

Current Transducer CKSR series

 $I_{DN} = 6, 15, 25, 50 A$

Ref: CKSR 6-NP, CKSR 15-NP, CKSR 25-NP, CKSR 50-NP

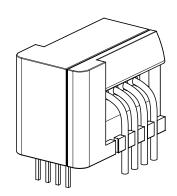
For the electronic measurement of current: DC, AC, pulsed..., with galvanic isolation between the primary (high power) and the secondary circuit (electronic circuit).











Features

- Closed loop (compensated) multi-range current transducer
- Voltage output
- Single supply
- · Isolated plastic case material recognized according to UL 94-V0
- · Compact design for PCB mounting.

Advantages

- Very low temperature coefficient of offset
- Very good dv/dt immunity
- High creepage / clearance distances
- · Reduced height
- Reference pin with two modes: Ref IN and Ref OUT
- Extended measuring range for unipolar measurement.

Applications

- · AC variable speed and servo motor drives
- · Static converters for DC motor drives
- · Battery supplied applications
- Uninterruptible Power Supplies (UPS)
- Switched Mode Power Supplies (SMPS)
- · Power supplies for welding applications
- Solar inverter.

Standards

- EN 50178
- UL 508 UR marking pending
- IEC 61010-1-safety.

Application Domain

Industrial.



Absolute maximum ratings

Parameter	Symbol	Unit	Value
Supply voltage	v _c	V	7
Primary conductor temperature		°C	110
ESD rating, Human Body Model (HBM)		kV	4

Stresses above these ratings may cause permanent damage. Exposure to absolute maximum ratings for extended periods may degrade reliability.

Isolation characteristics

Parameter	Symbol	Unit	Value	Comment
RMS voltage for AC isolation test 50/60Hz/1 min	V _d	kV	4.3	
Impulse withstand voltage 1.2/50 μs	$\hat{\mathbf{V}}_{\mathrm{w}}$	kV	8	
Partial discharge extinction voltage @ 10 pC (rms)	V _e	V	1000	
Clearance distance (pri sec.)	dCI	mm	8.2	Shortest distance through air
Creepage distance (pri sec.)	dCp	mm	8.2	Shortest internal path along device body
Case material	-	-	V0 according to UL 94	
Comparative tracking index	СТІ	V	600	
Application example	-	-	300 V CAT III PD2	Reinforced isolation, non uniform field according to EN 61010
Application example	-	-	600 V CAT III PD2	Reinforced isolation, non uniform field according to EN 50178
Application example	-	-	1000 V CAT III PD2	Simple isolation, non uniform field according to EN 50178

Environmental and mechanical characteristics

Parameter	Symbol	Unit	Min	Тур	Max	Comment
Ambient operating temperature	T _A	°C	-40		105	
Ambient storage temperature	T _s	°C	-55		105	
Mass	т	g		9		
Standards	EN 50178, IEC 60950-1, IEC 61010-1, IEC 61326-1, UL 508					





Electrical data CKSR 6-NP

At \mathbf{T}_{A} = 25°C, \mathbf{V}_{C} = + 5 V, \mathbf{N}_{P} = 1 turn, \mathbf{R}_{L} = 10 k Ω , internal reference, unless otherwise noted.

