	Step 8 wait value
	Setting range: 0 to 20% of the input span
	DC voltage, current inputs: 0 to 20% of scaling span (*1)
5 <i>9</i>	Step 9 SV
	Setting range: Scaling low limit to Scaling high limit (*1)
r 🗆 _ 9	Step 9 time
0000	Setting range: Elelel, or 00:00 to 99:59
J _ 9	Step 9 wait value
	Setting range: 0 to 20% of the input span
	DC voltage, current inputs: 0 to 20% of scaling span (*1)

### 13.6 Sub Setting Mode

The PV Display indicates setting characters, and the SV Display indicates factory default value.

Characters, Factory Default	Setting Item, Setting Range						
Rr	AT/Auto-reset Perform/Cancel						
	AT/AT on startup/Auto-reset Cancel						
	AT Perform						
	려고 '아 AT on startup Perform						
	ーっちに Auto-reset Perform						
<i>P</i>	OUT1 proportional band						
□□□ <i>10</i>	Setting range: 0 to Input span℃(℉)						
<b>,</b> <del>, , , , , , , , , , , , , , , , , , </del>	DC voltage, current inputs: 0.0 to 1000.0%						
	Integral time						
	Setting range: 0 to 3600 seconds						
	Derivative time						
8-5	Setting range: 0 to 1800 seconds ARW						
	Setting range: 0 to 100%						
- 485	Manual reset						
	Setting range: ±Proportional band value						
G	OUT1 proportional cycle						
<b></b>	Setting range: 0.5, or 1 to 120 seconds						
Factory default: Relay contact output:							
30 sec.							
Non-contact voltage output: 3 sec.							
<u> </u>	OUT1 ON/OFF hysteresis						
	Setting range: 0.1 to 1000.0°C (°F)						
al H	DC voltage, current inputs: 1 to 10000 (*1)						
000	OUT1 high limit						
	Setting range: OUT1 low limit value to 100% (Direct current output type: OUT1 low limit value to 105%)						
oll.	OUT1 low limit						
	Setting range: 0% to OUT1 high limit value						
han a dhan a dha an 1700.	(Direct current output type: -5% to OUT1 high limit value)						
or AF	OUT1 rate-of-change						
<i>0</i>	Setting range: 0 to 100 %/second						
cRcF	OUT2 cooling method						
81 r 🗌	Air cooling (linear characteristics)						
	□ □ ↓ □ Oil cooling (1.5th power of the linear characteristics)						
	<i>ū∺</i> Water cooling (2nd power of the linear characteristics)						
P_6	OUT2 proportional band						
	Setting range: 0 to Input span °C (°F)						
b	DC voltage, current inputs: 0.0 to 1000.0%						
	OUT2 proportional cycle Setting range: 0.5, or 1 to 120 seconds						
Factory default:							
Relay contact output: 30 sec.							
Non-contact voltage							
output: 3 sec.	OUT2 ON/OEE hystoresis						
	OUT2 ON/OFF hysteresis Setting range: 0.1 to 1000.0°C (°F),						
ii % (m)	DC voltage, current inputs: 1 to 10000 (*1)						

(\*1) The placement of the decimal point follows the selection.

