# General Specifications 

UP55A<br>Program Controller

## GS 05P02C41-01EN

## Overview

The UP55A program controller employs an easy-toread, 14 -segment large color LCD display, along with navigation keys, thus greatly increasing the monitoring and operating capabilities. A ladder sequence function is included as standard. The short depth of the controller helps save instrument panel space. The UP55A also support open networks such as Ethernet communication.

## Features

- A 14-segment, active (PV display color changing function) color LCD display is employed.
Two five-digit, high-resolution displays are possible. Alphabet letters can be displayed in an easy-to-read manner.
The guide display shows parameter names.
- Easy to operate

Navigation keys (SET/ENTER and Up/Down/Left/ Right arrow keys) are employed to facilitate making settings.

- 65 mm depth

The small depth enables the mounting in a thin and small instrumented panel.

- Ladder sequence function is included as standard. This function allows for creating a simple sequence control. Dedicated LL50A Parameter Setting Software (sold separately) allows for performing programming using a ladder language.
- Various built-in open network functions such as Ethernet are available. Easy connection with various vendors' PLCs is possible.
- Quick setting function

Setting only the minimum necessary parameters for operation is possible. (For single-loop control only)

- Equipped with a multitude of functions Universal I/O and eight control modes (cascade control, etc) are included as standard. PID control, heating/cooling control, feed forward control, etc. are available.


## Functional Specifications

## Program Pattern Functions

The program setting function increases or decreases the value of a target setpoint (SP) according to a given program pattern that varies with time. The controller stores two or more program patterns and the operator can switch between them according to the operating status. Each program pattern consists of multiple line segments (program segments). The operator sets the time interval of each program segment using the segment time or slope. The operator can also set such instructions as the number of repeats, start/stop, and status output (event output) for a given program pattern.


| Number of Program pattern | Max. 30 |
| :---: | :---: |
| Number of program segment per pattern | Max. 99 |
| Number of program pattern | ```Max. 300 (sum of program pattern for all program patterns)``` |
| Segment time | 0.00 to 999.59 (hour.minute or minute. second) |
| Number of PV event | 8 |
| PV event type | PV (measured value) high/low limit SP (setpoint) high/low limit Deviation high/low limit Deviation high and low limits Deviation within high and low limits Target SP high/low limit <br> Target SP deviation high/low limit Target SP deviation high and low limits Target SP deviation within high and low limits <br> Control output high/low limit alarm Cooling control output high/low limit alarm |
| Number of Time event | 16 |
| Time of time event | 0.01 to 999.59 (hour.minute or minute. second) |
| Number of repeat cycles | 0 to 999, CONT (limitless number of times) |
| Wait operation | 5 groups Can be set the upper-side wait zone and the lower zone for program setpoint. |
| Fast-forwarding of program operation | 1: Normal, 2: Twice, 5: Five times, 10: Ten times, 20: Twenty times Use this function when checking the program pattern setting. Only Time of Segment and Time event can be faster. |
| Synchronized program operation | If the progress of the operation of one unit is faster, the program operation can be forcibly stopped by digital input when switching between segments. |
| Program pattern link | Available |
| Program pattern edit | Addition and deleting of program segment can be available. Copy and deletion of program pattern can also be available. |

## Control Computation Function

## Control Specifications

## (1) Control Mode

Control functions of the controller can be set as control modes.

| Control mode | Function |
| :---: | :--- |
| SGL | Single-loop control |
| CAS1 | Cascade primary-loop control |
| CAS | Cascade control |
| PVSW | Loop control with PV switching |
| PVSEL | Loop control with PV auto-selector (Max./Min.// <br> Ave./Diff) |

*1: Remote auxiliary analog input is required.
(2) Control period

Selectable from 100 ms , and 200 ms

| Model and <br> suffix code <br> (See the <br> model code) | Number <br> of analog <br> input <br> points | Number <br> of analog <br> output <br> points (*1) | Number <br> of contact <br> input <br> points (*2) | Number of <br> contact <br> output <br> points (*3) |
| ---: | :---: | :---: | :---: | :---: |
| UP55A |  |  |  |  |
| $-x 0 x$ | 1 | 1 | 8 | 8 |
| $-x 1 x$ | 2 | 1 | $9(8)$ | 8 |
| $-x 2 x$ | 1 | 1 | 8 | 8 |
| $-x 3 x$ | 1 | 1 | 8 | 18 |
| $-x 4 x$ | 4 | 1 | $6(5)$ | 3 |

*1: Excluding control output
*2: The numbers in parentheses show the numbers of points with RSP direct input option (/DR).
*3: Excluding control output relays

## Control Computation Specifications

(1) Combination of types of control and control modes

| Types of control | Control mode |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  | SGL | CAS1 | CAS | PVSW | PVSEL |
| PID control | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ |
| ON/OFF control (*1) | $\checkmark$ | N/A | N/A | N/A | N/A |
| Heating and cooling control (*2) | $\checkmark$ | N/A | $\checkmark$ | $\checkmark$ | $\checkmark$ |

$\checkmark$ : Available, N/A: Not Available
*1: Not selectable for Position proportional type
*2: Selectable for heating and cooling control
(2) Control Computation Function
(a) The number of PID parameter groups

Eight sets of PID parameters can be set. For cascade control, respectively, eight sets can be set for main
(primary side) and slave (secondary side).
(b) Selecting the PID parameter group

The following PID parameter groups can be selected.

