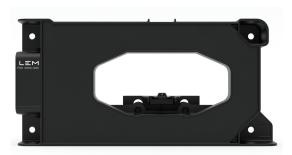


# Current Transducer FRS-Sxlx series <sub>IPN</sub> = 1000 A ... 3000 A

Ref: FRS 1000-Sxlx; FRS 1500-Sxlx; FRS 2000-Sxlx; FRS 2500-Sxlx; FRS 3000-Sxlx

For the electronic measurement of current: DC, AC, pulsed..., with galvanic separation between the primary and the secondary circuit.





#### **Features**

- Hall effect Open Loop Coreless Integral current transducer
- Uni- or Bi-directional <sup>1)</sup> measurement of primary current up to 9000 A
- Instantaneous 4-20 mA current output
- Power supply +12 or +24 V DC
- Galvanic separation between primary and secondary circuit
- Factory calibrated
- High bandwidth > 1 MHz
- Very low delay time < 400 ns.</li>

#### **Advantages**

- Wide measurement range
- No magnetic offset
- Low consumption and low losses
- Wide range of rectangular busbar dimensions
- · Light weight design
- M12 field connector.

## **Applications**

- · Wind turbine power converter
- Electrolyser
- High power drives.

## **Standards**

- IEC 62477-1: 2022
- IEC 61800-5-1: 2022
- IEC 62109-1: 2010
- IEC 61010-1: 2010
- EN 50155: 2021
- IEC 61992-7-2: 2006
- UL 61010-1: 3ED 2022.

## **Application Domains**

- Industrial
- Traction
- Trackside.

Note: 1) see reference table on page 12.

 $N^{\circ}\,97.Y9.60.001.0;\,N^{\circ}\,97.Y9.60.002.0;\,N^{\circ}\,97.Y9.65.003.0;\,N^{\circ}\,97.Y9.65.004.0;\,N^{\circ}\,97.Y9.69.005.0;\,N^{\circ}\,97.Y9.69.006.0;\,N^{\circ}\,97.Y9.70.007.0;\,N^{\circ}\,97.Y9.70.008.0;\,N^{\circ}\,97.Y9.71.009.0;\,N^{\circ}\,97.Y9.60.011.0;\,N^{\circ}\,97.Y9.60.012.0;\,N^{\circ}\,97.Y9.65.013.0;\,N^{\circ}\,97.Y9.65.014.0;\,N^{\circ}\,97.Y9.69.015.0;\,N^{\circ}\,97.Y9.69.016.0;\,N^{\circ}\,97.Y9.70.017.0;\,N^{\circ}\,97.Y9.70.018.0;\,N^{\circ}\,97.Y9.71.019.0;\,N^{\circ}\,97.Y9.71.020.0$ 





#### Safety



Ignoring the warnings can lead to serious injury and/or cause damage. The current transducer may only be installed and put into operation by qualified personnel that have received and appropriate training on applicable safety pecautions.

If the device is used in a way that is not specified by the manufacturer, the protection provided by the device may be compromised. Always inspect the transducer and connecting cable before using this product and do not use it if damaged.

The installation shall guarantee the maximum primary conductor temperature, respect clearance and creepage distances, minimize electric and magnetic coupling. Unless otherwise specified the transducer can be mounted in any orientation using its mounting holes. Primary conductors should not exert any force on the transducer.



Caution, risk of electrical shock

This transducer must be used in limited-energy secondary circuits SELV according to IEC 61010-1, in electric/electronic equipment with respect to applicable standards and safety requirements in accordance with the manufacturer's operating specifications.

Use caution during installation and use of this product; certain parts of the module can carry hazardous voltages and high currents (e.g. power supply, primary conductor).

Ignoring this warning can lead to injury and and/or cause serious damage.

De-energize all circuits and hazardous live parts before installing the product.

All installations, maintenance, servicing operations and use must be carried out by trained and qualified personnel practicing applicable safety precautions.

This transducer is a build-in device, whose hazardous live parts must be inaccessible after installation.

This transducer must be mounted in a suitable end-enclosure.

Besides make sure to have a distance of minimum 30 mm between the primary terminals of the transducer and other neighboring components.

Main supply must be able to be disconnected.

Never connect or disconnect the external power supply while the primary circuit is connected to live parts.

Always wear protective clothing and gloves if hazardous live parts are present in the installation where the measurement is carried out.

This transducer is a built-in device, not intended to be cleaned with any product. Nevertheless if the user must implement cleaning or washing process, validation of the cleaning program has to be done by himself.

Do not dispose of this product as unsorted municipal waste.

Contact a qualified recycler for disposal.





## **Absolute maximum ratings**

Parameter	Symbol	Unit	Value
Maximum supply voltage (not destructive)	$\pm U_{ m C\; max}$	V	-0.3 32 V DC
Maximum primary conductor temperature	$T_{ m B\ max}$	°C	105
Electrostatic discharge voltage (HBM - Human Body Model)	$U_{\rm ESD\; HBM}$	kV	2

Stresses above these ratings may cause permanent damage.

