

For the electronic measurement of voltage: DC, AC, pulsed..., with galvanic separation between the primary and the secondary circuit.



Features

- Bipolar and insulated measurement up to 1500 V
- Current output
- Primary input on cables
- Footprint compatible with OV, CV 4 and LV 200-AW/2 families.

Advantages

- Low consumption and low losses
- Compact design
- Good behavior under common mode variations
- Excellent accuracy (offset, sensitivity, linearity)
- Response time 60 μs
- Low temperature drift
- High immunity to external interferences.

Applications

- Single or three phase inverters
- Propulsion and braking choppers
- Propulsion converters
- Auxiliary converters
- High power drives
- Substations
- On-board energy meters
- Energy metering.

Standards

- EN 50155: 2007
- EN 50124-1: 2001
- EN 50121-3-2: 2006.
- EN 50463: 2012.

Application Domain

- Traction (fixed and onboard).

Absolute maximum ratings

Parameter	Symbol	Value
Maximum supply voltage ($V_p = 0, 0.1 \text{ s}$)	$\pm U_C$	$\pm 34 \text{ V}$
Maximum supply voltage (working) (-40 .. 85 °C)	$\pm U_C$	$\pm 26.4 \text{ V}$
Maximum input voltage (-40 .. 85 °C)	V_P	1.5 kV
Maximum steady state input voltage (-40 .. 85 °C)	V_{PN}	1000 V see derating on figure 2

Absolute maximum ratings apply at 25 °C unless otherwise noted.

Stresses above these ratings may cause permanent damage. Exposure to absolute maximum ratings for extended periods may degrade reliability.

Insulation coordination

Parameter	Symbol	Unit	Value	Comment
RMS voltage for AC insulation test 50/60Hz/1 min	U_d	kV	18.5	100 % tested in production
Impulse withstand voltage 1.2/50 μs	\hat{U}_W	kV	30	
Partial discharge extinction rms voltage @ 10 pC	U_e	V	5000	
Insulation resistance	R_{IS}	M Ω	200	measured at 500 V DC
Clearance (pri. - sec.)	d_{Cl}	mm	see dimensions drawing on page 8	Shortest distance through air
Creepage distance (pri. - sec.)	d_{Cp}	mm		Shortest path along device body
Case material	-	-	V0 according to UL 94	
Comparative tracking index	CTI	V	600	

Environmental and mechanical characteristics

Parameter	Symbol	Unit	Min	Typ	Max
Ambient operating temperature	T_A	°C	- 40		85
Ambient storage temperature	T_S	°C	- 50		90
Mass	m	g		750	

Parameter	Accuracy class	Comment
Class accuracy for a rated primary voltage $V_{PN} = 750 \text{ V}$	0.5 R	According to EN 50463-2

Electrical data DV 1000

At $T_A = 25\text{ °C}$, $U_C = \pm 24\text{ V}$, $R_M = 100\ \Omega$, unless otherwise noted.

Lines with a * in the conditions column apply over the $-40 \dots 85\text{ °C}$ ambient temperature range.

Parameter	Symbol	Unit	Min	Typ	Max	Conditions
Primary nominal rms voltage	V_{PN}	V		1000		*
Primary voltage, measuring range	V_{PM}	V	-1500		1500	*
Measuring resistance	R_M	Ω	0		133.3	* See derating on figure 2. For $ V_{PM} < 1500\text{ V}$, max value of R_M is given on figure 1
Secondary nominal rms current	I_{SN}	mA		50		*
Output range	I_S	mA	-75		75	*
Supply voltage	$\pm U_C$	V	± 13.5	± 24	± 26.4	*
Supply rise time (10-90%)		ms			100	
Current consumption @ $U_C = \pm 24\text{ V}$	I_C	mA		$20 + I_S$	$25 + I_S$	
Offset current	I_O	μA	-50	0	50	100% tested in production
Offset drift	I_{OT}	μA	-250	200	250	$-40 \dots 85\text{ °C}$, 100% tested in production
Sensitivity	G	$\mu\text{A/V}$		50		50 mA for 1000 V
Sensitivity error	ε_G	%	-0.2	0	0.2	
Thermal drift of sensitivity	ε_{GT}	%	-0.5 -0.8 -0.8		0.5 0.8 0.8	$-25 \dots 70\text{ °C}$ $-25 \dots 85\text{ °C}$ * $-40 \dots 85\text{ °C}$
Linearity error	ε_L	%	-0.1		0.1	* $\pm 1500\text{ V}$ range
Overall accuracy	X_G	% of V_{PN}	-0.3 -1 -1.4 -1.4		0.3 1 1.4 1.4	25 °C ; 100% tested in production $-25 \dots 70\text{ °C}$ $-25 \dots 85\text{ °C}$ * $-40 \dots 85\text{ °C}$
Output rms current noise	I_{no}	μA		17		1 Hz to 100 kHz
Reaction time @ 10 % of V_{PN}	t_{ra}	μs		21		
Response time @ 90 % of V_{PN}	t_r	μs		48	60	0 to 1000 V step, 6 kV/ μs
Frequency bandwidth	BW	kHz		12 6.5 1.6		3 dB 1 dB 0.1 dB
Start-up time		ms		190	250	*
Primary resistance	R_1	M Ω		23		*
Total primary power loss @ V_{PN}	P	W		0.045		*

