

High accuracy standard temperature controller

TK-XGT (RS485)

Technical Support Manual



Autonics

Preface

Thank you very much for selecting Autonics products.

Please familiarize yourself with the information contained in the **Safety Precautions** section before using this product.

This user manual contains information about the product and its proper use, and should be kept in a place where it will be easy to access.

Technical Support Manual Guide

- Please familiarize yourself with the information in this manual before using the product.
- This manual provides detailed information on the product's features. It does not offer any guarantee concerning matters beyond the scope of this manual.
- This manual may not be edited or reproduced in either part or whole without permission.
- This manual is not provided as part of the product package. Please visit our home-page (www.autonics.com) to download a copy.
- The manual's content may vary depending on changes to the product's software and other unforeseen developments within Autonics, and is subject to change without prior notice. Upgrade notice is provided through our homepage.
- We contrived to describe this manual more easily and correctly. However, if there are any corrections or questions, please notify us these on our homepage.

Technical Support Manual Symbols

Symbol	Description						
Note Supplementary information for a particular feature.							
Marning	Failure to follow instructions can result in serious injury or death.						
Caution Failure to follow instructions can lead to a minor injury or product							
Ex.	An example of the concerned feature's use.						
* 1	Annotation mark.						

Safety Precautions

Following these safety precautions will ensure the safe and proper use of the product and help prevent accidents, as well as minimizing possible hazards.

Safety precautions are categorized as Warnings and Cautions, as defined below:

Warning Warn	ing	Failure to follow the instructions may lead to a serious injury or accident.
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A Caution	Caution	Failure to follow the instructions may lead to a minor injury or accident.



Warning

■ Fail-safe device must be installed when using the unit with machinery that may cause serious injury or substantial economic loss. (e.g. nuclear power control, medical equipment, ships, vehicles, railways, aircraft, combustion apparatus, safety equipment, crime/disaster prevention devices, etc.)

Failure to follow this instruction may result in personal injury, fire, or economic loss.

- The unit must be installed on a device panel before use.
 - Failure to follow this instruction may result in electric shock.
- Do not connect, repair, or inspect the unit while connected to a power source.
 - Failure to follow this instruction may result in electric shock.
- Check the input power specifications and terminal polarity for correct connecting the power source.
 - Failure to follow this instruction may result in fire.
- Do not disassemble or modify the unit. Please contact us if necessary.
 Failure to follow this instruction may result in electric shock or fire.



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- Do not use the unit outdoors.
 - Failure to follow this instruction may result in shortening the life cycle of the unit, or electric shock.
- When connecting the power input and relay output cables, use AWG20 (0.5mm²) cables. Failure to follow this instruction may result in fire due to contact failure.
- Use the unit within the rated specifications.
 - Failure to follow this instruction may result in shortening the life cycle of the unit, or fire.
- Do not use loads beyond the rated switching capacity of the relay contact.
 - Do not use water or oil-based detergent when cleaning the unit. Use dry cloth to clean the unit.
- Do not use water or oil-based detergent when cleaning the unit. Use dry cloth to clean the unit.
 - Failure to follow this instruction may result in electric shock or fire.
- Do not use the unit where flammable or explosive gas, humidity, direct sunlight, radiant heat, vibration, or impact may be present.
 - Failure to follow this instruction may result in fire or explosion.
- Keep dust and wire residue from flowing into the unit.
 - Failure to follow this instruction may result in fire or product damage.

- Check the polarity of the measurement input contact before wiring the temperature sensor. Failure to follow this instruction may result in fire or explosion.
- For installing the unit with reinforced insulation, use the power supply unit which basic level is ensured.

