Shaft Type Ø18mm Incremental Rotary Encoder [NPN open collector/Voltage/No Amp. output]

Features

- Ultra-compact (Ø18mm) and ultra-lightweight (12g/10g)
- Easy installation in tight or limited spaces
- Low moment of inertia
- Power supply: 5VDC ±5%





[Axial cable type]

[Radial cable type]

Applications

• Suitable for office machine such as ATMs, bill counting machines, copy machines





※Except for No Amp. output type.

Ordering Information

E18S	2.5	_ 200 -	- 1 -	- N	- 5	- R
Series	Shaft diameter	Pulses/revolution	Output phase	Control output	Power supply	Cable
, ,	2: Ø2mm 2.5: Ø2.5mm	100, 200, 300, 400	1: A	N: NPN open collector output V: Voltage output		R: Axial cable type S: Radial cable type
, ,	2: Ø2mm 2.5: Ø2.5mm	200, 300	1: A	A: No Amp.	5: 5VDC ±5%	R: Axial cable type S: Radial cable type

(A) Photoelectric Sensors

SENSORS

CONTROLLERS

MOTION DEVICES

SOFTWARE

(B) Fiber Optic Sensors

(C) LiDAR

(D) Door/Area Sensors

(E) Vision Sensors

(F) Proximity Sensors

(G) Pressure Sensors

> H) lotary incoders

(I)
Connectors/
Connector Cables
Sensor Distributio

Autonics H-13

Shaft Type Ø18mm Incremental Rotary Encoder [NPN open collector/Voltage output]

Specifications

Item			Ø18mm shaft type of Incremental Rotary Encoder	
Resolution (PPR) ^{×1}		%1	100, 200, 300, 400	
cification	Output phase		A phase	
	Control output	NPN open collector output	Load current: max. 30mA, residual voltage: max. 0.4VDC==	
		Voltage output	Load current: max. 10mA, residual voltage: max. 0.4VDC	
	Response time	NPN open collector output	_Max. 1μs (cable length: 1m, I sink = 20mA)	
sbe	(rise/fall)	Voltage output		
gal	Max. response frequency		25kHz	
ctri	Power supply		5VDC== ±5% (ripple P-P: max. 5%)	
Ee	Current consumption		Max. 50mA (disconnection of the load)	
	Insulation resistance		Over 100MΩ (at 500VDC megger between all terminals and case)	
	Dielectric strength		500VAC 50/60Hz for 1 min (between all terminals and case)	
	Connection		Axial cable type, radial cable type	
io la	Starting torque		Max. 10gf·cm (9.8×10 ⁻⁴ N·m)	
Mechanical specification	Moment of	inertia	Max. 0.5g·cm² (5×10 ⁻⁸ kg·m²)	
ech ecif	Shaft loading		Radial: max. 200gf, Thrust: max. 200gf	
ĕ	Max. allowable revolution ^{×2}		6,000rpm	
Vibrat	tion		1.5mm amplitude at frequency of 10 to 55Hz (for 1 min) in each X, Y, Z direction for 2 hours	
Shock	<		Approx. max. 50G	
- musica		Ambient temperature	-10 to 70°C, storage: -20 to 80°C	
EllAll	onment	Ambient humidity	35 to 85%RH, storage: 35 to 90%RH	
Protection structure		re	IP50 (IEC standard)	
Cable			Ø1.28mm, 3-wire, 150mm, Flat ribbon cable (AWG26, core diameter: 0.16mm, number of cores: 7, insulator diameter: Ø1.28mm)	
Accessory			Ø2mm coupling (supplied only for Ø2mm shaft diameter model)	
Appro	val		(€ e % us	
Weight ^{*3}			Ø2mm Shaft diameter model: approx. 35.4g (approx. 12g) Ø2.5mm Shaft diameter model: approx. 34.2g (approx. 12g)	

 $[\]normalfont{\mathbb{X}}$ 1: Not indicated resolutions are customizable.

