

Series 2200 Programmable DC Power Supplies

Reference Manual

2200S-901-01 Rev. D / May 2017



2200S-901-01D

Series 2200

Programmable DC Power Supplies

Reference Manual

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The following safety precautions should be observed before using this product and any associated instrumentation. Although some instruments and accessories would normally be used with nonhazardous voltages, there are situations where hazardous conditions may be present.

This product is intended for use by qualified personnel who recognize shock hazards and are familiar with the safety precautions required to avoid possible injury. Read and follow all installation, operation, and maintenance information carefully before using the product. Refer to the user documentation for complete product specifications.

If the product is used in a manner not specified, the protection provided by the product warranty may be impaired.

The types of product users are:

Responsible body is the individual or group responsible for the use and maintenance of equipment, for ensuring that the equipment is operated within its specifications and operating limits, and for ensuring that operators are adequately trained.

Operators use the product for its intended function. They must be trained in electrical safety procedures and proper use of the instrument. They must be protected from electric shock and contact with hazardous live circuits.

Maintenance personnel perform routine procedures on the product to keep it operating properly, for example, setting the line voltage or replacing consumable materials. Maintenance procedures are described in the user documentation. The procedures explicitly state if the operator may perform them. Otherwise, they should be performed only by service personnel.

Service personnel are trained to work on live circuits, perform safe installations, and repair products. Only properly trained service personnel may perform installation and service procedures.

Keithley Instruments products are designed for use with electrical signals that are measurement, control, and data I/O connections, with low transient overvoltages, and must not be directly connected to mains voltage or to voltage sources with high transient overvoltages. Measurement Category II (as referenced in IEC 60664) connections require protection for high transient overvoltages often associated with local AC mains connections. Certain Keithley Instruments measuring instruments may be connected to mains. These instruments will be marked as category II or higher.

Unless explicitly allowed in the specifications, operating manual, and instrument labels, do not connect any instrument to mains.

Exercise extreme caution when a shock hazard is present. Lethal voltage may be present on cable connector jacks or test fixtures. The American National Standards Institute (ANSI) states that a shock hazard exists when voltage levels greater than 30 V RMS, 42.4 V peak, or 60 VDC are present. A good safety practice is to expect that hazardous voltage is present in any unknown circuit before measuring.

Operators of this product must be protected from electric shock at all times. The responsible body must ensure that operators are prevented access and/or insulated from every connection point. In some cases, connections must be exposed to potential human contact. Product operators in these circumstances must be trained to protect themselves from the risk of electric shock. If the circuit is capable of operating at or above 1000 V, no conductive part of the circuit may be exposed.

Do not connect switching cards directly to unlimited power circuits. They are intended to be used with impedance-limited sources. NEVER connect switching cards directly to AC mains. When connecting sources to switching cards, install protective devices to limit fault current and voltage to the card.

Before operating an instrument, ensure that the line cord is connected to a properly-grounded power receptacle. Inspect the connecting cables, test leads, and jumpers for possible wear, cracks, or breaks before each use.

When installing equipment where access to the main power cord is restricted, such as rack mounting, a separate main input power disconnect device must be provided in close proximity to the equipment and within easy reach of the operator.

For maximum safety, do not touch the product, test cables, or any other instruments while power is applied to the circuit under test. ALWAYS remove power from the entire test system and discharge any capacitors before: connecting or disconnecting cables or jumpers, installing or removing switching cards, or making internal changes, such as installing or removing jumpers.

Do not touch any object that could provide a current path to the common side of the circuit under test or power line (earth) ground. Always make measurements with dry hands while standing on a dry, insulated surface capable of withstanding the voltage being measured.


For safety, instruments and accessories must be used in accordance with the operating instructions. If the instruments or accessories are used in a manner not specified in the operating instructions, the protection provided by the equipment may be impaired.


Do not exceed the maximum signal levels of the instruments and accessories. Maximum signal levels are defined in the specifications and operating information and shown on the instrument panels, test fixture panels, and switching cards.

When fuses are used in a product, replace with the same type and rating for continued protection against fire hazard.

Chassis connections must only be used as shield connections for measuring circuits, NOT as protective earth (safety ground) connections.

If you are using a test fixture, keep the lid closed while power is applied to the device under test. Safe operation requires the use of a lid interlock.


If a  screw is present, connect it to protective earth (safety ground) using the wire recommended in the user documentation.

The  symbol on an instrument means caution, risk of danger. The user must refer to the operating instructions located in the user documentation in all cases where the symbol is marked on the instrument.

The  symbol on an instrument means caution, risk of electric shock. Use standard safety precautions to avoid personal contact with these voltages.

The  symbol on an instrument shows that the surface may be hot. Avoid personal contact to prevent burns.

The  symbol indicates a connection terminal to the equipment frame.

If this  symbol is on a product, it indicates that mercury is present in the display lamp. Please note that the lamp must be properly disposed of according to federal, state, and local laws.

The **WARNING** heading in the user documentation explains dangers that might result in personal injury or death. Always read the associated information very carefully before performing the indicated procedure.

The **CAUTION** heading in the user documentation explains hazards that could damage the instrument. Such damage may invalidate the warranty.

Instrumentation and accessories shall not be connected to humans.

Before performing any maintenance, disconnect the line cord and all test cables.

To maintain protection from electric shock and fire, replacement components in mains circuits — including the power transformer, test leads, and input jacks — must be purchased from Keithley Instruments. Standard fuses with applicable national safety approvals may be used if the rating and type are the same. The detachable mains power cord provided with the instrument may only be replaced with a similarly rated power cord. Other components that are not safety-related may be purchased from other suppliers as long as they are equivalent to the original component (note that selected parts should be purchased only through Keithley Instruments to maintain accuracy and functionality of the product). If you are unsure about the applicability of a replacement component, call a Keithley Instruments office for information.

Unless otherwise noted in product-specific literature, Keithley Instruments instruments are designed to operate indoors only, in the following environment: Altitude at or below 2,000 m (6,562 ft); temperature 0 °C to 50 °C (32 °F to 122 °F); and pollution degree 1 or 2.

To clean an instrument, use a damp cloth or mild, water-based cleaner. Clean the exterior of the instrument only. Do not apply cleaner directly to the instrument or allow liquids to enter or spill on the instrument. Products that consist of a circuit board with no case or chassis (e.g., a data acquisition board for installation into a computer) should never require cleaning if handled according to instructions. If the board becomes contaminated and operation is affected, the board should be returned to the factory for proper cleaning/servicing.

Safety precaution revision as of March 2016.

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Introduction

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Welcome

Thank you for choosing a Keithley Instruments product. The Series 2200 Programmable DC Power Supplies provide a wide range of voltage outputs to address the testing and characterization of components, circuits, modules, and complete devices whether you are in a research laboratory, in design and development, or in production test. The Series 2200 consists of the following models with output voltages from 20 V to 72 V that can deliver 86 W, 96 W, 100 W, and 150 W of power. In addition, these power supplies can act as constant current sources as well as constant voltage sources. The Series 2200 power supplies offer an excellent combination of performance, versatility, and ease of use that allow you to obtain quality test data as quickly as possible. They perform as effectively in automated test systems as they do in manual instrument configurations.

- 2200-20-5
- 2200-30-5
- 2200-32-3
- 2200-60-2
- 2200-72-1
- 2220-30-1
- 2220G-30-1
- 2220J-30-1
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- 2230-30-1
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- 2230J-30-1
- 2230GJ-30-1

Extended warranty

Additional years of warranty coverage are available on many products. These valuable contracts protect you from unbudgeted service expenses and provide additional years of protection at a fraction of the price of a repair. Extended warranties are available on new and existing products. Contact your local Keithley Instruments office, sales partner, or distributor for details.

Contact information

If you have any questions after you review the information in this documentation, please contact your local Keithley Instruments office, sales partner, or distributor. You can also call the corporate headquarters of Keithley Instruments (toll-free inside the U.S. and Canada only) at 1-800-935-5595, or from outside the U.S. at +1-440-248-0400. For worldwide contact numbers, visit the [Keithley Instruments website](http://www.tek.com/keithley) (<http://www.tek.com/keithley>).

CD-ROM contents

A CD-ROM is shipped with each Series 2200 order.

The Series 2200 Product Information CD-ROM contains:

- **Reference Manual:** Includes advanced operation topics and maintenance information. Programmers looking for a command reference, and users looking for an in-depth description of the way the instrument works (including troubleshooting and optimization), should refer to the Reference Manual.
- **Drivers and release notes:** IVI Instrument Driver, driver for National Instruments LabVIEW™, and related release notes.
- **Additional product information:** The product specifications are also included on the CD-ROM.

For the latest drivers and additional support information, see the [Keithley Instruments website](http://www.tek.com/keithley) (<http://www.tek.com/keithley>).

Key features

The Series 2200 offers:

- Single-output, DC power
- Linear regulation
- 0.03 percent basic voltage accuracy
- 0.05 percent basic current accuracy
- Less than 1 mV RMS ripple and noise
- 40 user-defined setup memories
- USB 2.0 device port on rear panel for PC connectivity and remote programming
- IEEE-488.2 General Purpose Interface Bus (GPIB) interface for PC connectivity and remote programming

NOTE

Not every Model has a GPIB connection (see the next table).

| Model | Description |
|-------------|---|
| 2200-20-5 | Programmable DC power supply. 20 V, 5 A, 1 channel, USB, GPIB |
| 2200-30-5 | Programmable DC power supply. 30 V, 5 A, 1 channel, USB, GPIB |
| 2200-32-3 | Programmable DC power supply. 32 V, 3 A, 1 channel, USB, GPIB |
| 2200-60-2 | Programmable DC power supply. 60 V, 2.5 A, 1 channel, USB, GPIB |
| 2200-72-1 | Programmable DC power supply. 72 V, 1.2 A, 1 channel, USB, GPIB |
| 2220-30-1 | Programmable DC power supply. 30 V, 1.5 A, 2 channel, USB |
| 2220G-30-1 | Programmable DC power supply. 30 V, 1.5 A, 2 channel, USB, GPIB |
| 2220J-30-1 | Programmable DC power supply. 30 V, 1.5 A, 2 channel, USB, for Japan |
| 2220GJ-30-1 | Programmable DC power supply. 30 V, 1.5 A, 2 channel, USB, GPIB, for Japan |
| 2230-30-1 | Programmable DC power supply. 30 V, 1.5 A, 2 channel, USB includes a 6 V, 5 A channel for powering digital circuits |
| 2230G-30-1 | Programmable DC power supply. 30 V, 1.5 A, 2 channel, USB, GPIB includes a 6 V, 5 A channel for powering digital circuits |
| 2230J-30-1 | Programmable DC power supply. 30 V, 1.5 A, 2 channel, USB, for Japan includes a 6 V, 5 A channel for powering digital circuits |
| 2230GJ-30-1 | Programmable DC power supply. 30 V, 1.5 A, 2 channel, USB, GPIB, for Japan includes a 6 V, 5 A channel for powering digital circuits |

Standard accessories

| Accessory | Keithley part number |
|------------------------------|----------------------|
| Rear panel mating connector | 131984300 |
| Documentation and Driver CD | 2200S-950-01 |
| Certification of calibration | N/A |

Optional accessories

| Optional accessory | Keithley part number |
|--|----------------------|
| IEEE-488.2 Interface Board for the PCI Bus | KPCI-488LPA |
| USB Cable Type A to B 1m (3.2 ft) | USB-B-1 |
| USB Cable Type A to B 3m (10 ft) | USB-B-3 |
| Fixed Rack Mount Kit | 4299-7 |
| Double Shielded Premium IEEE-488 Interface Cables, 0.5m (1.6 ft) | 7007-05 |
| Double Shielded Premium IEEE-488 Interface Cables, 1m (3.2 ft) | 7007-1 |
| Double Shielded Premium IEEE-488 Interface Cables, 2m (6.5 ft) | 7007-2 |
| Double Shielded Premium IEEE-488 Interface Cables, 3m (10 ft) | 7007-3 |
| Double Shielded Premium IEEE-488 Interface Cables, 4m (13 ft) | 7007-4 |

Services available

| Services | Keithley part number |
|---|----------------------|
| 1-year factory warranty extended to 3 years from date of shipment | 2200-3Y-EW-STD |
| 3 calibrations within 3 years of purchase | C/2200-3Y-STD |
| 3 (ANSI-Z540-1 compliant) calibrations within 3 years of purchase | C/2200-3Y-DATA |

Specifications

This topic provides information about:

- Electrical ratings for the power connection
- Environmental performance
- Nominal voltage ratings
- Float voltage rating

For additional specifications, refer to Series 2200 Programmable DC Power Supplies Specifications (document number SPEC-2200S) on the Product Information CD-ROM that came with your Series 2200. For the latest version of the specifications, go to the [Keithley Instruments website](http://www.tek.com/keithley) <http://www.tek.com/keithley>.

Electrical ratings for the power connection

| Model | Line selector switch setting | Frequency | Fuse rating | Max power |
|-------------|------------------------------|------------|--|-----------|
| 2200-20-5 | 110 V / 220 V | 50 / 60 Hz | For 110 V: 5 A TH, 250 V For 220 V: 2.5 A TH, 250 V | 350 VA |
| 2200-30-5 | 110 V / 220 V | 50 / 60 Hz | For 110 V: 5 A TH, 250 V For 220 V: 2.5 A TH, 250 V | 500 VA |
| 2200-32-3 | 110 V / 220 V | 50 / 60 Hz | For 110 V: 5 A TH, 250 V For 220 V: 2.5 A TH, 250 V | 350 VA |
| 2200-60-2 | 110 V / 220 V | 50 / 60 Hz | For 110 V: 5 A TH, 250 V For 220 V: 2.5 A TH, 250 V | 500 VA |
| 2200-72-1 | 110 V / 220 V | 50 / 60 Hz | For 110 V: 5 A TH, 250 V For 220 V: 2.5 A TH, 250 V | 350 VA |
| 2220-30-1 | 110 V / 220 V | 50 / 60 Hz | For 110 V: 5 A TH, 250 V For 220 V: 2.5 A TH, 250 V | 500 VA |
| 2220G-30-1 | 110 V / 220 V | 50 / 60 Hz | For 110 V: 5 A TH, 250 V For 220 V: 2.5 A TH, 250 V | 500 VA |
| 2220J-30-1 | 110 V / 220 V | 50 / 60 Hz | For 110 V: 5 A TH, 250 V For 220 V: 2.5 A TH, 250 V | 500 VA |
| 2220GJ-30-1 | 110 V / 220 V | 50 / 60 Hz | For 110 V: 5 A TH, 250 V For 220 V: 2.5 A TH, 250 V | 500 VA |
| 2230-30-1 | 110 V / 220 V | 50 / 60 Hz | For 110 V: 5 A TH, 250 V For 220 V: 2.5 A TH, 250 V | 500 VA |
| 2230G-30-1 | 110 V / 220 V | 50 / 60 Hz | For 110 V: 5 A TH, 250 V For 220 V: 2.5 A TH, 250 V | 500 VA |
| 2230J-30-1 | 110 V / 220 V | 50 / 60 Hz | For 110 V: 5 A TH, 250 V For 220 V: 2.5 A TH, 250 V | 500 VA |
| 2230GJ-30-1 | 110 V / 220 V | 50 / 60 Hz | For 110 V: 5 A TH, 250 V For 220 V: 2.5 A TH, 250 V | 500 VA |

Environmental performance

| Parameter | |
|-------------|--|
| Temperature | Temperature Operating: +0 °C to +40 °C |
| Humidity | Operating: 5 percent to 95 percent relative humidity (percent RH) at up to 40 °C, non-condensing Pollution degree 2, For indoor use only. |
| Altitude | Operating: 100 percent capability up to 2,000 meters. |

Nominal voltage ratings

There are two ranges for all models, selectable by the line-voltage selector switch. Check the voltage select switch on the bottom of the power supply before turning it on:

- 110 V setting, 110 / 115 / 120 VAC
- 220 V setting, 220 / 230 / 240 VAC

Fluctuations must not exceed 10 percent of the nominal rated voltage.

Float voltage rating

Float voltage rating: up to 100 V (DC + peak AC) between earth ground and any output terminal.

General operation

In this section:

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Operating requirements

This section provides information about operating requirements for the Series 2200 instruments.

Observe all safety precautions listed in [Safety precautions](#) (on page 1-1) and in this topic before using the Series 2200 instruments and any associated instruments.

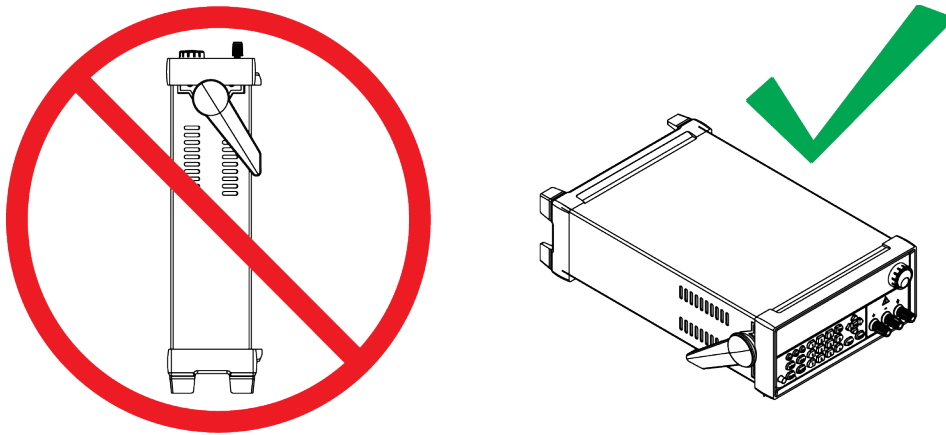
Read and follow all installation, operation, and maintenance information carefully before using the Series 2200 instruments.

Refer to the following sources for complete product specifications:

- [Specifications](#) (on page 1-4)
 - Series 2200 Programmable DC Power Supplies Specifications (document number SPEC-2200S) on the Product Information CD-ROM that came with your Series 2200. For the latest version of the specifications, go to the [Keithley Instruments website](http://www.tek.com/keithley) (<http://www.tek.com/keithley>).
1. Place the bottom of the instrument on a bench or similar surface. Do not stand the instrument on its rear panel. Refer to the following figure for an illustration of how to position the instrument.

WARNING

Do not stand the instrument on its rear panel. This position is unstable and the instrument might tip over and be damaged or fall on someone and cause injury. To avoid damage or bodily injury, place the bottom of the instrument flat on a stable surface.

Figure 1: Place bottom of instrument on flat stable surface

2. Before operating, ensure that the ambient temperature is between +0 °C and +40 °C (+32 °F to +104 °F).

⚠ WARNING

To ensure proper cooling, keep the front, sides, and rear of the instrument clear of obstructions.

⚠ WARNING

Use properly rated load wires. All load wires must be heavy enough not to overheat when carrying the maximum short-circuit output current of the power supply. If there is more than one load, then any pair of load wires must be capable of safely carrying the full-rated short-circuit output current of the power supply.

⚠ WARNING

To reduce risk of fire and shock, ensure the mains supply voltage fluctuations do not exceed 10% of the operating voltage range.

⚠ CAUTION

Do not loosen any screw on this product, except those in the rear connector, which are intended to retain attached external wires to the connector. There are no user serviceable components inside.

Installing the system

This section contains information on how to install your Model 2200 power supply.

- Unpack the instrument and check that you received all the items listed as standard accessories.
- Check that you also received any other accessories that you ordered with your instrument.

To verify that the power supply is ready to use, follow the procedures to:

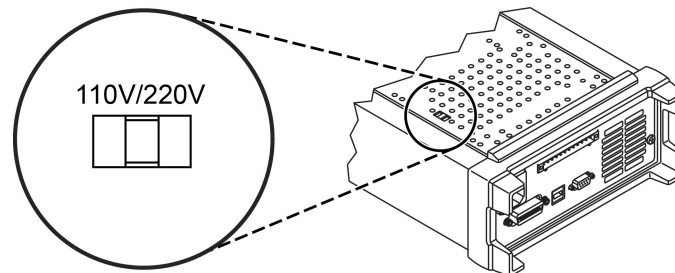
- [Power the instrument on and off](#) (on page 2-3)
- [Check the output](#) (on page 2-3)

Power the instrument on and off

To power on the instrument follow these steps:

1. Make all the connections.
2. Properly set the 110 V / 220 V selector switch located on the bottom of the instrument.

Figure 2: Selector switch



3. Connect the power cord that was provided with the instrument to the power connector on the rear panel. Connect the power cord plug to a properly grounded electrical outlet.
4. Press the power switch on the front panel.

To power off the instrument, press the power switch on the front panel.

⚠ WARNING

To satisfy safety requirements, always use load wires heavy enough not to overheat when carrying the maximum short-circuit output current of the power supply. If there is more than one load, then every pair of load wires must be capable of safely carrying the full-rated current of the power supply.

Check the output

The following procedures check that the power supply develops its rated outputs and properly responds to operation from the front panel.

Voltage output check

To verify basic voltage functions without a load, follow these steps.

1. Remove all leads from the output connectors.
2. Turn on the power supply.
3. Press **Shift** and **Menu (1)**. >Default Set shows on the display.
4. Press **Enter** to bring up the default settings options. No and Yes appear on the display.
5. Press the right arrow key to select **Yes**. Press **Enter** to enable the default settings.
6. Press the front-panel **On/Off key** to enable the output. The OFF message on the display turns off and the CV message on the display turns on. The upper line of the display shows the actual output voltage and current. The lower line shows the settings.
7. Check that the front-panel voltmeter properly responds to pressing keys on the numeric keypad. Press **V-set**, use the numeric keypad to set the voltage value to 0 and press **Enter**. Check if the displayed voltage value is approximately 0 V and check if the displayed current value is approximately 0 A. You can confirm the 0 V setting with a voltmeter.
8. Press **V-set** and use the numeric keys and **Enter** to set the voltage value to the maximum allowable for your power supply, as indicated on the instrument's front panel.
9. Check if the displayed voltage value is approximately the same value as the voltage setting.

Current output check

To verify the basic current functions with a short across the power supply output, follow these steps:

1. Remove all leads from the output connectors.
2. Turn on the power supply.
3. Press **Shift** and **Menu (1)**. >Default Set shows on the display.
4. Press **Enter** to bring up the default settings options. No and Yes appear on the display.
5. Press the right arrow key to select **Yes**. Press **Enter** to enable the default settings.
6. Ensure that the output is disabled and the display OFF message is turned on. If needed, press the **On/Off key** to ensure that the output is disabled and the OFF message is turned on.
7. Use an insulated test lead to connect a short across the (+) and (-) output terminals. Use a wire size sufficient to handle the maximum current. You should use at least a 22 gauge wire.

WARNING


To satisfy safety requirements, always use load wires heavy enough not to overheat when carrying the maximum short-circuit output current of the power supply. If there is more than one load, then every pair of load wires must be capable of safely carrying the full-rated current of the power supply.


8. Press the **On/Off key** to enable the output. The CC message should be lit.
9. Press **I-set** and use the numeric keypad and **Enter** key to set the current value to 0 A. Check if the displayed current value is approximately 0 A.
10. Press **I-set** and use the numeric keys and **Enter** to set the current value to the maximum allowable for your current supply. Check if the displayed current value is approximately the same value as the maximum allowable.
11. Turn off the power supply and remove the short wire from the (+) and (-) output terminals.

Operating basics

Front panel at a glance

The front panel of the Keithley Instruments Series 2200 contains the following items:

- Power switch
- Display
- Arrow keys
- The navigation wheel 
- Output connectors
- Keys
- Number keys

You can use the keys, display, and the navigation wheel  to access, view, and edit the configuration menu items and set values.

For additional information about the front panel, see the [Front panel operation](#) (on page 2-15) section.

The front panel of the Series 2200 is shown in the following figure.

Figure 3: Front panel



(1) Display

The display shows information.

(2) Information

During operation, the display provides information about the output (top row) and settings (bottom row) for volts (left column) and current (right column). During configuration, the display shows the configuration menus (bottom row).

(3) Arrow keys

Up, down, right, and left arrow keys (▲ and ▼) and Enter key.

(4) Navigation wheel

Rotate the navigation wheel ⦿ to increase or decrease digits or to select menu items.

(5) Output connectors

Three banana jack output connectors provide high, low, and chassis ground connections.

(6) Save and recall keys

See [Key descriptions](#) (on page 2-7) for descriptions of these keys.

(7) Numeric keypad

The numeric keypad provides number keys (0 to 9 and Esc) for direct numeric entry.

(8) V-Set, I-Set, Shift, and Output On/Off keys

See [Key descriptions](#) (on page 2-7) for descriptions of these keys.

(9) Power switch

Press the power switch to turn the instrument on (I). Press it again to turn the instrument off (O).



Key descriptions

The keys provide front panel control and configuration. See [Front panel at a glance](#) (on page 2-5) for an illustration of each key location. The following tables describe how to use each key.

Key descriptions

| Keys | Description |
|----------------------|---|
| V-set | Sets the voltage limit. See Setting the voltage limit (on page 2-17) for more information. |
| I-set | Sets the current limit. See Setting the current limit (on page 2-17) for more information. |
| Save | Saves the present settings to a specified setup memory location (1 to 40). See Save and recall setups (on page 2-18) for more information. |
| Recall | Recalls a saved setting from a specified setup memory location (1 to 40). See Save and recall setups (on page 2-18) for more information. |
| Shift | Used to access secondary functions of the numeric keys. For example, when the Shift key is used with the 1 key, the combination displays the configuration menu. See the following table for more information on Shift + numeric keypad descriptions. |
| Output On/Off | Turns on or off the output channel of the power supply. The regulation mode, constant voltage (CV) or constant current (CC), is shown on the display when the output is turned on. |
| Esc | Backs out of the selected function. If the instrument's focus is in a menu, pressing Esc will back up one menu level. |

Shift + numeric keypad descriptions

| Key | Numeric keypad | Description |
|--------------|----------------|--|
| Shift | 1 | Brings up the configuration menus. Turn the navigation wheel  or press the up or down keys to scroll through the list of menus. Press Enter to select which menu to use. |
| Shift | 2 | Brings up the list selection. Turn the navigation wheel  or press the up or down arrow keys to scroll through the various lists you can run. |
| Shift | 3 | Generates a manual trigger event. |
| Shift | 7 | Returns control from remote operation to local front panel control. This operation generates a return to local message. |

Keypad special operations



See the following table for the Series 2200 keypad special operations.

| Operation | Key press | | | | | | | | | | | | |
|---|---|-------|--------------|-----------|------|-----------|------|-----------|------|-----------|------|-----------|------|
| Display the instrument firmware version. | Shift + 8 | | | | | | | | | | | | |
| Display the internal temperature of the instrument. | Shift + . (decimal point) + 1 | | | | | | | | | | | | |
| Perform a factory reset. All setups and lists are erased. | Shift + . (decimal point) + 2 | | | | | | | | | | | | |
| Unlock the keypad. | If the instrument's keypad and front panel controls are locked, you will need a password to unlock them. If you forget the password, enter the appropriate default code for the model instrument you are using: | | | | | | | | | | | | |
| | <table border="1"> <thead> <tr> <th>Model</th> <th>Default code</th> </tr> </thead> <tbody> <tr> <td>2200-20-5</td> <td>4205</td> </tr> <tr> <td>2200-30-5</td> <td>4305</td> </tr> <tr> <td>2200-32-3</td> <td>4323</td> </tr> <tr> <td>2200-60-2</td> <td>4602</td> </tr> <tr> <td>2200-70-1</td> <td>4721</td> </tr> </tbody> </table> | Model | Default code | 2200-20-5 | 4205 | 2200-30-5 | 4305 | 2200-32-3 | 4323 | 2200-60-2 | 4602 | 2200-70-1 | 4721 |
| Model | Default code | | | | | | | | | | | | |
| 2200-20-5 | 4205 | | | | | | | | | | | | |
| 2200-30-5 | 4305 | | | | | | | | | | | | |
| 2200-32-3 | 4323 | | | | | | | | | | | | |
| 2200-60-2 | 4602 | | | | | | | | | | | | |
| 2200-70-1 | 4721 | | | | | | | | | | | | |
| | Cycling the instrument power also unlocks the keypad. | | | | | | | | | | | | |

Configuration menus description

Use the configuration menus to configure (setup) the instrument. Sometimes the configuration menus are called the settings menus. See the following table for information on the primary menu selections, secondary menu selections, options, and a brief description of each selection. The following table indicates default settings in **bold**.

| Primary menu | Secondary menu | First option | Additional option(s) | Allows you to ... |
|--------------|----------------|--------------|----------------------|--|
| >Default Set | | No | Yes | Return the instrument to the factory default configuration. See Initializing to the default setup (on page 2-17) for more information. |
| >Protect | >Reset Protect | No | Yes | Reset Protect menu selections to the factory default configuration. |
| | >Max Volt Set | Off | | Turn maximum output voltage setting off. |
| | | On | Max = | Set or edit maximum output voltage for the instrument. See Setting the maximum voltage (on page 2-18) for more information. |
| | >OVP Set | Off | | Turn overvoltage protection (OVP) off. |
| | | On | OVP = | Turn overvoltage protection on and set or edit the voltage threshold. See Setting the overvoltage protection (on page 2-19) for more information. |
| | >Out Time Set | Off | | Turn out time mode off. |
| | | On | Time = | Turn out time mode on and set or edit the time period. See Timer example (on page 2-30) for an example of setting a timer with Out Time Set. |
| | >Key Lock | Password = | unlock | Indicates that no password is set to lock all front panel controls except power switch and output on/off key. Enter up to 4 digits to set a password. |
| | | | Lck | Indicates that a password has been set. |
| >Edit List | >Recall 1-7 | Empty | | Recall or edit lists saved in up to 7 locations. Empty indicates no saved list. See Define a list of voltage and current steps (on page 2-24) for more information. |
| | | Continuous | Repeat = | Set instrument to continuous mode. If set, the instrument executes the entire sequence of steps as soon as it receives the next trigger signal. Repeat allows you to set or edit number of times to repeat the list. List Steps allows you to indicate the number of steps in the list. See List mode example (on page 2-30) for a list example. |
| | | Step | Repeat = | Set instrument to step mode. If set, |

| Primary menu | Secondary menu | First option | Additional option(s) | Allows you to ... |
|--------------|----------------|----------------|---|---|
| | | | | the instrument will advance to each step only after it receives a trigger signal. Repeat allows you to set or edit number of steps. List Steps allows you to indicate the number of steps in the list. |
| >User | >Reset User | No | Yes | Reset User menu selections to the factory default configuration. |
| | >Output Recall | Off | | Turn output recall mode off. |
| | | On | | Set power output state to that which was in use before power was last turned off. See Recall the power supply ON/OFF output state at power on (on page 2-20) for more information. |
| | >Save Last | On | | Save last operating parameters in use before turning instrument off. Restores saved parameters when instrument turned on. See Recall the power supply operating parameters at power on (on page 2-21) for more information. |
| | | Off | | Turns save last mode off. |
| | >Key Beep | Off | | Turns off key press notification sound. |
| | | On | | Turns on key press notification sound. See Setting the key sound (on page 2-21) for more information. |
| >Knob Lock | Off | | Unlocks navigation wheel  . | |
| | On | | Locks navigation wheel  . See Lock the navigation wheel (on page 2-22) for more information. | |
| >System | >Reset System | No | Yes | Reset System menu selections to the factory default configuration. |
| | >Port Mode | Trigger | | Set port mode input to trigger. You must also set the trigger source (Trig Source). |
| | | RI/Def | | Set port mode input and output to RI/Def. You must also set the remote inhibit mode (RI mode). |
| | | Digital | | Set port mode input and output to digital. This setting is for programmable interface commands described in Commands listed in alphabetical order (on page 4-2). |
| >Trig Source | Manual | | Set rear panel port mode to manual trigger. | |
| | External | | Set rear panel port mode to external trigger. | |
| | Bus | | Set rear panel port mode to bus trigger. | |

| Primary menu | Secondary menu | First option | Additional option(s) | Allows you to ... |
|--------------|----------------|--------------|----------------------|--|
| | | Immediate | | Set rear panel port mode to immediate trigger. |
| | >RI Mode | Off | | Turn remote inhibit (RI) mode off. |
| | | Latching | | Set remote inhibit mode to latching. Latching mode turns the output channel off when the instrument detects a high-to-low transition (5 V to 0 V). |
| | | Live | | Set remote inhibit mode to live. Live mode the output channel off when the RI input is low (0 V) and on when the RI input is high (5 V) |
| | >DFI Source | Off | | Turn the discrete fault input (DFI) source mode off. |
| | | Ques | | Set the DFI source to question (Ques). |
| | | Oper | | Set the DFI source to operation (Oper). |
| | | ESB | | Set the DFI source to error status byte (ESB). |
| | | RQS | | Set the DFI source to request service (RQS). |
| | >Communication | USBTMC | | Set the communications mode to USBTMC. |
| | | GPIB | Address= 22 | Set the communications mode to GPIB. Set or edit the GPIB primary address. See To change GPIB address settings (on page 3-2) for more information. |
| | | RS232 | 9600,8,N,1 | Set the communication mode to RS232. Set or edit the RS232 address. USBTCM and GPIB are the recommended communication modes. |

Upper display messages

The instrument shows messages on the upper row of the display to indicate output operating and error conditions. See [Configuring the instrument for your application](#) (on page 2-16) for general information about these messages. See the following tables for the messages and a description of what the messages indicate.

| Operating conditions | |
|----------------------|--|
| Messages | Description |
| OFF | Power supply output is off. |
| CV | Instrument is operating in constant voltage (CV) mode. |
| CC | Instrument is operation in constant current (CC) mode. |
| RI | Instrument output has been turned off by the remote inhibit (RI) input. See [SOURce:]DIGital:FUNction (on page 4-12) for more information. |

| Error conditions | |
|------------------|---|
| Messages | Description |
| OVP | Instrument has sensed a voltage level above the threshold set for overvoltage control and turned off the output. See Setting the overvoltage protection (on page 2-19) for more information. |
| RSV | Instrument has sensed a reverse remote sense polarity condition and turned the output off. Polarities of source and sense connections must be the same. See Using remote sense (on page 2-23) for more information. |
| OTP | Instrument has sensed an excessive internal temperature and turned off the output. |

CAUTION

If the instrument displays the OTP message, the instrument should be shut down immediately. Do not operate the instrument when temperatures are above the internal temperature trip level to avoid damaging internal components.

