Modbus Sensor Connector Type Digital Remote I/O

▣ Features

● Modbus RTU standard protocol
● Saving work time for wiring with sensor connector
  (CNE series, sold separately)
● Compact size
  : Small size with W26×L76×H54mm to install at narrow space
  : Available DIN Rail mounting and bolt mounting method
● Low-speed (16-bit/30CPS) counter function
● Real-time monitoring by various functions
  : Communication speed auto-recognition
  : Reading number of expansion units and specifications,
    Reading model name of basic and expansion units
  : Monitoring Single byte input/output, Multi byte input/output and status Flag
● Easy expansion
  : Available to connect up to 63 basic units per 1 master unit
  : Available to connect up to 7 expansion units per 1 basic units
    (controllable input/output for max. 64 points)
  : Combines the desired specifications of input/output by various input/output units
  : Organizes power and communication system by only communication cable lines
● High reliability
  : Built-in surge, short, over-heat, reverse power polarity and static prevention circuits

⚠ **Please read "Safety Considerations" in operation manual before using.**   C€

▣ Ordering Information

`AR` `M` — `D` `I` `08` `N` — `4S`

Terminal block	4S	Sensor connector type (4-pin socket)
I/O specifications	N	NPN open collector
	P	PNP open collector
I/O points	08	8 points type
I/O type	I	Input type
	O	Output type
Digital/Analog	D	Digital type
Network	M	Basic unit (Modbus RTU)
	X	Expansion unit (DeviceNet/Modbus)
Item	AR	Autonics Remote I/O

▣ Models

Models		Specification
Basic unit	Expansion unit	
ARM-DI08N-4S	ARX-DI08N-4S	10-28VDC NPN input 8-point, low-speed counter (10mA/point)
ARM-DI08P-4S	ARX-DI08P-4S	10-28VDC PNP input 8-point, low-speed counter (10mA/point)
ARM-DO08N-4S※	ARX-DO08N-4S※	10-28VDC NPN output 8-point, low-speed counter (0.3mA/point)
ARM-DO08P-4S※	ARX-DO08P-4S※	10-28VDC PNP output 8-point, low-speed counter (0.3mA/point)

※Low speed counter of digital output type is available only when using with digital input type.

▣ Manual

For the detail information and instructions of communication setting and Modbus mapping table, please refer to user manual for communication, and be sure to follow cautions written in the technical descriptions (catalog, homepage). Visit our homepage (www.autonics.com) to download manuals.

ARM Series

▣ Specifications

Model	Basic unit	ARM-DI08N-4S	ARM-DI08P-4S	ARM-DO08N-4S	ARM-DO08P-4S
	Expansion unit	ARX-DI08N-4S	ARX-DI08P-4S	ARX-DO08N-4S	ARX-DO08P-4S
Power supply		Rated voltage: 24VDC⎓, Voltage range: 12-28VDC⎓			
Power consumption		Max. 3W			
I/O points		NPN input 8-point	PNP input 8-point	NPN output 8-point	PNP output 8-point
Control I/O	Voltage	10-28VDC⎓ input		10-28VDC⎓ output (voltage drop: max. 0.5VDC⎓)	
	Current	10mA/point (sensor current: 150mA/points)		0.3A/point (leakage current: max. 0.5mA)	
	Common	8 points, Common			
Special function (input)		Counter for 16-bit (30CPS[1]) (only when using digital input unit of ARM, ARX)			
Communication speed[2]		2400, 4800, 9600, 19200, 38400, 57600, 115200bps (default: 9600bps)			
Communication method		2-wire half duplex			
Communication distance		Max. 800m			
Multi-drop		Max. 32 multi-drop			
Medium access		POLL			
Application standard		Compliance with EIA RS485			
Protocol		Modbus RTU			
Data bit		8-bit			
Stop bit		1-bit or 2-bit (default: 2-bit)			
Parity bit		None/Odd/Even (default: none)			
Isolation method		I/O and inner circuit: photocoupler insulation Modbus to internal bus and inner circuit: insulation Unit power: non-insulation			
Insulation resistance		Over 200MΩ (at 500VDC megger)			
Noise immunity		±240V the square wave noise (pulse width: 1us) by the noise simulator			
Dielectric strength		1,000VAC 50/60Hz for 1 minute			
Vibration		1.5mm amplitude at frequency of 10 to 55Hz (for 1 min) in each X, Y, Z direction for 2 hours			
Shock		500m/s^2 (approx. 50G) in each X, Y, Z direction for 3 times			
Environment	Ambient temp.	-10 to 55℃, storage: -25 to 75℃			
	Ambient humi.	35 to 85%RH, storage: 35 to 85%RH			
Protection structure		IP20 (IEC standards)			
Protection circuit		Surge, short-circuit, overheat (over 165℃) and ESD protection, reversed polarity protection circuit			
		Over current protection circuit (operated at min. 0.17A)		Over current protection circuit (operated at min. 0.7A)	
Indicator		Network status (NS) LED (green, red), unit status (MS) LED (green, red) I/O status LED (input: green, output: red)			
Material		Front case, body case: Polycarbonate			
Mounting		DIN rail or bolt mounting type			
Approval		C€			
Weight [3]	Basic	Approx. 123.3g (approx. 61.8g)	Approx. 123.3g (approx. 61.8g)	Approx. 123.3g (approx. 61.8g)	Approx. 123.3g (approx. 61.8g)
	Expansion	Approx. 117.5g (approx. 56g)	Approx. 118.5g (approx. 57g)	Approx. 119.5g (approx. 58g)	Approx. 120.5g (approx. 59g)