Characters, Factory Default	S	etting Item, Setting Range				
oLHb	OUT2 high limit					
00	Setting range: OUT2 low I (Direct current output type	imit value to 100% :: OUT2 low limit value to 105%)				
oLL6	OUT2 low limit	/				
	Setting range: 0% to OUT2 high limit value (Direct current output type: -5% to OUT2 high limit value)					
db	Overlap/Dead band Setting range: -200.0 to 200.0℃ (°F),					
<u> </u>						
	DC voltage, current inputs					
conf	Direct/Reverse action					
неяг	HE用다 Reverse (Heat	ing) action				
	COOL Direct (Cooling	) action				
<i>A</i> /	EV1 alarm value					
	High limit alarm	-(Input span) to Input span °C (°F) (*1) (*2)				
	Low limit alarm	-(Input span) to Input span °C (°F) (*1) (*2)				
	High/Low limits alarm	0 to Input span °C (°F) (*1) (*2)				
	High/Low limits independent	0 to Input span °C (°F) (*1) (*2)				
	High/Low limit range alarm	0 to Input span °C (°F) (*1) (*2)				
	High/Low limit range	0 to Input span $^{\circ}C$ ( $^{\circ}F$ ) (*1) (*2)				
	independent alarm					
	Process high alarm	Input range low limit to Input range high limit (*1) (*3)				
	Process low alarm	Input range low limit to Input range high limit (*1) (*         n       -(Input span) to Input span °C (°F) (*1) (*2)				
	High limit with standby alarm					
	Low limit with standby alarm	-(Input span) to Input span °C (°F) (*1) (*2)				
	High/Low limits with standby	0 to Input span °C (°F) (*1) (*2)				
	High/Low limits with standby	0 to Input span ℃ (°F) (*1) (*2)				
	independent alarm					
R IH	EV1 high limit alarm value					
	Setting range: Same as th	ose of EV1 alarm value				
82	EV2 alarm value					
	Setting range: Same as th	ose of EV1 alarm value				
<u>82H</u>	EV2 high limit alarm value					
	Setting range: Same as th					
	Heater burnout alarm 1 val	ue				
	Setting range:					
H I and CT1 current value are alternately indicated on the PV Display.	20.0 A: 0.0 to 20.0 A 100.0 A: 0.0 to 100.0 A					
	Heater burnout alarm 2 va	ue				
	Setting range:					
H2 and CT2 current value are alternately indicated on the PV Display.	20.0 A: 0.0 to 20.0 A 100.0 A: 0.0 to 100.0 A					
LP_T	Loop break alarm time					
	Setting range: 0 to 200 mi	nutes				
LP_H	Loop break alarm span					
	Setting range: 0 to 150℃	(°F), 0.0 to 150.0℃ (°F)				
	DC voltage, current inputs					
(*1) The placement of the	ment of the decimal point follows the selection.					

(\*1) The placement of the decimal point follows the selection.
(\*2) For DC voltage, current inputs, the input span is the same as the scaling span.
(\*3) For DC voltage, current inputs, input range low (or high) limit value is the same as scaling low (or high) limit value.

### 13.7 Engineering Mode

The PV Display indicates setting characters, and the SV Display indicates factory default value.

Characters, Factory Default	Setting Item, Setting Range							
Lock	Set valu	e lock						
			Change via Keypad		Change via Software Communication			
	Unlock		All set values can be changed.		All set values can be			
	Lec / Lock 1		None of the s	None of the set values can be		changed.		
			changed.			-		
	Locð	Lock 2		e control, only S				
				ilue can be chang ontrol, Step SV,	jea.			
			-	d Alarm value car	า			
			be changed.					
	Loc3	Lock 3		can be changed	Ι.	Setting item	is – except Input	
	Locy	Lock 4	None of the s	set values can be	;	type, Contro	oller/Converter –	
			changed.			can be char	nged temporarily	
	Locs	Lock 5		e control, only SV			communication.	
				lue can be chang	ged.		power is turned he set values	
			•	ontrol, Step SV,	_	-	e values before	
			be changed.	d Alarm value car	1	Lock 3, 4 or 5 was selected		
EBI 1	Event in	nut DI1 a						
000	Event input DI1 allocation [Event Input Allocation Table]							
	-		vent input	Input ON	I	Input OFF		
			function	(Closed)		(Open)		
	000		vent					
			alue memory					
	000			Control OFF		ontrol ON		
	00	actior	t/Reverse	Direct action		everse tion		
	00-		et output 1	Preset output		ual control		
		ON/C	=	i ieset output	03			
	00	-	et output 2	Preset output	Us	ual control		
		ON/C	=					
	000E	auto/	Manual	Manual	Au	Itomatic		
		contro		control		ntrol		
		-	ote/Local	Remote		cal		
	008	RUN/	ram control /STOP	RUN	ST	OP		
	009		ram control	Holding	No	ot holding		
			ng/Not					
		holdir	am control	Advance	c	sual control		
			nce function	function				
	0 /		ral action	Integral action	Us	sual		
		holdir		holding		egral action		