Lower display messages

The instrument shows the following messages on the lower row of the display.

| Message | Description |
|---------|--|
| OVP | If overvoltage protection (OVP) is set, the instrument displays the OVP message to indicate that OVP is set. Flashes when OVP has tripped. See Setting the overvoltage protection (on page 2-19) for more information. |
| Lck | If the front-panel controls are locked, the instrument displays the Lck message. See Configuration menus description (on page 2-9) for information on the >Protect >Key Lock configuration. See Keypad special operations (on page 2-8) for information on unlocking the front panel controls. |

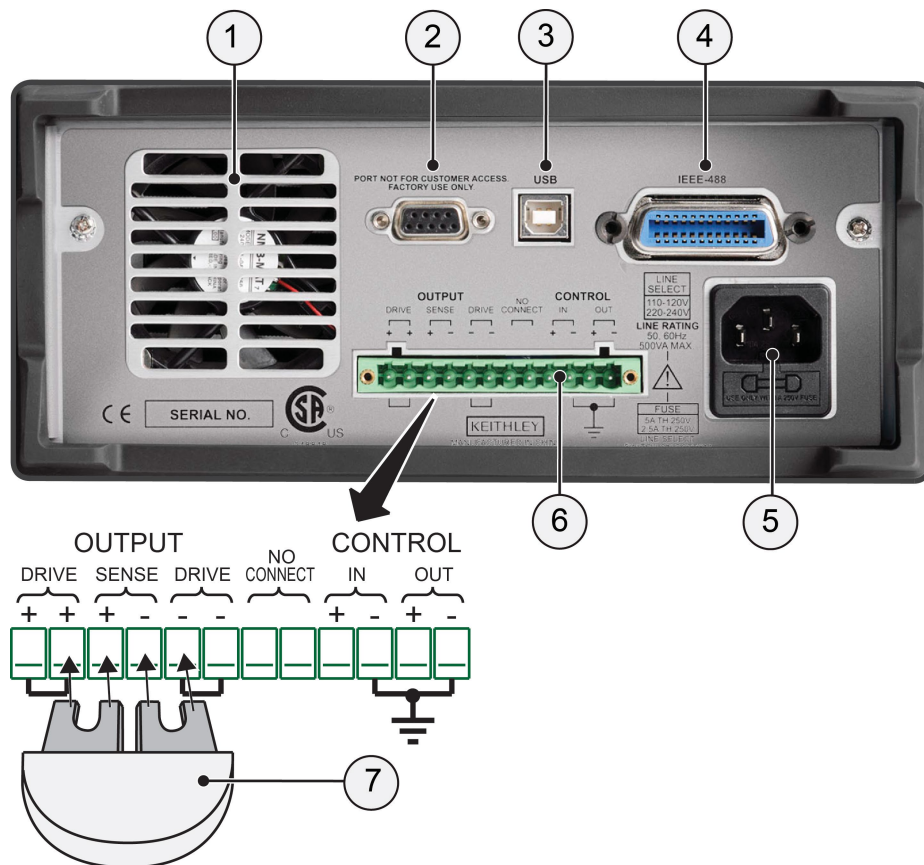
Rear panel at a glance

The rear panel of the Series 2200 contains the following items:

- Cooling vents
- Factory test port
- USB device port
- GPIB IEEE-488 port
- 110 V/220 V power connector
- 12-pin connector; includes remote sense
- Shorting clip. Use this for proper regulation when not using remote sense. This connector comes installed. It shorts the + drive to the + sense and the - drive to the - sense. To use remote sense, remove the clip.

The rear panel of the Series 2200 is shown in the following figure.

Figure 4: Rear panel



(1) Cooling vents

Exhaust vent for the internal cooling fan. Keep the vent free of obstructions to prevent overheating.

(2) Factory test port

Do not use the factory test port.



CAUTION

Unauthorized use of the factory test port could damage this product.

(3) USB device port

The USB 2.0 high-speed device port supports remote control and data transfer to a PC.

(4) General purpose interface bus (GPIB) connector

The GPIB supports remote control and data transfer to a PC.

(5) 110 V/220 V power connector

Using the supplied line cord, connect to a grounded AC power outlet.

(6) 12-pin connector

The 12-pin connector includes remote sense. The illustration of the 12-pin connector (see [Rear panel at a glance](#) (on page 2-13).) shows the location of the following output and control connectors:

- Two "Output Drive + " connectors are equivalent to the front-panel output + connector
- Two "Output Drive - " connectors are equivalent to the front-panel output - connector
- Two connectors: "Output Sense + " and "Output Sense - " are used for remote sensing
- Two No Connect connectors on the rear panel terminal strip are unused
- Four connectors "Control In + ", Control In - ", "Control Out + ", and Control In - " on the rear panel terminal strip are configured by the port mode controls. They support the trigger, RI/DFI, and digital I/O functions. See >System in [Configuration menus description](#) (on page 2-9) for more information about the port mode controls.

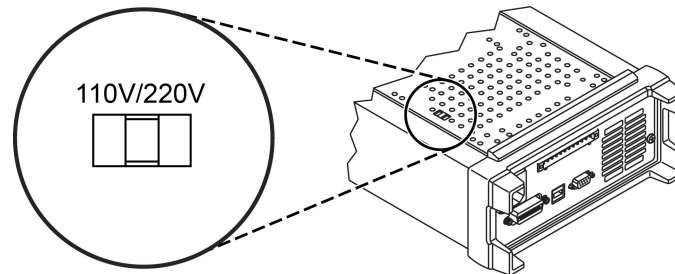
(7) Shorting clip

Use the shorting clip for proper regulation when not using remote sense. This connector comes installed. It shorts the + output drive to the + sense and the - output drive to the - sense for local sensing at the output terminals. To use remote sense, remove the clip.

110 V/220 V selector switch

The 110 V/220 V selector switch is located on the bottom of the instrument as shown in the following figure.

Figure 5: Selector switch



Front panel operation

Within a few seconds after turning on, the power supply displays the actual voltage and current output value on the display's top line and the voltage and current settings on the bottom line.

You can enable or disable the output of the power supply from the front panel by pressing the **Output On/Off** key. When the output is off, the **OFF** message displays to the right of the current and voltage values.

The display shows the present operating status of the power supply with display messages. When the power supply operates in constant voltage mode, the **CV** message displays. When the power supply operates in the constant current mode, the **CC** message displays.

NOTE

If the front panel was locked with a password, enter the correct password after you press a key (V-set, I-set, Save, Recall, or Shift), then you can change the settings.

NOTE

To cancel a function operation (V-set, I-set, Save, Recall, or Shift), press Esc.

Configuring the instrument for your application

The configuration menus (see [Configuration menus description](#) (on page 2-9)) include settings, like `OVP` and `Max Volt`, that determine the maximum voltage output of the power supply. The menu system also includes settings, like `Save Last` and `Output Recall`, that determine how the instrument initializes itself when it is turned on.

This power supply features a constant voltage/constant current automatic crossover. This feature permits continuous operation in the transition from constant-voltage mode to constant-current mode as the load changes. The intersection of the constant-current and constant-voltage modes is called the crossover point.

For example, if the load is such that the power supply is operating in constant-voltage mode, the power supply provides a regulated output voltage. The output voltage remains constant as the load increases until the preset current limit is reached. Then the crossover occurs. At that point, the output current becomes constant and the output voltage drops in proportion to further load increases.

Crossover is indicated by the front panel `CC` and `CV` messages. If the `CV` message appears, the instrument is operating in constant-voltage mode. If the `CC` message appears, the instrument is operating in constant-current mode.

Crossover from the constant-current mode to the constant-voltage mode also occurs automatically in response to a decrease in load. For example, suppose you are charging a 12 V battery. Initially, the open circuit voltage of the power supply is preset for 13.8 V. A low-battery places a heavy load on the power supply, and it operates in constant-current mode. You adjust the instrument to charge the battery at the rate of 1 A. As the battery becomes charged and its voltage approaches 13.8 V, the load decreases to the point where the battery no longer demands the full 1 A charging rate. The power supply then crosses over to constant-voltage mode.

Initializing to the default setup

Use the default setup to get the power supply into a default initial state:

1. Remove all leads from the output connectors.
2. Turn on the power supply.
3. Press **Shift** and **Menu (1)** to access the configuration menus. >Default Set shows on the display.
4. Press **Enter** to bring up the default settings menu. No and Yes show on the display.
5. Press the right arrow key or navigation wheel \odot to select **Yes**.
6. Press **Enter** to enable the default settings.

See the following table for the default settings.

| Default setting | |
|-----------------|----------|
| Output On/Off | OFF |
| V-Set | 1.000 V |
| I-Set | 0.1000 A |
| Max Volt Set | Off |
| OVP Set | Off |
| Out Time Set | Off |
| Key Lock | Off |
| Output Recall | Off |
| Save Last | On |
| Key Beep | Off |
| Knob Lock | Off |
| Port Mode | Trigger |
| Trig Source | Manual |
| RI Mode | Off |
| DFI Source | Off |
| Communication | RS232 |

Setting the current limit

You may set the current limit from 0 A to the maximum current value of each model. The maximum current rating is shown on the instrument name plate.

1. Press **I-set**.
2. Use the arrow keys, numeric keypad, or the navigation wheel \odot to enter the current limit.
3. Press **Enter** to set the current limit.

Setting the voltage limit


You may set the voltage limit from 0 V to the maximum voltage rating shown on the instrument name plate.

1. Press **V-set**.
2. Use the arrow keys, numeric keypad, or the navigation wheel \odot to enter the voltage limit.
3. Press **Enter** to set the voltage limit.


Save and recall setups

You can store up to 40 different setups in setup memory locations (1 to 40). Each setup includes the set voltage limit, the set current limit, and the protection menu settings. When shipped from the factory, setup memories 1 through 40 are empty. Save and recall setups as follows:

To save a setup:

1. After you set up the power supply, (voltage and current limits and the protection menu settings), push the **Save** key.
2. Use the arrow keys, numeric keypad, or the navigation wheel  to select the setup memory (1 to 40) that you want to store the values in.
3. Press **Enter** to confirm the memory location.





To recall a setup:

1. Press **Recall**.
2. Use the arrow keys, numeric keypad, or the navigation wheel  to select the setup memory that you want to recall from.
3. Press **Enter**.

Setting the maximum voltage

The Max Volt Set control determines the maximum voltage that you can set using the V-set control. This can help keep accidental over-voltage from being applied to sensitive loads. Set the maximum voltage as follows:

To set the maximum voltage:

1. Press **Shift** and **Menu (1)** to access the configuration menus.
2. Use the arrow keys, numeric keypad, or the navigation wheel  to select `>Protect`.
3. Press **Enter** and turn the navigation wheel  one click clockwise. `>Max Volt Set` shows on the display.
4. Press **Enter**. `Off (default)` shows on the display.
5. Use the arrow keys, numeric keypad, or the navigation wheel  to select `On`.
6. Press **Enter** to turn on the maximum voltage feature.
7. Use the numeric keys, arrow keys, or navigation wheel  to change the voltage value. The value must be less than the maximum voltage output noted on the nameplate of the power supply.
8. Press **Enter**.
9. Press **Esc** to exit the menu system.

NOTE

When you adjust the voltage value to the maximum voltage limit, the voltage setting flashes back at you.



NOTE

The default maximum voltage is the full voltage range of the particular power supply being used.

Setting the overvoltage protection

The OVP Set control turns overvoltage protection (OVP) on or off. If overvoltage protection is turned on and the instrument senses a voltage level above the threshold set for over-voltage control, the instrument will turn off the output and clamp the voltage on the output to below one volt.

To set the overvoltage protection:

1. Press **Shift** and **Menu (1)** to access the configuration menus.
2. Use the arrow keys, numeric keypad, or navigation wheel  to select **>Protect**.
3. Press **Enter**.
4. Use the up or down arrow keys to select **>OVP Set**.
5. Press **Enter**.
6. Select **On**.
7. Press **Enter**.
8. Enter the desired OVP value with the numeric keypad, arrow keys, or navigation wheel .
9. Press **Enter**

NOTE

The lower display shows OVP when the overvoltage protection feature is activated. The OVP indicator will flash on and off when the overvoltage protection feature detects an overvoltage condition.

NOTE

The default value for the Max Volt Set parameter is On.

Resetting the power supply after an overvoltage trip

To reset the power supply after an overvoltage trip:

1. Determine and remove the source of the overvoltage. Overvoltage may be caused by setting the voltage limit too high, external voltage sources, or equipment failure.
2. Press the **Output On/Off** key to clear the OVP status. This will put the power supply output in the off state.

Recall the power supply ON/OFF output state at power on

The Output Recall control determines the On or Off output state after the power supply is powered on. If you select **On**, the power supply will restore the state of the output to that which was in use before the power was last turned off. If the output was turned on when the power supply is turned off or loses power then the output will return to the On state when the power supply is turned back on or power is restored. Selecting **Off** will disable this function and the output channel will always be set to Off after the power supply is powered on.

To enable or disable this control:

1. Press the **Shift** and **Menu (1)** to access the configuration menus.
2. Use the up and down arrow keys to select **>User**.
3. Press **Enter**.
4. Use the up and down arrow keys to select **>Output Recall**.
5. Press **Enter**.
6. Use the up or down arrow keys to select **>On** or **>Off**.
7. Press **Enter**.
8. Press **Esc** to exit the menu system.

NOTE

Wait 3 seconds after changing the settings to allow the settings to be completely stored before powering off the instrument.

NOTE

The default value for the Output Recall control is Off.

Recall the power supply operating parameters at power on

The Save Last control determines whether the power supply saves its most recent settings, such as voltage and current, and restores these settings at power on. If you set this control to **Off** then the power supply returns to the default settings at power on. If you select **On**, the power supply will restore the state to that which was in use before the power was last turned off.

To enable or disable this control:

1. Press **Shift** and then **Menu (1)** to access the configuration menus.
2. Use the arrow keys to select **>User**.
3. Press **Enter**.
4. Use the arrow keys to select **>Save Last**.
5. Press **Enter**.
6. Use the arrow keys to select **>On** or **>Off**.
7. Press **Enter**.
8. Press **Esc** to exit the menu system.

NOTE

Wait 3 seconds after changing the settings to allow the settings to be completely stored before powering off the instrument


NOTE

The default value for the Save Last control is On.

Setting the key sound

The Key Beep control can switch on or off the beeper that sounds when you press any button or press any key.


To set the key sound:

1. Press **Shift** and **Menu (1)** to access the configuration menus.
2. Use the arrow keys, numeric keypad, or navigation wheel  to select **>User**.
3. Press **Enter**.
4. Use the arrow keys to select **>Key Beep**.
5. Press **Enter**.
6. Use the arrow keys to select **>On** or **>Off**.
7. Press **Enter**.
8. Press **Esc** to exit the menu system.




NOTE

The default value for the Key Beep control is Off.

Lock the navigation wheel

The Knob Lock control can be used to lock the navigation wheel  so it cannot be used to change settings or to select menu items.

To lock the navigation wheel :

1. Press **Shift** and **Menu (1)** to access the configuration menus.
2. Use the arrow keys, numeric keypad, or navigation wheel  to select **>User**.
3. Press **Enter**.
4. Use the arrow keys, numeric keypad, or navigation wheel  to select **>Knob Lock**.
5. Press **Enter**.
6. Use the arrow keys, numeric keypad, or navigation wheel  to select **>On** or **>Off**.
7. Press **Enter**.
8. Press **Esc** to exit the menu system.

NOTE

The default value for the Knob Lock control is Off.

Using local sense

Configuring the power supply for local sense allows connection to the device under test with two lead wires, but does not compensate for voltage drop in the leads.

To configure for local sense:

1. On the rear panel terminal strip, install wires between DRIVE + and SENSE +, and between DRIVE - and SENSE -. You may also use the included shorting clip described in Rear panel at a glance.
2. Connect to your device under test using two wires from either the front panel binding posts or the rear panel DRIVE + and DRIVE - terminals.

Using remote sense

Use remote sensing to regulate the output voltage at the device under test. This feature lets you compensate for the voltage drop in the leads between the power supply front-end terminals and the device-under-test.

To set the remote sensing mode:

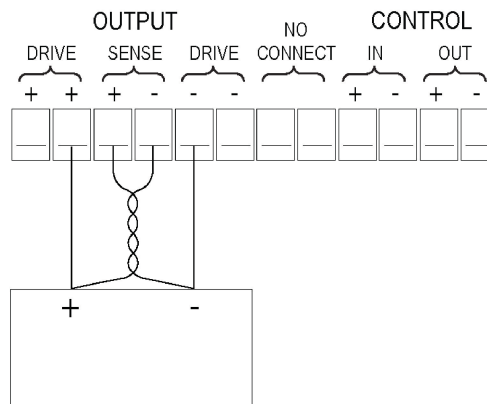
1. Remove any jumpers or shorting clip on the rear panel terminal strip connectors between DRIVE + and SENSE + and between DRIVE – and SENSE –.
2. See the following figure and connect a pair of sense leads from SENSE + and SENSE - to the device under test.

! CAUTION

To assure system stability, use a jacketed, twisted-pair cable between the remote sense terminals of the Series 2200 and the load.

3. Connect a pair of drive leads from the DRIVE + and DRIVE - to the device under test.



Figure 6: Load (device under test)



Define a list of voltage and current steps

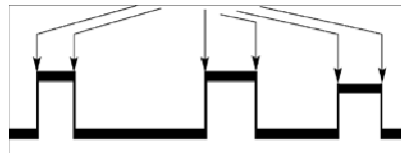
The Edit List feature lets you create up to seven sequences of steps, each with a voltage level, current level, and time duration.

To define and save a sequence, do the following:

1. Press **Shift** and **Menu (1)** to access the configuration menus. The instrument displays:
>Default Set
2. Use the arrow keys, numeric keypad, or navigation wheel  to select **>Edit List**. The instrument displays:
>Edit List
3. Press **Enter**. The instrument displays:
Recall 1
4. Rotate the navigation wheel  to select the number of the list to define or edit. You can choose from 1 to 7. The instrument displays:
Recall 1
5. Press **Enter**. The instrument displays:
Continuous
6. Use the up and down arrow keys to select the appropriate mode described in the following paragraph: **Continuous** or **Step**.

| Mode | Description |
|------------|---|
| Continuous | In continuous mode, the supply will trigger (execute) the entire sequence of steps as soon as it receives the next trigger signal. The trigger source is determined by the system menu's trigger source item. |

Figure 7: Triggers



| | |
|------|---|
| Step | In step mode, the supply will advance to each step only after it receives a trigger signal. |
|------|---|

Figure 8: Trigger



7. Press **Enter**. The instrument displays:
Repeat 1
8. Use the keypad or navigation wheel \odot to select the number of times to repeat the list. In this example, 2 is used. This means that the instruction will run through the list of steps two times before stopping. The instrument displays:
Repeat 2
9. Press **Enter**. The instrument displays:
List Steps 4
10. Rotate the navigation wheel \odot to select the number of steps in the list. In the example, 3 is used. The instrument displays:
List Steps 3
11. Press **Enter**. The instrument displays:
S 001 = 4.800 V
12. Use the keypad to set the voltage for this step. In the example, the voltage is set to 4.00 volts. The instrument displays:
S 001 = 4.00 V.
13. Press **Enter**. The instrument displays:
S 001 = 0.1000 A
14. Use the keypad to set the current for this step. In the example, the current is set to 1.500 amps. The instrument displays:
S 001 = 1.500 A
15. Press **Enter**. The instrument displays:
S 001 = 0.250 S
16. Use the keypad to set the time duration for this step. In the example, the duration is set to 0.100 seconds. The instrument displays:
S 001 = 0.100 S
17. Press **Enter**. The instrument displays:
S 002 = 4.500 V
18. Repeat steps 11 through 17 for each of the number of steps selected in step 10 above. The instrument displays:
Save List 1
19. Press the up or down arrow key to select the number of the list to save the current list to. In step 4 of this example, you started by selecting list 1. Now, you can save it in any of the 7 lists available to you. The instrument displays:
>Edit List
20. Press **Enter** to save the list.


NOTE

Running a list does not turn the output channel on. Before running a list, be sure to set the appropriate voltage and current and turn the output on.

21. Press **Esc** to exit the menu system.

Run a list of voltage and current steps

To run a defined list of voltage and current steps, do the following:

1. Set the output voltage to what you want it to be set at before running the list and press the **Output On/Off** key to turn the output on.
2. Press **Shift and List (2)**.
3. Use the keypad or navigation wheel  to select the list to run.
4. Press **Enter**. The power supply will wait for a trigger to start executing the list. The trigger source depends on the setting of the Trigger Source control. See [Configuration menus description](#) (on page 2-9) for information on setting the >System >Trig Source control.
5. To run the selected list with a manual trigger, press **Shift and Trigger (3)**.
6. To stop the list from running any more and to turn the output to off, press **Esc**.

NOTE

See the [Commands listed in alphabetical order](#) (on page 4-2) section and [Example 1](#) (on page 4-41) for information on programming the List Mode Function.

Rear panel operation

The Series 2200 instrument supports two remote interfaces:

- GPIB (general purpose interface bus)
- USB

The Series 2200 can only be controlled from one remote interface at a time. The unit will remote to the first interface on which it receives a message. It will ignore the other interface until the unit is taken back to local operation.

Connect to an external computer with IEEE-488

This topic contains information about GPIB standards, bus connections, and primary address selection.

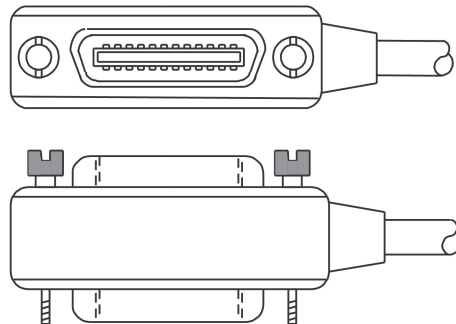
GPIB standards

The GPIB is the IEEE-488 instrumentation data bus with hardware and programming standards originally adopted by the IEEE (Institute of Electrical and Electronic Engineers) in 1975. The instrument is IEEE Std 488.1 compliant and supports IEEE Std 488.2 common commands and status model topology.

Connect the GPIB cable

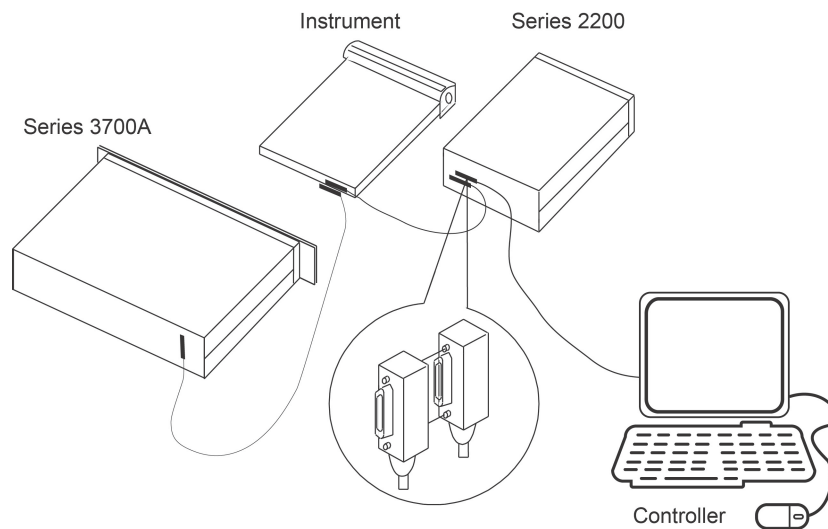
To connect a Series 2200 to the GPIB bus, use a cable equipped with standard IEEE-488 connectors, as shown below.

Figure 9: GPIB connector



To allow many GPIB connections to other instruments, stack the cable connectors. Two screws are located on each connector to ensure that connections remain secure. The figure below shows a typical connection scheme for a multi-unit test system.

Figure 10: Series 2200 multiple parallel connections



⚠ CAUTION

To avoid possible mechanical damage, stack no more than three connectors on any one unit. To minimize interference caused by electromagnetic radiation, use only shielded IEEE-488 cables. Contact Keithley Instruments for shielded cables.

To connect the Series 2200 to the IEEE-488 bus, line up the cable connector with the connector located on the rear panel. Install and tighten the screws securely, making sure not to overtighten them (see [Rear panel at a glance](#) (on page 2-13) for the location of the connections).

Connect any additional connectors from other instruments as required for your application. Make sure the other end of the cable is properly connected to the controller. You can only have 15 devices connected to an IEEE-488 bus, including the controller. The maximum cable length is either 20 meters or two meters multiplied by the number of devices, whichever is less. Not observing these limits may cause erratic bus operation.

Primary address

The Series 2200 ships from the factory with a GPIB primary address of 22. You can set the address to a value from 0 to 30, but do not assign the same address to another device or to a controller that is on the same GPIB bus (controller addresses are usually 0 or 21).

Terminator

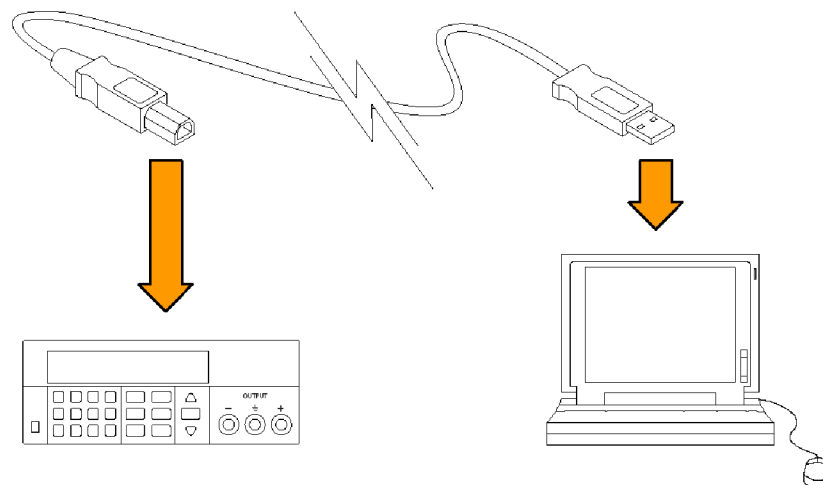
When receiving data over the GPIB, the instrument terminates messages on any line feed character or any data byte with EOI asserted (line feed with EOI asserted is also valid). When sending data, it appends a line feed character to all outgoing messages. The EOI line is asserted with the terminating line feed character.

Connect to an external computer with USB

To connect to an external computer with USB:

1. Install a VISA driver on your computer. This driver is available on the Keithley Instruments website.
2. Connect the instrument to the computer with a USB cable. The computer will then recognize the power supply as a USB device.

Figure 11: Connect the instrument to the computer



Operation examples

You can save tests in 40 memory locations to save up to 40 setups or use the Series 2200 List mode to define custom test sequences of up to 80 steps. This makes it easy to perform tests such as analyzing how your circuit or device under test performs at each voltage level within a range of voltages.

This topic provides examples of these operations. Each example describes how to complete the operation using both of the following methods:

- Front-panel keystrokes
- Programming commands



Saving setups example

This example describes how to set up the power supply to output 3.33 V, 1.6 A and save the setup in location 29 of the 40 setup memory locations available.


Keystrokes

Perform the following steps using the keys on the instrument's front panel to save the test setup.

To configure the power supply:


1. Press **V-Set**.
2. Use the arrow keys, navigation wheel , or the keypad to input **3.33 V**. Press **Enter**.
3. Press **I-Set**.
4. Use the arrow keys, navigation wheel , or the keypad to input **1.6 A**. Press **Enter**.

To save the setup:

1. Press **Save**.
2. Use the arrow keys, navigation wheel , or the keypad to select memory location **29**. Press **Enter**.

To recall the setup:

Use the following keystrokes to recall the setup saved in memory location 29.

1. Press **Recall**.
2. Use the arrow keys, navigation wheel , or the keypad to select memory location **29**. Press **Enter**. The condition previously set displays.

Programming commands

To configure and save the setup:

```
*RST
SOURCE:FUNC:MODE FIX
SOURCE:VOLT 3.33V
SOURCE:CURR 1.6A
*SAV 29
```

To recall the setup:

Program the following command:

```
*RCL 29
```







Timer example

This example sets up the power supply to output 6 V, 1 A for 7 seconds before the output automatically turns off.

Keystrokes

Perform the following procedure using the keys on the instrument's front panel to save the test setup.

To configure the duration of the timer and enable the timer feature:

1. Press **Shift** and **Menu (1)** to access the configuration menus.
2. Use the arrow keys, navigation wheel , or the keypad to select **Protect**. Press **Enter**.
3. Use the arrow keys, navigation wheel , or the keypad to select **Out Time Set**. Press **Enter**.
4. Use the arrow keys, navigation wheel , or the keypad to select **On**. Press **Enter**.
5. Use the arrow keys, navigation wheel , or the keypad to input **Time = 7.00 S**. Press **Enter**.
6. Press **Esc** a few times to return to the initial screen.
7. Press **V-Set**.
8. Use the arrow keys, navigation wheel , or the keypad to input **6 V**. Press **Enter**.
9. Press **I-Set**.
10. Use the arrow keys, navigation wheel , or the keypad to input **1 A**. Press **Enter**.
11. Press **Output On/Off** to turn on the output.

Wait for 7 seconds. The output will turn off automatically.