- Segment PID
- Measured input zone PID
- Target setpoint zone PID
- Reached target setpoint zone PID
- Local PID
- Reference deviation
(c) Auto-tuning
- Tuning results can be selected from two options, Normal or Stable.
- Tuning output limit can be set. (It cannot be used in heating/cooling control.)
(d) "Super" function: Overshoot-suppressing function
(e) "Super 2" function: Hunting-suppressing function
(f) RESET preset output function
(g) Input ERROR preset output function
(h) MANUAL preset output function
(3) Operation Mode Switching

|  | Start of program operation (PROG) <br> Stop of program operation (RESET) <br> Start of local-mode operation (LOCAL) |
| :--- | :--- |
| Operation |  |
| mode |  |
| switching |  | | Start of remote-mode operation (REM) |
| :--- |
| Pause/cancel release of program operation (HOLD) |
| Advance of segment (ADV) |
| Automatic (AUTO)/Manual (MAN) switching |
| Local (LSP)/CAS switching when in cascade control |

(4) Control Parameter Setting Range

| Proportional band | 0.1 to $999.9 \%$ |
| :--- | :--- |
| Integral time | 1 to 6000 sec. or OFF (using manual <br> reset) |
| Derivative time | 1 to 6000 sec. or OFF |
| ON/OFF control hysteresis <br> (one or two hysteresis <br> points) | 0.0 to $100.0 \%$ of measured input <br> range width |
| Preset output value | -5.0 to $105.0 \%$ (however, 0 mA or less <br> cannot be output) |
| High/low output limiter | -5.0 to $105.0 \%$ <br> Low limit setpoint < high limit setpoint |
| Tight shut function | When manual control is carried out <br> with 4 to 20 mA output, control output <br> can be reduced to about 0 mA. |
| Rate-of-change limiter of <br> output | 0.1 to $100.0 \% /$ sec., OFF |
| Output dead band | For heating and cooling control: <br> -100.0 to 50.0\% <br> For position proportional control: 1.0 <br> to 10.0\% |

## Alarm Functions

- Types of Alarm

|  | PV (measured value) high/low limit alarm <br> Deviation high/low limit alarm <br> Meviation high and low limits alarm <br> Meviation within high and low limits alarm <br> alarm <br> Deviation alarm <br> Rate-of-change <br> alarm |
| :--- | :--- |
| Analog input PV high/low limit alarm |  |
| Analog input RSP high/low limit alarm |  |
| Auxiliary analog input high/low limit alarm |  |
| Feedback input high/low limit alarm |  |
| PV rate-of-change alarm |  |$|$

- Alarm Functions

| Alarm output <br> action | Alarm stand-by action <br> Alarm latch-f (forced reset) function <br> Alarm hysteresis <br> Alarm ON/OFF delay timer |
| :--- | :--- |
| Number of <br> alarm settings | 8 (per loop) |
| Number of <br> alarm output <br> points | Up to 9 (differs by model code) |

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## Contact I/O Function

This function allows for allocating the input error condition, operation condition, alarm condition or other conditions to the contact input and contact output.

| Contact input | Switch to PROG (Start of program operation) |
| :---: | :---: |
|  | Switch to RESET (Stop of program operation) |
|  | Switch to LOCAL (LSP) (Start of local-mode operation) |
|  | Switch to REMOTE |
|  | PROG/RESET Switch |
|  | PROG/LOCAL (LSP) Switch |
|  | PROG/HOLD Switch |
|  | Switch to HOLD (Start of hold-mode operation) |
|  | Advance of segment |
|  | Wait ON/OFF switch |
|  | AUTO/MAN switch |
|  | LOCAL (LSP)/CAS switch |
|  | Auto-tuning START/STOP switch |
|  | Output tracking switching |
|  | Two-input switching |
|  | Latch release |
|  | LCD backlight ON/OFF switch |
|  | PV red/white switch |
|  | Message interrupt displays 1 through 4 |
|  | Program pattern number selection |
|  | PID number selection |
|  | Manual preset output number selection |
| Contact output | PV event, Time event, Alarm |
|  | Loop 2 alarm (for cascade control) |
|  | Status output |

## Ladder Sequence Function

(1) Number of I/O Points

| Number of digital input points | Up to 9 |
| :--- | :--- |
| Number of digital output points | Up to 18 |

This is limited by the number of contact I/O signal points. (See the model code.)

## (2) Types of Instruction

|  | Number of <br> instructions | Remark |
| :--- | :--- | :--- |
| Number of basic <br> instruction types | 13 | Load, AND, OR, Timer, <br> Counter, etc. |
| Number of <br> application <br> instruction types | 73 | Comparison, reverse, addition/ <br> subtraction/multiplication/ <br> division, logic operation, high/ <br> low limiter, etc. |

## (3) Sequence Device

|  | Types of device | Number of points |
| :--- | :--- | :--- |
| Digital I/O | Input relay | 9 (max.) |
|  | Output relay | 18 (max.) |
|  | M relay (bit data) | 256 |
|  | DAT register (data) | 28 |
|  | P register (parameter) | 10 |
|  | K register (constant) | 30 |
| Special device | Special relay (bit data) | 12 |

Process data and process relay can be used besides the above-mentioned.