Characters, Factory Default		Set	ting Item, Setting Range				
EBLZ	Event inpu	t DI2 allocation					
000	Selection	item: Same as Ev	ent input DI1 allocation				
E8a I	Event output EV1 allocation						
000	[Event O	utput Allocation <sup>-</sup>	Table]				
	000	No event					
	00 i	Alarm output, Hig	ıh limit alarm				
	002	Alarm output, Lov	w limit alarm				
	003	Alarm output, High/Low limits alarm					
	004 - C	Alarm output, Hig	h/Low limits independent alarm				
	005	Alarm output, Hig	h/Low limit range alarm				
	005	Alarm output, Hig	h/Low limit range independent alarm				
	C 0 0	Alarm output, Pro	ocess high alarm				
	$\Box 008$	Alarm output, Pro	ocess low alarm				
	009	Alarm output, Hig	h limit with standby alarm				
	0 10	Alarm output, Lov	w limit with standby alarm				
		Alarm output, Hig	h/Low limits with standby alarm				
	0 IZ	Alarm output, Hig alarm	h/Low limits with standby independent				
	0 I J	Heater burnout a	larm output				
	0 IH	Loop break alarm	n output				
	0 /5	Time signal outpu	ut				
	0 15	Output during AT					
	CI 0	Pattern end output	ut				
	0 18	Output by commu	unication command				
A IEA	EV1 alarm	value 0 Enabled/	Disabled				
~o[]]]]	no	Disabled					
	4E 4	Enabled					
<i>R (</i>	EV1 alarm	value					
	High limit a	larm	-(Input span) to Input span °C (°F) (*1) (*	*2)			
	Low limit al	arm	-(Input span) to Input span $^{\circ}C$ ( $^{\circ}F$ ) (*1) (*2)				
	High/Low li	mits alarm	0 to Input span $^{\circ}C$ ( $^{\circ}F$ ) (*1) (*2)				
	High/Low li alarm	mits independent	0 to Input span $^{\circ}C$ ( $^{\circ}F$ ) (*1) (*2)				
	High/Low li	mit range alarm	0 to Input span $^{\circ}C$ ( $^{\circ}F$ ) (*1) (*2)				
	High/Low li	mit range	0 to Input span $^{\circ}C$ ( $^{\circ}F$ ) (*1) (*2)				
	independer	nt alarm					
	Process hig	gh alarm	Input range low limit to Input range hig	Jh limit (*1) (*3)			
	Process lov	v alarm	Input range low limit to Input range hig	Jh limit (*1) (*3)			
	High limit w	ith standby alarm	-(Input span) to Input span $^{\circ}C$ ( $^{\circ}F$ ) (*1) (*	*2)			
	Low limit w	ith standby alarm	-(Input span) to Input span $^{\circ}C$ ( $^{\circ}F$ ) (*1) (*	*2)			
	High/Low li	mits with standby	0 to Input span $^{\circ}C$ ( $^{\circ}F$ ) (*1) (*2)				
	alarm						
	-	limits with standby 0 to Input span °C (°F) (*1) (*2)					
	independent alarm						
	-	imit alarm value					
	Setting ra	ange: Same as tho	se of EV1 alarm value				

(\*1) The placement of the decimal point follows the selection.
(\*2) For DC voltage, current inputs, the input span is the same as the scaling span.
(\*3) For DC voltage, current inputs, input range low (or high) limit value is the same as scaling low (or high) limit value.