Parameter	Symbol	Unit	Min	Тур	Max	Comment
Primary nominal current rms	I _{PN}	А		6		Apply derating according to fig. 25
Primary current, measuring range	I _{PM}	А	-20		20	
Number of primary turns	N _P	-		1,2,3,4		
Supply voltage	v _c	V	4.75	5	5.25	
Current consumption	I _C	mA		$15 + \frac{I_{p} \text{ (mA)}}{N_{S}}$	$20 + \frac{I_p \text{ (mA)}}{N_S}$	N _S = 1731 turns
Reference voltage @ I _P = 0 A	V _{REF}	V	2.495	2.5	2.505	Internal reference
External reference voltage	V _{REF}	V	0		4	
Output voltage	V _{OUT}	V	0.375		4.625	
Output voltage @ I _P = 0 A	V _{OUT}	V		V _{REF}		
Electrical offset voltage	V _{OE}	mV	-5.3		5.3	100% tested V _{OUT} - V _{REF}
Electrical offset current referred to primary	I _{OE}	mA	-51		51	100% tested
Temperature coefficient of V _{REF}	TCV _{REF}	ppm/K		±5	±50	Internal reference
Temperature coefficient of V _{OUT} @ I _P = 0 A	TCV _{OUT}	ppm/K		±6	±30	ppm/K of 2.5 V - 40°C 105°C
Theoretical sensitivity	Gth	mV/A		104.2		625 mV/ I _{PN}
Sensitivity error	E _G	%	-0.7		0.7	100% tested
Temperature coefficient of G	TCG	ppm/K			±40	- 40°C 105°C
Linearity error	ε,	% of I _{PN}	-0.1		0.1	
Magnetic offset current (10 x I _{PN}) referred to primary	I _{OM}	А	-0.1		0.1	
Output current noise (spectral density) rms100 Hz 100 kHz referred to primary	i _{no}	μΑ/Hz½		20		$R_L = 1 \text{ k}\Omega$
Peak-peak output ripple at oscillator frequency f = 450 kHz (typ.)	-	mV		40	160	$\mathbf{R}_{L} = 1 \text{ k}\Omega$
Reaction time @ 10 % of I _{PN}	t _{ra}	μs			0.3	\mathbf{R}_{L} = 1 k Ω , di/dt = 18 A/ μ s
Response time @ 90 % of I _{PN}	t _r	μs			0.3	\mathbf{R}_{L} = 1 k Ω , di/dt = 18 A/ μ s
Frequency bandwidth (± 1 dB)	BW	kHz	200			$R_L = 1 \text{ k}\Omega$
Frequency bandwidth (± 3 dB)	BW	kHz	300			$R_L = 1 \text{ k}\Omega$
Overall accuracy	X _G	% of I _{PN}			1.7	
Overall accuracy @ T _A = 85°C (105°C)	X _G	% of I _{PN}			2.6 (2.9)	
Accuracy	х	% of I _{PN}			0.8	
Accuracy @ T _A = 85°C (105°C)	х	% of I _{PN}			1.8 (2.1)	





Electrical data CKSR 15-NP

At \mathbf{T}_{A} = 25°C, \mathbf{V}_{C} = + 5 V, \mathbf{N}_{P} = 1 turn, \mathbf{R}_{L} = 10 k Ω , internal reference, unless otherwise noted.

Parameter	Symbol	Unit	Min	Тур	Max	Comment
Primary nominal current rms	I _{PN}	А		15		Apply derating according to fig. 26
Primary current, measuring range	I _{PM}	А	-51		51	
Number of primary turns	N _P	-		1,2,3,4		
Supply voltage	v _c	V	4.75	5	5.25	
Current consumption	I _C	mA		$15 + \frac{I_{P} \text{ (mA)}}{N_{S}}$	20 + I _P (mA) N _S	N _S = 1731 turns
Reference voltage @ I _P = 0 A	V _{REF}	V	2.495	2.5	2.505	Internal reference
External reference voltage	V _{REF}	V	0		4	
Output voltage	V _{OUT}	V	0.375		4.625	
Output voltage @ I _P = 0 A	V _{OUT}	V		V _{REF}		
Electrical offset voltage	V _{OE}	mV	-2.21		2.21	100% tested V _{OUT} - V _{REF}
Electrical offset current referred to primary	I _{OE}	mA	-53		53	100% tested
Temperature coefficient of V _{REF}	TCV _{REF}	ppm/K		±5	±50	Internal reference
Temperature coefficient of \mathbf{V}_{OUT} @ \mathbf{I}_{P} = 0 A	TCV _{OUT}	ppm/K		±2.3	±20	ppm/K of 2.5 V - 40°C 105°C
Theoretical sensitivity	Gth	mV/A		41.67		625 mV/ I _{PN}
Sensitivity error	\mathcal{E}_{G}	%	-0.7		0.7	100% tested
Temperature coefficient of G	TCG	ppm/K			±40	- 40°C 105°C
Linearity error	$\epsilon_{\scriptscriptstyle \! \! \! \! \! \! \! \! \! \! \! \! \! \! \! \! \! \! \!$	% of I _{PN}	-0.1		0.1	
Magnetic offset current (10 x I _{PN}) referred to primary	I _{OM}	А	-0.1		0.1	
Output current noise (spectral density) rms 100 Hz 100 kHz referred to primary	i _{no}	μΑ/Hz½		20		$R_L = 1 \text{ k}\Omega$
Peak-peak output ripple at oscillator frequency f = 450 kHz (typ.)	-	mV		15	60	\mathbf{R}_{L} = 1 k Ω
Reaction time @ 10 % of I _{PN}	t _{ra}	μs			0.3	\mathbf{R}_{L} = 1 k Ω , di/dt = 44 A/ μ s
Response time @ 90 % of I _{PN}	t _r	μs			0.3	$R_L = 1 \text{ k}\Omega, \text{ di/dt} = 44 \text{ A/}\mu\text{s}$
Frequency bandwidth (± 1 dB)	BW	kHz	200			$R_L = 1 \text{ k}\Omega$
Frequency bandwidth (± 3 dB)	BW	kHz	300			$R_L = 1 \text{ k}\Omega$
Overall accuracy	X _G	% of I _{PN}			1.2	
Overall accuracy @ T _A = 85°C (105°C)	X _G	% of I _{PN}			1.9 (2.1)	
Accuracy	х	% of I _{PN}			0.8	
Accuracy @ T _A = 85°C (105°C)	х	% of I _{PN}			1.5 (1.8)	