※1: CPS (counter per second): Specification of accepting external signals per second
※2: The communication speed is automatically set to the communication speed of the Master (PC, PLC, etc.).
　　When changing the communication speed during operation, the network status (NS) LED flashes in red and communication is not possible.
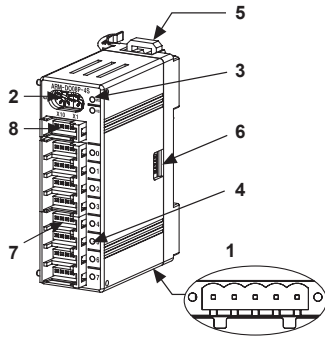※3: The weight includes packaging. The weight in parenthesis is for unit only.
※Environment resistance is rated at no freezing or condensation.

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Modbus Digital Remote I/O

■ Unit Descriptions

◎ Basic unit

1. Network connector

No.	For	Organization
5	24VDC (+)	5: 24VDC
4	GND	4: GND
3	N·C	3: N·C
2	B (-)	2: B (-)
1	A (+)	1: A (+)

2. Rotary switch for address: Rotary switch for setting the address ×10 represents tens digit and ×1 represents ones digit.
3. Status LED: It displays the status of unit (MS) and network (NS).
4. I/O status LED: It displays each I/O status.
5. Rail lock: It is used for mounting DIN rail or with bolts.
6. Connector output part: It connects an expansion unit.
7. Sensor connector: It is used for connecting external device I/O.
8. External power connector: It is used for supplying external power.

◎ Expansion unit
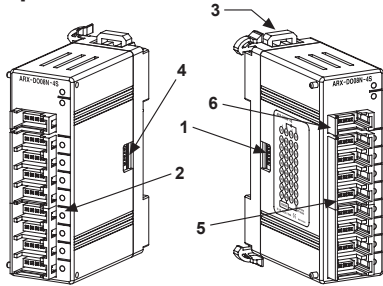
1. Connector input part: It connects expansion unit and is joined into the expansion connector output.
2. I/O status LED: It displays each I/O status.
3. Rail lock: It is used for mounting DIN rail or with bolts.
4. Connector output part: It connects an expansion unit.
5. Sensor connector: It is used for connecting external device I/O.
6. External power connector: It is used for supplying external power.