Characters, Factory Default	Setting Item, Setting Range						
A INA	EV1 alarm hysteresis						
	Setting range: 0.1 to 1000.0℃ (°F),						
	DC voltage, current inputs: 1 to 10000 (*1)						
8 189		EV1 alarm delay time					
	· · · · · ·	ange: 0 to 10000 seconds					
RILA		EV1 alarm Energized/De-energized					
noñl	non Energized						
	-884	De-energized					
		t step number					
	-	ange: 1 to 9					
	TS1 OFF ti						
0000	•	ange: 00:00 to 99:59 (*4)					
[ \ lo   nonn	TS1 ON tin	<b>ne</b> ange: 00:00 to 99:59 (*4)					
0000 E8o2	•						
	•	out EV2 allocation					
		utput Allocation Table]					
		No event					
	002	Alarm output, High limit alarm					
	003	Alarm output, Low limit alarm					
	<u>004</u>	Alarm output, High/Low limits alarm Alarm output, High/Low limits independent alarm					
	005						
	Image: Image and the second state of the second state o						
	$\square D D D Alarm output, Process high alarm$						
	Image:						
	$\square \square $						
	0 13	Heater burnout alarm output					
	0 14	Loop break alarm output					
	0 15	Time signal output					
	0 15	Output during AT					
	C 17	Pattern end output					
	Image: Image of the second						
	Image: Second						
REER	EV2 alarm	value 0 Enabled/Disabled					
~o[]]]	no[]]]	Disabled					
	ビビット Enabled						
(*1) The placement of the	•						

(\*1) The placement of the decimal point follows the selection. (\*4) Time unit follows the selection from [Step time unit].

Characters, Factory Default	Setting Item, Setting Range						
	EV2 alarm value						
	High limit alarm-(Input span) to Input span $^{\circ}C$ ( $^{\circ}F$ ) (*1) (*2)						
	Low limit alarm	-(Input span) to Input span $^{\circ}C$ (°F) (*1) (*2)					
	High/Low limits alarm	0 to Input span °C (°F) (*1) (*2)					
	High/Low limits independent alarm	0 to Input span °C (°F) (*1) (*2)					
	High/Low limit range alarm	0 to Input span ℃ (°F) (*1) (*2)					
	High/Low limit range	0 to Input span °C (°F) (*1) (*2)					
	independent alarm						
	Process high alarm	Input range low limit to Input range high limit (*1) (*3)					
	Process low alarm	Input range low limit to Input range high limit (*1) (*3)					
	High limit with standby alarm	-(Input span) to Input span °C (°F) (*1) (*2)					
	Low limit with standby alarm	-(Input span) to Input span °C (°F) (*1) (*2)					
	High/Low limits with standby	0 to Input span °C (°F) (*1) (*2)					
	alarm						
	High/Low limits with standby	0 to Input span ℃ (°F) (*1) (*2)					
	independent alarm						
R2H	EV2 high limit alarm value						
	Setting range: Same as those	se of EV2 alarm value					
8289	EV2 alarm hysteresis						
	Setting range: 0.1 to 1000.0°C (°F), DC voltage, current inputs: 1 to 10000 (*1)						
8239	EV2 alarm delay time						
	Setting range: 0 to 10000 seconds						
RZLA	EV2 alarm Energized/De-energized						
noñL	nonk Energized						
	-EU- De-energized						
1424	TS2 output step number						
[]]]] /	Setting range: 1 to 9						
TH2F	TS2 OFF time						
0000	Setting range: 00:00 to 99:59 (*4)						
142a	TS2 ON time						
0000	Setting range: 00:00 to 99:5	9 (*4)					
50E	Sensor correction coefficier	nt					
1000	Setting range: -10.000 to 10.000						
50	Sensor correction						
	Setting range: -1000.0 to 1000.0°C (°F)						
	DC voltage, current inputs: -10000 to 10000 (*1)						
FILE	PV filter time constant						
	Setting range: 0.0 to 10.0 seconds						
674L	Communication protocol						
noñl	กอลีL Shinko protocol						
	nedR Modbus ASCII						
	ñadr Modbus RTU						
cñno	Instrument number						
	Setting range: 0 to 95						
•	· · · ·						

(\*2) For DC voltage, current inputs, the input span is the same as the scaling span.