Safety Precautions Autonics

Table of Contents

Preta	ace	3
Tech	nnical Support Manual Guide	4
Tech	nnical Support Manual Symbols	5
Safe	ety Precautions	6
Table	e of Contents	9
Sys	tem	11
1.3	Communication cable connection	11
TK4	IM Communication Setting	12
2.1	TK4M Setting	12
2.2	XG5000 Setting	13
Ope	eration Check	22
	Tech Tech Safe Tabl Sys 1.1 1.2 1.3 TK4 2.1 2.2	Technical Support Manual Guide Technical Support Manual Symbols Safety Precautions Table of Contents System 1.1 Version 1.2 Connections 1.3 Communication cable connection TK4M Communication Setting 2.1 TK4M Setting 2.2 XG5000 Setting Operation Check

Table of Contents

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Autonics 1 System

1 System

1.1 Version

Software	Version	Note		
Operating system	Windows 7	_		
XG 5000	V4.07	Release : 2016.03.29		

1.2 Connections



1.3 Communication cable connection

TK	Cable	PLC (XGT – XGL-CH2A)
DC 405 ()		RX -
RS – 485 (-)		RX +
DC 405 (1)		TX -
RS – 485 (+)		TX +

2 TK4M Communication Setting

2.1 TK4M Setting

1st Supply power to the TK unit. Press the MODE key to enter parameter setting group.

2nd Enter PR-4 and set the communication settings as below.

Parameter	Display	Setting	Note
Communication address	Adr5	01	User setting
Communication speed	6P5	384	User setting
Communication parity bit	Prty	nonE	Fixed
Communication stop bit	SEP	2	Fixed
Communication response waiting time	r5 <u>%</u> E	20	User setting
Communication write	Coun	En.A	Fixed

^{*} Hold the MODE key over 3 sec while in setting mode to return to RUN mode.

^{*} Hold the MODE key for 1.5 sec while in setting mode to move to other parameter group.

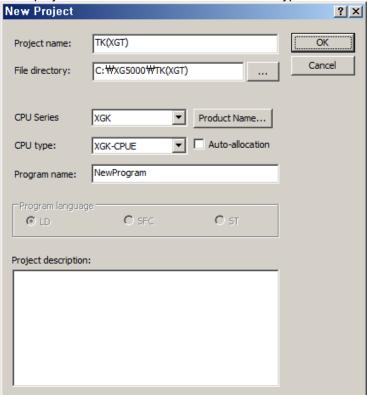
^{*} Press the MODE key after the setting and it is saved.

^{*} If there is no additional key operation within 30 sec after entering into setting mode, it will be automatically returned to RUN mode and previous set value will be remained.

^{*} Check that RS485 communication models are only available communication.

2.2 **XG5000 Setting**

1st Run XG5000, and select [Project] – [New Project] on menu. Enter project name and select CPU Series and type.



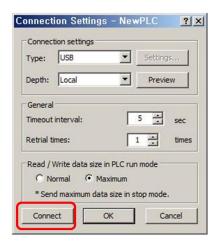
2nd After executing, enter the below contents at XG5000.

* This communication program is only for test. Before using it at field, review and test the program fully.

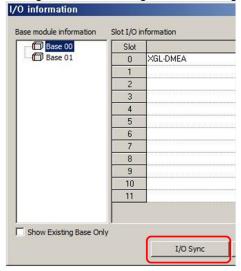


3rd Select [Online] – [Connection Settings] to select connection method. This test is connected via USB. After completing connection, select [Online] – [Mode Switch] – [Stop].

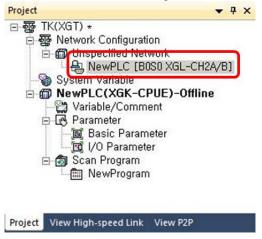
Connection settings	Settings
Туре	USB
Depth	Local



4th At [Online] – [Diagnose] – [I/O Information] , click 'I/O Sync'. After I/O synchronize, the settings are set as using module settings.

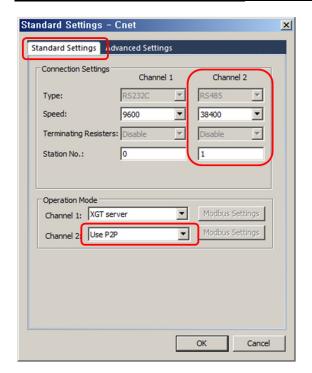


5th After I/O synchronize, you can check the added communication module below standard network. Double-click the right communication module.