■ Status LED

(☼: ON, ☀: Flash, ●: OFF)

Item	LED status Red	LED status Green	Description
Unit status (MS) LED	☼	●	Error of expansion units
	☀	●	Error of MAC ID
	●	☼	Normal operation
	●	●	Power is not supplied
Network status (NS) LED	☼	●	Not supported communication speed (at auto baud rate)
	☀	●	Error of packet
	●	☼	Normal communication
	●	☀	Communication standby

ARM Series

▣ I/O Circuit Diagram

Type	Network connector	Inner circuit	Sensor connector
NPN input	A B SHIELD 24VDC GND	Internal circuits	VDC NC GND NC VDC NC GND IN0 VDC NC GND IN1
PNP input	A B SHIELD 24VDC GND	Internal circuits	VDC NC GND IN0 VDC NC GND IN1 VDC NC GND NC
NPN output	A B SHIELD 24VDC GND	Internal circuits	VDC NC GND NC VDC NC NC OUT0 VDC NC NC OUT1
PNP output	A B SHIELD 24VDC GND	Internal circuits	VDC NC GND NC NC NC GND OUT0 NC NC GND OUT1

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Modbus Digital Remote I/O

(A)
Photoelectric
Sensors

(B)
Fiber
Optic
Sensors

(C)
Door/Area
Sensors

(D)
Proximity
Sensors

(E)
Pressure
Sensors

(F)
Rotary
Encoders

(G)
Connectors/
Connector Cables/
Sensor Distribution
Boxes/ Sockets

(H)
Temperature
Controllers

(I)
SSRs / Power
Controllers

(J)
Counters

(K)
Timers

(L)
Panel
Meters

(M)
Tacho /
Speed / Pulse
Meters

(N)
Display
Units

(O)
Sensor
Controllers

(P)
Switching
Mode Power
Supplies

(Q)
Stepper Motors
& Drivers
& Controllers

(R)
Graphic/
Logic
Panels

(S)
Field
Network
Devices

(T)
Software

■ Connections

※When wiring the communication connector, use AWG20 cable and tighten the connector screw with a tightening torque of 0.5N.m.

● **ARM-DI08N-4S**   ● **ARM-DI08P-4S**   ● **ARM-DO08N-4S**   ● **ARM-DO08P-4S**
● **ARX-DI08N-4S**   ● **ARX-DI08P-4S**   ● **ARX-DO08N-4S**   ● **ARX-DO08P-4S**
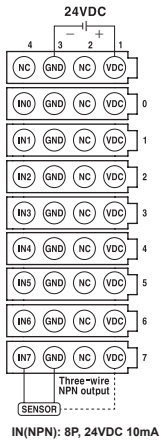
IN(NPN): 8P, 24VDC 10mA   IN(PNP): 8P, 24VDC 10mA   OUT(NPN): 8P, 24VDC 0.3A/Point   OUT(PNP): 8P, 24VDC 0.3A/Point
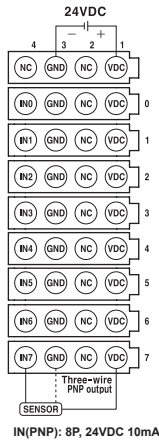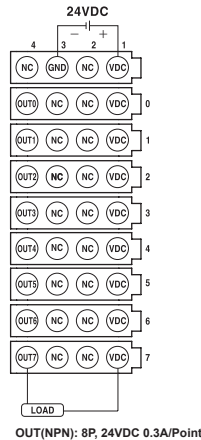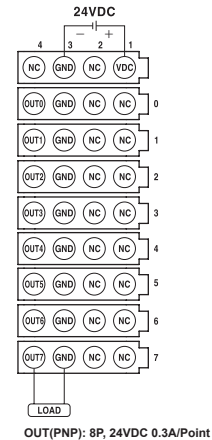
■ Terminating Resistance

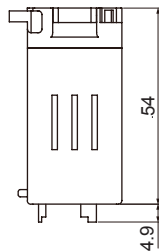● 120Ω   ● 1% of metallic film   ● 1/4W
※Connect terminating resistances on the both ends of the network cables. If not connecting terminating resistances, impedance can be too high or low. It may cause network problems.
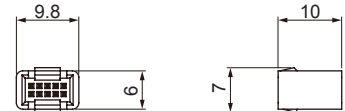
■ Dimensions