Programming commands

```
*RST
SOURCE:FUNC:MODE FIX
SOURCE:VOLT 6V
SOURCE:CURR 1A
```

To configure the duration of the timer:

```
OUTPUT:TIMER:DELAY 7S
```

To enable the timer feature:

```
OUTPUT:TIMER:STATE ON
OUTPUT:STATE ON
```

To disable the timer feature:

```
OUTPUT:TIMER:STATE OFF
```

List mode example

This example configures a 5 step list to be executed 2 times in continuous mode. The list is saved in location 3. The instrument runs the list upon entering the list mode operation.

| Step number | Voltage level (V) | Current level (A) | Duration (sec) |
|-------------|-------------------|-------------------|----------------|
| 1 | 2 | 5 | 0.001 |
| 2 | 5 | 5 | 0.001 |
| 3 | 1 | 1 | 1.000 |
| 4 | 7 | 3 | 0.001 |
| 5 | 3 | 1 | 0.001 |

Keystrokes

Use the following procedures to configure the list parameters, create the list steps, save the list, run, and stop running the list. In these procedures, you can use the arrow keys, numeric keypad, or the navigation wheel to select or enter numbers.

To configure the list parameters:

1. Press **Shift** and **1** to display the configuration menu.
2. Select **Edit List**. Press **Enter**. The display shows **Recall 1**.
3. Indicate that you want to save the list you are creating in location 3 by selecting **3** and pressing **Enter**. The display shows **Continuous**.
4. Indicate that you want the continuous mode by selecting **Continuous** and pressing **Enter**. The display shows **Repeat 1**.
5. Indicate that you want to repeat the sequence twice by selecting **2** and press **Enter**. The display shows **List Steps 1**.
6. Indicate that there will be 5 steps in the list by selecting **5** and pressing **Enter**. The display shows **S 001= 0.000 V**.

This completes entering the list parameters. You are ready to configure the first step.

To configure the first step in the list:

1. Input **S 001= 2.000 V**. Press **Enter**. The display shows **S 001= 0.0000A**.
2. Input **S 001= 5.000 A** as the current limit. Press **Enter**. The display shows **S 001= 1.001S**.
3. Input **S 001= 0.001 S** as the duration of the step. Press **Enter**. The display shows **S 002= 0.000V**.

This completes the configuration of the first step. You are ready to configure the second step.

To configure the second step in the list:

1. Input **S 002= 5.000 V**. Press **Enter**. The display shows **S 002= 0.0000A**.
2. Input **S 002= 5.000 A** as the current limit. Press **Enter**. The display shows **S 002= 1.0000A**.
3. Input **S 002= 0.001 S** as the duration of the step. The display shows **S 002= 0.001S**. Press **Enter**. The display shows **S 003= 0.000V**.

This completes the configuration of the second step. You are ready to configure the third step.

To configure the third step in the list:

1. Input $S\ 003= 1.000\text{ V}$. Press **Enter**. The display shows $S\ 003= 0.0000\text{A}$.
2. Input $S\ 003= 1.000\text{ A}$ as the current limit. Press **Enter**. The display shows $S\ 003= 1.0000\text{S}$.
3. Input $S\ 003= 1.000\text{ S}$ as the duration of the step. The display shows $S\ 003= 0.001\text{S}$. Press **Enter**. The display shows $S\ 004= 0.000\text{V}$.

This completes the configuration of the third step. You are ready to configure the fourth step.

To configure the fourth step in the list:

1. Input $S\ 004= 7.000\text{ V}$. Press **Enter**. The display shows $S\ 004= 0.0000\text{A}$.
2. Input $S\ 004= 3.000\text{ A}$ as the current limit. Press **Enter**. The display shows $S\ 004= 1.0000\text{A}$.
3. Input $S\ 004= 0.001\text{ S}$ as the duration of the step. The display shows $S\ 004= 0.001\text{S}$. Press **Enter**. The display shows $S\ 5= 0.000\text{V}$.

This completes the configuration of the fourth step. You are ready to configure the fifth step.

To configure the fifth step in the list:

1. Input $S\ 005= 3.000\text{ V}$. Press **Enter**. The display shows $S\ 005= 0.0000\text{A}$.
2. Input $S\ 005= 1.000\text{ A}$ as the current limit. Press **Enter**. $S\ 003= 0.0001\text{S}$.
3. Input $S\ 005= 0.001\text{ S}$ as the duration of the step. Press **Enter**. The display shows $\text{Save List } 1$.


This completes the configuration of the fifth step.

To save the list to location 3:

Input **3**. Press **Enter**. This saves the list to location 3. The display shows $>\text{Edit List}$.

The list is now complete and saved. You are ready to run the list.

To run the list:

1. Press **Output On/Off** to turn on the output.
2. Press **Shift** and **2** to display the available list.
3. Use the arrow keys, the navigation wheel , or the keypad to select **3** as the location of the saved list.
4. Press **Enter**. $L3:EE$ is displayed while the power supply waits for a trigger.
5. Press **Shift** and **3** to to run the list.

You are ready to stop running the list.

To stop running the list:

1. Press **Output On/Off** to turn off the output
2. Press **ESC** to exit the list mode.

Programming commands

To reset the power supply:

```
*RST
```

To set the trigger source to be internal:

```
TRIGGER:SOURCE:BUS
```

To configure the list:

```
SOURCE:LIST:STEP 5
SOURCE:LIST:MODE CONT
SOURCE:LIST:COUNT 2
SOURCE:LIST:VOLT 1, 2V
SOURCE:LIST:VOLT 2, 5V
SOURCE:LIST:VOLT 3, 1V
SOURCE:LIST:VOLT 4, 3V
SOURCE:LIST:VOLT 5, 7V
SOURCE:LIST:CURREN 1, 5A
SOURCE:LIST:CURREN 2, 5A
SOURCE:LIST:CURREN 3, 1A
SOURCE:LIST:CURREN 4, 3A
SOURCE:LIST:CURREN 5, 1A
SOURCE:LIST:WIDTH 1, 0.001S
SOURCE:LIST:WIDTH 2, 0.001S
SOURCE:LIST:WIDTH 3, 1S
SOURCE:LIST:WIDTH 4, 0.001S
SOURCE:LIST:WIDTH 5, 0.001S
SOURCE:LIST:SAVE 3
```

To run the list:

```
OUTPUT ON
SOURCE:FUNC:MODE LIST
*TRG
```

Default setup

The following table lists the settings that are restored when you return the power supply to default settings.

Default setup

| Menu or system | Defaults |
|----------------|----------|
| VOLT:PROT | MAX |
| VOLT:PROT:STAT | OFF |
| OUTP | OFF |
| VOLT | 1 V |
| VOLT:RANG | MAX |
| CURR | 0.1 A |
| OUTP:TIM | 60 |
| OUTP:TIM:STAT | OFF |

Clear and sanitize procedures

This section helps customers with data security concerns to sanitize or remove memory devices from the Series 2200 instrument.

These products have data storage (memory) devices and a data output device (USB port). These instructions tell how to clear or sanitize the memory devices and disable the data output device. The instructions also tell how to declassify an instrument that is not functioning.

Terms

The following terms may be used in this topic.

- **Clear.** This removes data on media/memory before reusing it in a secured area. All reusable memory is cleared to deny access to previously stored information by standard means of access.
- **Erase.** This is equivalent to clear.
- **Media storage/data export device.** Any of several devices that can be used to store or export data from the instrument, such as a USB port.
- **Nonvolatile memory.** Data is retained when the instrument is powered off.
- **Power off.** Some instruments have a “Standby” mode, in which power is still supplied to the instrument. For the purpose of clearing data, putting the instrument in Standby mode does not qualify as powering off. For these products, you will need to either press a rear-panel OFF switch or remove the power source from the instrument.
- **Remove.** This is a physical means to clear the data by removing the memory device from the instrument.
- **Sanitize.** This eradicates the data from media/memory so that the data cannot be recovered by other means or technology. This is typically used when the device will be moved (temporarily or permanently) from a secured area to a non-secured area.
- **Scrub.** This is equivalent to sanitize.
- **User-modifiable.** The user can write to the memory device during normal instrument operation, using the instrument interface or remote control.
- **Volatile memory.** Data is lost when the instrument is powered off.

Memory devices

The following tables list nonvolatile and volatile memory devices. Detailed procedures to sanitize or clear these devices are shown after the tables.

Nonvolatile memory devices

| Type and minimum size | Function | User modifiable | Data input method | Location | To sanitize |
|--------------------------------|--|-----------------|------------------------------------|------------|--|
| EEPROM, 8k x 8 bit | Current setup, saved setups, and calibration constants | Yes | Firmware operations and user input | Main board | See Clear nonvolatile memory devices procedure (on page 2-35). |
| Flash 8k x bit | List Data | Yes | Firmware operations and user input | Main board | See Clear nonvolatile memory devices procedure (on page 2-35). |
| AT91SAM7X 256, 256k Flash | No | Firmware update | CPU board | | See Clear volatile memory devices procedure (on page 2-35). |
| STM32F103 C8, 64k – 128k Flash | No | Firmware update | Main board | | See Clear volatile memory devices procedure (on page 2-35). |

Volatile memory devices

| Type and minimum size | Function | User modifiable | Data input method | Location | To clear |
|------------------------|----------|-----------------|---------------------|------------|--|
| AT91SAM7X256, 64k SRAM | | No | Firmware operations | CPU board | Cycle power with minimum of 15 seconds off |
| STM32F103C8, 20k SRAM | | No | Firmware operations | Main board | Cycle power with minimum of 15 seconds off |

Clear nonvolatile memory devices procedure

This procedure clears the flash and EEPROM memory. After performing this procedure, the power supply will return to the factory default settings.

1. Press the front-panel **Shift** key.
2. Press the front-panel . (decimal point) key.
3. Press the front-panel **2** key.

Clear volatile memory devices procedure

This procedure clears the STM32F103 and AT91SAM.

1. Press the front-panel power button to turn the instrument off.
2. Wait at least 15 seconds before turning the instrument back on.

Data export devices

The following table lists the data export device. There are no procedures to disable these devices.

Data export device

| Type and minimum size | Function | User modifiable | Data input method | Location | To disable |
|-----------------------|---|-----------------|---------------------------------|--------------------------|--------------------|
| USB device port | Supports remote control and data transfer to a PC | Yes | Remote control through USBTMC | Rear-panel of instrument | Cannot be disabled |
| GPIB port | Supports remote control and data transfer to a PC | Yes | Remote control through IEEE 488 | Rear-panel of instrument | Cannot be disabled |

Remote operation

In this section:

| | |
|-------------------------------|-----|
| Section overview | 3-1 |
| Communication interfaces..... | 3-1 |
| Command syntax | 3-3 |
| Command groups..... | 3-9 |

Section overview

This chapter explains how to use commands for remotely controlling the Series 2200 instruments. With this information, you can write computer programs to perform functions, such as setting the controls, taking measurements, performing statistical calculations, and exporting data for use in other programs.

The [Commands listed in alphabetical order](#) (on page 4-2) section provides detailed descriptions of each command.

Communication interfaces

Your power supply has a USB 2.0 high-speed device port to control the power supply using the USBTMC protocol. The USBTMC protocol allows USB devices to communicate using IEEE-488.2 style messages.

You can also remotely communicate between your power supply and PC over General Purpose Interface Bus (GPIB).

Using the USB

Start by connecting a USB cable (Keithley Instruments Model USB-B - 1) between the USB 2.0 high-speed device port on the rear panel of your power supply and a computer.

In order for the computer to recognize the power supply, a USBTMC driver must be installed on the computer. A USBTMC driver can be installed on your computer by installing Virtual Instrument Software Architecture (VISA), available for download from the [Keithley Instruments website](http://www.tek.com/keithley) (<http://www.tek.com/keithley>).

Once the USBTMC driver is loaded, your computer will establish communication with the power supply upon USB cable connection.

Using the GPIB

Connector for IEEE-488 (GPIB) operation. Use a shielded cable, such as the Keithley Instruments Model 7007-1 or Model 7007-2.

Connect a GPIB cable from the Series 2200 instrument to your PC.

GPIB requirements





Before setting up the power supply for remote communication using the electronic (physical) GPIB interface, you should familiarize yourself with the following recommendations:

- A unique device address should be assigned to each device on the bus. No two devices should share the same device address.
- No more than 15 devices can be connected to any one bus.
- Only one device should be connected for every 6 feet (2 meters) of cable used.
- No more than 65 feet (20 meters) of cable should be used to connect devices to a bus.
- At least two-thirds of the devices on the network should be on while using the network.
- Connect the devices on the network in a star or linear configuration. Do not use loop or parallel configurations.

To change GPIB address settings

Your power supply must have a unique device address to function properly. The default setting for the GPIB configuration is GPIB Address 22. If there is more than one GPIB instrument on the bus, you will need to change the default setting on the power supply.

To change the GPIB address settings, do the following:

1. On the instrument front-panel, press **Shift** and **Menu (1)**.
2. Press the down arrow key or navigation wheel  until you see `System` on the display, then press **Enter**.
3. Press the down arrow key or navigation wheel  until you see `Communication` on the display, then press **Enter**.
4. Press the down arrow key or navigation wheel  until you see `GPIB` on the display, then press **Enter**. The display shows the GPIB address. For example, if the GPIB address is 22, the display will show `Address=22`.
5. Use the arrow keys, numeric keypad, or navigation wheel  to change the GPIB address, then press **Enter**.

The power supply is now set up for bidirectional communication with your controller.

Command timing

The average time it takes to both send and receive every command is approximately 20 ms. In the case of more complex commands, more time may be required to complete transmission.

Command syntax

You can control the power supply through the GPIB or USB interface using commands and queries.

This section describes the syntax these commands and queries use and the conventions the power supply uses to process them. The commands and queries themselves are listed by group (see [Command groups](#) (on page 3-9)) and alphabetically (see [Commands listed in alphabetical order](#) (on page 4-2)).

You transmit commands to the power supply using the enhanced American Standard Code for Information Interchange (ASCII) character encoding. Appendix A contains a chart of the ASCII character set. The Backus Naur Form (BNF) notation listed in the following table is used in this manual to describe commands and queries.

BNF notation

| Symbol | Meaning |
|--------|-------------------------------------|
| ◇ | Defined element |
| ::= | Is defined as |
| | Exclusive OR |
| { } | Group; one element is required |
| [] | Optional; can be omitted |
| .. | Previous element(s) may be repeated |
| () | Comment |

Command and query structure

Commands consist of set commands and query commands (usually simply called commands and queries). Commands change power supply settings or perform a specific action. Queries cause the power supply to return data and information about its status.

Most commands have both a set form and a query form. The query form of the command is the same as the set form except that it ends with a question mark.

For example, the set command `STATus:OPERation:ENable` has a query form `STATus:OPERation:ENable?`. Not all commands have both a set and a query form; some commands are set only and some are query only.

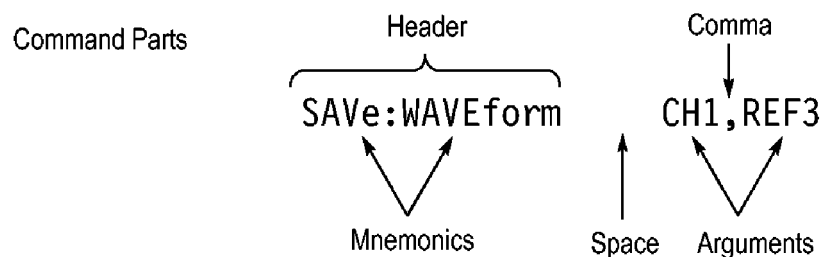
A command message is a command or query name, followed by any information the power supply needs to execute the command or query. Command messages consist of five different element types described in the following table.

Command message elements

| Symbol | Meaning |
|------------|---|
| <Header> | The basic command name. If the header ends with a question mark, the command is a query. The header may begin with a colon (:) character; if the command is concatenated with other commands the beginning colon is required. The beginning colon can never be used with command headers beginning with a star (*). |
| <Mnemonic> | A header subfunction. Some command headers have only one mnemonic. If a command header has multiple mnemonics, they are always separated from each other by a colon (:) character. |
| <Argument> | A quantity, quality, restriction, or limit associated with the header. Not all commands have an argument, while other commands have multiple arguments. Arguments are separated from the header by a <Space>. Arguments are separated from each other by a <Comma>. |
| <Comma> | A single comma between arguments of multiple-argument commands. It may optionally have white space characters before and after the comma. |
| <Space> | A white space character between command header and argument. It may optionally consist of multiple white space characters. |

The following figure shows the five command message elements.

Figure 12: Command message elements



Commands

Commands cause the power supply to perform a specific function or change one of its settings. Commands have the structure:

```
[ : ] <Header> [ <Space> <Argument> [ <Comma> <Argument> ] . . . ]
```

A command header is made up of one or more mnemonics arranged in a hierarchical or tree structure. The first mnemonic is the base or root of the tree and each subsequent mnemonic is a level or branch off of the previous one. Commands at a higher level in the tree may affect those at a lower level. The leading colon (:) always returns you to the base of the command tree.

Queries

Queries cause the power supply to return information about its status or settings. Queries have the structure:

```
[ : ] <Header>
[ : ] <Header> [ <Space> <Argument> [ <Comma> <Argument> ] . . . ]
```

You can specify a query command at any level within the command tree unless otherwise noted. These branch queries return information about all the mnemonics below the specified branch or level.

Query responses

When a query is sent to the power supply, only the values are returned. When the returned value is a mnemonic, it is noted in abbreviated format, as shown in the following table.

| Query response examples | |
|-------------------------|----------|
| Query | Response |
| MEASure:VOLTage:DC? | 5.0011 |
| SOURce:FUNCTion:MODE? | LIST |

Command entry

Follow these general rules when entering commands:

- Enter commands in upper or lower case.
- You can precede any command with white space characters. White space characters include any combination of the ASCII control characters 00 through 09 and 0B through 20 hexadecimal (0 through 9 and 11 through 32 decimal).
- The power supply ignores commands that consists of just a combination of white space characters and line feeds.

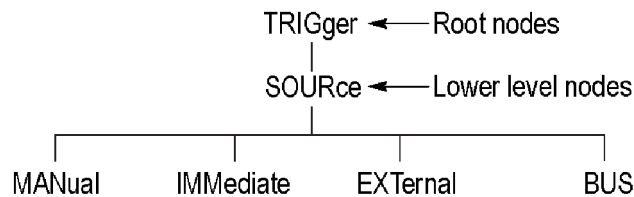
SCPI commands and queries

The power supply uses a command language based on the Standard Commands for Programmable Instruments (SCPI) standard. The SCPI standard was created by a consortium to provide guidelines for remote programming of instruments.

These guidelines provide a consistent programming environment for instrument control and data transfer. This environment uses defined programming messages, instrument responses and data formats that operate across all SCPI instruments, regardless of manufacturer.

The SCPI language is based on a hierarchical or tree structure that represents a subsystem. The top level of the tree is the root node; it is followed by one or more lower-level nodes as shown in the following figure.

Figure 13: Example of SCPI subsystem hierarchy tree



You can create commands and queries from these subsystem hierarchy trees. Commands specify actions for the instrument to perform. Queries return measurement data and information about parameter settings.

Message terminators

This manual uses the term <EOM> (End of message) to represent a message terminator.

USB end of message (EOM) terminators.

See the USB Test and Measurement Class Specification (USBTMC) section 3.2.1 for details. The power supply terminates messages by setting the EOM bit in the USB header of the last transfer of a message to the host (USBTMC Specification section 3.3.1), and by terminating messages with a LF.

When receiving, the power supply expects a LF and an asserted EOM bit as a message terminator.

Parameter types

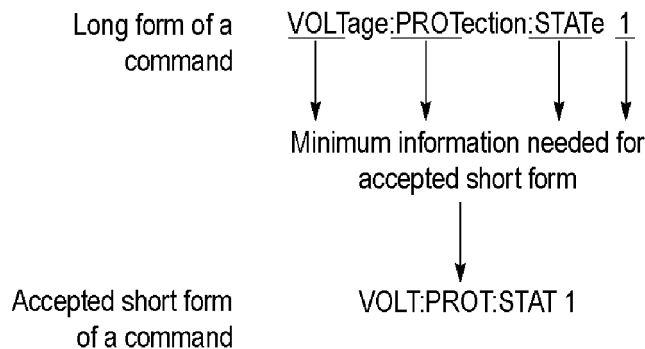
Many power supply commands require parameters. Parameters are indicated by angle brackets, such as <file_name>. There are several different types of parameters, as listed in the following table. The parameter type is listed after the parameter. Some parameter types are defined specifically for the arbitrary/ function generator command set and some are defined by SCPI.

| Types of parameters | | |
|---------------------|---|--|
| Parameter type | Description | Example |
| boolean | Boolean numbers or values | ON or ≠ 0 OFF or 0 |
| discrete | A list of specific values | MIN, MAX |
| NR1 numeric | Integers | 0, 1, 15, -1 |
| NR2 numeric | Decimal numbers | 1.2, 3.141516, -6.5 |
| NR3 numeric | Floating point numbers | 3.1415E-9, -16.1E5 |
| NRf numeric | Flexible decimal number that may be type NR1, NR2, or NR3 | See NR1, NR2, NR3 examples in this table |
| string | Alphanumeric characters (must be within quotation marks) | "Testing 1, 2, 3" |

Abbreviating commands, queries, and parameters

You can abbreviate most SCPI commands, queries, and parameters to an accepted short form. This manual shows these commands as a combination of upper and lower case letters. The upper case letters indicate the accepted short form of a command, as shown in the following figure. The accepted short form and the long form are equivalent and request the same action of the instrument.

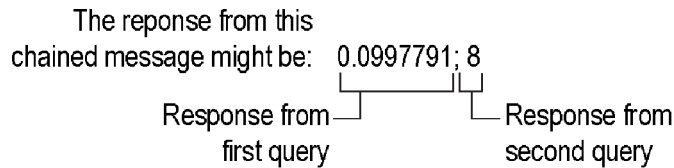
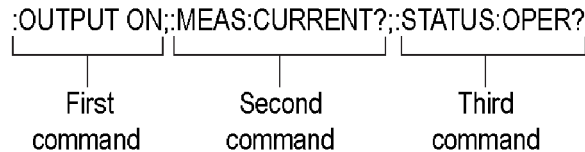
Figure 14: Example of abbreviating a command



Chaining commands and queries

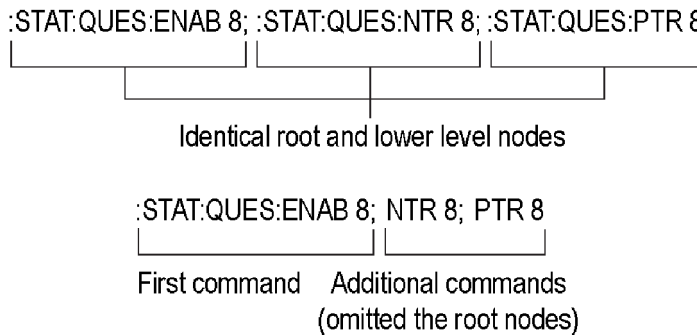
You can chain several commands or queries together into a single message. To create a chained message, first create a command or query, then add a semicolon (;), and finally add more commands or queries and semicolons until you are done. If the command following a semicolon is a root node, precede it with a colon (:). The following figure illustrates a chained message consisting of several commands and queries. The chained message should end in a command or query, not a semicolon. Responses to any queries in your message are separated by semicolons.

Figure 15: Example of chaining commands and queries



If a command or query has the same root and lower-level nodes as the previous command or query, you can omit these nodes. In the following figure, the second command has the same root node (STAT:QUES) as the first command, so these nodes can be omitted.

Figure 16: Example of omitting root and lower level nodes



General rules for using SCPI commands

The following are three general rules for using SCPI commands, queries, and parameters:

- You can use single (') or double (") quotation marks for quoted strings, but you cannot use both types of quotation marks for the same string.

| | |
|-----------|---|
| correct | "This string uses quotation marks correctly." |
| correct | 'This string also uses quotation marks correctly.' |
| incorrect | "This string does not use quotation marks correctly.' |

- You can use upper case, lower case, or a mixture of both. No embedded spaces are allowed between or within nodes.

```
:SOURCE:FREQUENCY 10MHZ
```

is the same as

```
:source:frequency 10mhz
```

and

```
:SOURCE:frequency 10MHZ
```

- No embedded spaces are allowed between or within nodes.

```
correct :OUTPUT:FILTER:LPASS:FREQUENCY 200MHZ
```

```
incorrect :OUTPUT: FILTER: LPASS:FREQUENCY 200MHZ
```

Command groups

This manual lists the power supply commands in two ways. First, it presents them by functional groups. Then, it lists them alphabetically. The functional group list starts below. The [Commands listed in alphabetical order](#) (on page 4-2) section provides details on each command.

The power supply interface conforms to Keithley standard codes and formats except where noted. The GPIB interface also conforms to IEEE Std 488.2–1987 except where noted. The USB interface also conforms to USB Test and Measurement Class, Subclass USB488 Specification, except where noted. Arguments are not mentioned in the group command descriptions, but are listed under the commands in the [Commands listed in alphabetical order](#) (on page 4-2) section of this manual.

Command reference

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| | |
|---|------|
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Commands listed in alphabetical order

You can use commands to either set instrument features or query instrument values. You can use some commands to do both, some only to set and some only to query. This document marks set-only commands with the words “No Query Form” included with the command name. It marks query-only commands with a question mark appended to the header, and includes the words “Query Only” in the command name.

This document spells out headers, mnemonics, and arguments with the minimal spelling shown in uppercase. For example, to use the abbreviated form of the MEASure:SCALar:VOLTage:DC? command, type MEAS:SCAL:VOLT:DC?.

*CLS (no query form)

The *CLS command clears all event registers and queues.

| | |
|-------------------------|---|
| Group | Status |
| Syntax | *CLS |
| Related Commands | *ESR? (query only) (on page 4-4) *STB? (query only) (on page 4-34) |

CONFigure:SOUNd[:STATe]

| | |
|------------------|--|
| | This command turns the key beep sound on or off. |
| Group | System |
| Syntax | CONFigure:SOUNd[:STATe] {0 1 ON OFF} CONFigure:SOUNd[:STATe]? |
| Arguments | 0 or OFF turns the key beep sound off. 1 or ON turns the key beep sound on. |
| Returns | 0 1 |
| Examples | CONF:SOUN:OFF CONF:SOUN? might return 0, indicating the key beeper is turned off. |

*ESE

| | |
|-------------------------|---|
| | Sets and queries the bits in the Event Status Enable Register (ESER). The ESER is an eight-bit mask register that determines which bits in the Standard Event Status Register (SESR) will set the ESB bit in the Status Byte Register (SBR) See Appendix C, Registers (on page C-3) for more information about registers. |
| Group | Status |
| Syntax | *ESE <mask> *ESE? |
| Related Commands | *CLS (no query form) (on page 4-2) *ESR? (query only) (on page 4-4) |
| Arguments | <mask> ::= <NR1> where: <NR1> is a value in the range from 0 through 255. The binary bits of the ESER are set according to this value. The power-on default for ESER is 0 if *PSC is 1. If *PSC is 0, the ESER maintains its value through a power cycle. |
| Examples | *ESE 145 sets the ESER to binary 10010001, which enables the PON, EXE, and OPC bits. *ESE might return the string *ESE 186, showing that the ESER contains the binary value 10111010. |

*ESR? (query only)

Returns the contents of the Standard Event Status Register (SESR). *ESR? also clears the SESR (since reading the SESR clears it) See Appendix C, [Registers](#) (on page C-3) for more information about SESR.

| | |
|-------------------------|---|
| Group | Status |
| Syntax | *ESR? |
| Related Commands | *CLS (no query form) (on page 4-2) *OPC (on page 4-7) *SRE (on page 4-27) |
| Returns | <NR1>, which is a decimal representation of the contents of the Standard Event Status Register (SESR). |
| Examples | *ESR? might return the value 149, showing that the SESR contains binary 10010101. |

FETCh:CURRent[:DC]? (query only)

This command returns the last measured output current stored in the communications buffer of the power supply. A new measurement is not initiated by this command.

| | |
|-------------------------|---|
| Group | Measurement |
| Syntax | FETCh:CURRent[:DC]? |
| Related Commands | MEASure:CURRent[:DC]? (query only) (on page 4-6) |
| Returns | <NR2>, which gives is the measured output current in amperes. |
| Examples | FETC:VOLT? might return 5.0011, which would be the measured voltage across the power supply outputs in volts. |

FETCh:VOLTage[:DC]? (query only)

This command returns the last measured output voltage stored in the communications buffer of the power supply. A new measurement is not initiated by this command.

| | |
|-------------------------|--|
| Group | Measurement |
| Syntax | FETCh:VOLTage[:DC]? |
| Related Commands | MEASure:VOLTage:DC]? (query only) (on page 4-7) |
| Returns | <NR2> is the measured output voltage in volts. |
| Examples | FETCh:VOLT? might return 5.0011, which would be the measured voltage across the power supply outputs in volts. |

FETCh[:SCALar]:POWER? (query only)

This command returns the last measured output current stored in the communications buffer of the power supply. A new measurement is not initiated by this command. The power calculation in the instrument is performed approximately every 100 ms. Insure that the voltage and current are stable longer than this for good results.

| | |
|-----------------|--|
| Group | Measurement |
| Syntax | FETCh[:SCALar]:POWER? |
| Returns | <NR2> is the measured output power in watts. |
| Examples | FETCh:POW? might return 6.01667, which would be the power measured at the output of the power supply in watts. |

*IDN? (query only)

Returns the power supply identification code in IEEE 488.2 notation.

| | |
|----------------|--|
| Group | Status |
| Syntax | *IDN? |
| Returns | A string that includes <manufacturer>, <model>, <serial number>, and <firmware_version> as defined in the following table. |

| <manufacturer> | <model> | <serial number> | <firmware_version> |
|----------------------|-----------|-----------------|--------------------|
| Keithley Instruments | 2200-XX-X | XX-X.XX. | X.XX-X.XX |

Examples *IDN? might return the following response for a 2200-72-1 instrument:

```
Keithley Instruments, 2200-72-1, 081003126672201022, 1.25-1.23
```

MEASure:CURRent[:DC]? (query only)

This command initiates and executes a new current measurement, and returns the measured output current of the power supply.

| | |
|-------------------------|--|
| Group | Measurement |
| Syntax | MEASure:CURRent[:DC]? |
| Related Commands | FETCh:VOLTage[:DC]? (query only) (on page 4-5) |
| Returns | <NR2> is the measured output current in amperes. |
| Examples | MEAS:CURR? might return 0.09998, which would be the measured current on the output of the power supply in amperes. |

MEASure:VOLTage[:DC]? (query only)

| | |
|-------------------------|---|
| | This command initiates and executes a new voltage measurement, and returns the measured output voltage of the power supply. |
| Group | Measurement |
| Syntax | MEASure:VOLTage[:DC]? |
| Related Commands | FETCh:VOLTage[:DC]? (query only) (on page 4-5) |
| Returns | <NR2> is the measured output voltage in volts. |
| Examples | MEAS:VOLT? might return 5.0011 which would be the voltage measured across the power supply output in volts. |

*OPC

| | |
|-----------------|--|
| | This command configures the instrument to generate an operation complete message by setting bit 0 of the Standard Event Status Register (SESR) when all pending commands that generate an OPC message are complete. The query command places the ASCII character "1" into the output queue when all such OPC commands are complete. |
| Group | Synchronization |
| Syntax | *OPC *OPC? |
| Examples | *OPC? might return 1 to indicate that all pending OPC operations are finished. |

*PSC

Sets and queries the power-on status flag that controls the automatic power-on execution of SRER and ESER. When *PSC is true, the SRER and ESER are set to 0 at power-on. When *PSC is false, the current values in the SRER and ESER are preserved in nonvolatile memory when power is shut off and are restored at power-on.

| | |
|-------------------------|---|
| Group | Source |
| Syntax | *PSC <NR1> *PSC? |
| Related Commands | *RST (no query form) *OPC (on page 4-7) |
| Arguments | <NR1> = 0 sets the power-on status clear flag to false, disables the power-on clear, and allows the power supply to possibly assert SRQ after power on. <NR1> ≠ 0 sets the power-on status clear flag to true. Sending *PSC 1 therefore enables the power-on status clear and prevents any SRQ assertion after power-on. |
| Returns | 0 1 |
| Examples | *PSC 0 sets the power-on status clear flag to false. *PSC? might return 1, indicating that the power-on status clear flag is set to true. |

*RCL (no query form)

Restores the state of the power supply from a copy of its settings stored in the setup memory. The settings are stored using the *SAV command. If the specified setup memory is deleted, this command causes an error.

| | |
|-------------------------|---|
| Group | Save and Recall |
| Syntax | *RCL <NR1> |
| Related Commands | *SAV (no query form) (on page 4-9) |
| Arguments | <NR1> is an integer value in the range from 0 to 40 and specifies the location of setup memory. |
| Examples | *RCL 3 sets the power supply to settings stored in memory location 3. |

*RST (no query form)

This command resets the power supply to default settings, but does not purge any stored settings.