 $[\text{Max. response revolution (rpm)=} \quad \frac{\text{Max. response frequency}}{\text{Resolution}} \times 60 \text{ sec}]$

H-14 Autonics

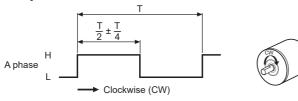
^{※2:} Make sure that max. response revolution should be lower than or equal to max. allowable revolution when selecting the resolution.

X3: The weight includes packaging. The weight in parenthesis is for unit only.

XEnvironment resistance is rated at no freezing or condensation.

Incremental Ø18mm Shaft Type

Output Waveform



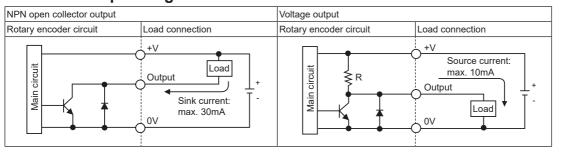
SENSORS

CONTROLLERS

MOTION DEVICES

SOFTWARE

Control Output Diagram



(A) Photoelectric Sensors

(B) Fiber Optic Sensors

(C) LiDAR

(D) Door/Area Sensors

> (E) Vision Sensors

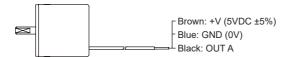
Proximity Sensors

(unit: mm)

Pressure Sensors

Sensor Distribution

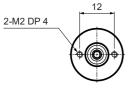
Connections

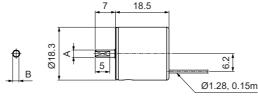


XDo not apply tensile strength over 10N to the cable.

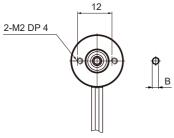
Dimensions

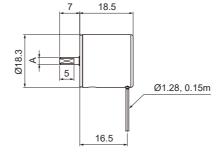
Axial cable type





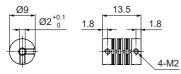
• Radial cable type





Model	Α	В
E18S2	$\emptyset 2.0^{-0.004}_{-0.02}$	1.7
E18S2.5	Ø2.5 ^{-0.004}	2.2

Coupling



- Parallel misalignment: max. 0.15mm
- Angular misalignment: max. 2°
- End-play: max. 0.2mm

XDo not load overweight on the shaft.

*Do not put strong impact when insert a coupling into shaft.

Failure to follow this instruction may result in product damage.

※Fix the unit or a coupling by a wrench under 0.15N·m of torque.

*When you install this unit, if eccentricity and deflection angle are larger,

it may shorten the life cycle of this unit.

**For parallel misalignment, angular misalignment, end-play terms, refer to the "Glossary" section of Technical Description. XFor flexible coupling (ERB series) information, refer to ERB series section

> H-15 **Autonics**

Shaft Type Ø18mm Incremental Rotary Encoder [No Amp. output]

Specifications

Item			Ø18mm shaft type of Incremental Rotary Encoder	
Resolution (PPR) ^{×1}		K1	200, 300	
Electrical specification	Output phase		A phase	
	Output waveform		Quasi-sinusoidal (No Amp.)	
	Output sign	al amplitude	Min. 150mV _{P-P}	
	Output amplitude variation		Max. 40%	
	Max. response frequency		10kHz	
rical	Power supp	ply	5VDC== ±5% (ripple P-P: max. 5%)	
lect	Insulation re	esistance	Over $100M\Omega$ (at $500VDC$ megger between all terminals and case)	
"	Dielectric st	trength	500VAC 50/60Hz for 1 min (between all terminals and case)	
	Connection		Axial cable type, radial cable type	
(0		Current flow	I _F : max. 50mA	
Optical elements specifications	LED	Reverse voltage	V _R : max. 5VDC==	
 - ifica		Current consumption	P _D : max. 95mW	
Optical s speci		Collector-Emitter voltage	V _{CEO} : max. 30VDC==	
Op of	Photo transistor	Emitter-Collector voltage	V _{ECO} : max. 5VDC==	
mer		Collector current	I _c : max. 20mA	
ele		Collector Current consumption	P _c : max. 75mW	
 u =	Starting tor	que	Max. 10gf⋅cm (9.8×10 ⁻⁴ N⋅m)	
Mechanical specification	Moment of	inertia	Max. 0.5g·cm² (5×10 ⁻⁸ kg·m²)	
ech	Shaft loading		Radial: max. 200gf, Thrust: max. 200gf	
≥ &	Max. allowable revolution ^{*2}		3,000rpm	
Vibrat	ion		1.5mm amplitude at frequency of 10 to 55Hz (for 1 min) in each of X, Y, Z directions for 2 hours	
Shock	Shock		Approx. max. 50G	
Envir	onment	Ambient temperature	-10 to 70°C, storage: -20 to 80°C	
Ellvild	ninent	Ambient humidity	35 to 85%RH, storage: 35 to 90%RH	
Protection structure		re	IP50 (IEC standard)	
Cable			Ø1mm, 4-wire, 150mm, Flat ribbon cable (AWG26, core diameter: 0.16mm, number of cores: 7, insulator diameter: Ø0.98mm)	
Acces			Ø2mm coupling (only for the Ø2mm shaft diameter model)	
Weigh	nt ^{**3}		Approx. 33.5g (approx. 10g)	
	at indicated	recelutions are sustamizable		

