

Technical Manual





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Table of Contents

| 1. | SAFETY INSTRUCTIONS | 4 |
|---|--|---|
| 2. | DECLARATION OF CONFORMITY FEHLER! TEXTMARKE NICHT DEFINIER | RT. |
| 3. 3.1. 3.2. 3.3. | INTRODUCTION Overview Key features and Specifications Housing | 5 6 9 |
| 4. 4.1. 4.1.1. 4.1.2. 4.2. 4.2.1. 4.2.2. 4.2.3. 4.2.4. 4.2.5. 4.3. 4.4. 4.5. | INSTALLATION Recommendations Control Cabinet Design Cabling Mechanical Installation Electrical Connections Power Supply and Grounding Load Cell Connection RS232 Connection RS 485 Connection Communication Interface Commissioning Cleaning Disposal | 10 .10 .10 .10 .10 .10 .11 .11 .12 .12 .12 |
| 5. 5.2. 5.3. 5.3.1. 5.3.2. 5.3.3. 5.4. 5.5. 5.6. 5.7. | SETUP. Installation of the xFace Software. Connection to the xFace Software. Setup and Calibration Scale Parameters Serial Interface Setup Scale Build and Calibration. Performance Test Bus Interface Setup . Bus Addressing via Setup Switch Back up Settings and Calibration Data | 13 .13 .14 .15 .16 .17 .20 .20 .20 |
| 6. 6.1. 6.2. 6.3. 6.4. 6.5. | SERIAL INTERFACES RS 232C Connection RS 485 Connection Interfacing Continuous Output Data Structure (for FAD-30/MB/EN only) BSI Data Structure (for FAD-30/MB only) | 21 .21 .22 .23 .23 |
| 7. 7.1. 7.2. 7.3. 7.4. | FAD-30 / FAD-30MB – WITH RS-485 INTERFACE Front View Electrical Connections Interfacing Modbus RTU Setup (for FAD-30MB only) | 27 .27 .28 .28 .29 |
| 8. 8.1. 8.2. 8.3. 8.4. | FAD-30PB – WITH PROFIBUS INTERFACE Front View Electrical Connections Profibus Setup and GSD /GSDML configuration Profibus Data StructureFehler! Textmarke nicht definiert. (for FAD-30PB only) | 31 .31 .32 .33 .33 |
| 9. 9.1. 9.2. 9.3. 9.4. | FAD-30PN – WITH PROFINET INTERFACE Front View Electrical Connections Profinet Setup and GSDML configuration Profinet Data Structure | 34 .34 .35 .36 .37 |
| 10. 10.1. 10.2. | FAD-30EN – WITH ETHERNET INTERFACE. Front View Electrical Connections. | 38 .38 .39 |

| 10.3. | Ethernet Setup | 40 |
|--|--|------------------------------------|
| 11. 11. 11. 11. 11. 2 | FAD-30CO – WITH CANOPEN INTERFACE. Front View | 40 41 41 42 |
| 11.4. | CANopen Data Structure (for FAD-30CO only) | 43 44 |
| 12. 12.1. 12.2. 12.3. 12.4. | FAD-30EI – WITH ETHERNET/IP INTERFACE Front View Electrical Connections EtherNet/IP Setup and ESD Configuration EtherNET/IP Data Structure | 48 50 51 51 |
| 13. 13.1. 13.2. 13.3. 13.4. | FAD-30EC WITH ETHERCAT INTERFACE Front View Electrical Connection EtherCAT Setup and ESI Configuration EtherCAT Data Structure | .52 52 54 55 55 |
| 14. 14.1. 14.2. 14.3. 14.4. | FAD-30CC WITH CC-LINK INTERFACE Front View Electrical Connection CC-Link Setup and configuration CC-Link Data Structure | . 56 57 58 58 |
| 15. 15.1. 15.2. 15.3. 15.1. | FAD-30 PL WITH POWERLINK INTERFACE Front View Powerlink Connection Powerlink Setup and XDD Configuration Powerlink Data Structure | .59 61 62 62 |
| 16. LINK | DATA STRUCTURE FOR PROFIBUS, PROFINET, ETHERNET/IP, ETHERCAT, C X, POWERLINK | ;C- 63 |
| 17. | ERROR TABLE | .67 |
| 18. | DIAGNOSTICS | .68 |
| | | |

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1. SAFETY INSTRUCTIONS



CAUTION READ this manual BEFORE operating or servicing this equipment. FOLLOW these instructions carefully. SAVE this manual for future reference. DO NOT allow untrained personnel to operate, clean, inspect, maintain, service, or tamper with this equipment. ALWAYS DISCONNECT this equipment from the power source before cleaning or performing maintenance. CALL FLINTEC ENGINEERING for parts, information, and service.



WARNING ONLY PERMIT QUALIFIED PERSONNEL TO SERVICE THIS EQUIPMENT. EXERCISE CARE WHEN MAKING CHECKS, TESTS AND ADJUSTMENTS THAT MUST BE MADE WITH POWER ON. FAILING TO OBSERVE THESE PRECAUTIONS CAN RESULT IN BODILY HARM.



WARNING FOR CONTINUED PROTECTION AGAINST SHOCK HAZARD CONNECT TO PROPERLY GROUNDED OUTLET ONLY. DO NOT REMOVE THE GROUND PRONG.



WARNING DISCONNECT ALL POWER TO THIS UNIT BEFORE REMOVING THE FUSE OR SERVICING.



WARNING BEFORE CONNECTING/DISCONNECTING ANY INTERNAL ELECTRONIC COMPONENTS OR INTERCONNECTING WIRING BETWEEN ELECTRONIC EQUIPMENT ALWAYS REMOVE POWER AND WAIT AT LEAST THIRTY (30) SECONDS BEFORE ANY CONNECTIONS OR DISCONNECTIONS ARE MADE. FAILURE TO OBSERVE THESE PRECAUTIONS COULD RESULT IN DAMAGE TO OR DESTRUCTION OF THE EQUIPMENT OR BODILY HARM.



CAUTION OBSERVE PRECAUTIONS FOR HANDLING ELECTROSTATIC SENSITIVE DEVICES.

3. INTRODUCTION

3.1. **Overview**

The type FAD-30 Converter Series consists of powerful and economic state-of-the-art instruments for static and dynamic weighing applications plus force and torque measurements.

Each instrument of the series converts the analogue low-level signal from a load cell or a strain gauge sensor to a digital high-resolution and high-accuracy signal and transmits the digital data to an external PLC or PC system. As a unique feature the instruments can switch between unipolar and bipolar input range without affecting the external resolution.

The type FAD-30 Converter Series comprises various instruments for different industrial bus systems:



FAD-30 with **RS485**



FAD-30MB with Modbus RTU



FAD-30PB with Profibus DP



FAD-30PN with Profinet



FAD-30EN with Ethernet TCP/IP



.... 0000 FAD-30CO with CANopen

Figure 3.1 – FAD-30 A/D Converter series instruments



FAD-30EI with EtherNET/IP



FAD-30EC with EtherCAT



FAD-30CC with CC-Link



Powerlink

3.2. Key features and Specifications

| Key Features | FAD-30 | FAD-30MB | FAD-30PB | FAD-30PN | FAD-30EN | FAD-30CO | FAD-30EI | FAD-30EC | FAD-30CC | FAD-30PL |
|---|--------|----------|----------|----------|----------|----------|----------|----------|----------|----------|
| Bipolar signal input in Force and Count modes | Yes | Yes | Yes | Yes | Yes | Yes | Yes | Yes | Yes | Yes |
| 500 to 100 000 counts external resolution at calibrated data | Yes | Yes | Yes | Yes | Yes | Yes | Yes | Yes | Yes | Yes |
| Unipolar 1 million and bipolar 2 million counts is adjusted and filtered to external resolution in count mode | Yes | Yes | Yes | Yes | Yes | Yes | Yes | Yes | Yes | Yes |
| High internal resolution up to 8 million counts | Yes | Yes | Yes | Yes | Yes | Yes | Yes | Yes | Yes | Yes |
| Up to 800 conversions per second | Yes | Yes | Yes | Yes | Yes | Yes | Yes | Yes | Yes | Yes |
| Standard Serial interface RS-232C | Yes | Yes | Yes | Yes | Yes | Yes | Yes | Yes | Yes | Yes |
| Standard Serial interface RS-485A | Yes | Yes | - | - | - | - | - | - | - | - |
| Modbus RTU | - | Yes | - | - | Yes | - | - | - | - | - |
| Modbus TCP | - | - | - | - | Yes | - | - | - | - | - |
| Profibus DP-V1 interface | - | - | Yes | - | - | - | - | - | - | - |
| Profinet interface | - | - | - | Yes | - | - | - | - | - | - |
| Ethernet (Modbus TCP/IP or BSI) interface | - | - | - | - | Yes | - | - | - | - | - |
| CANopen interface | | - | - | - | - | Yes | - | - | - | - |
| EtherNET/IP interface | - | - | - | - | - | - | Yes | - | - | - |
| EtherCAT | - | - | - | - | - | - | - | Yes | - | - |
| CC-Link interface | - | - | - | - | - | - | - | - | Yes | - |
| Powerlink interface | - | - | - | - | - | - | - | - | - | Yes |
| Continuous data output | Yes | Yes | - | - | Yes | - | - | - | - | - |
| BSI data interface | Yes | Yes | - | - | Yes | - | - | - | - | - |
| Bus address selection by setup switch (from 0 to 7) | Yes | Yes | Yes | - | - | Yes | - | - | Yes | Yes |
| Setup by Flintec xFace PC software | Yes | Yes | Yes | Yes | Yes | Yes | Yes | Yes | Yes | Yes |
| Auto-zero tracking and auto-zero at power-up | Yes | Yes | Yes | Yes | Yes | Yes | Yes | Yes | Yes | Yes |
| Motion detection | Yes | Yes | Yes | Yes | Yes | Yes | Yes | Yes | Yes | Yes |
| Zeroing and Taring by bus commands | Yes | Yes | Yes | Yes | Yes | Yes | Yes | Yes | Yes | Yes |
| Adaptive digital filter for fast and stable reading | Yes | Yes | Yes | Yes | Yes | Yes | Yes | Yes | Yes | Yes |
| Up to 6 load cells (350 Ω) or 18 load cells (1100 Ω) | Yes | Yes | Yes | Yes | Yes | Yes | Yes | Yes | Yes | Yes |
| Electronic calibration (eCal) without test weights | Yes | Yes | Yes | Yes | Yes | Yes | Yes | Yes | Yes | Yes |
| Zero and Span calibrations over bus interface | - | Yes |
| Zero adjustment | Yes | Yes | Yes | Yes | Yes | Yes | Yes | Yes | Yes | Yes |
| Span adjustment with test weights | Yes | Yes | Yes | Yes | Yes | Yes | Yes | Yes | Yes | Yes |
| Span adjustment with temporary zeroing for unloaded tanks | Yes | Yes | Yes | Yes | Yes | Yes | Yes | Yes | Yes | Yes |
| Power-on testing with setup switch | Yes | Yes | Yes | Yes | Yes | Yes | Yes | Yes | Yes | Yes |
| 11 to 28 VDC power supply | Yes | Yes | Yes | Yes | Yes | Yes | Yes | Yes | Yes | Yes |

Specifications

| A/D Converter: | | | | |
|---|---|---|--|--|
| A/D converter type: 24 bit Delta-Sigma radiometric with integral analog and digital filters | | | | |
| Analog input range: | 0 mV +18 mV (unipola | ar); - 18 mV +18 mV (bipolar) | | |
| Linearity: | < 0.0015 % FS | | | |
| Temperature coefficient: < 2 ppm/°C | | | | |
| Min. input per vsi | 0.1 µV/d (non approved) | I μV/d (non approved) | | |
| Conversion rate: | Up to 800 measurement values per second | | | |
| Internal resolution: | Up to 8 million counts | | | |
| External resolution | | | | |
| Count mode | | 1 million counts in unipolar range 2 million counts in bipolar range | | |
| Weighing and Force mode | | Up to 100 000 incriments | | |

| Calibration and Weighing Functions: | | | | |
|-------------------------------------|---|--|--|--|
| Calibration: | Electronic calibration without test weights (eCal) or calibration by test weights | | | |
| Digital filter: | 10 step programmable adaptive filter | | | |
| Weighing functions: | Tare, zero, auto zero tracking, motion detection, auto-zero at power-up, save tare at power-off, increased resolution | | | |
| Load cells: | | | | |
| Excitation: | 5 VDC at 581200 Ω, max. 100 mA | | | |
| Number of load cells: | Up to 6 load cells à 350 Ω or 18 load cells à 1100 Ω in parallel | | | |
| Connection: | 4- or 6-wire technique, cable length 250 m/mm ² for 6-wire connection | | | |
| Communication and Setup: | | | | |
| Serial interface RS-232C: | 9600 baud (8,N,1) | | | |
| Other interfaces | Depends on instrument type | | | |
| Response time | < 4 ms (delay after each read or write command) | | | |
| Setup and calibration | By PC software via RS232C, backup data stored on PC | | | |
| Power supply: | | | | |
| DC power supply | 10 28 VDC, < 200 mA, not galvanically isolated | | | |
| Environment and Enclosure: | | | | |
| Operation temperature: | Between -15°C and +55 °C at maximum 85% RH max, non-condensing | | | |
| Enclosure and protection | Polyamide, for DIN-rail mounting, IP20 | | | |

FAD-30 with RS485 interface:

| Communication: | |
|------------------------|---|
| Serial interface RS485 | 1200 to 57600 baud (8N1, 7E1, 7O1), bus capability up to 31 units |
| Communication mode | Continuous or requested |
| Dimensions & weight | 99 x 22.5 x 114.5 mm (L x W x H), weighs approx. 110 g |

FAD-30MB with Modbus RTU interface:

| Communication: | | |
|------------------------|---|--|
| Serial interface RS485 | 1200 to 57600 baud (8N1, 7E1, 7O1), bus capability up to 31 units | |
| Communication mode | Continuous or requested or Modbus RTU | |
| Address range | 131 | |
| Dimensions & weight | 99 x 22.5 x 114.5 mm (L x W x H), weighs approx. 110 g | |

| FAD-30PB with Profibus DP interface: | | |
|--------------------------------------|--|--|
| Communication: | | |
| Profibus DP-V0 + DP-V1 | 9,6 kbit/s to 12 Mbit/s (automatic), galvanically isolated interface | |
| Address range | 1126 | |
| Dimensions & weight | 99 x 45 x 114.5 mm (L x W x H), weighs approx. 150 g | |

| FAD-30PN with Profinet interface: | | | |
|-----------------------------------|--|--|--|
| Communication: | | | |
| Profinet | 100 Mbit/s (full duplex), galvanically isolated interface | | |
| IP settings | DHCP or manual setup over xFace PC software | | |
| Topology | Line, Bus, Star or Tree topology depending on physical media | | |
| Dimensions & weight | 99 x 45 x 114.5 mm (L x W x H), weighs approx. 150 g | | |

FAD-30EN with Ethernet TCP/IP interface:

| Communication: | | |
|---------------------|--|--|
| Ethernet TCP/IP | 10 Mbit/s (half duplex), galvanically isolated interface | |
| IP settings | Manual setup over xFace PC software | |
| Dimensions & weight | 99 x 45 x 114.5 mm (L x W x H), weighs approx. 150 g | |

| FAD-30CO with CANopen interface: | | |
|----------------------------------|--|--|
| Communication: | | |
| CANopen V.2.0 | 10 kbit/s1 Mbit/s (automatic), galvanically isolated interface | |
| Address range | 1126 | |
| Topology | Line with Trunkline, Dropline structure and Termination at both Ends | |
| Dimensions & weight | 45 x 114.5 mm (L x W x H), weighs approx. 150 g | |

| FAD-30EI with EtherNet/IP interface | | | |
|-------------------------------------|--|--|--|
| Communication | Communication | | |
| Data rate | 10 Mbit/s or 100 Mbit/s, full duplex | | |
| EDS file | Generic EDS-file provided | | |
| DLR (Device Level Ring) | Available | | |
| TCP/IP settings | DHCP or manual IP assign over EtherX PC Software. Device identity customization | | |
| Topology | Line, Bus, Star or Tree topology depending on physical media | | |
| Installation | Switched Ethernet transmission with shielded twisted pair cables and RJ-45 connectors. | | |
| Isolation | Galvanically isolated bus electronics | | |
| Response speed | Up to 4 ms. response delay after read/write commands. | | |

| FAD-30EC with EtherCAT interface | | |
|----------------------------------|--|--|
| Communication | | |
| Data rate | 100 Mbit/s, full duplex | |
| ESI file | Generic ESI-file provided | |
| Topology | Line, Tree, Star or Daisy-chain topology depending on physical media | |
| Installation | Switched Ethernet transmission with shielded twisted pair cables and RJ-45 connectors. | |
| Isolation | Galvanically isolated bus electronics | |
| Response speed | Up to 4 ms. response delay after read/write commands. | |

| FAD-30CC with CC-Link interface | | |
|---------------------------------|---|--|
| Communication | | |
| Data rate | 156 kbit/s – 10 Mbit/s (selectable) | |
| Topology | Line with Trunkline, Branch structure and Termination at both Ends. | |
| Installation | 3 wires shielded twisted pair cable. | |
| Max. Stations | Up to 64 stations per network | |
| Isolation | Galvanically isolated bus electronics | |
| Response speed | Up to 4 ms. response delay after read/write commands | |

FAD-30PL with Powerlink interface

| Communication | |
|-----------------|--|
| Data rate | 100 Mbit/s, half duplex |
| Compatibility | Supports POWERLINK V2.0 Communication Profile Specification version 1.2.0 |
| XDD file | XDD-file provided |
| Ring redundancy | Available |
| Topology | 100% free choice of star, tree, ring or daisy chain |
| Installation | Switched Ethernet transmission with shielded twisted pair cables and RJ-45 connectors. |
| Isolation | Galvanically isolated bus electronics |
| Response speed | Up to 4 ms. response delay after read/write commands |

3.3. Housing

FAD-30 instruments come within a polyamide housing sealed to IP20. They are prepared for mounting on NS 37/7 or NS 35/15 standard DIN rails (see drawings).