Sending the *RST command does the following:

- Returns the power supply settings to the defaults described in [Default setup](#) (on page 2-33).
- Clears the pending operation flag and associated operations

The *RST command does not change the following items:

- State of the USB or GPIB interface
- Calibration data that affects device specifications
- Current GPIB power supply address
- Stored settings
- Output queue
- Service Request Enable Register settings
- Standard Event Status Enable Register settings
- Power-On Status Clear flag setting front-panel LOCK state

| | |
|---------------|--------|
| Group | Status |
| Syntax | *RST |

*SAV (no query form)

Saves the state of the power supply into a specified nonvolatile memory location. Any settings that had been stored previously at the location are overwritten. You can later use the *RCL command to restore the power supply to this saved state.

| | |
|-------------------------|--|
| Group | Status |
| Syntax | *SAV <NR1> |
| Related Commands | *RCL (no query form) (on page 4-9) |
| Returns | <NR1> is an integer value in the range from 1 to 40. |
| Examples | *SAV 2 saves the settings in memory location 2. |

[SOURce:]CURRent[:LEVel]

This command sets the current value of the power supply in units of A or mA.

| | |
|------------------|--|
| Group | Source |
| Syntax | [SOURce:]CURRent[:LEVel] {<current> MIN MAX DEF} [SOURce:]CURRent[:LEVel]? |
| Arguments | <current> ::= <NRf><units> where: <NRf> is a flexible decimal between the minimum current and maximum nameplate current for the power supply. <units> ::= {mA A} MIN sets the current to the minimum level (0 A). MAX sets the current to the maximum level. DEF sets the current to the default level (0.1 A). |
| Returns | <NR2> is the current setting in amperes. |
| Examples | CURR 3A CURR 30mA CURR MIN |

CURR? might return 2.0000, which would be the current setting in amperes.

[SOURce:]DIGital:DATA

This command sets the output state of the rear-panel TTL control output and queries the state of the rear-panel TTL control input. When the port mode is DIGITAL, this command is enabled.

Group

Source

Syntax

[SOURce:]DIGital:DATA <NR1>

[SOURce:]DIGital:DATA?

Arguments

<NR1> ::= {0 | 1} sets the binary state of the rear-panel TTL control output to low or high state, respectively.

Returns

<NR1> ::= {0 | 1 | 2 | 3} is a decimal representation of the state of the rear-panel TTL control output and input.

| Value | Input Pin 9 & 10 | Output Pin 11 & 12 |
|-------|------------------|--------------------|
| 0 | Low | Low |
| 1 | Low | High |
| 2 | High | Low |
| 3 | High | High |

Examples

DIGITAL:DATA ON

DIGITAL:DATA? might return 3, which would indicate that the TTL control input is high and the output is also high.

[SOURce:]DIGital:FUNcTion

This command sets or queries the function of the TTL control lines on the rear panel of the power supply.

*RST value is TRIGger.

| | |
|-------------------------|---|
| Group | Source |
| Syntax | [SOURce:]DIGital:FUNcTion {TRIGger RIDFi DIGital} [SOURce:]DIGital:FUNcTion? |
| Related Commands | TRIGger:SOURce (on page 4-39) [SOURce:]OUTPut:DFI:SOURce (on page 4-18) [SOURce:]DIGital:DATA (on page 4-11) |
| Arguments | <p>Port Mode: TRIGger In: Trigger In Out: N/A Description: Configures the TTL control input as an external trigger source.</p> <p>Port Mode: RIDFi In: RI Out: DFI Description: Configures the TTL control input as a remote inhibit (RI) input. The RI input can be used to turn the power supply output on or off from an external signal.</p> <p>Configures the TTL control output as a Discrete Fault Input (DFI). The DFI output provides a signal indicating that an overvoltage, over-temperature, or improper remote sense connection fault has occurred.</p> <p>Port Mode: DIGital In: DI Out: DO Description: It can read and control the output port state by command. It configures the TTL input and output for direct control using the [SOURce:]DIGital:DATA command.</p> |
| Returns | TRIG RIDF DIG |
| Examples | <p>DIGITAL:FUNCTION TRIGGER</p> <p>DIG:FUNC? might return RIDF, which would indicate that the TTL input and output are configure to function as remote inhibit and discrete fault input respectively.</p> |

[SOURce:]FUNCTION:MODE

This command can be in either fixed mode or list mode. When this command is in fixed mode, the power supply responds to discrete commands. When this command is in list mode, the power supply operates in list mode.

Fixed mode

Set this command to `FIXed` to edit a list file. Once the list is finalized and you are ready to use the list, set this command to `LIST` to operate in list mode.

List mode

Set this command to `LIST` to operate the power supply in list mode. Attempts to edit a list while this command is in list mode will generate an error message of `settings conflict`. If you need to change the list, set this command to `FIXed` before changing the list.

| | |
|------------------|---|
| Group | Source |
| Syntax | [SOURce:]FUNCTION:MODE {FIXed LIST} [SOURce:]FUNCTION:MODE? |
| Arguments | FIXed configures the power supply to respond to discrete commands. LIST configures the power supply to operate in list mode. |
| Returns | FIX LIST |
| Examples | [SOURCE:]FUNCTION:MODE LIST |

[SOURce:]LIST:COUNT

This command configures the number of times the active list will execute before stopping.

| | |
|-------------------------|--|
| Group | Source |
| Syntax | [SOURce:]LIST:COUNT {<NR1> ONCE REPeat} [SOURce:]LIST:COUNT? |
| Related Commands | [SOURce:]LIST:MODE (on page 4-15) [SOURce:]LIST:COUNT (on page 4-13) |
| Arguments | <NR1> is an integer between 2 and 65535. It determines the number of times the active list will execute. ONCE: configures the lists to execute once and stop. REPeat: configures the lists to loop continuously. |

Returns <NR1> is the number of times the active list is set to execute.

Examples LIST:COUNT 6 would set the active list to execute 6 times before stopping.

[SOURce:]LIST:CURRent[:LEVel]

This command sets the current for a list step in units of A or mA.

Group Source

Syntax [SOURce:]LIST:CURRent[:LEVel] <NR1>,<current>
[SOURce:]LIST:CURRent[:LEVel]? <NR1>

Related Commands [\[SOURce:\]LIST:VOLTage\[:LEVel\]](#) (on page 4-17)
[\[SOURce:\]LIST:WIDTh](#) (on page 4-17)

Arguments <NR1> is an integer in the range from 1 to 80, , which is a step number in the active list.

<current> ::= <NRf>[<units>]

where

<NRf> is a flexible decimal number used to specify a current setting in the range 0 amperes to the nameplate current rating of the power supply.

<units> ::= {A|mA}

Returns <NR2> is a decimal representing the current setting in amperes for the step specified in the query.

Examples LIST:CURR 1, 3A
LIST:CURR? 1 might respond with 3.0000, which indicates the current level setting for step number 1.

[SOURce:]LIST:MODE

| | |
|-------------------------|--|
| | This command determines the response of the power supply to a trigger in list mode. |
| Group | Source |
| Syntax | [SOURce:]LIST:MODE {CONTinuous STEP}[SOURce:]LIST:MODE? |
| Related Commands | [SOURce:]LIST:COUNt (on page 4-13), [SOURce:]LIST:STEP (on page 4-16) |
| Arguments | CONTinuous: Sets the power supply to execute the entire list in response to a trigger. STEP: Sets the power supply to execute one step per trigger. |
| Returns | CONT STEP |
| Examples | LIST:MODE CONT LIST:MODE? might respond with STEP to indicate that the active list is configured to wait for one trigger for each step. |

[SOURce:]LIST:RCL (no query form)

| | |
|-------------------------|---|
| | This command recalls a previously saved list from the specified storage location and makes it the active list for editing or execution. |
| Group | Source: List |
| Syntax | [SOURce:]LIST:RCL <NR1> |
| Related Commands | [SOURce:]LIST:SAVe (no query form) (on page 4-16) |
| Arguments | <NR1> is an integer in the range from 1 to 8, representing a list storage location. |
| Examples | LIST:RCL 5 would make the list stored in location 5 the active list for editing or execution. |

[SOURce:]LIST:SAVe (no query form)

This command saves the active list file to a storage location in non-volatile memory.

| | |
|-------------------------|---|
| Group | Source |
| Syntax | [SOURce:]LIST:SAVe <NR1> |
| Related Commands | [SOURce:]LIST:RCL (no query form) (on page 4-15) |
| Arguments | <NR1> is an integer in the range from 1 to 8, representing a list storage location. |
| Examples | LIST:SAV 4 saves the active list in list storage location 4. |

[SOURce:]LIST:STEP

This command configures the number of steps in the active list. The number of steps must be configured before loading the voltage levels, current levels, and/or durations of the steps.

| | |
|-------------------------|---|
| Group | Source |
| Syntax | [SOURce:]LIST:STEP {<NR1> MIN MAX} [SOURce:]LIST:STEP? |
| Related Commands | [SOURce:]LIST:COUNt (on page 4-13), [SOURce:]LIST:MODE (on page 4-15) |
| Arguments | <NR1> is an integer in the range from 2 to 80, representing the number of steps to be configured in the list. |
| Returns | <NR1> is the number of steps configured in the active list. |
| Examples | Examples are provided in Programming examples (on page 4-40). |

[SOURce:]LIST:VOLTage[:LEVel]

| | |
|------------------|---|
| | This command sets the voltage level of a specified step in a list in units of V or mV. |
| Group | Source: List |
| Syntax | [SOURce:]LIST:VOLTage[:LEVel] <NR1>,<voltage> |
| Arguments | <p><NR1> is an integer in the range from 1 to 80, which is a step number in the active list.</p> <p><voltage> ::= <NRf><units></p> <p>where:</p> <p><NRf> is a flexible decimal that sets the voltage level fro the step.</p> <p><units> ::= {V mV}</p> |
| Returns | <NR2> |
| Examples | <p>LIST:VOLT 1, 3V</p> <p>LIST:VOLT? 1 might return 3.0000, which would be the voltage level for step number 1.</p> |

[SOURce:]LIST:WIDth

| | |
|-------------------------|---|
| | This command sets the duration of a specified step in a list. |
| Group | Source |
| Syntax | [SOURce:]LIST:WIDth <NR1>,{<duration> MIN MAX} [SOURce:]LIST:WIDth? <NR1> |
| Related Commands | [SOURce:]LIST:VOLTage[:LEVel] (on page 4-17) [SOURce:]LIST:CURRent[:LEVel] (on page 4-14) |
| Arguments | <p><NR1> is an integer in the range from 1 to 80, which is a step number in the active list. <duration> ::= <NRf><units></p> <p>where:</p> <p><NRf> is the time duration of the step <units> ::= {s ms}</p> |
| Returns | <NR2> |
| Examples | <p>LIST:WIDTH 12, 100ms</p> <p>LIST:WIDTH? 12 might return 0.1, which would be the duration of step 12.</p> |

[SOURce:]OUTPut:DFI:SOURce

This command associates the DFI TTL output on the rear panel with a specified bit in the status byte register (SBR). Once the bit is associated with the DFI signal, the DFI signal will reflect the state of the specified bit. The port needs to be in the DFI or RI mode before using this command. Use the [\[SOURce:\]DIGital:FUNcTion](#) (on page 4-12) command to set the port mode.

*RST value is OFF.

Group

Source: Digital I/O

Syntax

```
[SOURce:]OUTPut:DFI:SOURce
{OFF|QUES|OPER|ESB|RQS}
```

```
[SOURce:]OUTPut:DFI:SOURce?
```

Related Commands

[\[SOURce:\]DIGital:FUNcTion](#) (on page 4-12)

Arguments

OFF: the output level of the DFI output pin remains high.

QUES: the output level of the DFI output pin reflects the complement of the state of the QUES bit. For example, when the QUES bit is 1, the DFI output pin is low.

OPER: the output level of the DFI output pin reflects the state of the OPER bit.

ESB: the output level of the DFI output pin reflects the state of the ESB bit.

RQS: the output level of the DFI output pin reflects the state of the RQS bit.

Returns

```
OFF|QUES|OPER|ESB|RQS
```

Examples

`OUTPut:DFI:SOURCE QUES` sets the DFI signal to respond to the state of the QUES bit in the status byte register (SBR).

[SOURce:]OUTPut:PON[:STATe]

This command configures the power supply to power up with its output turned off, or to return the output to the state it was in when it powered down.

| | |
|------------------|--|
| Group | Source |
| Syntax | [SOURce:]OUTPut:PON[:STATe] {RST RCL0} [SOURce:]OUTPut:PON[:STATe]? |
| Arguments | RST sets the power supply to power-up with output off. RCL0 sets the power supply to power-up with the output in the last state before power was removed. |
| Returns | RST RCL0 |
| Examples | OUTPUT:PON RST OUTPUT:PON? might return RCL0, which would indicate that the instrument will return to the present output state if the power is cycled. |

[SOURce:]OUTPut:PROTection:CLEar (no query form)

This command clears a trip condition caused by over voltage (OV), over temperature (OT), or remote inhibit (RI).

| | |
|-------------------------|--|
| Group | Source |
| Syntax | [SOURce:]OUTPut:PROTection:CLEar |
| Related Commands | [SOURce:]VOLTage:PROTection[:LEVel] (on page 4-24) |
| Examples | OUTP:PROT:CLE |

[SOURce:]OUTPut:RI:MODE

This command sets the input mode of the RI (remote inhibit) input pin. In order for this command to be effective, the rear panel TTL input and output must be configured in RI/DFI mode using the [\[SOURce:\]DIGital:FUNcTion](#) (on page 4-12) command.

| | |
|-------------------------|---|
| Group | Source |
| Syntax | [SOURce:]OUTPut:RI:MODE {OFF LATChing LIVE} [SOURce:]OUTPut:RI:MODE? |
| Related Commands | [SOURce:]DIGital:FUNcTion (on page 4-12) |
| Arguments | <p>OFF: The level of the RI input pin does not affect the output state of the power supply.</p> <p>LATChing: When the level of the RI input pin changes from high to low, the output of power supply turns off.</p> <p>LIVE: The output state of power supply changes according to the level of the RI input pin. While the level is TTL high, the output will be on. While the level is TTL low, the output of the power supply will be off.</p> |
| Returns | OFF LATC LIVE |
| Examples | <p>OUTP:RI:MODE LATC</p> <p>OUTP:RI:MODE? might return OFF, which would indicate that remote inhibit is not controlling the output of the instrument.</p> |

[SOURce:]OUTPut[:STATe]

This command turns the power supply output channel on or off.

| | |
|-------------------------|---|
| Group | Source |
| Syntax | [SOURce:]OUTPut[:STATe] {0 1 ON OFF} [SOURce:]OUTPut[:STATe]? |
| Related Commands | [SOURce:]VOLTage:PROTection[:LEVel] (on page 4-24) [SOURce:]VOLTage:RANGe (on page 4-26) |
| Arguments | <p>0 or OFF turns the power supply output off.</p> <p>1 or ON turns the power supply output on.</p> |
| Returns | 1 0 |

Examples

```
OUTPUT ON
```

OUTPUT? might return 0, which would indicate that the output is off.

[SOURce:]OUTPut:TIMer:DElay

This command sets the time duration of the output timer. When the timer is activated and a duration is set, the output of the power supply will turn off automatically if left on longer than the specified duration. In order to ensure proper operation of the output timer, the timer must be activated using the [\[SOURce:\]OUTPut:TIMer:STATe\]](#) (on page 4-22) command before turning the output on.

Group

Source

Syntax

```
[SOURce:]OUTPut:TIMer:DElay
{<duration>|MIN|MAX|DEF}
```

```
[SOURce:]OUTPut:TIMer:DElay?
```

**Related
Commands**

[\[SOURce:\]OUTPut:TIMer:STATe\]](#) (on page 4-22)
[\[SOURce:\]OUTPut:STATe\]](#) (on page 4-20)

Arguments

```
<duration> ::= <NRf><units>
```

where:

<NRf> is a flexible decimal specifying time in the range 0.01s (or 10ms) to 60000s.

```
<units> ::= {S|ms}
```

MIN: The minimum time of the output timer (0.01 s).

MAX: The maximum time of the output timer (60,000 s).

DEF: The default time of the output timer (60 s).

Returns

<NR2> is the timer duration in seconds.

Examples

```
OUTP:TIM:DEL MIN
```

OUTP:TIM:DEL? might return 60.2, which would represent the maximum time, in seconds, that the output of the instrument could be turned on if the timer is active.

[SOURce:]OUTPut:TIMer[:STATe]

This command turns the output timer function on and off. When the timer is activated and a duration is set, the output of the power supply will turn off automatically if left on longer than the specified duration. In order to ensure proper operation of the output timer, the power supply must be turned on by using the [\[SOURce:\]OUTPut:TIMer\[:STATe\]](#) (on page 4-22) command.

| | |
|-------------------------|---|
| Group | Source |
| Syntax | [SOURce:]OUTPut:TIMer[:STATe] {0 1 ON OFF} [SOURce:]OUTPut:TIMer[:STATe]? |
| Related Commands | [SOURce:]OUTPut:PROTection:CLEar (no query form) (on page 4-19) [SOURce:]OUTPut:TIMer:DELay (on page 4-21) [SOURce:]OUTPut[:STATe] (on page 4-20) |
| Arguments | 0 or OFF turns the output timer off. 1 or ON turns the output timer on. |
| Returns | 0 1 |
| Examples | To start timer, first send OUTPUT:TIMER:STATE ON, then send OUTPUT:STATE ON. To end timer (turn timer off), send OUTPUT:TIMER:STATE OFF. |

[SOURce:]VOLTage[:LEVel]

| | |
|-------------------------|--|
| | This command sets the voltage value of the power supply. |
| Group | Source |
| Syntax | [SOURce:]VOLTage[:LEVel] {<NRf> MIN MAX DEF} [SOURce:]VOLTage[:LEVel]? |
| Related Commands | [SOURce:]CURRent[:LEVel] (on page 4-10) |
| Arguments | <p><voltage></p> <p>where:</p> <p><voltage> ::= <NRf><units></p> <p><NRf> is a flexible decimal specifying the voltage setting, ranging from 0 to the maximum nameplate voltage of the power supply.</p> <p><units> ::= {V mV kV}</p> <p>MIN sets the voltage to the minimum level (0 V).</p> <p>MAX sets the voltage to the maximum level (note that the maximum level may be somewhat higher than the nameplate).</p> <p>DEF is the default level (1 V).</p> |
| Returns | NR2 is the voltage setting in volts. |
| Examples | <p>VOLTAGE:MIN</p> <p>VOLTAGE? might return 1.05, which would be the voltage setting in volts.</p> |

[SOURce:]VOLTage:PROTection[:LEVel]

| | |
|-------------------------|--|
| | This command sets the over voltage protection (OVP) threshold level. |
| Group | Source |
| Syntax | <pre>[SOURce:]VOLTage:PROTection[:LEVel] {<voltage> MIN MAX DEF} [SOURce:]VOLTage:PROTection[:LEVel]?</pre> |
| Related Commands | [SOURce:]VOLTage:PROTection[:LEVel] (on page 4-24) [SOURce:]VOLTage:RANGe (on page 4-26) |
| Arguments | <p><voltage> ::= <NRf><units></p> <p>where:</p> <p><NRf> is a flexible decimal that specifies the OVP threshold, ranging from 0 to the maximum OVP level</p> <p><units> ::= {V mV}</p> <p>MIN: sets the minimum OVP level (1 V).</p> <p>MAX: sets the maximum OVP level, which is approximately 10% higher than the maximum output voltage rating of the power supply.</p> <p>DEF: sets the OVP level to the default level, which is equal to MAX.</p> |
| Returns | <p><NR2> is the OVP threshold in volts.</p> <p>MIN: set to minimum OVP level.</p> <p>MAX: set to maximum OVP level.</p> |
| Examples | <pre>VOLT:PROT 30V</pre> <p>VOLT:PROT? might return 30, which would be the OVP threshold in volts.</p> |

[SOURce:]VOLTage:PROTection:STATe

This command activates, deactivates, or checks the status of overvoltage protection (OVP).

Group

Source

Syntax

[SOURce:]VOLTage:PROTection:STATe {0|1|OFF|ON}

[SOURce:]VOLTage:PROTection:STATe?

**Related
Commands**

[\[SOURce:\]VOLTage:PROTection\[:LEVel\]](#) (on page 4-24)

[\[SOURce:\]VOLTage:RANGe](#) (on page 4-26)

Arguments

0 or OFF sets the over voltage protection to off.

1 or ON sets the over voltage protection to on.

Returns

0|1 means the over voltage protection is off.

Examples

VOLT:PROT:STAT 1

VOLT:PROT:STAT? might return 1, which would indicate that overvoltage protection is active.

[SOURce:]VOLTage:RANGe

This command limits the maximum voltage that can be programmed on the power supply. This command corresponds to the front-panel Max Voltage setting that can be found under the Protection submenu. This function is different from OVP, since it cannot turn the output off.

| | |
|-------------------------|---|
| Group | Source |
| Syntax | [SOURce:]VOLTage:RANGe {<voltage> MIN MAX DEF} [SOURce:]VOLTage:RANGe? |
| Related Commands | [SOURce:]VOLTage:PROTection[:LEVel] (on page 4-24) [SOURce:]VOLTage:PROTection:STATe (on page 4-25) |
| Arguments | <voltage> ::= <NRf><units> where: <NRf> is a flexible decimal that sets the maximum output voltage, ranging from 0 to the maximum nameplate voltage <units> ::= {V mV kV} MIN: sets the voltage limit to the minimum value (0 V). MAX: sets the voltage limit to the maximum value which is slightly higher than the maximum nameplate voltage. DEF: sets the voltage limit to the default value, which equals MAX. |
| Returns | <NR2> is the voltage limit in volts. |
| Examples | VOLT:RANG 3.2V VOLT:RANG? might return 3.2, which would be the maximum programmable voltage in volts. |

***SRE**

Service request enable (SRE) sets and queries the bits in the service request enable register (SRER). See Appendix C, [Registers](#) (on page C-3) for more information about SRER.

| | |
|-------------------------|--|
| Group | Status |
| Syntax | *SRE <NR1> *SRE? |
| Related Commands | *CLS (no query form) (on page 4-2) *ESR? (query only) (on page 4-4) *PSC (on page 4-8) |
| Arguments | <NR1> is an integer value in the range from 0 to 255. The binary bits of the SRER are set according to this value. Using an out-of-range value causes an execution error. The power-on default for SRER is 0 if *PSC is 1. If *PSC is 0, the SRER maintains its value through a power cycle. |
| Examples | *SRE 48 sets the bits in the SRER to 00110000 binary. *SRE? might return a value of 32, showing that the bits in the SRER have the binary value 00100000. |

STATus:OPERation:CONDition? (query only)

This command returns the contents of the operation condition register (OCR). Details on the OCR are available in Appendix C, [Registers](#) (on page C-3).

| | |
|-------------------------|--|
| Group | Status |
| Syntax | *SRE <NR1> *SRE? |
| Related Commands | *CLS (no query form) (on page 4-2) *ESR? (query only) (on page 4-4) *PSC (on page 4-8) |
| Arguments | <NR1> is an integer value in the range from 0 to 255. The binary bits of the service request enable register (SRER) are set according to this value. Using an out-of-range value causes an execution error. The power-on default for SRER is 0 if *PSC is 1. If *PSC is 0, the SRER maintains its value through a power cycle. |
| Examples | *SRE 48 sets the bits in the SRER to 00110000 binary. *SRE? might return a value of 32, showing that the bits in the |

SRER have the binary value 00100000.

STATus:OPERation:ENABLE

This command sets and queries the contents of the operation enable register (OENR). The OENR is an eight-bit mask register that determines which bits in the Operation Event Register (OEVR) will affect the state of the OPER bit in the Status Byte Register (SBR). Details about the status registers are available in Appendix C, [Registers](#) (on page C-3).

| | |
|-------------------------|---|
| Group | Status |
| Syntax | <pre>STATus:OPERation:ENABLE <NR1> STATus:OPERation:ENABLE?</pre> |
| Related Commands | <pre>STATus:OPERation:ENABLE STATus:OPERation:EVENT? (query only) (on page 4-29)</pre> |
| Arguments | <pre><mask>::=<NR1></pre> <p>where:</p> <p><NR1> is a decimal integer ranging from 0 through 255. The binary bits of the OENR are set according to this value.</p> |
| Returns | <mask> |
| Examples | <pre>STATUS:OPERATION:ENABLE 8</pre> <p>STATUS:OPERATION:ENABLE? might return 8, which would indicate that only the Constant Current bit of the Operation Event Register would affect the OPER bit of the Status Byte Register.</p> |

STATus:OPERation[:EVENT]? (query only)

This command returns the contents of the operation event register (OEVR). After executing this command the operation event register is reset. Details about the status registers are available in Appendix C, [Registers](#) (on page C-3).

| | |
|-------------------------|--|
| Group | Status |
| Syntax | STATus:OPERation[:EVENT]? |
| Related Commands | STATus:OPERation:CONDition? (query only) (on page 4-27) STATus:OPERation[:EVENT]? (query only) (on page 4-29) |
| Arguments | <NR1> is a decimal integer representation of the contents of the Operation Event Register (OEVR), ranging from 0 to 255. |
| Examples | STATUS:OPERATION:EVENT? might return 10, which indicates that the power supply is waiting for trigger and is in a constant current mode. |

STATus:QUEStionable:CONDition? (query only)

This command returns the contents of the questionable condition register (QCR). Details about the status registers are available in Appendix C, [Registers](#) (on page C-3).

| | |
|-------------------------|---|
| Group | Status |
| Syntax | STATus:QUEStionable:CONDition? |
| Related Commands | STATus:QUEStionable:ENABle (on page 4-30) STATus:QUEStionable[:EVENT]? (query only) (on page 4-31) |
| Returns | <NR1> is a decimal integer representation of the contents of the Questionable Condition Register (OCR), ranging from 0 to 255. |
| Examples | STATUS:QUESTIONABLE:CONDITION? might return 1, which would indicate an over voltage condition. |

STATus:QUEStionable:ENABle

This command sets and queries the contents of the questionable enable register (QENR). The QENR is an eight-bit mask register that determines which bits in the Questionable Event Register (QEVr) will affect the state of the QUES bit in the Status Byte Register (SBR).

| | |
|-------------------------|--|
| Group | Status |
| Syntax | <pre>STATus:QUEStionable:ENABle <mask> STATus:QUEStionable:ENABle?</pre> |
| Related Commands | <p>STATus:QUEStionable:EVENTj? (query only) (on page 4-31)</p> <p>STATus:QUEStionable:CONDition? (query only) (on page 4-29)</p> <p>STATus:QUEStionable:PTRansition (on page 4-33)</p> <p>STATus:QUEStionable:NTRansition (on page 4-32)</p> <p>*PSC (on page 4-8)</p> |
| Arguments | <pre><mask> ::= <NR1></pre> <p>where:</p> <p><NR1> is a decimal integer ranging from 0 through 255. The binary bits of the QENR are set according to this value.</p> |
| Returns | <mask> |
| Examples | <pre>STATus:QUESTIONABLE:ENABle 8</pre> <p>STATus:QUESTIONABLE:ENABle? might return 8, which would indicate that only a transition of the Remote Inhibit bit of the QCR would affect the QUES bit of the Status Byte Register.</p> |

STATus:QUEStionable[:EVENT]? (query only)

This command returns the contents of the questionable event register (QEVr). After executing this command, the quest event register is reset. Details about the QEVr are available in Appendix C, [Registers](#) (on page C-3).

| | |
|-------------------------|---|
| Group | Status |
| Syntax | STATus:QUEStionable[:EVENT]? |
| Related Commands | <p>STATus:QUEStionable[:EVENT]? (query only) (on page 4-31)</p> <p>STATus:QUEStionable:CONDition? (query only) (on page 4-29)</p> <p>STATus:QUEStionable:PTRansition (on page 4-33)</p> <p>STATus:QUEStionable:NTRansition (on page 4-32)</p> |
| Arguments | <p><mask> ::= <NR1></p> <p>where:</p> <p><NR1> is a decimal integer ranging from 0 through 255. The binary bits of the QENR are set according to this value.</p> |
| Returns | <mask> |
| Examples | <p>STATus:QUESTIONABLE:ENABLE 8</p> <p>STATus:QUESTIONABLE:ENABLE? might return 8, which would indicate that only a transition of the Remote Inhibit bit of the QCR would affect the QUES bit of the Status Byte Register.</p> |

STATus:QUEStionable:NTRansition

This command sets the negative transition filter of the questionable event register. The filter contents cause the corresponding bit in the questionable event register to become 1 when the bit value of the questionable condition register transitions from 1 to 0.

| | |
|-------------------------|---|
| Group | Status |
| Syntax | <pre>STATus:QUEStionable:NTRansition <mask> STATus:QUEStionable:NTRansition?</pre> |
| Related Commands | <p>STATus:QUEStionable:ENABle (on page 4-30)</p> <p>STATus:QUEStionable:EVENTf? (query only) (on page 4-31)</p> <p>STATus:QUEStionable:CONDition? (query only) (on page 4-29)</p> <p>STATus:QUEStionable:PTRansition (on page 4-33)</p> |
| Arguments | <pre><mask> ::= <NR1></pre> <p>where:</p> <p><NR1> is a number ranging from 0 through 255. The binary bits of the Questionable NTR register are set according to this value.</p> |
| Returns | <mask> |
| Examples | <pre>STATUS:QUESTIONABLE:NTRANSITION 8</pre> <p>STATUS:QUESTIONABLE:NTRANSITION? might return 8, which would indicate that a negative transition on the Remote Inhibit bit of the questionable condition register would be registered as an event.</p> |

STATus:QUEStionable:PTRansition

This command sets the positive transition filter of the questionable event register. The filter contents cause the corresponding bit in the questionable event register to become 1 when the bit value of the questionable condition register transitions from 0 to 1.

| | |
|-------------------------|--|
| Group | Status |
| Syntax | <pre>STATus:QUEStionable:PTRansition <mask> STATus:QUEStionable:PTRansition?</pre> |
| Related Commands | <p>STATus:QUEStionable:ENABle (on page 4-30)</p> <p>STATus:QUEStionable:EVENTn]? (query only) (on page 4-31)</p> <p>STATus:QUEStionable:CONDition? (query only) (on page 4-29)</p> <p>STATus:QUEStionable:NTRansition (on page 4-32)</p> |
| Arguments | <pre><mask> ::= <NR1></pre> <p>where:</p> <p><NR1> is a number ranging from 0 through 255. The binary bits of the questionable PTR register are set according to this value.</p> |
| Returns | <mask> |
| Examples | <pre>STATUS:QUESTIONABLE:PTRANSITION 8</pre> <p>STATUS:QUESTIONABLE:PTRANSITION? might return 8 which would indicate that a positive transition on the Remote Inhibit bit of the questionable condition register would be registered as an event.</p> |

*STB? (query only)

| | |
|-------------------------|--|
| | The byte query returns the contents of the status byte register (SBR) using the Master Summary Status (MSS) bit. Refer to Appendix C, Registers (on page C-3) for more information. |
| Group | Status |
| Syntax | *SRE <NR1> *SRE? |
| Related Commands | *CLS (no query form) (on page 4-2) *ESR? (query only) (on page 4-4) *PSC (on page 4-8) |
| Arguments | <NR1> is an integer value in the range from 0 to 255. The binary bits of the SRER are set according to this value. Using an out-of-range value causes an execution error. The power-on default for SRER is 0 if *PSC is 1. If *PSC is 0, the SRER maintains its value through a power cycle. |
| Returns | *SRE 48 sets the bits in the SRER to 00110000 binary. |
| Examples | *SRE? might return a value of 32, showing that the bits in the SRER have the binary value 00100000. |

SYSTem:ERRor? (query only)

| | |
|-----------------|--|
| | This command queries the error code and error information of the power supply and returns both values. See Messages and codes (on page C-9) for information about the codes. |
| Group | System |
| Syntax | SYSTem:ERRor? |
| Returns | <NR1>, <error_text> <error_text> ::= <string> where: <string> is a description of the error. |
| Examples | SYSTEM:ERROR? might return 110, which means No Input Command to parse. |

SYSTem:KEY

This command can produce the same effect as pressing one of the front-panel buttons. The instrument must be in local mode in order for this command to simulate a front-panel button press.

| | |
|------------------|---|
| Group | System |
| Syntax | SYSTem:KEY <NR1> SYSTem:KEY? |
| Arguments | <NR1> is an integer key code (see the following table). |
| Returns | <NR1> |

| Front-panel button | <NR1> key code |
|--------------------|----------------|
| KEY_VSET | 1 |
| KEY_ISET | 2 |
| KEY_SAVE | 3 |
| KEY_RECALL | 4 |
| KEY_LEFT | 5 |
| KEY_RIGHT | 6 |
| KEY_UP | 7 |
| KEY_DOWN | 8 |
| KEY_0 | 9 |
| KEY_1 | 10 |
| KEY_2 | 11 |
| KEY_3 | 12 |
| KEY_4 | 13 |
| KEY_5 | 14 |
| KEY_6 | 15 |
| KEY_7 | 16 |
| KEY_8 | 17 |
| KEY_9 | 18 |
| KEY_DECIMAL | 19 |
| KEY_ESC | 20 |
| KEY_ENTER | 21 |
| KEY_ON | 22 |
| KEY_SHIFT | 64 |

Examples SYSTem:KEY 64 would simulate a press of the Shift key.

