Ø18mm Incremental Rotary Encoder

Features

- Ultra-compact (Ø18mm) and ultra-lightweight (12g/10g)
- Easy installation in tight or limited spaces
- Low moment of inertia
- Power supply: 5VDC ±5%



[Axial cable type]

[Radial cable type]

Applications

• Suitable for office machine such as ATMs, bill counting machines, copy machines





Ordering Information

E18S	2.5	- 200 -	- 1 -	- N	- 5	- R
Series	Shaft diameter	Pulses/revolution	Output phase	Control output	Power supply	Cable
,	2: Ø2mm 2.5: Ø2.5mm	100, 200, 300, 400	11. Δ	N: NPN open collector output V: Voltage output		R: Axial cable type S: Radial cable type
,	2: Ø2mm 2.5: Ø2.5mm	200, 300	1: A	A: No Amp.		R: Axial cable type S: Radial cable type

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Incremental Ø18mm Shaft Type

Shaft Type Ø18mm Incremental Rotary Encoder

Specifications

Item			Ø18mm shaft type of Incremental Rotary Encoder	
Resolution (PPR) ^{*1}		X 1	100, 200, 300, 400	
	Output phase		A phase	
ctrical specifi	Control	NPN open collector output	Load current: max. 30mA, residual voltage: max. 0.4VDC	
	output	Voltage output	Load current: max. 10mA, residual voltage: max. 0.4VDC==	
	time	NPN open collector output	Max. 1μs (cable length: 1m, I sink = 20mA)	
	(rise/fall)	Voltage output		
	Max. response frequency		25kHz	
	Power supply		5VDC== ±5% (ripple P-P: max. 5%)	
	Current consumption		Max. 50mA (disconnection of the load)	
	Insulation resistance		Over 100MΩ (at 500VDC megger between all terminals and case)	
	Dielectric strength		500VAC 50/60Hz for 1 min (between all terminals and case)	
	Connection		Axial cable type, radial cable type	
on sa	Starting torque		Max. 10gf·cm (9.8×10 ⁻⁴ N·m)	
Mechanical specification	Moment of inertia		Max. 0.5g·cm² (5×10 ⁻⁸ kg·m²)	
Sciff	Shaft loadi	ng	Radial: max. 200gf, Thrust: max. 200gf	
Spe	Max. allowable revolution*2		6,000rpm	
Vibration			1.5mm amplitude at frequency of 10 to 55Hz (for 1 min) in each X, Y, Z direction for 2 hours	
Shock	<		Approx. max. 50G	
F		Ambient temperature	-10 to 70°C, storage: -20 to 80°C	
Enviro	onment	Ambient humidity	35 to 85%RH, storage: 35 to 90%RH	
Protection structure		ire	IP50 (IEC standard)	
Cable			Ø1.28mm, 3-wire, 150mm, Flat ribbon cable (AWG26, core diameter: 0.16mm, number of cores: 7, insulator diameter: Ø1.28mm)	
Accessory			Ø2mm coupling (supplied only for Ø2mm shaft diameter model)	
Approval			(€, 347, 5)	
Weight ^{*3}			Ø2mm Shaft diameter model: approx. 35.4g (approx. 12g) Ø2.5mm Shaft diameter model: approx. 34.2g (approx. 12g)	

X1: Not indicated resolutions are customizable.

[Max. response revolution (rpm)= Max. response frequency Resolution × 60 sec]

(A) Photoelectric Sensors

(B) Fiber Optic

(C) Door/Area Sensors

(D) Proximity Sensors

(E) Pressure Sensors

(F) Rotary Encoders

(G) Connectors/ Connector Cables/ Sensor Distribution Boxes/Sockets

(H) Temperature Controllers

(I) SSRs / Power Controllers

(J) Counters

> K) Timers

(L) Panel Meters

(M) Tacho / Speed / Pulse Meters

Meters (N)

Display Units

(O) Sensor Controllers

(P) Switching Mode Power Supplies

(Q) Stepper Motors & Drivers

(R) Graphic/ Logic Panels

> (S) Field Network Devices

(T) Software

Autonics F-9

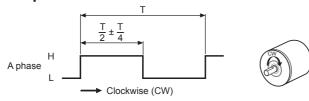
^{※2:} Make sure that max. response revolution should be lower than or equal to max. allowable revolution when selecting the resolution.

 $[\]times$ 3: The weight includes packaging. The weight in parenthesis is for unit only.

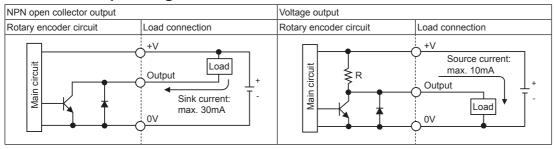
^{*}Environment resistance is rated at no freezing or condensation.

E18S Series

Output Waveform



Control Output Diagram



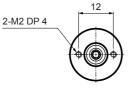
Connections



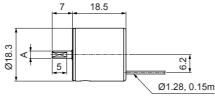
XDo not apply tensile strength over 10N to the cable.

