

Warrick® Series 16DM Controls Installation and Operation Bulletin

This bulletin should be used by experienced personnel as a guide to the installation of series 16DM controls. Selection or installation of equipment should always be accompanied by competent technical assistance. We encourage you to contact Gems Sensors Inc. or its representative if further information is required.

Specifications	
Control Design:	Solid-State components enclosed in clear Lexan plug-in style housing. Housing carries no NEMA rating
Contact Design:	2 SPDT (2 form C): Two Normally Open (N.O.) and two Normally Closed (N.C.), non-powered contacts
Contact Ratings:	5 A @ 120, 240 VAC resistive, 1/8 H.P. @ 120 or 240 VAC
Contact Life:	Mechanical: 5 million operations - Electrical: 100,000 operations minimum at rated load
Supply Voltage	24, 120, or 240 VAC Models - Factory Set. Plus 10%, minus 15%, 50/60 Hz
Supply Current:	120, 240, 24 VAC, Relay energized 4.4 VA
Secondary	12 VAC RMS Voltage on probes. 1.5 milli-amp Current
Circuit:	Models operate from 0 to 1,000,000 OHM maximum
Sensitivity:	specific resistance - Factory set -40° To 150°F Ambient
Temperature:	All connections #6-32 screw type with pressure clamps
Terminals:	Standard, 0.5 seconds on rising level.
Time Delays:	Additional time delays on rising and/or falling level available as option.
Listings:	U.L. Listing, Industrial Motor Control (508). 240 and 208 volt units are not U.L. limit control recognized.

Installation

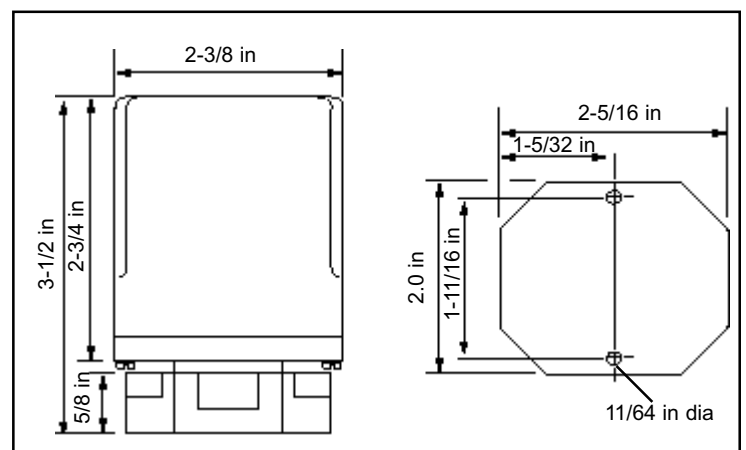
1. Install octal socket in appropriate enclosure using two #6 or #8 metal screws.
 - a) Install rail mount socket on appropriate rail (DIN mount) in appropriate enclosure, if applicable.
2. Wire control per wiring diagram, following N.E.C. and local codes.
3. Install control module in socket.

Sensitivities vs Maximum Probe Wire Distance*

Sensitivity Character	Sensitivity (K Ohms)	Distance (Ft.)
A or K	4.7	10,000
B or L	10	5,700
C or M	26	2,200
D or N	50	1,075
E or P	100	570
F or R	470	270
G or S	1,000	38

