

VADDIO[™] ROBOSHOT[™] HDMI SERIES CAMERAS

RoboSHOT 12 HDMI and RoboSHOT 30 HDMI, HD Robotic PTZ Cameras

999-9940-000: RoboSHOT 12 HDMI, 12X HD Robotic PTZ Camera (North America) 999-9940-001: RoboSHOT 12 HDMI, 12X HD Robotic PTZ Camera (International)

999-9943-000: RoboSHOT 30 HDMI, 30X HD Robotic PTZ Camera, Black Version (North America) 999-9943-001: RoboSHOT 30 HDMI, 30X HD Robotic PTZ Camera, Black Version (International)

999-9943-000W: RoboSHOT 30 HDMI, 30X HD Robotic PTZ Camera, White Version (North America) 999-9943-001W: RoboSHOT 30 HDMI, 30X HD Robotic PTZ Camera, White Version (International)



RoboSHOT 12 High-definition Robotic PTZ Conferencing Camera Featuring a 12X, 73° Wide Angle Optical Zoom Lens and Tri-Synchronous Motion

RoboSHOT 30

High-definition Robotic PTZ Camera for Medium to Large Venues Featuring 30X Optical Zoom Lens and Tri-Synchronous Motion. Available in Black or White finishes. Inside Front Cover - Mostly Blank



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OVERVIEW

The RoboSHOT HDMI PTZ cameras are professional quality cameras with very high quality imaging, fine detail and exceptional color reproduction. These cameras offer integrators, dealers and end users a substantial price/performance improvement over and above the value of other HDMI cameras available today.

The RoboSHOT 12 HDMI is perfect for small to medium sized conference rooms, training rooms or classrooms and provides incomparable support for applications including, UC conferencing, videoconferencing, distance learning, lecture capture, telepresence and more!

The optical zoom power of the RoboSHOT 30 HDMI is ideal for medium to large venues and provides exceptional support for applications including, House of Worship services, large auditorium A/V systems, live event theatres, IMAG for performances, large lecture theatres with lecture capture and more!

The key features of the RoboSHOT cameras are Tri-Synchronous Motion, the silent, smooth direct drive pan/tilt motors, advanced Exmor® image sensor, multi-element glass lens and ISP (image signal processor) combination.

The Tri-Synchronous Motion algorithm in the RoboSHOT cameras is capable of moving all three (pan, tilt and zoom) axes simultaneously. The algorithm calculates the position and velocity of the smooth, direct-drive motor movements between the presets so pan, tilt and zoom arrive at the preset subject simultaneously, which finally allows for smooth and manageable on-air camera movements. Yep, there's no more pan/tilt, then zoom like other PTZ cameras available today.

The lens, image sensor and ISP are the real magic behind these camera's awesome video performance characteristics. The RoboSHOT 12 HDMI lens features a 12X optical zoom with a 73° wide horizontal field of view and the powerful RoboSHOT 30 HDMI features a 30X optical zoom with an impressive 2.3° tele end and 65° wide field of view. The latest generation Exmor® 1/2.8", 2.38 Megapixel, Full HD (native 1080p/60) high-speed, low noise CMOS image sensor combined with the new ISP produces vivid, realistic color with extremely fast, razor sharp automatic focus and iris routines.

The RoboSHOT HDMI cameras have an Ethernet port and a built-in web server, which allows the user to control the camera functions on a web page with any browser over the IP network. Telnet, IR Remote and RS-232 control for the camera are available to satisfy almost any, if not all, system control requirements.

The RoboSHOT cameras were designed for the times and represent a new era in specifying and integrating professional quality cameras into A/V and conferencing system configurations. In short, it has never been easier to integrate cameras into any project than with the RoboSHOT HDMI cameras

Intended Use:

Before operating the device, please read the entire manual thoroughly. The system was designed, built and tested for use indoors with the power supply provided. The use of a power supply other than the one provided or outdoor operation hasn't been tested and may damage the device and/or create an unsafe operating condition.

Save These Instructions:

The information contained in this manual will help you install and operate your product. If these instructions are misplaced, Vaddio keeps copies of Specifications, Installation and User Guides and most pertinent product drawings (DWG and PDF) for the Vaddio product line on the Vaddio website. These documents can be downloaded from <u>www.vaddio.com</u> free of charge.

Important Safeguards:

Read and understand all instructions before using. Do not operate any device if it has been dropped or damaged. In this case, a Vaddio technician must examine the product before operating. To reduce the risk of electric shock, do not immerse in water or other liquids and avoid extremely humid conditions.

Use only the power supply provided with the system. Use of any unauthorized or extended DC power supplies will void any and all warranties.



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Images:



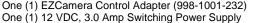




UNPACKING THE CAMERA SYSTEMS

Carefully remove the product and all of the included parts from the packaging. Identify the following parts:

RoboSHOT 12 HDMI Camera Part Number 999-9940-000 (North America) One (1) RoboSHOT 12 HDMI Camera (998-9940-000) One (1) Thin Profile Wall Mount with Mounting Hardware One (1) IR Remote Commander (998-2100-000) One (1) EZCamera Control Adapter (998-1001-232) One (1) 12 VDC, 3.0 Amp Switching Power Supply One (1) AC Cord Set for North America One (1) Quick Setup Guide Full Manuals are downloaded from support.vaddio.com **RoboSHOT 12 HDMI Camera** Part Number 999-9940-001 (International) One (1) RoboSHOT 12 HDMI Camera (998-9940-000) One (1) Thin Profile Wall Mount with Mounting Hardware One (1) IR Remote Commander One (1) EZCamera Control Adapter (998-1001-232) One (1) 12 VDC, 3.0 Amp Switching Power Supply One (1) Euro Power Cord One (1) UK Power Cord One (1) Quick Setup Guide Full Manuals are downloaded from support.vaddio.com **RoboSHOT 30 HDMI Camera (Black)** Part Number 999-9943-000 (North America) One (1) RoboSHOT 30 HDMI Camera (998-9943-000) One (1) Thin Profile Wall Mount with Mounting Hardware One (1) IR Remote Commander (998-2100-000) One (1) EZCamera Control Adapter (998-1001-232)



- One (1) AC Cord Set for North America
- One (1) Quick Setup Guide

Full Manuals are downloaded from support.vaddio.com

RoboSHOT 30 HDMI Camera (Black)

- Part Number 999-9943-001 (International)
- One (1) RoboSHOT 30 HDMI Camera (998-9943-000) One (1) Thin Profile Wall Mount with Mounting Hardware
- One (1) IR Remote Commander One (1) EZCamera Control Adapter (998-1001-232)
- One (1) 12 VDC, 3.0 Amp Switching Power Supply
- One (1) Euro Power Cord
- One (1) UK Power Cord
- One (1) Quick Setup Guide

Full Manuals are downloaded from support.vaddio.com

RoboSHOT 30 HDMI Camera (White)

- Part Number 999-9943-000W (North America) One (1) RoboSHOT 30 HDMI Camera (998-9943-000W)
- One (1) Thin Profile Wall Mount (White not shown) with Hardware
- One (1) IR Remote Commander (998-2100-000)
- One (1) EZCamera Control Adapter (998-1001-232)
- One (1) 12 VDC, 3.0 Amp Switching Power Supply
- One (1) AC Cord Set for North America
- One (1) Quick Setup Guide

Full Manuals are downloaded from support.vaddio.com

RoboSHOT 12 HDMI Camera (White) Part Number 999-9943-001W (International)

- One (1) RoboSHOT 30 HDMI Camera (998-9943-000W) One (1) Thin Profile Wall Mount (White - not shown) with Hardware One (1) IR Remote Commander One (1) EZCamera Control Adapter (998-1001-232) One (1) 12 VDC, 3.0 Amp Switching Power Supply One (1) Euro Power Cord
- One (1) UK Power Cord
- One (1) Quick Setup Guide

Full Manuals are downloaded from support.vaddio.com

























Image: RoboSHOT 12 HD PTZ Camera

Camera Front View with Feature Call-outs



1) Camera and Zoom Lens: This RoboSHOT model features a 12X optical zoom lens (12X in Super-Wide mode and 10X in normal mode) that is built around an Exmor 1/2.8-Type, high-speed, low noise image sensor with a total of 2.38 Megapixels for exceptionally precise HD video image acquisition in a small to medium sized conference room.

2) Camera Support Arm: The RoboSHOT cameras use a single control arm for pan and tilt movements. Both ends of the cast control arm are anchored with silent and smooth BLDC (brushless DC) direct drive motors. These motors provide ultra-accurate and fast camera positioning and are capable of the slowest of crawls, which are suitable for on-air use.

3) IR Sensors: IR sensors are built into the front of the RoboSHOT to receive IR signals from the IR Remote Commander supplied with the camera. The IR sensors sit behind the Makrolon IR Window on the front of the base.

4) Multi-Color LED:

The multi-colored LED indicates the use states of the camera:

- Purple LED is for Boot-up and Standby modes.
- Blue LED is for normal operation and is a power on, ready condition.
- The blue LED will blink when the camera receives a valid IR command.
- Solid red LED is to indicate a tally function illuminating when the camera is on-air.
- Blinking red LED indicates a fault condition.
- Yellow LED illuminates during a firmware update.

5) Logo: Really Cool Logo Badge (RCLB) is located on the IR Window.

6) Camera Base: Cast zinc alloy base for strength and stability, powder coated for toughness with fine texture.



Image: RoboSHOT 30 HD PTZ Camera

The differences between the 12X model and the 30X models center around the power of the optical zoom lens and overall color of the camera models. The 30X is available in both black and white.



1) Camera and Zoom Lens: This RoboSHOT model has a powerful 30X optical zoom lens that is built around an Exmor 1/2.8-Typ, high-speed, low noise image sensor with a total of 2.38 megapixels for vibrant, detailed HD video image acquisition in a large to medium sized room.

2) Camera Support Arm: The RoboSHOT cameras use a single control arm for pan and tilt movements. Both ends of the cast control arm are anchored with silent and smooth BLDC (brushless DC) direct drive motors. These motors provide ultra-accurate and fast camera positioning and are capable of the slowest of crawls, which are suitable for on-air use.

3) IR Sensors: IR sensors are built into the front of the RoboSHOT to receive IR signals from the IR Remote Commander supplied with the camera. The IR sensors sit behind the Makrolon IR Window on the front of the base.

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- Blinking red LED indicates a fault condition.
- Yellow LED illuminates during a firmware update.

5) Logo: Really Cool Logo Badge (RCLB) is located on the IR Window.

6) Camera Base: Cast zinc alloy base for strength and stability, powder coated for toughness with fine texture.



Image: RoboSHOT 12 and 30 Rear Panel Connections

Rear panel connections are identical for both models (RoboSHOT 12 shown).



1) CAMERA SETTINGS: DIP switch settings for IR remote frequency, baud rate and image flip can be configured on these switches. See the Switch Settings page for additional information.

2) HD VIDEO SELECT: A rotary switch allows the user to choose the HD video output resolution. See the Switch Settings page for additional information.

3) NETWORK CONTROL Port: The Ethernet 10/100 port allows the camera to be controlled from embedded web server with a web browser or through Telnet session.

4) RS-232 Port (Color Coded Blue): The RS-232 port accepts modified VISCA protocol for camera control over a Cat-5e cable. This port also acts as an IR Forwarding port with the Quick-Connect SR or Quick-Connect DVI/HDMI interfaces, which allows the user to transmit 3rd party IR signals through camera to the head-end.

5) HDMI Connector: HDMI video output jack (the output Color Space is defaulted to YCbCr for HDMI, but can be switched to sRGB for DVI-D only video devices).

6) Power Jack: The 12 VDC, 3.0 Amp power connector is on an EIAJ-04 jack with a positive center.



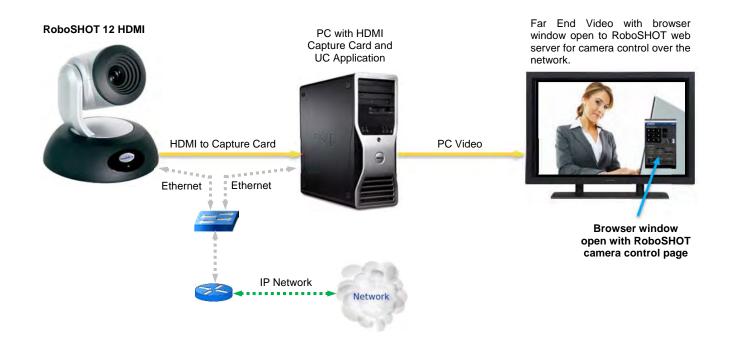
SYSTEM CONFIGURATION EXAMPLES

Diagram: Simple Connectivity Example of the RoboSHOT HDMI Cameras

RoboSHOT HDMI camera connected ProductionVIEW[™] Precision Camera Controller, Presentation Switcher and HD Monitor.