View A: FAD-30, FAD-30MB

View B: FAD-30PB, FAD-30PN, FAD-30EN, FAD-30CO, FAD-30EI, FAD-30EC, FAD-30CC, FAD-30PL Figure 3.2 – Dimensions

4. INSTALLATION

PRECAUTION: Please read this manual carefully before you install the instrument. If you apply all recommendations in this chapter you will increase the reliability and long-term performance of your system.

4.1. **Recommendations**

4.1.1. Control Cabinet Design

Warning: Please follow the following warnings for designing the control cabinet which will increase the reliability of your system.

The control cabinet should be designed therefor the A/D converters can operate safely. The panel should be placed in a clean area, without getting direct sun light if possible, with a temperature between -15 °C and +55°C, humidity not exceeding 85% non-condensing. All external cables should be installed safely to avoid mechanical damages.

FAD-30 instruments are very low level signal measuring instruments. To avoid electrical noise, the instruments should be separated from equipment that produces electrical noise. Preferably use a metal cabinet against radio frequency interference, to protect against electromagnetic disturbance the cabinet shall be connected to ground. Keep the load cell cable trays separated from others, if possible. If there is noise-generating equipment such as heavy load switches, motor control equipment, inductive loads etc., please be careful against the EMC interference in the cabinet. If possible protect FAD-30 instruments by a Faraday cage or install them in a separate section or install them far away from this kind of equipment. Install parallel reverse diodes to the DC inductive loads like relays, solenoids etc. to minimize voltage peaks on the DC power lines.

4.1.2. Cabling

All cables coming to the control cabinet shall be shielded. Please use separate cable trays for these low signal level cables. Distance from load cell cables, interface cables and DC power supply cables to power line cables shall be 50 cm at minimum.

4.1.3. Mechanical Installation

After designing the control panel and installing DIN rails according to the recommendation in this chapter, place the FAD-30 instruments on the DIN rail. Be sure that the mechanical installation of the instruments is done properly.

4.2. Electrical Connections

Warning: Please always remember that FAD-30 instruments are very low voltage measuring instruments. Your control cabinet design and proper installation increases the reliability and the performance of the instrument. Please do not forget that the instrument must be powered off before inserting or removing any peripheral connector. All required electrical connections should be done as described below.

4.2.1. Power Supply and Grounding

The power supply voltage of the instrument shall be between 12 VDC and 28 VDC. The current consumption of the power supply will be calculated by multiplying 0.2 A and the quantity of instruments. The pin configuration of the 24 V DC power supply connector located at the bottom front of the instrument is shown below in figure 4.1.



Warning: Do not forget to connect the Shield pin to the reference ground.

Figure 4.1 - The pin layout of 24 V DC connector

The quality of the instrument's ground will determine the accuracy and the safety of your measuring system. A proper ground connection is needed to minimize extraneous electrical noise effects on the measurement. A poor ground can result in an unsafe and unstable operation. It is important that the instrument should not share power lines with noise-generating equipment such as heavy load switching, motor control equipments,

inductive loads, etc. If the condition of the power line in the plant is poor, prepare a special power line and grounding. Before interfering the instrument, turn off the power and wait at least for 30 seconds.

4.2.2. Load Cell Connection

To avoid damages, the load cell wiring should be made carefully before energizing the instrument. Load cell connection details are shown below in figure 4.2. In 4-wire installations the sense and excitation pins with the same polarity should be short circuited at the connector side. If you have a junction box in your system, use a 6 wire cable between FAD-30 and the junction box, and short circuit these pins at junction box for better performance.





Figure 4.2 – Load cell connection



4.2.3. RS232 Connection

You can use the serial interface RS232 with the xFace software for configuration and adjustment.



Warning: Connecting the shield to the reference ground will protect your weighing system against EMC disturbances.

4.2.4. RS 485 Connection

RS 485 serial connection is done as indicated below. Line termination resistor (110 ohm) is needed both end of the RS 485 line.



Figure 4.1 - RS 485 serial interface connections

Warning: Connect the shield to the reference ground. *Warning:* Disconnect xFace PC software before starting Modbus-RTU interfacing.

4.2.5. Communication Interface

Please refer to the corresponding chapter:

| FAD-30 (RS485) | see chapter 6.2 |
|------------------------------------|------------------|
| FAD-30MB (Modbus RTU) | see chapter 6.2 |
| FAD-30PB (Profibus) | see chapter 7.2 |
| FAD-30PN (Profinet) | see chapter 8.2 |
| FAD-30EN (Ethernet and Modbus TCP) | see chapter 9.2 |
| FAD-30CO (CANopen) | see chapter 10.2 |
| FAD-30EI (EtherNET/IP) | see chapter 11.2 |
| FAD-30EC (EtherCAT) | see chapter 12.2 |
| FAD-30CC (CC-Link) | see chapter 13.2 |
| FAD-30PL (Powerlink) | see chapter 14.2 |
| | |

4.3. Commissioning

PRECAUTION: Please read this manual carefully before energizing the instrument. Perform the commissioning operation according the procedure given in this chapter. Only trained persons are allowed for cleaning, commissioning, checking and servicing of the instrument. The interference of untrained person may cause some unwanted damages or injuries.

Before energizing the instrument, please make the required mechanical and electrical installations. After power on, you have to setup your FAD-30 instrument before you can start to use the bus interface.

Install the xFace software onto your PC as described in chapter 5 Setup. The xFace software is used for setup, calibration and testing of FAD-30xx instruments.

After you have successfully checked the performance of the instrument with xFace, you can begin to use the instrument in your application.

4.4. Cleaning

Warning: Disconnect the instrument from power source before start cleaning for your safety.

FAD-30 instrument is designed for using in the cabinet. To maintain the instrument, never use harsh abrasive cleaners or solvents. Wipe the instrument with a soft cloth slightly dampened with warm soapy water or with mild detergent.

4.5. Disposal

In conformance with the European Directive 2002/96 EC Waste Electrical and Electronic Equipment (WEEE), this device may not be disposed of with domestic waste. This rule also applies to the non-EU countries, according to their specific regulations. Please dispose of this product in accordance with local regulations at the collecting point specified for electrical and electronic equipment. For your questions, please contact the responsible local authority. Thank you for your attention to environmental protection.

5. SETUP

PRECAUTION: Please read this manual carefully before energizing the instrument. Perform the commissioning according the procedure given in chapter 4.3. Only trained person are allowed for commissioning, checking, cleaning and servicing of the instrument. The interference of untrained person may cause some unwanted damages or injures.

FAD-30 series instruments are setup and calibrated by the xFace software supplied with the instrument. The instruments shall be setup in the sequence described below before you can use the bus interface.

- Install the xFace software onto your PC
- Connect your PC with the instrument over the serial interface (RS232 respective RS485)
- Setup and calibrate the instrument
- Check the performance of the instrument

5.1. Installation of the xFace Software

Please follow following steps to install the xFace software:

- Close all applications on your PC
- Insert the CD that contains the xFace software into the CD-ROM drive or download the software www.flintec.com.
- Double click "Setup.exe" to start the installation. The setup Wizard is displayed.

| £ | xFace Setup | × |
|---|--|---|
| | Welcome to the xFace installation program. |] |
| | Setup cannot install system files or update shared files if they are in use. Before proceeding, we recommend that you close any applications you may be running. | |
| | OK 🔨 Egit Setup | |

• Follow the menus in the setup wizard step by step.



• If the Version Conflict window is displayed, click to "No to All" button.



• After finishing the installation, the Setup Wizard will inform you about the success of the software installation. Click the OK button.

• After closing the Setup Wizard you can start to use the xFace software.

| Typ auswählen | | | |
|---------------|-------------|-------------|------------|
| ○ FAA-2x | • FAD-30 • | FAD-40 | MCS-08 |
| - 🙃 FAA-27 | - FAD-30 | -© FAD-40 | |
| C FAA-28 | -C FAD-30MB | -C FAD-40MB | -© MCS-08M |
| | -C FAD-30PB | -C FAD-40PB | -C MCS-08P |
| | C FAD-30PN | -C FAD-40PN | -C MCS-08P |
| | - FAD-30EN | -C FAD-40EN | C MCS-08E |
| | -C FAD-30CO | -C FAD-40CO | |
| | -C FAD-30EI | -C FAD-40EI | |
| | -C FAD-30EC | -C FAD-40EC | |
| | -C FAD-30CC | -C FAD-40CC | |
| | G FAD-30PL | C FAD-40PL | |
| | | ABBRECHEN | |
| | | AbbRechely | |

| 1 | Analog models |
|---|---|
| 2 | FAD-30 models: Select one of the FAD-30 models and press OK button. |
| 3 | FAD-40 models |
| 4 | MCS-08 models |
| | |

Figure 5.1 - xFace model selector window

5.2. Connection to the xFace Software

The connection between FAD-30 and the xFace software is done via the RS-232C service port for all models. Alternatively, RS-485 can be used for this connection.

After running the xFace software select the FAD-30 model you use (see figure 5.1). Select the PC's communication port within the Connection settings menu in the tools tab (see figure 5.2) and click the connect icon. After the communication between FAD-30 and your PC has successfully started the traffic light of the connect icon turns from red to green.

| Protocol | RS 232C | - |
|----------|-----------|---|
| Com Port | COM4 | - |
| Address | 1 | Ŧ |
| Baudrate | 9600 | Ŧ |
| Settings | 8 - N - 1 | - |

Protocol: Select the setup port of the instrument. FAD-30 and FAD-30MB instruments can be setup over RS-232 or RS-485. Other models can be setup over RS-232C.

Com Port: Select the communication port of the PC

Address: Select the RS-485 address, if RS-485 is selected

Baud rate: Select the RS-485 baud rate, if RS-485 is selected

Setting: Select the RS-485 communication port setting, if RS-485 is selected

Figure 5.2 – xFace Connection Settings

5.3. Setup and Calibration

WARNING: Read this manual carefully before you setup and calibrate the instrument. This will increase the performance of your weighing system by applying proper setup and calibration.



| 6 | Visual Weight Display: Displays the weight, count or force value |
|------|--|
| 7 | Toolbox: Contains shortcuts of some special commands |
| 8 | A/D Converter Parameters: This block allows the user to setup the A/D Converter's parameter related to the operation mode. Refer to chapter 5.3.1 |
| 9 | RS-232C: RS-232C serial port communication settings (not for FAD-30 and FAD-30MB) |
| 10 | RS-485: RS-485 port communication settings. (FAD-30 and FAD-30MB only) |
| (11) | Description: This block provides some clear-text explanations |
| | Read from A/D Converter: Click this button to read the parameter settings from the instrument |
| (12) | Write to A/D Converter: Click this button to save the parameter settings to the instrument |
| 12 | Default: Click this button to load the factory default settings |
| | Clear: Empties the parameter settings |
| | |

Figure 5.3 – FAD-30 Setup Parameters

For entering the parameter values enter the setup tab, adjust the parameter settings and then write this data to the A/D Converter. After changing parameter settings, the instrument always requires a re-calibration.

5.3.1. Scale Parameters

In the setup menu the scale parameters of FAD-30 can be viewed, changed or saved to the instrument. These parameter settings are:

Increased External Resolution

For service purposes this parameter enables the 10 times higher resolution of the weight value than the defined interval in weighing and force mode. Increased resolution must be disabled for use in normal operation (Not available in Count Mode). **Default setting: 'Disable'**.

Digital Filter

Environmental noise like bounding forces, air flow, vibration, motor control instruments etc. may disturb the load cell signal. The selection of proper filter settings determines how quickly the system will react to the load cell signal. Load cell signal digital filtering is done according to this parameter settings. The settings can be changed from 0 (fastest settling) to 9 (slowest settling). **Default setting:** '7'.

Motion Detection

This parameter defines the motion detection window which determines a stable weighing. If motion detection is not required, this parameter can be disabled. The available motion detection window values are:

Weighing and Force Mode:

| Disable | ±0.3e | ± 0.5e (default setting) | ±1e | ± 2e |
|-------------|-------|--------------------------|-----|------|
| Count Mode: | | | | |

| Disable ± 60 ± 100 (default setting) \pm | ± 200 | ± 400 |
|--|-------|-------|
|--|-------|-------|

Power On Zero

This parameter enables automatic zeroing after powering on the instrument. The automatic zeroing is only done if the total zero drift from the calibrated zero signal is in the defined zeroing window. This zeroing window will be defined in the percentage of the scale capacity.

| | Disable (default setting) | ± 2% | ± 10% |
|--|---------------------------|------|-------|
|--|---------------------------|------|-------|

To avoid unwanted zeroing at power on this parameter should be disabled or carefully set up in applications like silo weighing, tank weighing and automatic weighing applications. If the weight is not within the power on zeroing range, the instrument is powered on without zeroing (Not available in Count Mode).

Zeroing Range

Zeroing of the scale is performed if the difference between load cell signal value and unloaded load cell signal value at the calibration is in the selected percentage of the scale capacity. Zeroing can be done by zeroing command when the scale is stable. Zeroing can be done by zeroing command when the scale is stable. The available zeroing ranges in the percentage of the scale capacity are:

| Disable ± 2% (default | setting) ± 20% | ± 40% |
|-----------------------|----------------|-------|
|-----------------------|----------------|-------|

Auto Zero Tracking

AZT automatically re-adjusts the scale to zero for compensating defined small deviations around the center of zero. AZT only works within the defined zeroing range and stops working if this range is left. To avoid unwanted zeroing this parameter should be disabled or carefully set up in applications like silo weighing, tank weighing and automatic weighing applications (Not available in Count Mode). The available AZT window values are;

| Disable (default setting) | ± 0,5e | ±1e | ± 3e |
|---------------------------|--------|-----|------|
| | | | |

Tare

If this function is enabled, the weight is tared when the tare command is received. Additional conditions for taring are positive gross weight and no motion. Multi-taring is possible with FAD-30 series (Not available in Count Mode). **Default setting: 'Enable'**.

Save Tare at Power Off

If this function is enabled, the tare value is stored at power off and the instrument starts up in Net mode at power on (Not available in Count Mode). **Default setting: 'Enable'**.

5.3.2. Serial Interface Setup

Data Format

This parameter defines the serial communication port data format for RS232 respective RS485. The available data formats are:

| Disable: | Port will be disabled. Select "Disable" if this port is not used. |
|-----------------------------------|---|
| Continuous | The data is transmitted continuously (for FAD-30, FAD-30MB, FAD-30EN). Refer to chapter 6.4 for details. |
| BSI (default setting for FAD30)): | Communicates in BSI data format as a slave. Refer to chapter 6.5 for details. |
| Modbus RTU High-Low | Modbus RTU communication (for FAD-30MB and FAD-30EN only). |
| Modbus RTU Low-High | Modbus RTU communication (for FAD-30MB and FAD-30EN only). |

Note: xFace automatically connects to the instrument whatever the data format is. After xFace is disconnected, the instrument returns to operate with the last saved data format. **Warning:** Disable this interface if it is not used to increase the interfacing performance.

Checksum

The checksum can be enabled or disabled within BSI and Continuous output data format. The checksum calculation can be found in the related data format description. Default setting: 'Enable'.

Carriage Return (CR)

Carriage Return can be enabled or disabled within Continuous output data format. Default setting: 'Enable'.

Line Feed (LF)

Line Feed can be enabled or disabled within Continuous output data format. Default setting: 'Enable'.

The RS-485 setup is done by the xFace software as described in this chapter. Select the Setup tab after xFace has established a connection with your instrument. The Setup tab (see figure 5.3) includes all RS-485 settings.

Baud Rate (for RS485 only)

One of the following baudrate will be selected for the RS-485 communication port.

| 1200 | 2400 | 4800 | 9600 (default setting) |
|-------|-------|-------|------------------------|
| 19200 | 38400 | 57600 | |

Data Length and Parity (for RS485 only)

The data length and parity can be selected as 8 None 1 (default), 7 Odd 1 or 7 Even 1.

Address (for RS485 only)

The address range is 01 (default) to 31. If you enter 0, the instrument will operate without address data.

