# User manual DAS1800 High Speed Modular Data Acquisition Recorder







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-Chapter 1

## Safety and symbols

To ensure proper use of the unit, please observe the safety and operating requirements described in this manual. Specific warning signals appear throughout this manual to draw your attention to important points. Please read the following instructions in this chapter carefully before using your Data Acquisition System. The table below describes the symbols used on the device.

Symbol	Description
$\triangle$	Warning
<u> </u>	Earth ground
,	Chassis ground
	Earth terminal
	Direct current (DC)
$\sim$	Alternating and direct current (AC and DC)
<b>(</b>	Consult the user manual

Table 1.1: Symbols on the device

The table below describes the symbols used in this manual:

Symbol	Description
	Warning of a danger to the user
6	Important operating information
Ŷ	General tip

Table 1.2: Symbols in the manual



Before powering up the device :

- Read and understand the safety and operating information in this manual.
- Follow all listed safety precautions.
- Operating the instrument with the wrong supply voltage voids the warranty
- Make all connections to the instrument before switching it on.
- Do not use the instrument in any way not specified in this manual or by SEFRAM. Failure to observe these precautions or warnings elsewhere in this manual constitutes a violation of the safety standards relating to the design, manufacture and intended use of the instrument. SEFRAM assumes no responsibility for any failure by the customer to comply with these requirements.

## 1.0.1 Category rating

IEC 61010 defines safety categories that specify the amount of electrical energy available and the surges that can occur on the electrical conductors associated with these categories. The category index is a Roman numeral from I, II, III or IV. This classification is also accompanied by a maximum voltage, which defines the expected voltage pulses and required insulation distances. The categories are as follows :

- Category I (CAT I) : defines measuring instruments whose measurement inputs are not intended to be connected to the mains. Environmental voltages are generally derived from an energy-limited transformer or battery.
- Category II (CAT II) : defines measuring instruments whose measurement inputs are intended to be connected to the mains supply via a standard wall socket or similar sources. Examples include portable tools and household appliances.
- Category III (CAT III) : defines measuring instruments whose measurement inputs are intended to be connected to a building's electrical network. Examples include measurements inside a building's electrical panel, or the wiring of permanently installed motors.
- Category IV (CAT IV) : defines measuring instruments whose measurement inputs are intended to be connected to a building's primary power supply or other external wiring.



Do not use this instrument in an electrical environment with a higher category than that specified in this manual. You must ensure that each accessory used with this instrument has a category classification equal to or higher than that of the device to maintain the category classification of the instrument. Failure to do so will reduce the category classification of the measuring system.

## 1.0.2 Power supply

This instrument is designed to be powered from a CATEGORY II main power supply environment. The main power supply must be 110 V RMS or 240 V RMS. Use only the power cord supplied with the instrument, and make sure it is suitable for your country of use.



If smoke is produced when the unit is switched on, unplug the power cord from the mains socket and any cables connected to the unit, and contact B&K Precision or Sefram Technical Service.

### 1.0.3 Ground the instrument



To minimize the risk of electric shock, the chassis of the instrument must be connected to a safety ground. The instrument is earthed via the earth conductor of the supplied power cable, which must be plugged into an approved three-conductor electrical socket. The power plug and the power cable coupling plug comply with IEC safety standards. Do not tamper with or disable the ground connection. Without the safety ground connection, all accessible conductive parts (including control buttons) may cause electric shock. If the unit is battery-powered, you must connect the chassis to earth when using it. Failure to use an approved, properly earthed plug and the supplied power cable may result in injury or death.

### 1.0.4 Do not operate instrument if damaged



If the instrument is damaged, appears to be damaged, or if any liquid, chemical or other material is found on or inside the instrument, remove the power cord from the instrument, remove the instrument from service, label it for further use and return it to SEFRAM for repair. Notify Sefram or B&K Precision of the nature of any contamination of the instrument.

### 1.0.5 Clean the instrument only in accordance with the instructions

Do not clean the instrument, its switches or terminals with abrasive cleaners, lubricants, solvents, acids/bases or other chemicals. Clean the instrument only with a clean, lint-free cloth. This instrument is not authorized for use as a component in a life-support device.

### 1.0.6 Servicing



The instrument housing must not be disassembled by operating personnel. Component replacements and internal adjustments must be carried out by qualified maintenance personnel trained in the risks involved when instrument covers and screen are removed.

Under certain conditions, even with the power cord removed, dangerous voltages may exist when covers are removed. To avoid injury, always unplug the power cord from the instrument, disconnect all other connections (measurement leads, computer interface cables, etc.), discharge all circuits and check that no dangerous voltages are present on conductors by using a voltage detection device in good working order before touching internal parts. Check that the voltage sensing device is working properly before and after measurements by testing with known voltage sources and by testing AC and DC voltages. Do not insert any objects into the ventilation or other openings of the instrument. In the event of a fault, dangerous voltages may be present at unexpected points in the circuits under test. Fuse replacement must be carried out by qualified service personnel trained in the instrument's fuse requirements and safe replacement procedures. Disconnect the instrument from the power line before replacing fuses. Replace fuses only with new ones of the types, voltage ratings and current ratings specified in this manual or on the back of the instrument. Failure to do so may result in damage to the instrument, a safety hazard or fire. Failure to do so will void the warranty. Do not substitute parts not approved by SEFRAM or modify this instrument. Return the instrument to Sefram or B&K Precision for service and repair to ensure that safety and performance characteristics are maintained.

### 1.0.7 Operating environment

The instrument is designed for use in pollution degree 2 indoor environments. The operating temperature range is 0 to 40 degrees Celsius and a relative humidity of 20% to 80%, non-condensing at an altitude < 2000 meters.

Measurements taken with this instrument may be out of specification if the instrument is used in environments that may include rapid changes in temperature or humidity, sunlight, mechanical vibration and/or shock, acoustic noise, electrical noise, strong electric fields or strong magnetic fields.



- Do not use in explosive or flammable environments (ATEX).
- Do not use the instrument in the presence of flammable gases or vapors, fumes or fine particles.
- In relative humidity conditions outside instrument specifications.
- In environments where there is a risk of liquid spillage onto the instrument, or where liquid may condense on the instrument.
- In air temperatures exceeding specified operating temperatures.
- In atmospheric pressures outside specified altitude limits, or where the surrounding gas is not air.
- In environments with restricted cooling air flow, even if air temperatures are within specifications.
- · In direct sunlight.

### 1.0.8 Particular precautions

- Do not use this product for purposes other than those for which it is intended.
- To avoid electric shock, observe the following precautions when working with dangerous voltages:
- Before using the recording device, make sure that the instrument and the equipment required for its use (measuring lead, external box, accessories...) are in working order. Check cables for damage.
  - The instrument may only be used within the specified measuring ranges.
  - The instrument may only be used in the measurement circuit category for which it has been designed.
  - The instrument complies with EMC EN 61326. Otherwise, in rare cases, it may happen that an electrical device is disturbed by the electrical field of the instrument, or that the instrument is disturbed by an electrical device.
  - The instrument may only be operated by qualified personnel.
  - The test leads used to connect the instrument to the test points must comply with the standard.
  - To avoid the risk of shock, do not connect or disconnect measuring leads when they are connected to a source of electrical voltage.
  - Safety is no longer guaranteed if the instrument is modified or tampered with.
  - Do not place heavy objects on the instrument.
  - Do not block the flow of cooling air to the instrument.
  - Do not place a hot soldering iron on the instrument.
  - Do not pull on the instrument with the power cord or measuring leads connected.

Safety is not guaranteed in these cases, for example :

- · Damage to the instrument
- · After dropping the instrument
- · Instrument measurements/tests that cannot be performed
- · Unfavorable conditions over an extended period
- · Damage during transport
- · Battery leak

## 1.0.9 Concerning the exported devices in North America



This equipment has been tested and found to comply with the limits for a Class A digital device, pursuant to part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference when the equipment is operated in a commercial environment. This equipment generates, uses, and can radiate radio frequency energy and, if not installed and used in accordance with the instruction manual, may cause harmful interference to radio communications. Operation of this equipment in a residential area is likely to cause harmful interference in which case the user will be required to correct the interference at his own expense.

Changes or modifications not expressly approved by SEFRAM or B&K Precision could void the user's authority to operate the equipment.

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## -Chapitre 2-

## Introducing the device

## 2.1 | Introduction

SEFRAM thanks you for your confidence in us and is pleased to present the DAS1800. This new-generation multichannel Data Acquisition System is developed and manufactured in France. Its ability to record and analyze all types of electrical signals (sensors, electrical relays, electrical networks, etc.) makes it ideal for a wide range of industrial applications (maintenance, R&D, production, etc.). The choice of "à la carte" acquisition configurations gives the system great versatility, with the ability to capture microsecond events.

## 2.2 | Device description

The DAS1800 is a measurement system that can integrate up to 10 data acquisition modules in total, each with 4 or 8 analog measurement channels depending on type. The adjustable handle makes it easy to carry, and can be used as a kickstand when the unit is tilted.



FIGURE 2.1 : General views

## 2.2.1 Supplied accessories

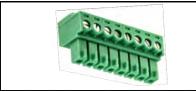
The device is provided with :



Main power cord (IEC)



Sub-D15 HD connector (x1)





Carrying case



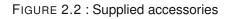
Sub-D25 connector (x1)



8-pin connector for external power supply output 4-pin connector (x8) (with multiplexed board)

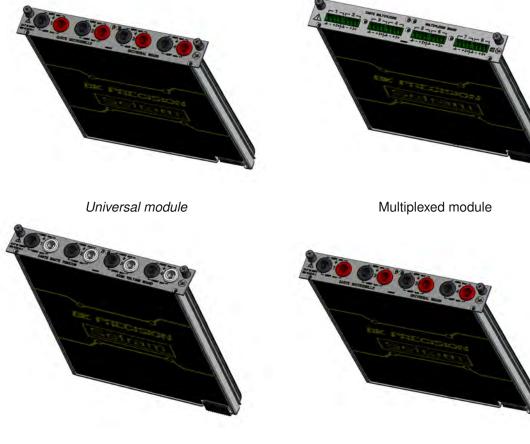


Pair of male banana plug connectors (x4) (for universal and high-voltage acquisition boards)



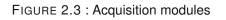
## 2.2.2 Acquisition modules

When ordering the device, you can choose from four different types of modules : universal, multiplexed, high-voltage or high-impedance. Each has its own technical characteristics (see technical specifications section for details).