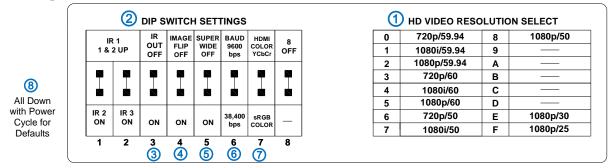
Diagram: Example of the RoboSHOT HDMI Camera in UC Conferencing Application RoboSHOT 12 HDMI camera connected to Room PC with capture card and UC Application.





ROBOSHOT HDMI SWITCH SETTINGS

The RoboSHOT cameras control the resolution of the video signal. There is, as explained on the page 10, a rotary switch to set the HD video resolution and a set of eight (8) DIP switches that determine certain camera functions. See drawing and Description on how to setup the camera.



Drawing: DIP Switch and Resolution Label on the Bottom of the RoboSHOT

Setting the RoboSHOT Switch Gear:

- ① Set the desired available HD output resolution for the camera with the Rotary Switch.
- 2 Set the IR control frequency of the camera if it is to respond to the IR remote control.
- ③ If using the IR forwarding features with a 3rd party codec IR remote, set the IR OUT switch to ON (SW3).
- 4 If inverting the camera, turn the IMAGE FLIP ON (SW4).
- (5) For the RoboSHOT 12X model only, set the Super-wide mode to ON for a 12X, 73° horizontal super-wide angle of view. Normal mode will produce 67.2° horizontal field of view (HFOV). The RoboSHOT 30 does not have a Super Wide mode.
- 6 Set the Baud Rate DIP switch (SW6) to 9600bps for most applications. Default is 9600 bps systems.
- ⑦ Set the color space for HDMI (YCbCr) or for DVI-D (sRGB).
- (B) Setting all DIP switches DOWN with a power cycle loads the default camera settings. Return DIPs to desired operating position after power cycle.

Note: Switch 8 is reserved for future use.

DIP Switch Settings Further Explained (DSSFE):

- IR 1, 2 and 3 (SW 1 &2): A single IR remote has the capability of operating up to three different PTZ cameras in a room. Use these selector DIP switches and the selector buttons at the top of the IR remote to select the frequency.
- IR OUT on/off (SW3): The IR output is sent out on the RS-232 RJ-45 jack on the back of the camera. Turning on the IR output will allow IR signals to be transmitted over the Cat-5 cable to the head end.
- Image Flip (SW4): To invert the camera, turn the IMAGE FLIP ON (switch down).
- **Super-Wide Mode:** Super-wide works only with the RoboSHOT 12 model and allows the camera to switch from 67.3° wide end HFOV to a Super Wide 73° wide end HFOV.
- **Baud Rate (SW6):** The options for baud rate are either 9600 or 38,400 bps. The 9600 bps works best with Cat-5e over distance. Use 38,400 bps for short control lines only.
- **DIP Switches (SW7 & 8)**: Not used for operation, please leave these DIP switches up or in the OFF position.



INSTALLATION BASICS:

All RoboSHOT cameras include a Thin Profile Wall Mount for…wall mounting the camera. There are options for IN-Wall[™] mounts and IN-Ceiling[™] Half-Recessed as well.

Pre-Installation

- Choose a camera mounting location while paying close attention to camera viewing angles, lighting conditions, possible line of site obstructions, and checking for in-wall obstructions where the camera is to be mounted. Always pick a mounting location that will *optimize* the performance of the camera.
- Please locate the camera to enable easy positioning of the camera body with the ability to point down and away from the ceiling and a pile of fluorescent lighting cells. *Cameras generally don't like to be swamped with fluorescent light and nobody sits on the ceiling anyway.*
- The included RoboSHOT wall mount can be mounted directly to a 2-gang wall box or can be mounted to the wall using the provided dry wall anchors.



RS-232 Cabling Notes:

For RS-232 cabling, use a standard Cat-5 (if you can still find Cat-5) or Cat-5e/6 cable with real RJ-45 connectors crimped on by real crimpers (568B termination) from the camera's RS-232 Port to the controllers RS-232 port. If the camera is connected to a third-party control system (such as AMX or Crestron), a DE-9F (also called a DB-9F in some circles) to RJ-45F control adapter is supplied.

Determine Camera Mount Location and Mount

After determining the optimum location of the camera, route the required cables (HDMI, Power and RS-232) from the camera to the head-end. There are two cable management pass-throughs on the provided mount; one in the back to pass-through into the wall and one in the platform to allow the cabling escape straight down behind a video monitor.

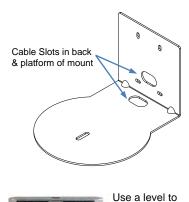
If the wall mount is to be mounted on a 2-gang wall box, use the screws supplied with the wall box cover plate to attach the Thin Profile Wall Mount Bracket. If mounting to drywall with wall anchors, use the four (4) quality wall anchors and screws provided.

The mounting holes are slotted and are 90° opposing to provide easy leveling. Level the mount and place the camera on the mount. Connect the marked and tested Cat-5e cables to the appropriate RJ-45 jacks. Check the level again to avoid any of those weird Batman camera angles. Use the provided $\frac{1}{4}$ °-20 x .375 mounting screw to attach the Camera to the mount.

Power Up

Connect the supplied 12 VDC, 3.0 Amp power supply to a power outlet

The camera will wake up and initialize (this will take a few seconds since RoboSHOTs use a Linux OS). When an image is available, the camera is ready to accept control information from the IR remote, RS-232, Telnet or embedded web server. We recommend that since there are 4 ways to control the RoboSHOT, pick one and run with it.







CONTROLLING THE CAMERA

IR Remote Commander

The following functions are accessible with the Vaddio IR remote:

- Camera Power On/Off (Toggle on/off same button)
- Back Light Compensation (Toggle on/off same button)
- Data Screen: Toggle on/off the OSD for the RoboSHOT's IP/MAC Address
- Camera Select (the remote can operate 3 cameras (with 3-IR Freq.)
- Pan/Tilt and Home controls with Reverse and Std. Pan direction
- Pan/Tilt Reset
- Auto Focus (Toggle on/off same button)
- Zoom In/Out controls Wide & Telephoto
 - Fast speed controls (W & T)
 - Slow speed controls (W & T)
- Manual Focus On/Off control (Toggle on/off same button)
 - Near (-) adjustment
 - Far (+) adjustment
- Six (6) pan/tilt/zoom positioning presets (1 through 6)
- Preset Set (store)
- Preset Reset (clear)
- Red LED that indicates IR Transmission and battery level

The IR Remote operational characteristics are as follows:

- Preset Activation: IR Remote is limited to executing Presets 1 through 6
- **Tri-Sync Speed on Preset**: If a global Tri-Sync speed is stored in the preset by the user/admin, then that speed is used. If no Tri-Sync speed is assigned, then a default (medium) speed will be used.
- **Preset Store:** IR Remote is limited to positional (PTZ) type presets. To set a preset, position the camera, hold down the Preset Button and touch the one of the preset numbered buttons 1 through 6.

Telnet Control Examples

The following Telnet* commands are available through the Ethernet Port.

- Camera Home
- Camera Pan (left, right and speed real-time operation)
- Camera Tilt (up, down and speed real-time operation)
- Camera Zoom (zoom in/out/stop and speed real-time operation)
- Camera Store Preset (Gets or Sets 16 presets with global relative PTZ [Tri-Sync] speed control to destination)
- Camera CCU(Gets or sets current image control values, sets in 1 of 3 CCU presets) (AWB or manual w/Red and Blue gain, BLC on/off, Auto Iris or manual with Iris value and Gain, Detail and Chroma)
- Camera Standby (Gets or sets standby power mode camera uses less power in this mode)
- Help (displays CLISH syntax)
- History (command history)
- Network Ping (send ICMP ECHO_REQUEST to network hosts)
- Network Settings (Gets MAC address, IP address, Subnet Mask, Gateway and NTP server address)
- System Factory Reset
- System Reboot
- Version (system version information)
- Exit (ends Telnet session)

*Please see the *full and actual* Telnet command list at the end of this manual for the actual command set.



Vaddio

IR Remote Commander





THE SCREEN SHOT TOUR

The RoboSHOT camera platform uses a Linux OS and has a built-in web server. The internal web pages will allow control of the attached camera via an Ethernet network connection. These web pages will allow the user or administrator to control the camera, set PTZ presets, set security passwords, change the IP address, view diagnostics, access the firmware upgrade page and more!

Compatible Web Browsers

You may ask, "What are the approved web browsers that work with the RoboSHOT's embedded web server?" The answer is Chrome[®] (latest version), Firefox[®] (latest version), Internet Explorer[®] (versions 8 through 11) and Safari[®] (versions 6 and 7) have been tested thoroughly with RoboSHOT and are compatible.

DHCP IP Set-up (Dynamic Host Configuration Protocol)

DHCP Set-up (skip this section if Static IP). If the LAN has a DHCP (dynamic host configuration protocol) server, then the IP address, gateway and routing information will automatically be assigned. The software is defaulted to DHCP and will attempt to dynamically obtain an IP address using DHCP, but it will fall back to the default address of (169.254.1.1) if no DHCP server can be found.

Static IP Set-up:

The static IP can be assigned either through the network or directly to a computer using a cross-over cable. Depending on the age of the computer, you may not need a cross-over cable. Either way the steps are the same for network or direct connection to a computer. The default address of the camera is 169.254.1.1 and the Subnet mask is 255.255.0.0. Different computer OS types all have their own way of doing things (without question), but they are essentially doing the same stuff, changing the IP address so the web pages of the RoboSHOT are accessible.

Screen Shot: Login

The RoboSHOT webserver is intended as a user's camera control page at one level, and an administrator's management tool at another level, which requires password authentication for access.

The Login Page will appear if there is a user name assigned by the administrator. Assigning a user name can limit access to the admin menus by a general user.

By default, the User name is: user, and the password for the User account is: password. The Administrator can set the name and password for the User account.

By default, the Admin user name is: admin, and the password for the admin account is: password.

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1.1	9 * =
Vaddio, Conference Room #1 Rm Tel x547, Help Tel 1-800-888-HELP	
	1.1 Vaddio, Conference Room #1

- If a user or an admin logs in through this screen, then the next page shown will be the camera control page.
- The user will only have access to the camera control page.
- The Admin will have complete access to all web pages.



Screen Shot: Camera Control Page

- 0 X > RoboSHOT 12 HDMI ×) C 169.254.1.1/# * * = NEW 0 vaddio Vaddio, Conference Room #1 Logout Rm Tel x547, Help Tel 1-800-888-HELP RoboSHOT 12 HDMI 2 1 ROBOSHOT 12 HDMI CONTROLS STANDBY 5 Camera Controls ÷ 4 ZOOM Auto Focu (¹) Logout 3 ÷ Encus FOCUS 4 Pan Speed . 12 0 10 Zoom Speed 0 4 **6**) PRESETS Stor Preset 3 Preset 9 Preset 10 CCU SCENES 8 Auto andescent Hi Fluorescent Hi Outdoo Incandescent Lo Fluorescent Lo

This web page provides access to the camera controls for the User and the Admin.

- 1) Pan, Tilt and Home Controls: These intuitive controls use the up/down and diagonal arrows for camera pan and tilt. The center button will move the camera to the home position.
- 2) Zoom Control: The camera's zoom lens can be controlled with the "+" to zoom-in and the "-"to zoom out.
- 3) Focus Control: Pop up allows the choice of Auto-focus or manual focus with near (+) and far (-) manual focus buttons.
- 4) Pan/Tilt and Zoom Speed Controls: The speed for both the Pan/Tilt and Zoom controls can be adjusted with the three (3) sliders in this section. For tighter shots, it is recommended that the slower speed is used. These controls are for real-time camera movements only.
- 5) Standby: The Standby control puts the camera in low power mode and effectively puts the RoboSHOT to sleep. The camera will pan 90° from center and 30° downward (to not collect dust on the lens). When the camera is inverted (ceiling mounted) the camera will pan 90° from center and 30° downward. If the system is on, then the button will be blue and controls will be visible. If the button is red, no controls are accessible and the screen states: Device is in standby. Click to power-up, then you'll know what to do.
- 6) Camera Presets: Twelve (12) camera position presets can be recalled simply by clicking a preset number.
- 7) Store Preset Button: Clicking the Store button opens up a Store Preset pop-up dialog box. To set presets, set up the camera shot, click on choice of preset number (1 through 12). The preset is stored and the dialog box closes. The Store Preset dialog bow will prompt the operator to enter the Tri-Sync speed to the stored camera preset and if the current color settings are to be stored with the preset too (see the next page).
- 8) CCU Scenes: The user has access to the CCU scenes set and stored on the Admin pages. There are three (3) user definable presets and six (6) presets preconfigured by the technical folks at Vaddio (really Scott set them all) that are meant to be used in certain lighting scenarios. These lighting presets included: Automatic, Incandescent Hi, Incandescent Lo, Fluorescent Hi, Fluorescent Lo and Outdoor.