(\*3) For DC voltage, current inputs, input range low (or high) limit value is the same as scaling low (or high) limit value.

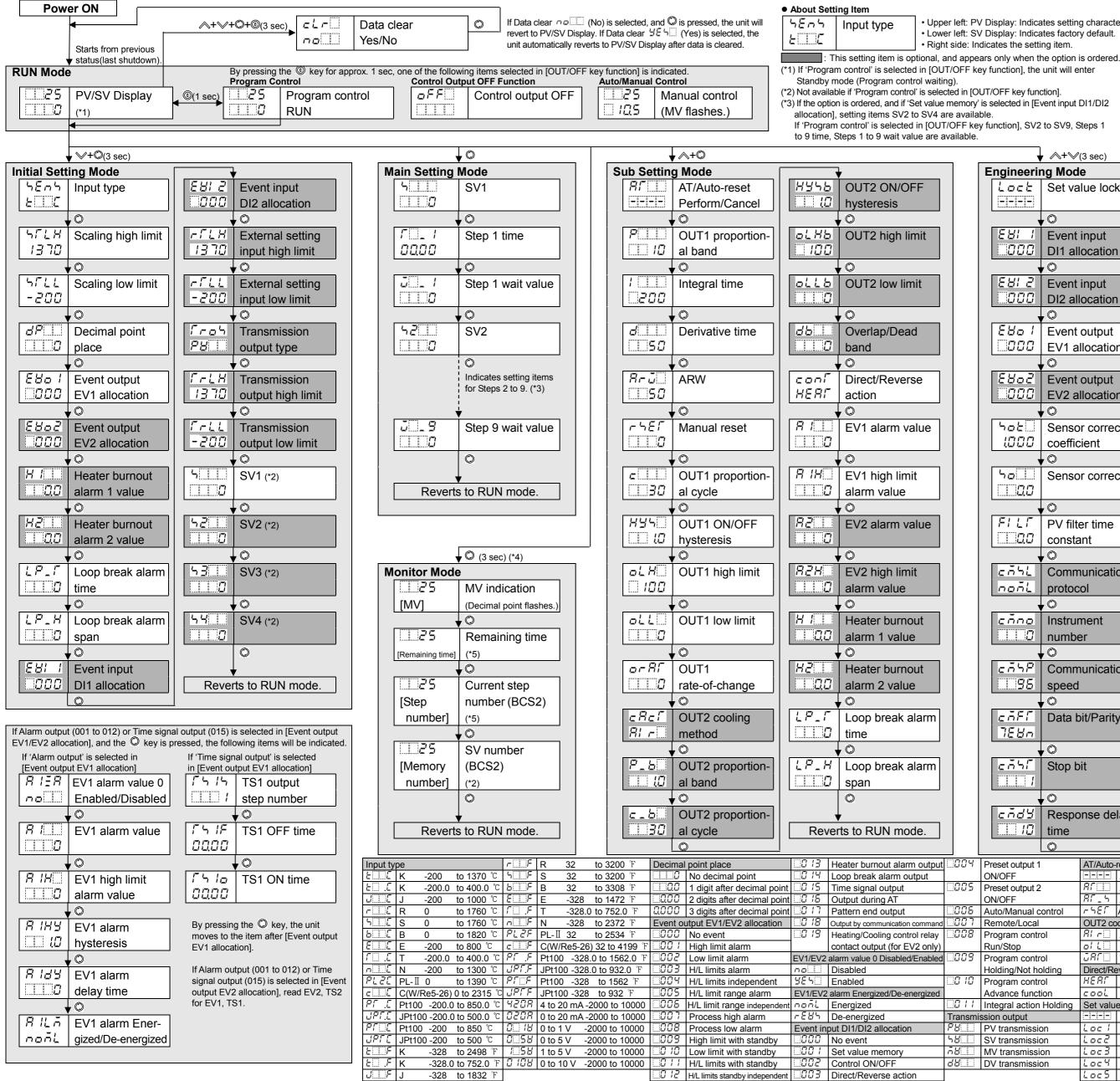
(\*4) Time unit follows the selection from [Step time unit].