SYSTem:LOCal (no query form)

| | |
|-------------------------|---|
| | <p>This command sets the power supply for control from the front-panel.</p> |
| Group | System |
| Syntax | SYSTem:LOCal |
| Related Commands | SYSTem:LOCal (no query form) (on page 4-36) SYSTem:RWLock (no query form) (on page 4-37) |
| Examples | SYS:LOC |

SYSTem:POSetup

| | |
|------------------|---|
| | <p>This command determines how the power supply initializes when its power switch is turned on. This command configures the instrument to power up with default settings, or power up with the settings that were in effect when the instrument was turned off.</p> |
| Group | System |
| Syntax | SYSTem:POSetup {RST RCL0} SYSTem:POSetup? |
| Arguments | <p>RST: initializes the power supply to default settings after a power cycle.</p> <p>RCL0: saves the most recent settings and restores these after a power cycle.</p> |
| Returns | <p>RST: default settings are applied after a power cycle.</p> <p>RCL0: most recent settings are saved and restored after a power cycle.</p> |
| Examples | <p>SYST:POS RST</p> <p>SYSTEM:POSETUP? might respond with RST, which would indicate that the power supply is configured to restore the power supply to default settings when it powers up.</p> |

SYSTem:REMOte (no query form)

| | |
|-------------------------|---|
| | This command sets the power supply to remote control mode. |
| Group | System |
| Syntax | SYSTem:REMOte |
| Related Commands | SYSTem:LOCAl (no query form) (on page 4-36) SYSTem:RWLock (no query form) (on page 4-37) |
| Arguments | None. |
| Examples | SYSTEM:REMOTE |

SYSTem:RWLock (no query form)

If the power supply is in remote mode, this command locks out the front panel LOCAL button. This command has no effect if the instrument is in local mode.

| | |
|-------------------------|---|
| Group | System |
| Syntax | SYSTem:RWLock |
| Related Commands | SYSTem:REMOte (no query form) (on page 4-37) SYSTem:LOCAl (no query form) (on page 4-36) |
| Arguments | None |
| Examples | SYSTEM:RWLOCK |

SYSTem:VERSion? (query only)

This command returns SCPI version of the instrument.

| | |
|-----------------|--|
| Group | System |
| Syntax | SYSTem:VERSion? |
| Returns | <NR2> is the software version of the power supply. |
| Examples | SYSTEM:VERSION? might return 1991.0, which is the SCPI version number. |

*TRG (no query form)

| | |
|-------------------------|--|
| | This command generates a trigger event. |
| Group | Trigger |
| Syntax | *TRG |
| Related Commands | TRIGger[:IMMEDIATE] (no query form) (on page 4-38) |
| Examples | *TRG |

TRIGger[:IMMEDIATE] (no query form)

| | |
|-------------------------|---|
| | This command forces an immediate trigger event. |
| Group | Trigger |
| Syntax | RIGger[:IMMEDIATE] |
| Related Commands | *TRG (no query form) (on page 4-38) |
| Arguments | None |
| Examples | TRIGGER |

TRIGger:SOURce

| | |
|-------------------------|---|
| | This command sets the source of trigger events. |
| Group | Trigger |
| Syntax | TRIGger:SOURce {MANual IMMEDIATE EXTERNAL BUS} TRIGger:SOURce? |
| Related Commands | [SOURCE:]DIGital:FUNCTION (on page 4-12) *TRG (no query form) (on page 4-38) TRIGger[:IMMEDIATE] (no query form) (on page 4-38) |
| Arguments | <p>MANual: When this value is sent, the power supply will wait for a trigger from the front-panel. Press Shift + Trigger (3) to trigger the power supply.</p> <p>IMMEDIATE: When this value is sent, the power supply will wait for a TRIGger:IMMEDIATE bus command.</p> <p>EXTERNAL: When this value is sent, the power supply can be triggered with a TTL pulse applied to pin 1 of the terminal connector in the rear. The pulse width should be at least 5 ms.</p> <p>BUS: When this value is sent, the power supply can be triggered by sending a *TRG or TRIGger:IMMEDIATE command to the power supply.</p> |
| Examples | TRIGGER:SOURCE BUS |

*TST? (query only)

| | |
|----------------|---|
| | Initiates a self-test and reports any errors. |
| Group | Diagnostic |
| Syntax | *TST? |
| Returns | <p><NR1></p> <p>where:</p> <p><NR1>= 0 indicates that the self-test completed with no errors.</p> <p><NR1> not equal to 0 indicates that the self test detected an error. Self test code descriptions are described in Self test errors (on page C-11).</p> |

***WAI (no query form)**

This command prevents the instrument from executing further commands or queries until all pending commands are complete.

| | |
|-----------------|-----------------|
| Group | Synchronization |
| Syntax | *WAI |
| Examples | *WAI |

Programming examples

This topic provides the following programming examples:

Example 1

This example is written in the C programming language, the Virtual Instrument Software Architecture (VISA) standard can be used. It demonstrates basic communication with the power supply and error checking. The program establishes communication with the power supply, and puts it into remote mode. It then initializes the voltage and current and turns the output on. It sends new values for the voltage and current, and reads back the actual meter values before turning off the power supply output and closing communications.

```
// pws_visa.cpp
//
#include "stdafx.h"
    #include <visa.h>
    #include <stdio.h>
    #include <string.h>
    #include <time.h>
    #include <conio.h>
#include <stdlib.h>
ViSession defaultRM; //Resource manager id
ViSession PWS4000; //Identifies the power supply
long ErrorStatus;
char commandString[256];
char ReadBuffer[256];
void OpenPort();
void SendSCPI(char* pString);
void CheckError(char* pMessage);
void delay(clock_t wait);
void ClosePort();
int main(int argc, _TCHAR* argv[])
{
double voltage;
char Buffer[256];
double current;
OpenPort();
//Query the power supply id, read response and print it
sprintf(Buffer, "*IDN?");
SendSCPI(Buffer);
printf("Instrument identification string:%s \n", Buffer);
SendSCPI("*RST"); //reset the power supply
SendSCPI("CURRENT 0.1A"); //set the current to 0.1A
SendSCPI("VOLTAGE 3V"); //set the voltage to 3V
SendSCPI("OUTPUT 1"); // turn output on
voltage=5.0;
current=0.2;
printf("Setting voltage(V) & current(A): %f,%f \n",
voltage, current);
ErrorStatus = viPrintf(PWS4000,"VOLT %f\n",voltage); //set
the output voltage
CheckError("Unable to set voltage");
ErrorStatus = viPrintf(PWS4000,"CURRENT %f\n",current);
//set the output current
CheckError("Unable to set current");
ErrorStatus = viPrintf(PWS4000,"MEASURE:VOLTAGE?\n");
//measure the output voltage
CheckError("Unable to write the device");
ErrorStatus = viScanf(PWS4000,"%f",&voltage); //retrieve
```

```

reading
CheckError("Unable to read voltage");
ErrorStatus = viPrintf(PWS4000,"MEASURE:CURRENT?\n");
//measure the output current
CheckError("Unable to write the device");
ErrorStatus = viScanf(PWS4000,"%f",&current); //retrieve
reading
CheckError("Unable to read current");
printf("Measured voltage(V) & current(A): %f,%f \n",
voltage, current);
SendSCPI("OUTPUT 0"); //turn output off
ClosePort();
while(1);
//return 0;
}
void OpenPort()
{
//Open communication session with the power supply, and
put the power supply in remote
ErrorStatus = viOpenDefaultRM(& defaultRM);
ErrorStatus =viOpen(defaultRM,
"USB0::0X0699::0X0391::006002206573001001::INSTR",0,0,&PWS4000);
CheckError("Unable to open the port");
SendSCPI("SYSTEM:REMOTE");
}
void SendSCPI(char* pString)
{
char* pdest;
strcpy(commandString,pString);
strcat(commandString, "\n");
ErrorStatus = viPrintf(PWS4000, commandString);
CheckError("Can't Write to Power Supply");
pdest = strchr(commandString, '?'); //Search for query
command
if (pdest != NULL)
{
ErrorStatus = viBufRead(PWS4000, (ViBuf)ReadBuffer,
sizeof(ReadBuffer), VI_NULL);
CheckError("Can't read from driver");
strcpy(pString, ReadBuffer);
}
}
void ClosePort()
{
viClose(PWS4000);
viClose(defaultRM);
}
void CheckError(char* pMessage)
{
if(ErrorStatus != VI_SUCCESS)
{
printf("\n %s",pMessage);
ClosePort();
exit(0);
}
}
void delay(clock_t wait)

```

```
{
clock_t goal;
goal = wait + clock();
while(goal > clock());
}
```

Example 2

This example shows a command sequence that configures a three-step list to execute once in continuous mode. It saves the list in location 1, and then places the instrument in list mode and runs the list.

```
SYSTEM:REMOTE
*RST
TRIGGER:SOURCE BUS
LIST:MODE CONT
LIST:COUNT ONCE
LIST:STEP 3
LIST:VOLT 1,2V
LIST:CURRENT 1,1.0A
LIST:WIDTH 1,5s
LIST:VOLT 2,4V
LIST:CURRENT 2,1.0A
LIST:WIDTH 2,10s
LIST:VOLT 3,0V
LIST:CURRENT 3,0.1A
LIST:WIDTH 3,2s
LIST:SAVE 1
FUNCTION:MODE LIST
OUTPUT ON
TRIGGER IMMEDIATE
```

Example 3

This example shows a command sequence that configures a two-step list to execute 20 times. It saves the list in location 1, and then places the instrument in list mode and runs the list.

```
SYSTEM:REMOTE
*RST
TRIGGER:SOURCE BUS
LIST:MODE CONT
LIST:COUNT 20
LIST:STEP 2
LIST:VOLTAGE 1,5V
LIST:CURRENT 1,1.0A
LIST:WIDTH 1,10s
LIST:VOLTAGE 2,5.5V
LIST:CURRENT 2,1.0A
LIST:WIDTH 2,5s
LIST:SAVE 1
FUNCTION:MODE LIST
OUTPUT ON
TRIGGER:IMMEDIATE
```

Example 4

This example is written in the C programming language; NI VISA can be used. The program demonstrates setting up and executing a list. It shows how to use the Operation Condition Register to determine when the list has finished executing.

```
// pws_visa.c
//
#undef MICROSOFT // Change this to #define if Microsoft
#ifdef MICROSOFT
#include "stdafx.h"
#include <conio.h>
#else
typedef char _TCHAR;
#endif
#include <visa.h>
#include <stdio.h>
#include <string.h>
#include <time.h>
#include <stdlib.h>
ViSession defaultRM; //Resource manager id
ViSession PWS4000; //Identifies the power supply
long ErrorStatus;
char commandString[256];
char ReadBuffer[256];
//
// Some compilers do not require that void arguments be
// declared, however, all should accept declaration of
// void argument lists.
//
void OpenPort(); // void added
void SendSCPI(char* pString);
void CheckError(char* pMessage);
void delay(clock_t wait);
void ClosePort(); // void added
int main(int argc, _TCHAR* argv[])
{
double voltage;
char Buffer[256];
double current;
int OPERreg,i;
float meas_voltage, meas_current;
int List_count=10;
int List_step =3;
double List_Volt[3]= {3.0, 4.0, 6.0};
double List_Curr[3] = {0.1, 0.1, 0.1};
int List_Time[3]= {1,2,3};
}
OpenPort();
//Query the power supply id, read response and print it
sprintf(Buffer, "*IDN?");
SendSCPI(Buffer);
printf("Instrument identification string:%s \n", Buffer);
SendSCPI("*RST"); //reset the power supply
delay(100)
SendSCPI("CURRENT 0.1A"); //set the current to 0.1A
```



```

SendSCPI("VOLTAGE 0V"); //set the voltage to 0V
SendSCPI("OUTPUT 1"); // turn output on
SendSCPI("TRIGGER:SOURCE BUS"); //set trigger source to bus
/* configure the list*/
SendSCPI("LIST:MODE CONT"); //set the list mode to
continuous
ErrorStatus = viPrintf(PWS4000,"LIST:COUNT
%d\n",List_count); //set the list count
CheckError("Unable to set list count");
ErrorStatus = viPrintf(PWS4000,"LIST:STEP %d\n",List_step);
//set the list step
CheckError("Unable to set list step");
/*set the list voltage, current and time */
for(i = 1; i<= List_step; i+=1)
{
ErrorStatus = viPrintf(PWS4000,"LIST:CURREnt %d, %f\n", i,
List_Curr[i-1]); //set the step current
CheckError("Unable to set list current");
ErrorStatus = viPrintf(PWS4000,"LIST:VOLTage %d, %f\n",
i, List_Volt[i-1]); //set the step voltage
CheckError("Unable to set list voltage");
ErrorStatus = viPrintf(PWS4000,"LIST:WIDTH %d, %f\n", i,
List_Time[i-1]); //set the output voltage
CheckError("Unable to set list time");
}
SendSCPI("LIST:SAVE 1"); // save the list
SendSCPI("FUNCTION:MODE LIST"); // set the power supply in
list mode
SendSCPI("TRIGGER"); // trigger the list
printf("List is running\n");
/*Check the state of bit 5 of the Operation Condition
Register to determine if list is still running. */
do
{
delay(500);
ErrorStatus = viPrintf(PWS4000,
"STAtus:OPERation:CONDition?\n");
CheckError("Unable to write the device");
ErrorStatus = viScanf(PWS4000,"%d",&OPERreg);
} while (OPERreg & 0x20);
printf("List finished\n");
ClosePort();
while(1); //return 0;
}
void OpenPort()
{
//Open communication session with the power supply
ErrorStatus = viOpenDefaultRM(& defaultRM);
ErrorStatus =viOpen(defaultRM,
"USB0::0X0699::0X0391::006002206573001001::INSTR",0,0,&PWS4000);
CheckError("Unable to open the port");
SendSCPI("SYSTEM:REMOTE");
}
void SendSCPI(char* pString)
{
char* pdest;
strcpy(commandString,pString);

```

```
strcat(commandString, "\n");
ErrorStatus = viPrintf(PWS4000, commandString);
CheckError("Can't Write to Power Supply");
pdest = strchr(commandString, '?'); //Search for query
command
if (pdest != NULL)
{
ErrorStatus = viBufRead(PWS4000, (ViBuf)ReadBuffer,
sizeof(ReadBuffer), VI_NULL);
CheckError("Can't read from driver");
strcpy(pString, ReadBuffer);
}
}
void ClosePort()
{
viClose(PWS4000);
viClose(defaultRM);
}
void CheckError(char* pMessage)
{
if(ErrorStatus != VI_SUCCESS)
{
printf("\n %s",pMessage);
ClosePort();
exit(0);
}
}
void delay(clock_t wait)
{
clock_t goal;
goal = wait + clock();
while(goal > clock());
}
```

Troubleshooting guide

In this section:

What to do if the power supply does not turn on 5-1

What to do if the power supply does not turn on

To solve problems you might encounter when turning on the instrument, follow these steps:

1. Verify that there is AC power to the power supply.

First, check that the AC power cord is firmly plugged into the power connector on the rear panel of the power supply. You should also make sure that the AC power source you plugged the power supply into is energized. Then, check that the power supply is turned on.

2. Verify the power-line voltage settings.

Check that the line voltage selector switch on the bottom of the instrument is set to the proper value for your country (110 VAC or 220 VAC). Change the voltage setting if it is not correct.

NOTE

Under certain circumstances, powering the instrument from a mains voltage for which it is not configured can cause the mains fuse to open.

3. Verify that the correct power-line fuse is installed.
 - If the fuse is damaged, replace the fuse for your power supply.
 - If you set the line selection to 110 V, use a 5 A, TH 250 V fuse.
 - If you set the line selection to 220 V, use a 2.5 A, TH 250 V fuse.
4. If you need more help, see [Additional Series 2200 information](#) (on page 6-1) for information.

In this section:

[Additional Series 2200 information.....](#) 6-1

Additional Series 2200 information

This manual has prepared you to start using your new Series 2200 instrument.

For additional information on the Series 2200, refer to:

- The Product Information CD-ROM (ships with the product): Contains software tools, drivers, and product documentation.
- The [Keithley Instruments website](http://www.tek.com/keithley) <http://www.tek.com/keithley>: Contains the most up-to-date information; from the website, you can access:
 - The Knowledge Center, which contains the following handbooks:
 - *The Low Level Measurements Handbook: Precision DC Current, Voltage, and Resistance Measurements*
 - *Switching Handbook: A Guide to Signal Switching in Automated Test Systems*
 - Application notes
 - Updated drivers
- Your local Field Applications Engineer can help you with product selection, configuration, and usage. Check the website for contact information.

Maintenance

In this appendix:

CleaningA-1

Cleaning

Inspect the power supply as often as operating conditions require. To clean the exterior surface, perform the following steps:

1. Remove loose dust on the outside of the power supply with a lint-free cloth. Use care to avoid scratching the display.
2. Use a soft cloth dampened with water to clean the power supply. Use an aqueous solution of 75% isopropyl alcohol for more efficient cleaning.



CAUTION

To avoid damage to the surface of the power supply, do not use any abrasive or chemical cleaning agents.

Performance verification and adjustments

In this appendix:

| | |
|--|------|
| Performance verification..... | B-1 |
| Performance verification procedures..... | B-11 |
| Adjustment procedures..... | B-38 |

Performance verification

This topic contains performance verification procedures. Additional test equipment is required to complete the verification procedures (see [Test equipment](#) (on page B-13)).

These procedures cover the following models (do not attempt to make adjustments to any model not listed)(for more detail about each model see [Key features](#) (on page 1-3)):

| Model | | |
|-----------|-------------|-------------|
| 2200-20-5 | 2220-30-1 | 2230-30-1 |
| 2200-30-5 | 2220G-30-1 | 2230G-30-1 |
| 2200-32-3 | 2220J-30-1 | 2230J-30-1 |
| 2200-60-2 | 2220GJ-30-1 | 2230GJ-30-1 |
| 2200-72-1 | | |

Print the [Test record](#) (on page B-2), and use it to record the performance test results for your power supply.

NOTE

Completion of the performance verification procedure does not update the stored time and date of the latest successful adjustment. The date and time are updated only when the factory adjustment procedures are successfully completed.

The performance verification procedures verify the performance of your instrument. They do not adjust your instrument. If your instrument fails any of the performance verification tests, you should refer to [Adjustment procedures](#) (on page B-38), or contact Keithley service.

Test record

| Model | Serial | Procedure performed by | Date |
|--|--------|------------------------|------|
| | | | |
| | | | |
| Test | Passed | Failed | |
| Self test | | | |
| DC voltage accuracy with remote sense | | | |
| DC voltage accuracy without remote sense | | | |
| DC voltage readback accuracy | | | |
| DC voltage line regulation | | | |
| DC voltage load regulation | | | |
| DC voltage detection | | | |
| DC current accuracy | | | |
| DC current readback accuracy | | | |
| DC current line regulation | | | |
| DC current load regulation | | | |
| Voltage noise at 7 MHz | | | |
| Voltage noise at 20 MHz | | | |
| Current noise at 20 MHz | | | |

DC voltage accuracy with remote sense

| Instrument | DUT voltage | Test current | Minimum | Measured | Maximum |
|-------------------|-------------|--------------|------------|----------|------------|
| 0% Test Voltage | | | | | |
| 2200-20-5 | 0 V | 2.5 A | -0.0030 V | | 0.0030 V |
| 2200-30-5 | 0 V | 2.5 A | -0.0030 V | | 0.0030 V |
| 2200-32-3 | 0 V | 1.5 A | -0.0030 V | | 0.0030 V |
| 2200-60-2 | 0 V | 1.25 A | -0.0060 V | | 0.0060 V |
| 2200-70-1 | 0 V | 0.63 A | -0.0060 V | | 0.0060 V |
| 25% Test Voltage | | | | | |
| 2200-20-5 | 5 V | 2.5 A | 4.9955 V | | 5.0045 V |
| 2200-30-5 | 7.5 V | 2.5 A | 7.49475 V | | 7.50525 V |
| 2200-32-3 | 8 V | 1.5 A | 7.9946 V | | 8.0054 V |
| 2200-60-2 | 15 V | 1.25 A | 14.9895 V | | 15.0105 V |
| 2200-70-1 | 18 V | 0.63 A | 17.9886 V | | 18.0114 V |
| 50% Test Voltage | | | | | |
| 2200-20-5 | 10 V | 2.5 A | 9.9940 V | | 10.0060 V |
| 2200-30-5 | 15 V | 2.5 A | 14.9925 V | | 15.0075 V |
| 2200-32-3 | 16 V | 1.5 A | 15.9922 V | | 16.0078 V |
| 2200-60-2 | 30 V | 1.25 A | 29.9850 V | | 30.0150 V |
| 2200-70-1 | 36 V | 0.63 A | 35.9832 V | | 36.0168 V |
| 75% Test Voltage | | | | | |
| 2200-20-5 | 15 V | 2.5 A | 14.9925 V | | 15.00750 V |
| 2200-30-5 | 22.5 V | 2.5 A | 22.49025 V | | 22.50975 V |
| 2200-32-3 | 24 V | 1.5 A | 23.9898 V | | 24.0102 V |
| 2200-60-2 | 45 V | 1.25 A | 44.9805 V | | 45.0195 V |
| 2200-70-1 | 54 V | 0.63 A | 53.9778 V | | 54.0222 V |
| 100% Test Voltage | | | | | |
| 2200-20-5 | 20 V | 2.5 A | 19.9910 V | | 20.0090 V |
| 2200-30-5 | 30 V | 2.5 A | 29.9880 V | | 30.0120 V |
| 2200-32-3 | 32 V | 1.5 A | 31.9874 V | | 32.0126 V |
| 2200-60-2 | 60 V | 1.25 A | 59.9760 V | | 60.0240 V |
| 2200-70-1 | 72 V | 0.63 A | 71.9724 V | | 72.0276 V |

DC voltage accuracy without remote sense

| Instrument | DUT voltage | Test current | Minimum | Measured | Maximum |
|--------------------------|-------------|--------------|------------|----------|------------|
| 0% Test Voltage | | | | | |
| 2200-20-5 | 0 V | 2.5 A | -0.0030 V | | 0.0030 V |
| 2200-30-5 | 0 V | 2.5 A | -0.0030 V | | 0.0030 V |
| 2200-32-3 | 0 V | 1.5 A | -0.0030 V | | 0.0030 V |
| 2200-60-2 | 0 V | 1.25 A | -0.0060 V | | 0.0060 V |
| 2200-70-1 | 0 V | 0.63 A | -0.0060 V | | 0.0060 V |
| 25% Test Voltage | | | | | |
| 2200-20-5 | 5 V | 2.5 A | 4.9955 V | | 5.0045 V |
| 2200-30-5 | 7.5 V | 2.5 A | 7.49475 V | | 7.50525 V |
| 2200-32-3 | 8 V | 1.5 A | 7.9946 V | | 8.0054 V |
| 2200-60-2 | 15 V | 1.25 A | 14.9895 V | | 15.0105 V |
| 2200-70-1 | 18 V | 0.63 A | 17.9886 V | | 18.0114 V |
| 50% Test Voltage | | | | | |
| 2200-20-5 | 10 V | 2.5 A | 9.9940 V | | 10.0060 V |
| 2200-30-5 | 15 V | 2.5 A | 14.9925 V | | 15.0075 V |
| 2200-32-3 | 16 V | 1.5 A | 15.9922 V | | 16.0078 V |
| 2200-60-2 | 30 V | 1.25 A | 29.9850 V | | 30.0150 V |
| 2200-70-1 | 36 V | 0.63 A | 35.9832 V | | 36.0168 V |
| 75% Test Voltage | | | | | |
| 2200-20-5 | 15 V | 2.5 A | 14.9925 V | | 15.0075 V |
| 2200-30-5 | 22.5 V | 2.5 A | 22.49025 V | | 22.50975 V |
| 2200-32-3 | 24 V | 1.5 A | 23.9898 V | | 24.0102 V |
| 2200-60-2 | 45 V | 1.25 A | 44.9805 V | | 45.0195 V |
| 2200-70-1 | 54 V | 0.63 A | 53.9778 V | | 54.0222 V |
| 100% Test Voltage | | | | | |
| 2200-20-5 | 20 V | 2.5 A | 19.9910 V | | 20.0090 V |
| 2200-30-5 | 30 V | 2.5 A | 29.9880 V | | 30.0120 V |
| 2200-32-3 | 32 V | 1.5 A | 31.9874 V | | 32.0126 V |
| 2200-60-2 | 60 V | 1.25 A | 59.9760 V | | 60.0240 V |
| 2200-70-1 | 72 V | 0.63 A | 71.9724 V | | 72.0276 V |

DC voltage readback accuracy

| Instrument | DUT voltage | Test current | Measured voltage | Voltage readout | Absolute difference | Maximum difference |
|-------------------|-------------|--------------|------------------|-----------------|---------------------|--------------------|
| 0% Test Voltage | | | | | | |
| 2200-20-5 | 0 V | 2.5 A | | | | 0.0030 V |
| 2200-30-5 | 0 V | 2.5 A | | | | 0.0025 V |
| 2200-32-3 | 0 V | 1.5 A | | | | 0.0030 V |
| 2200-60-2 | 0 V | 1.25 A | | | | 0.0060 V |
| 2200-70-1 | 0 V | 0.63 A | | | | 0.0050 V |
| 25% Test Voltage | | | | | | |
| 2200-20-5 | 5 V | 2.5 A | | | | 0.0040 V |
| 2200-30-5 | 7.5 V | 2.5 A | | | | 0.0040 V |
| 2200-32-3 | 8 V | 1.5 A | | | | 0.0046 V |
| 2200-60-2 | 15 V | 1.25 A | | | | 0.0090 V |
| 2200-70-1 | 18 V | 0.63 A | | | | 0.0086 V |
| 50% Test Voltage | | | | | | |
| 2200-20-5 | 10 V | 2.5 A | | | | 0.0050 V |
| 2200-30-5 | 15 V | 2.5 A | | | | 0.0050 V |
| 2200-32-3 | 16 V | 1.5 A | | | | 0.0062 V |
| 2200-60-2 | 30 V | 1.25 A | | | | 0.0120 V |
| 2200-70-1 | 36 V | 0.63 A | | | | 0.0122 V |
| 75% Test Voltage | | | | | | |
| 2200-20-5 | 15 V | 2.5 A | | | | 0.0060 V |
| 2200-30-5 | 22.5 V | 2.5 A | | | | 0.0070 V |
| 2200-32-3 | 24 V | 1.5 A | | | | 0.0078 V |
| 2200-60-2 | 45 V | 1.25 A | | | | 0.0150 V |
| 2200-70-1 | 54 V | 0.63 A | | | | 0.0158 V |
| 100% Test Voltage | | | | | | |
| 2200-20-5 | 20 V | 2.5 A | | | | 0.0070 V |
| 2200-30-5 | 30 V | 2.5 A | | | | 0.0085 V |
| 2200-32-3 | 32 V | 1.5 A | | | | 0.0094 V |
| 2200-60-2 | 60 V | 1.25 A | | | | 0.0180 V |
| 2200-70-1 | 72 V | 0.63 A | | | | 0.0194 V |

DC voltage line regulation

| Instrument | Minimum line | Maximum line | Nominal - Minimum | Maximum - Nominal | Largest | Maximum value |
|------------|--------------|--------------|-------------------|-------------------|---------|---------------|
| 2200-20-5 | | | | | | 0.0080 V |
| 2200-30-5 | | | | | | 0.0100 V |
| 2200-32-3 | | | | | | 0.0104 V |
| 2200-60-2 | | | | | | 0.0160 V |
| 2200-70-1 | | | | | | 0.0184 V |

DC voltage load regulation

| Instrument | Minimum load | Ref load | Maximum load | Ref - Minimum | Maximum - Ref | (Maximum - Ref) / 0.98 | Largest | Maximum value |
|------------|--------------|----------|--------------|---------------|---------------|------------------------|---------|---------------|
| 2200-20-5 | | | | | | | | 0.00800 V |
| 2200-30-5 | | | | | | | | 0.01000 V |
| 2200-32-3 | | | | | | | | 0.01040 V |
| 2200-60-2 | | | | | | | | 0.01600 V |
| 2200-70-1 | | | | | | | | 0.01840 V |

DC overvoltage detection

| Instrument | Minimum trigger voltage | Measured trigger voltage | Maximum trigger voltage |
|------------|-------------------------|--------------------------|-------------------------|
| 2200-20-5 | 4.75 V | | 5.525 V |
| 2200-30-5 | 4.75 V | | 5.525 V |
| 2200-32-3 | 4.75 V | | 5.525 V |
| 2200-60-2 | 4.75 V | | 5.525 V |
| 2200-70-1 | 4.75 V | | 5.525 V |

DC current accuracy

| Instrument | Test voltage | DUT current | Minimum | Measured current | Maximum |
|-------------------|--------------|-------------|-------------|------------------|-------------|
| 0% Test Current | | | | | |
| 2200-20-5 | 10 V | 0.0 A | -0.002 A | | 0.002 A |
| 2200-30-5 | 15 V | 0.0 A | -0.0026 A | | 0.0026 A |
| 2200-32-3 | 16 V | 0.0 A | -0.002 A | | 0.002 A |
| 2200-60-2 | 30 V | 0.0 A | -0.0015 A | | 0.0015 A |
| 2200-70-1 | 36 V | 0.0 A | -0.001 A | | 0.001 A |
| 25% Test Current | | | | | |
| 2200-20-5 | 10 V | 1.25 A | 1.247375 A | | 1.252625 A |
| 2200-30-5 | 15 V | 1.25 A | 1.246875 A | | 1.253125 A |
| 2200-32-3 | 16 V | 0.75 A | 0.747625 A | | 0.752375 A |
| 2200-60-2 | 30 V | 0.625 A | 0.6231875 A | | 0.6268125 A |
| 2200-70-1 | 36 V | 0.3 A | 0.29885 A | | 0.30115 A |
| 50% Test Current | | | | | |
| 2200-20-5 | 10 V | 2.5 A | 2.49675 A | | 2.50325 A |
| 2200-30-5 | 15 V | 2.5 A | 2.49625 A | | 2.50375 A |
| 2200-32-3 | 16 V | 1.5 A | 1.49725 A | | 1.50275 A |
| 2200-60-2 | 30 V | 1.25 A | 1.247875 A | | 1.252125 A |
| 2200-70-1 | 36V | 0.6 A | 0.5987 A | | 0.6013 A |
| 75% Test Current | | | | | |
| 2200-20-5 | 10 V | 3.75 A | 3.746125 A | | 3.753875 A |
| 2200-30-5 | 15 V | 3.75 A | 3.745625 A | | 3.754375 A |
| 2200-32-3 | 16 V | 2.25 A | 2.246875 A | | 2.253125 A |
| 2200-60-2 | 30 V | 1.875 A | 1.8725625 A | | 1.8774375 A |
| 2200-70-1 | 36 V | 0.9 A | 0.898553 A | | 0.90145 A |
| 100% Test Current | | | | | |
| 2200-20-5 | 10 V | 5 A | 4.9955 A | | 5.0045 A |
| 2200-30-5 | 15 V | 5 A | 4.995 A | | 5.005 A |
| 2200-32-3 | 16 V | 5 A | 2.9965 A | | 3.0035 A |
| 2200-60-2 | 30 V | 2.5 A | 2.49725 A | | 2.50275 A |
| 2200-70-1 | 36 V | 1.2 A | 1.1984 A | | 1.2016 A |