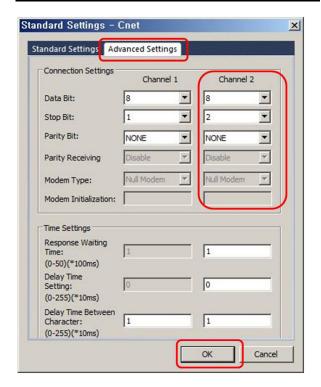
6th [Standard Settings-Cnet] dialog box appears. At standard settings, set as below.

Item		Setting	Note	
	Communication type	RS-485	Fixed	
Standard Settings Channel 2	Communication speed	38400	User setting	
	Terminating resisters	Disable	User setting	
	Station No.	1	User setting	
Operation mode	Channel 2	Use P2P		

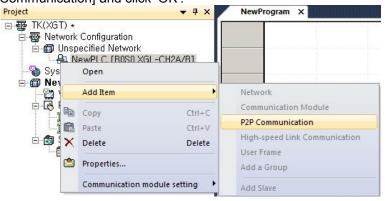


7th At advanced settings, set as below.

Item		Channel 2
	Data bit	8
Advanced settings	Stop bit	2
3.1.1	Parity bit	NONE

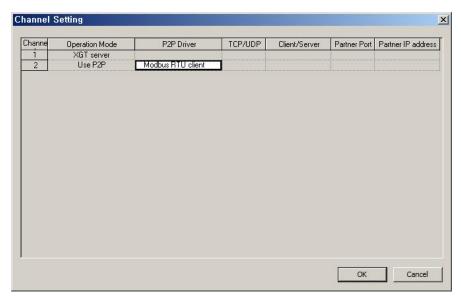


8th At Project window, select the communication module and [Add Item] – [P2P Communication] and click 'OK'.



9th Double-click 'P2P Channel' and select 'Modbus RTU client' of 'Use P2P'. Click 'OK'.





10thBelow P2P channel, double-click 'P2P block' and set as below.

Index	Ch	Driver Setting	P2P function	Conditional flag	Command type	Data type	No. of variables	Data size	Destina tion station	Destination station number	Frame	Setting	Variable setting contents
0	2	Modbus RTU client	READ	M01000	Single	WORD	1		F	1		Setting	Number:1 READ1:0x303E8,SAVE1:M0000
1	2	Modbus RTU client	READ	M01001	Single	WORD	1		Þ	2	PV	Setting	Number:1 READ1:0x303E8,SAVE1:M0001
2	2	Modbus RTU client	READ	M01002	Single	WORD	1		F	3	' '	Setting	Number:1 READ1:0x303E8,SAVE1:M0002
3	2	Modbus RTU client	READ	M01003	Single	WORD	1		F	4		Setting	Number:1 READ1:0x303E8,SAVE1:M0003
4	2	Modbus RTU client	WRITE	M01004	Single	WORD	1		F	1		Setting	Number:1 READ1:D00100,SAVE1:0x40000
5	2	Modbus RTU client	WRITE	M01005	Single	WORD	1		F	2	SV		Number:1 READ1:D00101,SAVE1:0x40000
6	2	Modbus RTU client	WRITE	M01006	Single	WORD	1		F	3		Setting	Number:1 READ1:D00102,SAVE1:0x40000
7	2	Modbus RTU client	WRITE	M01007	Single	WORD	1		P	4		Setting	Number:1 READ1:D00103,SAVE1:0x40000

СН	P2P function	Conditional flag	Command type	Data type	Destination station number
2	READ (PV)	M1000 to M1003	1. Single	WORD	Enter destination station (1 to 4).
2	WRITE (SV)	M1004 to M1007	1. Single	WORD	Enter destination station (1 to 4).

^{*} Refer to the below table for variable setting for PV and SV. Click 'Setting' to set variable.