Screen Shot: Storing Presets



- 1) Store Preset: When the Store Preset button is clicked (point 6 on previous page), the Store Preset dialog pops into existence. To save the current camera shot, click one of the Preset buttons (1 through 12), the button will be highlighted and the dialog box will present the Tri-Sync controls and if the CCU setting are to be kept with the preset.
- 2) Save with Tri-Sync and Setting the Tri-Sync Speed: The Tri-Synchronous Motion algorithm in the RoboSHOT cameras is capable of moving all three (pan, tilt and zoom) axes simultaneously. The algorithm calculates the PTZ position so pan, tilt and zoom start at the same time and arrive at the preset subject simultaneously. Tri-Sync speed is speed at which all other presets will use to get to the preset being stored. All axes will launch at the same time and if the next preset position is not too close or too far, axes should simultaneously arrive at the preset location. Storing the preset with Tri-Sync is fairly straight forward. Here's a quick method to set Tri-Sync:
 - a) Position the first preset, click on Store Preset and click on Preset 1. Check the Save with Tri-Sync box. Move the tri-Sync speed slider to about the approximate position above (about 1/3 up the speed scale). This is the speed that all the other presets will use to get to this Preset 1. The speed is stored with the destination preset. Click on Save to store the camera location and Tri-Sync speed.
 - b) Set another camera position, and try a different pan, tilt and zoom position and click on Store Preset. Click on Preset 2 through 12, click on the Save with Tri-Sync box and set the slider to about ½ way this time and click on Save. These two presets are stored with different preset destination speeds.
 - c) Click between these two recently stored presets and note the different speeds applied to the 2 presets.



Tri-Sync Notes: If a preset is very close to the previous preset, like within10° with no change in zoom, it certainly doesn't need to be Tri-Sync'd. If a preset is super-fast and off-air, Tri-Sync won't be of much use either. Tri-Sync is a cool tool to set for on-air shots, but the process of setting the speeds will need some practice.

- 3) Store with Current Color Settings: To save the currently assigned CCU scenes settings, check this box.
- 4) Click Save or Cancel to exit this pop-up dialog box.



Screen Shot: Admin login from the Camera Control Page

On the security page, which will be reviewed at a bit later in the tour, allows the Admin to set the system to allow automatic guest access to the main camera control page. If guest access is turned on by the Admin, then system will open to the camera control page and an additional Admin Login is provided.

The default Admin password is: password.

vaddio	Vaddio, Confe	rence Room	#1			
RoboSHOT	Rm Tel x547, H	lelp Tel 1-800	-888-HELP			Log
Camera Controls	CONTROLS				STANDBY	
Admin	ĸ	t	*	+	(b)	
20 Lange				ZOOM		
U Logout	+		+	-		
				Pan Speed	0 24	
	K	+	34	Tilt Speed	20	
				Zoom Speed	0 7	
	PRESETS				Store	
	Pro Pro Pro	Password		c	ancel Login	
	CCU SCEN	ES				
	4	uto	Incandes	cent Hi	Fluorescent Hi	

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Screen Shot: Admin Menu - Camera Settings

Once the Admin logs in, then all the admin menu buttons appear on the left side of the screen. The first menu after Camera Controls is Camera Settings.



- 1) Load Preset at Startup: Check this box to move the camera to a predefined preset location when the camera powers up. Use the pull down menu to select the Preset 1 through 12 to be loaded when this box is checked.
- 2) Load CCU Scene at Startup: Check this box to load a CCU Scene into the camera when the camera powers up. The pull down menu will allow the selection of one of the 6-factory scenes, or one of the 3 custom scenes.
- 3) CCU Scenes: Click on any of these 9 buttons to load one of the CCU scenes into the camera. These Scenes can be fine-tuned if changes are needed, and stored into any of the three User defined scenes.
- 4) Color Settings: When painting or shading camera scenes for specific lighting situations or environments, these parameters can be adjusted for matching cameras in the same area. The parameters within the Color Settings section are defined below (top to bottom):
 - Auto Iris Check Box: When checked, the camera will operate in Auto Iris mode, when unchecked, the camera will be in Manual Iris mode and allow adjustment of Iris and Iris Gain levels.
 - Iris: Move adjustment slider as required to adjust the iris opening. A numeric value will be displayed in the box to the right of the slider.



- Gain: Move adjustment slider as required for amount of iris gain desired. Numeric value will be displayed in the box to the right of the slider.
- Auto White Balance check box: When checked, camera will operate in Auto White Balance mode, when unchecked camera will be in Manual White Balance Mode and allow for adjustment of Red and Blue Gain.
 - **Red Gain:** Move the adjustment slider as required for amount of Red Gain desired. A numeric value will be displayed in the box to the right of the slider.
 - Blue Gain: Move the adjustment slider as required for amount of Blue Gain desired. Numeric value will be displayed in the box to the right of the slider.
- Back Light Compensation: When checked, Back Light Compensation will be applied to the camera if camera is in Auto White Balance mode.
- **Detail:** Move the adjustment slider as required for amount of detail (Aperture) desired. A numeric value will be displayed in the box to the right of the slider. **Note:** If the detail is too high, the video can look grainy and appear noisy too.
- **Chroma:** Move the adjustment slider as required for the amount of Chroma (Color Vibrancy) desired. A numeric value will be displayed in the box to the right of the slider.
- 5) Store CCU Scene button: Once the desired scene adjustments have been made, this button will activate a pop-up menu that can be used to store this scene into one of the three User Defined Scene locations. These User Defined Scenes can be named as required for clarity. These User Defined CCU Scenes can be adjusted and re-saved at any time.



- 6) Custom CCU Scene Labels: The labels for the (3) User Defined customizable Scenes can be changed as needed. Mouse the cursor into the appropriate window and edit the text. Press Save to store these changes or press Cancel to exit this window.
- 7) Global Preset Non-Tri-Sync Speeds: When Tri-Sync Presets are not being used, then this section governs the pan, tilt and zoom speeds between the camera presets. These will be defaulted to a nominal level, but can be tailored to most any application.

Screen Shot: Admin Menu - Room Labels

The Room Labels menu allows the Admin to label the company name, room name, room phone and help phone on a per RoboSHOT basis. The labels appear on every page at the top/middle of the page. Simply enter the room information and click Save.

	Vaddio, Conference Room Rm Tel x547, Help Tel 1-80	#1	Log
	ROOM LABELS		
Camera Controls	Company Name	Vaddio	
Camera Settings	Room Name	Conference Room #1	
Room Labels	Room Phone Number Help Phone Number	x547 1-800-888-HELP	
Networking			
Security	/		
Diagnostics			
System			
a Help			



Screen Shot: Admin Menu - DHCP Network Configuration

Under the Networking menu, The Network Configuration and Network Interfaces are displayed. This is where the Network administrator assigns either DHCP or a Static address and the associated parameters.

vaddio RoboSHOT	Vaddio, Conference Room #1 Rm Tel x547, Help Tel 1-800-888-HELP	Logo
Camera Controls	NETWORK CONFIGURATION Hostname vaddio-romulus-78-A5-04-A4-06-C5	
Camera Settings	NETWORK INTERFACES	
Room Labels	Ethernet Port (eth0:WAN) IP Address DHCP Static	
Networking		
Security	MAC Address 78:A5:04:A4:06:C5 IP Address 169:254:1.1	
Diagnostics	Subnet Mask 255.255.255.0 Gateway 10.10.11.254	
System	Cancel Save	
e Help	A second se	

Notes: If the LAN has a DHCP (dynamic host configuration protocol) server, then the IP address, gateway and routing information will automatically be assigned. The software is defaulted to DHCP and will attempt to dynamically obtain an IP address using DHCP, but it will fall back to the default address of (169.254.1.1) if no DHCP server can be found.

Screen SHOT: Admin Menu - Static IP Configuration

If Static IP is used, the IP Address, Subnet Mask and Gateway are manually entered. Click on Save to keep the Static IP information.

	Vaddio, Conference Room #1 Rm Tel x547, Help Tel 1-800-888-HELP	Logout
Camera Controls	NETWORK CONFIGURATION Hostname vaddio-romulus-78-A5-04-A4-06-C5	
Camera Settings	NETWORK INTERFACES Ethernet Port (eth0:WAN)	
Room Labels	IP Address DHCP O Static	
Networking		
Security	MAC Address 78:A5:04:A4:06:C5 IP Address 169:254.1.1 Subnet Mask 255:255.0	
Diagnostics	Subnet Mask 255.255.255.0 Gateway 10.10.11.254	_
) System	Cancel Save	
Help		



Screen SHOT: Admin Menu - Security

The Security menu allows the Admin to set the Admin and User account names and passwords. There is only one "user" password and only one "admin" password at any given time. If changes are made, click on Save to store the change (it's best to write down the new names and passwords). A Guest Access check box is provided to let any user access the camera control page without logging in. An Admin Login is provided on the camera control page if the "Allow Guest Access" box is checked.

vaddio RoboSHOT	Vaddio, Conference Room #1 Rm Tel x547, Help Tel 1-800-888-HELP	Logo
Camera Controls	GUEST ACCESS	
Camera Settings	ACCOUNT PASSWORDS	
Room Labels	'admin' Account New Password	
Networking	Confirm New Password	
Security	'user' Account	
Diagnostics	Confirm New Password	
System	Cancel Save	
a Help		
(¹) Logout		

Screen Shot: Admin Menu - Diagnostics

Diagnostics menu button will display a set of self-diagnostics. These diagnostics may help the Vaddio technical support team diagnose a problem with the RoboSHOT camera.