Exposure to absolute maximum ratings for extended periods may degrade reliability.

#### **Insulation coordination**

Parameter	Symbol	Unit	Value	Comment
RMS voltage for AC insulation test, 50 Hz, 1 min	$U_{\mathrm{d}}$	kV	12	
Impulse withstand voltage 1.2/50 µs	$U_{\mathrm{Ni}}$	kV	44	Target, TBC
RMS voltage for AC insulation routine test, 50 Hz, 2"		kV	5.3	Industry application 1)
RMS voltage for AC insulation routine test, 50 Hz, 5"		kV	18.5	Traction application 1)
Partial discharge RMS type test voltage ( $q_{\rm m}$ < 10 pC)	$U_{\mathrm{t}}$	V	2480	Primary/Secondary Industry application 1) 2)
Partial discharge RMS type test voltage ( $q_{\rm m}$ < 10 pC)	$U_{\mathrm{t}}$	V	4840	Primary/Secondary Traction application 1) 2)
Minimum clearance (pri sec.)	$d_{\text{CI}}$	mm	> 72	Shortest distance through air
Minimum creepage distance (pri sec.)	$d_{Cp}$	mm	> 100	Shortest path along device body
Case material	-	-	V0	According to UL 94
Comparative tracking index	CTI		600	
Application example Industry Working voltage		V	1500	Reinforced insulation non-uniform According to: IEC 61800-5-1, CAT III PD2 IEC 62477-1, CAT IV PD3
			1000	IEC 61010-1, CAT IV PD3
Application example Trackside/Traction Nominal voltage Rated insulation voltage	$\begin{array}{c} U_{\rm N} \\ U_{\rm Nm} \end{array}$	V	3000 3600/3700	Reinforced insulation non-uniform According to: IEC 62497-1, CAT III PD3

## **Environmental and mechanical characteristics**

Parameter	Symbol	Unit	Min	Тур	Max	Comment
Ambient operating temperature	$T_{A}$	°C	-40		+85	
Ambient storage temperature	$T_{Ast}$	°C	-40		+90	
Mass	m	g		472		

Notes:  $^{1)}$  See reference table on page 12  $^{2)}$  Garanteed with a centered busbar of 104 x 22 mm maximum dimension with an edge chamfer of 1.5 mm or any other shape and layout providing a minimum clearance of 3 mm between the bare metal and the inner wall of the transducer.



#### **Electrical data FRS 1000-Sxlx**

#### FRS 1000 3000-Sxlx series

At  $T_A$  = 25 °C,  $U_C$  = +24 V,  $R_M$  = 100  $\Omega$ , unless otherwise noted (see Min, Max, typ, definition paragraph in page 9).

Parameter	Symbol	Unit	Min	Тур	Max	Comment
Primary nominal current	$I_{PN}$	Α		1000		See 1)
Primary current, measuring range	$I_{PM}$	А	-3000 0		3000 3000	SBIx version SUIx version
Supply voltage	$U_{C}$	V	10	12 or 24	28	See 2)
Current consumption	$I_{C}$	mA		120 + 1.2 × I <sub>out</sub> 60 + 1.2 × I <sub>out</sub>	180 120	$ @\ U_{\rm C} = {\it 12 V DC}                                  $
Output current range @ $\pm I_{\rm PM}^{\ \ 3)}$ @ 0 $I_{\rm PM}$	$I_{\mathrm{out}}$	mA	4 4		20 20	SBIx version $I_{\rm out}$ = 12 mA @ $I_{\rm p}$ = 0 SUIx version $I_{\rm out}$ = 4 mA @ $I_{\rm p}$ = 0
Measuring resistance	$R_{M}$	Ω	10	100	240	
Electrical offset current referred to primary	$I_{\text{OE}}$	Α	-4.5		4.5	
Temperature coefficient of $I_{\rm OE}$ referred to primary	$TCI_{\text{OE}}$	mA/K	-450 -300		450 300	-40 °C 25 °C 25 °C 85 °C
Nominal sensitivity	$S_{N}$	μΑ/Α		2.667 5.333		SBIx version SUIx version
Magnetic offset current (@ $I_{\rm PN}$ ) referred to primary	$I_{\mathrm{O}\mathrm{M}}$	А		none		No magnetic core inside, OLCI technology
Temperature coefficient of S	TCS	ppm/K	-120		120	−40 °C +85 °C
Linearity error 0 $I_{\rm PM}$	$\varepsilon_{L}$	% of $I_{\rm PM}$	-0.35		0.35	
Sum of sensitivity & Linearity error 0 $I_{\rm PM}$	$\varepsilon_{\rm SL}$	% of $I_{\rm PM}$	-0.5		0.5	Primary busbar centered No return busbar considered 4) 6)
Total error @ 25 °C @ $I_p$ = 0	$arepsilon_{ ext{tot}}$	% of $I_{\rm PM}$	-0.15 -0.65		0.15 0.65	Primary busbar centered No return busbar considered 4) 6)
Total error @ -40 °C @ $I_P = 0$ @ $I_P = \pm I_{PM}$	$arepsilon_{ ext{tot}}$	% of $I_{\rm PM}$	-0.99 -1.55		0.99 1.55	Primary busbar centered No return busbar considered 4) 6)
Total error @ 85 °C @ $I_{\rm p}$ = 0	$arepsilon_{ ext{tot}}$	% of $I_{\rm PM}$	-0.62 -1.25		0.62 1.25	Primary busbar centered No return busbar considered 4) 6)
Delay time @ 10 % of the final output value $I_{\rm PN}$ step	t <sub>D 10</sub>	μs			0.3 0.4	SBIx version @ 100 A/µs SUIx version @ 100 A/µs
Delay time @ 90 % of the final output value $I_{\rm PN}$ step	t <sub>D 90</sub>	μs			0.3 0.4	SBIx version @ 100 A/µs SUIx version @ 100 A/µs
Frequency bandwidth (-3 dB)	BW	kHz		1000		See 5)
RMS noise current spectral density referred to primary 100 Hz 100 kHz 100 kHz 1 MHz	i <sub>no</sub>	mA/√Hz			21.1 & 423 0.7 & 1.3	FRS xxx-SBI & FRS xxx-SUI
Peak to peak noise current referred to primary: up to 10 kHz up to 100 kHz up to 1 MHz		А		1.4 & 2.9 2.0 & 4.0 2.1 & 4.3		FRS xxx-SBI & FRS xxx-SUI