Modbus RTU Setup (for FAD-30MB only)

RS-485 Data Format:'Modbus RTU',RS-485 Data Length & Parity:'8 none 1',RS-485 Address:'01' to '31'

5.3.3. Scale Build and Calibration

Scale build, operation mode selection and scale calibration is performed in the calibration tab of xFace as shown in figure 5.4. Please follow the procedure in the sequence as described in the following chapters.



| 15 | Mode: Here the user selects the operation mode and the polarity. |
|----|---|
| 16 | Write to A/D Converter: Click this button to save the operation mode and polarity to A/D Converter. |
| 17 | Calibration block: This block allows the user to calibrate with test weights. |
| 18 | eCal Calibration: This block allows the user to calibrate without test weights. |
| 19 | Calibration Coefficients: This function allows the user to restore a calibration if the calibration |
| | |



Mode selection

FAD-30 instruments have three operation modes which are:

| Count Mode: | Filtered and normalized ADC count data will be transmitted in this mode. The |
|----------------|--|
| | calibration is performed at the PLC, if any. |
| Weighing Mode: | Unipolar weight data in calibrated weighing unit will be transmitted. This mode is |
| | compatible to OIML R76 and EN 45501. |
| Force Mode: | Bipolar or unipolar force measurement data in calibrated force unit will be transmitted. |

Select the scale operation mode and the polarity. Then click the "Write to A/D Converter" button to save your mode selection. The default calibration of FAD-30 instruments is Count Mode and 10 mV unipolar input signal range. If you select the Count Mode, there is no scale build and instrument calibration. Each FAD-30 instrument is adjusted for high accuracy during the production. The FAD-30 input signal ranges and their external resolutions are shown in Table 5.1.

| Input signal range | Input Signal level | Polarity | External resolution |
|--------------------|--------------------|----------|---------------------|
| 0 to 5 mV | 5 mV | Unipolar | 1 million counts |
| -5 to 5 mV | | Bipolar | 2 million counts |
| 0 to 10 mV | 10 mV | Unipolar | 1 million counts |
| -10 to 10 mV | | Bipolar | 2 million counts |
| 0 to 15 mV | 15 mV | Unipolar | 1 million counts |
| -15 to 15 mV | | Bipolar | 2 million counts |
| 0 to 18 mV | 18 mV | Unipolar | 1 million counts |
| -18 to 18 mV | | Bipolar | 2 million counts |

Table 5.1 - Count Mode, Input Signal Ranges and External Resolution

Select the input signal level and polarity for high external resolution. Write your mode selection to the instrument by clicking "Write to A/D Converter" button. Jump to the chapter 5.4.

Scale Build

The scale capacity, the increment and the unit have to be introduced to the FAD-30 instrument before you can perform a calibration in Weighing or Force mode.

Capacity: To select a new value for the scale capacity, click in the text box.

Use the keyboard to enter a new value or use the drop-down menu.

Increment: Use the drop-down menu to select the increment.

Unit: Select the unit

The scale calibration can be performed by using test weights or by electronic calibration (eCal).

Calibration by Test Weights

This calibration method performs zero and span calibrations using test weights. For accurate calibration the test weight value should not be less than 1/10 of the scale capacity.



Figure 5.5 – Calibration by test weights

Please note that the scale build values should be entered before you start the calibration.

Select "Full Calibration" for performing a complete scale calibration. Click the "Start" button. Unload the scale for performing the zero calibration and click the "Yes" button. The virtual display will show the [WAIT] message during the zero calibration. During the zero calibration the scale must be stable. Approximately 5 seconds later the span calibration window will be displayed. Load the scale and enter the loaded test weight value, then click the "OK" button. The scale must be stable during the span calibration. Approximately 5 seconds later the new calibration settings are saved automatically.

If any error occurs during the calibration an error message warns you. Click the "Yes" button to reload the previous values or click the "No" button to use the new settings.

You can adjust the zero or the span of your scale without performing a full calibration. Additionally the "span calibration to the unloaded scale" feature is another tool of FAD-30 instruments for after-sale services.

Zero Adjustment

If your scale has a residual zero drift you may perform a zero adjustment only. Select "Zero Adjustment" and press the "Start" button. Then the zero-calibration window will be displayed. Unload the scale and click the "OK" button. The [WAIT] message appears on the virtual display during the zero adjustment. Approximately 5 seconds later the zero adjustment will be finalized.

Note: Zero adjustment is also performed over the bus interface. Refer to the data structure of the related bus interface.

Span Adjustment

If your scale has a span drift, you may perform a span adjustment only. After selecting "Span Adjustment" and pressing the "Start" button, enter the test weight value; place the test weights on the scale and press the "Yes" button. The [WAIT] message appears on the virtual display approximately for 5 seconds while the span calibration is being performed. After finalizing the span adjustment, the instrument will save the span coefficients automatically.

Note: Span adjustment is also performed over the bus interface. Refer to data structure of the related bus interface.

Span Adjustment under Load

This feature is being used to perform a span adjustment without unloading the scale. This operation is especially used for the span adjustment for non-empty tanks to make a span adjustment without emptying the tank. After selecting "Span Adjustment under Load" press the "Start" button. The temporary zeroing message appears on the monitor. This means the instrument will determine the existing load as the temporary zero. If the scale is stable press the "Yes" button. The [WAIT] message appears on the virtual display approximately for 5 seconds to determine the temporary zero. Then the span calibration window will be displayed. Load the scale and enter the loaded test weight value, then click the "OK" button. The scale must be stable in this period. Approximately 5 seconds later, the new calibration settings are saved automatically.

Please refer to the chapter 5.4 A/D Converter Performance Test).

Electronic Calibration (eCal)

eCal allows to perform a calibration without using test weights. FAD-30 is adjusted during production for increased eCal accuracy. The calibration will be done based on the scale capacity, the total load cell capacity, the load cell output and the estimated dead load. If the conditions are convenient for zero calibration, you may perform automatic zero adjustment instead of entering an estimated dead load.

| Total Load Cell Capacity : | 20000 kg | |
|----------------------------|-------------|-------------------------------|
| Avarage Load Cell Output : | 2.0052 mV/V | N |
| Estimated Dead Load : | 5490 kg | |
| Read eCal | Write eCal | |
| Indicator | Adjustment | Figure 5.6 – eCal Calibration |

After selecting eCal calibration enter the following values as:

Total Load Cell Capacity: Enter the total load cell capacity in kg as shown in the example below. Example: If the weighing system has 4 pcs 1000 kg load cells, then enter 4000 kg.

Average Load Cell Output: Enter the load cell output in mV/V. If the weighing system has more than one load cell, calculate the mean value of the load cells output as indicated in the certificates of the individual load cells.

Example: If the load cell outputs are LC1: 2.0010, LC2: 1.9998, LC3:1.9986 and LC4:2.0002, the mean value will be LC output = (2.0010 + 1.9998 + 1.9986 + 2.0002) ÷ 4 = 1.9999 mV/V.

Estimated Dead Load: Enter the estimated dead load value of the weighing system in kg. You may perform a zero adjustment in convenient time for an exact dead load compensation.

After pressing "Save eCal Data to Converter" these data will be transferred to the instrument and eCal will be finalized.

If the scale is empty and you want to make an automatic zero adjustment instead of entering an estimated dead load, then press the "eCal with Zero Adjustment" button for starting the zero calibration. The display will show the [WAIT] message during the zero adjustment for approximately 5 seconds. In this period the scale must be unloaded and stable. The eCal calibration coefficients are saved automatically.

5.4. **Performance Test**

The scale performance test should be performed before you install the bus connection. The tests are linearity, repeatability and eccentricity. You can follow the test at the virtual display and/or status tab which show the measurement data, the instrument data and the software version. For convenience keys for Taring, Zeroing and Clear are located in this tab.

5.5. Bus Interface Setup

FAD-30 instruments have a bus interface and these parameters have to be setup before the bus will be connected. Bus communication settings are done in the Gateway tab.

Bus communication parameters and their descriptions can be found in the related instrument chapters.



22 Gateway Information: Gives the user info about the bus interface

- (23) Communication setup: Network parameters
 - Load Defaults: Loads the default values
 Refresh: Reads the settings from the instrument and updates the window
 Write to Converter: Saves and activates the settings to the instrument
 Find on Network: Search

for the instrument on the network

Figure 5.8 – Bus Interface Setup

5.6. Bus Addressing via Setup Switch

The bus addressing of FAD-30 instruments is done by the xFace software (Refer to chapter 5.5). The alternative way for addressing is the setup switch on the front panel for addresses between 0 and 7 for RS-485, Modbus RTU, Profibus and CANopen interfaces. This feature gives you the practical advantage for addressing the instrument up to address 7 without requiring a PC connection.

For addressing via the setup switch, press this switch for 5 seconds. Then the status LEDs indicate the bus address as shown in the table below. If the address is higher than 7 all LEDs are flashing. The address can be changed by pressing the setup switch sequentially. To save and exit, press the setup switch for 5 seconds. To return to normal operation without saving, wait 15 seconds without pressing the switch.



5.7. Back up Settings and Calibration Data

The parameter settings and the calibration coefficients can be saved to a backup file after reading these data from the FAD-30 instrument. This backup file can be re-written to FAD-30 after opening it by xFace. The backup feature gives a service advantage to FAD-30 instruments. We propose to burn these files to CD / DVD and save this backup CD / DVD in the control cabinet additionally to a backup file on your PC.

Important note: The previous parameter settings and calibration coefficients in FAD-30 will get lost after loading a backup to the instrument.

6. SERIAL INTERFACES

6.1. RS 232C Connection

RS 232C port usage and specifications are shown in the table below.

| Usage | Interfacing with PC or PLC, remote display connection, programming via xFace | | | | | |
|---------------------------------------|--|--|--|--|--|--|
| Data formats | Continuous, BSI (<i>Default</i>), *Modbus RTU High-Low, *Modbus RTU Low-High | | | | | |
| Baud rate | 9600 bps | | | | | |
| Length and parity | 8 bit no parity | | | | | |
| Start / Stop bits | 1 start bit and 1 stop bit | | | | | |
| * Available for FAD-30MB and FAD-30EN | | | | | | |
| | | | | | | |

Table 6.1 – RS 232C Serial Interface Specifications

RS 232C serial connection is done with three wires as indicated below in Figure 6.1.



Figure 6.1 - FAD-30 and FAD-30MB serial interface connections

Warning: Connecting the shield to the reference ground will protect your weighing system against EMC disturbances.

6.2. RS 485 Connection

RS 485 port usage and specifications are shown in the table below.

| Usage | Interfacing with PC or PLC, remote display connection, programming via xFace |
|---|---|
| Data formats | Continuous, BSI (<i>Default for FAD-30</i>), *Modbus RTU High-Low (<i>Default for FAD-30MB</i>), *Modbus RTU Low-High |
| Baud rate | 1200 / 2400 / 4800 / 9600 (<i>Default</i>) / 19200 / 38400 / 57600 bps |
| Length and parity | 8 bit no parity (<i>Default</i>), 7 bit even, 7 bit odd |
| Start / Stop bits * Available for FAD-30MB | 1 start bit and 1 stop bit |

Table 6.2 - RS 485 Serial Interface Specifications

RS 485 serial connection is done as indicated below. Line termination resistor (110 ohm) is needed both end of the RS 485 line.



Figure 6.2 - RS 485 serial interface connections

Warning: Connect the shield to the reference ground. *Warning:* Disconnect xFace PC software before starting Modbus-RTU interfacing.

6.3. Interfacing

FAD-30 and FAD-30MB instruments have two serial interface connectors on the front of the instruments: RS-485 and RS-232C serial interface connector.

FAD-30 and FAD-30MB instruments interface with its peripheral in to programmed data structure. The table below describes the data formats for interfacing the peripherals and their application:

| Data Format | Description | Application | Hardware |
|--|--|--|-------------------|
| Continuous | Asynchronous continuous data format. Refer to Section 6.4. | Continuous data transfer to PC or PLC Remote display connection Remote Taring, Zeroing | RS-232C RS-485 |
| BSI | Demand interface on BSI Serial Interface format. Refer to Section 6.5. | Master – Slave data interfacing with PLC or PC. | RS-232C RS-485 |
| Modbus RTU High-Low (only FAD-30MB) | Modbus RTU interfacing. Refer to Section 7.4. | Interfacing with PLC. | RS-232C RS-485 |
| Modbus RTU Low-High (only FAD-30MB) | Modbus RTU interfacing. Refer to Section 7. Fehler! V erweisquelle konnte nicht gefunden werden.4. | Interfacing with PLC. | RS-232C RS-485 |

Table 6.3 - Serial data output interfacing

ATTENTION: Please disable the interface you will not use to increase the performance of the instrument.

6.4. Continuous Output Data Structure (for FAD-30/MB/EN only)

The continuous data output of the instrument will be transmitted in the following data structure at the speed which is determined by the baud rate and the data length. The definition of the continuous data format is described below.

In weighing mode and force mode:

| Status | | | | Indicated | | | | Tare | | | | | | | | | | | |
|--------|-----|-----|-----|-----------|----|----|----|------|----|----|----|----|----|----|----|----|----|----|-----|
| | STX | STA | STB | STC | D5 | D4 | D3 | D2 | D1 | D0 | D5 | D4 | D3 | D2 | D1 | D0 | CR | LF | CHK |
| | | | - | | | | | | | | | | | | | | | | |

In count mode:

| | Status | Count Data | | | | Not used | | | | | | | | | | | | |
|-----|--------|------------|----|----|----|----------|----|----|----|----|----|----|----|----|----|----|----|-----|
| STX | STB | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 | D5 | D4 | D3 | D2 | D1 | D0 | CR | LF | CHK |

The definition of the status bytes STA, STB and STC is described below.

| Definiti | Definition Table for Status A (STA) | | | | | | | | | |
|----------|-------------------------------------|---|---------------|------|---------|----------------|-------|-------|-------|--|
| Bits 0, | 1 and 2 | | | Bits | 3 and 4 | 1 | Bit 5 | Bit 6 | Bit 7 | |
| 0 | 1 | 2 | Decimal point | 3 | 4 | Increment size | | | | |
| 0 | 0 | 0 | XXXXOO | 1 | 0 | X 1 | | | | |
| 1 | 0 | 0 | XXXXXO | 0 | 1 | X 2 | | | | |
| 0 | 1 | 0 | XXXXXX | 1 | 1 | X 5 | s 1 | Š, | | |
| 1 | 1 | 0 | XXXXX.X | | | | 'ay | 'ay | Х | |
| 0 | 0 | 1 | XXXX.XX | | | | | | | |
| 1 | 0 | 1 | XXX.XXX | | | | | | | |
| 0 | 1 | 1 | XX.XXXX | | | | | | | |
| 1 | 1 | 1 | X.XXXXX | | | | | | | |

| Definition Table for Status B | (STB) | |
|-------------------------------|---------------------|-------------------------------|
| Bit 0 | Gross = 0 | Net = 1 |
| Bit 1 | Weight positive = 0 | Weight negative = 1 |
| Bit 2 | No Error = 0 | Error = 1 |
| Bit 3 | Stable = 0 | Unstable = 1 |
| Bit 4 | Always = 1 | |
| Bit 5 | Always = 1 | |
| Bit 6 | Not power on zeroed | Zeroed with power on zero = 1 |
| Bit 7 | x | |

| Definition Table for Status C | (STC) | |
|-------------------------------|----------|--|
| Bit 0 | Always 0 | |
| Bit 1 | Always 0 | |
| Bit 2 | Always 0 | |
| Bit 3 | Always 0 | |
| Bit 4 | Always 1 | |
| Bit 5 | Always 1 | |
| Bit 6 | Always 0 | |
| Bit 7 | х | |

CHK (Checksum) = 0 - (STX + STATUS A + + LF)

Error Messages: UNDER, OVER, A.OUT, L-VOLT, H-VOLT are annunciated in the Indicated or Count Data fields.

Note: Weight data is represented with right alignment, error messages with left alignment.

6.5. BSI Data Structure (for FAD-30/MB only)

Depending on their functionality all new generation Flintec instruments launched on the market support the standardized command set with BSI data structure. This easy data format gives a reliable and fast interface for communicating with PLC or PC for process control or transactional applications. You can expand your system with additional scales from Flintec without having to change your application program base.

General Rules:

- 1. Commands are only in CAPITAL letters
- 2. CHK (2 ASCII char) can be enabled or disabled from both command and response.
- 3. Weight data is 8-byte with dot and non-significant zeros on the left.
- 4. Address (2 ASCII char) will be located in the structure if not 00.

Command format:

A general description of the command is the following: [ADR][COMMAND][CHK][CR][LF]

Response format with weight / force or count data A general description of the response is the following: [ADR][COMMAND][STATUS][SIGN][WEIGHT/FORCE/COUNT][CHK][CR][LF]

Response format without weight / force or count data [ADR][COMMAND][STATUS][CHK][CR][LF]

Command Table:

| А | Read all weight data immediately |
|---|---|
| В | Read Gross weight value immediately |
| С | Clear the tare memory |
| D | Read Count value immediately |
| 1 | Read current (indicated) weight value immediately |
| Р | Print: Read the current stable weight value |
| S | Read Status |
| Т | Tare |
| Х | Read current weight value in increased resolution immediately |
| Z | Zero |

Status Table:

| А | Acknowledged, the command is operated successfully |
|---|--|
| D | Unstable weight |
| E | Errors except of H, L, O, +, - |
| Н | High voltage detected |
| 1 | The weight is in range |
| L | Low voltage detected |
| Ν | Not acknowledged, the command couldn't be operated |
| 0 | ADC out |
| S | Stable weight |
| Х | Syntax error (received command not recognized) |
| + | Overload |
| - | Underload |

Note: CHK, CR and LF will not be shown in the below data format descriptions in this chapter.