High voltage module

High impedance module



Specifications	Universal board	Multiplexed board	High voltage board	High impedance board
Number of channels	4 isolated single-pole channels	8 non-isolated differential channels	4 isolated differential channels	4 isolated single-pole channels
Maximum voltage	+/- 600V DC or 424V RMS	+/- 48V DC	+/- 1000V DC or 424V RMS	+/- 600V DC or 424V RMS
Maximum sampling rate	1MSa/s	5Sa/s	1MSa/s	1MSa/s
Bandwith	100kHz	1kHz	30 kHz	70 kHz
Input impedance	1MOhms	2MOhms	10MOhms	10MOhms
Safety catefory	CAT III 600V	CAT I 48V	CAT III 1000V / CAT IV 600V	CAT III 600V

TABLE 2.1 : Specifications

## 2.2.3 Interfaces

The various device interfaces are shown in the following diagrams :

Sefram



FIGURE 2.4 : View from above	FIGURE 2.4	:	View from	above
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Symbol	Description
(1)	On/off push-button
(2)	Ethernet port for connecting the device to a computer network (x2) (see remote control section)
(3)	HDMI port for transferring the screen display to an external display
(4)	USB port for connecting mouse, keyboard, USB sticks or Wi-Fi (option) (x4)
(5)	Acquisition boards

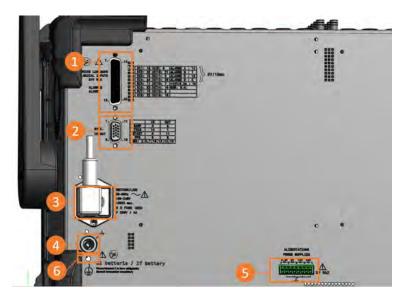


FIGURE 2.5 : Interfaces vue arrière

Symbol	Description
(1)	Sub-D25 connector for logical channel inputs and outputs (see logical channels section)
(2)	Sub-D15 connector for external synchronization (See external synchronization section)
(3)	Power supply
(4)	Chassis ground connector
(5)	External power supply
(6)	Protective earth terminal (battery operation)

## 2.2.4 Optional accessories

Optional accessories are listed below :

- Logic channel box : allows logic inputs/outputs to be transferred to an external module, increasing the maximum permissible voltage.
- · Logic channel cable : allows inputs/outputs to be remotely connected to a standard banana plug cable
- Wi-Fi dongle : enables remote control or file transfer via Wi-Fi connection (available soon)

## 2.2.5 Factory option

- GPS/IRIG input : allows the instrument to be time-synchronized with a GPS/IRIG signal (available soon)
- · Battery option : allows the instrument to work without power cord to a electrical grid

A battery charge status LED is present on the device.



FIGURE 2.6 : Battery LED

Status	Description
Off	No battery connected or insufficient mains supply
On continuously	Battery fully charged
Blinking at 0.5 Hz	The battery is charging
Blinking at 2.5 Hz	Battery error

## 2.3 | Interface and ergonomic

## 2.3.1 Touch control

The product is designed for smartphone-type touch screen use. The following movements are implemented:

- · Single tap: performs an action
- Drag & drop: moves graphic objects
- 2-finger zoom
- · Long press: displays a help tooltip

## 2.3.2 Sounds

Sound notifications indicate:

- Product startup
- Click for feedback
- · Recording start and end

## 2.4 | Interface layout

## 2.4.1 Navigation

Navigation on the device is via the menu bars at the top of the page (main and secondary).

### 2.4.2 Status

The bar at the bottom indicates the device status:

- Registration status
- Error messages
- Date and time

## 2.4.3 Notifications

Notifications are classified into 2 levels of importance :

- High importance: a warning window opens in the center of the page. A user action is required to make it disappear. They are used for configuration or hardware errors.
- Low importance: a message bar appears at the top of the screen and disappears after a few seconds. It notifies the user of product events (end of recording, file saving, etc.).

## 2.4.4 User fields

The value of a user field is taken into account as soon as editing is complete. No further validation is required. When the value is incorrect, a red error message informs the user that the current value is invalid.

## 2.5 | Built-in help

## 2.5.1 Tool type

When you long-click on a button, a tooltip displays help on the corresponding action.

### 2.5.2 Help window

Clicking on the question mark icon opens a help window.

### 2.5.3 On-board user manual

The user manual is embedded in the product and available from any page by clicking on the manual button in the main menu bar at the top of the page.

## 2.5.4 Help video

Help videos are available from the "Home" page.

### 2.5.5 Step-by-step guides

Step-by-step guides are available on the "Home" page, to help you get the most out of your product.

## -Chapitre 3-

## **Getting started**

## 3.1 | Installing and removing acquisition modules



Module installation and removal must be carried out with the power off. When doing so, switch off the device and ensure that no cables are connected to the module inputs.

#### Add an acquisition module :

The module plugs into the device as a simple way. Simply follow the keyed connection (1) and guide the module to the backplane to connect to the connector (2). Press to ensure a good connection. Once connected, use a Phillips screwdriver to tighten the two screws on either side of the module (3).



Modules are detected at startup.



FIGURE 3.1 : Add an acquisition module

#### Remove an acquisition module :

To remove an acquisition module, loosen the two screws on either side of the board (3). Pull on the module to disconnect it.

## 3.2 | File creation

Before starting a measurement campaign, we recommend that you organize your files in advance. To do this, go to "File Manager" in the navigation bar.

HOME	CONFIGURATION	Po REALTIME	RECORDINGS	START RECORDING	o 💷 🕯
C REFRESH		Current folder: /			
Quick access	Name		Size Modified at		
A ROOT	<b>D</b> .	-	20 Items 10/16/23 3:19 PM		
	internalDisk	-(1)	13 Items 10/18/23 8:03 AM	0	
/internaldisk/	sdb1	-2	7 Items	D	
/internaldisk		-			
ψ USB Vedb1	]				
VEDDT	1				
▲ EJECT USB DRIVE					
				<b>▼</b> Fifters	
				▼ Fitters All files (* Storage	

#### Figure 3.2: File Manager

"sda1" (solid drive a1) (1) corresponds to the contents of the device's disk memory. It is also available by pressing "DISK" (4). If a USB stick is connected to the device, then a "sdb1" folder will be displayed, and will be available from this page. The contents of the USB stick are also available by pressing "USB" (5). You can also access the contents of the working directory (3).

### 3.2.1 Working directory

To create a measurement campaign folder and define it as a working directory, go to the disk memory folder "sda1".



The working directory is the defined location where all files (measurement records, configuration files, screenshots, bug reports) will be saved. Several folders can be created, but only one folder can be defined as the working directory at a time. It is not possible to define a folder on a USB stick as a working directory. By default, files are placed at the root of the hard disk:

C RERESH         D MARKI FOLDER         Current folder, /internalDisk           wick access         Nume         Star         Moduled at         Image: 10/17/23 1/42 PM         Image: 10/17/23 1/42 PM           ROOT         Image: 10/17/23 1/42 PM         Image: 10/17/23 1/44 PM	1 🔒 номе	CONFIGURATION Po REALTIME	IDINGS 🗁 FILE MANAGER	START RECORDING	o 💷
NOT         Image: Construction of the construction of	C REFRESH	PARENT FOLDER Current folder: /internalDisk			~
WORKNO DIRECTORY       Myrecordcampaign       13 Items       10/17/23 1/4 PM       Image: Constraint of the second se	ck access	Name	Size Modified at	0	Ac folder
Image: Second File 23:10.06.07,54.29,827 bmp       593 MB       10/6/237.54 AM       Image: Second File 23:10.18,08,04,59,55 bmp         US8       23,10,18,08,04,50,089 bmp       593 MB       10/18/23 8.03 AM       Image: Second File 23:10,08,00,07,527 bmp         US8       23,10,18,08,00,45,00,27,507 bmp       593 MB       10/18/23 8.04 AM       Image: Second File 23:10,05,00,27,36,046 mf4       Second File 23:10,05,00,27,36,046 mf4       683 MB       10/10/23 9.128 AM       Image: Second File 23:10,11,07,24,10,11,13,50,049 mf4       Second File 23:10,11,07,24,10,11,13,50,049 mf4       Second File 23:10,11,07,24,10,11,13,50,049 mf4       Second File 23:10,11,07,24,10,11,11,13,50,049 mf4       Second File 23:10,11,07,24,10,11,11,11,10,10,11,11,10,10,11,11,10,10	ROOT	<b>1</b>	3 items 10/17/23 1:42 PM	<b>a</b>	CREATE FOLDER HERE
Disk.       23,10,06,07,54,29,227,5mp       593 MB       10/6/23,754 AM       I         Disk.       23,10,18,06,03,45,855 bmp       593 MB       10/18/23 803 AM       I         USB       23,10,18,06,04,50,089 bmp       593 MB       10/18/23 803 AM       I         USB       23,10,18,09,00,47,527 bmp       593 MB       10/18/23 804 AM       I         ELECT USB DRIVE       MecordFile,231045,09,27,36,046 mf4       683 MB       10/5/23 927 AM       I         ELECT USB DRIVE       MecordFile,231041,07,24,10,134 mf4       625 GB       10/11/23 743 AM       I         MecordFile,231041,07,24,10,134 mf4       625 GB       10/16/23 301 PM       I       I         MecordFile,231041,07,24,00,16 mf4       653 76 KB       10/16/23 301 PM       I       I         MecordFile,231041,07,24,00,16 mf4       655 76 KB       10/16/23 310 PM       I       I         MecordFile,231041,07,14,00,2308 mf4       605 76 KB       10/16/23 317 PM       I       I         MecordFile,231041,07,09,50,48,275 mf4       50.66 MB       10/17/23 9.51 AM       I       I		Myrecordcampaign	13 Items 10/13/23 3:12 PM	D	E) SET AS WORKING
Manualsk		23_10_06_07_54_29_827.bmp	5.93 MB 10/6/23 7:54 AM	D	
USB Instrume         533 MB         10/18/23 900 AM         Image: Imag		23_10_18_08_03_45_855.bmp	5.93 MB 10/18/23 8:03 AM	D	
M <sup>3</sup> 23,10,18,09,00,47,527 bmp       593 MB       10/18/23 900 AM       □         JECT USB DRIVE       RecordFile,231005,09,27,36,046 mf4       6.83 MB       10/5/23 927 AM       □         JECT USB DRIVE       RecordFile,231010,11,13,50,049 mf4       5.93 MB       10/16/23 918 AM       □         JECT USB DRIVE       RecordFile,231011,07,24,10,134 mf4       525 GB       10/17/23 743 AM       □         M       RecordFile,231016,16,55,51,793 mf4       2       996,47 kB       10/16/23 301 PM       □         M       RecordFile,231016,17,02,09,016 mf4       683 98 kB       10/16/23 302 PM       □         M       RecordFile,231016,17,02,09,016 mf4       6057 6k B       10/16/23 310 PM       □         M       RecordFile,231016,17,10,02,308 mf4       6057 6k B       10/16/23 310 PM       □         M       RecordFile,231016,17,10,07,34 mf4       6057 6k B       10/16/23 310 PM       □         M       RecordFile,231016,17,10,10,714 mf4       839 MB       10/16/23 317 PM       □         M       RecordFile,23107,00,90,90,48,275 mf4       50.65 MB       10/17/23 951 AM       □	JSB	23_10_18_08_04_50_089.bmp	5.93 MB 10/18/23 8:04 AM	a	
DECT USB DRIVE         RecordFile.23.10-10.11.13.50_049 mt4         3.97 GB         10/10/23 918 AM         □           Machine         625 GB         10/11/23 7.43 AM         □           RecordFile.23.10-11.07.24.10_134 mt4         625 GB         10/11/23 7.43 AM         □           RecordFile.23.10-11.07.24.10_134 mt4         625 GB         10/11/23 7.43 AM         □           RecordFile.23.10-16_16_55_51_793 mt4         996.47 kB         10/16/23 301 PM         □           RecordFile.23.10-16_17_02_09_016 mt4         683.98 kB         10/16/23 302 PM         □           RecordFile.23.10-16_17_10_0_730 mt4         605 76 kB         10/16/23 310 PM         □           RecordFile.23.10-16_17_10_0_734 mt4         605 76 kB         10/16/23 310 PM         □           RecordFile.23.10-16_17_10_0_734 mt4         605 76 kB         10/16/23 317 PM         □           RecordFile.23.10-17_09_50_48_275 mt4         50.65 MB         10/17/23 951 AM         □		23_10_18_09_00_47_527.bmp	5.93 MB 10/18/23 9:00 AM		
RecordFile.23:10:11_07.24_10_134.mt4       625 68       10/17/23 7.43 AM       □         RecordFile.23:10:16_15_5_5_1793.mt4       996.47 kB       10/16/23 301 PM       □         RecordFile.23:10:16_17_02_09_016.mt4       996.47 kB       10/16/23 301 PM       □         RecordFile.23:10:16_17_02_09_016.mt4       683.98 kB       10/16/23 302 PM       □         RecordFile.23:10:16_17_10_02_308 mt4       605 76 kB       10/16/23 310 PM       □         RecordFile.23:10:16_17_10_07_14mt4       839 MB       10/16/23 317 PM       □         RecordFile.23:10:17_09_50_48_275 mt4       50.65 MB       10/17/23 951 AM       □		RecordFile_23-10-05_09_27_36_046.mf4	6.83 MB 10/5/23 9:27 AM		
RecordFile.23-10-16.15.55.51_793 mt4       996.47 kB       10/16/23 301 PM       □         RecordFile.23-10-16.17_02_09_016 mt4       683.98 kB       10/16/23 302 PM       □         RecordFile.23-10-16.17_02_09_016 mt4       683.98 kB       10/16/23 302 PM       □         RecordFile.23-10-16.17_02_09_016 mt4       683.98 kB       10/16/23 310 PM       □         RecordFile.23-10-16.17_10_02_308 mt4       605.76 kB       10/16/23 310 PM       □         RecordFile.23-10-16.17_10_07.14 mt4       839 MB       10/16/23 317 PM       □         RecordFile.23-10-17_09_50_48_275 mt4       50.65 MB       10/17/23 951 AM       □	EJECT USB DRIVE	RecordFile_23-10-10_11_13_50_049.mf4	3.97 GB 10/10/23 9:18 AM		
RecordFile_23-10-16_17_02_09_016 m/4       683.98 kB       10/16/23 3:02 PM       □         RecordFile_23-10-16_17_10_02_308 m/4       605.76 kB       10/16/23 3:10 PM       □         RecordFile_23-10-16_17_10_02_308 m/4       83.99 MB       10/16/23 3:10 PM       □         RecordFile_23-10-16_17_10_10_714 m/4       8.39 MB       10/16/23 3:17 PM       □         RecordFile_23-10-17_09_50_48_275 m/4       50.65 MB       10/17/23 951 AM       □		RecordFile_23-10-11_07_24_10_134.mf4	6.25 GB 10/11/23 7:43 AM	a	
RecordFile_23-10-16_17_10_02_308 mt4         605.76 kB         10/16/23 3:10 PM         □           RecordFile_23-10-16_17_10_10_714 mt4         8.39 MB         10/16/23 3:17 PM         □           RecordFile_23-10-17_09_50_48_275 mt4         50.65 MB         10/17/23 9:51 AM         □		RecordFile_23-10-16_16_55_51_793.mf4	996.47 kB 10/16/23 3:01 PM	O	
RecordFile_23-10-16_17_10_10_714.mf4         8.39 MB         10/16/23 3:17 PM         I           RecordFile_23-10-17_09_50_48_275 mf4         50.65 MB         10/17/23 9:51 AM         I		RecordFile_23-10:16_17_02_09_016.mf4	683.98 kB 10/16/23 3:02 PM	0	
RecordFile_23-10-17_09_50_48_275.ml4 50.65 MB 10/17/23 9:51 AM		RecordFile_23-10-16_17_10_02_308.mf4	605.76 kB 10/16/23 3:10 PM	0	
		RecordFile_23-10:16_17_10_10_714.mf4	8.39 MB 10/16/23 3:17 PM	0	
Record Ella 23 10 17 (00 51 42 406 ml4 1 002 55 MR 10/17/23 9 52 4M		RecordFile_23-10-17_09_50_48_275.mf4	50.65 MB 10/17/23 9:51 AM	0	
		RecordFile_23-10-17_09_51_42_496.mf4	1,002.55 MB 10/17/23 9:52 AM	Q	
					T Filters
All files (*) •					Storage used - 2% 50 27 GB/1.74 TB