	.1/#diagnostics	Ŧ	1
vaddio RoboSHOT	Vaddio, Conference Room #1 Rm Tel x547, Help Tel 1-800-888-HELP	L	o
Camera Controls	DIAGNOSTICS		
Camera Settings	vaddio-romulus-78-A5-04-A4-06-C5 video-service: : put_setting 0 {"zoom_direct_speed":0} error: 4 (u vaddio-romulus-78-A5-04-A4-06-C5 video-service: : put_setting 0 {"zoom_direct_speed":0} error: 4 (u vaddio-romulus-78-A5-04-A4-06-C5 video-service: : put_setting 0 {"zoom_direct_speed":0} error: 4 (u vaddio-romulus-78-A5-04-A4-06-C5 video-service: : put_setting 0 {"zoom_direct_speed":0} error: 4 (u vaddio-romulus-78-A5-04-A4-06-C5 video-service: : put_setting 0 {"zoom_direct_speed":0} error: 4 (u vaddio-romulus-78-A5-04-A4-06-C5 video-service: : put_setting 0 {"zoom_direct_speed":0} error: 4 (u vaddio-romulus-78-A5-04-A4-06-C5 video-service: : put_setting 0 {"zoom_direct_speed":0} error: 4 (u vaddio-romulus-78-A5-04-A4-06-C5 video-service: : : put_setting 0 {"zoom_direct_speed":0} error: 4 (u vaddio-romulus-78-A5-04-A4-06-C5 video-service: : : : : : : : : : : : : : : : : : :	messa messa	aç
Room Labels	vaddio-romulus-78-A5-04-A4-06-C5 video-service: ; put_setting 0 ("zoom_direct_speed":0) error: 4 {u vaddio-romulus-78-A5-04-A4-06-C5 video-service: ; put_setting 0 ("zoom_direct_speed":0) error: 4 {u vaddio-romulus-78-A5-04-A4-06-C5 video-service: ; put_setting 0 ("zoom_direct_speed":0) error: 4 {u vaddio-romulus-78-A5-04-A4-06-C5 video-service: ; put_setting 0 ("zoom_direct_speed":0) error: 4 {u vaddio-romulus-78-A5-04-A4-06-C5 video-service: ; put_setting 0 ("zoom_direct_speed":0) error: 4 {u vaddio-romulus-78-A5-04-A4-06-C5 video-service: ; put_setting 0 ("zoom_direct_speed":0) error: 4 {u vaddio-romulus-78-A5-04-A4-06-C5 video-service: ; put_setting 0 ("zoom_direct_speed":0) error: 4 {u vaddio-romulus-78-A5-04-A4-06-C5 video-service: ; put_setting 0 ("zoom_direct_speed":0) error: 4 {u vaddio-romulus-78-A5-04-A4-06-C5 video-service: ; put_setting 0 ("zoom_direct_speed":0) error: 4 {u vaddio-romulus-78-A5-04-A4-06-C5 video-service: ; put_setting 0 ("zoom_direct_speed":0) error: 4 {u vaddio-romulus-78-A5-04-A4-06-C5 video-service: ; put_setting 0 ("zoom_direct_speed":0) error: 4 {u vaddio-romulus-78-A5-04-A4-06-C5 video-service: ; put_setting 0 ("zoom_direct_speed":0) error: 4 {u vaddio-romulus-78-A5-04-A4-06-C5 video-service: ; put_setting 0 ("zoom_direct_speed":0) error: 4 {u vaddio-romulus-78-A5-04-A4-06-C5 video-service: ; put_setting 0 ("zoom_direct_speed":0) error: 4 {u vaddio-romulus-78-A5-04-A4-06-C5 video-service: ; put_setting 0 ("zoom_direct_speed":0) error: 4 {u vaddio-romulus-78-A5-04-A4-06-C5 video-service: ; put_setting 0 ("zoom_direct_speed":0) error: 4 {u vaddio-romulus-78-A5-04-A4-06-C5 video-service: ; put_setting 0 ("zoom_direct_speed":0) error: 4 {u vaddio-romulus-78-A5-04-A4-06-C5 video-service: ; put_setting 0 ("zoom_direct_speed":0) error: 4 {u vaddio-romulus-78-A5-04-A4-06-C5 video-service: ; put_setting 0 ("zoom_direct_speed":0) error: 4 {u vaddio-romulus-78-A5-04-A4-06-C5 video-service: ; put_setting 0 ("zoom_direct_speed":0) error: 4 {u vaddio-romulus-78-A5-04-A4-06-C5 video-service	messa	aç
Networking	vaddio-romulus-78-A5-04-A4-06-C5 video-service: calletta struttata: "Intality calletta struttata" ("position":16384]} er vaddio-romulus-78-A5-04-A4-06-C5 video-service: : 4 put_ptz_position 0 ("zoom":{"position":0}} comp vaddio-romulus-78-A5-04-A4-06-C5 visca-service; : exceptions.KeyError; "22'	or: 4 {	u
Security	vaddio-romulus-78-A5-04-A4-06-C5 visca-service: Traceback (most recent call last): vaddio-romulus-78-A5-04-A4-06-C5 File "/usr/lib/python2.7/site-packages/ng_mv_visca/visca_decod vaddio-romulus-78-A5-04-A4-06-C5 requested iris = iiis info[vser map][str(requested iris)]	e.py",	li
Diagnostics	vaddio-romulus-78-A5-04-A4-06-C5 KeyError. '22' vaddio-romulus-78-A5-04-A4-06-C5 video-service: : visca_pass_thru 0 [129, 1, 4, 75, 0, 0, 1, 6, 255] v vaddio-romulus-78-A5-04-A4-06-C5 visca-service: exceptions.KeyError: '18'	rror: 4	
System	vaddio-romulus-78-A5-04-A4-06-C5 visca-service: Traceback (most recent call last): vaddio-romulus-78-A5-04-A4-06-C5 File "/usr/lib/python2.7/site-packages/vng_mw_visca/visca_decod vaddio-romulus-78-A5-04-A4-06-C5 requested_iris = iris_info['user_map][str(requested_iris)]	e.py",	lir
i Help	vaddio-romulus-78-A5-04-A4-06-C5 KeyError. ¹ 18' vaddio-romulus-78-A5-04-A4-06-C5 video-service: : visca_pass_thru 0 [129, 1, 4, 75, 0, 0, 1, 2, 255] v vaddio-romulus-78-A5-04-A4-06-C5 visca-service: exceptions.KeyError: '21'	rror: 4	
🕐 Logout	vaddio-romulus-78-A5-04-A4-06-C5 visca-service: Traceback (most recent call last): vaddio-romulus-78-A5-04-A4-06-C5 File "/usr/lib/python2.7/site-packages/yng_mw_visca/visca_decod vaddio-romulus-78-A5-04-A4-06-C5 requested_iris = iris_info['user_map'][str(requested_iris)]	e.py",	lin
	vaddio-romulus-78-A5-04-A4-06-C5 KeyError: '21' vaddio-romulus-78-A5-04-A4-06-C5 video-service: 'visca_pass_thru 0 [129, 1, 4, 75, 0, 0, 1, 5, 255] v vaddio-romulus-78-A5-04-A4-06-C5 visca-service: visca-pass_thru 0 [129, 1, 4, 75, 0, 0, 1, 5, 255] v vaddio-romulus-78-A5-04-A4-06-C5 visca-service: Traceback (most recent call last):	rror: 4	
	vaddio-formulus-78-A5-04-A4-06-C5 File "/usr/lib/python2.7/site-packages/vng_mw_visca/visca_decod vaddio-romulus-78-A5-04-A4-06-C5 File "/usr/lib/python2.7/site-packages/vng_mw_visca/visca_decod vaddio-romulus-78-A5-04-A4-06-C5 fevError: 19'	e.py",	lir
	vaddio-romulus-78-A5-04-A4-06-C5 video-service: : visca_pass_thru 0 [129, 1, 4, 75, 0, 0, 1, 3, 255] v	rror: 4	1
	<		•



Screen Shot: Admin Menu - System

The System Menu is where the System Info is displayed and Firmware Updates are performed. There will be firmware updates and upgrades over the life of the camera. The file for the firmware update is chosen in this menu and the update is started here too. A remote system Reboot and Restore to Factory Presets is also available.

🔇 🕽 C 🗋 169.254.1	.1/#system	P 🌣 🎄
vaddio Roboshot	Vaddio, Conference Room #1 Rm Tel x547, Help Tel 1-800-888-HELP	Logo
Camera Controls	FIRMWARE UPDATE	
Camera Settings	Firmware File: Choose File No file chosen Cancel Begin Firmware Update	
Room Labels		
Q Networking	SYSTEM UTILITES Reboot Restore Factory Settings 2	
Security		
Diagnostics	System Version: RoboSHOT 1.0.0 Commit: d033ddb2378357a87f011eb820706dcaa64ec0e2	
System	Pan Motor Version: 0.2.4586 Tilt Motor Version: 0.2.4586 Sensor Version: 02.00	
Help		
🕐 Logout	REAR DIP SWITCHES STATUS 4.	
	1 2 3 4 5 6 7 8	
	IR 2 IR 3 IR Out On On On bps	
	REAR ROTARY SWITCH STATUS 5	
	18.9 ° 720p/59.94 8 1080p/50	
	1 1080/59.94 9 720p/30 2 1080p/59.94 A 1080p/30	
	3 720p/60 B 720p/25	
	4 1080i/60 C 1080p/25	
	5 1080p/60 D	
	6 720p/50 E 6	

- 1) Firmware Update: The file for the firmware update is chosen in this menu and the update is started here.
- 2) System Utilities: A remote system Reboot and Restore to Factory Presets is also available.
- 3) System Information: The System version, Pan & Tilt Motor Versions and Sensor version are displayed in this section.
- 4) Rear DIP Switch Status: The DIP Switches on the camera are read and displayed for the Admin's reference. This information is read only. These switches determine the IR remote frequency, image flip, and baud rate of the camera and more!
- 5) Rear Rotary Switch Status: The rotary switch on the back of the RoboSHOT camera determines the video output resolution of the camera. The status is read from the camera (read only) and displayed for the Admin's reference.



Important Note: Anytime a *Firmware Update*, a **System Reboot** or a *Restore to Factory Settings* button is clicked, then a pop-up dialog box will spring up and ask if the intent is to continue or cancel. Please read and understand all the information in the presented in the dialog box prior to proceeding with any unknown procedure.



Screen Shot: Admin Menu - Update Confirmation

After choosing an update file and clicking on "Begin Firmware Update..." a confirmation pop-up and warning will be displayed. Please contact Vaddio Tech support for assistance with updates. Please read and completely understand the pop-up warnings as it is easy to lose patience waiting for updates. Click on continue to start the update.

RoboSHOT - Conferen		
	1.1/#system	7 4 *
Repushor	Vaddio, Conference Room et. Rei Trif x547, Heiji Tei 1:4500-888-HELP	Logoa
	FIRMWARE LIPDATE	
Camine Sellings	Concel Beats Transver United	
🖉 fizenti ala	SYSTEMUTUTES	
ي . Himanykatty	Retout Retout Factor Ferre	
Decarety	Svoter Confirm ×	
Disgrames	System Commit You are about to update your device. During this process the device	
Syawitt	Non-Mo-may not be available. At the end of the process the device may The Mole automatically reboot.	
i mp	Service This process can take up to 20 minutes. Please be patient and do reflexit or navigate away from this web page.	
	REAR L UPGRADE PROCESS UNLESS DIRECTED.	
	When the update is complete this page will attempt to re-connect to the device. Depending on your network and device configuration it may not be able to re-connect.	
	Cancel Continue	
	ter 1 et 1 et 0 e 0 e 1 e 1 e 1 e 1 e 1 e 1 e 1 e 1 e	
	REAR ROTARY SWITCH STATUS	
	189 в партила в сладот	
	A There is a region	
	4 3 Linexids (a) 4 Linexids (a) 5 3 Traplet 8 Traplet 6	
	FI A H HANNER	

Screen Shot: Admin Menu - Update in Progress

After the firmware load has been started, a pop-up screen will advise patience and notify, in terms of percentage completed, the progress of the firmware update load. Again, please don't interrupt the firmware load.

	4.1.1/#system	9 \$ \$ 3
	Vaddio, Conference Room #1 Rm: Tel x547, Hep: Tel 1-80G-888-HELP	Logut
	FIRBIWARE UPDATE	
	Foreward File: Choose File: Valda-como: Latente 07/0	
🖁 - Catolia Samayo	Crucial Degn Remains Update	
Fites a Labora		
	SYSTEM UTILITES	
Neworking	Report. (Result Angury Settings).	
a Searcy		
	Firmware Update In Progress	
Dodates.	Preparing device for firmware update Done preparing device for firmware update	
D ann	Ready for file upload Finished firmware update install prehook	
	Uploading file, please be patient.	
Hung-		
		and the second se
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k	N.1 H.1 H Cost Cost Height type Topole Height type REAH HOTARY SWITCH STATUS 0 1000000000000000000000000000000000000	
	N_1 N_1 N_2 N_2 <td></td>	
	N.1 # On On Impleting Tope Tope Tope REAR ROYARY SWITCH STATUS 0 Tope 0 Tope Tope 1 8 0 Tope 0 Tope Tope 1 1 (Implete) 0 Tope Tope Tope 1 Implete 0 Tope 0 Tope Tope	



Screen Shot - Admin Menu - Help

Service/Help information can be found under the Help menu. Support phone numbers and e-mail, manuals, FAQ's and System information is listed on support@vaddio.com.

	Vaddio, Conference Room #1 Rm Tel x547, Help Tel 1-800-888-HELP	Logout
Camera Controls	TECHNICAL SUPPORT	
Camera Settings	You can reach Vaddio technical support by calling: Direct: +1 (763) 971-4400	
Room Labels	Toll Free: +1 (800) 572-2011 Fax: +1 (763) 971-4464	
Networking	Through email by sending your questions to: support@vaddio.com	
Security	Or access support information directly on our web page at: http://help.vaddio.com/roboshot	
Diagnostics		
System		
🖁 Help		
🕖 Logout		

This concludes the RoboSHOT Screen Shot Tour. Please enjoy yourself while reading the rest of this RoboSHOT Camera Manual.

The Next Sections:

The General Specifications, Communication Specifications, API, Telnet Command List, Warranty Information and Declaration of Compliance are breathtaking, stimulating and provocative as one would expect.