DC current readback accuracy

| Instrument | Test current | Measured current | Current readout | Absolute difference | Maximum difference |
|-------------------|--------------|------------------|-----------------|---------------------|--------------------|
| 0% Test Current | | | | | |
| 2200-20-5 | 0 A | | | | 0.0020 A |
| 2200-30-5 | 0 A | | | | 0.0025 A |
| 2200-32-3 | 0 A | | | | 0.0020 A |
| 2200-60-2 | 0 A | | | | 0.0015 A |
| 2200-72-1 | 0 A | | | | 0.0010 A |
| 25% Test Current | | | | | |
| 2200-20-5 | 1.2500 A | | | | 0.0026 A |
| 2200-30-5 | 1.2500 A | | | | 0.0031 A |
| 2200-32-3 | 0.7500 A | | | | 0.0024 A |
| 2200-60-2 | 0.6250 A | | | | 0.0018 A |
| 2200-72-1 | 0.3000 A | | | | 0.0012 A |
| 50% Test Current | | | | | |
| 2200-20-5 | 2.500 A | | | | 0.0033 A |
| 2200-30-5 | 2.500 A | | | | 0.0038 A |
| 2200-32-3 | 1.500 A | | | | 0.0028 A |
| 2200-60-2 | 1.2500 A | | | | 0.0021 A |
| 2200-72-1 | 0.6000 A | | | | 0.0013 A |
| 75% Test Current | | | | | |
| 2200-20-5 | 3.7500 A | | | | 0.0039 A |
| 2200-30-5 | 3.7500 A | | | | 0.0044 A |
| 2200-32-3 | 2.2500 A | | | | 0.0031 A |
| 2200-60-2 | 1.8750 A | | | | 0.0024 A |
| 2200-72-1 | 0.9000 A | | | | 0.0015 A |
| 100% Test Current | | | | | |
| 2200-20-5 | 5.0000 A | | | | 0.0045 A |
| 2200-30-5 | 5.0000 A | | | | 0.0050 A |
| 2200-32-3 | 3.0000 A | | | | 0.0035 A |
| 2200-60-2 | 2.5000 A | | | | 0.0028 A |
| 2200-72-1 | 1.2000 A | | | | 0.0016 A |

DC current line regulation

| Instrument | Test voltage | Minimum line | Maximum line | Nominal line | Nominal - Minimum | Maximum - Nominal | Largest | Maximum value |
|------------|--------------|--------------|--------------|--------------|-------------------|-------------------|---------|---------------|
| 2200-20-5 | 10 V | | | | | | | 0.0052 A |
| 2200-30-5 | 15 V | | | | | | | 0.0052 A |
| 2200-32-3 | 16 V | | | | | | | 0.0032 A |
| 2200-60-2 | 30 V | | | | | | | 0.0026 A |
| 2200-72-1 | 36 V | | | | | | | 0.0014 A |

DC current load regulation

| Instrument | Meas @ min volts | Meas @ ref volts | Meas @ maximum volts | Ref Minimum | Maximum - Ref | Largest | Maximum difference |
|------------|------------------|------------------|----------------------|-------------|---------------|---------|--------------------|
| 2200-20-5 | | | | | | | 0.0021 A |
| 2200-30-5 | | | | | | | 0.0035 A |
| 2200-32-3 | | | | | | | 0.0013 A |
| 2200-60-2 | | | | | | | 0.0016 A |
| 2200-72-1 | | | | | | | 0.00098 A |

Voltage noise at 7 MHz

| Instrument | Voltage test load R 1 | Measured RMS | Maximum RMS | Measured peak-to-peak | Maximum peak-to-peak |
|------------|-----------------------|--------------|-------------|-----------------------|----------------------|
| 2200-20-5 | 5 Ω | | 1 mV | | 3 mV |
| 2200-30-5 | 10 Ω | | 1 mV | | 4 mV |
| 2200-32-3 | 12 Ω | | 1 mV | | 4 mV |
| 2200-60-2 | 40 Ω | | 1 mV | | 5 mV |
| 2200-72-1 | 65 Ω | | 1 mV | | 3 mV |

* Load R must be rated at 100 W minimum.

Voltage noise at 20 MHz

| Instrument | Voltage test load R 1 | Measured RMS | Maximum RMS | Measured peak-to-peak | Maximum peak-to-peak |
|------------|-----------------------|--------------|-------------|-----------------------|----------------------|
| 2200-20-5 | 5 Ω | | 3 mV | | 20 mV |
| 2200-30-5 | 10 Ω | | 4 mV | | 20 mV |
| 2200-32-3 | 12 Ω | | 3 mV | | 20 mV |
| 2200-60-2 | 40 Ω | | 3 mV | | 20 mV |
| 2200-72-1 | 65 Ω | | 3 mV | | 20 mV |

* Load R must be rated at 100 W minimum.

Current noise at 20 MHz

| Instrument | Current test load R 1 | Measured RMS | Maximum RMS |
|------------|-----------------------|--------------|-------------|
| 2200-20-5 | 1.0 Ω | | 3 mV |
| 2200-30-5 | 1.0 Ω | | 4 mV |
| 2200-32-3 | 1.0 Ω | | 3 mV |
| 2200-60-2 | 1.0 Ω | | 3 mV |
| 2200-72-1 | 1.0 Ω | | 3 mV |

* Load R must be rated at 100 W minimum

Performance verification procedures

Use the procedures in this topic to verify the performance of the Series 2200 instruments.

Performance verification conditions

The following conditions must be met before performing these procedures:

1. The device under test (DUT) and all test equipment must have been operating continuously for 20 minutes in an environment that meets the operating range specifications for temperature and humidity.
Test setup changes affecting the remote sense require an additional 20 minute warm-up period.
2. The procedures are intended to be used in sequence. If it is necessary to partially test the DUT using an individual test, a 20 minute warm-up period is required for the individual test.
3. You must connect the DUT and the test equipment to the same AC power circuit. Connect the DUT and test instruments to a common power strip if you are unsure of the AC power circuit distribution. Connecting the DUT and test instruments into separate AC power circuits can result in offset voltages between the equipment, which can invalidate this performance verification procedure.
4. The AC power Source for the DUT must match the voltage selector switch setting located on the bottom of the DUT.

| DUT voltage selector switch | AC source voltage |
|-----------------------------|-------------------|
| 110 | 115 V |
| 220 | 230 V |

WARNING

Some procedures use hazardous voltages. To prevent electrical shock that could result in injury or death, or equipment failure, always power off instruments before touching exposed circuitry. Read and follow the precautions in the Safety precautions.

Equipment required

These procedures use external equipment to directly check warranted characteristics. The following table lists the required equipment.

Test equipment

| Item | Connectors | Minimum requirements | Example |
|------|--|---|---------------------------------|
| 1. | Connectors | Connectors for wire assemblies and test resistors, item numbers 5, 6, 9, 10, and 11. <ul style="list-style-type: none"> (Qty. 6) #10 fork lugs similar to Tyco part number 52951 (Qty, 14) Stackable, gold plated, banana plugs/jacks similar to Pomona model 4897-0. Used for lower current connections, and connection to the load resistors (items 10 and 11) used for noise testing. (Qty. 4) Sheathed banana jacks similar to Pomona model 4834 to put connectors on the Resistors (item 9) | |
| 2. | AC power source | Variable AC output from 90 to 265 V AC with at least 750 VA capacity | Kikusui PCR2000M |
| 3. | Electronic load | Variable DC Load capable of 6 ADC and 75 V DC | B&K Precision 8510 |
| 4. | DC digital multimeter (DMM) | Voltage measurement at 12 mV through 72 V to better than 100 ppm accuracy with the ability to multiply the result by a scalar. | Keithley Instruments Model 2000 |
| 5. | High current wire (High current connections are indicated with bold lines in the setup illustrations) | 18 AWG (minimum) wire assemblies. TO perform all tests, the following wire assemblies need to be created: <ul style="list-style-type: none"> #10 fork lug to #10 fork lug, Qty 2, (included in Guildline 92301 if used). Stackable banana to #10 fork lug, Qty 2 Wire lengths are not critical. | |
| 6. | Low current wire (Low current connections are indicated with light lines in the setup illustrations) | 22 AWG (minimum) wires To perform all tests, the following wire assemblies need to be created: <ul style="list-style-type: none"> Banana plug to banana plug, Qty 2 Bare wire to stackable banana, Qty 2 Bare wire to banana, Qty 2 Wire lengths are not critical. | |
| 7. | 50 mΩ precision shunt resistor | 0.050 Ω ±100 ppm at 25 V ±4 ppm/°C temperature coefficient | Guildline 9230A-50 |
| 8. | Current sense resistor cabling | Kelvin 4-terminal measuring cables for shunt resistor to DMM | Guildline 92301 cable set |
| 9. | 50 mΩ resistor for Remote Sense testing (2 required) One of these 50 mΩ resistors may be substituted with item 7. | 0.050 Ω, 5 W To perform the tests as illustrated, both leads of each resistor require a banana jack connector (e.g. Pomona model 4834). | OHMITE 15FR050E |
| 10. | Load resistor for Voltage Noise testing | Loading resistors for high current in voltage mode, and high voltage in current mode All resistors should be rated for at least 100 W. Ohms tolerance within 5%. Resistor composition is not critical. To perform the tests as illustrated, both leads of the load resistor require a banana plug/jack (or equivalent) to connect to the power supply. | |

| Item | Connectors | Minimum requirements | Example |
|------|---|---|------------------------------------|
| | | 2200-20-5 5 Ω | HL10006E5R00JJ |
| | | 2200-30-5 10 Ω | HL10006E10R00JJ |
| | | 2200-32-3 12 Ω | HL10006E12R00JJ |
| | | 2200-60-2 40 Ω | HL10006E40R00JJ |
| | | 2200-72-1 65 Ω | HL10006E65R00JJ |
| 11. | Load Resistor for Current Noise testing | 1 Ω, 100 W, 5% To perform the tests as illustrated, both leads of the load resistor require a Banana plug/jack (or equivalent) to connect to the power supply. | Vishay/Dale HL10006Z1R000JJ |
| 12. | Oscilloscope | 20 MHz bandwidth limited oscilloscope at 1 mV/division | Tektronix DPO3012 |
| 13. | Oscilloscope probe | Low capacitance 1 MΩ/10 MΩ 1X/10X 6 MHz/200 MHz probe | Tektronix P2220, 1X probe |
| 14. | Oscilloscope probe | Low capacitance 10 MΩ 500 MHz probe | Tektronix P6139A, 10X probe |
| 15. | Coaxial cable | 50 Ω BNC, male-to-male | Tektronix part number: 012-0482-00 |
| 16. | BNC adapter | BNC female to banana breakout | Pomona Electronics 3073 |

Self test

This procedure uses internal routines to verify that the DUT functions and passes its internal self tests. No test equipment is required.

1. Disconnect all cables from the DUT outputs.
2. Power on the DUT. The front-panel display will light up briefly while the DUT performs its power-on self test. All the display annunciators will light up at once.
3. Review the display with all the annunciators. Visually check if there are any strokes lost on any annunciator.

Figure 17: Display



4. If any of the messages listed in the following table appear in the display, it indicates that the EEPROM is experiencing the condition associated with the message.
5. If there is no response when you power on the DUT, verify that there is AC power to the power supply, verify the power-line voltage settings, and verify that the correct power-line fuse is installed. If you need more help, contact Keithley.
6. Power off the DUT.

| Display shows | EEPROM Condition |
|--------------------------|---|
| <i>ERREEPROM</i> | EEPROM is damaged or the latest operation data in the EEPROM is missing |
| <i>ERROR CAL</i> | Calibration data in the EEPROM is missing |
| <i>Error Config Data</i> | Operating state of the power supply in the EEPROM is missing |

Check DC voltage accuracy with remote sense

Equipment required

| | |
|--------------------------|---------------------------------------|
| (Item 2) AC Power Source | (Item 5) High current wire |
| (Item 3) Electronic Load | (Item 6) Low current wire |
| (Item 4) DC Voltmeter | (Item 9) 0.050 Ω 5 W Resistor (Qty 2) |

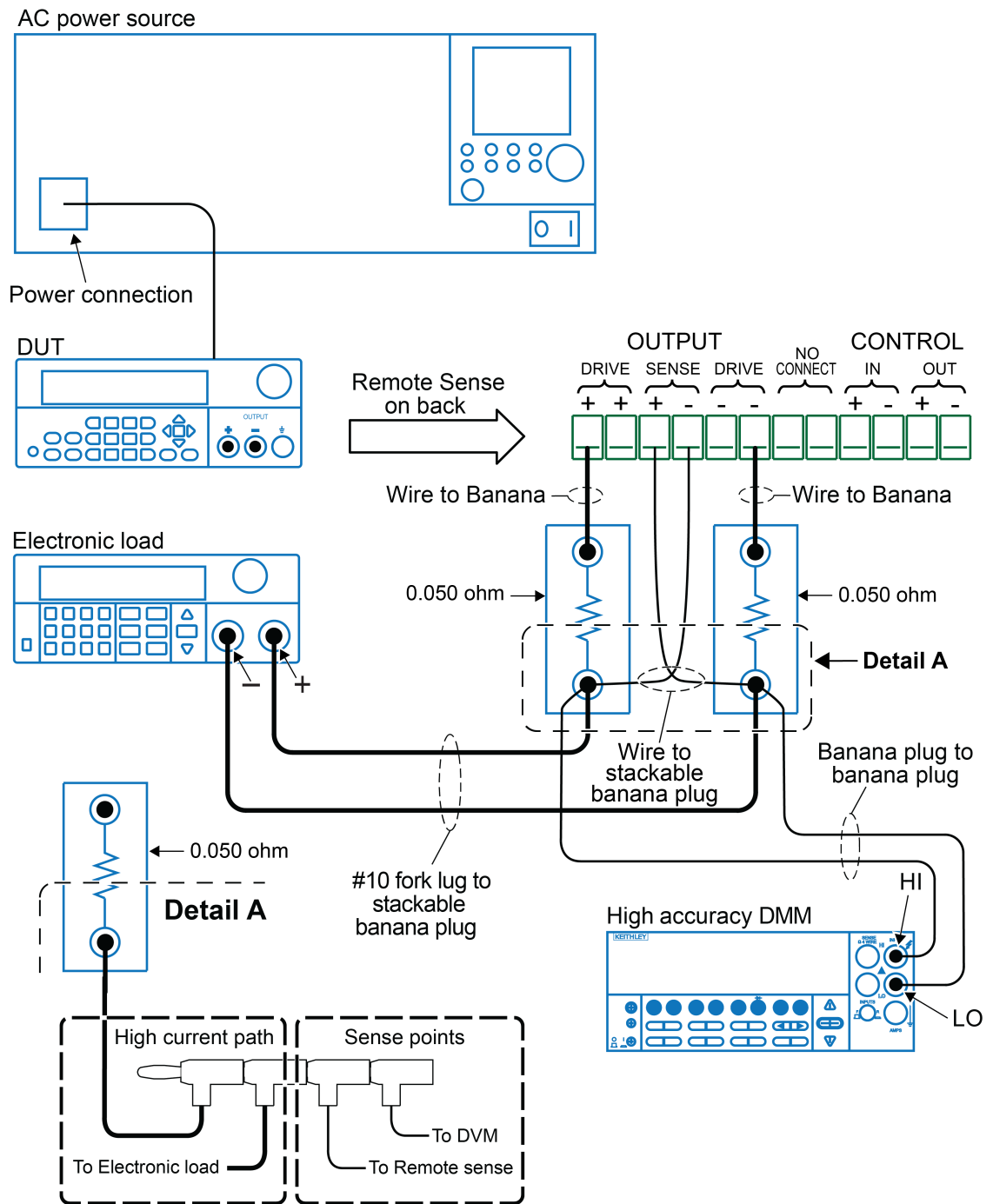
1. Power off the DUT.
2. Remove the shorting clip (that connects the Output Sense to the Output Drive connections) from the Remote Sense connector on the rear panel.
3. Set up the equipment as shown in the next figure.

NOTE

To assure accurate measurements, it is important that a significant amount of current does not flow through the sense leads. For this reason, we recommend that the wiring of the remote sense and the voltmeter be away from the high current connections between the electronic load and the DUT.

A solution is a pair fork lugs with all three wires crimped in. Another alternative is a fork lug between the DUT and the load, and separate connections (probably also fork lugs) holding the wiring for one or both of the voltmeter and remote sense. A third alternative is to stack banana jacks at the voltmeter, with the remote sense toward the voltmeter, and the two high current connections on the outside.

Figure 18: DC voltage accuracy with remote sense test setup



4. Power on the DUT.

NOTE

Ensure the warm-up criteria has been met as described in the [Performance verification conditions](#) (on page B-11).

5. Set the DMM to:

- DC volts
- Autorange
- Verify that the Math mX+b function is disabled (shift Dcv), assuring that volts are read.

6. Set the electronic load to:

- Constant Current
- Draw a constant current at the test current specified for the DUT in the table DC voltage accuracy with remote sense

7. Set the DUT to the full-scale output current.

8. Set the DUT to 0% of the full-scale output voltage (0 V).

9. Turn the DUT output on.

10. Enter the voltmeter reading into the table DC voltage accuracy with remote sense.

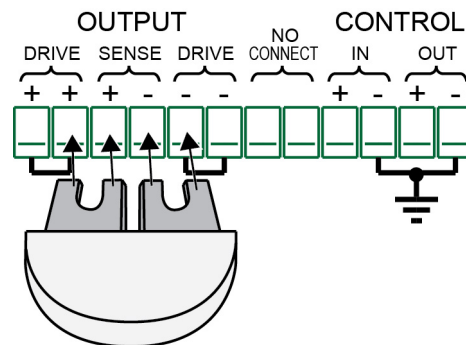
11. Increase the DUT output voltage by 25% of the Full-scale output voltage.

12. Repeat steps 10 and 11 until you complete testing at 100% of the full-scale.

13. Power off the DUT.

14. Disconnect the Remote Sense connector and reinstall the shorting clip between the Output Sense and Output Drive connectors as shown in the following figure.

Figure 19: Installing shorting clip on remote sense connector



15. Power on the DUT.

Check DC voltage accuracy without remote sense and voltage readback accuracy

Equipment required

| | |
|--------------------------|----------------------------|
| (Item 2) AC Power Source | (Item 5) High current wire |
| (Item 3) Electronic Load | (Item 6) Low current wire |
| (Item 4) DC Voltmeter | |

1. Set up the equipment as shown in the following figure.

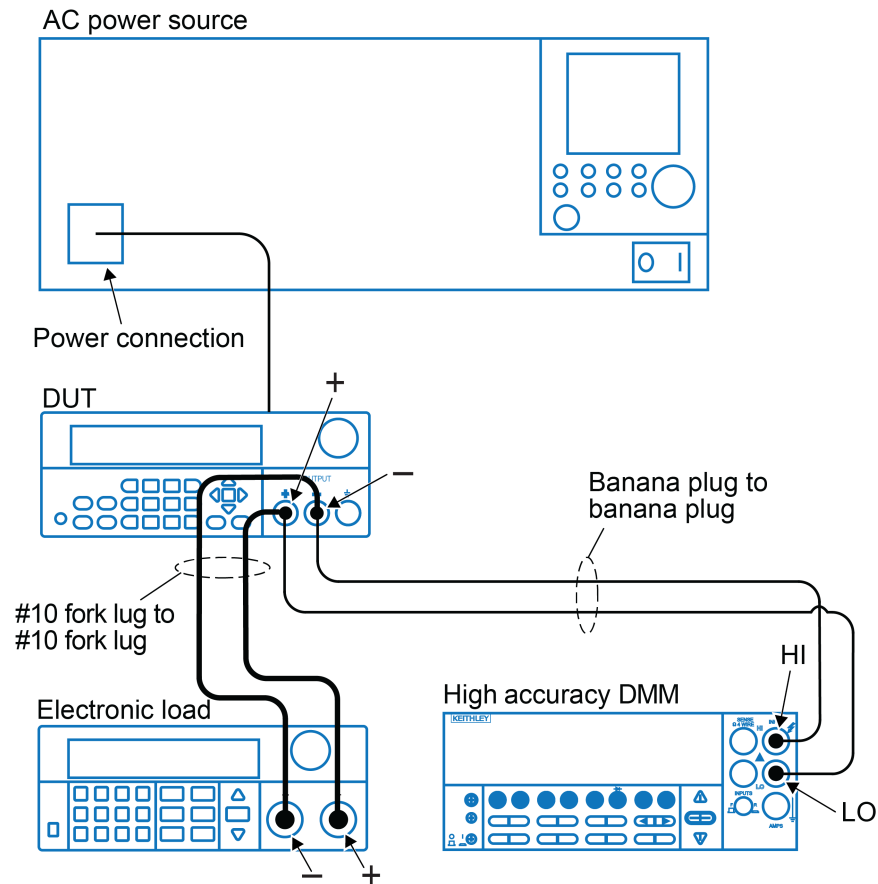
NOTE

Ensure the warm-up criteria has been met as described in the Performance verification conditions.

NOTE

To assure accurate measurements, the voltmeter must connect as close as possible to the front panel of the DUT. A solution is to use fork lugs between the electronic load and the DUT, and banana plugs between the DUT and voltmeter. An alternative solution is to use fork lugs for both connections at the DUT.

Figure 20: Voltage accuracy regulation and protection test setup



2. Set the voltmeter as follows:
 - a. Set to measure DC volts.
 - b. Set to auto range.
 - c. Verify that the Math mX+b function is disabled (shift Dcv), assuring that volts are being read.
3. Set the electronic load as follows:
 - a. Set to Constant Current.
 - b. Set to draw a constant current at the test current specified for the DUT in the table [DC voltage accuracy without remote sense](#) (on page B-4).
4. Set the DUT to the full-scale output current.
5. Set the DUT to 0% of the full-scale output voltage (0 V).
6. Turn the DUT output on.
7. Enter the voltmeter reading into the table [DC voltage accuracy without remote sense](#) (on page B-4).
8. Enter the voltmeter reading into the table [DC voltage readback accuracy](#) (on page B-5).
9. Enter the DUT Readback Voltage into the table [DC voltage readback accuracy](#) (on page B-5).
10. Calculate the difference of the two measurements taken in steps 8 and 9 and enter the absolute value into the difference column of the table. [DC voltage readback accuracy](#) (on page B-5).
11. Increase the DUT output voltage by 25% of the full-scale output voltage.
12. Repeat steps 7 through 11 until you complete testing at 100% of full-scale.

Check DC voltage line regulation

This check procedure uses the same test setup as the previous procedure. (see [Check DC voltage accuracy without remote sense and voltage readback accuracy](#) (on page B-18)).

1. Change the AC Power Source output to the minimum voltage specified in the following table.

| DUT voltage selector switch | AC power source voltage |
|-----------------------------|-------------------------|
| 110 | 98 V |
| 220 | 196 V |

NOTE

Ensure the warm-up criteria has been met as described in the Performance Verification Conditions.

2. Set the voltmeter as follows:
 - a. Set to measure DC volts.
 - b. Set to auto range.
 - c. Verify that the Math mX+b function is disabled (shift Dcv), assuring that volts are being read.
3. Set the electronic load as follows:
 - a. Set to Constant Current.
 - b. Set to draw the specified test current.

| Instrument | Test current |
|---------------|--------------|
| 2200 - 20 - 5 | 2.5 A |
| 2200 - 30 - 5 | 2.5 A |
| 2200 - 32 - 3 | 1.5 A |
| 2200 - 60 - 2 | 1.25 A |
| 2200 - 72 - 1 | 0.63 A |

4. Set the DUT to 100% of the full-scale output current.
5. Set the DUT to 100% of the full-scale output voltage.
6. Turn the DUT output on.
7. Enter the voltmeter reading into the table DC voltage line regulation under the Min column for your product.
8. Change the AC Power Source output to the maximum voltage specified in the following table.

| DUT voltage selector switch | AC power source voltage |
|-----------------------------|-------------------------|
| 110 | 132 V |
| 220 | 264 V |

9. Enter the voltmeter reading into the table DC voltage line regulation under the maximum column for your product.

10. Change the AC Power Source output to match the Voltage Selector switch setting of the DUT 65as shown in the following table.

| DUT voltage selector switch | AC Power Source voltage |
|------------------------------------|--------------------------------|
| 110 | 115 V |
| 220 | 230 V |

11. Enter the voltmeter reading into table for checking DC Voltage Line Regulation under the Nominal column for your product. (see DC voltage line regulation.)
12. Calculate the two values: Nominal – Min and maximum– Nominal. Enter the values into the appropriate columns in the DC voltage line regulation table.
13. Enter the largest of the two values calculated in step 12 into the Largest column in the DC voltage line regulation table.

Check DC voltage load regulation

This check procedure uses the same test setup as the previous procedure (see [Check DC voltage accuracy without remote sense and voltage readback accuracy](#) (on page B-18)).

NOTE

Make sure the warm-up criteria has been met as described in the [Performance verification conditions](#) (on page B-11).

1. Set the DMM to:
 - DC volts
 - Autorange
 - Verify that the Math mX+b function is disabled (shift Dcv), assuring that volts are read
2. Set the electronic load to:
 - Constant current
 - Draw 0 amperes
3. Set the DUT to 100% of the full-scale output current.
4. Set the DUT to 100% of the full-scale output voltage.
5. Turn the DUT output on.
6. Enter the voltmeter reading into the table [DC voltage load regulation](#) (on page B-6) under the Min column for your product.
7. Increase the electronic load to the reference load test current value.

| Instrument | Test current |
|---------------|--------------|
| 2200- 20 - 5 | 2.5 A |
| 2200 - 30 - 5 | 2.5 A |
| 2200 - 32 - 3 | 1.5 A |
| 2200 - 60 - 2 | 1.25 A |
| 2200 - 72 - 1 | 0.6 A |

8. Enter the DMM reading into the table [DC voltage load regulation](#) (on page B-6) under the reference load column for your product.
9. Increase the electronic load to the maximum load test current value.

| Instrument | Test current |
|---------------|--------------|
| 2200- 20 - 5 | 4.9 A |
| 2200 - 30 - 5 | 4.9 A |
| 2200 - 32 - 3 | 2.94 A |
| 2200 - 60 - 2 | 2.45 A |
| 2200 - 72 - 1 | 1.17 A |

10. Enter the DMM reading into table for checking DC Voltage Load Regulation under the Nominal column for your product (see [DC voltage load regulation](#) (on page B-6)).

11. Calculate the three values: Ref – Min, maximum– Ref, and (Maximum – Ref)/0.98. Enter the values into the appropriate columns in the [DC voltage load regulation](#) (on page B-6) table.
12. Enter the largest of the three values calculated in step 11 into the Largest column in the [DC voltage load regulation](#) (on page B-6) table.

Check DC overvoltage detection

This check procedure uses the same test setup as the previous procedure. (see [Check DC voltage accuracy without remote sense and voltage readback accuracy](#) (on page B-18))

NOTE

Ensure the warm-up criteria has been met as described in the Performance Verification Conditions.

1. Set the DMM to:
 - DC volts
 - Autorange
 - Verify that the Math $mX+b$ function is disabled (shift Dcv), assuring that volts are read
2. Set the electronic load to:
 - Constant current
 - Draw 1 ampere
3. Set the DUT to 100% of the full-scale output current.
4. Set the DUT to 4 V output voltage.

NOTE

OVP and Maximum Volt Set are submenus of the Protect menu.

5. Set the DUT OVP (over voltage protection) to ON, set the OVP threshold to 5 V, and turn Maximum Volt off as follows:
 - a. Press **Shift** and **Menu (1)**.
 - b. Press the down arrow until `Protect` is shown and press **Enter**.
 - c. Press the down arrow until `OVP Set` is shown and press **Enter**.
 - d. Press the down arrow until `On` is shown and press **Enter**.
 - e. Press 5 and press **Enter**.
 - f. Press the down arrow until `Max Volt Set` is shown and press **Enter**.
 - g. Press the down arrow until `Off` is shown and press **Enter**.
 - h. Press the **Esc** key as needed to exit the menu system.
6. Turn the DUT output on.

NOTE

During the next step, closely monitor the voltmeter reading. Noting the highest output voltage achieved before OVP is triggered.

7. Slowly increase the DUT output voltage until OVP is triggered. When triggered, the output voltage abruptly drops below 1 V, signals with beeps, and OVP is indicated in the display.
8. Enter the DMM reading (where OVP triggering occurred) into the [DC overvoltage detection](#) (on page B-6) table for checking DC Overvoltage Detection.
9. Reset OVP.
 - a. Press **Shift** and **Menu (1)**.
 - b. Press the down arrow until `Protect` is shown and press **Enter**.
 - c. Press the down arrow until **Reset Protect** is shown and press `Enter`.

- d. Press the right arrow to select `Yes` and press **Enter**.
- e. Press the **Esc** key as needed to exit the menu system.

Check DC current and DC current readback accuracy

Equipment required

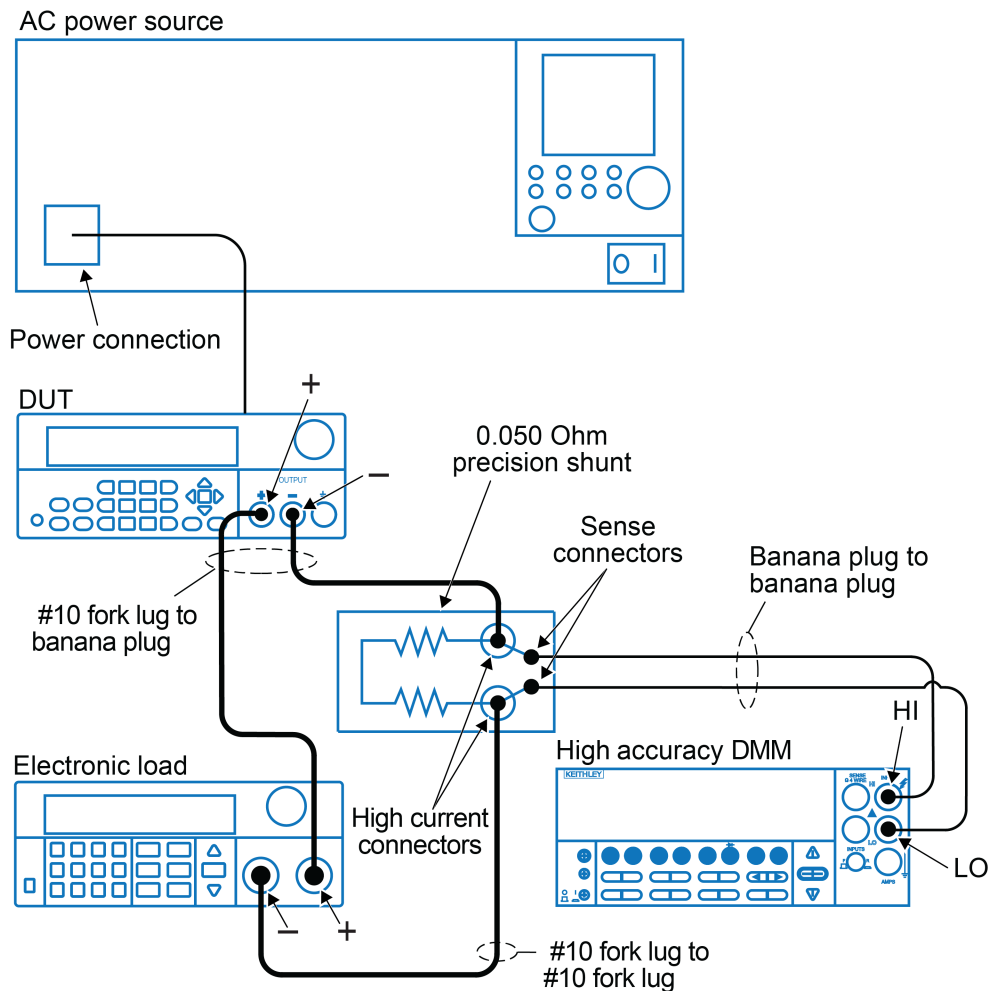
| | |
|--------------------------|---|
| (Item 2) AC Power Source | (Item 5) High current wire |
| (Item 3) Electronic Load | (Item 7) High Accuracy 0.05 Ω Resistor |
| (Item 4) DC Voltmeter | (Item 8) Current Shunt Resistor Cabling |

1. Set up the equipment as shown in the following figure.

NOTE

Ensure the warm-up criteria has been met as described in the Performance verification conditions.