Figure 3.3: File creation

By default, screenshots (1) and measurement recordings (2) are at the root of the disk. Click on create a new folder, name and select it then click on "choose as working directory".

🗟 🏠 HOME	CONFIGURATION	Po REALTIME	RECORDINGS	DIRLEN	IANAGER	START RECORDING	0	III 🔒 📋
C REFRESH	PARENT FOLDER C	urrent folder: /sda1						
Quick access	Name				Modified at		Actions on selec	cted items
n ROOT	4			1 Item	11 Sep 2023 11:48:49			
EI WORKING DIRECTORY	Test			2 Items	8 Sep 2023 07:22:50	, i	REMOVE	
🗩 DISK							COPY	2
ф usв							SET AS WOR	KING
▲ EJECT USB DRIVE								
							T Filters	
							All files (*)	
							Storage used	
No acquisition running							01 25 82 MB/884	1 <i>94 GB</i> 11 Sep 2023 12:58:44

Figure 3.4: File creation as working directory

## 3.3 | Channels and measurements

A channel corresponds to a physical input to the device. It is identified by its Alias, which corresponds to its position on the instrument. For example, channel B3 corresponds to channel number 3 on acquisition board B (i.e. the second board).

A measurement is a direct input or calculation derived from a physical channel.

The type of measurement available depends on the property being measured and configuration of the physical channel. Examples include RMS, average, minimum, maximum, derivative and integral.

## 3.4 | Analog channel settings

To access acquisition board analog channel settings, use the main navigation bar by tapping on Configuration then Channels.

Home	CONFIGURA	TION	Po REALTH	ME	RECORDINGS	FILE MANAGER	<b>.</b>	TART RECO	RDING		
leasurements realtime	CHANNELS		CO RECO	RDS	ALARMS	SYNC	REMOTE	1	MPORT EXPORT	😳 SYST	EM
+	N Analog	Y,	ine by care) All								
CLICK TO ADD MEASUREMENT	0/1 Digital			_							_
MEASONEMENT	🔬 All channels	\$= T	vpe, Sensor, M	lin, Max							
	Sensors library	Color	Position *	Name	Board	Sensor	Min		Max	Measuremento	Configu
	O Units library		AT	Ch_A1	Simulator	No_sensor_numeric_input	¢.	EI.	10	0	٠
	Calibration	0	A2	Ch_A2	Simulator	No_sensor_numeric_input	0	EI.	10	0	٠
	Wizard	0	A3	ch_A3	Simulator	No_sensor_numeric_input		E?		•	٠
			A4	Ch_A4	Simulator	No_sensor_numeric_input		EI.		•	٠
			81	Ch_B1	Universal	No_sensor_voltage_measurement	ÖV	£1	10V	•	٠
			82	Ch_B2	Universal	No_sensor_voltage_measurement	0V	Ð	10V	•	٠
			B3	Ch_B3	Universal	No_sensor_voltage_measurement		E?	10 V	•	٠
			84	Ch_B4	Universal	No_sensor_voltage_measurement	٥v	E.	104	•	٠
			-C1	Ch_C1	Multiplexed	No_sensor_voltage_measurement		E)		0	٠
rms 0 8 0 C 0 D 0			C2	Ch_C2	Multiplexed	No_sensor_voltage_measurement	ov	e	101	•	٠

FIGURE 3.5 : Analog channel settings

On this page you can view the table containing all the parameters of the analog channels. It's possible to filter the display of channels by acquisition board )present on the device (1), and to customize the display of information given in columns (2). Single-channel parameters are displayed as rows in the table (3). Most parameters can be edited from this table, allowing you to define all the settings required for your measurement. For example, referring to channel A1 in the table above (3) :

- The *Position* column corresponds to the physical location of the channel and in the device (e.g slot A, channel 1).
- The Name column corresponds to the channel name (editable).
- The Module column corresponds to the type of acquisition board installed.
- The *Sensor* column defines the physical parameter to be measured by the channel. The default value is voltage measurement. First define the unit, then the sensor.



By default, a choice of sensors is present in the sensor library. You can add new sensors as required by clicking on the pencil symbol that brings you to the Sensor libraries section.

The Min and Max columns define the range measured by the channel. It has an impact on measurement accuracy (see accuracy section for more details). The button automatically centers zero between Min and Max terminals (editable).

The *Measurement* column defines which measurements associated with the channel will be activated for viewing and/or recording. Once validated, they appear in the left pane of the screen (4). It is possible, for example, to record both the direct voltage and the RMS value of the same channel signal.

By pressing A in the *configure* column, you open the complete page of channel parameters shown above.



By pressing directly on a measurement in the left pane (4), you can delete it, access the channel parameters or access the recording frequency settings.



FIGURE 3.6 : Page configuration

Field (1) corresponds to the channel name, and you can also add a full description in field (2). In the same way as above, define the physical quantity (3) you are going to measure, then the sensor used (4). To add a sensor not present in the library, click on the "pencil" icon, and go to the sensor library section for more details. Define the measurement range to be displayed, which will define the upper and lower limits for the on-screen graph, and select the zero point.



Please note that if the measured value is outside these limits, it will not be displayed on the screen.

Define the measurements to be displayed and/or recorded in frame (6). Note that for the *frequency, counter and PWM* measurement, you need to set a detection threshold. For the *derivative and integral* measurement, be sure to define an integration period and amplitude (7), which are essential for calculation. The *Average, Min and Max* measurements (8) plot the signal's minimum and maximum average values over a defined time period. The drop-down menu (9) lets you define a low-pass filter, which is ideal for attenuating/removing electronic noise induced by external disturbances on your measurement. See "How to attenuate noise on my signal" for more details. Total bandwidth depends on the type of filter used. To apply a cutoff frequency before 100Hz, use the keyboard to define

a digital filter (software processing). Alternatively, apply a hardware filter (signal input processing) from a choice of 100Hz, 1000Hz or 10,000Hz.



By pressing the icon shown below, you can duplicate all the parameters of the selected channel to other channels on the device.





## 3.5 | Digital channels setting

Digital channels are accessible via the device's 25-pin D-Sub connector. To access digital channel settings, press Configuration > Channels > Digital.



The optional digital channel cable accessory allows all digital channels to be wired using standard banana plugs, giving you greater convenience when wiring your equipment.

CONFIGURATI	ON	Po REALTIN	ME 🔂	RECORDINGS 🗁 FILE MANAGER		🗧 STA	RT RECORDI	NG	o 🖽
de CHANNELS		RECO	RDS	🖸 ALARMS 👩 🟹 SYNC	REI REI	иоте	MP	ORT EXPOR	RT 🔅 SYSTEM
🚺 Analog	Color	Position 1	Name	Measurements	Configure	Connee	tor pino	ut	
1 Digital		VLOG1	Ch_Vlog1	0	۵	Pin No.	Name	Pin No.	Name
验 Ali channels		VLOG2	Ch_Vlog2	0	٠	1	Alarm B	14	Alarm A
### Sensors library		VL0G3	Ch_Vlog3	•	٠	2	Alarm D		Alarm C
Ω Units library		VLOG4	Ch_Vlog4	0	۰	3	GND	16	
Calibration		VLOG5	Ch_VlogS	•	٠	4	GND	17	
Wizard		VL0G6	Ch_Vlog6	•	•	5	GND	18	Vilog16
		VLOG7	Ch_Vlog7	•	•	6	Viog15	18	Viog14
		VLOG8	Ch_Vlog8	0	٠	7	Vlog13	20	Vlog12
		VLOG9	Ch_Vlog9	•	٠	8	Vlog11		Vlog10
		VLOG10	Ch_Vlog10	•	۰	9	Vlog9	22	Vlog8
		VL0G11	Ch_Vlog11	•	۰	10	Vlog7	23	Vlogé
		VLOG12	Ch_Vlog12	•	٠	11	Vlog5	24	Vlog4
		VLOG13	Ch_Vlog13	0	٠	12	Vinga	24	Vioga

FIGURE 3.8 : Digital channels table

On this page, you'll find a table showing all logic inputs. Each channel is shown as a row (1). The position column defines the corresponding pin on the physical connector. The complete connector schematic with associated pins is shown on the right-hand pane of the screen to guide your wiring (2). It consists of :

## 3.5.1 16 logic inputs (Vlog)

To open all the parameters of a digital input, press the symbol 🔯 from the measure colomn :



The logic inputs can monitor all signals up to 24V. To increase the maximum permissible voltage, the Logic channel box option 917008000 is available.