- <sup>2)</sup> Above 28 V, accuracy performance may change irremediably
- <sup>3)</sup> Rounded, actual value is obtained by the following formula:  $\pm I_{\rm PM} \times S_{\rm N}$
- See <u>page 11</u> typical influence of the return busbar regarding its position
- The maximum admissible couple of ( $I_{\rm PM}$  and frequency) is specified on page 10
- Transducer may have an additional drift when exposed to high temperature and high humidity:
  - A drift of 1.7 % could be seen after an exposure at 85 °C /85 % during 1000 hours
  - This drift is reversible when the transducer goes back to normal conditions.



#### **Electrical data FRS 1500-Sxlx**

#### FRS 1000 3000-Sxlx series

At  $T_A$  = 25 °C,  $U_C$  = +24 V,  $R_M$  = 100  $\Omega$ , unless otherwise noted (see Min, Max, typ, definition paragraph in page 9).

Parameter	Symbol	Unit	Min	Тур	Max	Comment
Primary nominal current	$I_{PN}$	Α		1500		See 1)
Primary current, measuring range	$I_{PM}$	А	-4500 0		4500 4500	SBIx version SUIx version
Supply voltage	$U_{C}$	V	10	12 or 24	28	See 2)
Current consumption	$I_{C}$	mA		120 + 1.2 × I <sub>out</sub> 60 + 1.2 × I <sub>out</sub>	180 120	
Output current range @ $\pm I_{\rm PM}^{~3)}$ @ 0 $I_{\rm PM}$	$I_{\mathrm{out}}$	mA	4 4		20 20	SBIx version $I_{\text{out}}$ = 12 mA @ $I_{\text{p}}$ = 0 SUIx version $I_{\text{out}}$ = 4 mA @ $I_{\text{p}}$ = 0
Measuring resistance	$R_{M}$	Ω	10	100	240	
Electrical offset current referred to primary	$I_{\text{OE}}$	Α	-6.8		6.8	
Temperature coefficient of $I_{\text{OE}}$ referred to primary	TCI <sub>o E</sub>	mA/K	-600 -450		600 450	-40 °C 25 °C 25 °C 85 °C
Nominal sensitivity	$S_{N}$	μA/A		1.778 3.556		SBIx version SUIx version
Magnetic offset current (@ $I_{\rm PN}$ ) referred to primary	$I_{\mathrm{O}\mathrm{M}}$	А		none		No magnetic core inside, OLCI technology
Temperature coefficient of S	TCS	ppm/K	-120		120	−40 °C +85 °C
Linearity error 0 $I_{PM}$	$\varepsilon_{L}$	% of $I_{\rm PM}$	-0.35		0.35	
Sum of sensitivity & Linearity error 0 $I_{\rm PM}$	$\varepsilon_{\mathrm{SL}}$	% of $I_{PM}$	-0.5		0.5	Primary busbar centered No return busbar considered 4) 6)
Total error @ 25 °C @ $I_P = 0$	$arepsilon_{ ext{tot}}$	% of $I_{\rm PM}$	-0.15 -0.65		0.15 0.65	Primary busbar centered No return busbar considered 4) 6)
Total error @ -40 °C @ $I_P = 0$ @ $I_P = \pm I_{PM}$	$arepsilon_{ ext{tot}}$	% of $I_{\rm PM}$	-0.99 -1.55		0.99 1.55	Primary busbar centered No return busbar considered 4) 6)
Total error @ 85 °C @ $I_P = 0$	$arepsilon_{ ext{tot}}$	% of $I_{\rm PM}$	-0.62 -1.25		0.62 1.25	Primary busbar centered No return busbar considered 4) 6)
Delay time @ 10 % of the final output value $I_{\rm PN}$ step	t <sub>D 10</sub>	μs			0.3 0.4	SBIx version @ 100 A/µs SUIx version @ 100 A/µs
Delay time @ 90 % of the final output value $I_{\rm PN}$ step	t <sub>D 90</sub>	μs			0.3 0.4	SBIx version @ 100 A/µs SUIx version @ 100 A/µs
Frequency bandwidth (-3 dB)	BW	kHz		1000		See 5)
RMS noise current spectral density referred to primary 100 Hz 100 kHz 100 kHz 1 MHz	i <sub>no</sub>	mA/√Hz			33.0 & 66.0 0.8 & 1.7	FRS xxx-SBI & FRS xxx-SUI
Peak to peak noise current referred to primary: up to 10 kHz up to 100 kHz up to 1 MHz	$I_{nopp}$	А		1.9 & 3.8 2.5 & 4.9 2.6 & 5.3		FRS xxx-SBI & FRS xxx-SUI