Figure 21: DC current accuracy and regulation test setup



2. Set the DMM to:
 - DC volts
 - Autorange
 - Set to show amps (instead of volts) by multiplying the voltmeter result by 20.
 - Press Shift DC V (mX+B)
 - Use the arrow key to move the cursor as far to the right as it can go until it is positioned on the ^.
 - Press the up range button once: M=10.00000
 - Move the arrow key to the 1's digit and up range once: M=20.00000
 - Press Enter. The display shows B=0
 - Press Enter. The display shows Units:
 - Use the arrow keys to modify the display to show AMP.
 - Adjust each letter individually.
3. Set the electronic load to:
 - Constant voltage
 - Set to the specified voltage for your DUT (see [DC current accuracy](#) (on page B-7))
4. Set the DUT to 0% of the full-scale output current.
5. Set the DUT to 100% of the full-scale output voltage.
6. Turn the DUT output on.
7. Enter the voltmeter reading into the table [DC current accuracy](#) (on page B-7).
8. Enter the voltmeter reading into the table [DC current readback accuracy](#) (on page B-8).
9. Enter the DUT current readout into the table [DC current readback accuracy](#) (on page B-8) under the current readout column.
10. Calculate the difference of the two measurements taken in steps 8 and 9. Enter the absolute value of the calculated value into the difference column of the table. [DC current readback accuracy](#) (on page B-8).
11. Increase the DUT output current by 25% of the full-scale output current.
12. Repeat steps 7 through 11 until you complete testing at 100% of the full-scale output current.

Check DC current line regulation

This check procedure uses the same test setup as the previous procedure (see Check DC current and DC current readback accuracy).

1. Change the AC Power Source output to the minimum voltage specified in the following table.

| DUT voltage selector switch | AC Power Source voltage |
|-----------------------------|-------------------------|
| 110 | 98 V |
| 220 | 196 V |

NOTE

Ensure the warm-up criteria has been met as described in the Performance verification conditions.

2. Set the DMM to:
 - DC volts
 - Autorange
 - Set to show amps (instead of volts) by multiplying the voltmeter result by 20
 - Press Shift DC V (mX+B)
 - Use the arrow key to move the cursor as far to the right as it can go until it is positioned on the ^.
 - Press the up range button once: M=10.00000
 - Move the arrow key to the 1's digit and up range once: M=20.00000
 - Press Enter. The display shows B=0
 - Press Enter. The display shows Units:
 - Use the arrow keys to modify the display to show AMP.
 - Adjust each letter individually.
3. Set the electronic load to:
 - Constant voltage
 - Set to the specified voltage for your DUT (see [DC current line regulation](#) (on page B-9))
4. Set the DUT to 0% of the full-scale output voltage.
5. Set the DUT to 100% of the full-scale output current.
6. Turn the DUT output on.
7. Enter the DMM reading into the table [DC current line regulation](#) (on page B-9).
8. Change the AC Power Source output to the voltage specified in the following table.

| DUT voltage selector switch | AC power source voltage |
|-----------------------------|-------------------------|
| 110 | 132 V |
| 220 | 264 V |

9. Enter the DMM reading into the Maximum line for your product in the table [DC current line regulation](#) (on page B-9).

10. Change the AC Power Source output to the voltage specified in the following table.

| DUT voltage selector switch | AC power source voltage |
|------------------------------------|--------------------------------|
| 110 | 115 V |
| 220 | 230 V |

11. Enter the DMM reading into the Nominal line for your product in the table [DC current line regulation](#) (on page B-9).
12. Calculate the two values: Nominal – Min and Maximum – Nominal. Enter the values into the appropriate columns in the [DC current line regulation](#) (on page B-9) table.
13. Select the largest of the two calculations from step 12 and enter the value into the Largest column in the [DC current line regulation](#) (on page B-9) table.
14. Turn the DUT output off.

Check DC current load regulation

This check procedure uses the same test setup as the previous procedure (see [Check DC current line regulation](#) (on page B-28)).

1. Set the DMM to:
 - DC volts
 - Autorange
 - Set to show amps (instead of volts) by multiplying the voltmeter result by 20
 - Press Shift DC V (mX+B)
 - Use the arrow key to move the cursor as far to the right as it can go until it is positioned on the ^.
 - Press the up range button once: M=10.00000
 - Move the arrow key to the 1's digit and up range once: M=20.00000
 - Press Enter. The display shows B=0
 - Press Enter. The display shows Units:
 - Use the arrow keys to modify the display to show AMP.
 - Adjust each letter individually.
2. Set the electronic load to:
 - Constant voltage
 - Set to the minimum test voltage level

| Instrument | Minimum test voltage |
|---------------|----------------------|
| 2200 - 20 - 5 | 2.0 V |
| 2200 - 30 - 5 | 3.0 V |
| 2200 - 32 - 3 | 3.2 V |
| 2200 - 60 - 2 | 6.0 V |
| 2200 - 72 - 1 | 7.2 V |

3. Set the DUT to 100% of the full-scale output current for your product.
4. Set the DUT to 100% of the full-scale output voltage for your product.
5. Turn the DUT output on.
6. Enter the DMM reading into the DC current load regulation table for checking current load regulation at the minimum voltage for your product.
7. Increase the electronic load to the Reference test voltage level.

| Instrument | Minimum test voltage |
|---------------|----------------------|
| 2200 - 20 - 5 | 10.0 V |
| 2200 - 30 - 5 | 15.0 V |
| 2200 - 32 - 3 | 16.0 V |
| 2200 - 60 - 2 | 30.0 V |
| 2200 - 72 - 1 | 36.0 V |

8. Enter the DMM reading into the DC current load regulation table for checking current load regulation at the reference test voltage for your product.

9. Increase the electronic load to the Maximum test voltage level.

| Instrument | Minimum test voltage |
|-------------------|-----------------------------|
| 2200 - 20 - 5 | 18.0 V |
| 2200 - 30 - 5 | 27.0 V |
| 2200 - 32 - 3 | 28.8 V |
| 2200 - 60 - 2 | 54.0 V |
| 2200 - 72 - 1 | 64.8 V |

10. Enter the DMM reading into the DC current load regulation table for checking current load regulation at the maximum voltage for your product.
11. Calculate the two values: REF – Min and Maximum – REF. Enter the values into the appropriate columns in the DC current load regulation table.
12. Power off the DUT and test equipment.

Check voltage noise (7 MHz)

Equipment required

(Item 5) High current wire

(Item 12) Oscilloscope

(Item 10) Load Resistor

(Item 13) Oscilloscope 1X probe

1. Plug the DUT into your local line power from the mains.
2. Plug the test oscilloscope into the same mains outlet as the DUT.

NOTE

Some AC Power Sources create large amounts of high frequency noise on the power line that the instrument may not fully reject. Noise directly on the mains is typically better controlled.

Use the same mains outlet for both the DUT and test oscilloscope to avoid ground loops which may cause noise.

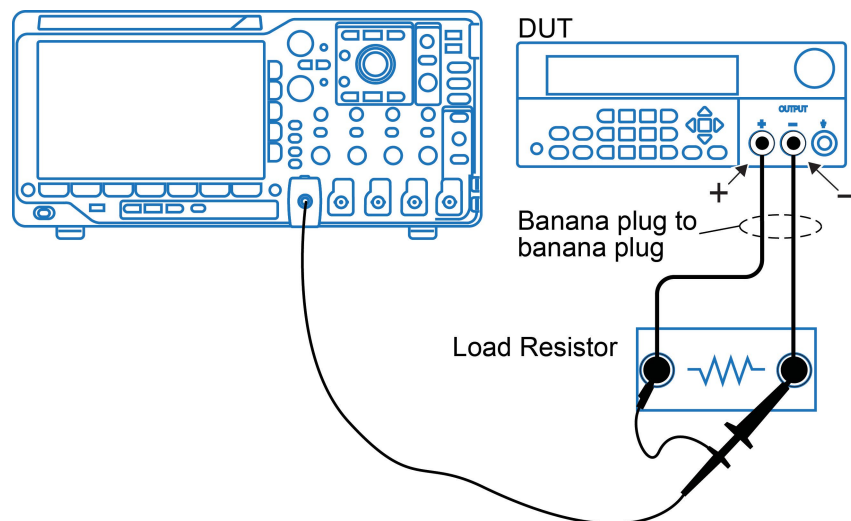
3. Power on the DUT and test oscilloscope.

NOTE

Ensure the warm-up criteria has been met as described in the Performance verification conditions.

4. Set up the equipment as shown in the following figure.
Use the appropriate load resistor depending on the model of the DUT. See [Voltage noise at 7 MHz](#) (on page B-10) for information.

Figure 22: 7 MHz test setup



5. Set the oscilloscope as follows:
 - a. 1 mV/division
 - b. 1 M Ω input resistance
 - c. 20 MHz bandwidth (BW) limit
 - d. AC Coupled
 - e. Auto-trigger
 - f. 1 ms/div
 - g. Set to measure V_{p-p} and V_{RMS}
6. Set the oscilloscope probe to 1X mode.
7. Set the DUT to the 100% full-scale output voltage.
8. Set the DUT to the 100% full-scale output current.
9. Turn the DUT output on.

 **WARNING**

Do not touch the load resistor. The load resistor may become hot enough to cause personal injury.

10. Enter the oscilloscope measurements into the [Voltage noise at 7 MHz](#) (on page B-10) table for checking Noise at 7 MHz.

Check voltage noise (20 MHz)

Equipment required

(Item 5) High current wire

(Item 15) Coaxial cable (BNC M-M)

(Item 10) Load Resistor

(Item 16) BNC F-to-Banana

(Item 12) Oscilloscope

1. Plug the DUT into your local line power from the mains.
2. Plug the test oscilloscope into the same mains outlet as the DUT.

NOTE

Some AC Power Sources create large amounts of high frequency noise on the power line that the instrument may not fully reject. Noise directly on the mains is typically better controlled.

Use the same mains outlet for both the DUT and test oscilloscope to avoid ground loops which may cause noise.

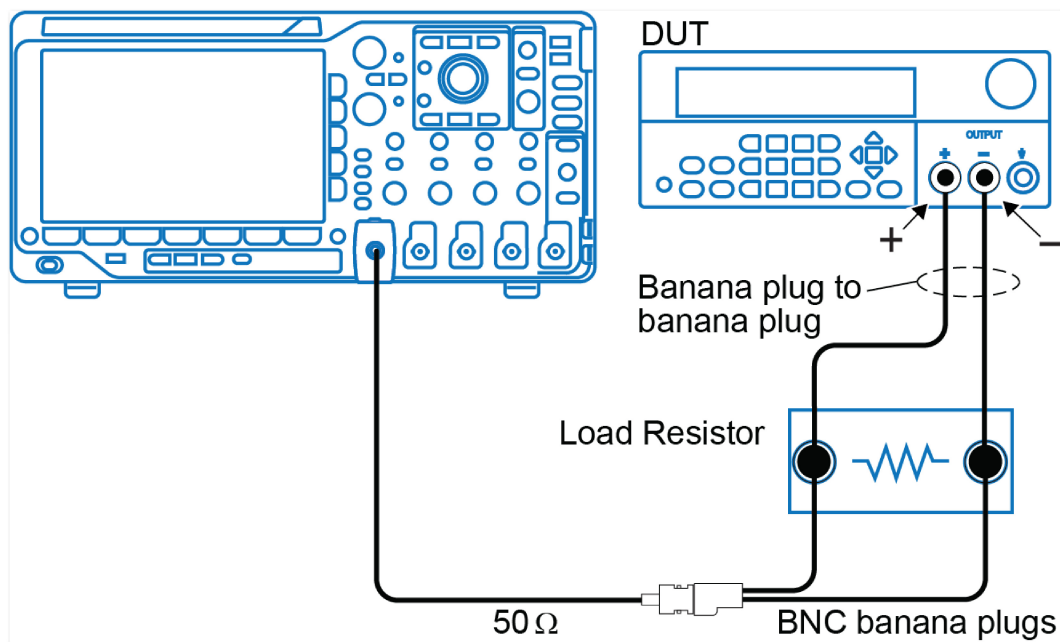
3. Power on the DUT and test oscilloscope.

NOTE

Ensure the warm-up criteria has been met as described in the Performance Verification Conditions.

4. Set up the equipment as shown in the following figure.
Use the appropriate load resistor depending on the model of the DUT. See [Voltage noise at 20 MHz](#) (on page B-10) for information.

Figure 23: 20 MHz voltage noise test setup



5. Set the oscilloscope as follows:
 - a. 1 mV/division
 - b. 1 M Ω input resistance
 - c. 20 MHz bandwidth (BW) limit
 - d. AC Coupled
 - e. Auto-trigger
 - f. 1 ms/div
 - g. Set to measure V_{p-p} and V_{RMS}
6. Set the DUT to the 100% full-scale output voltage.
7. Set the DUT to the 100% full-scale output current.
8. Turn the DUT output on.

 **WARNING**

Do not touch the load resistor. The load resistor may become hot enough to cause personal injury.

9. Enter the oscilloscope measurements into the [Voltage noise at 20 MHz](#) (on page B-10) table for checking Noise at 20 MHz.

Check current noise

Equipment required

(Item 5) High current wire

(Item 12) Oscilloscope

(Item 11) 1 Ω Load Resistor

(Item 14) Oscilloscope 10X probe

1. Plug the DUT into your local line power from the mains.
2. Plug the test oscilloscope into the same mains outlet as the DUT.

NOTE

Some AC Power Sources create large amounts of high frequency noise on the power line that the instrument may not fully reject. Noise directly on the mains is typically better controlled.

Use the same mains outlet for both the DUT and test oscilloscope to avoid ground loops which may cause noise.

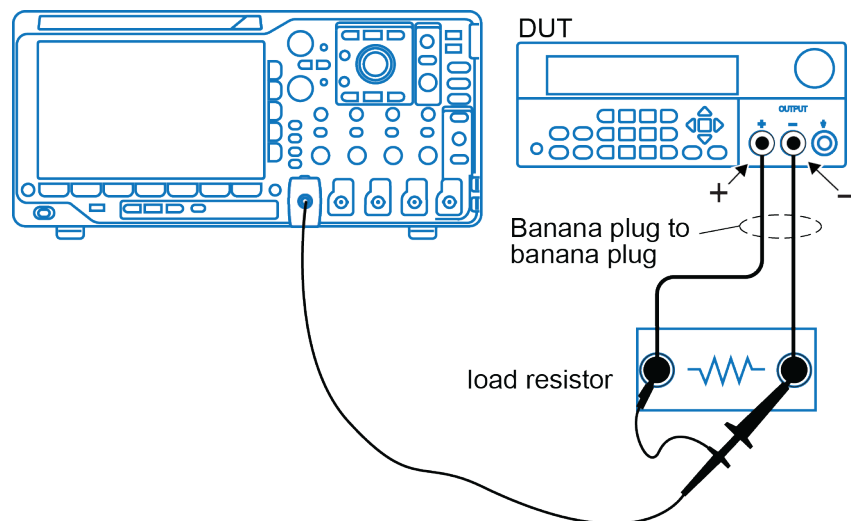
3. Power on the DUT and test oscilloscope.

NOTE

Ensure the warm-up criteria has been met as described in the Performance Verification Conditions.

4. Set up the equipment as shown in the following figure.
Use the appropriate load resistor depending on the model of the DUT. See [Voltage noise at 20 MHz](#) (on page B-10) for information.

Figure 24: 20 MHz current noise test setup



5. Set the oscilloscope as follows:
 - a. 1 mV/division
 - b. 1 M Ω input resistance
 - c. 20 MHz bandwidth (BW) limit
 - d. AC Coupled
 - e. Auto-trigger
 - f. 1 ms/div
 - g. Set to measure V_{p-p} and V_{RMS}
6. Set the DUT to the 100% full-scale output voltage.
7. Set the DUT to the 100% full-scale output current.
8. Turn the DUT output on.

 **WARNING**

Do not touch the load resistor. The load resistor may become hot enough to cause personal injury.

9. Enter the oscilloscope measurements into the [Current noise at 20 MHz](#) (on page B-10) table for checking current noise.
10. Power off the DUT and test equipment.

This completes the performance verification procedure.

Adjustment procedures

This topic contains adjustment procedures. See [Equipment required](#) (on page B-12) for a complete list needed for making any adjustments to your power supply.

These procedures cover the following models (do not attempt to make adjustments to any model not listed)(for more detail about each model see [Key features](#) (on page 1-3)): Note the software that is needed for each model:

| Model | Software needed for adjusting |
|-------------|-------------------------------|
| 2200-20-5 | PC4000.exe |
| 2200-30-5 | |
| 2200-32-3 | |
| 2200-60-2 | |
| 2200-72-1 | |
| 2220-30-1 | PC2220-2230.exe |
| 2220G-30-1 | |
| 2220J-30-1 | |
| 2220GJ-30-1 | |
| 2230-30-1 | |
| 2230G-30-1 | |
| 2230J-30-1 | |
| 2230GJ-30-1 | |

Plus, you will need a calculator or equivalent software program, such as Microsoft® Excel® to calculate engineering equations.

Print the [Test record](#) (on page B-2), and use it to record the performance test results for your power supply.

The adjustment procedures are designed to make any necessary adjustments required for your instrument. If your instrument fails to meet the required adjustment procedures, you should contact Keithley service.

NOTE

You should perform [Voltage adjustment](#) (on page B-40), [Current adjustment](#) (on page B-44), and [Overvoltage protection \(OVP\)](#) (on page B-45) in this order.

Initialization

WARNING

To prevent electrical shock that could result in injury or death, or equipment failure, always power off instruments and disconnect all power sources before touching exposed circuitry. Read and follow the information in the Safety precautions.

To start initialization:

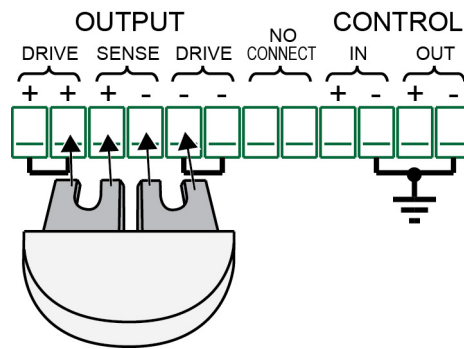
1. On the back of your power supply (device under test - DUT) remove two #10 Torx screws from the DB9 cap, and remove the cap.

Quick Tip

Use an open face wrench to hold the nut of the Torx screws so that the nut inside the DUT does not fall off.

2. Before you begin any adjustments, you will need to disconnect all cables from the remote sense connector DUT and reinstall the shorting clip between the OUTPUT Sense and OUTPUT Drive connectors, as shown in the next figure.

Figure 25: Installing shorting clip on remote sense connector



3. Connect the RS-232 cable between your personal computer and the power supply (DUT).
4. Connect your DUT (refer to [Adjustment procedures](#) (on page B-38) for more information) and the DMM to a power source. Power on the DUT and let it warm up for 20 minutes prior to making adjustments.
5. Enable the RS-232 serial port on the DUT by following the next sequence, depending on the DUT you have:

| Model | Press these buttons to enable RS-232 | | |
|-------------|--------------------------------------|--------------|---|
| 2200-20-5 | Shift | • "period" | 3 |
| 2200-30-5 | | | |
| 2200-32-3 | | | |
| 2200-60-2 | | | |
| 2200-72-1 | | | |
| 2220-30-1 | Enter | ESC "escape" | 3 |
| 2220G-30-1 | | | |
| 2220J-30-1 | | | |
| 2220GJ-30-1 | | | |
| 2230-30-1 | | | |
| 2230G-30-1 | | | |
| 2230J-30-1 | | | |
| 2230GJ-30-1 | | | |

When you enable the serial port, the software will display "SEL RS-232."

1. Set the DMM to:
 - DC Volts
 - Autorange
2. Run the appropriate software for your DUT (refer to [Adjustment procedures](#) (on page B-38) for more information).

NOTE

You will have to select the appropriate channel (1 or 2) when using the PC2220_30 software. Notice that the PC2200 software includes three tabs: Local Voltage, Current, and Overvoltage Protection. Each tab corresponds to the next three sections.

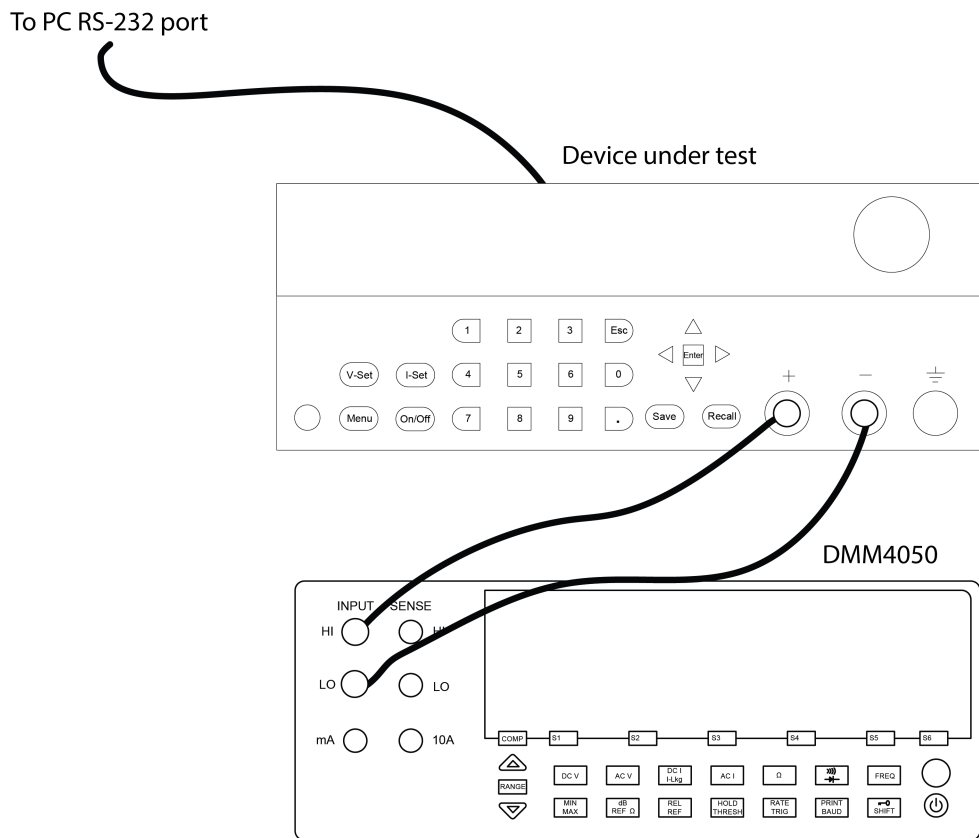
Voltage adjustment

To do the voltage adjustment:

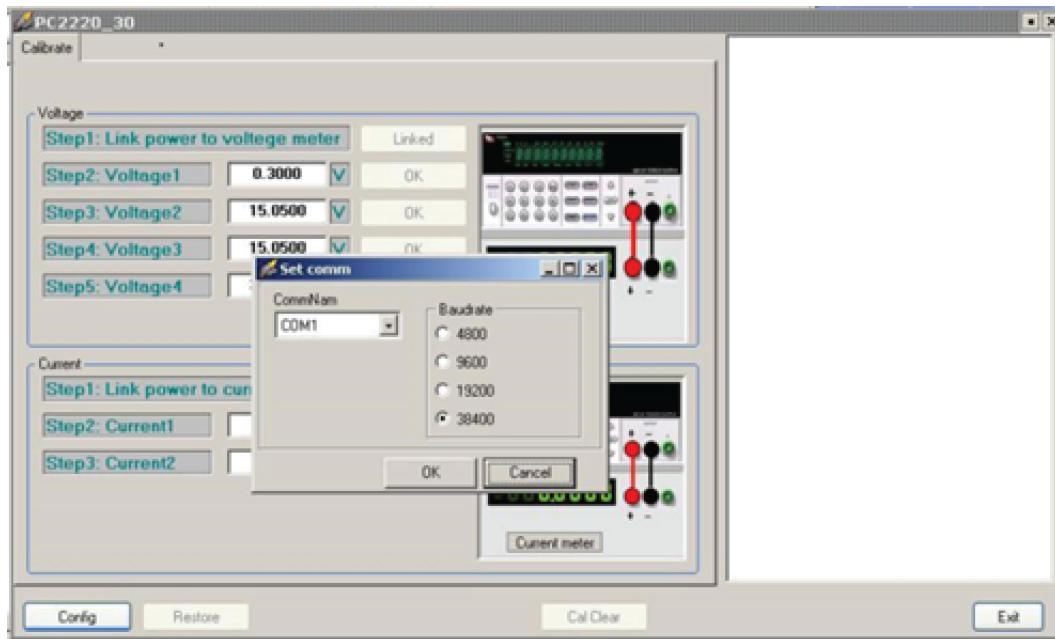
NOTE

Make sure that the equipment is set up as shown in the next figure.

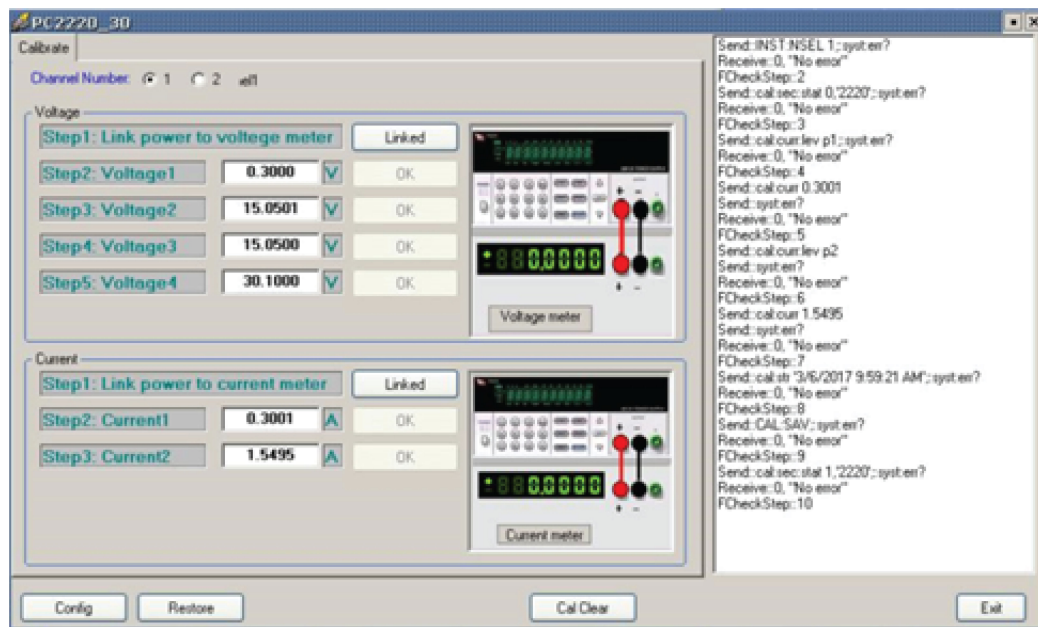
Figure 26: 2200S Voltage calibration with DMM4050



1. Make sure that the software is running.
2. Click the Voltage **Config** button and select Baudrate 9600, if you are using the PC2220_30 software (see next figure and see the NOTE below if you are using the PC2200 software).



3. Click the **Linked** button in the software. The right pane of window should indicate INST:NSEL 1:system? and the response "No error".



4. Click the **Linked** button in the software. **Step 2** is selected (the software sets up the instrument to a voltage depending on the DUT).
5. Enter the value indicated on the DMM to at least four digits after the decimal point. It should be approximately the same value that the DUT shows as the output voltage and may vary between 0.25 V and 2 V.
6. Click **OK** to store the value. **Step 3** is selected.
7. Enter the value indicated on the DMM to at least four digits after the decimal point. This value should be approximately the full-scale voltage of the DUT getting adjusted.
8. Click **OK** to store the value.

A pop-up will indicate that the adjustment is complete.

If you want to repeat the voltage adjustment, click the **Linked** button to restart the process.

NOTE

If you receive a system error, you should see an alert pop-up, however, the software may not close properly. Use the Windows Task Manager by simultaneously pressing control, alt, delete (Ctrl > Alt > Delete) in order to stop and close the software.

NOTE

If are using the PC2200 software, the following figures are examples of the screens you will see when you click the **Config** button on the Local Voltage tab and then click **Linked** and select Baudrate 9600. You should follow the steps above for making your voltage adjustments and refer to these figures.