Definition of typical, minimum and maximum values

Minimum and maximum values for specified limiting and safety conditions have to be understood as such as well as values shown in "typical" graphs. On the other hand, measured values are part of a statistical distribution that can be specified by an interval with upper and lower limits and a probability for measured values to lie within this interval. Unless otherwise stated (e.g. "100 % tested"), the LEM definition for such intervals designated with "min" and "max" is that the probability for values of samples to lie in this interval is 99.73 %. For a normal (Gaussian) distribution, this corresponds to an interval between -3 sigma and +3 sigma. If "typical" values are not obviously mean or average values, those values are defined to delimit intervals with a probability of 68.27 %, corresponding to an interval between -sigma and +sigma for a normal distribution. Typical, maximal and minimal values are determined during the initial characterization of a product.

Typical performance characteristics

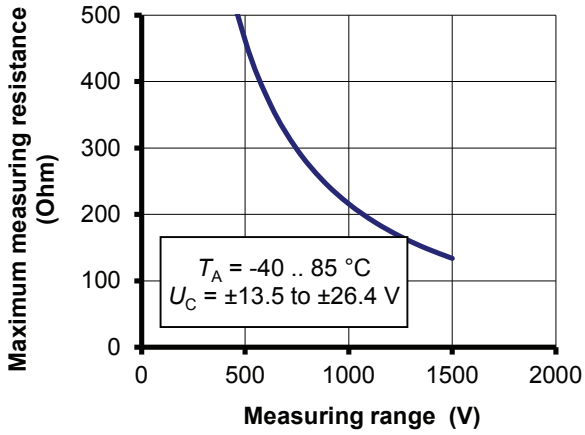


Figure 1: Maximum measuring resistance

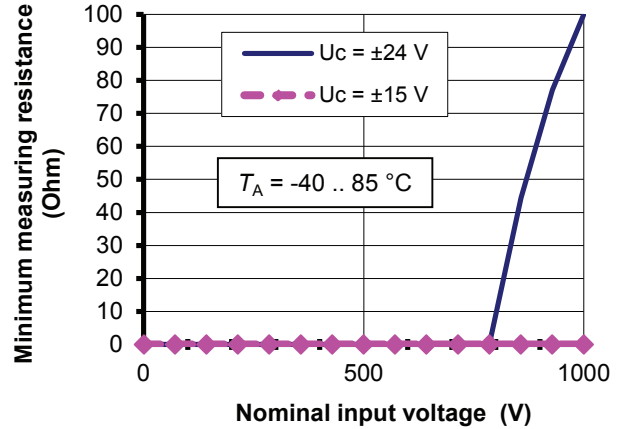


Figure 2: Minimum measuring resistance
For T_A under 80°C , the minimum measuring resistance is $0\ \Omega$ whatever U_C