Electrical data CKSR 25-NP

At $\mathbf{T}_{\rm A}$ = 25°C, $\mathbf{V}_{\rm C}$ = + 5 V, $\mathbf{N}_{\rm P}$ = 1 turn, $\mathbf{R}_{\rm L}$ = 10 k Ω , internal reference, unless otherwise noted.

Parameter	Symbol	Unit	Min	Тур	Max	Comment
Primary nominal current rms	I _{PN}	А		25		Apply derating according to fig. 27
Primary current, measuring range	I _{PM}	Α	-85		85	
Number of primary turns	N _P	-		1,2,3,4		
Supply voltage	v _c	V	4.75	5	5.25	
Current consumption	I _C	mA		$15 + \frac{I_{P} (mA)}{N_{S}}$	$20 + \frac{I_{P} (mA)}{N_{S}}$	N _S = 1731 turns
Reference voltage @ I _P = 0 A	V _{REF}	V	2.495	2.5	2.505	Internal reference
External reference voltage	V _{REF}	V	0		4	
Output voltage	V _{OUT}	V	0.375		4.625	
Output voltage @ I _P = 0 A	V _{OUT}	V		V _{REF}		
Electrical offset voltage	V _{OE}	mV	-1.35		1.35	100% tested V _{OUT} - V _{REF}
Electrical offset current referred to primary	I _{OE}	mA	-54		54	100% tested
Temperature coefficient of \mathbf{V}_{REF}	TCV _{REF}	ppm/K		±5	±50	Internal reference
Temperature coefficient of \mathbf{V}_{OUT} @ $\mathbf{I}_{\text{p}} = 0 \text{ A}$	TCV _{OUT}	ppm/K		±1.4	±10	ppm/K of 2.5 V - 40°C 105°C
Theoretical sensitivity	Gth	mV/A		25		625 mV/ I _{PN}
Sensitivity error	E _G	%	-0.7		0.7	100% tested
Temperature coefficient of G	TCG	ppm/K			±40	- 40°C 105°C
Linearity error	$\epsilon_{\scriptscriptstyle \! \! \! \! \! \! \! \! \! \! \! \! \! \! \! \! \! \! \!$	% of I _{PN}	-0.1		0.1	
Magnetic offset current (10 x I _{PN}) referred to primary	I _{OM}	А	-0.1		0.1	
Output current noise (spectral density) rms 100 Hz 100 kHz referred to primary	i _{no}	μΑ/Hz ^½		20		$R_L = 1 \text{ k}\Omega$
Peak-peak output ripple at oscillator frequency f = 450 kHz (typ.)	-	mV		10	40	\mathbf{R}_{L} = 1 k Ω
Reaction time @ 10 % of I _{PN}	t _{ra}	μs			0.3	\mathbf{R}_{L} = 1 k Ω , di/dt = 68 A/ μ s
Response time @ 90 % of I _{PN}	t _r	μs			0.3	\mathbf{R}_{L} = 1 k Ω , di/dt = 68 A/ μ s
Frequency bandwidth (± 1 dB)	BW	kHz	200			$R_L = 1 \text{ k}\Omega$
Frequency bandwidth (± 3 dB)	BW	kHz	300			$R_L = 1 \text{ k}\Omega$
Overall accuracy	X _G	% of I _{PN}			1	
Overall accuracy @ T _A = 85°C (105°C)	X _G	% of I _{PN}			1.5 (1.7)	
Accuracy	х	% of I _{PN}			0.8	
Accuracy @ T _A = 85°C (105°C)	х	% of I _{PN}			1.3 (1.4)	





Electrical data CKSR 50-NP

At \mathbf{T}_{A} = 25°C, \mathbf{V}_{C} = + 5 V, \mathbf{N}_{P} = 1 turn, \mathbf{R}_{L} = 10 k Ω , internal reference, unless otherwise noted.