- Above 28 V, accuracy performance may change irremediably
- Rounded, actual value is obtained by the following formula:  $\pm I_{\rm PM} \times S_{\rm N}$
- See <u>page 11</u> typical influence of the return busbar regarding its position
- The maximum admissible couple of  $(I_{PM})$  and frequency) is specified on page 10
- 6) Transducer may have an additional drift when exposed to high temperature and high humidity:
  - A drift of 1.7 % could be seen after an exposure at 85 °C /85 % during 1000 hours
  - This drift is reversible when the transducer goes back to normal conditions.



#### **Electrical data FRS 2000-Sxlx**

#### FRS 1000 3000-Sxlx series

At  $T_A = 25$  °C,  $U_C = +24$  V,  $R_M = 100$   $\Omega$ , unless otherwise noted (see Min, Max, typ, definition paragraph in page 9).

Parameter	Symbol	Unit	Min	Тур	Max	Comment
Primary nominal current	$I_{PN}$	Α		2000		See 1)
Primary current, measuring range	$I_{\mathrm{PM}}$	А	-6000 0		6000 6000	SBIx version SUIx version
Supply voltage	$U_{C}$	V	10	12 or 24	28	See 2)
Current consumption	$I_{\mathtt{C}}$	mA		120 + 1.2 × I <sub>out</sub> 60 + 1.2 × I <sub>out</sub>	180 120	(@ $U_{\rm c}$ = 12 V DC (@ $U_{\rm c}$ = 24 V DC
Output current range @ $\pm I_{\rm PM}^{\ \ 3)}$ @ 0 $I_{\rm PM}$	$I_{\mathrm{out}}$	mA	4 4		20 20	SBIx version $I_{\rm out}$ = 12 mA @ $I_{\rm p}$ = 0 SUIx version $I_{\rm out}$ = 4 mA @ $I_{\rm p}$ = 0
Measuring resistance	$R_{M}$	Ω	10	100	240	
Electrical offset current referred to primary	Ioe	Α	-9		9	
Temperature coefficient of $I_{\text{OE}}$ referred to primary	TCI <sub>OE</sub>	mA/K	-900 -600		900 600	-40 °C 25 °C 25 °C 85 °C
Nominal sensitivity	$S_{N}$	μΑ/Α		1.333 2.667		SBIx version SUIx version
Magnetic offset current (@ $I_{\rm PN}$ ) referred to primary	$I_{ m OM}$	А		none		No magnetic core inside, OLCI technology
Temperature coefficient of S	TCS	ppm/K	-120		120	−40 °C +85 °C
Linearity error 0 $I_{\rm PM}$	$\varepsilon_{L}$	% of $I_{\rm PM}$	-0.35		0.35	
Sum of sensitivity & Linearity error 0 $I_{\rm PM}$	$\varepsilon_{\rm SL}$	% of $I_{\rm PM}$	-0.5		0.5	Primary busbar centered No return busbar considered <sup>4) 6)</sup>
Total error @ 25 °C @ $I_{\rm p}$ = 0	$arepsilon_{ ext{tot}}$	% of $I_{\rm PM}$	-0.15 -0.65		0.15 0.65	Primary busbar centered No return busbar considered 4) 6)
Total error @ -40 °C @ $I_P = 0$ @ $I_P = \pm I_{PM}$	$arepsilon_{ ext{tot}}$	% of $I_{\rm PM}$	-0.99 -1.55		0.99 1.55	Primary busbar centered No return busbar considered 4) 6)
Total error @ 85 °C @ $I_p = 0$	$arepsilon_{ ext{tot}}$	% of $I_{\rm PM}$	-0.62 -1.25		0.62 1.25	Primary busbar centered No return busbar considered 4) 6)
Delay time @ 10 % of the final output value $I_{\rm PN}$ step	t <sub>D 10</sub>	μs			0.3 0.4	SBIx version @ 100 A/µs SUIx version @ 100 A/µs
Delay time @ 90 % of the final output value $I_{\rm PN}$ step	t <sub>D 90</sub>	μs			0.3 0.4	SBIx version @ 100 A/µs SUIx version @ 100 A/µs
Frequency bandwidth (-3 dB)	BW	kHz		1000		See 5)
RMS noise current spectral density referred to primary 100 Hz 100 kHz 100 kHz 1 MHz	i <sub>no</sub>	mA/√Hz			39.0 & 77.9 0.9 & 1.8	FRS xxx-SBI & FRS xxx-SUI
Peak to peak noise current referred to primary: up to 10 kHz up to 100 kHz up to 1 MHz	$I_{nopp}$	А		2.1 & 4.3 2.7 & 5.4 2.9 & 5.8		FRS xxx-SBI & FRS xxx-SUI