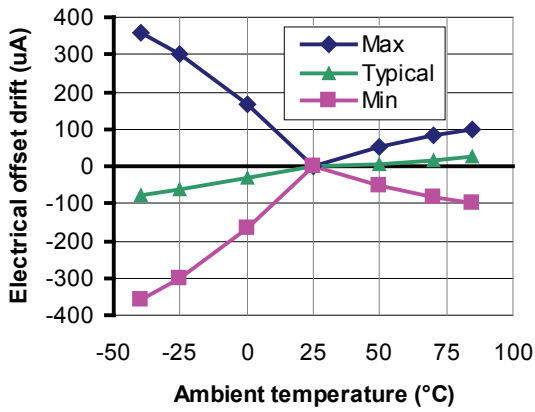


Figure 3: Electrical offset thermal drift

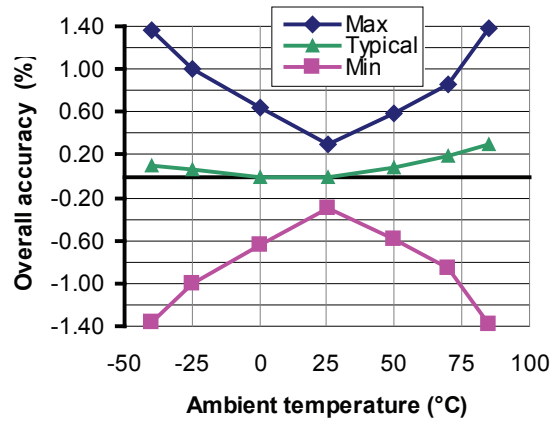


Figure 4: Overall accuracy in temperature

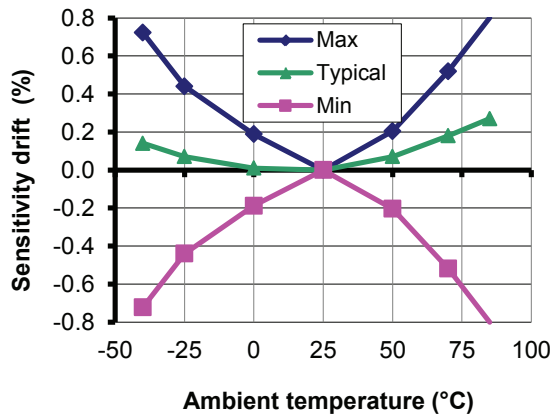


Figure 5: Sensitivity thermal drift

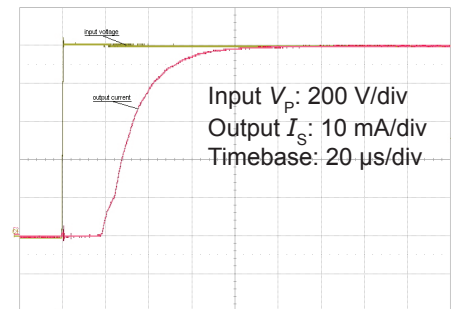


Figure 6: Typical step response (0 to 1000 V)

Typical performance characteristics continued

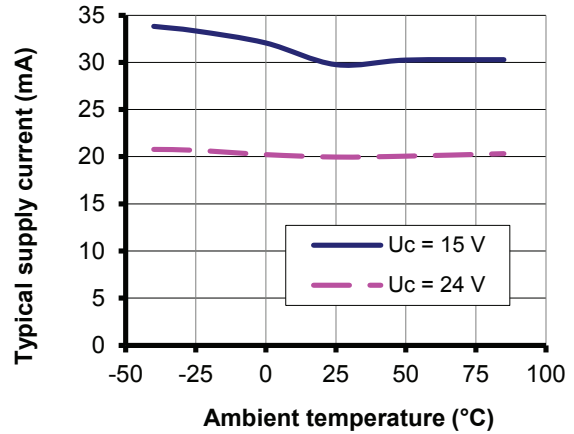
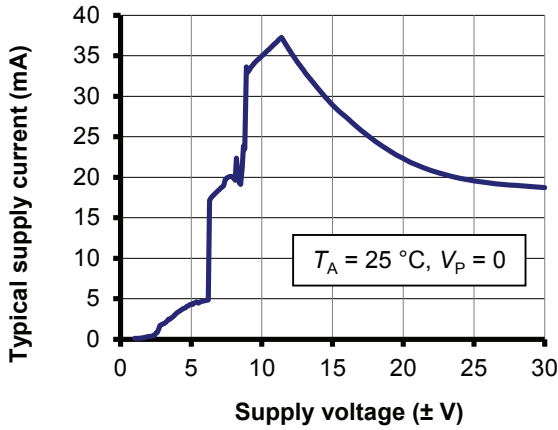