GENERAL SPECIFICATIONS

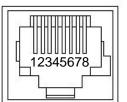
Function	Description
Part Numbers	999-9940-000: RoboSHOT 12 HDMI, 12X HD Robotic PTZ Camera (North America)
	999-9940-001: RoboSHOT 12 HDMI, 12X HD Robotic PTZ Camera (International)
	999-9943-000: RoboSHOT 30 HDMI, 30X HD Robotic PTZ Camera, Black (North America) 999-9943-001: RoboSHOT 30 HDMI, 30X HD Robotic PTZ Camera, Black (International)
	999-9943-000W: RoboSHOT 30 HDMI, 30X HD Robotic PTZ Camera, White (North America) 999-9943-001W: RoboSHOT 30 HDMI, 30X HD Robotic PTZ Camera, White (International)
Image Device	1/2.8-Type Exmor CMOS Sensor
Video Resolution/Frequencies	1080p60/59.94/50/30/25, 1080i/60/59.94i/50, 720p/60/59.94/50
Vaddio Special Features	 Tri-Synchronous Motion: Concurrent PTZ motor movement and simultaneous PTZ arrival at a stored preset Advanced ISP: Vivid and accurate color reproduction with extremely fast, razor sharp automatic focus and iris routines
Video Aspect Ratio	16:9 Aspect Ratio for all resolutions
Effective Pixels	2.14 Million Effective pixels 2.38 Million Total Pixels
RoboSHOT 12 Lens and Horizontal FOV	12X Optical Zoom, Super Wide Mode: 73.0° (wide) to 6.6° (tele),f=3.91mm to 47.0mm, F1.8 to F3.4 10X Optical Zoom, Normal Mode: 67.3° (wide) to 7.6° (tele), f=3.8mm to 38.0mm, F1.8 to F3.4 NOTE: Default is Normal Mode
RoboSHOT 30 Lens and Horizontal FOV	30X Optical Zoom 65° (wide end) to 2.3° (tele end), F1.6 to F4.7
Minimum illumination RoboSHOT 12	1.0 lx (F1.8, 50IRE), recommended illumination >100 lux and <100,000 lux
Minimum illumination RoboSHOT 30	1.4 lx (F1.6, 50IRE), recommended illumination >100 lux and <100,000 lux
Minimum working distance RoboSHOT 12	10mm (wide), 800mm (tele)
Minimum working distance RoboSHOT 30	10mm (wide), 1.2m (tele)
S/N ratio	More than 50 dB
Sync system	Internal
White balance	Auto, ATW, Indoor, Outdoor, One-push, Manual (accessible through external control)
Gain	Auto / Manual (0 to 28 steps - accessible through external control)
Back-light compensation	On/Off (IR Remote)
Focusing system	Auto Focus / Manual Focus Mode / One Push Trigger Mode / Infinity Mode / Near Limit Mode
Noise Reduction	On/Off, 6 Steps, Off through 5 (accessible through external control)
Aperture/Detail	16 Steps (accessible through external control)
Control Interface(s)	 RS-232 API: Modified VISCA Emulation (TTL signal level), Baud rate: 9600 bps and 38,400 bps, 1-Stop bit. Default to 9.6 Kb/s for Cat-5e Distance Telnet Serial Command API Internal Web page for Network Set-up, firmware updates and network management Vaddio IR Remote Commander
Pan & Tilt Angle/Speed	Pan/Tilt Angles: ±160°, Tilt: +90°, -30°, Pan/Tilt Speeds: Both Axes 0.35°/sec to 120°/sec
Rear Panel Connectors	 Network: RJ-45 with Green & Yellow LED to show connection and usage RS-232: RJ-45, Carries bidirectional control to and from the camera EZ Power Video: RJ-45 Shielded, carries power and differential video signals for the Quick-Connect Cat-5 systems
Rear Panel Controls	16-Position Rotary Switch for Resolution selection 8-Position DIP Switch for IR Frequency, Image Flip, wide mode and Reset to Default Settings
Power Supply	Powered by Quick-Connect SR Interface
Compatible Joystick and Video Control Consoles	ProductionVIEW Precision Camera Controller AV Bridge MATRIX PRO
Operating/Storage Temperature/Humidity	0°C (32°F) to 40°C (104°F), 20% to 80%
Mass	4.85 lbs.(2.199923 kg - Roughly 900 peanut M&Ms)
Dimensions	Small (3 dimensions not counting space/time) 6.942" (176.3mm) H x 7.056" (179.2 mm) W x 6.757" (171.6mm) D,
lates. Encoifications and priving are subject	

Specifications and pricing are subject to change without prior notice or obligation. For dimensional drawings of the products, go to support.vaddio.com and click on drawings. Notes:



COMMUNICATION SPECIFICATION

Communication Speed: 9600 bps (default) Start bit: 1 Stop bit: 1 Data bits: 8 Parity: None No Flow control



RJ-45 RS-232 and IR Out Pins Pin

- 1) Unused
- 2) Unused 3) Unused
- 4) IR Output (Diff Signal to Quick-Connect SR)
- 5) IR Ground (Diff Signal to Quick-Connect SR)
 6) GND (GND of IR Short Range Pin 3)
- 7) RXD (from TXD of control source)
- 8) TXD (to RXD of control source)

NOTE: The Vaddio RoboSHOT Control Protocol is similar, but not identical to, the Sony® VISCA™ command set in order to be compatible with several popular control devices. Not all VISCA commands are supported and there are many Vaddio specific commands in the following Command and Inquiry Lists.

RoboSHOT Command List (1/3)