The switchover threshold is between 1,2V and 2,8V.

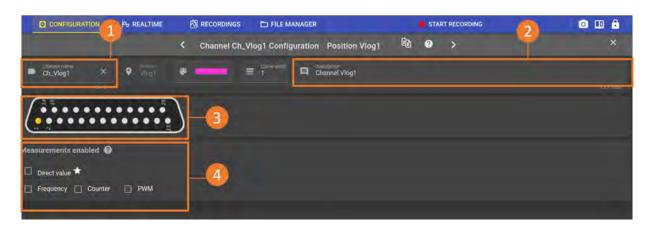


FIGURE 3.9 : Logic input channel parameters

Field (1) corresponds to the name of the digital channel; you can also add a description in field (2). The pin position on the connector is shown in diagram (3). Next, define the type of measurands to be displayed and/or recorded (4). Note that Frequency, Counter and PWM measurands will be available in a later version. You can also

activate measurements from the table 3.8 thanks to the button 🕒 from the *Mesurand colomn*.



By pressing the icon shown below, you can duplicate all the parameters of the selected logic input on other channels of the device :



FIGURE 3.10 : Copying logic input parameters

## 3.5.2 Power Supply Outputs

The external power supply located on the 25-pin D-Sub connector provides a nominal voltage of 12V +/- 5% with a maximum delivered current of 200 mA (limited by resettable fuse).



For example, the power supply can be used to power a sensor.

There are also 3 others power supply outputs (3.3V, 5V, 12V, 24V) on the rear pannel (5W maximum) :



## 3.5.3 Alarm outputs

To set the parameters for the 4 alarm outputs, please refer to the section on alarms setting.

## 3.6 | Recording measurements

## 3.6.1 Recording file configuration

Recording file configuration is available from the menu Configuration > Records > File info

#### File name

The file name is a string of characters. All alphanumeric characters are allowed, with the exception of the following characters: "/| ' : ? < >.

The file extension is .mf4 and is not configurable. It corresponds to the MDF4 (Measurement Data Format) recording format, standard ASAM (Association for Standardization of Measuring Systems).

#### Date suffix

If the box is checked, the file name will be automatically followed by the date and time of the start of recording (pressing the "Start recording" button, independently of any triggers) in the following format: \_yy-MM-dd\_HH\_mm\_ss\_zzz,

- yy  $\rightarrow$  Last 2 figures of the year
- $\rm MM \rightarrow issue of the month$
- dd  $\rightarrow$  day of the month
- + HH  $\rightarrow$  hours in 24h format
- mm  $\rightarrow$  minutes
- ss  $\rightarrow$  seconds
- \* zzz  $\rightarrow$  milliseconds

For example, if the filename is set to "RecordFile" and the "Suffix by date" box is checked, we could have a file called: RecordFile\_23-01-28\_15\_02\_28\_792.mf4 corresponding to a record from 28/01/2023 at 15:02:28.792.



Caution: If the "Suffix by date" function is deactivated, you must manually change the file name for each recording, otherwise the last recording will systematically overwrite the previous one and you will lose your data. We strongly recommend that you keep this function enabled to avoid any loss of recordings.

#### Recording file size or duration limit

In addition to triggers, it is also possible to add a limit to the recording file. This can be used, for example, to avoid obtaining a very large file if the event associated with the end-of-recording trigger is never reached.

If the "Enable record file size limit" checkbox is disabled, the DAS records for the maximum duration (available disk space).

If the box is checked, the user can configure the limit in 2 different ways:

- Memory size on disk → if the channel configuration changes (addition or deletion of measurements, change
  of recording frequency), the size limit will be retained and its equivalence in recording duration will be reevaluated
- Recording duration → if the channel configuration changes, the recording duration will be retained and the size of the recording file will be reassessed.
- Please note that if you add measurements or increase the recording frequency, the corresponding file size will increase while retaining the recording time. The system will then limit the size to the available disk space, and the recording time cannot be retained.

#### **User information**

The user can add a certain amount of information to be included in the registration file:

- Author
- Department
- Project
- · Subject
- Comments

Each of these fields is a character string. They can be left empty, but this has no influence on the file name or the recording sequence.

### 3.6.2 Sampling frequency



Only activated measurements can be taken into account for recording.

To set the recording frequency, go to Configuration > Records > Sampling frequency

22 CHANNELS		1	RECORDS	🚺 ALAR	MS 🔯 SYNC	E REMOTE	MPORT EXPORT	SYSTEM
Sampling freq	#=	Color, Nar		1_Type, Max_Freq		Y	Filter by name	9
Trigger		L					22	
File info					E Freq	E Freq	Freq	E Freq
Post actions	Color	Name T	Measurement	Max_Freq	Recorded Instanton Hz (1µ)	s) 5k Hz (200µs)	Pasconting traquerus 250 Hz (4ms)	Fernanding Inequatory Hz (1s)
					Baudrate 2M Bytes/s 98.9%	Baudrate 10k Bytes/s 0.4945%	Baudrate 500 Bytes/s 0.0247%.	Baudrate 2 Bytes/s 0.0001%
		Ch_A1	Direct	TMHZ			D	<b>Q</b>
		Ch_A2	Direct	1MH2	α		D	Ū.
		Ch_A3	Direct	TMH2				
		Ch_A4	Direct	1MHz		α		
		Ch_B4	RMS	100kHz	П		Ū.	0
		Ch_C1	Direct	5kHz		D	D	D
							items per page 1000	1-6016

FIGURE 3.11 : Setting recording frequencies

You can customize the information displayed using the displayed columns field (1), and filter the channel display using the Filter by name field (2). 4 different sampling frequencies can be set (3).



The same measurement can be recorded at a single frequency. Two measurements of the same channel can have different sampling frequencies.

In the example shown in the table above, the direct voltage measurement of channel 1 is recorded at 1MHz, while the RMS measurement of channel 1 is recorded at 5kHz. Channel 2 forward voltage is recorded at 100Hz. All the other measurements shown in the table can be viewed in real time, but are not recorded, as they are not activated in a frequency group.



The sampling frequency is limited and depends on the acquisition card used (1MSa/s for the universal card). It is independent of the recording frequency. For example, if a recording is set to 1kSa/s on a universal card, the trigger will still be accurate to 1 $\mu$ s. Calculations are based on all samples present in the period  $\Delta t$ .

8

Depending on the type of measurement recorded and the acquisition card used, a maximum refresh rate is calculated in column (5). If the user-defined recording frequency is higher than this value, the measurement will be oversampled. The same measurement point will be sampled several times, which can lead to a "plateau" effect on the measurement curve. It is therefore recommended not to exceed this limit. Depending on the configuration, an optimum recording frequency is proposed by default to avoid this behaviour.

## 3.7 | Start and stop settings

To set your acquisition trigger conditions, go to *Configuration > Records > Trigger*.

🔐 HOME 🖸	CONFIGURATION						START	RECORDING			
CHANNELS	RECORDS	ALARMS	SYNC	REMOTE.	N	MPORT EXPORT	🔯 SYSTE	M			
Sampling freq	Record start condit	ion		•	1	Record a	stop condition				
Trigger	🗿 💃 Manual 🖗					🔘 💲 Manual	0				
E File info	Start at date				2)	🔿 🕤 Stop at d	ate				
Post actions	O FTrigger 🕐					O F Trigger	0				
						C Enable limit File maximum lim		0			
						Q 520		O Dura	tion		
					3-	20.13M	bytes "r	u U	D.	0	10
					Ť	5		SET TO D	ISK FREE SPACE		
						Disk free space	e 933.2Gavtes				

FIGURE 3.12 : Start and stop settings

Each record must be set up with a start condition and a stop condition (1). For each, there are 3 different types of triggers : manual, date and trigger (2).

## 3.7.1 Manual :

Users can start and stop recording themselves, using the start/stop button at the top right of the screen.

### 3.7.2 Start at date :



FIGURE 3.13 : Start a date

The user can define a calendar date at which recording starts and/or stops. Alternatively, you can set a timer before recording (start condition) and/or a recording duration (stop condition).

## 3.7.3 Trigger on level :

The user can program recording start and stop conditions according to the values measured on the analog and digital channels :

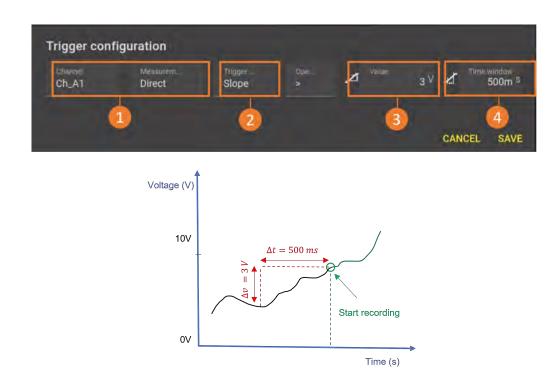


FIGURE 3.14 : Trigger on level

First define the physical channel and its associated measurement to which you want to apply the trigger condition (1). Then describe the condition by selecting "level" in type, the ">" or "<" operation for the overshoot direction, and the threshold value (2). In the example above, recording will be triggered if the "voltage" measurement on channel 1 exceeds 25V. It is possible to activate a duration on this condition. In this case, the user defines a time delay during which the condition must remain true for the condition to be validated. In the example above, exceeding the 25V threshold must last at least 1 second for recording to start/stop (3).



The filter prevents unwanted triggering caused by transient interference on the channel.



## 3.7.4 Trigger on slope (available in a later version)

FIGURE 3.15 : Trigger on slope

To set up a slope trigger, also define the physical channel and associated measurement to which you wish to apply the recording condition (1). Choose slope (2) . The "+" or "-" sign in front of the amplitude value defines the direction of the slope (3). In the example above, if the "voltage" measurement on channel 1 increases by more than 3V over a maximum sliding time window of 500ms (4), then the trigger condition is validated.

## 3.7.5 Trigger on window (avalaible in a later version)

To set up a window trigger, also define the physical channel and associated measurement to which you wish to apply the recording condition (1). Choose window (2).

## **Combination of trigger conditions**

It is possible to combine several conditions on several channels which, once verified, will start/stop recording. When several conditions are set, the user selects the "AND" or "OR" connector :

- AND : All defined conditions must be true simultaneously for recording to start/stop.
- OR : At least one of the defined conditions must be true for recording to start/stop.



The set of conditions can include both analog and digital channels (in a later version). It is also possible to have two different conditions on two measurements of the same physical channel. Trigger and stop conditions can be set independently.

32

1-	⊙ ⊅ or ○ ⊅ and	
	Ch_A1 < 50Volt	1
2	🦲 Ch_A2 RMS > 25Volt √₀ 0.1s	
	+ ADD CONDITION	

FIGURE 3.16 : Combination of conditions

In the example above, if one of the defined conditions is true, then recording is triggered (1). If the voltage of analog channel 1 is less than 50V OR if the RMS value of channel 2 is greater than 25V for 100 ms, then recording is triggered (2).

## 3.7.6 Pre-trigger

When the start condition is a trigger or a combination of triggers, the user can configure a pre-trigger. This corresponds to a number of samples or a time to be recorded before the trigger condition. The user can configure the duration of this window (1). Please note that if the event before the pre-trigger duration has been met, its duration will be shorter unless the inhibit option (2) is enabled.