Characters,							
Factory Default	Setting Item, Setting Range						
674P	Communication speed						
<b></b>	<u> 19</u> 5 9600 bps						
	0 192	19200 bp	S				
	384	38400 bp					
CAFE	Data bit/Parity						
768~	8non	parity					
	Inon	7 bits/No	parity				
	888n	8 bits/Eve	en				
	788n	7 bits/Eve	en				
	Bodd	8 bits/Od	d				
	Todd	7 bits/Od	d				
674F	Stop bit						
		1 bit					
	5	2 bits					
cñdy	Response	delay time	9				
	Setting ra	ange: 0 to <sup>2</sup>	1000 ms				
58 <u>5</u>	SVTC bias						
<b>B</b>	Setting range: ±20% of the input span						
	DC voltage, current inputs: ±20% of the scaling span (*1)						
FEAC	Remote/Local						
Locl							
	rEn/ Remote						
	External setting input high limit						
		-	rnal setting input low limit to Input range high limit				
	External setting input low limit						
-200	Setting range: Input range low limit to External setting input high limit						
	Remote bi						
	Setting range: ±20% of the input span						
		-	inputs: ±20% of the scaling span (*1)				
	Transmiss	-	• •				
	P8	PV transr					
	58 SV transmission						
	- 78	MV trans					
Ггін	d'B     DV transmission       Transmission output high limit						
1370		-	-				
	PV, SV transmission Transmission output low limit to Input range high limit va						
	MV transmi		Transmission output low limit to 105.0%				
	DV transmission Transmission output low limit to Scaling span (*1)						
-200	Transmission output low limit           PV, SV transmission         Input range low limit to Transmission output high limit valu						
			Input range low limit to Transmission output high limit value				
	MV transmi		-5.0% to Transmission output high limit value				
	DV transmi	hission -Scaling span to Transmission output high limit value (*1)					

Characters,	Setting Item, Setting Range					
Factory Default						
~_ <u>~</u>	Step time unit					
āl a	A Hours:Minutes					
	らちょう Minutes:Seconds					
PrEF	Power restore action					
4F0P		Stops after power is restored				
	conf	Continues (resumes) after power is restored.				
	Hold	Suspends (on hold) after power is restored.				
<u> </u>	•	tart temperature				
	-	ange: Scaling low limit value to Scaling high limit value (*1)				
4_44		ontrol start type				
P B	<i>P 8</i>	PV start				
		PVR start				
	<i>чЯ</i>	SV start				
FEPT		repetitions				
		ange: 0 to 10000 times				
-855		all rate start type				
5855	4846	SV start				
	PBらに PV start					
- 85 U	SV rise rate					
	Setting range: 0 to10000 °C/min (°F/min)					
	Thermocouple, RTD inputs with a decimal point: 0.0 to 1000.0 °C/min (°F/min)					
-AFd	DC voltage, current inputs: 0 to 10000/min SV fall rate					
	Sv fall rate Setting range: 0 to10000°C/min (°F/min)					
1	Thermocouple, RTD inputs with a decimal point: 0.0 to 1000.0 $^{\circ}$ C/min ( $^{\circ}$ F/min)					
	DC voltage, current inputs: 0 to 10000/min					
PSB	Indication when control output OFF					
off.	$\Box F F \Box$ OFF indication					
	BaFF No indication					
	PB PV indication					
	PUBL     PV indication + Any Alarm active					
ЯГ_Ь	AT bias					
	Setting range: 0 to 50°C (0 to 100°F), or 0.0 to 50.0°C (0.0 to 100.0°F)					
86.5	AT gain					
	Setting range: 0.1 to 10.0 times					
EaUF	Output status when input errors occur					
	on III	Output ON				
ARAU	OUT/OFF key function					
oFF	$\square F F \square$ Control output OFF function					
	$\overline{aBaU}$ Auto/Manual control					
	ProG	Program control				
		al after power interruption				
RUFa	Auto/Mant RUF o	Automatic control				
	- nur a AR-U					
	nnnu	Manual control				