Commands and Responses

| Α | Read all | weight data | | | | | | | |
|-----------|-------------------------|--|---|--|--|--|--|--|--|
| Command: | [ADR][A] | | | | | | | | |
| Response: | [ADR][A][STA | TUS][SIGN][NET W] | [SIGN][TARE W][SIGN][GROSS W] | | | | | | |
| Example: | | | | | | | | | |
| | Command : | 01A | | | | | | | |
| | Response : | 01AS+000123.4+0 | 000111.1+000234.5 | | | | | | |
| | | 01AD+000123.4+(| 000111.1+000234.5 | | | | | | |
| 0 | T I | 01AO | (ADC out error) | | | | | | |
| Comments: | I ne response | is net, tare and gros | s weight values or error status. All weight data will be | | | | | | |
| | transmitted in | imediately after recei | ving the command. | | | | | | |
| B | Read Gr | oss weight | | | | | | | |
| Command: | | | | | | | | | |
| Response: | [ADR][B][STA | TUSIISIGNIIWEIGH | T VALUE1 | | | | | | |
| Example: | [, [] [] [] [] [] [] [] | | | | | | | | |
| | Command: | 01B | | | | | | | |
| | Response: | 01BS+000123.4 | (gross weight is stable and 123.4) | | | | | | |
| | · | 01BD+000123.4 | (gross weight is unstable and 123.4) | | | | | | |
| | | 01B- | (under load) | | | | | | |
| Comments: | The response | is the gross weight w | value (stable or unstable) or error status. Gross weight data | | | | | | |
| | will be transm | will be transmitted immediately after receiving command. | | | | | | | |
| | | | | | | | | | |
| | Clear the | e tare memory | | | | | | | |
| Command: | | (Cleared and the s | ando in grano modo) | | | | | | |
| Response: | | (Cleared and the s | cale is in gross mode) | | | | | | |
| Commonto: | | | in weighing or force mode and always X in count mode | | | | | | |
| Comments. | The response | status is always Ack | | | | | | | |
| D | Read Co | ount value immediat | elv | | | | | | |
| Command: | [ADR][D] | | | | | | | | |
| Response: | [ADR][D][STA | TUS][SIGN][COUNT | VALUE] | | | | | | |
| Example: | | | - | | | | | | |
| | Command: | 01D | | | | | | | |
| | Response: | 01DD+00123400 | | | | | | | |
| | | 01DO | (ADC out error) | | | | | | |
| | | 01DX | (Not in count mode) | | | | | | |
| Comments: | Count value v | vill be sent immediate | ly. | | | | | | |
| | Deeding | die ete d weight | | | | | | | |
| Commond: | | licated weight | | | | | | | |
| Response: | | TUSISIGNIWEIGHT | ναιμει | | | | | | |
| Example: | | | VALUE] | | | | | | |
| Example. | Command. | 011 | | | | | | | |
| | Response: | 01IS+000123.4 | (weight is stable and 123.4) | | | | | | |
| | | 01ID+000123.4 | (weight is unstable and 123.4) | | | | | | |
| | | 01 + | (overload) | | | | | | |
| Comments: | The response | is the indicated weig | ht value (stable or unstable). It will be transmitted | | | | | | |
| | immediately a | after receiving the con | nmand. The weight value may be in gross or net. | | | | | | |
| | | | | | | | | | |
| Р | Print :Re | ad the stable weigh | t | | | | | | |
| Command: | [ADR][P] | | | | | | | | |
| Response: | [ADR][P][STA | TUSJSIGNJWEIGH | [VALUE] | | | | | | |
| Example: | 0 | 040 | | | | | | | |
| | Command: | | (weight is stable and 102.4) ar | | | | | | |
| | Response: | 01P3+000123.4 | (weight is stable and 123.4) Of (could not print) | | | | | | |
| Comments | Checks status | s and it must he stahl | e Else Nack status will be sent. There is no time period for | | | | | | |
| | stability check | king. Status can be Stabl | table or Nack. | | | | | | |

| S | Read Status | | | | | |
|---|---|--|--|--|--|--|
| Command: Response: Example: | [ADR][S] [ADR][S][STATUS-1][STATUS-2][STATUS-3] | | | | | |
| | Command: 01S Response: 01SSGI (Stable, Gross, In Range) 01SDGL (Unstable, Gross, Low voltage error) | | | | | |
| Comments: | The response includes 3 status information. STATUS-1 can be Stable or Unstable. STATUS-2 can be Gross or Net. | | | | | |
| | STATUS-3 can be 'in range', 'out of range', 'low voltage' or 'high voltage'. | | | | | |
| Т | Tare | | | | | |
| Command: | [ADR][T] | | | | | |
| Response: | [ADR][T][A] (Taring is done successfully, and scale is in net) [ADR][T][N] (Taring could not be executed) [ADR][T][X] (Taring is disabled, or instrument is in count mode) | | | | | |
| Comments: | The tare value will be overwritten by the new tare weight value. The status must be stable | | | | | |
| | within 2 seconds delay time. If so, Ack will be sent. Otherwise Nack will be sent. | | | | | |
| X | Read weight value in increased resolution | | | | | |
| Command: Response: Example: | [ADR][X] [ADR][X][STATUS][SIGN][WEIGHT VALUE] | | | | | |
| | Command: 01X | | | | | |
| | Response: 01XS+00123.41 (weight is stable and 123.41) or 01XD+00123.41 (weight is unstable and 123.41) or 01XE (Error) | | | | | |
| Comments: | The response includes the weight data with the increment divided by 10. | | | | | |
| Ζ | Zero | | | | | |
| Command: | [ADR][Z] | | | | | |
| Response: | [ADR][Z][A] (Zeroed) [ADR][Z][N] (Zeroing could not be operated) [ADR][Z][X] (Zeroing is disabled) | | | | | |
| Comments: | The Zero command does not work in net weighing mode. The Weight or Count must be within the zeroing range for all operating modes. The status must be stable within 2 seconds delay time. If so, Ack will be sent. Otherwise Nack will be sent. | | | | | |
| CHK will be tran Checksum = 0 - | nsmitted as two ASCII characters calculated with the checksum formula: - (SUM of all response data before CHK) | | | | | |
| Example: Read | I stable current weight data | | | | | |
| BSI Examples: | (CHK is enabled and instrument address is 01) | | | | | |
| Command: 01P | [CHK][CR][LF] | | | | | |
| Checksum = 0 - CHK = Char '4' | Checksum = 0 − (0x30 + 0x31 + 0x50) = 0 − 0XB1 = 0x4F CHK = Char '4' and 'F' | | | | | |
| Response: 01P | S+000123.4[CHK][CR][LF] | | | | | |
| Checksum = 0 - 0x34) = 0 - 0x0 CHK = Char '4' | - (0x30 + 0x31 + 0x50 + 0x53 + 0x2B + 0x30 + 0x30 + 0x30 + 0x31+ 0x32 + 0x33 + 0x2E + 2B7 = 0x49: and Char '9' | | | | | |

7. FAD-30 / FAD-30MB – WITH RS-485 INTERFACE

FAD-30 and FAD-30MB instruments are state-of-the-art strain gauge load cell signal digitizers with RS-485 interface. These instruments are used for any type of process weighing and force measurement including tank and silo weighing, dynamic weighing, check weighing, filling, tension /compression force measurement etc.

7.1. Front View

There are 3 status LEDs on the front panel which indicate the operational instrument status.

The setup switch on front panel of the instrument is used for RS-485 addressing without PC (Refer to chapter 5.6) and for diagnostics (Refer to page 68).

When the error LED is ON, the other two LED indicate the error type (Refer to page 67).

Load cell connection, power supply and serial interface terminals are located at the front of the DIN rail mount instrument (See figure 6.1).





The meanings of these LEDs in operation are described below.

| LED | | Operational Mode | | | | | |
|--------|-------------------|--|--|--|--|--|--|
| Symbol | Name | Weight / Force | Count | | | | |
| Ι | Stable | Stable Unstable | Off for 0.3 seconds in 2 seconds period (No stable indication) | | | | |
| →0← | Center of Zero | In the center of zero range (-0.25 e < w < 0.25 e) Out of center of zero range | Always off (No center of zero indication) | | | | |
| Err | Error (*) | ADC conversion error Digital processing error No error | ADC conversion error Digital processing error No error | | | | |

Off On * Flashing Off for 0.3 seconds

(*) : Refer to the error table page 67.

Table 6.1 – Status LEDs

7.2. Electrical Connections

RS-232 and RS-485 connections are shown in figure 6.2.





RS-232C Serial Interface

| Use | Interfacing with PC or PLC, setup via xFace |
|-------------------|---|
| Data format | Continuous, BSI (Default) |
| Baud rate | 9600 bps |
| Length and parity | 8 bit, no parity |
| Start / Stop bits | 1 start bit and 1stop bit |

RS-485 Serial Interface

| Disable | No data will be transmitted. Select disable if this port is not used. |
|---------------------|---|
| Continuous | The data is transmitted continuously. |
| BSI | Communicates in BSI data format as a slave. |
| Modbus RTU High-Low | Modbus RTU communication. (only FAD-30MB) |
| Modbus RTU Low-High | Modbus RTU communication. (only FAD-30MB) |

Warning: Connect the shield to the reference ground.

Warning: Disconnect xFace PC software for Modbus-RTU interfacing

7.3. Interfacing

FAD-30 and FAD-30MB instruments have two serial interface connectors on the front of the instrument: RS-232 and RS-485. The table below describes the data format for interfacing the peripherals and their application:

| Data Format | Description | Application | Hardware |
|---|---|--|-------------------|
| Continuous | Asynchronous continuous output. Refer to chapter 6.4 | Continuous data transfer to PC or PLC Remote display connection Remote Taring, Zeroing | RS-232C RS-485 |
| BSI | Demand interface on BSI Serial Interface format. Refer to chapter 6.5 | Master – Slave data interfacing with PLC or PC. | RS-232C RS-485 |
| Modbus RTU High-Low (FAD-30MB only) | Modbus RTU interfacing. Refer to chapter 7.4 | Interfacing with PLC. | RS-485 |
| Modbus RTU Low-High (FAD-30MB only) | Modbus RTU interfacing. Refer to chapter 7.4. | Interfacing with PLC. | RS-232C RS-485 |

Table 6.1 – Data output interfacing

Attention: Please disable the interface if not used to increase the performance of the instrument.

7.4. Modbus RTU Setup (for FAD-30MB only)

If the FAD-30MB instrument is setup for Modbus, it can be used as a Modbus RTU slave in a RS-485 communication network. Function codes '0x03' and '0x10' are supported. For RS-485 setup please refer to chapter 5.3.2, for the Modbus data structure please refer to chapter 7.4.

Modbus Data Structure (for FAD-30MB + FAD-30EN only)

Modbus RTU High-Low: In two-word registers, the data is stored to the registers in big-endian format. Least significant word is stored to the highest register address; and most significant word is stored to the lowest register address.

Modbus RTU Low-High: In two-word registers, the data is stored to the registers in little-endian format. Least significant word is stored to the lowest register address; and most significant word is stored to the highest register address.

| Address | R/W | Word | Command | Definiti | ion | | | | |
|---------|-------|------|-----------------------------|---|-----------|--|-----------------------------|----------------------------|---------------------------|
| 40001 | R | 2 | Weight / Force / Count Data | | | | | | |
| | | | | D0 | 0 – S | Syster | n Ready | 1 – 5 | System Busy |
| | | | | D1 | 0 – E | rror (| ref. B13-15) | 1 – [| Data ok |
| | | | | D2 | 0 – V | Veigh | t Stable | 1 – \ | Neight unstable |
| | | | | D3 | 0 – 0 | Gross | Mode | 1 – 1 | Net mode |
| | | | | D4 | Not l | Jsed | | | |
| | | | | D5 | 0 - V | Veigh | t / Force | 1 – 0 | Count Mode |
| | | | | D6-D11 | | | | Not | Used |
| 40003 | R | 1 | Status | D12 | 0 – C | Out of | zero range | 1 – \ | Veight is in zero range |
| | | | | | | | | 0 | No Errors |
| | | | | | | | | 1 | ADC out of range |
| | | | | D13 | | | | 2 | ADC over range |
| | | | | D14 | Error | Cod | e | 3 | ADC under range |
| | | | | D15 | | | | 4 | System error |
| | | | | | | | | 5 | In setup mode |
| | | | | | | | | 6 | Low/High voltage det. |
| 40004 | R | 2 | Tare weight | | | | | | |
| 40006 | R | 2 | Gross weight | | | | | | |
| 40008 | R | 1 | Status | Motion, | Net n | node, | Data ok, (ima | age o | f register 40003) |
| | | 1 | Control | 0 | 0 None | | | | |
| 40009 | R/W | | | 1 Zero | | | | | |
| | | | | 2 Tare | | | | | |
| | | | | 3 | Clea | r | | | |
| | R/W | 1 | | U None | | | | | |
| 40010 | | | Calibration | Adjust Zero Calibration Adjust Span Calibration (First load calibration weight on scale and load 40011 with span test weight value) | | | o Calibration | t lood collibration waight | |
| | | | | | | | | | |
| 40011 | D/M | 2 | Span Calibration V | | onso | | 1000 4001 | i wiu | i span test weight value) |
| 40011 | K/ VV | 2 | Spart Calibration | | 7 | 1 | Poody for or | librat | ion |
| | | | | DU D7 Calibration | | 3 | Zero calibration in process | | |
| | | | | Process | 1011 S | 1 | Span calibra | tion i | |
| | | | | | 5 | 9 | Error (Refer | | |
| | | | | Olalus | | 5 | Calibration T | Timeo | |
| | | | | | | - Restart cali | ibratio | on | |
| | | | | | ADC Error | | | | |
| | | | | | | 2 - Re-energize | e the | instrument | |
| | R | 1 | Calibration Status | | | | in. ch | ange the board. | |
| 40013 | | | | | | Instrument | Instrument c | anno | t be calibrated |
| | | | | D8 D | 15 | 3 | - Check load | d cell o | cable |
| | | | | Calibra | tion | | - Re-energiz | e the | instrument |
| | | | | Errors | | 34 Instrument c - Load cell s | anno | t be calibrated | |
| | | | | | | | ignal | is very low or too high | |
| | | | | | | Calibration | Calibration E | Error | |
| | | | | | | 35 - Calibration - Increase ca - Check load | - Calibration | test v | weight is not enough |
| | | | | | | | - Increase ca | alibrat | tion weight value (40011) |
| | | | | | | | d cell (| connections | |

| | | | | | 37 Scale unstable - Wait until scale become stable - Check grounding wiring |
|-------|------|----|----------------------------|---|---|
| | | | | 0 | Count Mode Unipolar |
| | | | | 1 | Count Mode Bipolar |
| 40014 | R/W | 1 | Operation Mode | 2 | Force Mode Unipolar |
| | | | Selector | 3 | Force Mode Bipolar |
| | | | | 4 | Weight Mode Unipolar |
| | | | | 0 | 5 mV |
| 10015 | DAA | 1 | mV operation | 1 | 10 mV |
| 40015 | r/vv | 1 | in Count Mode | 2 | 15 mV |
| | | | | 3 | 18 mV |
| | | | | 0 | Fast |
| | | | | 1 | |
| | | | | 2 | |
| | | | | 3 | |
| 10016 | R/W | 1 | Digital filters | 4 | |
| 40010 | | | | 5 | Medium |
| | | | | 6 | |
| | | | | 7 | Default |
| | | | | 8 | |
| | | | | 9 | Slow |
| 40017 | R | 17 | Not used | | |
| 40034 | R | 1 | Voltage of Power Supply | Voltage of power supply is indicated with 0.1V, e.g. 23.4VDC is indicated as interger 234incriments | |

EXPLANATION

Attention: For hardware connection details, please refer to the related hardware descriptions in this manual.

In the two word registers the data is stored to the registers in big-endian format. The least significant word is stored to the highest register address; and the most significant word is stored to the lowest register address. Please find Modbus information in the web site of <u>http://www.modbus.org</u>

Exception codes:

- 1: Function code is not supported.
- 2: Out of address range
- 3: Invalid value or wrong byte number
- 4: Operation error

Examples:

Performing Read and Write operations according to hex system with the instrument set to address "0x01". Request weight data: 01.03.00.00.00.02.C4.0B

| | 01,00,00,00,00,02,04,00 |
|---|--|
| Answer of requested weight: | 01,03,04,00,01,86,A0,38,4A |
| Weight is 100000 | |
| Request status data: | 01,03,00,02,00,01,25,CA |
| Taring: | 01,10,00,08,00,01,02,00,02,26,D9 |
| Request tare data: | 01,03,00,03,00,02,34,0B |
| Answer of requested tare: | 01,03,04,00,00,27,10,E0,0F |
| Tare is 10000 | |
| Weight Mode Selection: | 01,10,00,0D,00,01,02,00,04,A6,8E |
| Count in Unipolar Mode Selection: | 01,10,00,0D,00,01,02,00,00,A7,4D |
| 5 mV Input signal range selection: | 01,10,00,0E,00,01,02,00,00,A7,7E |
| Load Medium (5) to Digital filter: | 01,10,00,0F,00,01,02,00,05,66,AC |
| Request Calibration Status: | 01,03,00,0C,00,01,44,09 |
| Answer of requested Calibration Status: | 01,03,02,00,01,79,84 |
| Instrument is ready for calibration | |
| Zero Calibration Command: | 01,10,00,08,00,01,02,00,01,66,D8 |
| Span Calibration with Span Value 50000: | 01,10,00,09,00,03,06,00,DC,00,00,C3,50,B7,B0 |
| | |

8. FAD-30PB – WITH PROFIBUS INTERFACE

FAD-30PB instruments are state-of-the-art strain gauge load cell signal digitizers with Profibus DP interface. The **GSD** file is available on <u>www.flintec.com</u>.