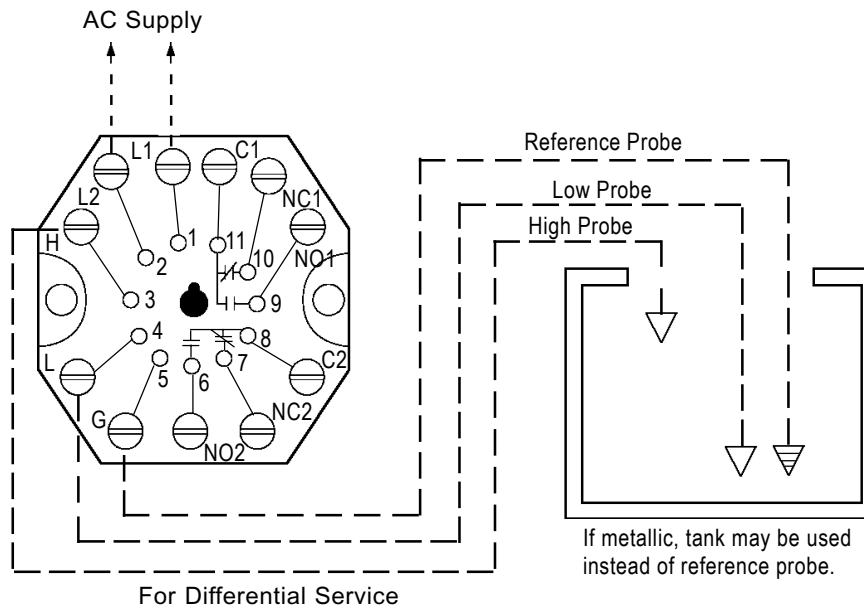
* Based on type MTW or THHN wire, #14 or #16 Awg

Dimensions



Use copper (60/70° C) wire only. Torque to 20 inch pounds.

Wiring Diagram



Note: For Single Level Service, use "H" and "G" Connections

Operation

Direct Mode - Single Level Service:

When the liquid rises to the electrode on terminal 3, the control energizes, changing state of the load contacts. **(LED will be lit)** The control remains energized until the liquid level recedes below electrode on terminal 3. The control then de-energizes, **(LED will not be lit)** returning load to original state.

Inverse Mode - Single Level Service:

Control energizes with power, changing state of the load contacts. **(LED will be lit)** When the liquid rises to the electrode on terminal 3, the control de-energizes, returning the load contacts to shelf state. **(LED will not be lit)** The control remains de-energized until liquid level recedes below the electrode connected to terminal 3. The control then energizes.

Direct Mode - Differential Service:

When the liquid rises to the electrode on terminal 3, the control energizes, changing state of the load contacts. **(LED will be lit)** The control remains energized until the liquid level recedes below electrode on terminal 4. The control then de-energizes, **(LED will not be lit)** returning the load contacts to original state.

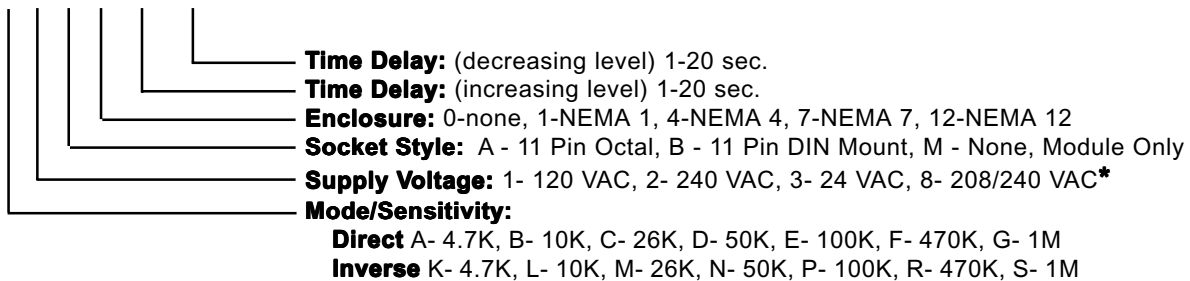
Inverse Mode - Differential Service:

Control energizes with power, **(LED will be lit)** changing state of the load contacts. When the liquid rises to the electrode on terminal 3, the control de-energizes, returning load contacts to shelf state. **(LED will not be lit)** The control remains de-energized until the liquid level recedes below the electrode on terminal 4. The control then energizes.

Optional

Time Delays: With time delay on increasing level, the liquid must be in contact with the short electrode for the full duration of the time delay before control will operate. With delay on decreasing level, the liquid must be below long electrode for the full duration of the time delay before control will operate. In single level service, terminals 3 and 4 must be jumpered together to achieve time delays on both increasing and decreasing levels or just decreasing level.

16DM X-X-X-X-XX-XX



*187 Vmin to 255 Vmax VAC



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