Command Set	Command	Command Packet	Comments
AddressSet	Broadcast	88 30 01 FF	Address setting
IF_Clear	Broadcast	88 01 00 01 FF	I/F Clear
CommandCancel		8x 2p FF	p= Socket No.(1-2)
CAM Power	On	8x 01 04 00 02 FF	Power on
-	Off	8x 01 04 00 03 FF	Power off
CAM_Zoom	Stop	8x 01 04 07 00 FF	
	Tele(std)	8x 01 04 07 02 FF	
	Wide(std)	8x 01 04 07 03 FF	
	Tele(variable)	8x 01 04 07 2p FF	p= speed 0:low to 7:high
	Wide(variable)	8x 01 04 07 3p FF	p= speed 0:low to 7:high
	Direct	8x 01 04 47 0p 0g 0r 0s FF	pgrs=Zoom Position (0h-4000h)
CAM_DZoom	2.000	Not supported	
CAM_Focus	Stop	8x 01 04 08 00 FF	
or im_r ocus	Far(std)	8x 01 04 08 02 FF	
	Near(std)	8x 01 04 08 03 FF	
	Far(variable)	8x 01 04 08 2p FF	p= speed 0:low to 7:high
	Near(variable)	8x 01 04 08 3p FF	p= speed 0:low to 7:high
	Direct	8x 01 04 48 0p 0q 0r 0s FF	pgrs=Focus Position (1000h – F000h)
	Auto Focus	8x 01 04 38 02 FF	pqrs=1 0cus P 0sition (100011 = 1 00011)
	Manual Focus	8x 01 04 38 03 FF	
	Auto/Manual	8x 01 04 08 10 FF	
	One Push Trigger	8x 01 04 18 01 FF	One push AF Trigger
	Near Limit	8x 01 04 18 01 FF 8x 01 04 28 0p 0q 0r 0s FF	pqrs=Near focus Limit***
		8x 01 04 58 02 FF	AF Sensitivity High / Low
CAM_AFSensitivity	Normal		AF Sensitivity High / Low
CAM AFMode	Low	8x 01 04 58 03 FF	AF movement mode
CAIM_AFINIODE	Normal AF	8x 01 04 57 00 FF	AF movement mode
	Internal AF	8x 01 04 57 01 FF	
	Zoom Trigger AF	8x 01 04 57 02 FF	a sure and the sure that and
	Activate/Internal Time	8x 01 04 27 0p 0q 0r 0s FF 8x 01 04 11 00 FF	pqrs=movement time, rs=Interval
CAM_IRCorrection	Standard		Focus IR compensation data switching
~~~~ =	IR light	8x 01 04 11 01 FF	
CAM_ZoomFocus	Direct	8x 01 04 47 0p 0q 0r 0s	pqrs=Zoom Position (0h – 7AC0h)
		Ot Ou Ov Ow FF	tuvw=Focus Position (1000h – F000h)
CAM_WB	Auto	8x 01 04 35 00 FF	Normal Auto
	Indoor	8x 01 04 35 01 FF	Indoor mode
	Outdoor	8x 01 04 35 02 FF	Outdoor mode
	One Push WB	8x 01 04 35 03 FF	One Push WB mode
	ATW	8x 01 04 35 04 FF	Auto Tracing White Balance
	Manual	8x 01 04 35 05 FF	Manual Control mode
	One Push Trigger	8x 01 04 10 05 FF	One Push WB Trigger
	Outdoor Auto	8x 01 04 35 06 FF	Outdoor auto
	Sodium Lamp Auto	8x 01 04 35 07 FF	Auto including sodium lamp source
	Sodium Lamp	8x 01 04 35 08 FF	Sodium lamp source fixed mode
	Sodium Lamp Outdoor Auto	8x 01 04 35 09 FF	Outdoor auto including sodium lamp
	-		source
CAM_RGain	Reset	8x 01 04 03 00 FF	Manual control of red gain
	Up	8x 01 04 03 01 FF	
	Down	8x 01 04 03 02 FF	
	Direct	8x 01 04 43 00 00 0p 0q FF	pq=Red gain (00h – FFh)
CAM_BGain	Reset	8x 01 04 04 00 FF	Manual control of blue gain
	Up	8x 01 04 04 01 FF	
	Down	8x 01 04 04 02 FF	
	Direct	8x 01 04 44 00 00 0p 0q FF	pq=Blue gain (00h – FFh)
CAM_AE	Full Auto	8x 01 04 39 00 FF	Auto Exposure mode
	Manual	8x 01 04 39 03 FF	Manual Control mode
	Shutter Priority	8x 01 04 39 0A FF	Shutter Priority Auto Exposure mode
	Iris Priority	8x 01 04 39 0B FF	Iris Priority Auto Exposure Mode



## RoboSHOT Command List (2/3)

Command Set	Command	Command Packet	Comments
CAM Shutter	Reset	8x 01 04 0A 00 FF	Shutter Setting
OAM ONULLE	Up	8x 01 04 0A 01 FF	onution betting
	Down	8x 01 04 0A 02 FF	
	Direct	8x 01 04 4A 00 00 0p 0g FF	pq=Shutter Position (00h – 15h)
CAM_Iris	Reset	8x 01 04 0B 00 FF	Iris Setting
CAIVI_IIIS	Up	8x 01 04 0B 00 FF 8x 01 04 0B 01 FF	pq=Iris Position**
	Down	8x 01 04 0B 02 FF	RoboSHOT 12 (0h, 07h-11h)
	Direct	8x 01 04 0B 02 FF 8x 01 04 4B 00 00 0p 0q FF	RoboSHOT 30 (0h, 05h-11h)
CAM_Gain	Reset	8x 01 04 0C 00 FF	Iris Gain Setting
CAW_GaIII	Up	8x 01 04 0C 00 FF	ins Gain Setting
	Down	8x 01 04 0C 02 FF	
	Direct	8x 01 04 4C 00 00 0p 0g FF	pq=Gain Position (01h – 0Fh)
	+Gain Limit	8x 01 04 2C 0p FF	p= Gain limit (04h-0Fh)
			• • • •
CAM_ExpComp	On	8x 01 04 3E 02 FF	Exposure Compensation On
	Off	8x 01 04 3E 03 FF	Exposure Compensation Off
	Reset	8x 01 04 3E 00 FF	
	Up	8x 01 04 3E 01 FF	
	Down	8x 01 04 3E 02 FF	
	Direct	8x 01 04 4E 00 00 0p 0q FF	pq=ExpComp Position(0h-0Eh)
CAM_BackLight	On	8x 01 04 33 02 FF	Backlight Compensation On/Off
	Off	8x 01 04 33 03 FF	
CAM_Tally	On	8x 01 7E 01 0A 00 02 FF	
	Off	8x 01 7E 01 0A 00 03 FF	
CAM_SpotAE	On	8x 01 04 59 02 FF	Spot Auto Exposure Setting
	Off	8x 01 04 59 03 FF	
	Position	8x 01 04 29 0p 0q 0r 0s FF	pq=X-(0h-0fh), rs=Y-(0h-0fh)
CAM_WD	On	8x 01 04 3D 02 FF	WD On
	Off	8x 01 04 3D 03 FF	WD Off
	VE On	8x 01 04 3D 06 FF	VE On
	Set Parameter	8x 01 04 2D 00 0q 0r 0s	p=Display brightness level (0Dark -
		00 00 00 00 FF	6Bright)
			r=Brightness compensation selection
			(0:Very dark,1:Dark,2:std,3:bright)
			s=Compensation level
			(0:Low,1:Mid,2:High)
CAM_Aperture	Reset	8x 01 04 02 00 FF	Aperture Setting
	Up	8x 01 04 02 01 FF	
	Down	8x 01 04 02 02 FF	
	Direct	8x 01 04 42 00 00 0p 0q FF	pq=Aperture Position (0h-ffh)
CAM_HR	On	8x 01 04 52 02 FF	High Resolution Mode On/Off
	Off	8x 01 04 52 03 FF	
CAM_NR		8x 01 04 53 0p FF	p= Noise Reduction level(0:Off,1-5)
CAM_Gamma		8x 01 04 5B 0p FF	p= Gamma setting(0:std,1:Straight)
CAM_LR_Reverse	On	8x 01 04 61 02 FF	LR Reverse On/Off (mirror)
	Off	8x 01 04 61 03 FF	
CAM_Freeze	On	8x 01 04 62 02 FF	Freeze On/Off
	Off	8x 01 04 62 03 FF	
CAM_PictureEffect	Off	8x 01 04 63 00 FF	Picture Effect Setting
	Neg.Art	8x 01 04 63 02 FF	
	Black & White	8x 01 04 63 04 FF	
CAM_PictueFlip	On	8x 01 04 66 02 FF	Image-Flip On/Off
	Off	8x 01 04 66 03 FF	
CAM_ICR	On	8x 01 04 01 02 FF	ICR Mode On/Off
	Off	8x 01 04 01 03 FF	
CAM_IDWrite		8x 01 04 22 0p 0q 0r 0s FF	pqrs=Camer ID (0h-ffffh)
			p= preset number(0h-0fh)
CAM_Memory	Reset	8x 01 04 3F 00 0p FF	
	Set standard	8x 01 04 3F 01 0p FF	qr= Speed(01h-18h)
	Set standard Set standard with 'scene'	8x 01 04 3F 01 0p FF 8x 01 04 3F 21 0p FF	
	Set standard Set standard with 'scene' Set Tri-sync	8x 01 04 3F 01 0p FF 8x 01 04 3F 21 0p FF 8x 01 04 3F 11 0p 0q 0r FF	
	Set standard Set standard with 'scene' Set Tri-sync Set Tri-Sync with 'scene'	8x 01 04 3F 01 0p FF 8x 01 04 3F 21 0p FF 8x 01 04 3F 11 0p 0q 0r FF 8x 01 04 3F 11 0p 0q 0r FF	
	Set standard Set standard with 'scene' Set Tri-sync	8x 01 04 3F 01 0p FF 8x 01 04 3F 21 0p FF 8x 01 04 3F 11 0p 0q 0r FF	



## RoboSHOT Command List (3/3)

Command Set	Command	Command Packet	Comments
Cam_Display	On	8x 01 04 15 02 FF	Display On/Off
ean_biopiay	On(alternate)	8x 01 06 06 02 FF	
	Off	8x 01 04 15 03 FF	
	Off(alternate)	8x 01 06 06 03 FF	
	On/Off	8x 01 04 15 10 FF	
	On/Off(alternate)	8x 01 06 06 10 FF	
Cam_Mute	On	8x 01 04 75 02 FF	Mute On/Off
	Off	8x 01 04 75 03 FF	
	On/Off	8x 01 04 75 10 FF	
CAM_ColorEnhance	Parameter Set	8x 01 04 20 mm 00 pp	mm: Threshold level
		qq rr ss tt uu FF	pp: Y fixed color for high-intensity
			qq: Cr fixed color for high-intensity
			rr: Cb fixed color for high-intensity
			ss: Y fixed color for low-intensity
			tt: Cr fixed color for low-intensity
			uu: Cb fixed color for low-intensity
	0.	0:: 01 01 50 00 FF	Each parameter setting 00h to 7Fh
	On Off	8x 01 04 50 02 FF	Color Enhancement On/Off
CAM ChromoCupproce	Off	8x 01 04 50 03 FF	ne. Chrome Cuerrage acting layel
CAM_ChromaSuppress		8x 01 04 5F pp FF	pp: Chroma Suppress setting level 00: Off
			01h to 03h: On (3 levels).
			Effect increases as the level number
			increases.
CAM ColorGain	Direct	8x 01 04 49 00 00 00 0p FF	p: Color Gain Setting 0h to 4h
CAM ColorHue	Direct	8x 01 04 4F 00 00 00 0p FF	p: Color Hue Setting 0h (-14 degrees) to
OAM_COUNTRE	Direct		Eh (+14 degrees)
CAM GammaOffset	Direct	8x 01 04 1E 00 00 00 0s 0t 0u FF	s: Polarity offset (0 is plus, 1 is minus)
e, m_eannachter	Billoot		tu: Offset s=0 (00h to 40h)
			Offset $s=1$ (00h to 10h)
Pan-TiltDrive	Up	8x 01 06 01 vv ww 03 01 FF	vv = Pan speed (01h-18h)
	Down	8x 01 06 01 vv ww 03 02 FF	ww=Tilt speed (01h-14h)
	Left	8x 01 06 01 vv ww 01 03 FF	···· ·································
	Right	8x 01 06 01 vv ww 02 03 FF	
	UpLeft	8x 01 06 01 vv ww 01 01 FF	
	UpRight	8x 01 06 01 vv ww 02 01 FF	
	DownLeft	8x 01 06 01 vv ww 01 02 FF	
	DownRight	8x 01 06 01 vv ww 02 02 FF	
	Stop	8x 01 06 01 vv ww 03 03 FF	
	Absolute Position	8x 01 06 02 vv ww 0Y 0Y 0Y 0Y	vv= Pan speed (01h-18h)
		0Z 0Z 0Z 0Z FF	ww=Tilt speed (01h-14h)
			0Y0Y0Y0Y = Pan position
			(90E2h-6BD8h)
			0Z0Z0Z0Z = Tilt position
	Llama		(EB99h-3D59h)
Pan-Tilt-ZoomDrive	Home	8x 01 06 04 FF 8x 01 06 0A vy ww rr 03 01 03 FF	New Dop oppod (01h 19h)
Pan-Hit-ZoomDrive	Up	8x 01 06 0A vv ww rr 03 01 03 FF 8x 01 06 0A vv ww rr 03 02 03 FF	vv= Pan speed (01h-18h) ww=Tilt speed (01h-14h)
	Down Left	8x 01 06 0A VV ww rr 03 02 03 FF 8x 01 06 0A vv ww rr 01 03 03 FF	rr=Zoom speed (00h-07h)
	Right	8x 01 06 0A VV ww II 01 03 03 FF	11=20011 speed (001-071)
	In	8x 01 06 0A VV ww 11 02 03 03 FF	
	Out	8x 01 06 0A vv ww rr 03 03 02 FF	
	Stop	8x 01 06 0A vv ww rr 03 03 03 FF	
	Absolute Position	8x 01 06 0B vv ww 0Y 0Y 0Y 0Y	vv: Pan speed (01h-18h)
		0Z 0Z 0Z 0Z 0R 0R 0R 0R FF	ww: Tilt speed (01h-14h)
			0Y0Y0Y0Y = Pan position
			(90E2h-6BD8h)
			0Z0Z0Z0Z = Tilt position
			(EB99h-3D59h)
			0R0R0R0R = Zoom position
			(0000h-7AC0h)
	Home	8x 01 06 0C FF	
CAM_PTZ_PresetSpeed		8x 01 7e 01 0b pp qq rr FF	pp:pan speed (01h-18h),
			qq:tilt speed (01h-14h),
			rr:zoom speed (0h-07h)



## RoboSHOT Inquiry List (1/2)

Inquiry Command	Command	Response Packet	Comments
CAM_PowerInq	8x 09 04 00 FF	y0 50 02 FF	On
		y0 50 03 FF	Off (Standby)
CAM_ZoomPosInq	8x 09 04 47 FF	y0 50 0p 0q 0r 0s FF	pqrs: Zoom Position
CAM_FocusModeInq	8x 09 04 38 FF	y0 50 02 FF	Auto Focus
		y0 50 03 FF	Manual Focus
CAM_FocusPosInq	8x 09 04 48 FF	y0 50 0p 0q 0r 0s FF	pqrs: Focus Position
CAM_FocusNearLimitIng	8x 09 04 28 FF	y0 50 0p 0q 0r 0s FF	pqrs: Focus Near Limit Position
CAM_AFSensitivityInq	8x 09 04 58 FF	y0 50 02 FF	AF Sensitivity Normal
		y0 50 03 FF	AF Sensitivity Low
CAM_AFModeInq	8x 09 04 57 FF	y0 50 00 FF	Normal AF
		y0 50 01 FF	Interval AF
		y0 50 02 FF	Zoom Trigger AF
CAM_AFTimeSettingIng	8x 09 04 27 FF	y0 50 0p 0q 0r 0s FF	pg: Movement Time, rs: Interval
CAM_IRCorrectionIng	8x 09 04 11 FF	y0 50 00 FF	Standard
		y0 50 01 FF	IR Light
CAM_WBModeIng	8x 09 04 35 FF	y0 50 00 FF	Auto
		y0 50 01 FF	Indoor
		y0 50 02 FF	Outdoor
		y0 50 03 FF	One Push WB
		y0 50 04 FF	ATW
		y0 50 05 FF	Manual
		y0 50 06 FF	Outdoor Auto
		y0 50 07 FF	Sodium Lamp Auto
		y0 50 08 FF	Sodium Lamp
		y0 50 09 FF	Sodium Lamp Outdoor Auto
CAM_RGainIng	8x 09 04 43 FF	y0 50 00 00 0p 0q FF	pq: R Gain
CAM BGainIng	8x 09 04 44 FF	y0 50 00 00 0p 0q FF	pg: B Gain
CAM_AEModeIng	8x 09 04 39 FF	y0 50 00 FF	Full Auto
e, m_, Emodernq		y0 50 03 FF	Manual
		y0 50 0A FF	Shutter Priority
		y0 50 0B FF	Iris Priority
		y0 50 0D FF	Bright
CAM_ShutterPosInq	8x 09 04 4A FF	y0 50 00 00 0p 0q FF	pq: Shutter Position
CAM_IrisPosIng	8x 09 04 4B FF	y0 50 00 00 0p 0q FF	pg: Iris Position
CAM_GainPosIng	8x 09 04 4C FF	y0 50 00 00 0p 0q FF	pq: Gain Position
CAM_GainLimitIng	8x 09 04 2C FF		p: Gain Limit
		y0 50 0q FF	
CAM_ExpCompModeInq	8x 09 04 3E FF	y0 50 02 FF	On Off
		y0 50 03 FF	
CAM_ExpCompPosInq	8x 09 04 4E FF	y0 50 00 00 0p 0q FF	pq: ExpComp Position
CAM_BackLightModeInq	8x 09 04 33 FF	y0 50 02 FF	On
		y0 50 03 FF	Off
CAM_TallyInq	8x 09 7E 01 0A FF	y0 50 02 FF	On
		y0 50 03 FF	Off
CAM_ResolutionInq	8x 09 06 23 FF	y0 50 0p 0q FF	Pq=Video Resolution
CAM_SpotAEModeInq	8x 09 04 59 FF	y0 50 02 FF	On
		y0 50 03 FF	Off
CAM_SpotAEPosInq	8x 09 04 29 FF	y0 50 0p 0q 0r 0s FF	pq: X Position, rs: Y Position
CAM_WDModeInq	8x 09 04 3D FF	y0 50 02 FF	On
		y0 50 03 FF	Off
		y0 50 06 FF	VE On
CAM_WDParameterInq	8x 09 04 2D FF	y0 50 00 0q 0r 0s 0t 0u 00 00 FF	<ul> <li>q: Display brightness level (0: Dark to 6: Bright)</li> <li>r: Brightness compensation selection (0: Very dark, 1: Dark, 2: Standard, 3: Bright)</li> <li>s: Compensation level (00h: Low, 01h: Mid, 02h: High)</li> <li>tu: Always 0</li> </ul>
CAM Aporturolog	9x 00 04 40 FF		
CAM_ApertureInq	8x 09 04 42 FF	y0 50 00 00 0p 0q FF	pq: Aperture Gain