8.1. Front View

There are 5 status LEDs on the front panel which indicate the operational instrument status (Refer to table 7.1).and the Profibus status. The setup switch on front panel of the instrument is used for Profibus addressing without PC (Refer to chapter 5.6) and for diagnostics (Refer to page 68).

When the error LED is ON, the other two LED indicate the error type (Refer to page 67).

Load cell connection, Profibus connection, power supply and serial interface terminals are located at the front of the DIN rail mount instrument (See figure 7.1).



Figure 7.1 - Front view

The meanings of these LEDs in operation are described below.

| LED | | Operational Mode | | |
|-------------|-------------------|--|--|--|
| Symbol | Name | Weight / Force | Count | |
| | Stable | Stable Unstable | Off for 0.3 seconds in 2 seconds period (No stable indication) | |
| →0 ← | Center of Zero | in the center of zero range (-0.25 e < w < 0.25 e) Out of center of zero range | Always off (No center of zero indication) | |
| Err | Error (*) | ADC conversion error Digital processing error No error | ADC conversion error Digital processing error No error | |

Off • On * Flashing • Off for 0.3 seconds

(*) : Refer to the error table page 67.

Table 7.1 – Status LEDs

ST Status LED

| State | Indication | Comment |
|----------------|--|--|
| Off | No power or not initialized | No power or Profibus module is in initializing |
| Green | Initialized | |
| Flashing Green | Initialized, diagnostic event(s) present | Diagnostic is active |
| Red | Exception error | There is an exception error |

OP Operation Mode LED

| State | Indication | Comment |
|-------------------|------------------------------|-------------------------------|
| Off | Not on-line / No power | Check power and cable |
| Green | On-line, data exchange | - |
| Flashing Green | On-line, clear | - |
| Flashing Red (2x) | PROFIBUS configuration error | Check GSD file configuration. |

8.2. Electrical Connections

For RS-232C connection refer to chapter 6.1.

PROFIBUS Connector (DB9F)

| Pin | Signal | Description |
|---------|----------------|----------------------------------|
| 1 | - | - |
| 2 | - | - |
| 3 | B Line | Positive RxD / TxD, RS-485 level |
| 4 | RTS | Request to send |
| 5 | GND Bus | Ground (isolated) |
| 6 | +5V Bus output | +5V termination power (isolated) |
| 7 | - | - |
| 8 | A Line | Negative RxD / TxD, RS-485 level |
| 9 | - | - |
| Housing | Cable shield | Ground |





Profibus-DP Interface

| Use | Interfacing with PC or PLC |
|-------------|---|
| Data format | Profibus |
| Baud rate | Automatically detected and supported baud rates are 9.6 kbps, 19.2 kbps, 45.45 kbps, 93.75 kbps, 187.5 kbps, 500 kbps, 1.5Mbps, 3 Mbps, 6 Mbps and 12 Mbps. No 'baud rate' instance exists. |

Warning: Connect the shield to the reference ground or shield pin of the power connector. **Warning:** Disconnect xFace PC software for Profibus interfacing.

8.3. Profibus Setup and GSD /GSDML configuration

The Profibus setup is done by xFace software as described in this chapter. Select the Gateway tab after connecting xFace to the instrument. You will see the Profibus parameters in this tab.

There is only one setup parameter for Profibus network.

| Profibus Rack Address | The address range is 1 (default setting) to 126 |
|-----------------------|---|
|-----------------------|---|

Hardware Configuration Hint

To install the FAD-30PB or FAD-30PN into the PLC Hardware Configuration use the GSD file memory parts to create **exactly** the following memory structure:

| GSD / GSDML Configuration | Descriptio | n |
|------------------------------|-----------------------|------------------------------|
| Input 2 words | 1 st Dword | (Not used) |
| Output 2 words | 1 st Dword | (Not used) |
| Input 2 words | 2 nd Dword | (FAD-30 Output to PLC Input) |
| Input 2 words | 3 rd Dword | (FAD-30 Output to PLC Input) |
| Output 2 words | 2 nd Dword | (PLC Output to FAD-30 Input) |
| Output 2 words | 3 rd Dword | (PLC Output to FAD-30 Input) |



8.4. Profibus Data Structure (for FAD-30PB only)

Please refer to chapter 16 "Data Structure for ... ".

9. FAD-30PN – WITH PROFINET INTERFACE

FAD-30PN instruments are state-of-the-art strain gauge load cell signal digitizers with Profinet interface. The **GSDML** file is available on <u>www.flintec.com</u>.

9.1. Front View

There are 4 status LEDs on the front panel which indicate the operational instrument status and the Profinet status. The setup switch on front panel of the instrument is used for Profinet addressing without PC (Refer to chapter 5.6) and for diagnostics (Refer to page 68).

When the error LED is ON, the other two LED indicate the error type (Refer to page 67).

Load cell connection, Profinet connection, power supply and serial interface terminals are located at the front of the DIN rail mount instrument (See figure 8.1).



The meanings of these LEDs in operation are described below.

| LED | | Operational Mode | | | |
|-------------|-------------------|--|--|--|--|
| Symbol | Name | Weight / Force | Count | | |
| | Stable | Stable Unstable | Off for 0.3 seconds in 2 seconds period (No stable indication) | | |
| →0 ← | Center of Zero | in the center of zero range (-0.25 e < w < 0.25 e) Out of center of zero range | Always off (No center of zero indication) | | |
| Err | Error (*) | ADC conversion error Digital processing error No error | ADC conversion error Digital processing error No error | | |
| O Off | 🛡 On 🗱 | Flashing 0 Off for 0.3 seconds | | | |

(*) : Refer to the error table page 67.

Table 8.1 – Status LEDs

MS Module Status LED

| LED State | Description | Comment |
|------------------|--|---|
| Off | No power or not initialized | No power or Profinet module is in initialization state |
| Green | Initialized | |
| Green, 1 flash | Initialized, diagnostic event(s) present | Diagnostic is active |
| Green, 2 flashes | Blink | Used by engineering tools to identify the node on the network |
| Red | Exception error | There is an exception error |
| Red, 1 flash | Configuration error | Check EDS configuration |
| Red, 2 flashes | IP address error | IP address not set |
| Red, 3 flashes | Station name error | Station name not set |
| Red, 4 flashes | Internal module error | Re-energize the instrument. |

LINK/Activity LED

| LED State | Description | Comment | |
|------------------|-------------|-----------------------------------|--|
| Off | No Link | No link, no communication present | |
| Green | Link | Ethernet link established, | |
| | LIIK | no communication present | |
| Croop flickoring | Activity | Ethernet link established, | |
| Green, nickening | ACTIVITY | communication present | |

NS Network Status LED

| LED State | Description | Comment |
|-----------------|----------------------|-----------------------|
| Off | Not online /No power | Check power and cable |
| Green | On-line (RUN) | - |
| Green, flashing | On-line (STOP) | - |

9.2. Electrical Connections

For RS-232C connection refer to chapter 6.1.



Figure 8.2 – FAD-30PN interface connections

PROFINET Connector pin configuration (RJ45)

| Pin | Signal | DIR | Description |
|-----|----------|-----|---------------------------------------|
| 1 | TX+ | Out | Differential Ethernet transmit data + |
| 2 | TX- | Out | Differential Ethernet transmit data - |
| 3 | RX+ | In | Differential Ethernet receive data + |
| 6 | RX- | In | Differential Ethernet receive data – |
| 4 | Not used | | Terminated |
| 5 | Not used | | Terminated |
| 7 | Not used | | Terminated |
| 8 | Not used | | Terminated |
| | Shield | | Chassis ground |

The HUB connection cabling will be a direct connection as shown below:



The PC connection cabling will be done via cross cable as shown below. IP address blocks and gateway address of FAD-30PN and PC should be the same in cross connection.



Warning: Connect the shield to the reference ground or the shield pin of the power connector. **Warning:** Disconnect xFace PC software for Profinet interfacing. **Attention:** Please disable the interface you will not use to increase the performance of the instrument.

9.3. Profinet Setup and GSDML configuration

The Profinet setup should be done by xFace software as described in this chapter. Select the Gateway tab after connecting xFace to the instrument. You will see the Profinet parameters in this tab.

There are 7 setup parameters for Profinet network.

| DHCP | Dynamic Host Configuration Protocol automates network parameters if it is enabled. Default is 'Disable'. |
|-----------------|---|
| IP Address | If DHCP is disabled, define IP address manually. Default is '192.168.16.250' |
| Subnet Mask | If DHCP is disabled, define subnet mask manually. Default is '255.255.255.0'. |
| Default Gateway | If DHCP is disabled, define default gateway manually. Default is '192.168.16.254'. |
| Primary DNS | If DHCP is disabled, define primary DNS manually. Default is '208.67.222.222'. |
| Secondary DNS | If DHCP is disabled, define secondary DNS manually. Default is '208.67.220.220'. |
| Host Name | Enter a unique host name to the instrument. Default is ' ' |

For Profinet GSDML Parameter please refer to chapter 8.3.

Click on the button "Find on LAN" in section "Gateway".

"EtherX" will automatically be started



All connected FAD-30PN or EN devices will be listed.

Double click on the device you want to change the parameters.

A new window appears. The network parameters can be changed.

After the change the password will be required. The default **password is "123456**"

The status of the storage "OK" will be displayed, as shown below

9.4. **Profinet Data Structure**

To install FAD-30PN into the PLC Hardware Configuration use the **GSDML** file memory parts to create **exactly** the following memory structure:

Please refer to chapter 16 "Data Structure for ... ".

Attention: Different versions of Profinet and their GSDM files.

until June 2016



GSDML-V2.2-HMS-ABCC-PRT-20100329.xml

since July 2016



GSDML-V2.3-HMS-ABCC-PRT2P-20140703.xml

10. FAD-30EN – WITH ETHERNET INTERFACE

FAD-30EN instruments are state-of-the-art strain gauge load cell signal digitizers with Ethernet interface.

10.1. Front View

There are 3 status LEDs on the front panel which indicate the operational instrument status. The setup switch on front panel of the instrument is used for diagnostics (Refer to page 68) When the error LED is ON, the other two LED indicate the error type (Refer to page 67). Load cell connection, Ethernet, power supply and serial interface terminals are located at the front of the DIN rail mount instrument (See figure 9.1).



Figure 9.1 - Front view

The meanings of these LEDs in operation are described below.

| LED Operational Mode | | | | |
|----------------------|-------------------|--|--|--|
| Symbol | Name | Weight / Force | Count | |
| | Stable | Stable Unstable | Off for 0.3 seconds in 2 seconds period (No stable indication) | |
| →0 ← | Center of Zero | in the center of zero range (-0.25 e < w < 0.25 e) Out of center of zero range | Always off (No center of zero indication) | |
| Err | Error (*) | ADC conversion error Digital processing error No error | ADC conversion error Digital processing error No error | |

| Ο | Off | | On | * | Flashing | 0 | Off for 0.3 seconds |
|---|-----|--|----|---|----------|---|---------------------|
|---|-----|--|----|---|----------|---|---------------------|

(*) : Refer to the error table page 67.

Table 9.1 – Status LEDs

10.2. Electrical Connections

Ethernet Connector (RJ45)

| Pin | Signal | DIR | Description |
|-----|----------|-----|---------------------------------------|
| 1 | TX+ | Out | Differential Ethernet transmit data + |
| 2 | TX- | Out | Differential Ethernet transmit data – |
| 3 | RX+ | In | Differential Ethernet receive data + |
| 6 | RX- | In | Differential Ethernet receive data - |
| 4 | Not used | | Terminated |
| 5 | Not used | | Terminated |
| 7 | Not used | | Terminated |
| 8 | Not used | | Terminated |
| | Shield | | Chassis ground |

The HUB connection cabling will be a direct connection as shown below:



Figure 9.2 – HUB connection

The PC connection cabling will be done via cross cable as shown below:



Figure 9.3 – Direct PC connection with cross cable

FAD-30EN interface connections are shown below:



Figure 9.4 - FAD-30EN interface connections

Ethernet Interface

| Usage | Interfacing with PC or PLC, |
|--------------|---|
| Data formats | Continuous, BSI, Modbus TCP/IP High-Low (<i>Default</i>), Modbus TCP/IP Low-High |
| Data rate | The Ethernet interface operates at 10Mbit, half duplex |

Warning: Connect the shield to the reference ground or shield pin of the power connector. **Warning:** Disconnect xFace PC software for Ethernet interfacing.

10.3. Ethernet Setup

The Ethernet setup is done by xFace software as described in this chapter. Select the Gateway tab after connecting xFace to the instrument. You will see the Ethernet parameters in this tab.

Data Format

| Disable | No data will be transmitted. Select disable if this port is not used. | | |
|----------------------------|---|--|--|
| Continuous | The data is transmitted continuously. Refer to Section 6.4 for details. | | |
| BSI | Communicates in BSI data format as a slave. Refer to Section 6.5 for details. | | |
| Modbus TCP/IP High- Low | Madhua TCD/ID communication, Defer to 'Section 7.4 for dataile | | |
| Modbus TCP/IP Low- High | woubus ICF/IF communication. Relet to Section 7.4 for details. | | |

Ethernet Setup

There are setup parameters for the Ethernet network as described below:

| Host Name | Device name of the instrument. Default is ' '. | |
|---------------|--|--|
| IP Address | Define IP address manually. Default is '192.168.16.250' | |
| Local Port | Ethernet connection port of the instrument. Default is '10001. | |
| Gateway | Network point that acts as an entrance to other networks. Default is '192.168.16.254'. | |
| Subnet Mask | Defines IP addresses which can be used in network. Default is '255.255.255.0'. | |
| Primary DNS | Define primary DNS manually. Default is '208.67.222.222'. | |
| Secondary DNS | Define secondary DNS manually. Default is '208.67.220.220'. | |

10.4. Modbus Data Structure

If the instrument is set up for Modbus TCP/IP, it can be used as a Modbus TCP/IP slave on an Ethernet communication network. The function codes '0x03' and '0x10' are supported.

For the Modbus Data Structure please refer to chapter 7.4.

Modbus TCP/IP High-Low: In two-word registers, the data is stored to the registers in big-endian format. Least significant word is stored to the highest register address; and most significant word is stored to the lowest register address.

Modbus TCP/IP Low-High: In two-word registers, the data is stored to the registers in little-endian format. Least significant word is stored to the lowest register address; and most significant word is stored to the highest register address.

Parameter's set-up:

| Set Ethernet Data Format | : Modbus TCP/IP High-Low or Modbus TCP/IP Low-High |
|--------------------------|--|
| Ethernet Address | : 01 |

Warning: Transmitter can be run the Modbus protocol for one interface at the same time.

Please find Modbus information in the web site of http://www.modbus.org

11. FAD-30CO – WITH CANOPEN INTERFACE

FAD-30CO instruments are state-of-the-art strain gauge load cell signal digitizers with CANopen interface. The **EDS** file is available on <u>www.flintec.com</u>

11.1. Front View

There are 5 status LEDs on the front panel which indicate the operational instrument status and the CANopen status. The setup switch on front panel of the instrument is used for CANopen addressing without PC (Refer to chapter 5.6) and for diagnostics (Refer to page 68).

When the error LED is ON, the other two LED indicate the error type (Refer to page 67).

Load cell connection, CANopen connection, power supply and serial interface terminals are located at the front of the DIN rail mount instrument (See figure 10.1).





The meanings of these LEDs in operation are described below.

| | (| Operational Mode | | |
|-----------------|---|--|--|--|
| Symbol Na | me Weight / Force | Count | | |
| Stab | le Stable O Unstable | Off for 0.3 seconds in 2 seconds period (No stable indication) | | |
| →0← Cer of Z | ter ero in the center of zero range (-0.25 e < w < 0.25 e) Out of center of zero range | Always off (No center of zero indication) | | |
| Err Er | or ADC conversion error Digital processing error No error | ADC conversion error Digital processing error No error | | |

🔘 Off 🖲 On 🏶 Flashing 🕕 Off for 0.3 seconds

(*) : Refer to the error table page 67.

Table 10.1 – Status LEDs

RUN LED

| State | Indication | Comment |
|---------------------|--------------------------------------|----------------------------|
| Off | No power or not initialized | No power or cable broken |
| Green | On-line, data exchange | |
| Green, flashing | On-line, initializing | |
| Green, single flash | Stopped | Check for hardware damages |
| Green, flickering | Auto baud rate detection in progress | |
| Red | Exception error | Check EDS file |

ERR LED

| State | Indication | Comment |
|-------------------|-----------------------|--|
| Off | No error | No power or CANopen module is initializing |
| Red, single flash | Warning limit reached | Bus error counter reached or exceeded its warning limit |
| Red, flickering | LSS | LSS services in progress |
| Red, double flash | Error count event | A guard (NMT slave or master) or heartbeat event has occured |
| Red | Bus off (fatal event) | Bus off |

11.2. Electrical Connections



Figure 10.2 - FAD-30CO interface connections

CANopen Connector (DB9M)

| Pin | Signal | Description |
|---------|--------------|-------------|
| 1 | - | - |
| 2 | CAN_L | - |
| 3 | CAN_GND | - |
| 4 | - | - |
| 5 | CAN_SHIELD | - |
| 6 | - | - |
| 7 | CAN_H | - |
| 8 | - | - |
| 9 | - | - |
| Housing | Cable shield | - |

CANopen Interface

| Use | Interfacing with PC or PLC |
|-------------|---|
| Data format | CANopen |
| Baud rate | Automatically detected baud rates are 10 kbps, 20 kbps, 50 kbps, 100 kbps, 125 kbps, 250 kbps, 500 kbps, 800 kbps, 1 Mbps; Autobaud is default setting. |

Warning: Connect the shield to the reference ground or shield pin of the power connector. **Warning:** Disconnect xFace PC software for Profibus interfacing.