- <sup>2)</sup> Above 28 V, accuracy performance may change irremediably
- Rounded, actual value is obtained by the following formula:  $\pm I_{\rm PM} \times S_{\rm N}$
- See <u>page 11</u> typical influence of the return busbar regarding its position
- The maximum admissible couple of  $(I_{PM}$  and frequency) is specified on page 10
- Transducer may have an additional drift when exposed to high temperature and high humidity:
  - A drift of 1.7 % could be seen after an exposure at 85 °C /85 % during 1000 hours
  - This drift is reversible when the transducer goes back to normal conditions.



#### Electrical data FRS 2500-Sxlx

#### FRS 1000 3000-Sxlx series

At  $T_{\rm A}$  = 25 °C,  $U_{\rm C}$  = +24 V,  $R_{\rm M}$  = 100  $\Omega$ , unless otherwise noted (see Min, Max, typ, definition paragraph in page 9).

Parameter	Symbol	Unit	Min	Тур	Max	Comment
Primary nominal current	$I_{PN}$	А		2500		See 1)
Primary current, measuring range	$I_{PM}$	А	-7500 0		7500 7500	SBIx version SUIx version
Supply voltage	$U_{C}$	V	10	12 or 24	28	See 2)
Current consumption	$I_{C}$	mA		120 + 1.2 × I <sub>out</sub> 60 + 1.2 × I <sub>out</sub>	180 120	$\bigcirc U_{\rm C} = 12 \text{ V DC}$ $\bigcirc U_{\rm C} = 24 \text{ V DC}$
Output current range @ $\pm I_{\rm PM}^{~3)}$ @ 0 $I_{\rm PM}$	$I_{\mathrm{out}}$	mA	4 4		20 20	SBIx version $I_{\rm out}$ = 12 mA @ $I_{\rm P}$ = 0 SUIx version $I_{\rm out}$ = 4 mA @ $I_{\rm P}$ = 0
Measuring resistance	$R_{M}$	Ω	0	100	240	
Electrical offset current referred to primary	$I_{\text{OE}}$	А	-11.3		11.3	
Temperature coefficient of $I_{\text{OE}}$ referred to primary	TCI <sub>OE</sub>	mA/K	-1125 -750		1125 750	-40 °C 25 °C 25 °C 85 °C
Nominal sensitivity	$S_{N}$	μΑ/Α		1.067 2.133		SBIx version SUIx version
Magnetic offset current (@ $I_{\rm PN}$ ) referred to primary	$I_{\mathrm{OM}}$	А		none		No magnetic core inside, OLCI technology
Temperature coefficient of S	TCS	ppm/K	-120		120	−40 °C +85 °C
Linearity error 0 I <sub>PM</sub>	$\varepsilon_{L}$	% of $I_{\rm PM}$	-0.35		0.35	
Sum of sensitivity & Linearity error 0 $I_{\rm PM}$	$\varepsilon_{\rm SL}$	% of $I_{\rm PM}$	-0.5		0.5	Primary busbar centered No return busbar considered 4) 6)
Total error @ 25 °C @ $I_P = 0$	$arepsilon_{ ext{tot}}$	% of $I_{\rm PM}$	-0.15 -0.65		0.15 0.65	Primary busbar centered No return busbar considered 4) 6)
Total error @ -40 °C @ $I_P = 0$ @ $I_P = \pm I_{PM}$	$arepsilon_{ ext{tot}}$	% of $I_{\rm PM}$	-0.99 -1.55		0.99 1.55	Primary busbar centered No return busbar considered 4) 6)
Total error @ 85 °C @ $I_P = 0$	$arepsilon_{ ext{tot}}$	% of $I_{\rm PM}$	-0.62 -1.25		0.62 1.25	Primary busbar centered No return busbar considered 4) 6)
Delay time @ 10 % of the final output value $I_{\rm PN}$ step	t <sub>D 10</sub>	μs			0.3 0.4	SBIx version @ 100 A/µs SUIx version @ 100 A/µs
Delay time @ 90 % of the final output value $I_{\rm PN}$ step	t <sub>D 90</sub>	μs			0.3 0.4	SBIx version @ 100 A/µs SUIx version @ 100 A/µs
Frequency bandwidth (-3 dB)	BW	kHz		1000		See 5)
RMS noise current spectral density referred to primary 100 Hz 100 kHz 100 kHz 1 MHz	i <sub>no</sub>	mA/√Hz			42.5 & 85.0 1.0 & 1.9	FRS xxx-SBI & FRS xxx-SUI
Peak to peak noise current referred to primary: up to 10 kHz up to 100 kHz up to 1 MHz	$I_{nopp}$	mA		2.3 & 4.6 2.9 & 5.7 3.1 & 6.1		FRS xxx-SBI & FRS xxx-SUI