## (4) Program capacity

Max. Program capacity: 500 steps *
*: Available number of steps differs according to the parameters, using command and control period.
(5) Ladder computation period

Ladder computation period is the same as control period.

## Communication Function

|  | Function | Method | Interface | Targets | Max connection | Communication Data |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Modbus/TCP | A standard industry protocol allowing communications between the controller and devices such as PCs, PLCs, and DCSs. | Server | Ethernet | PLC and others | 2 connections | PV, ALM etc |
|  |  | Gateway | Ethernet + RS-485 | RS-485: UT55A/UT52A/ UT35A/UT32A/UP55A/ UP35A/UM33A (*1) | 31 units |  |
| Modbus <br> (RTU/ASCII) |  | Slave | RS-485 | PLC and others, UT55A/ UT52A/UT35A/UT32A/ UP55A/UP35A/UM33A (*1) | 31 units |  |
| PROFIBUS-DP | Used for communication between PLCs and remote I/O, enabling highspeed data transmission. | Slave | RS-485 | PLC and others | Number of nodes: $126$ |  |
|  |  | Modbus master function | RS-485 | UT55A/UT52A/UT35A/ UT32A/UP55A/UP35A | 31 Units (Main Controller is included.) |  |
| CC-Link |  | Slave | RS-485 | PLC and others | Number of nodes: 42 (Remote device) |  |
|  |  | Modbus master function | RS-485 | UT55A/UT52A/UT35A/ UT32A/UP55A/UP35A | 31 Units (Main Controller is included.) |  |
| DeviceNet |  | Slave | RS-485 | PLC and others | Number of nodes: 64 |  |
|  |  | Modbus master function | RS-485 | UT55A/UT52A/UT35A/ UT32A/UP55A/UP35A | 31 Units (Main Controller is included.) |  |
| Peer to peer | A protocol allowing multiple controllers to send and receive data between one another. The Ladder Program is used. | Multi-drop | RS-485 (2 wire only) | UT55A/UT52A/UT35A/ UT32A/UP55A/UP35A | Read/Write: 4 units Read only : 28 units |  |
| Coordinated Communication | A protocol to coordinate the operation of two or more instruments controlling the same process. | Master/ Slave | RS-485 | UT55A/UT52A/UT35A/ <br> UT32A/UP55A/UP35A (*2) | Master : 1 unit Slave : 31 units |  |
| PC link | The proprietary Yokogawa protocol allowing communications to PCs, PLCs and touch panels. | Slave | RS-485 | UT55A/UT52A/UT35A/ UT32A/UP55A/UP35A/ UM33A (*2) | 31 units |  |
| Ladder | A protocol to communicate to PLCs. |  |  |  |  |  |

*1: UT digital indicating controller, Signal conditioner JUXTA, Power monitor POWERCERT can be connected.
*2: UT digital indication controllers can be connected.

## Physical interface

Ethernet Standard : IEEE802.3 (10BASE-T, 100BASE-TX)
Max segment length : 100 m
Max. Connecting Configuration : Cascade Max. 4 level (10BASE-T), Max. 2 level (100BASE-TX)
RS-485
Communication method: Two-wire harf-duplex or four-wire harf-duplex, start-stop synchronization, and non-procedural
Baud rate: 600,1200,2400,4800,9600,19200 or 38400 bps
Peer to peer communication is only 19200 bps
Maximum communication distance: 1200 m
Terminating resistor: $220 \Omega$ (External)
*3: 38400 bps for UP55A model code: Type $3=1$.
PROFIBUS-DP Standard : Field bus (IEC61158)
Corresponding version : DP V0
Baud rate : 9.6k, 19.2k, $45.45 \mathrm{k}, 93.75 \mathrm{k}, 187.5 \mathrm{k}, 0.5 \mathrm{M}, 1.5 \mathrm{M}, 3 \mathrm{M}, 6 \mathrm{M}, 12 \mathrm{M}$, AUTO (*4)
Communication distance : 1200 m ( 9.6 k to 93.75 k ), 1000m (187.5k), 400 m ( 0.5 M ), 200m (1.5M), 100m (3M to 12M)
*4: AUTO automatically sets the baud rate to that of the host controller (PROFIBUS-DP master).
CC-Link Supported on version: Remote device (Ver.1.10, Ver.2.00)
Baud rate : 156k, 625k, 2.5M, 5M, 10M bps
Transmission distance : 1.2 km (156k bps), 600 m ( 625 kbps ), 200 m ( 2.5 M bps ), 150 m ( 5 M bps ), 100 m ( $10 \mathrm{M} \mathrm{bps)}$
When used optical repeater : 7.6 km (156k) to 4.3 km (10M)
DeviceNet Standard: Field bus (IEC61158)
Baud rate 125k, 250k, 500k bps
Transmission distance 500m (125k bps), 250m (250k bps), 100m (500k bps)

## Hardware Specifications

## Display Specifications

- PV display: 5-digit, 14-segment active color LCD (white/red)