11.3. CANopen Setup and EDS configuration

FAD-30CO instruments have two interface connectors on the front of the instrument: CANopen and RS-232C. The table below describes the data formats for interfacing the peripherals and their application.

Attention: Please disable the interface you will not use to increase the performance of the instrument.

There is only one parameter for the CANopen network.

CANopen Rack Address The address range is 1 (default setting) to 127.

CANopen data structures of FAD-30CO includes 2 x TxPDO and 2 x RxPDO. EDS configuration for PLC programmers is shown below.

| Definition | Size | Description | |
|-----------------|---------|-----------------|------------------------------|
| TxPDO 1 (T_DW1) | 2 words | Unsigned Double | (Not used) |
| TxPDO 2 (T_UL1) | 4 words | Unsigned Long | (FAD-30 Output to PLC Input) |
| RxPDO 1 (R_DW1) | 2 words | Unsigned Double | (Not used) |
| RxPDO 2 (R_UL1) | 4 words | Unsigned Long | (PLC Output to FAD-30 Input) |

| TX2 CO - TwinCAT System Manager | | | | | | | l | - | x |
|-------------------------------------|---|---------------------------------|--------|------------------------|------------|----------------|--------------|---------|----------|
| File Edit Actions View Options Help | | | | | | | | | |
| | 件 | 8 🗒 📾 🗸 🌌 | Ø. | 👷 💱 🔨 🌒 📕 | C B | <u>) 🧏 🔊 (</u> | 🖉 🖪 🤻 | | |
| TX 2CO | * | General Size / Offset | Inp | ut Output | | | | | <u> </u> |
| | | Name: TX 2 | co | | 1 | ld: 4 | 1 | | |
| Hard Carl Task 3 | | Type: Mast | er Im | age | | CONTROL LAL | | | |
| COM Objects | | Comment: | | | | | * | | |
| in I/O - Configuration | | | | | | | | | III |
| Device 1 (EtherCAT) | | | | | | | | | |
| | | | | | | | * | | |
| ⊕ | | D | isable | ed | | Create symbol | ols 📃 | | |
| Box 1 (CANopen Node) | | | | | | | | | - |
| | | Name | | Online | Туре | Size | >Addr | In/Out | User ID |
| ⊟ ∎↑ TxPDO 1 | | <mark>∲</mark> Not used (T_DW1) | Х | 0x00010000 (65536) | UDINT | 4.0 | 0.0 | Input | 0 |
| ⊡ <mark>≩†</mark> Inputs | | <pre> fT_UL1 </pre> | Х | 0x00000000000383 (899) | ULINT | 8.0 | 4.0 | Input | 0 |
| Not used (I_DWI) | | Not used (R_DW1) | Х | 0x00000000 (0) | UDINT | 4.0 | 0.0 | Output | 0 |
| | | B R_UL1 | X | 0x000000000000000 (0) | ULINT | 8.0 | 4.0 | Output | 0 |
| T UL1 | | | | | | | | | |
| E ■↓ RxPDO 1 | | | | | | | | | |
| 🗄 🖷 😫 Outputs | - | | | | | | | | |
| → A Not used (R_DW1) | | | | | | | | | |
| i⊒ ∎↓ RxPDO 2 | | | | | | | | | |
| E. S. Outputs | | | | | | | | | |
| | - | < | | III 2 | | | | | P. |
| Ready | | | | | | Local (192.1 | 68.16.28.1.1 |) RTime | 1% |

Figure 11.1 - EDS Configuration

11.4. CANopen Data Structure (for FAD-30CO only)

FAD-30CO Output to PLC Input

| Dword | D31 | D30 | D29 | D28 | D27 | D26 | D25 | D24 | D23 | D22 | D21 | D20 | D19 | D18 | D17 | D16 |
|--------------------|------------|----------|--------|--------|-------|-------|-------------|---------------|--------------|-----|-----|--------|-------|-------|-----|-------------|
| Dirora | D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
| TxPDO 1 (T_DW1) | | reserved | | | | | | | | | | | | | | |
| TxPDO 2 | W31 MSB | W30 | W29 | W28 | W27 | W26 | W25 | W24 | W23 | W22 | W21 | W20 | W19 | W18 | W17 | W16 |
| (T_DW2) | W15 | W14 | W13 | W12 | W11 | W10 | W9 | W8 | W7 | W6 | W5 | W4 | W3 | W2 | W1 | W0 LSB |
| | Not in use | | | | | | | | | | | | | | | |
| (T_DW3) | Error | codes | of con | verter | Not i | n use | Op. mode | Zero range | Gross Net | MD | Re | ad con | nmand | respo | nse | Cmd Flag |

FAD-30CO Output to PLC Input T_DW2

T_DW2 contains the weight value respective the calibration information according to the "read command response" (Refer to FAD-30COOutput to PLC Input T_DW3).

FAD-30CO Output to PLC Input T_DW3

| Bit No. | TxPDO 2 (T_UL1) Description | | | | | | | |
|---------|--|---|-------------------------------------|---|--|--|--|--|
| B63 B48 | Not in use | | | | | | | |
| | | Binary | Dec. | Description | | | | |
| | | 0000 | 0 | No error found | | | | |
| | | 0001 | 1 | ADC out | | | | |
| | Emer Order of | 0010 | 2 | ADC over | | | | |
| B47 B44 | Error Codes of | 0011 | 3 | ADC under | | | | |
| | Digitizei | 0100 | 4 | System Error | | | | |
| | | 0101 | 5 | In programming mode | | | | |
| | | 0110 | 6 | Low/High Voltage Error | | | | |
| | | 0111 | 7 | Instrument hasn't been found | | | | |
| B43 B42 | Not in use | | | | | | | |
| D44 | Operation Made | 0 | Weigh | t & Force Mode | | | | |
| D4 I | Operation Mode | 1 | Count Mode | | | | | |
| B40 | Zero Pange | 0 | Weigh | t is out of center of zero range | | | | |
| D40 | Zero Kange | 1 | Weigh | t is in the center of zero range | | | | |
| B30 | Gross or Net | 0 | Gross | | | | | |
| 800 | | 1 | Net | Net | | | | |
| B38 | Motion Detection | 0 | Stable | | | | | |
| 200 | | 1 | Dynan | | | | | |
| | | Binary | Dec. | Description | | | | |
| | | 00000 | 0 | Actual weight or Count value (32 bit integer type) (Net if the indication is in Net for Weight & Force mode) | | | | |
| | | 00001 | 1 | Gross weight (32 bit integer type) | | | | |
| B37 B33 | Read Command | 00010 | 2 | Tare weight (32 bit integer type) | | | | |
| D07 D00 | Response | 00011 | 3 | Actual weight or Count value (floating point type) | | | | |
| | | 00011 | 5 | (Net if the indication is in Net for Weight & Force mode) | | | | |
| | | 00100 | 4 | Gross weight (floating point type) | | | | |
| | | 00101 | 5 | Tare weight (floating point type) | | | | |
| | | 10000 | 16 | Calibration Status | | | | |
| B32 | CMD Flag | Toggles | The command is applied successfully | | | | | |
| B31B0 | By default, Indicate To represent other | default, Indicated weight value is represented. represent other weight or calibration status, refer to B37B33. | | | | | | |

Calibration Status

Low Dword of TxPDO 2 (T_UL1) descriptions when read command is 'Calibration Status'. Refer to RxPDO 2 (R_UL1) of PLC Output to FAD-30 Input.

| Bit No. | Low Dword of TxPDO 2 (T_UL1) Description | | | | | | | |
|---------|--|----------------|------|--|--|--|--|--|
| B31 B16 | Not in use | | | | | | | |
| | | Binary | Dec. | Description | | | | |
| | | 0000 0001 | 1 | Calibration Timeout - Restart calibration | | | | |
| | | 0000 0010 | 2 | ADC Error - Re-energize the instrument | | | | |
| | | 0000 0011 | 3 | Instrument cannot be calibrating - Check load cell cable - Re-energize the instrument | | | | |
| B15 B8 | Calibration Errors | 0010 0010 | 34 | Instrument cannot be calibrating - Load cell signal is very low or too high | | | | |
| | | 0010 0011 | 35 | Calibration Error - Calibration test weight is not enough - Increase calibration weight value (Write test weight value to Low Dword of RxPDO 2 (R_UL1) of PLC Output to FAD-30 Input then restart the calibration) - Check load cell connections | | | | |
| | | 0010 0101 | 37 | Scale unstable - Wait until scale become stable - Check grounding wiring | | | | |
| | | 0000 0001 | 1 | System ready for calibration | | | | |
| | Calibration | 0000 0011 | 3 | Zero calibration in process | | | | |
| B7 B0 | Status | 0000 0100 | 4 | Span calibration in process | | | | |
| | | 0000 1001 9 | | Error (Refer to Calibration Errors) | | | | |

PLC Output to FAD-30CO Input

| | | | | • | | | 1 | | | | | | | | | |
|--------------------|------------|----------|---------|-----|-----|-----|-----|-------|------|-----|-----|------|---------|-------|-----|------------|
| Dword | D31 | D30 | D29 | D28 | D27 | D26 | D25 | D24 | D23 | D22 | D21 | D20 | D19 | D18 | D17 | D16 |
| Dword | D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
| RxPDO 1 (R_DW1) | | Reserved | | | | | | | | | | | | | | |
| RxPDO 2 | W31 MSB | W30 | W29 | W28 | W27 | W26 | W25 | W24 | W23 | W22 | W21 | W20 | W19 | W18 | W17 | W16 |
| (R_DW2) | W15 | W14 | W13 | W12 | W11 | W10 | W9 | W8 | W7 | W6 | W5 | W4 | W3 | W2 | W1 | W0 LSB |
| | Not in use | | | | | | | | | | | | | | | |
| (R_DW3) | | N | ot in u | se | | | Con | nmand | List | | | Data | a Selec | ction | | New CMD |

PLC Output to FAD-30CO Input R_DW 2

R_DW 2 contains the setting / parameter value (Refer to "Adjust span calibration" and "I/O configuration" in "Command List", see PLC Output to FAD-30CO Input R_DW3).

| Bit No. | RxPDO 2 (R | (R_UL1) Description | | | | | | | | |
|------------------------|---|---------------------|-------|---|-------------------------------|--|--|--|--|--|
| B63B43 | Not used | 1 | 1 | 1 | | | | | | |
| | | Binary | Dec. | Description | | | | | | |
| | | 00000 | 0 | None command is activated | | | | | | |
| | | 00001 | 1 | Zero | | | | | | |
| | | 00010 | 2 | Tare | | | | | | |
| | | 00011 | 3 | Clear | Clear | | | | | |
| | | 00100 | 4 | Not in use | | | | | | |
| | | 00101 | 5 | Adjust zero calibration | | | | | | |
| | | 00110 | 6 | Adjust span calibra | Adjust span calibration (1) | | | | | |
| | | 00111 | 7 | Not in use | | | | | | |
| | | | | Operation mode selection ⁽¹ | Dec. | Description | | | | |
| B42 Commar B38 List | | | | | 0 | Count mode unipolar | | | | |
| | | 04000 | | | 1 | Count mode bipolar | | | | |
| | | 01000 | 8 | | 2 | Force mode unipolar | | | | |
| | Command | | | , | 3 | Force mode bipolar | | | | |
| | LIST | | | | 4 | Weight mode unipolar | | | | |
| | | - | | | 0 | 5 mV | | | | |
| | | | | Operation mV | 1 | 10 mV | | | | |
| | | 01001 | 9 | of Count Mode (1) | 2 | 15 mV | | | | |
| | | | | | 3 | 18 mV | | | | |
| | | | | | 0 | Fast | | | | |
| | | | | | 1 | | | | | |
| | | | 10 | | 2 | | | | | |
| | | | | | 3 | | | | | |
| | | | | | 4 | | | | | |
| | | 01010 | | Digital Filter (1) | 5 | Medium | | | | |
| | | | | | 6 | | | | | |
| | | | | | 7 | Default | | | | |
| | | | | | 8 | | | | | |
| | | | | | 9 | Slow | | | | |
| | | Binary | Dec. | Description | J | 1 | | | | |
| | | 00000 | 0 | Actual weight or Co | ount valu n is in N | ue (32 bit integer type) let for Weight & Force mode) | | | | |
| | | 00001 | 1 | Gross weight (32 b | it intege | r type) | | | | |
| | Read Data | 00010 | 2 | Tare weight (32 bit | integer | type) | | | | |
| D37 D33 | Selection | 00011 | 3 | Actual weight or Co | ount valu <i>n is in N</i> | ue (floating point type) let for Weight & Force mode) | | | | |
| | | 00100 | 4 | Gross weight (float | ing poin | t type) | | | | |
| | | 00101 | 5 | Tare weight (floatin | g point | type) | | | | |
| | | 10000 | 16 | Calibration Status | 01. | . , | | | | |
| B32 | New CMD | Toggle | Apply | commands which are | e listed i | in this table | | | | |
| B31 B0 | B37 ~ B33 c | lefines the | | of this Dword | | | | | | |
| 00100 | Dor ~ Doo dennes the usage of this Dword. | | | | | | | | | |

PLC Output to FAD-30CO Input RxPDO 2 (R_UL1)

*Span test weight value has to be entered ignoring the decimal point; e.g. "300.00" must be entered as "30000"

Programming steps of frequent use.

Reading a weight or Count value:

- 1. Check the B44...B47 bits of 'TxPDO 2 (T,_UL1)'.
- 2. If there is not any error, read a weight or count value (gross, net or tare),

Zero Calibration procedure (only weight mode):

- 1. Check the low byte of Calibration Status. it should be decimal '1' to start adjustment.
- 2. Write 'Adjust Zero Calibration' command and apply New CMD to start Zero calibration.
- 3. Check the low byte of Calibration Status. it is decimal '3' during zero calibration process.
- 4. The low byte of Calibration Status changes to decimal '1' at the end of the Zero calibration.
- 5. If the low byte of Calibration Status is '9', check the high byte of Calibration Status to understand the calibration error.

Span Calibration procedure (only weight mode):

- 1. Check the low byte of Calibration Status. it should be decimal '1' to start adjustment.
- 2. Write 'Adjust Span Calibration' command after writing test weight values to Low Dword of RxPDO 2 (R_UL1), then apply this command with New CMD to start Span calibration.
- 3. Check the low byte of Calibration Status. it is decimal '4' during span calibration process.
- 4. The low byte of Calibration Status changes to decimal '1' at the end of the Span calibration.
- 5. If the low byte of Calibration Status is '9', check the high byte of Calibration Status to understand the calibration error.

12. FAD-30EI – WITH ETHERNET/IP INTERFACE

FAD-30EI instruments are a state-of-the-art strain gage load cell signal digitizer with EtherNet/IP interface.

The EDS file is available on www.flintec.com.

EtherNet/IP interface of the weighing instrument can be done via hub switch or serial bus over two EtherNet/IP ports.

- 1. Serial bus connection of instruments. You may connect instruments serial to your EtherNet/IP bus via two ports.
- 2. Star connection. If you connect the instrument to your PLC via hub switch, you can use P1 or P2 port on the instrument. You may change the port, if there is any malfunction on port in usage.

The EtherNet/IP interface supports 10/100Mbit, full or half duplex operation.

12.1. Front View

There are 3 annunciator LEDs on front panel to show the instrument status in operation and 4 LEDs (MS, NS, Link1 and Link2) for showing EtherNET/IP status in operation.

The programming switch on front panel of the instrument is used for diagnostic tests.

The operation mode of the instrument is announced by different lights at stable condition and there is no zero indication in count mode operation.

When error LED lightened, other two LED announces the error type. Please refer to page 67 Fehler! Verweisquelle konnte nicht gefunden werden.for detailed error descriptions.

Load cell, EtherNet/IP, power and serial interface terminals are located at the front of the DIN rail mount instrument as seen in below.



Figure 12.1 - Front view

The meanings of these LEDs in operation are given below.

| L | .ED | Operating Mode | | | | | | |
|--------|----------------|---|--|--|--|--|--|--|
| Symbol | Name | Weight / Force mode | Count mode | | | | | |
| | Stable | Stable Unstable (Dynamic) | Blanks for 0.3 seconds in 2 seconds period. (No stable indication) | | | | | |
| +0← | Centre of Zero | in the center of zero range (-0.25 e < w < 0.25 e) Out of center of zero range | Always blank (No center of zero indication) | | | | | |
| Err | Error (*) | ADC conversion error Digital processing error No error | ADC conversion error Digital processing error No error | | | | | |



(*) : Refer to the error table page 67.

Table 12.1 - Annunciator LEDs

NS Network Status LED

| LED State | Description |
|-----------------|--|
| Off | Not IP address |
| Green | Online, one or more connections established (CIP Class 1 or 3) |
| Green, flashing | Online, no connections established |
| Red | Duplicate IP address, FATAL error |
| Red, flashing | One or more connections timed out (CIP Class 1 or 3) |

MS Module Status LED

| LED State | Description |
|-----------------|---|
| Off | No power |
| Green | Controlled by a scanner in run state |
| Green, flashing | Not configured, or scanner in idle state |
| Red | Major fault (EXCEPTION state, FATAL error etc.) |
| Red, flashing | Recoverable fault(s) |

In the case of red LED warning, check cabling, configuration and IP address before reenergizing the instrument after 30 seconds power off.