- <sup>2)</sup> Above 28 V, accuracy performance may change irremediably
- Rounded, actual value is obtained by the following formula:  $\pm I_{\rm PM} \times S_{\rm N}$
- See <u>page 11</u> typical influence of the return busbar regarding its position
- The maximum admissible couple of  $(I_{PM})$  and frequency) is specified on page 10
- Transducer may have an additional drift when exposed to high temperature and high humidity:
  - A drift of 1.7 % could be seen after an exposure at 85 °C /85 % during 1000 hours
  - This drift is reversible when the transducer goes back to normal conditions.



#### **Electrical data FRS 3000-Sxlx**

#### FRS 1000 3000-Sxlx series

At  $T_{\rm A}$  = 25 °C,  $U_{\rm C}$  = +24 V,  $R_{\rm M}$  = 100  $\Omega$ , unless otherwise noted (see Min, Max, typ, definition paragraph in page 9).

Parameter	Symbol	Unit	Min	Тур	Max	Comment
Primary nominal current	$I_{PN}$	Α		3000		See 1)
Primary current, measuring range	$I_{\mathrm{PM}}$	А	-9000 0		9000 9000	SBIx version SUIx version
Supply voltage	$U_{C}$	V	10	12 or 24	28	See 2)
Current consumption	$I_{\mathtt{C}}$	mA		120 + 1.2 × I <sub>out</sub> 60 + 1.2 × I <sub>out</sub>	180 120	$( U_{\rm C} = 12 \text{ V DC} )$ $( U_{\rm C} = 24 \text{ V DC} )$
Output current range @ $\pm I_{\rm PM}^{\ \ 3)}$ @ 0 $I_{\rm PM}$	$I_{\mathrm{out}}$	mA	4 4		20 20	SBIx version $I_{\rm out}$ = 12 mA @ $I_{\rm P}$ = 0 SUIx version $I_{\rm out}$ = 4 mA @ $I_{\rm P}$ = 0
Measuring resistance	$R_{M}$	Ω	0	100	240	
Electrical offset current referred to primary	$I_{\text{OE}}$	Α	-13.5		13.5	
Temperature coefficient of $I_{\text{OE}}$ referred to primary	TCI <sub>OE</sub>	mA/K	-1350 -900		1350 900	−40 °C 25 °C 25 °C 85 °C
Nominal sensitivity	$S_{N}$	μΑ/Α		0.889 1.778		SBIx version SUIx version
Magnetic offset current (@ $I_{\rm PN}$ ) referred to primary	$I_{ m OM}$	А		none		No magnetic core inside, OLCI technology
Temperature coefficient of S	TCS	ppm/K	-120		120	−40 °C +85 °C
Linearity error 0 $I_{_{\rm PM}}$	$\varepsilon_{L}$	% of $I_{\rm PM}$	-0.35		0.35	
Sum of sensitivity & Linearity error 0 $I_{\rm PM}$	$\varepsilon_{_{\mathrm{S}\mathrm{L}}}$	% of $I_{\rm PM}$	-0.5		0.5	Primary busbar centered No return busbar considered 4) 6)
Total error @ 25 °C @ $I_p$ = 0	$arepsilon_{ ext{tot}}$	% of $I_{\rm PM}$	-0.15 -0.65		0.15 0.65	Primary busbar centered No return busbar considered 4) 6)
Total error @ -40 °C @ $I_P = 0$ @ $I_P = \pm I_{PM}$	$arepsilon_{ ext{tot}}$	% of $I_{\rm PM}$	-0.99 -1.55		0.99 1.55	Primary busbar centered No return busbar considered 4) 6)
Total error @ 85 °C @ $I_p$ = 0	$arepsilon_{ ext{tot}}$	% of $I_{\rm PM}$	-0.62 -1.25		0.62 1.25	Primary busbar centered No return busbar considered 4) 6)
Delay time @ 10 % of the final output value $I_{\rm PN}$ step	t <sub>D 10</sub>	μs			0.3 0.4	SBIx version @ 100 A/µs SUIx version @ 100 A/µs
Delay time @ 90 % of the final output value $I_{\rm PN}$ step	t <sub>D 90</sub>	μs			0.3 0.4	SBIx version @ 100 A/µs SUIx version @ 100 A/µs
Frequency bandwidth (-3 dB)	BW	kHz		1000		See 5)
RMS noise current spectral density referred to primary 100 Hz 100 kHz 100 kHz 1 MHz	i <sub>no</sub>	mA/√Hz			44.9&89.8 1.0&2.0	FRS xxx-SBI & FRS xxx-SUI
Peak to peak noise current referred to primary: up to 10 kHz up to 100 kHz up to 1 MHz	$I_{nopp}$	А		2.4 & 4.8 3.0 & 5.9 3.2 & 6.3		FRS xxx-SBI & FRS xxx-SUI