Parameter	Symbol	Unit	Min	Тур	Max	Comment
Primary nominal current rms	I _{PN}	Α		50		Apply derating according to fig. 28
Primary current, measuring range	I _{PM}	Α	-150		150	
Number of primary turns	N _P	-		1,2,3,4		
Supply voltage	v _c	V	4.75	5	5.25	
Current consumption	I _C	mA		$15 + \frac{I_{P} (mA)}{N_{S}}$	$20 + \frac{I_p \text{ (mA)}}{N_S}$	N _S = 966 turns
Reference voltage @ I _P = 0 A	V _{REF}	V	2.495	2.5	2.505	Internal reference
External reference voltage	V _{REF}	V	0		4	
Output voltage	V _{OUT}	V	0.375		4.625	
Output voltage @ I _P = 0 A	V _{OUT}	V		V _{REF}		
Electrical offset voltage	V _{OE}	mV	-0.725		0.725	100% tested V _{OUT} - V _{REF}
Electrical offset current referred to primary	I _{OE}	mA	-58		58	100% tested
Temperature coefficient of V _{REF}	TCV _{REF}	ppm/K		±5	±50	Internal reference
Temperature coefficient of V _{OUT} @ I _P = 0 A	TCV _{OUT}	ppm/K		±0.7	±7	ppm/K of 2.5 V - 40°C 105°C
Theoretical sensitivity	Gth	mV/A		12.5		625 mV/ I _{PN}
Sensitivity error	E _G	%	-0.7		0.7	100% tested
Temperature coefficient of G	TCG	ppm/K			±40	- 40°C 105°C
Linearity error	$\epsilon_{\scriptscriptstyle \! \! \! \! \! \! \! \! \! \! \! \! \! \! \! \! \! \! \!$	% of I _{PN}	-0.1		0.1	
Magnetic offset current (10 x I _{PN}) referred to primary	I _{OM}	А	-0.1		0.1	
Output current noise (spectral density) rms 100 Hz 100 kHz referred to primary	i _{no}	μΑ/Hz ^½		20		\mathbf{R}_{L} = 1 k Ω
Peak-peak output ripple at oscillator frequency f = 450 kHz (typ.)	-	mV		5	20	$R_L = 1 \text{ k}\Omega$
Reaction time @ 10 % of I _{PN}	t _{ra}	μs			0.3	\mathbf{R}_{L} = 1 k Ω , di/dt = 100 A/ μ s
Response time @ 90 % of I _{PN}	t,	μs			0.3	\mathbf{R}_{L} = 1 k Ω , di/dt = 100 A/ μ s
Frequency bandwidth (± 1 dB)	BW	kHz	200			$R_L = 1 \text{ k}\Omega$
Frequency bandwidth (± 3 dB)	BW	kHz	300			$R_L = 1 \text{ k}\Omega$
Overall accuracy	X _G	% of I _{PN}			0.9	
Overall accuracy @ T _A = 85°C (105°C)	X _G	% of I _{PN}			1.3 (1.5)	
Accuracy	х	% of I _{PN}			0.8	
Accuracy @ T _A = 85°C (105°C)	х	% of I _{PN}			1.2 (1.3)	