Example 60s pre-trigger without inhibit

If the event starts at 15s, recording will begin and the pre-trigger will only be 15s long.

Example 60s pre-trigger with inhibit

If the event occurs after 15s, recording will not start. The event must occur again after 60s to be taken into account; recording will start and the pre-trigger will be 60s as defined by the user.



FIGURE 3.17 : Pre-trigger

By activating Inhibit (2), triggering is ignored if the pre-trigger window is not full :

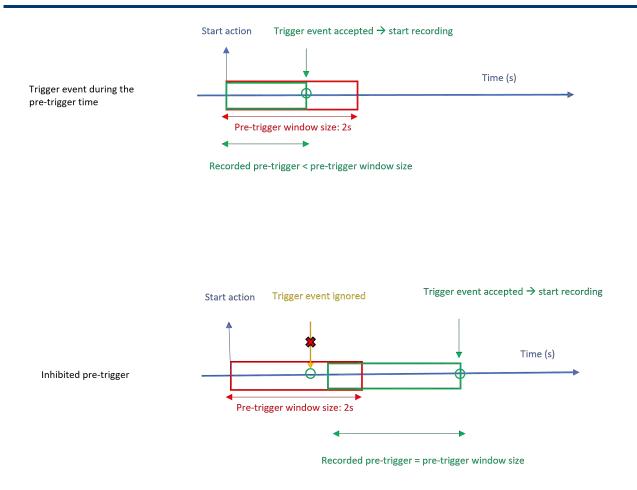


FIGURE 3.18 : Inhibit function

## 3.7.7 Post-trigger

The user can set a time during which the device continues to record after the stop condition has been triggered.

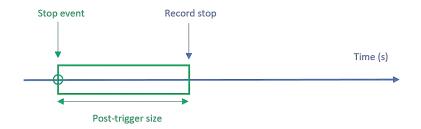


FIGURE 3.19 : Post-trigger

### 3.7.8 Setting save

You can save a acquisition configuration file (1) with all the parameters defined for an acquisition, it can be recalled later by importing it (3):

- Measurement parameters (measured phenomenon, range, sensor, channel color, etc. )
- Recording parameters (recording frequency, triggers, file name)

· Settings for real-time pages

You can also save a system configuration file (2) that includes all system parameters, it can be recalled later by importing it (3):

- Network
- · Time synchronization
- Screen
- · Keyboard
- Sounds

You can reset the settings when necessary (4).

8	A HOME	CONFIGURATIO	A Po REALTIME		EI FILE MANAGER	START RECORDING	0	III 🔒	î
Measurem	ents realtime	CHANNELS	RECORDS	REMOTE		SYSTEM			
Ch_A2 <sub>Min</sub> Ch_A3 <sub>mes</sub>		Settings	👲 Setting save			0			
	Ð	- [	Acquisition configuration	Nenimet acq_of	I ± Såve Acquisition coni	ndustion			
		l	System configuration file	neme sys_ch	. SAVE SYSTEM COMFIG	зиячтки			
			🛨 Settings load			•			
		l l	1.0	2 LOAD CO	NFIGURATION				
			😨 Settings reset			0			
				G RESET ALL SET	TINGS TO FACTORY				
				B RESET ACQUI	SITION SETTINGS	-4			
				C RESET SYS	TEM SETTINGS				
Alarms A 0 B 0 (	C O D O								
No acquis	ition running						-11	Sep 2023 1	13 03 51

Figure 3.20: Creation of configuration file



When a configuration file is created, it is linked to the type and location of the measurement modules in the device. If the device configuration changes, the file is no longer compatible.

## -Chapitre 4-

## **Measurement data display**

## 4.1 | Real-time display

To view your measurements in real time, click on the "real time" tab in the main navigation bar :



FIGURE 4.1 : Real-time data display

To view previously configured measurements, drag and drop them into the graph area (1).



You can also add or remove a measurement from the graph area by pressing and holding.

There are 4 real-time display modes :

- F(t): oscilloscope mode to display measurements as a function of time in the form of a waveform (2).
- XY (avalaible in a later version) : mode to display one measurement as a function of another in the form of a curve (3).
- *DMM* : multimeter mode for displaying the current numerical value of one or more measurements in digital form (4).
- *Custom :* customizable display mode where measurements can be displayed in curve and numerical form (5).

## 4.1.1 F(t) : Oscilloscope

See visualization and graphic analysis chapter

#### 4.1.2 DMM display

DMM mode displays real-time measurements in digital format. In order to be visible, the value displayed is an average.



You can use the HDMI output on the unit to transfer the image to a display.



FIGURE 4.2 : DMM Display

To display measurements in numerical format, simply press and drag the measurement over the graphic area. A bar graph shows where the measured value lies in relation to the defined range.



Press on a measurement to access the channel, sampling frequency or average settings :



FIGURE 4.3 : DMM average period setting



The DMM average period can be set on 200ms or 2s. The number of samples used for the calculation depends on the acquisition module speed frequency. For instance, with an universal acquisition module, it will be 1 MSa/s.

## **Custom display**

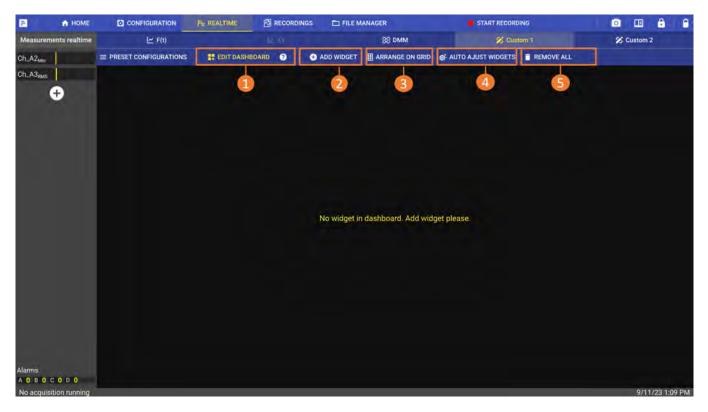
These two dashboards (custom 1 and custom 2) are fully configurable. They are saved in the configuration export. Up to 16 widgets can be displayed simultaneously. Widgets can be of different types.

- DMM : numeric format
- F(t) : Scrolling waveform display
- · Live record : Full waveform display
- · Image : import an image in jpg, png or svg format



The widgets and layout parameters allow you to create a synoptic supervision dashboard.

To perform an action, enter edit mode by clicking on 'Modify dashboard (1). Several functions will appear :



#### FIGURE 4.4 : Dashboard personalization

- Add widget : Create an additional widget. Default grid layout (2).
- Divide on a grid : Overwrites the current layout, setting all widgets to the same size and aligned on a grid. (3).
- Auto widget adjustment : Slightly adjusts the size of adjacent widgets to eliminate gaps (4).
- Delete all : removes all widgets from the dashboard (5).

#### To redesign widgets you can :

In touch navigation : in edit mode, pinch to change size and drag to move. Mouse navigation : in edit mode, use the scroll wheel to change size and drag to move.



Go to 'Size and position' to resize on a single axis at a time.

## 4.2 | Visualization and graphical analysis



The user interface for viewing F(t), or analyzing a recording on the device or on a PC (via DASpro software) is similar.

To display the measurement, drag-and-drop it into the graph area (1), and adjust the desired scale using the various touch gestures :

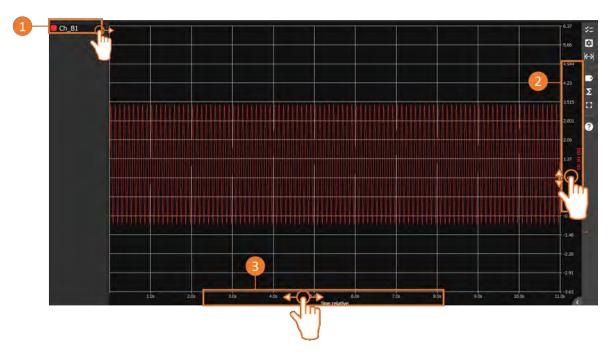


FIGURE 4.5 : Min and max settings for X and Y axes

You can set the minimum and maximum limits by sliding on the axis (2). The same applies to the x-axis (time) (3).



A short press on each axis opens a settings window, where you can manually enter the limits. From this menu, you can, for example, perform an "auto zoom" on the Y axis to automatically center the measurement, or add an additional scale on the Y axis.

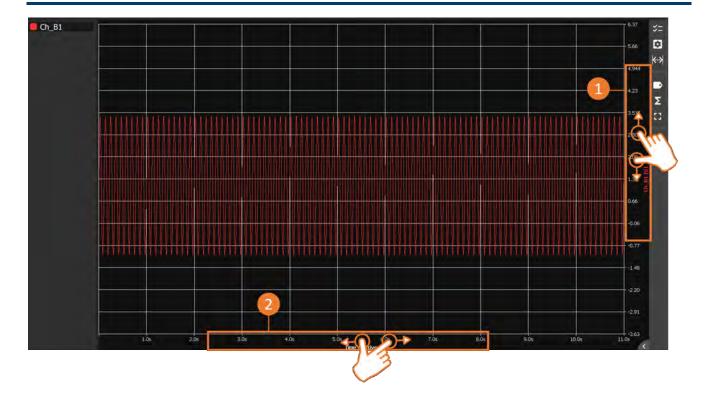


FIGURE 4.6 : Zooming in and out on X and Y axes

By moving the thumb and forefinger closer or further apart on the Y ordinate axis (amplitude), it's possible to zoom in and out between the defined limits (1). The same applies to the X-axis, to change the time base (2).

 $\mathbf{O}$ 

On a computer or if a mouse is connected to the device, use the mouse wheel to perform this function, positioning the cursor on the desired axis.

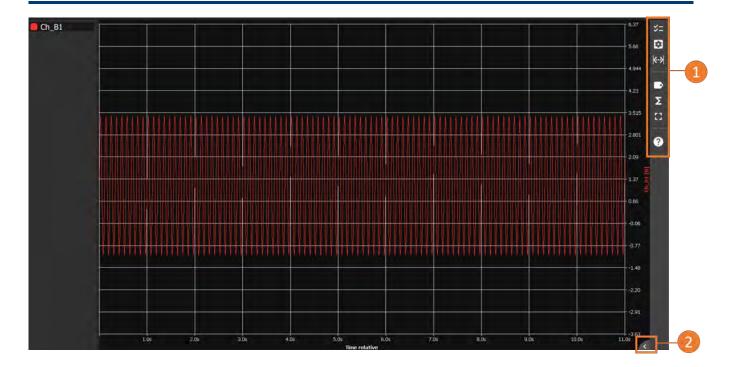


FIGURE 4.7 : Graphic display parameters

On the vertical bar to the right of the screen, a set of parameters is available (1). Use the arrow at the bottom right of the screen to open the text description of each parameter (2).

Symbol	Description
<b>\$</b> =	Selects the measurements to be displayed in the graphics area
8	Allows you to set display parameters : division of the graphics area into several screens, choice of colors, background image, etc.
K·≯	Shows/hides vertical and horizontal cursors
₽	Displays/hides full name of displayed measurement(s) with access to display parameters
Σ	Displays/hides predefined mathematical calculations in real time (see mathematical calculations chapter)
	Displays/exits full-screen mode
0	Opens the help window

6

Mathematical calculations take into account all measurement points displayed on the screen. If vertical cursors are displayed, the calculation will only take into account the points between the cursors.

## 4.3 | Recording analysis

To open a saved measurement file, go to "Recordings" in the main navigation bar.