Character height: 21.5 mm

- Data display: 5 -digit, 11 -segment color LCD (orange)
- Bar graph display: 12 -segment color LCD (orange)

$(2)+(3)+(4):$ Setpoint display
Names of Display Parts



## Universal Input Specifications

- Number of inputs: 1
- Input type, instrument range, and measurement accuracy: See the table below.

| Input Type |  | Instrument Range ( ${ }^{\circ} \mathrm{C}$ ) |  |  | Instrument Range ( ${ }^{\circ} \mathrm{F}$ ) |  |  | Accuracy |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Thermocouple | K | -270.0 |  | $1370.0^{\circ} \mathrm{C}$ | -450.0 | to | $2500.0^{\circ} \mathrm{F}$ | $\pm 0.1 \%$ of instrument range $\pm 1$ digit for $0^{\circ} \mathrm{C}$ or more $\pm 0.2 \%$ of instrument range $\pm 1$ digit for less than $0^{\circ} \mathrm{C}$ $\pm 2 \%$ of instrument range $\pm 1$ digit for less than $-200.0^{\circ} \mathrm{C}$ of thermocouple K <br> $\pm 1 \%$ of instrument range $\pm 1$ digit for less than $-200.0^{\circ} \mathrm{C}$ of thermocouple T |
|  |  | -270.0 | to | $1000.0^{\circ} \mathrm{C}$ | -450.0 | to | $2300.0^{\circ} \mathrm{F}$ |  |
|  |  | -270.0 | to | $500.0^{\circ} \mathrm{C}$ | -200.0 | to | $1000.0^{\circ} \mathrm{F}$ |  |
|  | J | -200.0 | to | $1200.0^{\circ} \mathrm{C}$ | -300.0 | to | $2300.0^{\circ} \mathrm{F}$ |  |
|  | T | -270.0 | to | $400.0^{\circ} \mathrm{C}$ | -450.0 | to | $750.0^{\circ} \mathrm{F}$ |  |
|  |  | 0.0 | to | $400.0^{\circ} \mathrm{C}$ | -200.0 | to | $750.0^{\circ} \mathrm{F}$ |  |
|  | B | 0.0 | to | $1800.0^{\circ} \mathrm{C}$ | 32 | to | $3300{ }^{\circ} \mathrm{F}$ | $\pm 0.15 \%$ of instrument range $\pm 1$ digit for $400^{\circ} \mathrm{C}$ or more $\pm 5 \%$ of instrument range $\pm 1$ digit for less than $400^{\circ} \mathrm{C}$ |
|  | S | 0.0 | to | $1700.0^{\circ} \mathrm{C}$ | 32 | to | $3100^{\circ} \mathrm{F}$ | $\pm 0.15 \%$ of instrument range $\pm 1$ digit |
|  | R | 0.0 | to | $1700.0^{\circ} \mathrm{C}$ | 32 | to | $3100^{\circ} \mathrm{F}$ |  |
|  | N | -200.0 | to | $1300.0^{\circ} \mathrm{C}$ | -300.0 | to | $2400.0^{\circ} \mathrm{F}$ | $\pm 0.1 \%$ of instrument range $\pm 1$ digit <br> $\pm 0.25 \%$ of instrument range $\pm 1$ digit for less than $0^{\circ} \mathrm{C}$ |
|  | E | -270.0 | to | $1000.0^{\circ} \mathrm{C}$ | -450.0 | to | $1800.0^{\circ} \mathrm{F}$ | $\pm 0.1 \%$ of instrument range $\pm 1$ digit for $0^{\circ} \mathrm{C}$ or more $\pm 0.2 \%$ of instrument range $\pm 1$ digit for less than $0^{\circ} \mathrm{C}$ $\pm 1.5 \%$ of instrument range $\pm 1$ digit for less than $200.0^{\circ} \mathrm{C}$ of thermocouple E. |
|  | L | -200.0 | to | $900.0^{\circ} \mathrm{C}$ | -300.0 | to | $1600.0^{\circ} \mathrm{F}$ |  |
|  | U | -200.0 | to | $400.0^{\circ} \mathrm{C}$ | -300.0 | to | $750.0^{\circ} \mathrm{F}$ |  |
|  |  | 0.0 | to | $400.0^{\circ} \mathrm{C}$ | -200.0 | to | $1000.0^{\circ} \mathrm{F}$ |  |
|  | W | 0.0 | to | $2300.0^{\circ} \mathrm{C}$ | 32 | to | $4200^{\circ} \mathrm{F}$ | $\pm 0.2 \%$ of instrument range $\pm 1$ digit (Note 2) |
|  | Platinel 2 | 0.0 | to | $1390.0^{\circ} \mathrm{C}$ | 32.0 | to | $2500.0^{\circ} \mathrm{F}$ | $\pm 0.1 \%$ of instrument range $\pm 1$ digit |
|  | PR20-40 | 0.0 | to | $1900.0^{\circ} \mathrm{C}$ | 32 | to | $3400^{\circ} \mathrm{F}$ | $\pm 0.5 \%$ of instrument range $\pm 1$ digit for $800^{\circ} \mathrm{C}$ or more Accuracy is not guaranteed for less than $800^{\circ} \mathrm{C}$. |
|  | W97Re3W75Re25 | 0.0 | to | $2000.0^{\circ} \mathrm{C}$ | 32 | to | $3600^{\circ} \mathrm{F}$ | $\pm 0.2 \%$ of instrument range $\pm 1$ digit |
| RTD | JPt100 | -200.0 | to | $500.0^{\circ} \mathrm{C}$ | -300.0 | to | $1000.0^{\circ} \mathrm{F}$ | $\pm 0.1 \%$ of instrument range $\pm 1$ digit (Note 1) |
|  |  | -150.00 | to | $150.00^{\circ} \mathrm{C}$ | -200.0 | to | $300.0^{\circ} \mathrm{F}$ | $\pm 0.1 \%$ of instrument range $\pm 1$ digit |
|  | Pt100 | -200.0 | to | $850.0^{\circ} \mathrm{C}$ | -300.0 | to | $1560.0^{\circ} \mathrm{F}$ | $\pm 0.1 \%$ of instrument range $\pm 1$ digit (Note 1) |
|  |  | -200.0 | to | $500.0^{\circ} \mathrm{C}$ | -300.0 | to | $1000.0^{\circ} \mathrm{F}$ |  |
|  |  | -150.00 | to | $150.00^{\circ} \mathrm{C}$ | -200.0 | to | $300.0^{\circ} \mathrm{F}$ | $\pm 0.1 \%$ of instrument range $\pm 1$ digit |
| Standard signal |  | 0.400 to 2.000 V |  |  |  |  |  | $\pm 0.1 \%$ of instrument range $\pm 1$ digit |
|  |  | 1.000 to 5.000 V |  |  |  |  |  |  |
|  |  | 4.00 to 20.00 mA |  |  |  |  |  |  |
| DC voltage/current |  | 0.000 to 2.000 V |  |  |  |  |  |  |
|  |  | 0.00 to 10.00 V |  |  |  |  |  |  |
|  |  | 0.00 to 20.00 mA |  |  |  |  |  |  |
|  |  | -10.00 to 20.00 mV |  |  |  |  |  |  |
|  |  | 0.0 to 100.0 mV |  |  |  |  |  |  |