- <sup>2)</sup> Above 28 V, accuracy performance may change irremediably
- Rounded, actual value is obtained by the following formula:  $\pm I_{\rm PM} \times S_{\rm N}$
- See <u>page 11</u> typical influence of the return busbar regarding its position
- The maximum admissible couple of  $(I_{PM})$  and frequency) is specified on page 10
- Transducer may have an additional drift when exposed to high temperature and high humidity:
  - A drift of 1.7 % could be seen after an exposure at 85 °C /85 % during 1000 hours
  - This drift is reversible when the transducer goes back to normal conditions.





#### FRS 1000 3000-Sxlx series

#### Definition of typical, minimum and maximum values

Minimum and maximum values for specified limiting and safety conditions have to be understood as such as well as values shown in "typical" graphs.

On the other hand, measured values are part of a statistical distribution that can be specified by an interval with upper and lower limits and a probability for measured values to lie within this interval.

Unless otherwise stated (e.g. "100 % tested"), the LEM definition for such intervals designated with "min" and "max" is that the probability for values of samples to lie in this interval is 99.73 %.

For a normal (Gaussian) distribution, this corresponds to an interval between -3 sigma and +3 sigma. If "typical" values are not obviously mean or average values, those values are defined to delimit intervals with a probability of 68.27 %, corresponding to an interval between -sigma and +sigma for a normal distribution.

Typical, maximal and minimal values are determined during the initial characterization of the product.



## Maximum admissible couple of ( $I_{\rm P\,M}$ & Frequency)

## Typical input/output characteristics

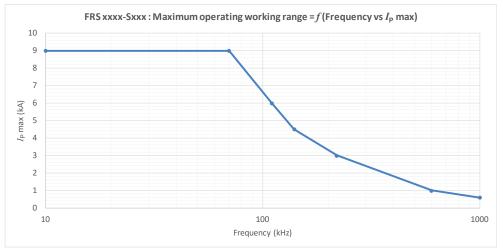


Figure 1: Bi-polar output current  $I_{\rm out}\,{\rm VS}$  primary current  $I_{\rm P}$ 

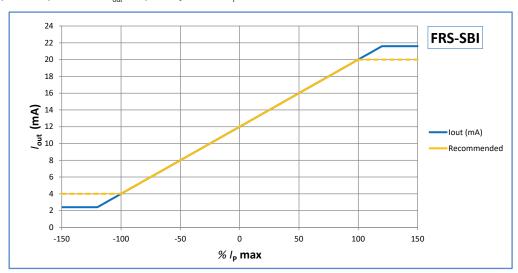
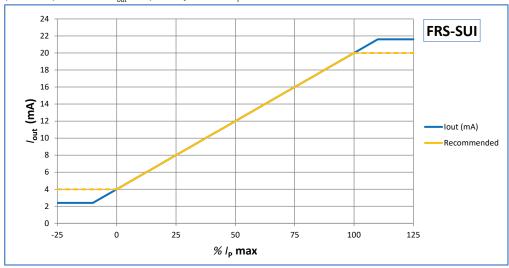


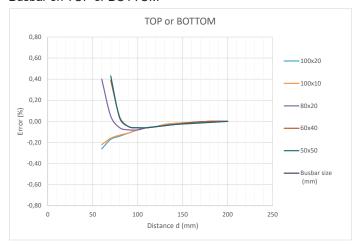
Figure 2: Uni-polar output current  $I_{\mathrm{out}}$  VS primary current  $I_{\mathrm{P}}$ 

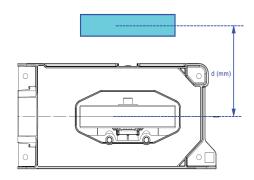




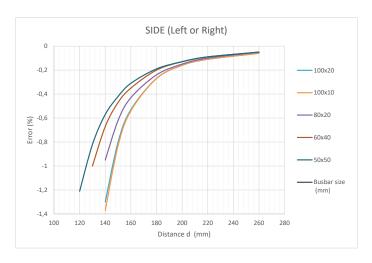
## Typical additional error due to return busbar layout and distance