* Modbus Mapping Table

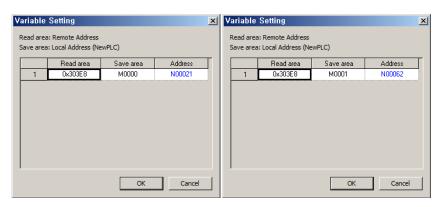
Address	Туре		Setting range	Factory default
301001 (03E8)	PV	Present value	1999 to 9999	-
400001 (0000)	sv	Setting value	Within L-Sv to H-Sv range	0

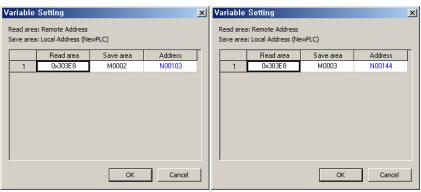
11th Variable settings

* PV setting

Station	Read area (setting)	Save area (setting)	Address (fixed)
Station 1	0x303E8	M0000	N00021
Station 2	0x303E8	M0001	N00062
Station 3	0x303E8	M0002	N00103
Station 4	0x303E8	M0003	N00144

Address	Туре	Note
301001 (03E8)	PV	Present value

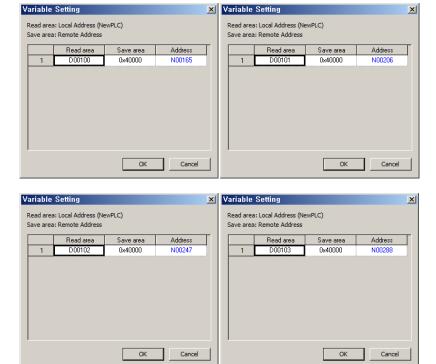




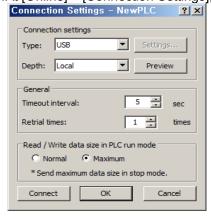
* SV setting

Station	Read area (setting)	Save area (setting)	Address (fixed)
Station 1	D00100	0x40000	N00165
Station 2	D00101	0x40000	N00206
Station 3	D00102	0x40000	N00247
Station 4	D00103	0x40000	N00288

Address	Туре	Note
400001 (0000)	SV	Setting value

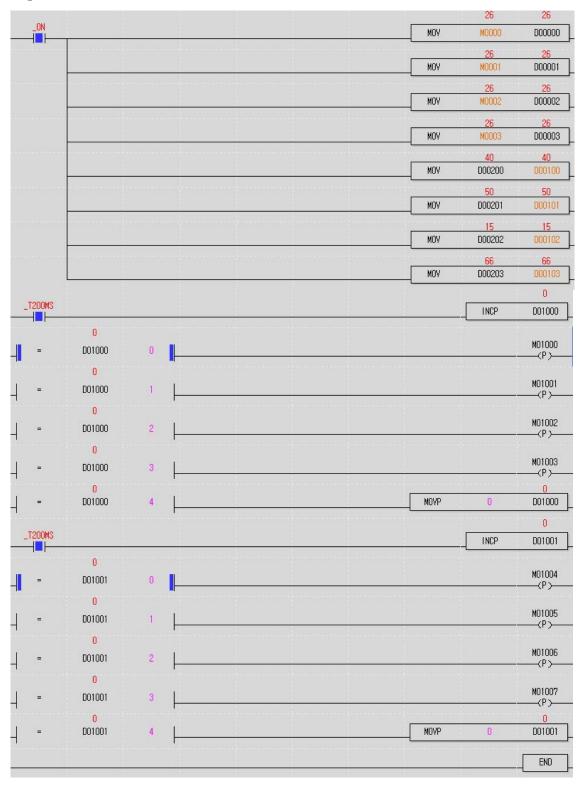


12thAt [Online] - [Connection Settings], select connection method between PC and PLC.



13th Select [Online] - [Write] to execute download.

3 Operation Check



D00000 to D00003 are present temperature values of station 1 to 4. D00100 to D00103 are setting values of station 1 to 4. You can change setting values to select D100 to 103.

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