CAM_ApertureInq CAM_HRModeInq	8x 09 04 42 FF 8x 09 04 52 FF	y0 50 02 FF	pq: Aperture Gain On
			pq: Aperture Gain



## RoboSHOT Inquiry List (2/2)

Inquiry Command	Command	Response Packet	Comments
CAM_LR_ReverseModeInq	8x 09 04 61 FF	y0 50 02 FF	On (mirror)
·		y0 50 03 FF	Off
CAM_FreezeModeInq	8x 09 04 62 FF	y0 50 02 FF	On
		y0 50 03 FF	Off
CAM_PictureEffectModeInq	8x 09 04 63 FF	y0 50 00 FF	Off
		y0 50 02 FF	Neg. Art
		y0 50 04 FF	Black & White
CAM_PictureFlipModeInq	8x 09 04 66 FF	y0 50 02 FF	On
		y0 50 03 FF	Off
CAM_ICRModeInq	8x 09 04 01 FF	y0 50 02 FF	On
		y0 50 03 FF	Off
CAM_MemoryIng	8x 09 04 3F FF	y0 50 pp FF	pp: Memory number recalled last
CAM_MemoryStatusInq	8x 09 04 3F 0p FF	y0 50 0p 0q 0r 0s FF	p: Memory number
, ,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,			q: mode (00-std, 10-std /w ccu, 01-trisync,11-trisyc /w ccu) rs: speed (0x1-0x18) 1 - 24
CAM_MemSaveInq	8x 09 04 23 0X FF	y0 50 0p 0q 0r 0s FF	X: 00h to 07h (Address)
CAM_MemSaveInq	0X 09 04 23 0A FF	yo so op og of os FF	pgrs: 0000h to FFFFh (Data)
CAM_DisplayModeInq	8x 09 04 15 FF	y0 50 02 FF	On
CAM_DIsplayModelliq	(8x 09 06 06 FF)	y0 50 03 FF	Off
CAM_MuteModeIng	8x 09 04 75 FF	y0 50 02 FF	On
CAM_MULEWODEING	0X 09 04 73 FF	y0 50 03 FF	Off
CAM IDIng	8× 00 04 22 FF	y0 50 0p 0g 0r 0s FF	pgrs: Camera ID
CAM_IDInq CAM_VersionIng	8x 09 04 22 FF 8x 09 00 02 FF	y0 50 00 10	mnpg: Model Code
CAIM_Versioning	8X 09 00 02 FF		mnpq: Model Code
Vaddio_ModelIng	8x 09 08 0e FF	mn pq 0E 0E 02 FF y0 50 05 00 00 00 00 FF	RoboSHOT-12
vaddio_iviodeiinq	8X 09 08 08 FF	y0 50 05 01 00 00 00 FF	RoboSHOT-30
CAM_RegisterValueInq	8x 09 04 24 mm FF	y0 50 0p 0p FF	mm: Register No. (=00h to 7Fh)
CAM_Register valuering	8X 09 04 24 mm FF	yu 50 up up FF	pp: Register Value (=00h to FFh)
CAM_ColorEnhanceInq	8x 09 04 20 FF	y0 50 mm 00 pp qq rr ss tt uu FF	mm: Threshold level
CAM_COOFERINATCEINq	8x 09 04 20 FF	y0 50 02 FF	pp: Y fixed color for high-intensity qq: Cr fixed color for high-intensity rr: Cb fixed color for high-intensity ss: Y fixed color for low-intensity tt: Cr fixed color for low-intensity uu: Cb fixed color for low-intensity On
		y0 50 03 FF	Off
CAM_ChromaSuppressInq	8x 09 04 5F FF	y0 50 pp FF	pp: Chroma Suppress setting level
CAM_ColorGainInq	8x 09 04 49 FF	y0 50 00 00 00 0p FF	p: Color Gain Setting 0h to 4h
CAM_ColorHueInq	8x 09 04 4F FF	y0 50 00 00 00 0p FF	p: Color Hue Setting 0h (- 14 degrees) to Eh (+ 14degrees)
CAM_TempInq	8x 09 04 68 FF	Y0 50 00 00 0p 0q FF	pq: Lens Temperature
CAM_GammaOffsetInq	8x 09 04 1E FF	y0 50 00 00 00 0s 0t 0u FF	s: Polarity offset (0 is plus, 1 is minus) tu: Offset s=0 (00h to 40h) Offset s=1 (00h to 10h)
Pan-tiltPosInq	8x 09 06 12 FF	y0 50 0w 0w 0w 0w	wwww= Pan position
-		0z 0z 0z 0z FF	zzzz=Tilt Position

# vaddio

## COMMAND SETTING VALUES Exposure Control

Shutter	Value	60/59.94/30/29.97	50/25
Speed	0x15	1/10000	
Speed			1/10000
	0x14	1/6000	1/6000
	0x13	1/4000	1/3500
	0x12	1/3000	1/2500
	0x11	1/2000	1/1750
	0x10	1/1500	1/1250
	0x0F	1/1000	1/1000
	0x0E	1/725	1/600
	0x0D	1/500	1/425
	0x0C	1/350	1/300
	0x0B	1/250	1/215
	0x0A	1/180	1/150
	0x09	1/125	1/120
	0x08	1/100	1/100
	0x07	1/90	1/75
	0x06	1/60	1/50
	0x05	1/30	1/25
	0x04	1/15	1/12
	0x03	1/8	1/6
	0x02	1/4	1/3
	0x01	1/2	1/2
	0x00	1/1	1/1

Iris	Value	RoboSHOT 12	RoboSHOT 30
	0x11	F1.8	F1.6
	0x10	F2	F2
	0x0F	F2.4	F2.4
	0x0E	F2.8	F2.8
	0x0D	F3.3	F3.4
	0x0C	F4	F4
	0x0B	F4.8	F4.8
	0x0A	F5.6	F5.6
	0x09	F6.8	F6.8
	0x08	F8	F8
	0x07	F9.6	F9.6
	0x06	N/A	F11
	0x05	N/A	F14
	0x00	CLOSE	CLOSE

Iris	Value	Steps
Gain	0x0F	28
	0x0E	26
	0x0D	24
	0x0C	22
	0x0B	20
	0x0A	18
	0x09	16
	0x08	14
	0x07	12
	0x06	10
	0x05	8
	0x04	6
	0x03	4
	0x02	2
	0x01	0
Iris	Value	Steps

Iris	Value	Steps
Gain	0x0F	28
Limit	0x0E	26
	0x0D	24
	0x0C	22
	0x0B	20
	0x0A	18
	0x09	16
	0x08	14
	0x07	12
	0x06	10
	0x05	8
	0x04	6

Exposure	Value	Iris	Gain
Comp.	0x0E	+7	+10.5 dB
	0x0D	+6	+9 dB
	0x0C	+5	+7.5 dB
	0x0B	+4	+6 dB
	0x0A	+3	+4.5 dB
	0x09	+2	+3 dB
	0x08	+1	+1.5 dB
	0x07	0	0 dB
	0x06	-1	-1.5 dB
	0x05	-2	-3 dB
	0x04	-3	-4.5 dB
	0x03	-4	-6 dB
	0x02	-5	-7.5 dB
	0x01	-6	-9 dB
	0x00	-7	-10.5 dB



## **TELNET SERIAL COMMAND API**

The Vaddio Serial Command protocol is a high level text based command line interface supported via telnet session on the RoboSHOT. The command application protocol interface is intended to allow external device such as AMX or Crestron to control the camera. The protocol is based upon ASCII format following the VT100 terminal emulation standard and uses an intuitive text command nomenclature for ease of use. The API is accessed by a telnet client on the Ethernet port. All ASCII characters will be <u>echoed</u> to terminal program and appended with VT100 string -ESC[J (HEX- 1B 5B 4A). Vaddio Command lines are terminated on carriage return. After the carriage return, the VT100 appends with –ESC[J. (Note: Most terminal programs automatically strip the VT100 string.) General format usage follows a get/set structure. Usage examples for each type are:

## Set Example

COMMAND: > camera pan right RESPONSE: > OK

Get Example COMMAND: > camera home get RESPONSE: > OK

Syntax Error Example COMMAND: > camera right pan RESPONSE: > ERROR

Additional programming controls associated with the terminal protocol includes:

• CTRL 5 - Clears the current serial buffer on the device.

Telnet sessions will require access verification and uses the same username and password associated with the Administrator account on the embedded web server. The default Telnet Port is 23. Command lines are terminated with a carriage return.

## **Telnet Command List**

## **Camera Home**

- NAME
  - camera home Move the camera to the home position
- SYNOPSIS
- camera home
- DESCRIPTION
  - Method used to move the camera to the home position
- EXAMPLES

camera home Move the camera back to the home position

## Camera Pan

- NAME
  - camera pan Pans the camera left or right
- SYNOPSIS
  - camera pan { left [<speed>] | right [<speed>] | stop }
- DESCRIPTION
- Method used to pan the camera
- OPTIONS
  - left Move the camera left
  - right Move the camera right stop Stop the camera movement
  - **speed** Optional integer from 1-24 that represents the speed (Default: 12)
- EXAMPLES
  - camera *pan* left Pans the camera left at the default speed camera *pan* right 20 Pans the camera right using a speed of 20 camera pan stop



Image: Invigorating simulated Telnet session.



## **Camera Tilt**

- NAME
  - camera tilt Tilts the camera up or down
- SYNOPSIS
   camera tilt { ur
  - camera tilt { up [<speed>] | down [<speed>] | stop }
- DESCRIPTION
  - Method used to tilt the camera
- OPTIONS
  - up Move the camera up down Move the camera down stop Stop the camera movement speed Optional integer from 1-20 that represents the speed (Default: 10)
  - EXAMPLES camera *tilt* Up Tilts the camera up at the default speed camera *tilt* down 20 Tilts the camera up using a speed of 20 camera *tilt* stop Stops the *tilt* movement of the camera

## Camera Zoom

- NAME
  - camera zoom zoom the camera in or out
- SYNOPSIS
  - camera zoom { in [<speed>] | out [<speed>] | stop }
- DESCRIPTION
  - Method used to zoom the camera
- OPTIONS
  - in Zoom in
  - out Zoom out
  - stop Stop the camera movement
  - speed Optional integer from 1-7 that represents the speed (Default: 3)
- EXAMPLES
  - camera zoom in Zooms the camera in at the default speed camera zoom out 7 - Zooms the camera out using a speed of 7 camera zoom stop - Stops the zoom movement of the camera

## **Camera Preset**

- NAME
  - camera preset
- SYNOPSIS
  - camera preset recall <1-16>
  - camera preset store <1-16> [tri-sync <1-24>] [save-ccu]
  - DESCRIPTION Method used to recall and store camera presets
- OPTIONS
  - recallRecall presetstoreStore preset
  - preset
  - Required value from 1-16 used to indicate the preset number
- EXAMPLES
  - camera recall 3 Move camera to *preset* position 3 camera store - Store current camera position as *preset* 1 camera *preset* store 2 *tri-sync* 10 save-ccu Store current camera position and CCU settings as *preset* 2, will recall using *tri-sync* at speed 10 camera *preset* store 4 *tri-sync* 15 Store current camera position as *preset* 4, will recall using *tri-sync* at speed 15





## **Camera Focus**

- NAME
  - camera focus
  - SYNOPSIS camera focus { { near [<speed>] | far [<speed>] } | stop } camera focus mode { auto | manual }
- DESCRIPTION
- Method used to focus the camera
- OPTIONS
  - near Move the camera focus near (with optional speed)
  - far Move the **camera** focus far (with optional speed)
  - stop Stop the camera focus
  - mode Set the focus mode to auto or manual
  - speed Optional integer from 1-8 that represents the speed
- EXAMPLES
  - camera focus near Focuses the camera near at the default speed camera focus far 8 Focuses the camera far at a speed of 8 camera focus stop Stops focus movement of the camera

## **Camera CCU**

- NAME
  - camera ccu get Gets the ccu settings
- SYNOPSIS
  - camera ccu get <key>
- DESCRIPTION Method used to get the ccu values of the connected camera
- OPTIONS
  - <key> all Gets all supported CCU information auto_white_balance Gets auto white balance red_gain Gets red gain value blue_gain Gets blue gain value backlight_compensation Gets backlight compensation auto_iris Gets auto-iris mode iris Gets iris value gain gain Gets gain value detail Gets detail value chroma Gets chroma value
- EXAMPLES
  - Camera *ccu* get iris Gets the iris value camera *ccu* get red gain Gets the red gain

## CCU Camera Scene

- NAME
  - camera ccu scene Stores or recalls the ccu scene
- SYNOPSIS
  - camera ccu scene {recall {factory [1-6]|custom [1-3]} | store custom [1-3]}
- DESCRIPTION
  - Method used to get or set the ccu scene
- OPTIONS
  - recall Recalls a *ccu scene*store Stores a custom *ccu scene*custom A custom *scene* (can be stored or recalled)
    factory A factory *scene* (can be recalled)
- EXAMPLES
  - camera ccu scene recall factory 2 Recalls the factory scene stored at index 2







## Camera CCU Set

- NAME
  - camera ccu set Sets and gets the CCU Settings SYNOPSIS
    - camera ccu set <key> <value>
- DESCRIPTION
  - Method used to sets the ccu values
  - OPTIONS <kev>

<key>
auto_white_balance Sets auto white balance to {on/off}
red_gain <0-255> Sets red gain value
blue_gain <0-255> Sets blue gain value
Backlight_compensation Sets backlight compensation {on/off}
auto_iris Sets auto iris {on/off}
iris Sets iris value <0-13>
gain Sets gain value <0-13>
detail Sets detail value <0-15>
chroma Sets chroma value <0-14>

- EXAMPLES
  - camera *ccu* set auto iris off camera *ccu* set red gain 10 Sets the red gain to be 10

## **Camera Standby**

- NAME
  - camera standby
- SYNOPSIS
  - camera standby { on | off | toggle }
- DESCRIPTION
  - Method used to put the camera in and out of standby
    - OPTIONS
      - <key>
        - on put the camera into standby mode
        - off put the camera out of standby mode toggleswitches the standby mode state
- EXAMPLES

camera standby off camera standby on

## **History**

- NAME
  - history command history
- SYNOPSIS
  - history [limit]
- DESCRIPTION

Since many of the programs read user input a line at a time, the command **history** is used to keep track of these lines and also recall historic information

HISTORY NAVIGATION

The command **history** can be navigated using the up and down arrow keys. The up arrow will move up a single entry in the command **history** while the down arrow moves down in the command **history**.

HISTORY EXPANSION

The command **history** supports the expansion functionality from which previous commands can be recalled from within a single session. History expansion is performed immediately after a complete line is read.