Typical performance characteristics CKSR 6-NP

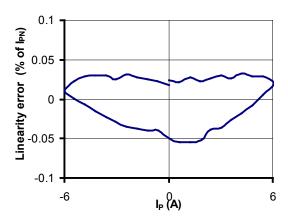


Figure 1: Linearity error

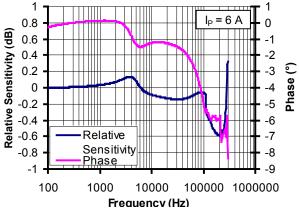


Figure 2: Frequency response

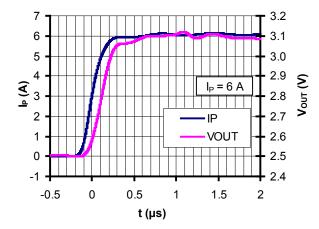


Figure 3: Step response

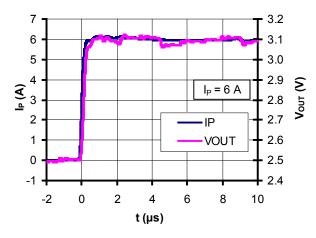


Figure 4: Step response

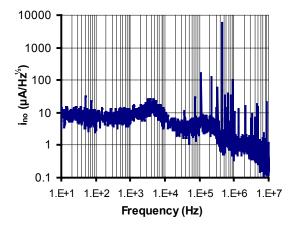


Figure 5: Input referred noise

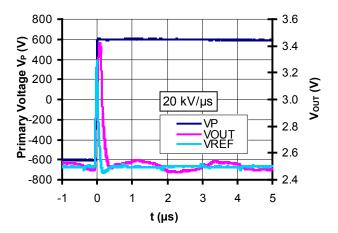


Figure 6: dv/dt



Typical performance characteristics CKSR 15-NP

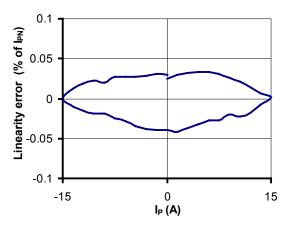


Figure 7: Linearity error

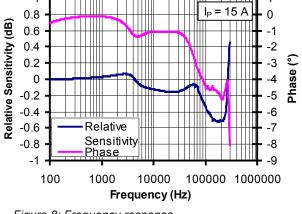


Figure 8: Frequency response

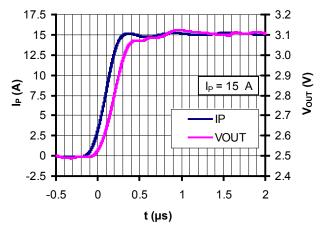


Figure 9: Step response

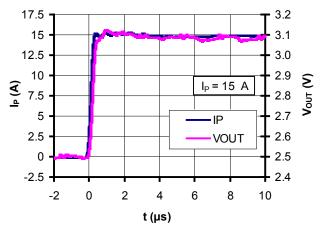


Figure 10: Step response

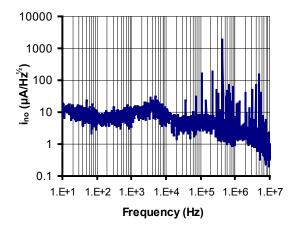


Figure 11: Input referred noise

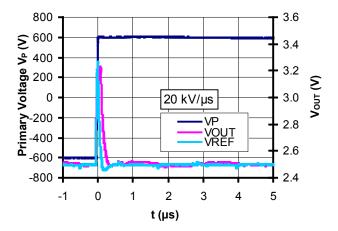


Figure 12: dv/dt



Typical performance characteristics CKSR 25-NP

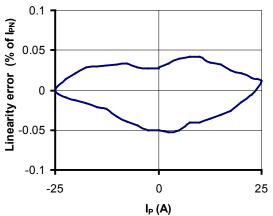


Figure 13: Linearity error

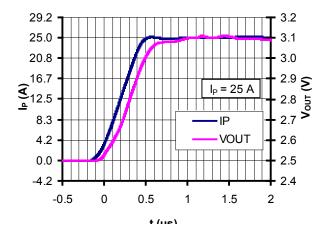


Figure 15: Step response

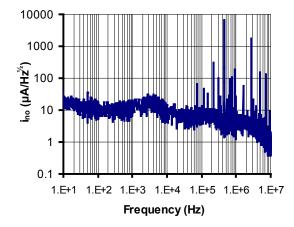


Figure 17: Input referred noise

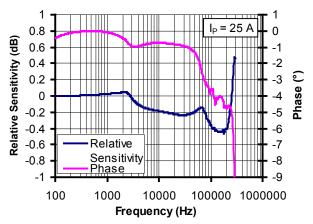


Figure 14: Frequency response

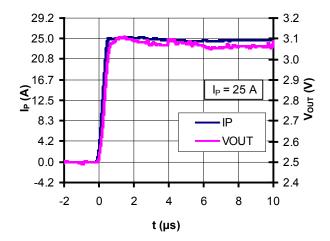


Figure 16: Step response

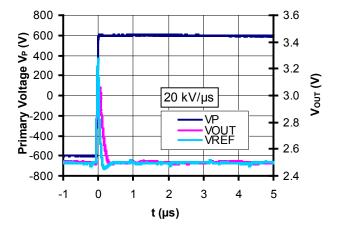


Figure 18: dv/dt



Typical performance characteristics CKSR 50-NP

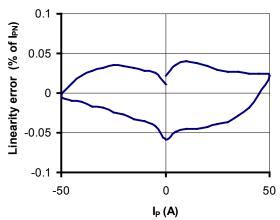


Figure 19: Linearity error

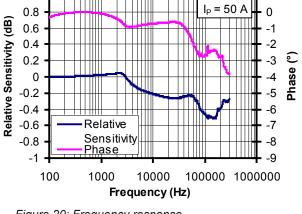


Figure 20: Frequency response

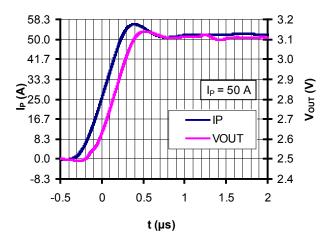


Figure 21: Step response

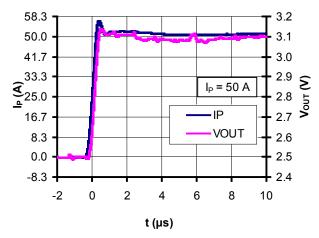


Figure 22: Step response

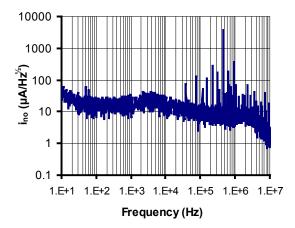


Figure 23: Input referred noise

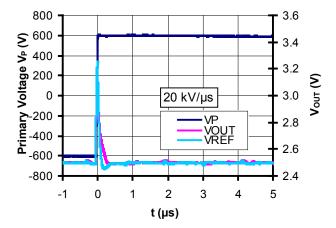


Figure 24: dv/dt



Maximum continuous DC primary current

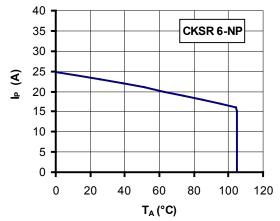
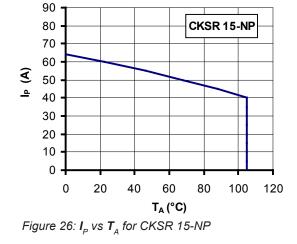


Figure 25: I_P vs T_A for CKSR 6-NP



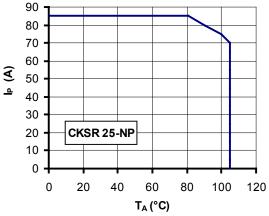


Figure 27: I_P vs T_A for CKSR 25-NP

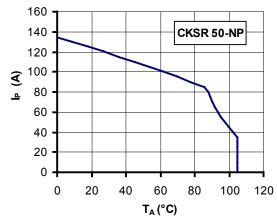


Figure 28: I_P vs T_A for CKSR 50-NP