The accuracy is that in the standard operating conditions: $23 \pm 2^{\circ} \mathrm{C}, 55 \pm 10 \% \mathrm{RH}$, and power frequency at $50 / 60 \mathrm{~Hz}$.
Note $1: \pm 0.3^{\circ} \mathrm{C} \pm 1$ digit in the range between 0 and $100^{\circ} \mathrm{C}, \pm 0.5^{\circ} \mathrm{C} \pm 1$ digit in the range between -100 and $200^{\circ} \mathrm{C}$.
Note 2: W: W-5\% Re/W-26\% Re(Hoskins Mfg.Co.). ASTM E988

Input sampling (control) period: Select from 100 and 200 ms

- Burnout detection:

Functions at TC, RTD, and standard signal.
Upscale, downscale, and off can be specified.
For standard signal, burnout is determined to have
occurred if it is 0.1 V or 0.4 mA or less.

- Input bias current: $0.05 \mu \mathrm{~A}$ (for TC or RTD)
- Measured current (RTD): About 0.16 mA
- Input resistance:

TC or mV input: $1 \mathrm{M} \Omega$ or more
V input: About $1 \mathrm{M} \Omega$
$m A$ input: About $250 \Omega$

- Allowable signal source resistance:

TC or mV input: $250 \Omega$ or less

Effects of signal source resistance: $0.1 \mu \mathrm{~V} / \Omega$ or less DC voltage input: $2 \mathrm{k} \Omega$ or less
Effects of signal source resistance: About $0.01 \% / 100 \Omega$

- Allowable wiring resistance: RTD input: Max. $150 \Omega$ /wire (The conductor resistance between the three wires shall be equal.) Wiring resistance effect: $\pm 0.1^{\circ} \mathrm{C} / 10 \Omega$
- Allowable input voltage/current:

TC, mV, mA and RTD input: $\pm 10$ V DC V input: $\pm 20$ V DC mA input: $\pm 40 \mathrm{~mA}$

- Noise rejection ratio:

Normal mode: 40 dB or more (at $50 / 60 \mathrm{~Hz}$ )
Common mode: 120 dB or more (at $50 / 60 \mathrm{~Hz}$ )

For 100-240 V AC, the power frequency can be set manually. Automatic detection is also available.
For $24 \mathrm{VAC} / \mathrm{DC}$, the power frequency can be set manually.