Figure 27: PC2200 software Local Voltage tab

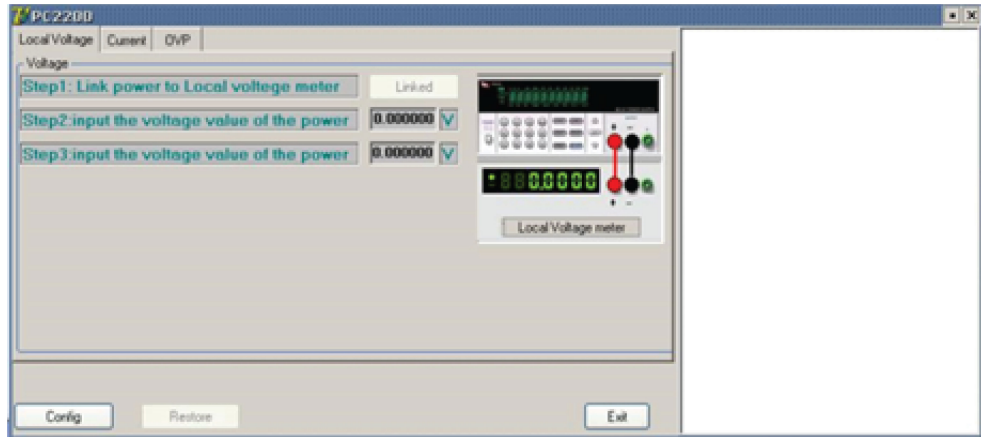
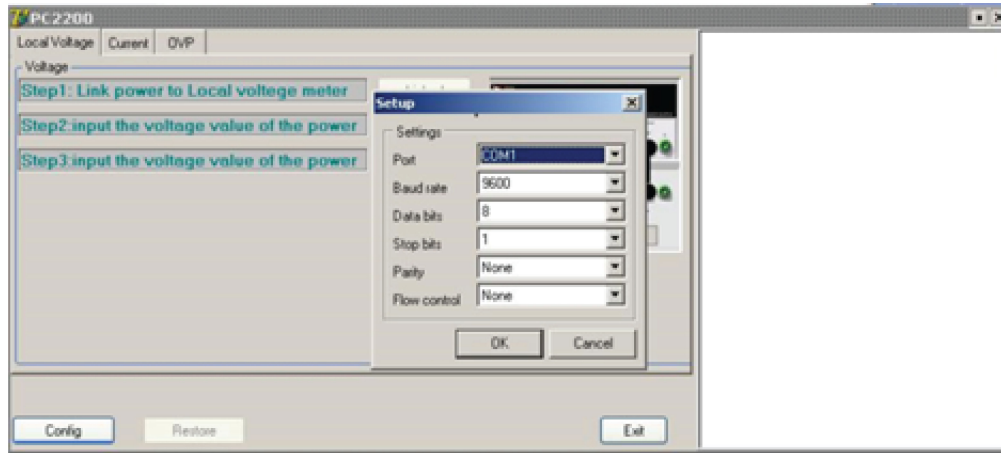


Figure 28: PC2200 software Local Voltage tab Baudrate



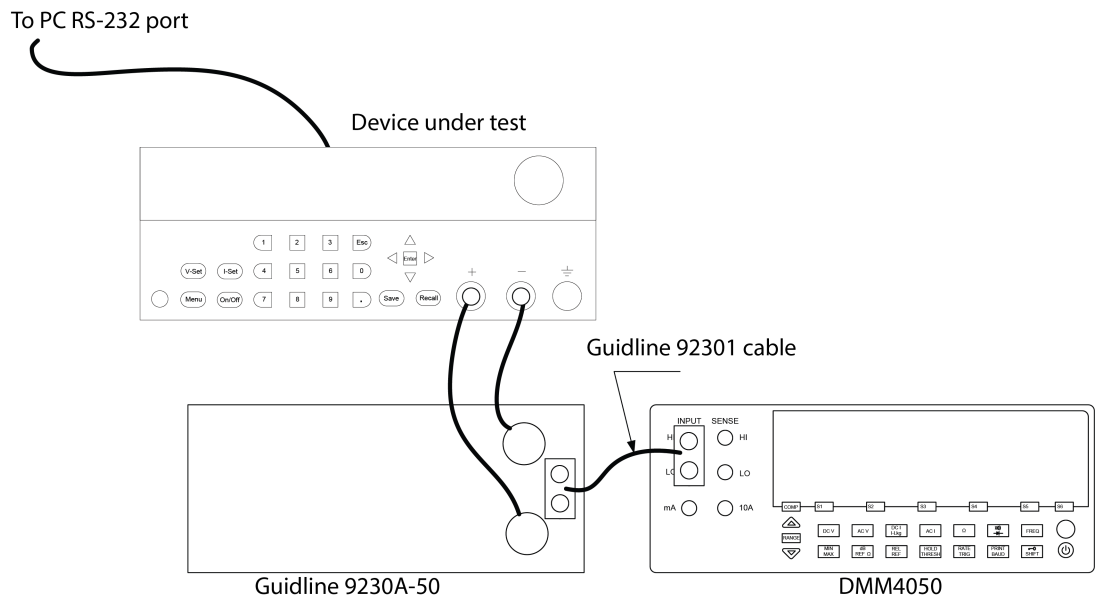
Current adjustment

To do the current adjustment:

NOTE

Make sure that the equipment is set up as shown in the next figure. It is important to attach the cables exactly as shown. Additionally, you can refer to the figures that are in the [Voltage adjustment](#) (on page B-40) topic since the Current adjustment steps are identical (make sure that you refer to the appropriate figures based on the software you are using).

Figure 29: Current adjustment with a Guideline 9230A and a DMM4050



1. Make sure that the software is running and that it is on the Current tab.
2. Click the Current **Linked** button and select Baudrate 9600, if you are using the PC2220_30 software.
3. Click the **Config** button in the software. The right pane of window should indicate INST:NSEL 1:system? and the response "No error".
4. Click the **Linked** button in the software. **Step 2** is selected. The DUT will display the approximate current that you will also achieve after following the next steps using your calculator.
5. Enter the value indicated on the DMM to at least four digits after the decimal point on your calculator.
6. Multiply the calculator entry by 20 to convert the volts to amperage (this is equivalent to dividing by 0.05Ω , which is the value of the shunt resistor).
7. Enter the calculated amperes value to at least five digits, including digits both before and after the decimal point for the Step 2 entry in the software.
8. Click **Enter** to store the value. **Step 3** is selected and the DUT displays the current output.
9. Enter the measured voltage on the shunt resistor to your calculator and multiply by 20.
10. Enter the calculated current for the Step 3 entry. This value should be approximately the full-scale voltage of the power supply getting adjusted.
11. Click **Enter** to store the value.

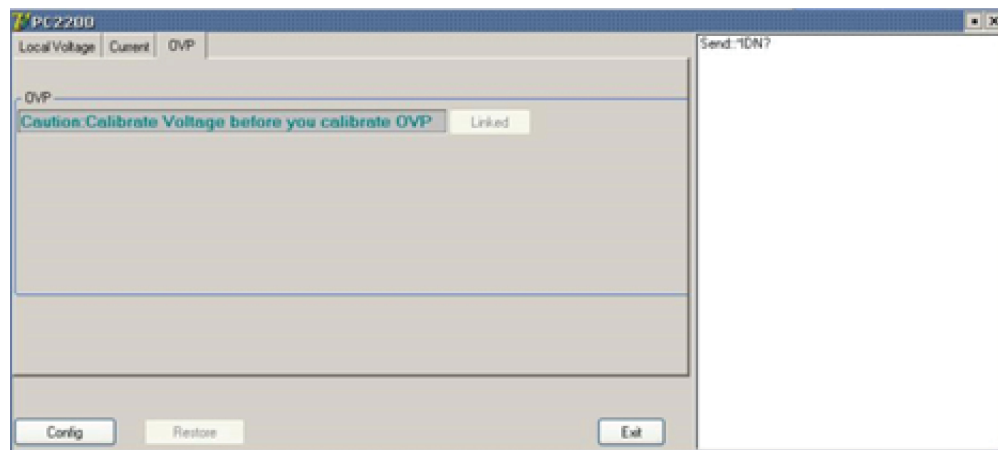
A pop-up will indicate that the adjustment is complete.

If you want to repeat the current adjustment, click the **Linked** button to restart the process.

Overvoltage protection (OVP)

1. Disconnect your DUT from the shunt resistor and the DMM.
2. Select the OVP option (if you are using the PC2220_30 software, you will not have an OVP tab option).
3. Click the **Linked** button in the software. The OVP adjustment is an automatic process.

Figure 30: 2200S PC2200 Linked OVP adjustment



A pop-up will indicate that the adjustment is complete.

Status model

In this appendix:

| | |
|----------------------------------|-----|
| Status and events..... | C-1 |
| Status reporting structure | C-1 |
| Registers | C-3 |

Status and events

This appendix provides details about the status information and events the power supply reports.

Status reporting structure

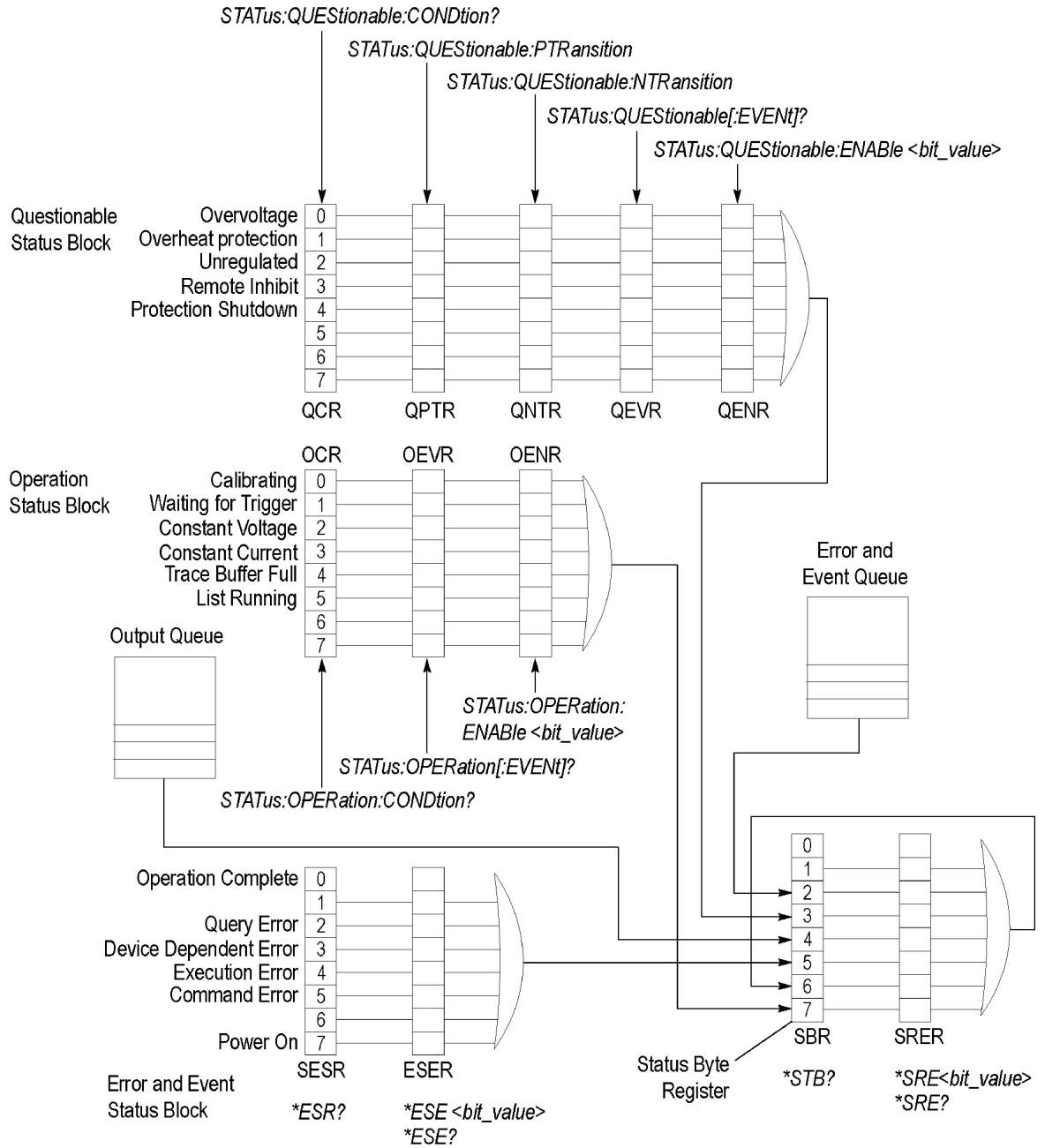
A diagram is provided showing an outline of the power supply error and event reporting function.

The error and event reporting system consists of the following three blocks:

- Standard/Event Status
- Operation Status
- Questionable Status

The operations processed in these blocks are summarized in status bytes, which provide the error and event data.

Figure 31: Error and event handling process



Registers

The registers in the event reporting system fall into two functional groups:

- Status registers contain information about the status of the power supply. They include the standard event status register (SESR).
- Enable registers determine whether selected types of events are reported to the status registers and the event queue. They include the event status enable register (ESER), the service request enable register (SRER), the operation enable register (OENR), and the questionable enable register (QENR).

Status registers

This topic describes the following six types of status registers:

- [Status byte register \(SBR\)](#) (on page C-3)
- [Standard event status register \(SESR\)](#) (on page C-4)
- [Operation condition register \(OCR\)](#) (on page C-5)
- [Operation event register \(OEVR\)](#) (on page C-5)
- [Questionable condition register \(QCR\)](#) (on page C-5)
- [Questionable event register \(QEVR\)](#) (on page C-6)

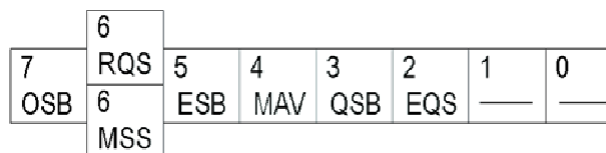
NOTE

The questionable event register may be filtered by a positive transition filter ([Questionable positive transition register \(QPTR\)](#) (on page C-6)) and a negative transition filter ([Questionable negative transition register \(QNTR\)](#) (on page C-6)).

Status byte register (SBR)

The status byte register is made up of 8 bits. Bits 4, 5 and 6 are defined in accordance with IEEE Std 488.2-1992. These bits are used to monitor the output queue, standard event status register, and service requests, respectively.

Figure 32: Status byte register (SBR)



SBR bit functions

| Bit | Function | |
|---------|----------|--|
| 7 (MSB) | OSB | Operation Status Bit. Indicates that an operation event has occurred. |
| 6 | RQS | Request Service. Obtained from a serial poll. Shows that the power supply requests service from the GPIB controller. |
| 6 | MSS | Master Status Summary. Obtained from *STB? query. Summarizes the OSB, ESB, MAV, QSB, and EQS bits in the SBR. |
| 5 | ESB | Event Status Bit. Shows that status is enabled and present in the SESR. |
| 4 | MAV | Message Available. Shows that output is available in the Output Queue. |
| 3 | QSB | Questionable Status Bit. Indicates that a questionable event has occurred. |
| 2 | EQS | Shows that information is available in the Error/Event Queue. |
| 1 | ———— | Not used. |
| 0 | ———— | Not used. |

Standard event status register (SESR)

The standard event status register records six types of events that can occur within the power supply as shown in the following figure.

Figure 33: Standard event status register (SESR)

| | | | | | | | |
|-----|------|-----|-----|-----|-----|------|-----|
| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| PON | ———— | CME | EXE | DDE | QYE | ———— | OPC |

SESR bit functions

| Bit | Function | |
|---------|----------|--|
| 7 (MSB) | PON | Power On. Shows that the power supply was powered |
| 6 | ———— | This bit is not used. |
| 5 | CME | Command Error. Shows that an error occurred while the power supply was parsing a command or query. |
| 4 | EXE | Execution Error. Shows that an error occurred while the power supply was executing a command or query. |
| 3 | DDE | Device Error. Shows that a device dependent error occurred. |
| 2 | QYE | Query Error. Either an attempt was made to read the Output Queue when no data was present or pending, or that data in the Output Queue was lost. |
| 1 | ———— | This bit is not used. |
| 0 (LSB) | OPC | Operation Complete. Shows that the operation is complete. This bit is set when all pending operations complete following an *OPC command. |

Operation condition register (OCR)

The operation condition register is made up of eight bits, which note the occurrence of events as shown here.

Figure 34: Operation Condition Register (OCR)

| | | | | | | | |
|---|---|-----|-----|----|----|-----|-----|
| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| — | — | RUN | TFB | CC | CV | WTG | CAL |

OCR bit functions

| Bit | Function | |
|---------|----------|---|
| 7 (MSB) | — | This bit is not used. |
| 6 | — | This bit is not used. |
| 5 | RUN | Running List. Indicates that the power supply is executing a lis |
| 4 | TBF | Trace Buffer Full. This bit is used internally, by the instrument. |
| 3 | CC | Constant Current. Indicates that the power supply is in constant current mode and is regulating its output current. |
| 2 | CV | Constant Voltage. Indicates that the power supply is in constant voltage mode and is regulating its output voltage. |
| 1 | WTG | Waiting for Trigger. Indicates that the power supply is waiting for a trigger |
| 0 (LSB) | CAL | Calibrating. Indicates that the power supply is calculating a new calibration parameter. |

Operation event register (OEVR)

The operation event register has the same content as the operation condition register. See [Operation condition register \(OCR\)](#) (on page C-5) for information on the operation event register.

Questionable condition register (QCR)

The questionable condition register is made up of eight bits which note the occurrence of five types of events as shown in the following figure.

Figure 35: Questionable condition register (QCR)

| | | | | | | | |
|---|---|---|----|----|-----|----|----|
| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| — | — | — | PS | RI | UNR | OT | OV |

SESR bit functions

| Bit | Function | |
|---------|----------|--|
| 7 (MSB) | ———— | This bit is not used. |
| 6 | ———— | This bit is not used. |
| 5 | ———— | This bit is not used. |
| 4 | PS | Protection Shutdown. |
| 3 | RI | Remote Inhibit. This bit indicates the state of the Remote Inhibit input. |
| 2 | UNR | Unregulated. Indicates that the power supply has gone out of regulation. |
| 1 | OT | Over Temperature. Indicates that the power supply has experienced an over temperature condition and the output has been shut down. |
| 0 (LSB) | OV | Over Voltage. Indicates that the overvoltage protection threshold has been exceeded and the output has shut down. |

Questionable positive transition register (QPTR)

The [Questionable event register \(QEVr\)](#) (on page C-6) can be configured to respond to specific transitions in the [Questionable condition register \(QCR\)](#) (on page C-5). The transitions and the polarity of these transitions are specified in the questionable positive transition register (QPTR) and [Questionable negative transition register \(QNTR\)](#) (on page C-6). These registers act as filters between the QCR and the QEVr. If a bit is set to 1 in the QNTR, the corresponding bit in the QEVr will be set to 1 whenever the same bit in the QCR makes a negative transition, from 1 to 0. If a bit is set to 1 in the QPTR, the corresponding bit in the QEVr will be set to 1 when the same bit in the QCR makes a positive transition, from 0 to 1.

Questionable negative transition register (QNTR)

The [Questionable event register \(QEVr\)](#) (on page C-6) can be configured to respond to specific transitions in the [Questionable condition register \(QCR\)](#) (on page C-5). The transitions and the polarity of these transitions are specified in the [Questionable positive transition register \(QPTR\)](#) (on page C-6) and Questionable negative transition register (QNTR). These registers act as filters between the QCR and the QEVr. If a bit is set to 1 in the QNTR, the corresponding bit in the QEVr will be set to 1 whenever the same bit in the QCR makes a negative transition, from 1 to 0. If a bit is set to 1 in the Questionable positive transition register (QPTR), the corresponding bit in the QEVr will be set to 1 when the same bit in the QCR makes a positive transition, from 0 to 1.

Questionable event register (QEVr)

The questionable event register is made up of eight bits, which have the same significance as the [Questionable condition register \(QCR\)](#) (on page C-5), but have been filtered by the [Questionable positive transition register \(QPTR\)](#) (on page C-6) and [Questionable negative transition register \(QNTR\)](#) (on page C-6).

Enable registers

This topic describes the following four types of enable registers:

- [Event status enable register \(ESER\)](#) (on page C-7)
- [Service request enable register \(SRER\)](#) (on page C-7)
- [Operation enable register \(OENR\)](#) (on page C-8)
- [Questionable enable register \(QENR\)](#) (on page C-8)

ESER, SRER, OENR, and QENR allow you to select which events are reported to the status byte register (SBR). Each bit in an enable register corresponds to a bit in an event register. In order for an event to be reported to a bit in the status byte register (SBR), the corresponding bit in the enable register must be set to one. If the bit in the enable register is set to zero, the event will not affect the status bit. Various commands set the bits in the enable registers. The enable registers and the commands used to set them are described in the following topics.

Event status enable register (ESER)

This register controls which types of events are summarized by the event status bit (ESB) in the status byte register (SBR). Use the *ESE command to set the bits in the ESER. Use the *ESE? query to read it.

Figure 36: Event status enable register (ESER)

| | | | | | | | |
|-----|---|-----|-----|-----|-----|---|-----|
| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| PON | — | CME | EXE | DDE | QYE | — | OPC |

Service request enable register (SRER)

This register controls which bits in the status byte register (SBR) generate a Service Request and are summarized by the master status summary (MSS) bit.

Use the *SRE command to set the SRER. Use the *SRE? query to read the register. The RQS bit remains set to one until either the SBR is read with a Serial Poll or the MSS bit changes back to a zero.

Figure 37: Service request enable register (SRER)

| | | | | | | | | |
|-----|-----|-----|-----|-----|-----|---|---|--|
| | 6 | | | | | | | |
| 7 | RQS | 5 | 4 | 3 | 2 | 1 | 0 | |
| OSB | 6 | ESB | MAV | QSB | EAV | — | — | |
| | MSS | | | | | | | |

Operation enable register (OENR)

The OENR consists of bits defined exactly the same as bits 0 through 7 in the OEVR. You can use this register to control whether or not the operation status bit (OSB) in the SBR is set when an event occurs and the corresponding OEVR bit is set.

Use the STATus:OPERation:ENABLE command to set the bits in the OENR.

Use the STATus:OPERation:ENABLE? query to read the contents of the OENR.

Figure 38: Operation enable register (OENR)

| | | | | | | | |
|---|---|-----|-----|----|----|-----|-----|
| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| — | — | RUN | TFB | CC | CV | WTG | CAL |

Questionable enable register (QENR)

The QENR consists of bits defined exactly the same as bits 0 through 7 in the QEVR register. You can use this register to control whether the QSB in the SBR is set when an event occurs and the corresponding QEVR bit is set.

Use the STATus:QUEStionable:ENABLE command to set the bits in the QENR.

Use the STATus:QUEStionable:ENABLE? query to read the contents of the QENR.

Figure 39: Questionable enable register (QENR)

| | | | | | | | |
|---|---|---|----|----|-----|----|----|
| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| — | — | — | PS | RI | UNR | OT | OV |

*PSC Command

The *PSC command controls the enable registers contents at power-on. Sending *PSC 1 sets the enable registers at power on as follows:

- ESER 0 (equivalent to an *ESE 0 command)
- SRER 0 (equivalent to an *SRE 0 command)

Sending *PSC 0 lets the enable registers maintain their values in nonvolatile memory through a power cycle.

Queues

Output queue

The power supply stores query responses in the Output Queue and empties this queue each time it receives a new command or query message after an <EOM>. The controller must read a query response before it sends the next command (or query) or it will lose responses to earlier queries.

Error/event queue

The Event Queue stores detailed information on up to 32 events. When 32 events stack up in the Event Queue, the 32nd event is replaced by event code 350, "Queue Overflow."

Read the Event Queue with the EVENT? query (which returns only the event number), with the EVMSG? query (which returns the event number and a text description of the event), or with the ALLEV? query (which returns all the event numbers with a description of the event). Reading an event removes it from the queue.

Before reading an event from the Event Queue, you must use the *ESR? query to read the summary of the event from the SESR. This makes the events summarized by the *ESR? read available to the EVENT? and EVMSG? queries, and empties the SESR.

Reading the SESR erases any events that were summarized by previous *ESR? reads but not read from the Event Queue. Events that follow an *ESR? read are put in the Event Queue but are not available until *ESR? is used again.

Messages and codes

Error and event codes with negative values are SCPI standard codes. Error and event codes with positive values are unique to the Series 2200.

No event messages

| Code | Message |
|------|---|
| 0 | No events to report; queue empty |
| 1 | No events to report; new events pending *ESR? |

Command errors

The following table shows the command error messages generated by improper syntax. Check that the command is properly formed and that it follows the rules in the section on command Syntax.

Command error messages (CME bit 5)

| Code | Message |
|------|---|
| 101 | Design error: Too many numeric suffices in Command Spec |
| 110 | No Input Command to parse |
| 114 | Numeric suffix is invalid value |
| 116 | Invalid value in numeric or channel list, e.g. out of range |
| 117 | Invalid number of dimensions in a channel list |
| 120 | Parameter of type Numeric Value overflowed its storage |
| 130 | Wrong units for parameter |
| 140 | Wrong type of parameter(s) |
| 150 | Wrong number of parameters |
| 160 | Unmatched quotation mark in parameters (single/double) |
| 165 | Unmatched bracket |
| 170 | Command keywords were not recognized |
| 180 | No entry in list to retrieve |
| 190 | Too many dimensions in entry to be returned in parameters |
| 191 | Too many char |

Execution errors

The following table lists the execution errors that are detected during execution of a command.

Execution error messages (EXE bit 4)

| Code | Message |
|------|--------------------------------|
| -220 | Execution error |
| -221 | Settings conflict |
| -222 | Data out of range |
| -223 | Too much data |
| -224 | Illegal parameter value |
| -225 | Out of memory |
| -270 | Macro error |
| -272 | Macro execution error |
| -273 | Illegal macro label |
| -276 | Macro recursion error |
| -277 | Macro redefinition not allowed |

System errors

The following table lists the system errors that can occur during power supply operation.

System error messages (DDE bit 3)

| Code | Message |
|------|-----------------|
| -310 | System error |
| -350 | Too many errors |

Query errors

Query error messages (Standard Event Status Register bit 2)

| Code | Message |
|------|--------------------|
| -400 | Query error |
| -410 | Query INTERRUPTED |
| -420 | Query UNTERMINATED |
| -430 | Query DEADLOCKED |
| -440 | Query UNTERMINATED |

Self test errors

The following table lists the self test errors that can occur during power supply operation.

Self test error messages (Standard Event Status Register bit 3)

| Code | Message |
|------|--|
| 0 | No error |
| 1 | Module Initialization Lost |
| 2 | Mainframe Initialization Lost |
| 3 | Module Calibration Lost |
| 4 | Non-volatile RAM STATE section checksum failed |
| 5 | Non-volatile RAM RST section checksum failed |
| 10 | RAM selftest |
| 40 | Flash write failed |
| 41 | Flash erase failed |
| 80 | Digital I/O selftest error |

Device dependent errors

The following table lists the device errors that can occur during power supply operation. These errors may indicate that the power supply needs repair.

Device dependent error messages (DDE bit 3)

| Code | Message |
|-------------|--|
| 220 | Front panel uart overrun |
| 221 | Front panel uart framing |
| 222 | Front panel uart parity |
| 223 | Front panel buffer overrun |
| 224 | Front panel timeout |
| 225 | Front Crc Check error |
| 226 | Front Cmd Error |
| 401 | CAL switch prevents calibration |
| 402 | CAL password is incorrect |
| 403 | CAL not enabled |
| 404 | Computed readback cal constants are incorrect |
| 405 | Computed programming cal constants are incorrect |
| 406 | Incorrect sequence of calibration commands |
| 407 | CV or CC status is incorrect for this command |
| 603 | FETCH of data that was not acquired |
| 604 | Measurement overrange |

Display character codes

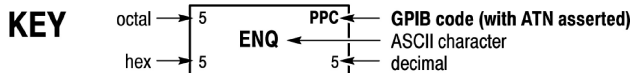
In this appendix:

ASCII code chart D-2

ASCII code chart

Figure 40: ASCII code chart

| B7 B6 B5 BITS B4 B3 B2 B1 | 0 0 0 | | 0 0 1 | | 0 1 0 | | 0 1 1 | | 1 0 0 | | 1 0 1 | | 1 1 0 | | 1 1 1 | |
|---------------------------------------|---------|-----------------------|-----------------------|-----|---------------------|------|-------------------|------|------------------------------------|------|-------|------|------------|------|-------|-----------------|
| | CONTROL | | | | NUMBERS SYMBOLS | | | | UPPER CASE | | | | LOWER CASE | | | |
| 0 0 0 0 | 0 | NUL | 20 | DLE | 40 | LA0 | 60 | LA16 | 100 | TA0 | 120 | TA16 | 140 | SA0 | 160 | SA16 |
| | 0 | | 10 | | 20 | SP | 30 | 0 | 40 | @ | 50 | P | 60 | ` | 70 | p |
| 0 0 0 1 | 1 | GTL | 21 | LL0 | 41 | LA1 | 61 | LA17 | 101 | TA1 | 121 | TA17 | 141 | SA1 | 161 | SA17 |
| | 1 | SOH | 11 | DC1 | 21 | ! | 31 | 1 | 41 | A | 51 | Q | 61 | a | 71 | q |
| 0 0 1 0 | 2 | STX | 22 | DC2 | 42 | " | 62 | LA18 | 102 | TA2 | 122 | TA18 | 142 | SA2 | 162 | SA18 |
| | 2 | | 12 | | 22 | | 32 | 2 | 42 | B | 52 | R | 62 | b | 72 | r |
| 0 0 1 1 | 3 | ETX | 23 | DC3 | 43 | # | 63 | LA19 | 103 | TA3 | 123 | TA19 | 143 | SA3 | 163 | SA19 |
| | 3 | | 13 | | 23 | | 33 | 3 | 43 | C | 53 | S | 63 | c | 73 | s |
| 0 1 0 0 | 4 | SDC | 24 | DCL | 44 | LA4 | 64 | LA20 | 104 | TA4 | 124 | TA20 | 144 | SA4 | 164 | SA20 |
| | 4 | EOT | 14 | DC4 | 24 | \$ | 34 | 4 | 44 | D | 54 | T | 64 | d | 74 | t |
| 0 1 0 1 | 5 | PPC | 25 | PPU | 45 | LA5 | 65 | LA21 | 105 | TA5 | 125 | TA21 | 145 | SA5 | 165 | SA21 |
| | 5 | ENQ | 15 | NAK | 25 | % | 35 | 5 | 45 | E | 55 | U | 65 | e | 75 | u |
| 0 1 1 0 | 6 | ACK | 26 | SYN | 46 | LA6 | 66 | LA22 | 106 | TA6 | 126 | TA22 | 146 | SA6 | 166 | SA22 |
| | 6 | | 16 | | 26 | & | 36 | 6 | 46 | F | 56 | V | 66 | f | 76 | v |
| 0 1 1 1 | 7 | BEL | 27 | ETB | 47 | LA7 | 67 | LA23 | 107 | TA7 | 127 | TA23 | 147 | SA7 | 167 | SA23 |
| | 7 | | 17 | | 27 | ' | 37 | 7 | 47 | G | 57 | W | 67 | g | 77 | w |
| 1 0 0 0 | 10 | GET | 30 | SPE | 50 | LA8 | 70 | LA24 | 110 | TA8 | 130 | TA24 | 150 | SA8 | 170 | SA24 |
| | 8 | BS | 18 | CAN | 28 | (| 38 | 8 | 48 | H | 58 | X | 68 | h | 78 | x |
| 1 0 0 1 | 11 | TCT | 31 | SPD | 51 | LA9 | 71 | LA25 | 111 | TA9 | 131 | TA25 | 151 | SA9 | 171 | SA25 |
| | 9 | HT | 19 | EM | 29 |) | 39 | 9 | 49 | I | 59 | Y | 69 | i | 79 | y |
| 1 0 1 0 | 12 | LF | 32 | SUB | 52 | LA10 | 72 | LA26 | 112 | TA10 | 132 | TA26 | 152 | SA10 | 172 | SA26 |
| | A | | 1A | | 2A | * | 3A | : | 4A | J | 5A | Z | 6A | j | 7A | z |
| 1 0 1 1 | 13 | VT | 33 | ESC | 53 | LA11 | 73 | LA27 | 113 | TA11 | 133 | TA27 | 153 | SA11 | 173 | SA27 |
| | B | | 1B | | 2B | + | 3B | ; | 4B | K | 5B | [| 6B | k | 7B | { |
| 1 1 0 0 | 14 | FF | 34 | FS | 54 | LA12 | 74 | LA28 | 114 | TA12 | 134 | TA28 | 154 | SA12 | 174 | SA28 |
| | C | | 1C | | 2C | , | 3C | < | 4C | L | 5C | \ | 6C | l | 7C | |
| 1 1 0 1 | 15 | CR | 35 | GS | 55 | LA13 | 75 | LA29 | 115 | TA13 | 135 | TA29 | 155 | SA13 | 175 | SA29 |
| | D | | 1D | | 2D | - | 3D | = | 4D | M | 5D |] | 6D | m | 7D | } |
| 1 1 1 0 | 16 | SO | 36 | RS | 56 | LA14 | 76 | LA30 | 116 | TA14 | 136 | TA30 | 156 | SA14 | 176 | SA30 |
| | E | | 1E | | 2E | . | 3E | > | 4E | N | 5E | ^ | 6E | n | 7E | ~ |
| 1 1 1 1 | 17 | SI | 37 | US | 57 | LA15 | 77 | UNL | 117 | TA15 | 137 | UNT | 157 | SA15 | 177 | RUBOUT (DEL) |
| | F | | 1F | | 2F | / | 3F | ? | 4F | O | 5F | - | 6F | o | 7F | 127 |
| | | ADDRESSED COMMANDS | UNIVERSAL COMMANDS | | LISTEN ADDRESSES | | TALK ADDRESSES | | SECONDARY ADDRESSES OR COMMANDS | | | | | | | |



REF: ANSI STD X3.4-1977
IEEE STD 488.1-1987
ISO STD 646-2973

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