Figure 7: Supply current function of supply voltage

Figure 8: Supply current function of temperature

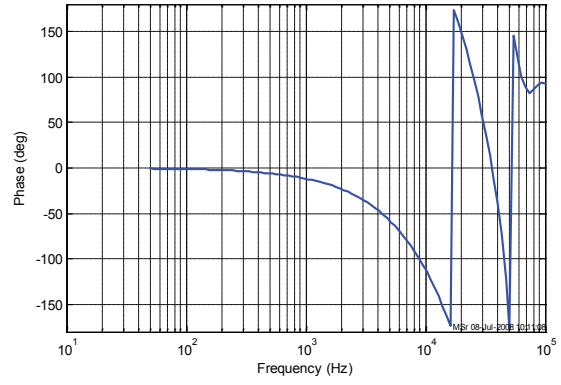
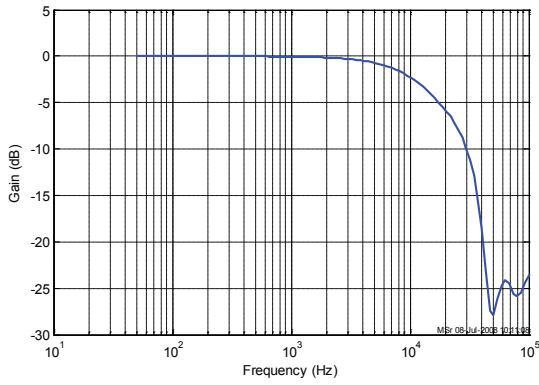


Figure 9: Typical frequency response

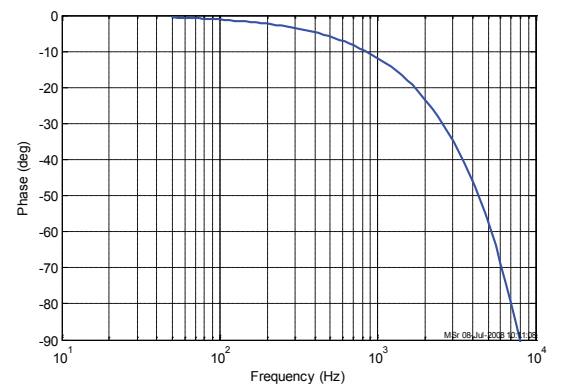
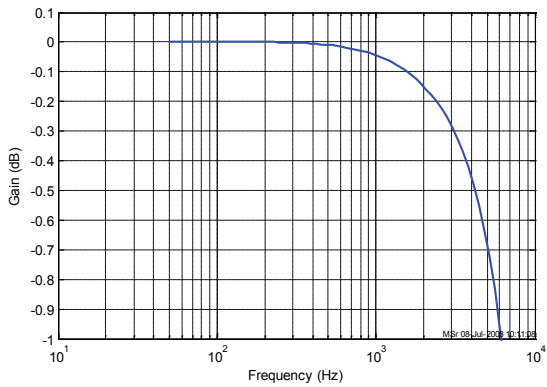


Figure 10: Typical frequency response (detail)

Typical performance characteristics continued

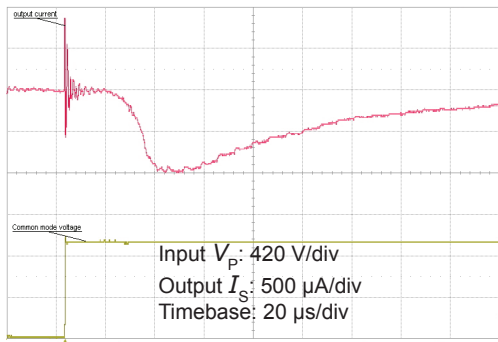


Figure 11: Typical common mode perturbation (1000 V step with 6 kV/µs $R_M = 100 \Omega$)

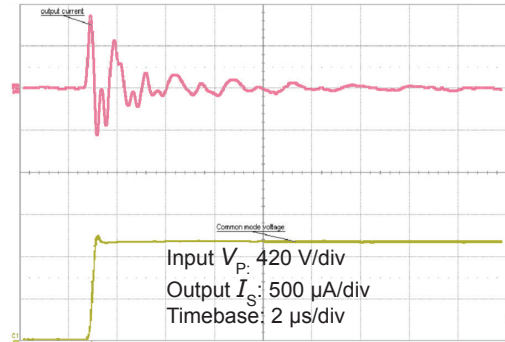


Figure 12: Detail of typical common mode perturbation (1000 V step with 6 kV/µs, $R_M = 100 \Omega$)