The maximum continuous DC primary current plot shows the boundary of the area for which all the following conditions are true:

- **I**_P < **I**_{PM}
- Junction temperature Tj < 125 °C
- Primary conductor temperature < 110 °C
- Resistor power dissipation < 0.5 x rated power

Frequency derating

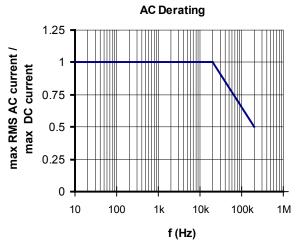


Figure 29: Maximum RMS AC primary current / maximum DC primary current vs frequency



Performance parameters definition

Ampere-turns and amperes

The transducer is sensitive to the primary current linkage $\Theta_{\rm p}$ (also called ampere-turns).

$$\Theta_{P} = N_{P} I_{P} (At)$$

Where $\mathbf{N}_{\rm P}$ is the number of primary turn (1, 2 , 3 or 4 depending on the connection of the primary jumpers)

Notice: As most transducer user will use it with only one single primary turn ($N_p = 1$), most of this datasheet is written with primary currents instead of current linkages. The unit is kept as ampere-turn (At) to make clear that ampere-turns are meant

Transducer simplified model

The static model of the transducer at temperature $\mathbf{T}_{\rm A}$ is: $\mathbf{V}_{\rm OUT}$ = G $\Theta_{\rm P}$ + error

In which error =

$$\textbf{V}_{\text{OE}} + \textbf{V}_{\text{OT}}(\textbf{T}_{\text{A}}) + \epsilon_{\text{G}} \cdot \Theta_{\text{P}} \cdot G + \epsilon_{\text{L}}(\Theta_{\text{Pmax}}) \cdot \Theta_{\text{Pmax}} \cdot G + \textbf{TCG} \cdot (\textbf{T}_{\text{A}} \text{-} 25) \cdot \Theta_{\text{P}} \cdot \textbf{G}$$

With: $\Theta_{P} = \mathbf{N}_{P} \mathbf{I}_{P}$:the input ampere-turns (At)

Please read above warning.

 Θ_{p} max : the maxi input ampere-turns that have

been applied to the transducer (At)

V_{OUT} :the secondary voltage (V)
T_A :the ambient temperature (°C)
V_{OE} :the electrical offset voltage (V)
V_{OT}(T_A) :the temperature variation of V_O at

temperature \mathbf{T}_{A} (V)

G :the sensitivity of the transducer (V/At)

 $\begin{array}{ll} \epsilon_{_{G}} & \text{:the sensitivity error} \\ \epsilon_{_{L}}\left(\Theta_{_{Pmax}}\right) & \text{:the linearity error for } \Theta_{_{Pmax}} \end{array}$

This model is valid for primary ampere-turns $\Theta_{\rm P}$ between $-\Theta_{\rm Pmax}$ and $+\Theta_{\rm Pmax}$ only.