※Same dimensions are applied to both basic and expansion unit.
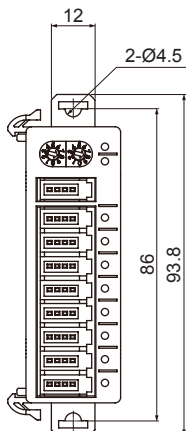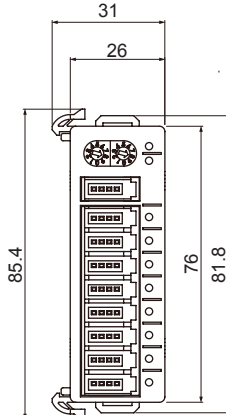※Tightening torque for mounting bolts: 1.8 to 2.5N·m

(unit:mm)

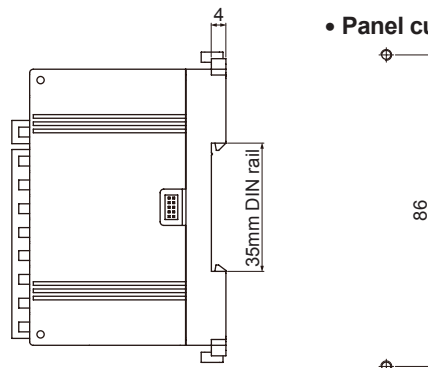
● **Expansion connector**
(supplied only for expansion unit)

● **Rail lock position: mounting with bolt**
● **Rail lock position: mounting on DIN rail**

● **Panel cut-out**

ARM Series

◼ Setup and Installation

◎ Setting node address

-Setting address is able to be done by rotary switch for address, or by in the EEPROM.

-If the rotary switch for address' number is "00", the address is available to set by in the EEPROM.
 The others, the desired number of rotary switch is that address.

- The address of the connected unit must not be duplicated.
  When changing the address during operation, the unit status (MS) LED flashes in red and the unit communicates to the address before the change.

● By rotary switch for address

① Two rotary switches are used for setting address. The X10 switch represents tens digit and the X1 switch represents ones digit. The address can be set 01 to 99.

②After setting the desired address, re-supply the unit power for applying the changed address.

(E.g.)
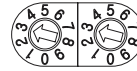
X10   X1

The X10 and X1 switches point both at "3", the address is "33".

● By in the EEPROM for address

①During communicate status with master system (PLC or PL), set the desired address on the 41029 EEPROM MAC ID parameter.

②The set address is changed after unit power is supplied. Re-supply the unit power for applying the changed address.

◎ Unit Installation

● Mounting on panel

① Pull two Rail locks on the rear part of a unit, there is a fixing bolt hole.

② Place unit on a panel to be mounted.

③ Make a hole on a fixing bolt hole position.

④ Fasten the bolt to fix the unit tightly. Please set the tightening torque under 0.5N·m.

● Mounting on DIN rail

①Pull two Rail locks on the rear part of a unit.

②Place the unit on DIN rail to be mounted.

③Press Rail locks to fix the unit tightly.

● Connection of basic and expansion units

① Turn OFF the power of a basic unit.

② Remove the cover of connector for extension with nippers.

③ Connect connector input part of an expansion unit and connector output part of a basic unit with the connector which is enclosed with an expansion unit box.

④ Connected expansion units are installed as the right figure.

⑤ Supply power to the basic unit.

※Re-supply power to the basic unit, and it recognizes expansion units.

◼ Cautions during Use

1. Follow instructions in 'Cautions during Use'. Otherwise, it may cause unexpected accidents.
2. 24VDC power supply should be insulated and limited voltage/current or Class 2, SELV power supply device.
3. Use only designated connector and do not apply excessive power when connecting or disconnecting the connectors.
4. Keep away from high voltage lines or power lines to prevent inductive noise.In case installing power line and input signal line closely, use line filter or varistor at power line and shielded wire at input signal line.Do not use near the equipment which generates strong magnetic force or high frequency noise.
5. Do not connect or disconnect the expansion unit when power is being supplied.
6. This unit may be used in the following environments.
   ①Indoors (in the environment condition rated in 'Specifications')
   ②Altitude max. 2,000m
   ③Pollution degree 2
   ④Installation category II

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