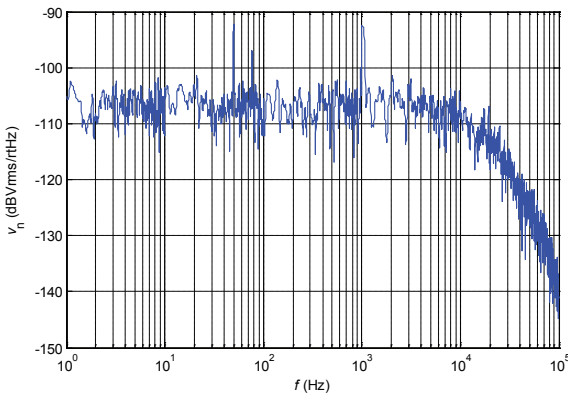


Figure 13: Typical noise power density of $V (R_M)$ with $R_M = 50 \Omega$

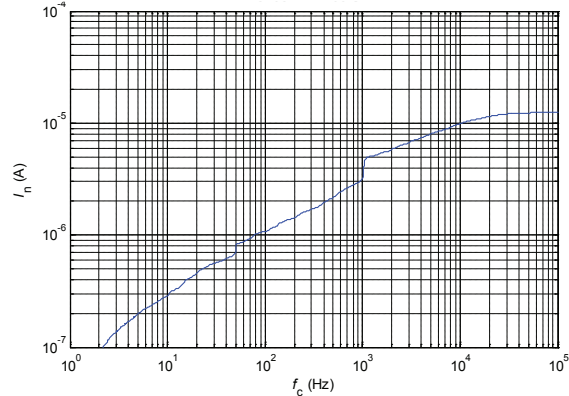


Figure 14: Typical total output current noise (rms) with $R_M = 50 \Omega$ (f_c is upper cut-off frequency of bandpass, low cut off frequency is 1 Hz)

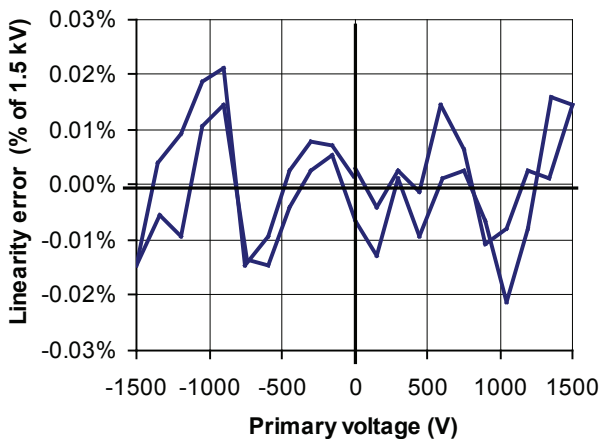


Figure 15: Typical linearity error

Figure 13: (noise power density) shows that there are no significant discrete frequencies in the output. Figure 14 confirms the absence of steps in the total output current noise that would indicate discrete frequencies. To calculate the noise in a frequency band $f1$ to $f2$, the formula is:

$$I_{no}(f1\text{ to }f2) = \sqrt{I_{no}(f2)^2 - I_{no}(f1)^2}$$

with $\ln(f)$ read from figure 14 (typical, rms value).

Example:

What is the noise from 10 to 100 Hz?

Figure 14 gives $\ln(10 \text{ Hz}) = 0.3 \mu\text{A}$ and $\ln(100 \text{ Hz}) = 1 \mu\text{A}$.

The output current noise (rms) is therefore.

$$\sqrt{(1 \cdot 10^{-6})^2 - (0.3 \cdot 10^{-6})^2} = 0.95 \mu\text{A}$$

Performance parameters definition

The schematic used to measure all electrical parameters are:

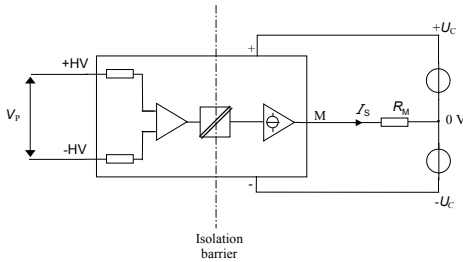


Figure 16: standard characterization schematics for current output transducers ($R_M = 50 \Omega$ unless otherwise noted)