FIGURE 4.8 : Recording measurement file

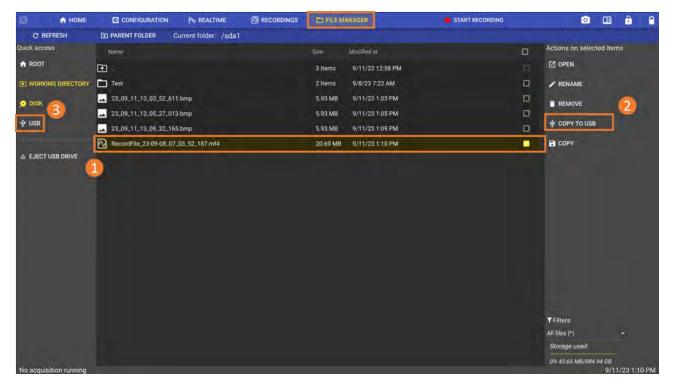
By pressing data (1), you can :

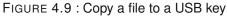
- · Access all saved measurement files
- Convert the displayed measurement file to .csv format, which will be found in the file manager.

## 4.4 | File transfer

#### 4.4.1 File retrieval via USB key

Plug a USB key into one of the device's ports. To retrieve a file from the device's hard disk and transfer it to your computer, go to "File Manager" from the main navigation bar. Press "DISK" to access the entire contents of the device's internal memory. Select the desired file (1) and press "COPY TO USB" (2). An "operation in progress" message will appear before the pasted file appears in "USB" (3).





### 4.4.2 File transfer via FTP protocol (avalaible in a later version)



If you want to retrieve files from the device remotely, connect it to a computer network via the Ethernet port or Wi-Fi option. For more information, see remote control section.

Then go to Configuration > Remote > FTP Activate the FTP protocol, setting a password if necessary.



By default, the connection is in anonymous mode on port 20 + 21.

## -Chapitre 5-

## **Advanced features**

## 5.1 | Sensors library

Each measurement is associated with a sensor.

To access the sensor library, go to *Configuration > Channel > Sensors library* A table listing all sensors and their parameters is shown on this page.

B 6	HOME CONFIGURATION	Po REALTIME		FILE MANAGER		START RE			0 10
📩 CHANK	NELS RECORDS	ALARMS	SYNC			PORT	SYSTEM		
N Analo	+ ADD SENSOR	7	Filler by name	S= Name, N	oume fanufactwer, Measure, Ur	it_Input, Type, I	Physical_min_value, P	hysical_max_value	Is_cu_
0/1 Digital	Name †	Manutactur	er Measure	Unit	Туре	Min yalue	Max value	Configure	Delete
Sensors libri	A 1007	Sefram	Current	Ampere	Current_clamp	-3000	3000	•	
O Units library	Charge_FTY	Siemens	Electric char	ge Coulomb	Other			٠	
32 Calibration	Clamp_UF	Universal	Technic Current	Ampere	Current_clamp	-200	200	٠	
Wizard	Clamp_UP	Universal	Technic Current	Ampere	Current_clamp	2000	2000	۰	
	Lineur_potentiometer		Length	Motor	Other			٠	
	Luminosity_T25_IK	Hoosywell	filuminance	Lox	Öther		55	۰	
	Luminosity_YTUH		Illuminance	Lux	Other			۰	
	No_sensor_calTempVolt_measureme	int Setram	Vollage	Voll	Other				

FIGURE 5.1 : Sensors library table

You can search for sensors already in the library by name (1) or filter the information given by column for each sensor (2). To modify the parameters of an existing sensor, press (3)

### 5.1.1 How to add a 4-20 mA pressure sensor with 50 ohm shunt



To carry out a current measurement (excluding clamp), it is essential to have a shunt plugged in the channel input. A shunt is a resistor used to convert current into voltage, so that the measurement can be acquired by the device.

To create a new 4-20 mA pressure sensor, click on "Create sensor" and fill in the following parameters :

Other 4-20mA	Physica Bar	0	
Senisor name*		d Manufacturer	
Description			
Min	Bat	Max	Ba

FIGURE 5.2 : 4-20 mA sensor settings

Set sensor type to "Other" (1) and sensor interface to 4-20mA\_with\_Shunt (2). Enter the unit of the sensor's physical input (3). Enter the associated information in the various fields (4).



If the unit is not available in the drop-down list, you can add it manually.

The Min and Max fields correspond to the display range of the measured variable (5). If the measured value is outside these limits, it will not appear on the display.



Next, define the conversion ratio of your sensor in volts, taking into account the conversion linked to the shunt.

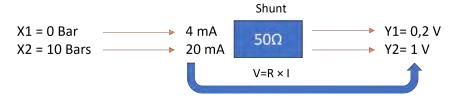


FIGURE 5.3 : 4-20mA sensor conversion ratio with 50 ohm shunt



FIGURE 5.4 : Affine conversion settings

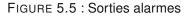
In the case of our sensor, when it measures 0 Bar, it delivers 4mA, which corresponds to 0.2V across shunt (1). When it measures 10 Bar, the sensor delivers 20 mA, which corresponds to 1V across shunt (2).

## 5.2 | Alarms setting (available in a later version)

#### 5.2.1 4 logic output (Alarms)

Alarms A, B, C and D send a TTL voltage signal when the set event occurs.

	ION Po REALTIME	ECORDINGS 🖬 FI	LE MANAGER	<b>•</b> S	TART RECORDING	o 💷 🔒
CHANNELS	RECORDS	ALARMS	SYNC	REMOTE	IMPORT EXPORT	SYSTEM
Alarms table	Name	Туре	Add automatic mark	er	Send E	Mail
Alarm A	Alarm B	Disabled	2 d	_	3 0	
🔋 Alarm B	Alarm C	Disabled	Ø		-	
C Alarm C	Alarm D	Disabled				
间 Alarm D	Alarm A	Disabled	ġ			



When activating a logic output, you must first define the alarm type (1) :

- · Trigger condition : activation on event without starting/stopping recording
- · Recording start : activation of measurement file recording during the event

## 5.3 | Remote control



To use the remote control functions, the device must be connected to a network. Please refer to the "Network settings" chapter for further information on configuration.

#### 5.3.1 Web server

The system incorporates a web server function, enabling a connection to be established via the Internet from a web browser. To do this, enter the IP address in the browser address bar (1). You'll find the device's IP address in the "Status" section of the home menu (2).

C A Nonsecurité 192.168.0.50/en-US/#/hormo	🗿 🖻 🖈 🇯	
桁 Follow the guide	Quick access	
CONFIGURE YOUR CHANNEL(S) AND START A RECORD	OPEN THE LAST RECORD	
AUTOMATIC RECORDING START AND STOP ON DATE	LOAD CONFIG FROM FILE	
GET READY FOR A POWER ANALYSIS	EXPORT CONFIG TO FILE	
MULTIPLE SAMPLING SPEED RECORD	SELECT THE OUTPUT FILE PATH	
🦈 Video tutorial	🙆 Status	
0-10V SENSOR CONNECTION	Storage used	
4-20MA SENSOR CONNECTION	•	
EMPERATURE RECORD	Free space corresponds to a record of: 1d 14h	
DATE SYNCHRONIZATION	Network state	
	P address: 192.168.0.50	
	Not connected	

FIGURE 5.6 : Web server



Real-time visualization and file retrieval are not available. To view your measurement data in real time, use the VNC viewer® shown below.

#### VNC viewer®

You can also use the VNC viewer® utility, which is freely downloadable from the Internet. It lets you access your device remotely, with a duplicate of its complete interface on your computer screen.

Once downloaded, launch the utility and go to File > New connection (1). Enter the device IP address in the VNC server field (2).

R FINC Viewer	2 192.168.0.50 - Properties -		×	- 0. 8
File View Help	General Options Expert			
192.168.0.43		0	1142	Sign in_ •
172,1060,49	VNC Server: 192.168.0.50 Name: Friendly identifier Labels To nest labels, separate names with a forward slash (/) Enter a label name, or press Down to apply existing labels		6.142	
	Security Encryption: Let VNC Server choose Authenticate using single sign-on (SSO) if possible Authenticate using a smartcard or certificate store if poss	sible		
	Privacy Update desktop preview automatically			
5 device(s)	OK	Cancel		

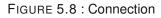
FIGURE 5.7 : New VNC viewer® connection

The new connection appears in the list, click to connect :



You can secure your connection with a password.





You can then operate the device with full access to all functions :

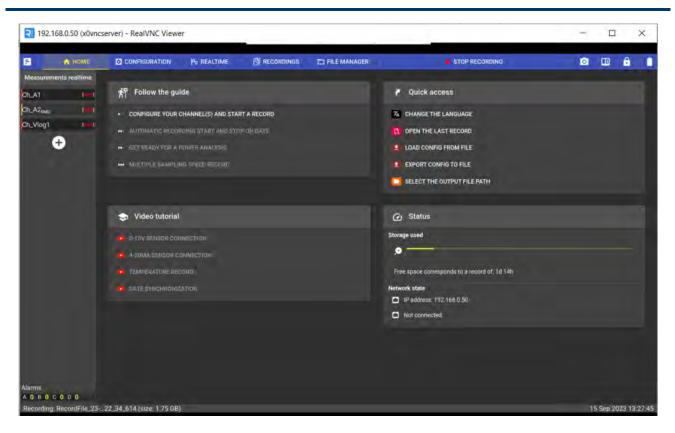


FIGURE 5.9 : VNC viewer® control

## 5.4 | SCPI protocol

SCPI (Standard Commands for Programmable Instruments) is a universal programming language for electronic test and measurement instruments, based on the IEEE 488.1 and IEEE 488.2 standards. Commands are ASCII textual strings which are sent to the instrument over the physical layer. Commands are a series of one or more keywords, many of which take parameters.

See wikipedia description

### 5.5 | Physical layer

SCIPI is based over the LAN interface that can be connected via a commercial RJ-45 cable to a network with TCP/IP protocol. The TCP port used is **23** (Telnet port).

### 5.6 | Command syntax

SCPI commands to an instrument may either perform:

- · command operation (e.g. switching a power supply on)
- query operation (e.g. reading a voltage). Queries are issued to an instrument by appending a question-mark to the end of a command.

Use a semicolon (;) to separate multiple commands.

#### Abbreviating commands

The command syntax shows some characters in a mixture of upper and lower case. Abbreviating the command to only sending the upper case has the same meaning as sending the upper and lower case command.

For example, the command "DATe" could also alternatively be abbreviated "DAT"

#### 5.6.1 Arguments

Some commands require an additional argument. Arguments are given after the command, and are separated by a space.For example, the command to set the trigger mode of an instrument to "normal" may be given as "TRIGger:MODe NORMal". Here, the word "NORMal" is used as the argument to the "TRIGger:MODe" command.