- Reference junction compensation error:
$\pm 1.0^{\circ} \mathrm{C}\left(15\right.$ to $\left.35^{\circ} \mathrm{C}\right)$
$\pm 1.5^{\circ} \mathrm{C}$ ( -10 to $15^{\circ} \mathrm{C}$ and 35 to $50^{\circ} \mathrm{C}$ )
- Applicable standards: JIS/IEC/DIN (ITS-90) for TC and RTD


## Auxiliary Analog Input

- Use: Remote setpoint setting, external compensating input, auxiliary input for computation, etc.
- Number of inputs: See the table of Model and Suffix Codes.
- Input type, instrument range, and measurement accuracy: See the table below.

| Input Type | Instrument <br> Range | Accuracy |
| :--- | :--- | :--- |
| Standard <br> signal | 0.400 to 2.000 V | $\pm 0.2 \%$ of instrument range $\pm 1$ digit |
|  | $\pm 0.1 \%$ of instrument range $\pm 1$ digit |  |
| DC voltage | 0.000 to 2.000 V | $\pm 0.2 \%$ of instrument range $\pm 1$ digit |
|  | 0.00 to 10.00 V | $\pm 0.1 \%$ of instrument range $\pm 1$ digit |
| DC voltage <br> for high-input <br> impedance | 0.000 to 1.250 V | $\pm 0.1 \%$ of instrument range $\pm 1$ digit |

- Input sampling (control) period: Same as universal input
- Input resistance: About $1 \mathrm{M} \Omega$

However, $10 \mathrm{M} \Omega$ or more for DC voltage for highinput impedance range

- Burnout detection: Functions at standard signal Burnout is determined to have occurred if it is 0.1 V or less.


## Remote Input with Direct Input

- Number of inputs: See the table of Model and Suffix Codes.
- Input type, instrument range, and measurement accuracy: Same as universal input except the table below.

| Input Type |  | Instrument Range |  | Accuracy |
| :--- | :--- | :--- | :--- | :--- |
|  | ${ }^{\circ} \mathrm{C}$ |  | ${ }^{\circ} \mathrm{F}$ |  |$)$.

Note $1: \pm 0.5^{\circ} \mathrm{C} \pm 1$ digit in the range between -200.0 and $500.0^{\circ} \mathrm{C} /-300.0$ and $1000.0^{\circ} \mathrm{F}$.

- Input sampling (control) period: Same as universal input
- Burnout detection: Same as universal input


## Analog Output Specifications

- Number of outputs:

Control output: 1
Cooling-side control output of Heating/cooling type: 1

- Output type: Current output or voltage pulse output
- Current output: 4 to 20 mA DC or 0 to $20 \mathrm{~mA} \mathrm{DC/load}$ resistance of $600 \Omega$ or less
- Current output accuracy: $\pm 0.1 \%$ of span ( $\pm 5 \%$ of span for 1 mA or less)
The accuracy is that in the standard operating conditions: $23 \pm 2^{\circ} \mathrm{C}, 55 \pm 10 \% \mathrm{RH}$, and power frequency at $50 / 60 \mathrm{~Hz}$.
- Voltage pulse output:

Use: Time proportional output
On-voltage: 12 V or more/load resistance of $600 \Omega$ or more Off-voltage: 0.1 V DC or less
Time resolution: 10 ms or $0.1 \%$ of output, whichever is larger

## Step Response Time Specifications

Within 500 ms (when the control period is 100 ms ) Within 1 s (when the control period is 200 ms ) ( $63 \%$ of analog output response time when a step change of 10 to $90 \%$ of input span is applied)

## Relay Contact Output Specifications

- Contact type and number of outputs: Control output: contact point 1c; 1 point Cooling-side control output of Heating/cooling type: contact point 1c; 1 point Event output: contact point 1a; 3 points (common is independent)
- Contact rating: Contact point 1c (control output): 250 V AC, 3 A or 30 V DC, 3A (resistance load) Contact point 1a (event output): 240 V AC, 1 A or 30 V DC, 1 A (resistance load)
- Use: Time proportional output, event output, alarm output, FAIL output, etc.
- Time resolution of control output: 10 ms or $0.1 \%$ of output, whichever is larger
Note: This cannot be used for a small load of 10 mA or less.
*: The control output should always be used with a load of 10 mA or more.
The event output should always be used with a load of 1 mA or more.


## Position Proportional Output Specifications

- Position signal input:

Slide resistance: $100 \Omega$ to $2.5 \mathrm{k} \Omega$ of total resistance $100 \%$ side and slide line: with disconnection detection $0 \%$ side: without disconnection detection Current input: 4 to 20 mA (with disconnection detection) Input resistance: about $330 \Omega$

- Sampling period: 50 ms
- Measurement resolution: $0.1 \%$ of input span
- Position proportional relay output: Contact point 1a; 2 points, 250 V AC, 3 A or 30 V DC, 3 A (resistance load)
*: This should always be used with a load of 10 mA or more.


## Retransmission Output Specifications

- Number of outputs: Retransmission output; 1, shared with 15 V DC loop power supply
- Current output: 4 to 20 mA DC or 0 to $20 \mathrm{mADC/}$ load resistance of $600 \Omega$ or less
- Current output accuracy (conversion accuracy from PV display on the set scale): $\pm 0.1 \%$ of span ( $\pm 5 \%$ of span for 1 mA or less)

The accuracy is that in the standard operating conditions: $23 \pm 2^{\circ} \mathrm{C}, 55 \pm 10 \% \mathrm{RH}$, and power frequency at $50 / 60 \mathrm{~Hz}$.
This is not conversion accuracy through input and output but the performance of transmission output itself.