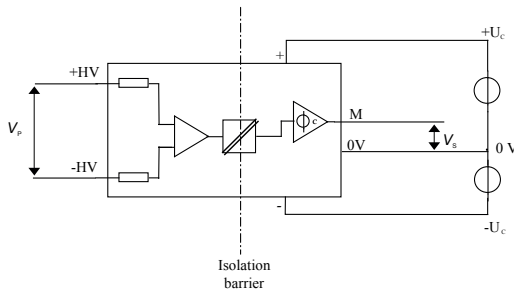


Figure 17: standard characterization schematics for voltage output transducers ($R_M = 100 \text{ k}\Omega$ unless otherwise noted)

For all the following explanations, the output currents I_S , I_O , I_{OT} , etc. should be replaced by voltages for transducers with voltage output: V_S , V_O , V_{OT} etc.

Transducer simplified model

The static model of the transducer at temperature T_A is:

$$I_S = G V_P + \text{error}$$

In which

$$\text{error} = I_{OE} + I_{OT}(T_A) + \epsilon_G G V_P + \epsilon_{GT}(T_A) G V_P + \epsilon_L G V_{PM}$$

- I_S : secondary current (A)
- G : sensitivity of the transducer (A/V)
- V_P : primary voltage (V)
- V_{PM} : primary voltage, measuring range (V)
- T_A : ambient operating temperature ($^{\circ}\text{C}$)
- I_{OE} : electrical offset current (A)
- $I_{OT}(T_A)$: temperature variation of I_O at temperature T_A (A)
- ϵ_G : sensitivity error at 25°C
- $\epsilon_{GT}(T_A)$: thermal drift of sensitivity at temperature T_A
- ϵ_L : linearity error

This is the absolute maximum error. As all errors are independent, a more realistic way to calculate the error would be to use the following formula:

$$\text{error} = \sqrt{\sum (\text{error_component})^2}$$

Sensitivity and linearity

To measure sensitivity and linearity, the primary voltage (DC) is cycled from 0 to V_{PM} , then to $-V_{PM}$ and back to 0 (equally spaced $V_{PM}/10$ steps).

The sensitivity G is defined as the slope of the linear regression line for a cycle between $\pm V_{PM}$.

The linearity error ϵ_L is the maximum positive or negative difference between the measured points and the linear regression line, expressed in % of the maximum measured value.

Magnetic offset

Due to its working principle, this type of transducer has no magnetic offset current I_{OM} .

Electrical offset

The electrical offset current I_{OE} is the residual output current when the input voltage is zero.

The temperature variation I_{OT} of the electrical offset current I_{OE} is the variation of the electrical offset from 25°C to the considered temperature.

Overall accuracy

The overall accuracy X_G is the error at $\pm V_{PN}$, relative to the rated value V_{PN} .

It includes all errors mentioned above.

Response and reaction times

The response time t_r and the reaction time t_{ra} are shown in the next figure.

Both depend on the primary voltage dv/dt . They are measured at nominal voltage.