There are several types of data items:

- Alphanumerical data: 1 to 12-character words that can be alphabetical (upper or lower case) digital or the "-" character (95d). A word always starts with an alphabetical character. For example, for a non-digital parameter: S1M.
- Decimal digital data: Made of a significand and, possibly, an exponent, and displayed as a chain of ASCIIcoded characters starting with a digit or a sign (+ or -).
- Text: Any chain of characters under 7-bit ASCII code, between quotation marks (") or apostrophes ('). For example: "Channel 1"

### 5.7 | Examples

```
>> Send : *IDN?
<< Rcv : DAS1800 V0.0.4 (N0012)
>> Send : VALID ?
<< Rcv : Ch_B1 ;Ch_B2 ;Ch_B3 ;
>> Send : *OPT?
<< Rcv : No options
>> Send : DAT ?
<< Rcv : 05,11,2022
>> Send : :DAT ?
<< Rcv : 05,11,2022
>> Send : :DATE ?
<< Rcv : 05,11,2022
>> Send : :RDC ?
<< Rcv : Ch_B1 Direct 1.12572; Ch_B2 Direct -0.756034; Ch_B3 Direct -1.78915;
>> Send : HOUrs ?
<< Rcv : 09,27,37
>> Send : FILE:NAMe ?
<< Rcv : RecordFile
```

## 5.8 | Programming dictionary

## 5.8.1 Requests list

HEADER	DESCRIPTION	RESPONSE	EXEMPLE
*IDN?	Identification request	SEFRAM,	SEFRAM 8460 Version 4.7.2
		Product Name,	(N:00010)
		Serial Numer,	
		VersionMajor.VersionMinor	
*OPT?	Idendtification of options	Number of acquition boardsSS	titi
:DATe?	Return the current date	Day,Month,Year	30,12,2022
:HOUrs?	Return the current time	Hour, Minutes, Seconds	09,53,37
RDC?	Read all measurements values	Measurement name, type and values separated by comma	Ch_B1 Direct 0.1514, Ch_B2 Direct 8.9716
REC?	Read recording state	"Waiting for start of record" or "Recording in progress"	Waiting for start of record
VALID?	Read list of all measurements enabled	Measurement name and type separated by comma	Ch_B1 Direct, Ch_B2 Direct
:FILE:NAMe?	Read record file name	File name string	MyFileName

Table 5.1: SCPI request description

DAS

5

HEADER	DESCRIPTION	PARAMETERS	EXEMPLE
*REM	Start remote control	-	*REM
*LOC	Stop remote control	-	*LOC
:MEMSpeed	Set recording frequency	Frequency (Hz)	:MEMSpeed 10000
:START:MANual	Start recording	-	:START:MANual
:STOP:MANual	Stop recording	-	:STOP:MANual
:SCREEN	Change current screen	REplay, SETUP, SCOpe	:SCREEN SCO
:FILE:NAMe	Set record file name	File name	:FILE:NAMe myFileName
:REB	Reboot the product	-	-
:VIEWer	Open a record file	File name	:VIEWer myFileName

Table 5.2: SCPI command description

DAS

### 5.9 | Examples

Bellow an example of a Python implementation

```
Listing 5.1: SCPI python implemntation exemple
```

```
import time
import telnetlib
```

```
TIMEOUT = 0.5 # Timeout on frame receive
PORT = 23
```

```
# Remove end of line chars to print
def extractCmd(cmd):
   cmd = cmd.replace(" \ n", "")
   cmd = cmd.replace("\r", "")
    return cmd
# Send a frame and wait for response
def sendFrame(tn, cmd):
   cmd = cmd + " \setminus n"
    print(">>_Send_:_" + extractCmd(cmd))
    tn.write(cmd.encode('ascii'))
    res = tn.read_until(b'\n', TIMEOUT).decode('ascii')
    if len(res) == 0:
        print("Timeout")
        time.sleep(1)
    else:
        print("<<_Rcv__: + res)</pre>
    return res
class scpi(object):
    def __init__(self, ip):
        self.tn = telnetlib.Telnet(ip, PORT, TIMEOUT)
    def runCmd(self, frame):
        return sendFrame(self.tn, frame)
    def __del__(self):
        self.tn.close()
scpilnst = scpi("192.168.0.110")
scpilnst.runCmd('*REM')
scpilnst.runCmd('*IDN?')
scpilnst.runCmd('VALID_?')
scpilnst.runCmd('*LOC')
```

## 5.10 | User interface

The DAS interface connection state and error queue can be montitored to help debuging.

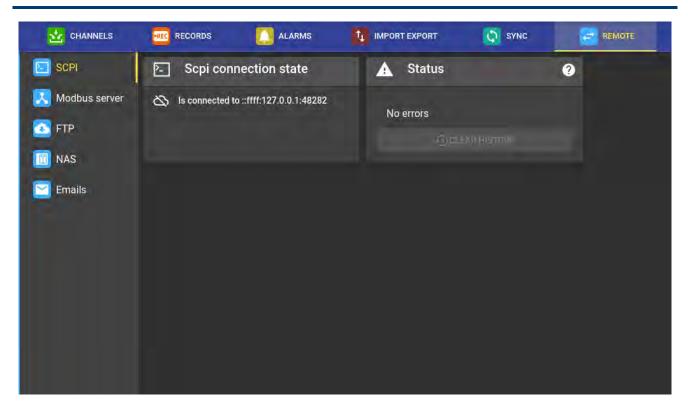


Figure 5.10: SCPI user interface

## -Chapter 6-

## **MDF4 file format**

Measurement Data Format version 4 (MDF4) is an ASAM file standard for storing measurement data in a binary file format. For more information about the MDF4 file format, please visit https://www.asam.net/standards/detail/mdf/wiki/.

## 6.1 | Format

The MDF contains both raw measurement data and the metadata needed to interpret the raw data. The metadata contains, for example, information for converting the raw data into usable physical quantities, or the names of ASAM-compliant signals. The file is organized in binary blocks, where each block consists of a number of adjacent bytes that can be viewed as a record or data structure.

## 6.2 | Version and compliance with ASAM standard

Our file format follows the MDF 4.1.1 standard, and can be verified using MDF Validator 2.9.10.

## 6.3 | Interoperability

Our MDF4 files can be read by the following tools:

- Flexpro
- NI DIAdem
- Matlab + Vehicle Network Toolbox
- Python Asammdf
- Turbolab MDF4-LIB

Other software may be able to open our files if they support the MDF4 standard, but we haven't tested them.

## 6.4 | Functionality

Main MDF4 features in our devices:

- · File description fields: allow users to store information about the context of their measurements
- · File history: saves the file creation date
- · Marker: time markers added by the user
- · Raw data: the raw data saved against the conversion functions defined in the header
- · Time synchronization information: information on the source and accuracy of time synchronization
- Attachment: the DAS configuration file is included in the registration file as a backup of the device configuration.
- · Lane information: lane identifier, short and long lane names, and color of layout
- · Subsampling calculated on the fastest frequency group

## 6.5 | Example

signal.plot()

Here's an example of a Python implementation using the Asammdf library to open an MDF4 record

```
Listing 6.1: Exemple d'utilisation de la bibliothèque MDF4 en Python

from asammdf import MDF

mdf = MDF('sample.mdf')

speed = mdf.get('WheelSpeed')

speed.plot()

important_signals = ['WheelSpeed', 'VehicleSpeed', 'VehicleAcceleration']

# get short measurement with a subset of channels from 10s to 12s

short = mdf.filter(important_signals).cut(start=10, stop=12)

# convert to version 4.10 and save to disk

short.convert('4.10').save('important_signals.mf4')

# plot some channels from a huge file

efficient = MDF('huge.mf4')

for signal in efficient.select(['Sensor1', 'Voltage3']):
```

## -Chapitre 7

## System

## 7.1 | Ergonomic settings

To set the general system settings, go to Configuration > System

					-				
E A HOME	CONFIGURATION	A REALTIME	RECORDINGS	FILE MANAGER	140	START RECORDING	0	 ô	1
Measurements realtime	CHANNELS	RECORDS	E REMOTE	IMPORT EXPORT	P	SYSTEM			

FIGURE 7.1 : Access to system settings

You'll then be able to adjust :

- Screen : brightness, screen saver
- Touchscreen : lock touchscreen or virtual keyboard
- The keyboard : regional keyboard selection
- Sounds : loudspeaker sound level

### 7.2 | Firmware update

It's essential to have the latest firmware version of your device to benefit from the latest improvements and fixes. To do this, go to the *Configuration > System > Version :* 

There are 3 ways to update the device :

"Load from the web" (1) : the system must be connected to the Internet and will automatically fetch the latest update file from the url presented.

"Load from USB stick (2): retrieve the update file from https://www.sefram.com/en/software-updates.html and copy it to the root of a USB stick. Plug it into one of the device's USB ports and click on "Load from USB".

"Load from local file" (3) : load the configuration file from the device's internal file manager.

## 7.3 | Time setting

#### 7.3.1 Manual

Select the system time manually.



This parameter is used if the system is isolated (without network) and loses its internal clock. The user can then manually enter the date.

#### 7.3.2 NTP

The device features NTP : Network Time Protocol, a synchronization protocol via IP. NTP enables the device to set its time automatically. An Internet connection (or to a local NTP server) is required to operate.



To set up a local NTP server, contact your IT department, who will be able to help you.

#### 7.3.3 Time zone

This parameter lets you define the time zone to which the device refers.

## 7.4 | Network settings

#### 7.4.1 Ethernet

To connect your device to a network, go to Configuration > System > Network :

E A HOME	CONFIGURATIO	N Po REALTIME 🔯 RECORDINGS	FILE MANAGER	START RECORDING		٥		ê 🔒
Measurements realtime	CHANNELS	TECORDS E REMO	DTE 1MPORT EXPORT	SYSTEM				
Ch_A2 <sub>Min</sub>	Date time		int خيا	terface Ethernet	0			
	Screen	Name: enp2a0 Ia Upi false address: 00:13:95:20:7E:49	Name: eng3 fs Up: false Mac address					
	<ul> <li>Sounds</li> <li>User level</li> </ul>	CONFIGURE						
	Bug report	Hostname DAS1800-667023008 #2.47.6-90						
		P Network tools		• 4				
		- 1mec						Ĭ
Alarms A 0 B 0 C 0 D 0 No acquisition running							9/11/	23 1 26 PM

FIGURE 7.2 : Network configuration page

It is possible to configure 2 different Ethernet networks on the device simultaneously (1). Give your network a name (3). The name must begin with a letter and be at least 254 characters long. It cannot be composed solely of letters or numbers.

The device must be restarted for the new network name to take effect.

 $\mathbf{O}$ 

Several combinations can be used simultaneously by configuring the two networks to best support your application :

- Remote control (see remote control section for more information)
- · Remote file retrieval (see FTP chapter for more information)\*
- · Connecting a camera with Ethernet interface\*
- PTP connection for time synchronization between multiple devices (optional function\*)

\*Avalaible in a later version

To configure the network, click on "Configure" (2), and the following page will appear :



FIGURE 7.3 : Enp2s0 Interface

If your network is directly connected to a DHCP server via a router, you need to check DHCP mode (1). Your network will automatically assign an available network address to your device, thus avoiding address conflicts.

In some cases, if the user does not have access to the corporate network, a point-to-point connection is required. This is an isolated connection between the PC and the device. In this case, set the network parameters manually (2).