## 15 V DC Loop Power Supply Specifications

(Shared with retransmission output)

- Power supply: 14.5 to 18.0 V DC
- Maximum supply current: About 21 mA (with shortcircuit current limiting circuit)


## Contact Input Specifications

- Number of inputs: See the table of Model and Suffix Codes.
- Input type: No-voltage contact input or transistor contact input
- Input contact rating: 12 V DC, 10 mA or more Use a contact with a minimum on-current of 1 mA or more.
- ON/OFF detection: No-voltage contact input: Contact resistance of $1 \mathrm{k} \Omega$ or less is determined as "ON" and contact resistance of $50 \mathrm{k} \Omega$ or more as "OFF." Transistor contact input: Input voltage of 2 V or less is determined as " ON " and leakage current must not exceed $100 \mu \mathrm{~A}$ when "OFF."
- Minimum status detection hold time: Control period +50 ms
- Use: PTNO. switch, operation mode switch, and event input


## Transistor Contact Output Specifications

- Number of outputs: See the table of Model and Suffix Codes.
- Output type: Open collector (SINK current)
- Output contact rating: Max. 24 V DC, 50 mA
- Output time resolution: Min. 100 ms


## Heater Break Alarm Specifications

- Number of inputs: 2
- Number of outputs: 2 (transistor contact output)
- Use: Measures the heater current using an external current transformer (CT) and generates a heater break alarm when the measured value is less than the break detection value.
- Current transformer input resistance: About $9.4 \Omega$
- Current transformer input range: 0.0 to 0.1 Arms (0.12 Arms or more cannot be applied.)
- Heater current setting range: OFF, 0.1 to 300.0 Arms Heater current measured value display range: 0.0 to 360.0 Arms

Note: The CT ratio can be set. CT ratio setting range: 1 to 3300

- Recommended CT: CT from U.R.D., Ltd. CTL-6-S-H: CT ratio 800, measurable current range: 0.1 to 80.0 Arms CTL-12L-30: CT ratio 3000, measurable current range: 0.1 to 180.0 Arms
- Heater current measurement period: 200 ms
- Heater current measurement accuracy: $\pm 5 \%$ of current transformer input range span $\pm 1$ digit (CT error is not included.)
- Heater current detection resolution: Within 1/250 of current transformer input range span
- Break detection On-time: Min. 0.2 second (for time proportional output)


## Safety and EMC Standards

- Safety:

Compliant with IEC/EN61010-1 (CE), IEC/EN61010-2-030 (CE), approved by CAN/CSA C22.2 No. 61010-1 (CSA), approved by UL61010-1.
Installation category: II
Pollution degree: 2
Measurement category: I (CAT I) (UL, CSA)
O (Other) (CE)
Rated measurement input voltage: Max. 10 V DC Rated transient overvoltage: 1500 V (*)
*: This is a reference safety standard value for measurement category I of IEC/EN/CSA/UL610101. This value is not necessarily a guarantee of instrument performance.

- EMC standards:

Compliant with
CE marking
EN 61326-1 Class A, Table 2 (For use in industrial locations),
EN 61326-2-3
*: The instrument continues to operate at a measurement accuracy of within $\pm 20 \%$ of the range during testing.
EN 55011 Class A, Group 1
EN 61000-3-2 Class A
EN 61000-3-3
EMC Regulatory Arrangement in Australia and New Zealand EN 55011 Class A, Group 1

- KC marking: Electromagnetic wave interference prevention standard, electromagnetic wave protection standard compliance


## Construction, Installation, and Wiring

- Dust-proof and drip-proof: IP66 (for front panel) (Not available for side-by-side close mounting.)
- Material: Polycarbonate (Flame retardancy: UL94V-0)
- Case color: White (Light gray) or Black (Light Charcoal gray)
- Weight: 0.5 kg or less
- External dimensions (mm): $96(\mathrm{~W}) \times 96(\mathrm{H}) \times 65$ (depth from the panel face) (Depth except the projection on the rear panel)
- Installation: Direct panel mounting; mounting bracket, one each for upper and lower mounting
- Panel cutout dimensions (mm): $92^{+0.810}(\mathrm{~W}) \times 92^{+0.8 / 0}(\mathrm{H})$
- Mounting attitude: Up to 30 degrees above the horizontal. No downward titling allowed.
- Wiring: M3 screw terminal with square washer (for signal wiring and power wiring)


## Power Supply Specifications and Isolation

- Power supply:

Rated voltage: $100-240$ V AC (+10\%/-15\%), $50 / 60 \mathrm{~Hz}$
24 V AC/DC (+10\%/-15\%) (for /DC option)

- Power consumption: 18 VA (DC:9 VA, AC: 14 VA if /DC option is specified)
- Data backup: Nonvolatile memory
- Power holdup time: 20 ms (for 100 V AC drive)
- Withstanding voltage

Between primary terminals and secondary terminals: 2300 V AC for 1 minute (UL, CSA)
Between primary terminals and secondary terminals: 3000 V AC for 1 minute (CE)
Between primary terminals: 1500 V AC for 1 minute Between secondary terminals: 500 V AC for 1 minute (Primary terminals: Power ${ }^{*}$ and relay output terminals; Secondary terminals: Analog I/O signal terminals, contact input terminals, communication terminals and functional grounding terminals.)
*: Power terminals for 24V AC/DC models are the secondary terminals.