Characters, Factory Default	Setting Item, Setting Range				
FI AE	Indication time				
0000	Setting range: 00:00 to 60:00 (Minutes:Seconds)				
	When set to 00:00, Displays remain ON.				
P4F (	OUT1 MV preset value				
	Setting range: 0.0 to 100.0% (Direct current output: -5.0 to 105.0%)				
PHEZ	OUT2 MV preset value				
	Setting range: 0.0 to 100.0% (Direct current output: -5.0 to 105.0%)				
FUnc	Controller/Converter function				
entr	enfr	Controller			
	en8F	Converter			

### 14. Key Operation Flowchart



 Upper left: PV Display: Indicates setting characters. Lower left: SV Display: Indicates factory default. · Right side: Indicates the setting item.

★ ★+ ★ (3 sec)

- (\*4) The unit cannot proceed to Monitor mode if it is in Standby of Program control. (\*5) Available only when 'Program control' is selected in [OUT/OFF key function].

- To revert to RUN mode, press and hold the (1) key for approx. 3 sec while in any mode.
   To revert to RUN mode, press and hold the (1) key for approx. 3 sec while in any mode.
   If 'Control output OFF function' is selected in [OUT/OFF key function], the unit will enter Control output OFF status. If 'Auto/Manual control' is selected, the unit will enter Manual control status. If 'Program control' is selected, the unit will enter Program control RUN or Standby mode.