LINK/Activity LED

| LED State | Description |
|--------------------|-------------------------------|
| Off | No link, no activity |
| Green | Link (100 Mbit/s) established |
| Green, flickering | Activity (100 Mbit/s) |
| Yellow | Link (10 Mbit/s) established |
| Yellow, flickering | Activity (10 Mbit/s) |

12.2. Electrical Connections

EtherNet/IP usage and specifications are shown in the table below

| Usage | Interfacing with PC or PLC, |
|---------------------------------------|---|
| Data formats | EtherNet/IP |
| Data rate | The EtherNet/IP interface supports 10/100Mbit, full or half duplex operation. |
| Table 12.2 – Interface Specifications | |

EtherNet/IP connection is done as indicated below.



Figure 11.4 - FAD-30EI interface connections

EtherNet/IP Connector pin configuration (RJ45)

| Pin | Signal | DIR | Description |
|-----|----------|-----|---------------------------------------|
| 1 | TX+ | Out | Differential Ethernet transmit data + |
| 2 | TX- | Out | Differential Ethernet transmit data – |
| 3 | RX+ | In | Differential Ethernet receive data + |
| 6 | RX- | In | Differential Ethernet receive data - |
| 4 | Not used | | Terminated |
| 5 | Not used | | Terminated |
| 7 | Not used | | Terminated |
| 8 | Not used | | Terminated |
| | Shield | | Chassis ground |

The HUB connection cabling will be a direct connection as shown below:



Figure 9.2 – HUB connection

The PC connection cabling will be done via cross cable as shown below:



Figure 9.3 – Direct PC connection with cross cable

Ethernet Interface

| Usage | Interfacing with PC or PLC, |
|--------------|---|
| Data formats | Continuous, BSI, Modbus TCP/IP High-Low (<i>Default</i>), Modbus TCP/IP Low-High |
| Data rate | The Ethernet interface operates at 10Mbit, half duplex |

Warning: Connect the shield to the reference ground or shield pin of the power connector. *Warning:* Disconnect xFace PC software for EtherNet/IP interfacing.

12.3. EtherNet/IP Setup and ESD Configuration

EtherNet/IP set up is done by xFace software as described in this section.

The ESD file is available on www.flintec.com.

EtherNet/IP Parameters

There are 7 parameters for EtherNet/IP network and EtherNet/IP set up is done by EtherX PC software over Local Network Area as described in this section. Click "Find on LAN" button to run EtherX program and search a transmitter on LAN (Local Area Network).

| Host Name | Device name of the instrument. Default is ' '. |
|---------------|--|
| IP Address | Define IP address manually. Default is '192.168.16.250' |
| Local Port | Ethernet connection port of the instrument. Default is '10001. |
| Gateway | Network point that acts as an entrance to other networks. Default is '192.168.16.254'. |
| Subnet Mask | Defines IP addresses which can be used in network. Default is '255.255.255.0'. |
| Primary DNS | Define primary DNS manually. Default is '208.67.222.222'. |
| Secondary DNS | Define secondary DNS manually. Default is '208.67.220.220'. |

EDS Configuration

EtherNet/IP data consists of 3 x Input 2 words and 3 x Output 2 words. EDS configuration for PLC programmers is shown below.

| TX2 EI - TwinCAT System Manager | |
|---|--|
| File Edit Actions View Options Help | |
| Image: System - Configuration Image: System - Configuration Image: Strings Image: Strings < | a ✓ ﷺ ଊ ଊ ଋ ୯ ເ to te |
| | Transport Trigger Uyclic Timeout Multiplier Config Instance Config Size 0 |
| Anybus-CC EtherNet/IP (2-Port) | Inputs (Data Length: 12 Byte) Connection Point 100 Run/Idle Transport Type Multicast Priority Scheduled |
| Outputs O | Outputs (Data Length: 12 Byte) Connection Point 150 Iransport Type Point to Point Priority Scheduled |
| | ۲ |
| Ready | Local (192.168.16.28.1.1) RTime 2% |

12.4. EtherNET/IP Data Structure

Please refer to chapter 16 "Data Structure for ... ".

13. FAD-30EC WITH ETHERCAT INTERFACE

FAD-30EC instruments are a state-of-the-art strain gage load cell signal digitizer with EtherCAT interface.

The ESI file is available on www.flintec.com.

EtherCAT interface of the weighing instrument can be done via hub switch or serial bus over two EtherCAT port.

- 1. Serial bus connection of instruments. You may connect instruments serial to your EtherCAT bus via two ports.
- 2. Star connection. If you connect the instrument to your PLC via hub switch, you can use P1 port on the instrument.

The EtherCAT interface supports 100Mbit, full duplex operation.

13.1. Front View

There are 3 annunciator LEDs on front panel to show the instrument status in operation and 4 LEDs (Run, Err, Link1 and Link2) for showing EtherCAT status in operation.

The programming switch on front panel of the instrument is used for diagnostic tests (Refer to page 68).

The operation mode of the instrument is announced by different lights at stable condition (Refer to Table 13.1) and there is no zero indication in count mode operation.

When error LED lightened, other two LED announces the error type. Please refer to **page 67** for detailed error descriptions.

Load cell, EtherCAT, power and serial interface terminals are located at the front of the DIN rail mount instrument as seen in below.



Figure 13.1 - Front view

The meanings of these LEDs in operation are given below.

| LED | | Operating Mode | | |
|--------|----------------|--|---|--|
| Symbol | Name | Weight / Force mode | Count mode | |
| 1 | Stable | Stable Unstable (Dynamic) | Blanks for 0.3 seconds in 2 seconds period. (No stable indication) | |
| +0← | Centre of Zero | in the center of zero range (-0.25 e < w < 0.25 e Out of center of zero range | Always blank No center of zero indication) | |
| Err | Error (*) | ADC conversion error Digital processing error No error | ADC conversion error Digital processing error No error | |

[○] Blank ● Light 苯 Flash ● Blank for 0.3 second

(*) : Refer to the error table page 67.

RUN LED

| U | | | |
|---|---------------------|------------------|--|
| | LED State | Description | |
| | Off | INIT | |
| | Green | OPERATIONAL | |
| | Green, blinking | PRE-OPERATIONAL | |
| | Green, single flash | SAFE-OPERATIONAL | |
| | Red | (Fatal Event) | |

ERR LED

| LED State | Description |
|-------------------|--|
| LED State | Description |
| Off | No error (or no power) |
| Red, blinking | Invalid configuration; State change received from master is not possible due to invalid register or object settings. |
| Red, single flash | Unsolicited state change; Slave device application has changed the EtherCAT state autonomously. |
| Red, double flash | Application watchdog timeout |
| Red | Application controller failure |

In the case of red LED warning, check cabling and configuration, before reenergizing the instrument after 30 seconds power off.

LINK/Activity LED

| LED State | Description | |
|-------------------|--------------------------|--|
| Off | No link, no activity | |
| Green | Link sensed, no activity | |
| Green, flickering | Link sensed, activity | |

Table 13.1 - Annunciator LEDs

13.2. Electrical Connection

| EtherCAT | usage and | specifications | are shown | in the | table below. |
|----------|-----------|----------------|-----------|--------|--------------|
|----------|-----------|----------------|-----------|--------|--------------|

| Usage | Interfacing with PC or PLC, |
|--------------|--|
| Data formats | EtherCAT |
| Data rate | The EtherCAT interface supports 10/100Mbit, full or half duplex operation. |
| | |

Table 13.2 – Interface Specifications

EtherCAT connection is done as indicated below.



EtherCAT Connector pin nfiguration (RJ45)

| Pin | Signal | DIR | Description |
|-----|----------|-----|---------------------------------------|
| 1 | TX+ | Out | Differential Ethernet transmit data + |
| 2 | TX- | Out | Differential Ethernet transmit data - |
| 3 | RX+ | In | Differential Ethernet receive data + |
| 6 | RX- | In | Differential Ethernet receive data - |
| 4 | Not used | | Terminated |
| 5 | Not used | | Terminated |
| 7 | Not used | | Terminated |
| 8 | Not used | | Terminated |
| | Shield | | Chassis ground |

The HUB connection cabling will be a direct connection as shown below:



Figure 13.2 - HUB connection

Warning: Connect the shield to the reference ground or shield pin of the power connector. *Warning:* Disconnect xFace PC software for EtherCAT interfacing.

13.3. EtherCAT Setup and ESI Configuration

EtherCAT set up is done by PLC Software.

The **ESI** file is available on <u>www.flintec.com</u>.

ESI Configuration

EtherCAT data structures is consist of 3 x Input 2 words and 3 x Output 2 words. ESI configuration for PLC programmers is shown below.



Figure 13.3 – Configuration of module properties for Beckhoff

| Input/Output | Definition | Description | |
|--------------|--------------|----------------------------------|----------------------|
| | BU -> PLC | 1 st Dword (Not used) | |
| DI TxPDO-Map | SubIndex 001 | 2 nd Dword (FAD-30 C | Output to PLC Input) |
| | SubIndex 002 | 3 rd Dword (FAD-30 C | Output to PLC Input) |
| | PLC -> BU | 1 st Dword (Not used) | |
| DO RxPDO-Map | SubIndex 001 | 2 nd Dword (PLC Outp | out to FAD-30 Input) |
| | SubIndex 002 | 3 rd Dword (PLC Outp | out to FAD-30 Input) |

13.4. EtherCAT Data Structure

Please refer to chapter 16 "Data Structure for ... ".

14. FAD-30CC WITH CC-LINK INTERFACE

FAD-30CC instruments are a state-of-the-art strain gage load cell signal digitizer with CC-Link interface.

14.1. Front View

There are 3 annunciator LEDs on front panel to show the instrument status in operation and 4 LEDs (Run, Err, Link1 and Link2) for showing the status in operation.

The programming switch on front panel of the instrument is used for diagnostic tests.

The operation mode of the instrument is announced by different lights at stable condition (Refer to Table 14.1) and there is no zero indication in count mode operation.

When error LED lightened, other two LED announces the error type. Please refer to page 67 for detailed error descriptions.

Load cell, CC-Link, power and serial interface terminals are located at the front of the DIN rail mount instrument as seen in below.



Figure 14.1 - Front view

The meanings of these LEDs in operation are given below.

| LED | | Operating Mode | | |
|-------------|----------------|---|--|--|
| Symbol Name | | Weight / Force mode | Count mode | |
| Υ | Stable | Stable Unstable (Dynamic) | Blanks for 0.3 seconds in 2 seconds period. No stable indication) | |
| →0+ | Centre of Zero | in the center of zero range (-0.25 e < w < 0.25 e) Out of center of zero range | Always blank (No center of zero indication) | |
| Err | Error (*) | ADC conversion error Digital processing error No error | ADC conversion error Digital processing error No error | |
| O Blank | Dight 🇚 F | lash 🌒 Blank for 0.3 second | • | |

(*) : Refer to the error table page 67.

Table 14.1 - Annunciator LEDs

Run LED

| State | Indication |
|-------|---|
| Off | No network participation, timeout status (no power) |
| Green | Participating, normal operation |
| Red | Major fault (FATAL error) |

Error LED

| State | Indication |
|-----------------|--|
| Off | No error detected (no power) |
| Red | Major fault (Exception or FATAL event) |
| Red, flickering | CRC error (temporary flickering) |
| Red, flashing | Station Number or Baud rate has changed since startup (flashing) |

In the case of red LED warning, check cabling and configuration before reenergizing the instrument after 30 seconds power off.

14.2. Electrical Connection

| Usage | Interfacing with PLC, |
|--------------|---|
| Data formats | CC-Link |
| Data rate | Supported CC-Link version is v1.10 and baud rates are 156 kbps (default), 625 kbps, 2,5 Mbps, 5 Mbps and 10 Mbps. |

Table 14.2 - Interface Specifications

CC-Link connection is done as indicated below.





CC-Link Connector pin configuration

| | Pin | Signal | Description | |
|---|-----|--------|-----------------------|---|
| | 1 | DA | PositiveRS485 Rxd/TxD | |
| | 2 | DB | NegativeRS485 Rxd/TxD | _ |
| | 3 | DG | Signal ground | |
| - | 4 | SLD | Cable Shield | |
| - | 5 | FG | Protective Earth | |



Warning: Connect the shield to the reference ground or shield pin of the power connector. *Warning:* Disconnect xFace PC software for CC-Link interfacing.

14.3. CC-Link Setup and configuration

CC-Link set up is done by xFace software as described in this section. Select Gateway tab after connecting xFace to instrument. You will see the CC-Link parameters in this tab.

CC-Link Parameters

There are only two parameters for CC-link network.

Rack Address range is 0 to 64.

Default is '0'.

Baudrate 156 kbps, 625 kbps, 2,5 Mbps, 5 Mbps and 10 Mbps.

Default is '156 kbps'.

CC-Link Configuration

FAD-30 has two occupied station areas on CC-Link network and station type of FAD-30 must be programmed as 'Remote device station' in the PLC software. CC-Link configuration for PLC programmers is shown below.

| | | Europeandered Counting | blumbau af | Damata Station | Deserve (Touslid | Tabellia | ant Duffer Cala | -+0.01 |
|-------------|---------------------------------------|------------------------|---------------------------|-----------------|------------------|----------|-----------------|-----------|
| Station No. | Station Type | Setting | Occupied Stations | Points | Station Select | Send | Receive | Automatic |
| 1/1 | Remote Device Station 👻 | Single - | Occupied Stations 2 - | 64Points - | No Setting | • | ////// | |
| | | | | | | | | |
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| | | | | | | | | |
| | Intelligent device station at station | n type also includes l | local station and standby | master station. | | | | |

Figure 14.2 - Station information

| Input/Output | Definition | Description |
|-----------------------|------------|--|
| | RWr0, RWr1 | 1 st Dword <i>(Not used)</i> |
| Remote Register (RWr) | RWr2, RWr3 | 2 nd Dword (FAD-30 Output to PLC Input) |
| | RWr4, RWr5 | 3 rd Dword (FAD-30 Output to PLC Input) |
| Remote Input (RX) | RX0 ~ RX31 | Not used |
| | RWw0, RWw1 | 1 st Dword (Not used) |
| Remote Register (RWw) | RWw2, RWw3 | 2 nd Dword (PLC Output to FAD-30 Input) |
| | RWw4, RWw5 | 3 rd Dword (PLC Output to FAD-30 Input) |
| Remote Output (RY) | RY0 ~ RY31 | Not used |

14.4. CC-Link Data Structure

Please refer to chapter 16 "Data Structure for ... ".

15. FAD-30 PL wITH POWERLINK INTERFACE

FAD-30PL instruments are a state-of-the-art strain gage load cell signal digitizer with Powerlink interface.

The XDD file is available on www.flintec.com

Powerlink interface of the weighing instrument can be done via hub switch or serial bus over two Powerlink ports.

- 1. Serial bus connection of instruments. You may connect instruments serial to your Powerlink bus via two ports.
- 2. Star connection. If you connect the instrument to your PLC via hub switch, you can use P1 or P2 port on the instrument. You may change the port, if there is any malfunction on port in usage.

The Powerlink interface is 100Mbit and half duplex.

15.1. Front View

There are 3 annunciator LEDs on front panel to show the instrument status in operation and 4 LEDs (STS, Err, Link1 and Link2) for showing Powerlink status in operation.

The programming switch on front panel of the instrument is used for diagnostic tests.

The operation mode of the instrument is announced by different lights at stable condition (Refer to Table 15.1) and there is no zero indication in count mode operation.

When error LED lightened, other two LED announces the error type. Please refer to **page 67** for detailed error descriptions.

Load cell, Powerlink, power and serial interface terminals are located at the front of the DIN rail mount instrument as seen in below.



Figure 15.1 - Front view

The meanings of these LEDs in operation are given below.

| L | _ED | Operating Mode | | |
|--------|----------------|---|---|--|
| Symbol | Name | Weight / Force mode | Count mode | |
| | Stable | Stable Unstable (Dynamic) | Blanks for 0.3 seconds in 2 seconds period. (No stable indication) | |
| →0← | Centre of Zero | in the center of zero range (-0.25 e < w < 0.25 e) Out of center of zero range | Always blank (No center of zero indication) | |
| Err | Error (*) | ADC conversion error Digital processing error No error | ADC conversion error Digital processing error No error | |
| ~ | _ | | · | |

○ Blank ● Light 🏶 Flash II Blank for 0.3 second

(*) $\,$: Refer to the error table page 67.

Table 15.1 - Annunciator LEDs

STS Status LED

| I ED State | Description |
|-----------------------------------|--|
| | |
| O ff | Module is off, initializing, or not active. |
| Green fast flashinga | NMT_CS_BASIC_ETHERNET |
| | Basic Ethernet state: no POWERLINK traffic has been detected. |
| Orean aingle flech | NMT_CS_PRE_OPERATIONAL_1. |
| Green, single hash | Only asynchronous data. |
| One an also bla flash | NMT_CS_PRE_OPERATIONAL_2. |
| Green, double flash | Asynchronous and synchronous data. No PDO data. ^b |
| Croop triple fleeb | NMT_CS_READY_TO_OPERATE. |
| Green, inple hash | Ready to operate. Asynchronous and synchronous data. No PDO data. ^b |
| | NMT_CS_OPERATIONAL. |
| Green | Fully operational. Asynchronous and synchronous data. PDO data is sent and received. |
| | NMT_CS_STOPPED |
| Green, slow flashing ^c | Module stopped (for controlled shutdown, for example). Asynchronous and synchronous |
| | data. No PDO data. ^b |
| Red | If the ERROR LED also is red, a fatal event was encountered. |
| 2 On 50 ms off 50 ms | • |

a. On 50 ms, off 50 ms.

b. Any process data sent is declared not valid and received process data must be ignored in this state.

c. On 200 ms, off 200 ms.