- Insulation resistance: Between power supply terminals and a grounding terminal $20 \mathrm{M} \Omega$ or more at 500 V DC
- Isolation specifications

| PV (universal ) input terminals |  |  |
| :--- | :--- | :--- |
| Remote (universal) input terminals with direct input / Remote input terminals |  |  |
| Aux. analog (AIN2) input terminals |  |  |
| Aux. analog (AIN4) input terminals |  |  |
| Control, retransmission (analog) output terminals <br> (not isolated between the analog output terminals) <br> Valve position (feedback) input terminals |  |  |
| Control relay (contact point c) output terminals |  |  |
| PV event-1 relay (contact point a) output terminals |  |  |
| PV event-2 relay (contact point a) output terminals | Power |  |
| cupply |  |  |
| PV event-3 relay (contact point a) output terminals |  |  |
| Position proportional relay output terminals |  |  |
| Contact input terminals (all) <br> RS-485 communication terminals (2 ports) |  |  |
| Contact output (transistor) terminals |  |  |
| Ethernet communication terminal |  |  |
| PROFIBUS-DP/DeviceNet/CC-Link communication terminals |  |  |
| Current transformer input terminals |  |  |

The circuits divided by lines are insulated mutually.

## Environmental Conditions

## Normal Operating Conditions:

- Ambient temperature: -10 to $50^{\circ} \mathrm{C}\left(-10\right.$ to $40^{\circ} \mathrm{C}$ for side-by-side close mounting)
For the CC-Link option, 0 to $50^{\circ} \mathrm{C}\left(0\right.$ to $40^{\circ} \mathrm{C}$ for side-by-side close mounting)
- Ambient humidity: 20 to $90 \% \mathrm{RH}$ (no condensation allowed)
- Magnetic field: $400 \mathrm{~A} / \mathrm{m}$ or less
- Continuous vibration at 5 to 9 Hz : Half amplitude of 1.5 mm or less, 1 oct/min for 90 minutes each in the three axis directions
Continuous vibration at 9 to $150 \mathrm{~Hz}: 4.9 \mathrm{~m} / \mathrm{s}^{2}$ or less, 1oct/ min for 90 minutes each in the three axis directions
- Short-period vibration: $14.7 \mathrm{~m} / \mathrm{s}^{2}, 15$ seconds or less
- Shock: $98 \mathrm{~m} / \mathrm{s}^{2}$ or less, 11 ms
- Altitude: 2000 m or less above sea level
- Warm-up time: 30 minutes or more after the power is turned on
- Startup time: Within 10 seconds
*: The LCD (a liquid crystal display) is used for a display portion of this product. The LCD has a
characteristic that the display action becomes late at the low temperature. However, the control function is not affected.


## Transportation and Storage Conditions:

- Temperature: -25 to $70^{\circ} \mathrm{C}$
- Temperature change rate: $20^{\circ} \mathrm{C} / \mathrm{h}$ or less
- Humidity: 5 to $95 \%$ RH (no condensation allowed)


## Effects of Operating Conditions

- Effect of ambient temperature:

Voltage or TC input: $\pm 1 \mu \mathrm{~V} /{ }^{\circ} \mathrm{C}$ or $\pm 0.01 \%$ of $\mathrm{F} . \mathrm{S} .{ }^{\circ} \mathrm{C}$,
whichever is larger
Current input: $\pm 0.01 \%$ of F.S. ${ }^{\circ} \mathrm{C}$
RTD input: $\pm 0.05^{\circ} \mathrm{C} /{ }^{\circ} \mathrm{C}$ (ambient temperature) or less
Analog output: $\pm 0.02 \%$ of $\mathrm{F} . \mathrm{S} .{ }^{\circ} \mathrm{C}$ or less

- Effect of power supply voltage fluctuation

Analog input: $\pm 0.05 \%$ of F.S. or less
Analog output: $\pm 0.05 \%$ of F.S. or less
(Each within rated voltage range)

## Block Diagram



## Terminal Arrangement




■ External Dimensions and Panel Cutout Dimensions


Model and Suffix Code

*1: When " 3 " is specified for the Type 2 code, only " 0 " can be specified for the Type 3 code.
*2: English, German, French, and Spanish can be displayed as the guide display.
*3: When any of " 1 " or " 4 " is specified for the Type 2 code, the /DR option can be specified.
*4: When " 0 " is specified for the Type 1 code, the /HA option can be specified.
*5: When the /CT option is specified, the UP55A does not conform to the safety standards (UL and CSA) and CE marking.

■ Items to be specified when ordering Model and suffix codes, whether User's Manual and QIC required.

## ■ Standard accessories

Terminal cover, Brackets (mounting hardware), Unit label, and Operation Guide for Single-loop Control.

## - Special Order Items

| Name | Model |
| :--- | :--- |
| Terminal cover | UTAP001 |
| User's Manual (CD) | UTAP003 |


| Model code | Suffix code | Description |
| :--- | :--- | :--- |
| LL50A | -00 | Parameter Setting Software |
| X010 | See the General <br> Specifications (*) | Resistance Module |

*: Necessary to input current signal to voltage input terminal.

## User's Manual

Product user's manuals can be downloaded or viewed at the following URL. To view the user's manual, you need to use Adobe Reader 7 or later by Adobe Systems.
URL: http://www.yokogawa.com/ns/ut/im/