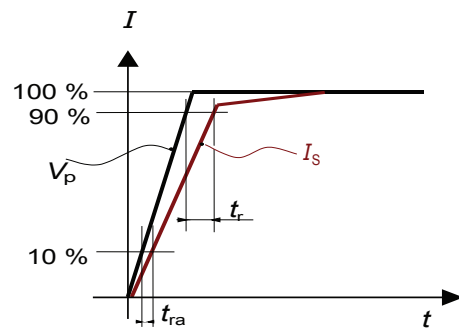
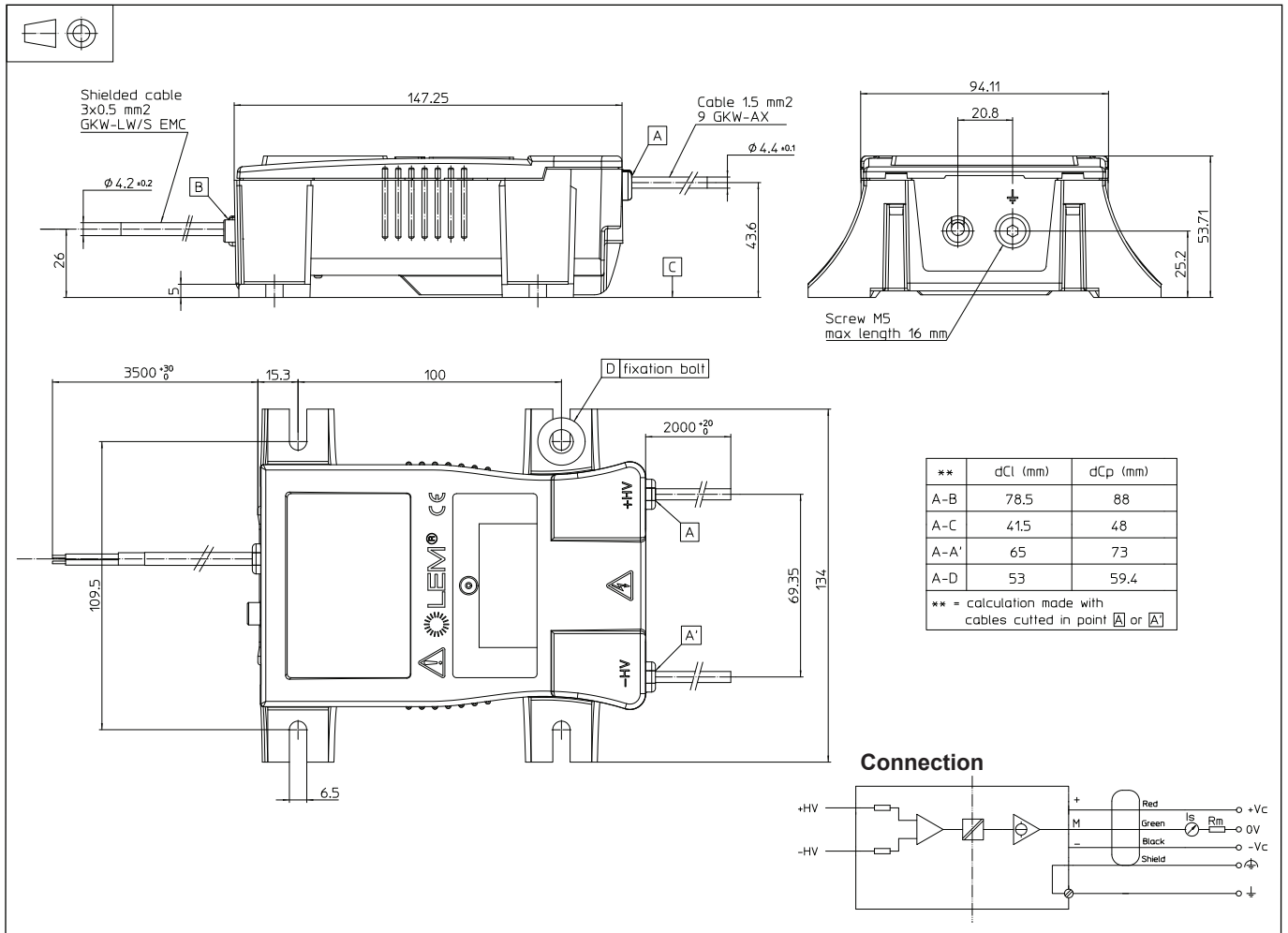


Figure 18: response time t_r and reaction time t_{ra}

Dimensions DV 1000 (in mm)



Mechanical characteristics

- General tolerance ± 1 mm
- Transducer fastening 4 M6 steel screws
4 washers ext. Ø 18 mm
- Recommended fastening torque 5 N·m
- Connection of primary 2 x 1.5 mm² cables
- Connection of secondary 3 x 0.5 mm² shielded cable
- Earth connection M5 threaded stud
- Recommended fastening torque 2.2 N·m

Remarks

- I_s is positive when a positive voltage is applied on +HV.
- The transducer is directly connected to the primary voltage.
- The primary cables have to be routed together all the way.
- The secondary cables also have to be routed together all the way.
- Installation of the transducer is to be done without primary or secondary voltage present.

Safety



This transducer must be used in electric/electronic equipment with respect to applicable standards and safety requirements in accordance with the manufacturer's operating instructions.



Caution, risk of electrical shock

When operating the transducer, certain parts of the module can carry hazardous voltage (eg. primary busbar, power supply). Ignoring this warning can lead to injury and/or cause serious damage. This transducer is a build-in device, whose conducting parts must be inaccessible after installation. A protective housing or additional shield could be used. Main supply must be able to be disconnected.