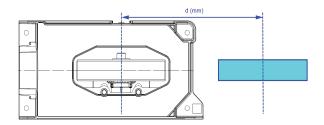
## Busbar on TOP or BOTTOM





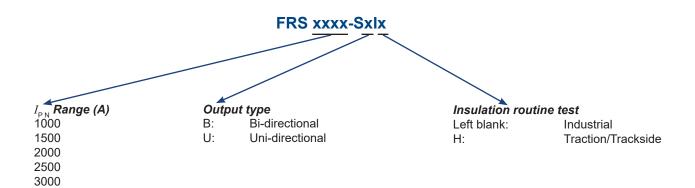
## Busbar on the side (LEFT or RIGHT)







## FRS-Sxlx series: name and codification



## FRS-Sxlx series: ordering

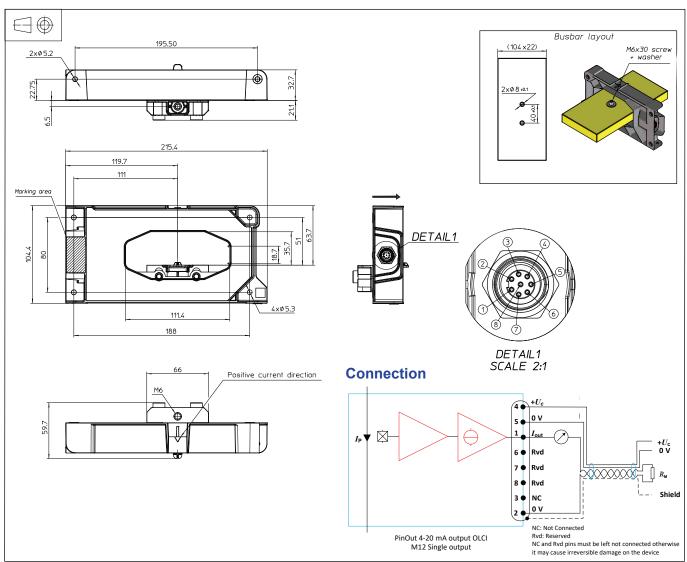
Name	Part numbers
FRS 1000-SBI	90.Y9.60.001.0
FRS 1000-SUI	90.Y9.60.002.0
FRS 1500-SBI	90.Y9.65.003.0
FRS 1500-SUI	90.Y9.65.004.0
FRS 2000-SBI	90.Y9.69.005.0
FRS 2000-SUI	90.Y9.69.006.0
FRS 2500-SBI	90.Y9.70.007.0
FRS 2500-SUI	90.Y9.70.008.0
FRS 3000-SBI	90.Y9.71.009.0
FRS 3000-SUI	90.Y9.71.010.0
FRS 1000-SBIH	90.Y9.60.011.0
FRS 1000-SUIH	90.Y9.60.012.0
FRS 1500-SBIH	90.Y9.65.013.0
FRS 1500-SUIH	90.Y9.65.014.0
FRS 2000-SBIH	90.Y9.69.015.0
FRS 2000-SUIH	90.Y9.69.016.0
FRS 2500-SBIH	90.Y9.70.017.0
FRS 2500-SUIH	90.Y9.70.018.0
FRS 3000-SBIH	90.Y9.71.019.0
FRS 3000-SUIH	90.Y9.71.020.0

Note: 1) This is an exhaustive list, to date some references may not yet exist, please contact your local LEM's sales support.





#### **Dimensions** (in mm)



#### **Mechanical characteristics**

General tolerance ±1 mm

Aperture for primary conductor
 104 mm × 22 mm (max)

Transducer fastening

 $\begin{array}{ll} \text{Bracket fastening} & 2 \times \text{M6 (supplied)} \\ \text{Busbar fastening} & 1 \times \text{M6 (not supplied)} \\ \text{Recommended fastening torque} & 6 \text{ N} \cdot \text{m} \pm 10 \text{ \%} \\ \end{array}$ 

Connection of secondary

Use M12 Male/Male, coding A, 8 terminals, shielded

#### **Remarks**

- ullet  $I_{\mathrm{out}}$  is positive when positive  $I_{\mathrm{P}}$  flows in direction of the arrow shown on the drawing above.
- Temperature of the primary conductor should not exceed 105 °C.
- Installation of the transducer must be done unless otherwise specified on the datasheet, according to LEM Transducer Generic Mounting Rules. Please refer to LEM document N°ANE120504 available on our Web site: <a href="https://www.lem.com/en/file/3137/download">https://www.lem.com/en/file/3137/download</a>

#### Recommandation

When primary and return busbars carry high frequency current it is highly recommanded to use a twisted signal pair (pin number 1 & 2).