X1: Not indicated resolutions are customizable.

[Max. response revolution (rpm)= $\frac{\text{Max. response frequency}}{\text{Resolution}} \times 60 \text{ sec}]$

H-16 Autonics

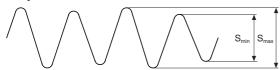
x2: Make sure that max. response revolution should be lower than or equal to max. allowable revolution when selecting the resolution.

X3: The weight includes packaging. The weight in parenthesis is for unit only.

^{*}Environment resistance is rated at no freezing or condensation.

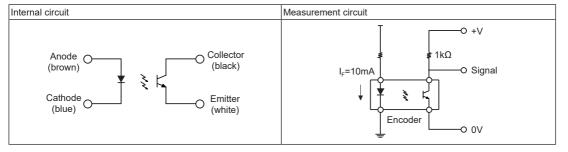
Incremental Ø18mm Shaft Type

Output Waveform

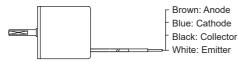


 XOutput signal amplitude: S_{min}≥150mV_{P-P} Output amplitude variation: (S_{max}/S_{min}-1)×100≤40%

Control Output Diagram



Connections



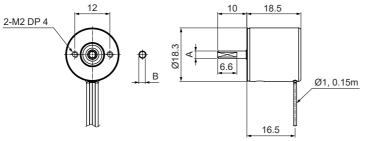
XDo not apply tensile strength over 10N to the cable.

Dimensions

Axial cable type

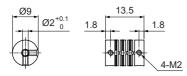
10 18.5 2-M2 DP 4 6.2 6.6 Ø1, 0.15m

Radial cable type



Model	A	В
E18S2	$\emptyset 2.0^{-0.01}_{-0.02}$	1.8 0
E18S2.5	Ø2.5 ^{-0.01} _{-0.02}	2.3_0

Coupling



- Parallel misalignment: max. 0.15mm
- Angular misalignment: max. 2°
- End-play: max. 0.2mm

XDo not load overweight on the shaft.

XDo not put strong impact when insert a coupling into shaft. Failure to follow this instruction may result in product damage.

*Fix the unit or a coupling by a wrench under 0.15N·m of torque.

*When you install this unit, if eccentricity and deflection angle are larger,

it may shorten the life cycle of this unit.

XFor parallel misalignment, angular misalignment, end-play terms, refer to the "Glossary" section of Technical Description. XFor flexible coupling (ERB series) information, refer to the ERB series section.

SENSORS

CONTROLLERS

MOTION DEVICES

SOFTWARE

(A) Photoelectric Sensors

(B) Fiber Optic Sensors

(C) LiDAR

(D) Door/Area Sensors

Vision Sensors

Proximity Sensors

Pressure Sensors

(unit: mm)

Sensor Distribution