Dimensions

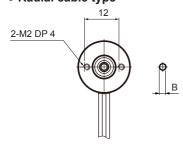


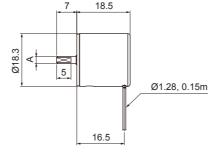






• Radial cable type

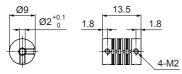




Model	А	В
E18S2	Ø2.0 ^{-0.004}	1.7
E18S2.5	Ø2.5 ^{-0.004}	2.2

(unit: mm)

Coupling



- Parallel misalignment: max. 0.15mm
- Angular misalignment: max. 2°
- End-play: max. 0.2mm

XDo not load overweight on the shaft.

*Do not put strong impact when insert a coupling into shaft.

Failure to follow this instruction may result in product damage.

*Fix the unit or a coupling by a wrench under 0.15 N·m of torque.

*When you install this unit, if eccentricity and deflection angle are larger,

it may shorten the life cycle of this unit.

*For parallel misalignment, angular misalignment, end-play terms, refer to page F-87.

XFor flexible coupling (ERB series) information, refer to page F-80.

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Incremental No Amp. output Type Ø18mm Shaft Type

Shaft Type No Amp. Output Type Ø18mm Incremental Rotary Encoder • Specifications

Item			Ø18mm shaft type of Incremental Rotary Encoder	(B Fi
	lution (PPR)	% 1	200, 300	O _I
11030	Output pha		A phase	(C
	Output waveform		Quasi-sinusoidal (No Amp.)	Se
ioi	Output signal amplitude		Min. 150mV _{P.P}	(D Pr
Electrical specification	Output signal amplitude Output amplitude variation		Max. 40%	Pr Se
	Max. response frequency		10kHz	
				(E Pr
ctric	Power supply		5VDC= ±5% (ripple P-P: max. 5%)	
E E	Insulation resistance		Over 100MΩ (at 500VDC megger between all terminals and case)	
	Dielectric strength		500VAC 50/60Hz for 1 min (between all terminals and case)	(F) Ro En
	Connection	1	Axial cable type, radial cable type	(G Co
o o	LED	Current flow	I _F : max. 50mA	Co Sei Bo
Optical elements specifications		Reverse voltage	V _R : max. 5VDC==	(H
		Current consumption	P _D : max. 95mW	Te
Optical s specif	Photo transistor	Collector-Emitter voltage	V _{CEO} : max. 30VDC	\neg
Op Its s		Emitter-Collector voltage	V _{ECO} : max. 5VDC==	(I) SS Cc
l ae		Collector current	I _c : max. 20mA	
ee		Collector Current consumption	P _c : max. 75mW	(J)
<u> </u>	Starting tor	que	Max. 10gf-cm (9.8×10 ⁻⁴ N·m)	$\exists \vdash$
Mechanical specification	Moment of inertia		Max. 0.5g·cm² (5×10 ⁻⁸ kg·m²)	(K Tii
echa	Shaft loadii	ng	Radial: max. 200gf, Thrust: max. 200gf	\neg
Σg	Max. allowable revolution**2		3,000rpm	(L)
Vibration			1.5mm amplitude at frequency of 10 to 55Hz (for 1 min) in each of X, Y, Z directions for 2 hours	Me (M
Shock			Approx. max. 50G	Ta Sp Me
Fi		Ambient temperature	-10 to 70°C, storage: -20 to 80°C	
Envir	onment	Ambient humidity	35 to 85%RH, storage: 35 to 90%RH	(N Di Ur
Prote	ction structu	re	IP50 (IEC standard)	
Cable	:		Ø1mm, 4-wire, 150mm, Flat ribbon cable (AWG26, core diameter: 0.16mm, number of cores: 7, insulator diameter: Ø0.98mm)	(O Se Cc
Acces	ssory		Ø2mm coupling (only for the Ø2mm shaft diameter model)	(P)
				- Cv

X1: Not indicated resolutions are customizable

Weight*3

Approx. 33.5g (approx. 10g)

X3: The weight includes packaging. The weight in parenthesis is for unit only.

*Environment resistance is rated at no freezing or condensation.

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(Q) Stepper Motor & Drivers

& Drivers & Controllers

(R) Graphic/ Logic Panels

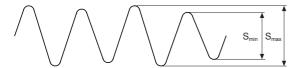
(S) Field Network Devices

(T) Software

Autonics F-11

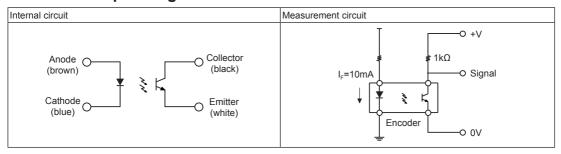
E18S Series

Output Waveform



%Output signal amplitude: $S_{min} \ge 150 mV_{P-P}$ Output amplitude variation: $(S_{max}/S_{min}-1) \times 100 \le 40\%$

Control Output Diagram



Connections

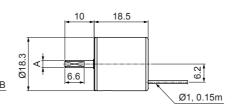


※Do not apply tensile strength over 10N to the cable.

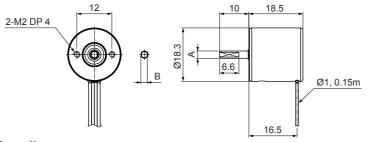
Dimensions

2-M2 DP 4

Axial cable type



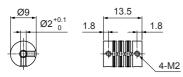
Radial cable type



Model	A	В
E18S2	$\emptyset 2.0^{-0.01}_{-0.02}$	1.8 0
E18S2.5	Ø2.5 ^{-0.01} _{-0.02}	2.3_0

(unit: mm)

Coupling



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