En eller i		(0 000)								
Engineerin										1
	Lock Set value lock		<u>ちど_ち</u> SVTC bias		ー 用「凵 SV rise rate					
	Ö				Ø			↓ Ø		Ĩ
E81 1	Event	input		LEAL	Remote		$\begin{bmatrix} -8f \end{bmatrix}$			1
					Remote	LUCAI				
000		ocatior	1	Lock						J
	$\circ$				Ø			$\checkmark \bigcirc$		
E 81 2	Event	input		FELH	Externa	al setting	P58	Indication w	hen	] ]
000		ocation		1370	input hi	•	oFF			
		Ucaliui	1		•	grimmi				J
	Ø				Ø			<b>↓</b> ©		-
E80 /	Event	output		FLL	Externa	al setting	<i>RE</i> _	b AT bias		
000	EV1 a	llocatio	n l	-200	input lo	w limit	500	0		
	0		···		©			<b>↓</b> ©		1
						h h h h h h h h h h h h h h h h h h h	000			1
5995		output		<u>-Г_Б</u>	Remote	e blas	Br -			
000	EV2 a	llocatio	n					8		
	Ô				Ø			↓ Ø		
502		r corre	ction	Frah	Transm	ission	EoU		is when	1
1000	coeffic	lient		<i>P 8</i>	output	lype	OFF		occur	l
	Ø				Ø			<b>↓</b> ©		
50	Senso	r corre	ction	[F-LH	Transm	ission	- ARA	U OUT/OFF k	ev	
				1370		high limit	off		- )	
	<i>a</i> s				•	ingri illi illi				
	Ø				Ø			<b>↓</b> ©		-
FILE	PV filte	er time		[[F-LL	Transm	ission	<u> </u>	ት Auto/Manua	al after	
0.0	consta	int		-200	output	ow limit	RUE	power interr	ruption	
	Ö				Ø				<u></u>	J
			_					_		1
<u>cñ4L</u>	Comm	unicati	on	ñ_ 40	Step tin	ne unit	<i>Г</i> ГА		me	
noñL	protoc	ol		i ni ni i			000	0		
	Ö				Ø	,		<b>↓</b> ©		1
		mont		PrEF		raatara	PSE		react	1
cnno	Instrur				Power	restore			reset	
0	numbe	er		46 oP	action			🛛 🛛 value		
	Ø				Ø					
c ñ h P	Comm	unicati	on	5_58	Program	m start	PSE	🖉 🗍 OUT2 MV p	reset	1
		unicati			-	1			10301	
98	speed				temper	ature		🛛 value		
	Ø				Ø			<b>↓</b> ©		
c AFF	Data b	it/Parit	v	5.56	Program	m control	FUn	Controller/		
7886			,	PB	start typ		I cof			
12 011		_								J
	Ø				Ø			Ø		
6755	Stop b	it		- EPF	Numbe	r of				
1					repetitio	ons				
	0				Ø					
cndy	Respo	nse de	lay	- <i>8</i> 55	SV Rise	e/Fall rate		★		_
10	time			5855	start typ	be	R	everts to RUN m	node.	
	Ø				Ô					
Dreg - t _ t _ t _			mar of D			ientiere t			In the C	
Preset output 1		AT/Auto-		rform/Cancel	Commun	hication protocol	Remote/L	Local		when control output OFF OFF indication
ON/OFF Preset output 2		Rſ	AT Perf	o-reset Cancel	non. nod8	Shinko protocol Modbus ASCII	rEní	Remote		No indication
ON/OFF				orm tartup Perform	noon nodr	Modbus ASCII Modbus RTU	Step time			PV indication
Auto/Manual c	ontrol			set Perform		nication speed		Hours:Minutes		PV Indication PV + Any Alarm active
Remote/Local	01101	OUT2 co				9600 bps	5Ec	Minutes:Seconds		tus when input errors occur
Program contr	ol	RI r	Air cool		192	19200 bps		store action		Output OFF
Run/Stop		ol L	Oil cool	•	384	38400 bps	5/ pP	Stop		Output ON
Program contr	ol	J.8.	Water c	0	Data bit/		coní	Continue (resume)		key function
Holding/Not ho		Direct/Re	•	*	Bnon	8 bits/No parity	Hold	Suspend (on hold)	oFF	Control output OFF
Program contr	U	HERF	Reverse	e action	Inon	7 bits/No parity	Program	control start type	⊼8nU	Auto/Manual control
Advance funct		cool	Direct a	iction	8687	8 bits/Even				Program control
Integral action	Holding	Set valu			7880	7 bits/Even	PB	PV start		ual after power interruption
sion output			Unlock		Bodd	8 bits/Odd	P8-	PVR start	RUFo	Automatic control
PV transmissio	-	Loci	Lock 1		Todd	7 bits/Odd	58 <u></u>	SV start		Manual control
	SV transmission			Stop bit			Fall rate start type		Converter function	
MV transmissi	-	Loc3	Lock 3			1 bit	5855 P855	SV start	enfr en8f	Controller
DV transmissio	וונ	Loc4 Loc5	Lock 4 Lock 5			2 bits	ורסין	PV start	וסייב	Converter
			LOCK 3							

\*\*\*\*\* Inquiries \*\*\*\*\*

For any inquiries about this unit, please contact our agency or the vendor where you purchased the unit after checking the following.

	[Example]
• Model	BCS2R00-12
• Option	EV2, C5W (100A)
Serial number	No. 145F05000

In addition to the above, please let us know the details of the malfunction, or discrepancy, and the operating conditions.

### SHINKO TECHNOS CO., LTD. **OVERSEAS DIVISION**

Head Office: 2-5-1, Senbahigashi, Minoo, Osaka, Japan http://www.shinko-technos.co.jp URL: E-mail: overseas@shinko-technos.co.jp

Tel: +81-72-727-6100

Fax: +81-72-727-7006