Listed below are examples of history expansion:

- * !! Substitute the last command line.
- * IN Substitute the Nth command line (absolute as per 'history' command)
- * !-N Substitute the command line entered N lines before (relative)
- EXAMPLES
  - history Displays the current command buffer

history 5 - Sets the history command buffer to remember the last 5 unique entries

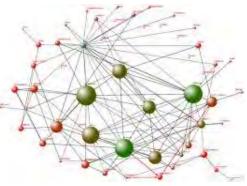




## **Network Settings**

- NAME
  - network settings get current network settings
  - SYNOPSIS
    - network settings {get}
- DESCRIPTION
  - Method used to get the current **network** settings of the device
- OPTIONS
  - get Get the current network settings for the machine
- EXAMPLES

network settings get MAC Address: 00:04:a3:85:0a:ee IP Address: 10.10.8.116 Netmask: 255.255.255.0 Gateway: 10.10.8.100 Returns the current network settings for mac addres, ip address, netmask, and gateway



## **Network Ping**

- NAME
  - network ping send ICMP ECHO_REQUEST to network hosts
- SYNOPSIS
  - network ping [count <count>] [size <size>] <destination-ip>
- DESCRIPTION

Use the ICMP protocol's mandatory ECHO_REQUEST datagram to elicit an ICMP ECHO_RESPONSE from a host or gateway. ECHO_REQUEST datagrams have an IP and ICMP header, followed by a struct timeval and then an arbitrary number of pad bytes used to fill out the packet.

• OPTIONS

*count* Stop after sending *count* ECHO_REQUEST packets. With deadline option, *ping* waits for *count* ECHO_REPLY packets, until the timeout expires. The default is 5.

destination The destination IP address where the ECHO_REQUESTS are sent

size The data size of the ICMP packet to send. The default is 56 bytes

EXAMPLES

network ping 192.168.1.1 Attempt to send 5 ICMP ECHO_REQUESTs with data *size* 56 to the host at 192.168.1.1 network ping count 10 size 100 192.168.1.1 Attempt to send 10 ICMP ECHO_REQUESTs with data *size* of 100 to the host at 192.168.1.1

## System Factory-Reset

- NAME
  - system factory-reset Gets or sets factory reset status
- SYNOPSIS
  - system factory-reset {get|on|off}



DESCRIPTION

Method used to get or set the factory reset status

- OPTIONS
  - get Get the current factory reset status
  - on Enable factory reset on reboot
  - off Disable factory reset on reboot
- EXAMPLES

system factory-reset get

factory-reset (software):

off

factory-reset (hardware): [Hardware reset is designated by rear panel DIP switches in down position] off

Returns the factory reset status

System factory-reset on factory-reset (software): on factory-reset (hardware): off Enables factory reset upon reboot



## System Reboot

- NAME
  - system reboot Reboots system
- SYNOPSIS
   system reboot [<seconds>]
- DESCRIPTION
  - Method used to reboot system
  - OPTIONS
    - seconds
      - The number of seconds to delay the reboot
- EXAMPLES reboot Reboot system immediately reboot 30 Reboot the system in 30 seconds

## Help

.

- NAME
  - help display an overview of the CLI syntax SYNOPSIS
- help
  - DESCRIPTION Display an overview of the command line syntax



## Version

- NAME
  - version display the system version information SYNOPSIS
- version
- DESCRIPTION
  - Display an overview of the command line syntax **EXAMPLES** 
    - version Returns the current software version

## Exit

- NAME
- exit
- SYNOPSIS
   exit
- DESCRIPTION

Ends the current API command session. If the session is over telnet, the session is ended and the socket is closed. If the session is over serial, a new session is started.



# COMPLIANCE AND CE DECLARATION OF CONFORMITY - ROBOSHOT HDMI CAMERAS

- Compliance testing was performed to the following regulations:
   FCC Part 15 (15.107, 15.109), Subpart B
- ICES-003. Issue 4: 2004
- ICES-003, ISSUE 4: 2004
- EN 55022 A: 2006 + A1: 2007
   KN24 2008 (CISER 24: 4007 4
- KN24 2008 (CISPR 24: 1997 + A1: 2000 + A2: 2002)
- KN22 2008 (CISPR 22: 2006)
- EMC Directive 2004/108/EC
- EN 55024: A2: 2003
- IEC 60950-1:2005 (2nd Edition); Am 1:2009
- EN 60950-1:2006+A11:2009+A1:2010+A12:2011



#### FCC Part 15 Compliance

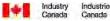
Class A Safety Safety



This equipment has been tested and found to comply with the limits for a Class A digital device, pursuant to Part 15, Subpart B, of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference when the equipment is operated in a commercial environment. This equipment generates, uses, and can radiate radio frequency energy and, if not installed and used in accordance with the instruction manual, may cause harmful interference to radio communications. Operation of this equipment in a residential area is likely to cause harmful interference in which case the user will be required to correct the interference at his/her own expense.

Operation is subject to the following two conditions: (1) This device may not cause interference, and (2) This device must accept any interference including interference that may cause undesired operation of the device.

Changes or modifications not expressly approved by Vaddio can affect emission compliance and could void the user's authority to operate this equipment.



#### **ICES-003** Compliance

This digital apparatus does not exceed the Class A limits for radio noise emissions from digital apparatus set out in the Radio Interference Regulations of the Canadian Department of Communications.

Le présent appareil numérique n'emet pas de bruits radioélectriques dépassant les limites applicables aux appareils numeriques de la classe A préscrites dans le Règlement sur le brouillage radioélectrique édicte par le ministère des Communications du Canada.

## **C E** European Compliance

This product has been evaluated for Electromagnetic Compatibility under the EMC Directive for Emissions and Immunity and meets the requirements for a Class A digital device. In a domestic environment this product may cause radio interference in which case the user may be required to take adequate measures.

#### Standard(s) To Which Conformity Is Declared: EMC Directive 2004/108/EC

EN 55022:2010

## EN 55024: 1998 + Amendments A1: 2001 + A2: 2003

- EN 61000-4-2: 1995 + Amendments A1: 1998 + A2: 2001
- EN 61000-4-3: 2006 + A1: 2008
- EN 61000-4-4: 2004 + Corrigendum 2006
- EN 61000-4-5: 2006
- EN 61000-4-6: 2009
- EN 61000-4-8: 2010
- EN 61000-4-11: 2004

## KN24 2008 (CISPR 24: 1997 + A1: 2000 + A2: 2002)

- EN 61000-4-2
- EN 61000-4-3
- EN 61000-4-4
- EN 61000-4-5
- EN 61000-4-6
- EN 61000-4-8
- EN 61000-4-11

IEC 60950-1:2005 (2nd Edition); Am 1:2009 EN 60950-1:2006+A11:2009+A1:2010+A12:2011 Conducted and Radiated Emissions Immunity Electrostatic Discharge Radiated Immunity **Electrical Fast Transients** Surge Immunity Conducted Immunity Power Frequency Magnetic Field Voltage Dips, Interrupts and Fluctuations IT Immunity Characteristics Electrostatic Discharge **Radiated Immunity Electrical Fast Transients** Surge Immunity Conducted Immunity Power Frequency Magnetic Field Voltage Dips, Interrupts and Fluctuations Safety Safety



#### WARRANTY INFORMATION

(See Vaddio Warranty, Service and Return Policies posted on vaddio.com for complete details):

**Hardware*** **Warranty:** Two (2) year limited warranty on all parts and labor for Vaddio manufactured products. Vaddio warrants its manufactured products against defects in materials and workmanship for a period of two years from the day of purchase, to the original purchaser, if Vaddio receives notice of such defects during the warranty. Vaddio, at its option, will repair or replace products that prove to be defective. Vaddio manufactures its hardware products from parts and components that are new or equivalent to new in accordance with industry standard practices.

**Exclusions**: The above warranty shall not apply to defects resulting from improper or inadequate maintenance by the customer, customers applied software or interfacing, unauthorized modifications or misuse, mishandling, operation outside the normal environmental specifications for the product, use of the incorrect power supply, modified power supply or improper site operation and maintenance. OEM and Special Order products manufactured by other companies are excluded and are covered by the manufacturer's warranty.

**Vaddio Customer Service**: Vaddio will test, repair, or replace the product or products without charge if the unit is under warranty. If the product is out of warranty, Vaddio will test then repair the product or products. The cost of parts and labor charge will be estimated by a technician and confirmed by the customer prior to repair. All components must be returned for testing as a complete unit. Vaddio will not accept responsibility for shipment after it has left the premises.

Vaddio Technical Support: Vaddio technicians will determine and discuss with the customer the criteria for repair costs and/or replacement. Vaddio Technical Support can be contacted through one of the following resources: e-mail support at support @vaddio.com or online at vaddio.com.

**Return Material Authorization (RMA) Number:** Before returning a product for repair or replacement request an RMA from Vaddio's technical support. Provide the technician with a return phone number, e-mail address, shipping address, product serial numbers and original purchase order number. Describe the reason for repairs or returns as well as the date of purchase. See the General RMA Terms and Procedures section for more information. RMA's are valid for 30 days and will be issued to Vaddio dealers only. End users must return products through Vaddio dealers. Include the assigned RMA number in all correspondence with Vaddio. Write the assigned RMA number clearly on the shipping label of the box when returning the product. All products returned for credit are subject to a restocking charge without exception. Special Order product are not returnable.

**Voided Warranty**: The warranty does not apply if the original serial number has been removed or if the product has been disassembled or damaged through misuse, accident, modifications, use of incorrect power supply, use of a modified power supply or unauthorized repair.

**Shipping and Handling**: Vaddio will not pay for inbound shipping transportation or insurance charges or accept any responsibility for laws and ordinances from inbound transit. Vaddio will pay for outbound shipping, transportation, and insurance charges for all items under warranty but will not assume responsibility for loss and/or damage by the outbound freight carrier. If the return shipment appears damaged, retain the original boxes and packing material for inspection by the carrier. *Contact your carrier immediately.* 

Products not under Warranty: Payment arrangements are required before outbound shipment for all out of warranty products.

## **Other General Information:**

### **Care and Cleaning**

Do not attempt to take this product apart at any time. There are no user-serviceable components inside.

- Do not spill liquids in the product
- Keep this device away from food and liquid
- For smears or smudges on the product, wipe with a clean, soft cloth
- Use a lens cleaner on the lens...
- Do not use any abrasive chemicals.

#### **Operating and Storage Conditions:**

Do not store or operate the device under the following conditions:

- Temperatures above 40°C (104°F) or temperatures below 0°C (32°F)
- High humidity, condensing or wet environments
- In inclement weather
- Between converging tectonic plates
- Dry environments with an excess of static discharge
- Within the Thermosphere (temperature issue)
- Under severe vibration



Unintentionally Mostly Blank



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