Sensitivity and linearity

To measure sensitivity and linearity, the primary current (DC) is cycled from 0 to I_p , then to $-I_p$ and back to 0 (equally spaced $I_p/10$ steps).

The sensitivity **G** is defined as the slope of the linear regression line for a cycle between $\pm I_{PN}$.

The linearity error \mathcal{E}_{L} is the maximum positive or negative difference between the measured points and the linear regression line, expressed in % of I_{PN} .

Magnetic offset

The magnetic offset current I_{OM} is the consequence of a current on the primary side ("memory effect" of the transducer's ferro-magnetic parts). It is included in the linearity figure but can be measured individually.

It is measured using the following primary current cycle. I_{OM} depends on the current value I_{P1} .

$$I_{\scriptscriptstyle OM} = \frac{V_{\scriptscriptstyle OUT}(t_{\scriptscriptstyle 1}) - V_{\scriptscriptstyle OUT}(t_{\scriptscriptstyle 2})}{2} \cdot \frac{1}{Gth}$$

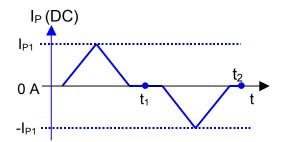


Figure 30: Current cycle used to measure magnetic and electrical offset (transducer supplied)



Performance parameters definition (continued)

Electrical offset

The electrical offset voltage \mathbf{V}_{OE} can either be measured when the ferro-magnetic parts of the transducer are:

- completely demagnetized, which is difficult to realize,
- or in a known magnetization state, like in the current cycle shown in figure 30.

Using the current cycle shown in figure 30, the electrical offset is:

 $V_{OE} = \frac{V_{OUT}(t_{1}) + V_{OUT}(t_{2})}{2}$

The temperature variation \mathbf{V}_{OT} of the electrical offset voltage \mathbf{V}_{OE} is the variation of the electrical offset from 25°C to the considered temperature:

$$V_{or}(T) = V_{oe}(T) - V_{oe}(25^{\circ}C)$$

Note: the transducer has to be demagnetized prior to the application of the current cycle (for example with a demagnetization tunnel).

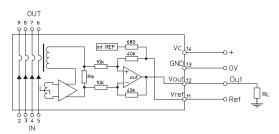


Figure 31: Test connection

Overall accuracy

The overall accuracy at 25°C \mathbf{X}_{G} is the error in the - \mathbf{I}_{PN} .. + \mathbf{I}_{PN} range, relative to the rated value I_{PN}.

It includes:

- the electrical offset V_{OE}
- $\bullet~$ the sensitivity error $\boldsymbol{\epsilon}_{_{G}}$

 $\bullet~$ the linearity error $\epsilon_{_L}$ (to I $_{_{PN}})$ The magnetic offset is part of the overall accuracy. It is taken into account in the linearity error figure provided the transducer has not been magnetized by a current higher than I_{PN}

Response and reaction times

The response time t, and the reaction time t, are shown in the next figure.

Both depend on the primary current di/dt. They are measured at nominal ampere-turns.

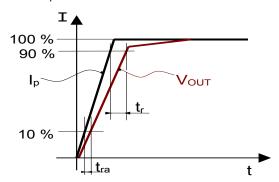


Figure 32: response time t_r and reaction time t_r

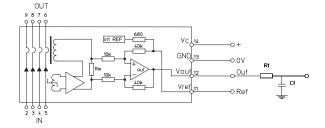
Application information

Filtering and declouping Supply voltage V_c

The fluxgate oscillator draws current pulses of up to 30 mA at a rate of ca. 900 kHz. Significant 900 kHz voltage ripple on V_c can indicate a power supply with excessive impedance. At these frequencies power supply rejection ratio is low, and the ripple may appear on the transducer output \mathbf{V}_{OUT} and reference $\mathbf{V}_{\mathsf{RFF}}$. The transducer has internal decoupling capacitors, but in the case of a power supply with excessive impedance, it is advised to provide local decoupling (100 nF or more, located close to the transducer)



The output \mathbf{V}_{OUT} has a very low output impedance of typically 2 Ohms; it can drive 100 pF directly. Adding Rf = 100 Ohms allows much larger capacitive loads. Empirical evaluation may be necessary to obtain optimum results. The minimum load resistance on V_{OUT} is 1 kOhm.



Reference V_{RFF}

Ripple present on the reference output can be filtered with a low value of capacitance because of the internal 680 Ohm series resistance. The maximum filter capacitance value is 1 µF.