Err Error LED

| _ | LED State | Description |
|---|-----------|--|
| | Off | No error |
| | Dad | If the STATUS LED is not red, a non-fatal error has been detected. |
| | Red | If the STATUS LED is red, a fatal event was encountered. |

In the case of red LED warning, check cabling and configuration before reenergizing the instrument after 30 seconds power off.

LINK/Activity LED

| LED State | Description |
|-----------------|-------------------|
| Off | No link. |
| Green | Link, no traffic. |
| Green, flashing | Link and traffic. |

15.2. Powerlink Connection

Powerlink usage and specifications are shown in the table below.

| Usage Interfacing with PLC, | | | | | | | |
|---|-----------|--|--|--|--|--|--|
| Data formats | Powerlink | | | | | | |
| Compatibility Supports POWERLINK V2.0 Communication Profile Specification version | | | | | | | |
| Data rate The Powerlink interface is 100Mbit and half duplex | | | | | | | |
| Table 15.2 – Interface Specifications | | | | | | | |

Powerlink connection is done as indicated below.



Powerlink Connector pin configuration (RJ45)

| Pin | Signal | DIR | Description |
|-----|----------|-----|---------------------------------------|
| 1 | TX+ | Out | Differential Ethernet transmit data + |
| 2 | TX- | Out | Differential Ethernet transmit data – |
| 3 | RX+ | In | Differential Ethernet receive data + |
| 6 | RX- | In | Differential Ethernet receive data - |
| 4 | Not used | | Terminated |
| 5 | Not used | | Terminated |
| 7 | Not used | | Terminated |
| 8 | Not used | | Terminated |
| | Shield | | Chassis ground |

The HUB connection cabling will be a direct connection as shown below:





Warning: Connect the shield to the reference ground or shield pin of the power connector. *Warning:* Disconnect xFace PC software for Powerlink interfacing.

15.3. Powerlink Setup and XDD Configuration

Powerlink set up is done by xFace software as described in this section. Select Gateway tab after connecting xFace to instrument. You will see the Powerlink parameters in this tab.

Powerlink Parameters

There is only one parameter for Powerlink network.

Rack Address range is 1 to 239.

Default is '01'.

XDD Configuration

Powerlink data consists of 3 x Input 2 words and 3 x Output 2 words. XDD configuration for PLC programmers is shown below.



Figure 15.3 – Configuration of module properties with XDD file

| Data Length | Descriptior | ı |
|-----------------------------|-----------------------|------------------------------|
| 1_Dword_Input_I2001_S01 | 1 st Dword | Not used) |
| 1_Dword_Output_I2002_S01Out | 1 st Dword | (Not used) |
| 2_Dword_Input_I2003_S01 | 2 nd Dword | (FAD-30 Output to PLC Input) |
| 3_Dword_Input_I2003_S02 | 3 rd Dword | (FAD-30 Output to PLC Input) |
| 2_Dword_Output_I2004_S01Out | 2 nd Dword | (PLC Output to FAD-30 Input) |
| 3_Dword_Output_I2004_S02Out | 3 rd Dword | (PLC Output to FAD-30 Input) |

15.1. Powerlink Data Structure

Please refer to chapter 16 "Data Structure for ... ".

16. DATA STRUCTURE FOR PROFIBUS, PROFINET, ETHERNET/IP, ETHERCAT, CC-LINK, POWERLINK

FAD-30 Output to PLC Input

| Durand | D31 | D30 | D29 | D28 | D27 | D26 | D25 | D24 | D23 | D22 | D21 | D20 | D19 | D18 | D17 | D16 |
|--------------|------------|-------|--------|--------|-------|-------|-------------|---------------|--------------|-----|-----|--------|-------|--------|-----|-------------|
| Dworu | D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
| 1st Dword | Reserved | | | | | | | | | | | | | | | |
| 2nd | W31 MSB | W30 | W29 | W28 | W27 | W26 | W25 | W24 | W23 | W22 | W21 | W20 | W19 | W18 | W17 | W16 |
| Dword | W15 | W14 | W13 | W12 | W11 | W10 | W9 | W8 | W7 | W6 | W5 | W4 | W3 | W2 | W1 | W0 LSB |
| 3rd | Not in use | | | | | | | | | | | | | | | |
| Dword | Error | codes | of con | verter | Not i | n use | Op. mode | Zero range | Gross Net | MD | Re | ad con | nmand | respor | nse | Cmd Flag |

FAD-30 Output to PLC Input 2nd Dword

The 2nd Dword contains the weight value respective the calibration information according to the "read command response" (Refer to PLC Output to FAD-30 Input 3rd Dword).

FAD-30 Output to PLC Input 3rd Dword

| Bit no. | 3 rd Dword Description | | | | | | | | |
|---------|-----------------------------------|---------|---|--|--|--|--|--|--|
| D31D16 | Not in use | | | | | | | | |
| | | Binary | Dec. | Description | | | | | |
| | | 0000 | 0 | No error found | | | | | |
| | | 0001 1 | | ADC out | | | | | |
| | Error oodoo of | 0010 2 | | ADC over | | | | | |
| D15D12 | converter | 0011 | 3 | ADC under | | | | | |
| | conventer | 0100 | 4 | System error | | | | | |
| | | 0101 | 5 | In setup mode | | | | | |
| | | 0110 | 6 | Low/High voltage error | | | | | |
| | | 0111 | 7 | Instrument not found | | | | | |
| D11D10 | Not in use | | | | | | | | |
| D9 | Operation mode | 0 | | Weight & Force Mode | | | | | |
| | Operation mode | 1 | | Count Mode | | | | | |
| D9 | Zoro rango | 0 | | Weight is out of zero range | | | | | |
| Do | Zero range | 1 | | Weight is in zero range | | | | | |
| 707 | Indication | 0 | | Gross | | | | | |
| זט | Indication | 1 | | Net | | | | | |
| De | MD – | 0 | | Stable | | | | | |
| DO | Motion detection | 1 | - | Unstable | | | | | |
| | | Binary | Dec. | Description | | | | | |
| | | 0000 | 0 | Indicated weight | | | | | |
| | | 0001 | 1 | Gross weight | | | | | |
| D5 D1 | Read command | 0010 | 2 | Tare weight | | | | | |
| 0501 | response | 0011 | 3 | Indicated weight (floating point type) | | | | | |
| | | 0100 | 4 | Gross weight (floating point type) | | | | | |
| | | 0101 | 5 | Tare weight (floating point type) | | | | | |
| | | 1000 | 16 | Calibration Status (Refer to table "Calibration Status") | | | | | |
| D0 | CMD flag | A chang | A change of Flag indicates: The command is applied successfully | | | | | | |

Calibration Status

| Bit no. | 2 nd Dword descriptions when read command is 'Calibration Status'. Refer to PLC Output to FAD-30 Input 3 rd Dword | | | | | | | | |
|---------|--|----------------|------|--|--|--|--|--|--|
| D31D16 | Not in use | | | | | | | | |
| | | Binary | Dec. | Description | | | | | |
| | | 0000 0001 | 1 | Calibration timeout: - Restart calibration | | | | | |
| | | 0000 0010 | 2 | ADC error: - Re-energize the instrument | | | | | |
| | | 0000 0011 | 3 | Instrument cannot be calibrated - Check load cell cable; - Re-energize the instrument | | | | | |
| D15D8 | Calibration error | 0010 0010 | 34 | Instrument cannot be calibrated - Load cell signal is very low or too high | | | | | |
| | | 0010 0011 | 35 | Calibration Error - Calibration test weight is too small; Increase calibration weight value (Write test weight value from PLC Output to FAD-30 Input 2 nd Dword then restart the calibration) - Check load cell connections | | | | | |
| | | 0010 0101 | 37 | Scale unstable: - Wait until scale becomes stable - Check ground wiring | | | | | |
| | | 0000 0001 | 1 | System ready for calibration | | | | | |
| | Calibration | 0000 0011 3 | | Zero calibration in process | | | | | |
| D7D0 | status | 0000 0100 4 | | Span calibration in process | | | | | |
| | | 0000 1001 | 9 | Error (Calibration error) | | | | | |

PLC Output to FAD-30 Input

| Dword | D31 | D30 | D29 | D28 | D27 | D26 | D25 | D24 | D23 | D22 | D21 | D20 | D19 | D18 | D17 | D16 |
|-----------------------|------------|------------|----------|-----|-----|--------------|-----|-----|-----|-----|-----|------|---------|-------|-----|------------|
| Dworu | D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
| 1 st Dword | | Not in use | | | | | | | | | | | | | | |
| 2 nd | W31 MSB | W30 | W29 | W28 | W27 | W26 | W25 | W24 | W23 | W22 | W21 | W20 | W19 | W18 | W17 | W16 |
| Dword | W15 | W14 | W13 | W12 | W11 | W10 | W9 | W8 | W7 | W6 | W5 | W4 | W3 | W2 | W1 | W0 LSB |
| 3 rd Dword | | Not in use | | | | | | | | | | | | | | |
| | | N | ot in us | se | | Command List | | | | | | Data | a Seleo | ction | | New CMD |

PLC Output to FAD-30PInput 2nd Dword

The 2nd Dword contains the setting / parameter value (Refer to "Command List", see PLC Output to FAD-30 Input 3rd Dword).

PLC Output to FAD-30 Input 3rd Dword

| Bit No. | 3rd Dword Description | | | | | | | | | | |
|---------|-----------------------|--------|-------|---|------------------------|--|--|--|--|--|--|
| D31D11 | Not used | | | | | | | | | | |
| | | Binary | Dec. | Description | | | | | | | |
| | | 00000 | 0 | None command is activated | | | | | | | |
| | | 00001 | 1 | Zero | | | | | | | |
| | | 00010 | 2 | Tare | | | | | | | |
| | | 00011 | 3 | Clear | | | | | | | |
| | | 00100 | 4 | | | | | | | | |
| | | 00101 | 5 | Adjust zero calibration | | | | | | | |
| | | 00110 | 6 | Adjust span calibrat | $\frac{1}{100}$ | | | | | | |
| | | 00110 | 7 | Not in use | | | | | | | |
| | | 00111 | / | NOT IN USE | 1 | Description | | | | | |
| | | | | | Dec. | (Load 2 nd Dword with one of these) | | | | | |
| | | 01000 | 8 | Operation | 0 | Count mode unipolar | | | | | |
| D10 D6 | Command List | 01000 | | mode selection (1) | 1 | Count mode bipolar | | | | | |
| | | | | | 2 | Force mode unipolar | | | | | |
| | | | | | 3 | Force mode bipolar | | | | | |
| | | | | | 4 | Weight mode unipolar | | | | | |
| | | 01001 | 9 | Operation mV of Count Mode ⁽¹⁾ | 0 | 5 mV | | | | | |
| | | | | | 1 | 10 mV | | | | | |
| | | | | | 2 | 15 mV | | | | | |
| | | | | | 0 | Fast | | | | | |
| | | | | | 1 | | | | | | |
| | | | | | 2 | • | | | | | |
| | | | | | 3 | | | | | | |
| | | | | | 4 | | | | | | |
| | | 01010 | 10 | Digital Filter (1) | 5 | Medium | | | | | |
| | | | | | 6 | | | | | | |
| | | | | | 7 | Default | | | | | |
| | | | | | 8 | | | | | | |
| | | | | | 9 | Slow | | | | | |
| | | Binary | Dec. | Description | | | | | | | |
| | | 00000 | 0 | Actual weight or Co (Net if the indication | unt valu n is in Ne | e (32-bit integer type) et for Weight & Force mode) | | | | | |
| | Read | 00001 | 1 | Gross weight (32-bi | t integer | type) | | | | | |
| D5 B1 | Data | 00010 | 2 | Tare weight (32-bit | integer t | type) | | | | | |
| | Selection | 00011 | 3 | Actual weight or Co (Net if the indication | unt valu n is in Ne | e (floating point type) et for Weight & Force mode) | | | | | |
| | | 00100 | 4 | Gross weight (floati | ng point | type) | | | | | |
| | | 00101 | 5 | I are weight (floating | g point t | ype) | | | | | |
| | | 10000 | 16 | Calibration Status (| Refer to | table "Calibration Status") | | | | | |
| D0 | New CMD | Toggle | Apply | commands which are | e listed i | n this table | | | | | |

*Span test weight value must be entered ignoring the decimal point; e.g. "300.00" must be entered as "30000"

Programming steps of frequent use

Reading a weight or Count value:

- 1. Check the B12...B15 bits of 'FAD-30 Output to PLC Input 3rd Dword'.
- 2. If there is not any error, read a weight or count value (gross, net or tare),

Zero Calibration procedure (only weight mode):

- 1. Check the low byte of Calibration Status. it should be decimal '1' to start adjustment.
- 2. Write 'Adjust Zero Calibration' command and apply New CMD to start Zero calibration.
- 3. Check the low byte of Calibration Status. it is decimal '3' during zero calibration process.
- 4. The low byte of Calibration Status changes to decimal '1' at the end of the Zero calibration.
- 5. If the low byte of Calibration Status is '9', check the high byte of Calibration Status to understand the calibration error.

Span Calibration procedure (only weight mode):

- 1. Check the low byte of Calibration Status. it should be decimal '1' to start adjustment.
- 2. Write 'Adjust Span Calibration' command after writing test weight values to 2nd Dword, then apply this command with New CMD to start Span calibration.
- 3. Check the low byte of Calibration Status. it is decimal '4' during span calibration process.
- 4. The low byte of Calibration Status changes to decimal '1' at the end of the Span calibration.
- 5. If the low byte of Calibration Status is '9', check the high byte of Calibration Status to understand the calibration error.

17. ERROR TABLE

The FAD-30 Converters have been designed as very reliable and virtually error free instruments. However if an error occurs do not attempt to repair the equipment before you understand what caused the error. Note the problems you have with your instrument and the error messages shown by the LEDs located on the front panel. Then try to solve the problem according to the error table given below.

| Error Code | | | Description | Actions to undertake / Possible cause | | | | | |
|------------|-----|-----|---------------------------------|--|--|--|--|--|--|
| | +0+ | Err | | | | | | | |
| 0 | 0 | • | ADC error | Re-energize the instrument. Instrument could be defective. | | | | | |
| 0 | • | • | Overload | – Check the load. | | | | | |
| • | 0 | • | Weight is too low | Load cell or instrument could be defective. | | | | | |
| • | • | • | ADC out | Check the load. Check the calibration. Load cell or instrument could be defective. | | | | | |
| 0 | 0 | * | System error | Re-energize the instrument. Instrument could be defective. | | | | | |
| • | 0 | * | Board identity error | Re-energize the instrument. If seen again, repeat the setup of the instrument. | | | | | |
| • | • | * | Internal communication error | Re-energize the instrument. If seen again, change the cabling inside the housing. | | | | | |
| 0 | * | * | High voltage detected | Check the power supply, the voltage has to be within the required voltage range. | | | | | |
| * | 0 | * | Low voltage detected | Check the power supply, the voltage has to be within the required voltage range. | | | | | |

🔘 Off 🌒 On 🌞 Flash

Table 11.1 – Error table

18. DIAGNOSTICS

In this test menu serial interface tests (RC-232C and/or RS-485) and load cell signal analog to digital conversion and processing tests are performed sequentially.

For entering the diagnostics mode, press the setup switch before power on and release the switch after the instrument is powered on. The instrument will go into the RS-232C RXD test mode which is indicated by lighted LED and flashed Err LED as shown below. The status of LEDs on the front panel indicate the test steps and the test result as described below. You can go to the next test by pressing the setup switch.

| Test | LED's Status | | | Description |
|---|--------------|-------------|-----|---|
| | | →0 ← | Err | Description |
| RS-232C RxD | 0 | 0 | * | LED gets off 0.3 s after receiving any data. Press the setup switch to go to the next test step. |
| RS-232C TxD | 0 | * | * | 'A' to 'Z' characters are sent sequentially in 0.8 s intervals. If the same data is received, ► LED gets off for 0.3 s. Press the setup switch to go to the next test step. |
| RS-485 Receive | 0 | 0 | 0 | LED gets off for 0.3 s after receiving any data. Press the setup switch to go to the next step. |
| RS-485 Transmit | • | * | 0 | 'A' to 'Z' characters are sent sequentially in 0.8 s intervals. Press the setup switch to go to the next step. |
| Load cell signal | • | 0 | • | →0← LED gets off while the load cell signal increases. Press the setup switch to go to the next step. |
| | 0 | • | • | LED gets off while the load cell signal decreases. Press the setup switch to return to the RS-232C RxD test. |
| ○ Off ● On 🏶 Flash ● Off for 0.3 second | | | | |

Table 12.1 – Diagnostics

If you short circuit RXD and TXD pin of the instrument's RS-232C port and go in to 'RS-232C TXD' test, the receiving data, announced by \sim LED, indicates the instrument's interface pins have functionality. Press programming switch for 5 seconds to exit diagnostic test mode and go to operation mode.