Application information (continued)

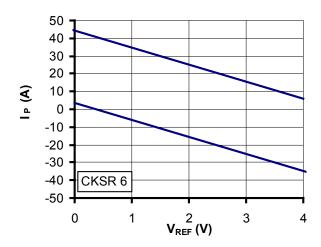
External reference voltage

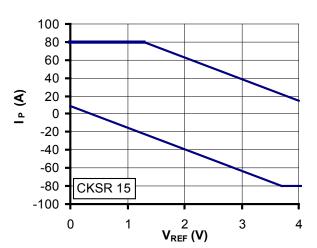
If the Ref pin of the transducer is not used it could be either left unconnected or filtered according to the previous paragraph "Reference \mathbf{V}_{RFF} ".

The Ref pin has two modes Ref IN and Ref OUT:

- In the Ref OUT mode the 2.5 V internal precision reference is used by the transducer as the reference point for bipolar measurements; this internal reference is connected to the Ref pin of the transducer through a 680 Ohms resistor. it tolerates sink or source currents up to ± 5 mA, but the 680 Ohms resistor prevents this current to exceed these limits.
- In the Ref IN mode, an external reference voltage is connected to the Ref pin; this voltage is specified in the range 0 to 4 V
 and is directly used by the transducer as the reference point for measurements.
 The external reference voltage Vref must be able:
 - either to source a typical current of $\frac{\textit{Vref}-2.5}{680}$, the maximum value will be 2.2 mA typ. when Vref = 4 V.
 - or to sink a typical current of $\frac{2.5 Vref}{680}$, the maximum value will be 3.68 mA typ. when Vref = 0 V.

The following graphs show how the measuring range of each transducer version depends on the external reference voltage value Vref.





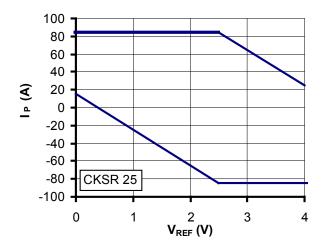
Upper limit : $I_p = -9.6 * Vref + 44.4 (Vref = 0 ... 4 V)$

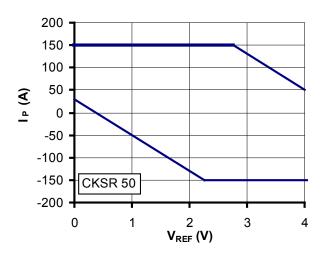
Lower limit : $I_p = -9.6 * Vref + 3.6$ (Vref = 0 .. 4 V)

Upper limit : $I_p = -24 * Vref + 111$ (Vref = 1.29 .. 4 V) Upper limit : $I_p = 80$ (Vref = 0 .. 1.29 V) Lower limit : $I_p = -24 * Vref + 9$ (Vref = 0 .. 3.7 V) Lower limit : $I_p = -80$ (Vref = 3.7 .. 4 V)



External reference voltage (continued)





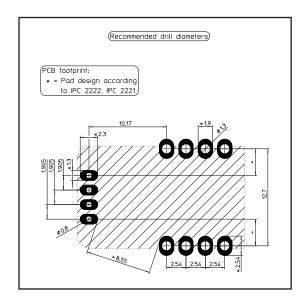
Example with $V_{REF} = 1.65 \text{ V}$:

- The 6 A version has a measuring range from 12.24 A to + 28.5 A
- The 15 A version has a measuring range from 30.6 A to + 71.4 A
- The 25 A version has a measuring range from 51 A to + 85 A
- The 50 A version has a measuring range from 102 A to + 150 A

Example with $V_{REF} = 0 V$:

- The 6 A version has a measuring range from + 3.6 A to + 44.4 A
- The 15 A version has a measuring range from + 9 A to + 80 A
- The 25 A version has a measuring range from + 15 A to + 85 A
- The 50 A version has a measuring range from + 30 A to + 150 A

CKSR Series, PCB footprint



Assembly on PCB

• Recommended PCB hole diameter 1.3 mm for primary pin

0.8 mm for secondary pin

Maximum PCB thickness

2.4 mm

 Wave soldering profile No clean process only. maximum 260°C for 10 s

Safety

This transducer must be used in limited-energy secondary circuits according to IEC 61010-1.



This transducer must be used in electric/electronic equipment with respect to applicable standards and safety requirements in accordance with the manufacturer's operating instructions.



Caution, risk of electrical shock

When operating the transducer, certain parts of the module can carry hazardous voltage (eg. primary busbar, power supply).

Ignoring this warning can lead to injury and/or cause serious damage.

This transducer is a build-in device, whose conducting parts must be inaccessible after installation.

A protective housing or additional shield could be used.

Main supply must be able to be disconnected.



Dimensions CKSR Series (in mm. General linear tolerance ± 0.25 mm)