#### Example of manual point-to-point network settings :

First, set up a fixed IP on your PC by following the steps below :

🚽 👻 🕈 🦉 > Control	Panel > Network and Internet > Net	work and Sharing Center		~	Search Control Panel	
Control Panel Home Change adapter settings	View your basic network View your active networks	information and s	et up connections			
ange advanced sharing tings	Ethernet Status	>	Access type: Internet			
edia streaming options	General Connection		connections & Enternet	Ethernet Properties	×	
	IPv6 Connectivity: No network acce Media State: Enabl Duration: 00:03:	Internet No network access Enabled		Networking Sharing Connect using:		
		00:03:07 1.0 Gbps	or set up a router or access poin			
	Details		oubleshooting information.	This connection uses the following terms:		
	Activity			Partage de fichiers et imprimantes P Planificateur de paquets QoS	Réseaux Microsoft	
	Sent —	Received		FortiClient NDIS 6.3 Packet Filter D     Protocole Internet version 4 (TCP/I    Protocole de multiplexage de carte	(Pv4)	
	Bytes: 3 2 609 239	3 895 061		<ul> <li>Pilote de protocole LLDP Microsoft</li> </ul>	, 5	
also	Properties Disable	Diagnose		Install Unstall Unstall	Properties	
Internet Options Windows Defender Firewall	Close			Protocole TCP/IP (Transmission Control F Protocol). Protocole de réseau étendu pa communication entre différents réseaux in	r défaut permettant la	

FIGURE 7.4 : Fixed IP address setting

The device is connected to the PC via ethernet cable, and the configurations are as follows :

Configure interface Enp0s3	Protocole Internet version 4 (TCP/IPv4) Properties	×
	General	
O DHCP ?	You can get IP settings assigned automatically if your network supports	
O Manual IPv4	this capability. Otherwise, you need to ask your network administrator for the appropriate IP settings.	
IP address*	Obtain an IP address automatically	
192.168.0.2	() Use the following IP address:	
	IP address: 192 . 168 . 0 . 1	
Mask* 255.255.255.0	Subnet mask: 255 . 255 . 255 . 0	
	Default gateway: 192 . 168 . 0 . 2	
Gateway*	Obtain DNS server address automatically	
255.255.255.0	Use the following DNS server addresses:	
	Preferred DNS server:	
DNS	Alternate DNS server:	
	Validate settings upon exit Advanced	ľ
V APPLY SCANCEL	OK Cancel	
Address IP configuration on DAS1800	Address IP configuration on PC	

FIGURE 7.5 : Manual IP configuration of PC and the recorder



The configuration shown below is an example. If you have any doubts about your settings, please contact your IT department.



In a point-to-point connection, you can send SCPI commands using the supplied programming manual. This means you can edit and run your own script over an isolated connection.

## 7.5 | User level

Several user levels can be defined, giving access to more or less advanced functions and information. The aim is to simplify the user interface as required:

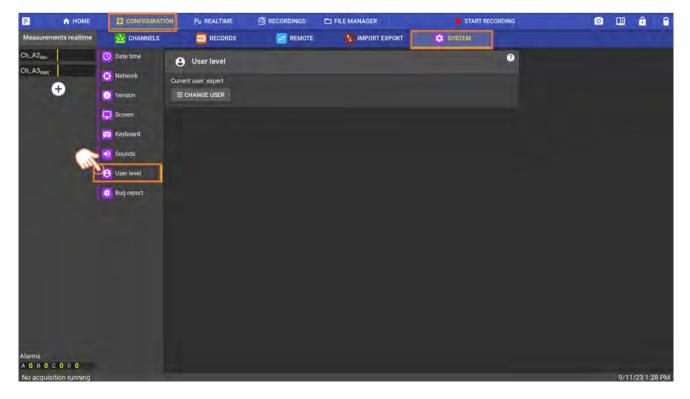


Figure 7.6: User level

#### 7.5.1 Viewer level:

The device is virtually read-only. The user can only start or stop recording. He/she cannot modify any configuration (network, channels, trigger...) and has no access to the file manager.



For example, this mode is used when an operator has access to the device, but the configuration has been made by a third party. This limits the risk of tampering.

#### Normal level:

The interface functions available are those intended for standard use. The user has access to virtually all functions.

#### **Expert level:**

Certain functions or additional information become available.

#### Admin level:

This level is dedicated to your company's IT department or competent person. It gives access to network security parameters.

## 7.6 | Bug report

If you notice a malfunction while using the device, a dedicated bug report menu is available: *Configuration > System > Bug report* 

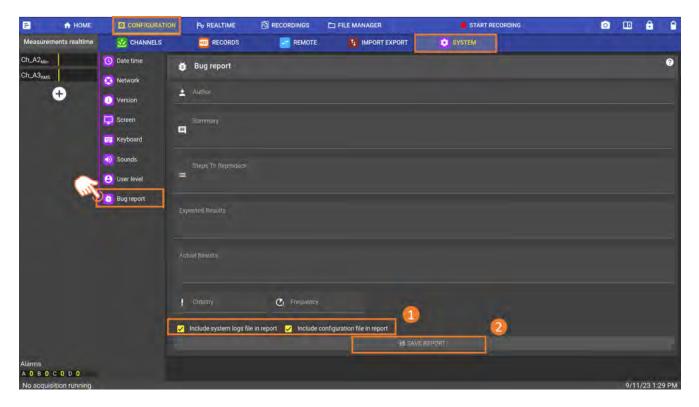


Figure 7.7: Créer un rapport de bogue

Fill in the various fields, providing as much detail as possible. If you suspect a software problem, please check the boxes to include the system and configuration files in the report (1). This will give SEFRAM all the information it needs for a complete diagnosis.

Then press "Save Report" (2), which will create a compressed folder of type xxxx.bugreport in the working directory available from the file manager (see file manager chapter for more information). You can retrieve the file via a USB key or via the network (FTP or web server, see network settings and remote control chapters for more information). Then send the file to SEFRAM's support department: support@sefram.com or support@bkprecision.com for customers in North America.



If any doubt, please contact SEFRAM telephone at 04 77 59 01 01. For customers in North America, please contact B&K Precision at 800-462-9832 (US & CAN toll free). -Chapter 8-

# **Technical specifications**

**Specifications, base unit** Note: All specifications apply to the unit after a temperature stabilization time of 30 minutes over an ambient temperature range of 23 °C  $\pm$  5 °C.

Data Acquisition System			
Recording (files written to SSD)			
npling Rate <sup>1</sup>	ng Rate <sup>i</sup> I MS	I MSa/s up to 40 channels	
ing Groups	Groups	4	
e Speed	eed 12	0 MB/s (7 GB/min)	
Format	nat As	SAM MDF4 (.mf4)	
ize Limit	Limit 90	0% of disk capacity	
f Acquisition	Quisition N	otify, rearm trigger	
Measure	isure		
	E(t)	oll mode: 100 ms/div to 10 min/div cope mode: 10 µs/div to 50 ms/div	
ay Mode	DMM Node	Acquisition time: 200ms (10 NPLC <sup>2</sup> at 50Hz), 2s (100 NPLC <sup>2</sup> at 50Hz)	
	Record live view	Typical Refresh period 2s, Zoom Mode	
	Custom 2 C	Customizable Views Widgets: F(t), RecLive F(t), DMM, Picture	
r			
Time (typical)	e (typical) IO s	ec per 100 GB of file	
ibplot	ot	I6 axis	
ursors	rs H	Horizontal, vertical	
urements	On the data	displayed or between cursors	
urements		Min, Max, Pk to Pk, Frequency, RMS, Rising time	
stem	n		
ute Period	Period	I μs	
ource	e delay (on	Analog channel, external source, manual, date/time, delay (on start), duration (on stop), AND/OR combination of channels (128 max)	
og Channel		Edge (rising, falling, both), Threshold (above, below), windows (in, out)	
-trigger	ger	I28 Msamples	
-trigger	ger	1000 s maximum	
r Time (typical) Time	live view       Custom     2 G       custom     2 G       custom     10 s       ot     10 s       ot     10 s       ot     10 s       on the data     10 n       Min, Max, Pk to     10 s       n     10 s       Period     10 s       channel     Edge (rising, fragelog)       ger     10 s	Record       Typical Refresh period 2s, Zoom Mode         live view       Zoom Mode         Custom       2 Customizable Views Widgets: F(t), RecLive F(t), DMM, Picture         IO       sec per 100 GB of file         II       IG         II       period         III       period         III       period         III       period         IIII       period         IIIIIIIII       period         IIIIIIIIIIIIIIIIIIIIIIIIIIIIIIIIIIII	

Digital I/O		
Input		
Number of Channels	16	
Max Voltage	24 V	
Threshold	1.2 V to 2.8 V	
Sampling Interval	I μs (I MSa/s) each channel	
Output		
Number of Channels	4	
Output Characteristics	TTL 5 V, IO mA	
Trigger Source	Analog/Digital channels, acquisition start/stop, disk full	
Power Supply <sup>3</sup>	+ 12 V ± 5 %, 200 mA	

(I) For D18-UNI4 and D18-HIZ4 Module

(2) NPLC: Number of power line cycles(3) Used to power the isolated digital input board(4) Time with only the 1st frequency group used

Power Supply Rail		
Maximum Power Consumption 5 W		
Output Characteristics	+ 3.3 V ± 5%, 500 mA	
	+ 5 V ± 5%, 500 mA	
	+ 12 V ± 5%, 400 mA	
	+ 24 V ±5 %, 200 mA	

Synchronization I/O			
On Sync	On Synchronization Connector (SUB-D 15 HD pin)		
	Signal level	TTL 3.3 V	
Input	External trigger	Pull-up resistor: ΙΟ kΩ Rising edge sensitive Minimum pulse width: ΙΟΟ μs	
External start/stop	Pull-up resistor: 10 kΩ Rising edge sensitive for start Falling edge sensitive for stop Minimum pulse width: 500 ms		
	Signal	TTL 3.3 V	
Output	Trigger	I ms positive pulse at trig event	
	Start/stop	Set when record is launched	

Software Feature			
Remote Access	VNC for remote monitoring and control		
	Web server		
	File management	FTP, SFTP	
	Bench automation	SCPI command port (23 or 5025)	
Sensor Library	Predefined sensors and user created		
Date and Time	Manual, NTP		
Software Update	Through web or USB		
Languages	English, French		

General		
Internal Solid State Memory	2 TB SSD 3D TLC NAND	
Operating Temperature	0 °C to 40 °C (32 °F to 104 °F)	
Storage Temperature	-20 °C to 60 °C (-4 °F to 140 °F)	
Display	15.6" TFT LCD full HD 1920x1080	
Power Supply	110 VAC to 240 VAC, 50 to 60 Hz (150 VA max)	
Interfaces	2 USB3.0, 2 USB 2.0 , 2 LAN IGbps, HDMI	
Battery (optional)	Non removable, Lithium-ion	
Battery Life (typical)	3 ½ hrs - One D18-UNI4 module installed 1 ½ hrs - Ten D18-UNI4 modules installed	
Weight	II lbs (5 kg) base unit + battery option I.21 lbs (550 g) each module	
Safety	N 61010-1 (2010) + AI (2019)	
Electromagnetic Compatibility	IEC 61326-1 (2021)	
Dimensions (W x H x D)	19.1" x 11" x 7.9" (485 x 280 x 200 mm)	
Warranty	3 Years	
Supplied Accessories	Power cord, SUB-D 25 pin male connector and back shell, SUB-D 15 HD pin male connector and back shell, 8 pin connector, rugged carrying case	

#### **Specifications, measurement Modules**

Note: All specifications apply to the unit after a temperature stabilization time of 30 minutes over an ambient temperature range of 23 °C  $\pm$  5 °C.

	Univ	ersal Module (D18	3-UNI4)	
Number of Channels			4	
Input Type	Isolated single ended input - 4mm Banana Plug			
Voltage		0 1 1 1	1	
Max. Input Voltage	± 600 VDC or 424 Vrms			
Range	19 Ranges: ± 500 μV / 1 mV / 2.5 mV / 5 mV / 10 mV / 25 mV / 50 mV / 100 mV / 250 mV / 500 mV / 1 V / 2.5 V / 5 V / 10 V / 25 V / 50 V / 100 V / 250 V / 600 V			
	≤ ± 25 mV		$\pm$ 0.1% of full range + 10 $\mu V^2$	
DC Accuracy <sup>1</sup>	± 25 mV to ± 500 mV		$\pm$ 0.1% of full range + 10 $\mu V$	
	≥ ± I V		± 0.06% of full range	
Offset Drift		± 50 ppm	/°C ± I μV/°C	
Input Impedance	IN	$M\Omega$ for ranges $\geq \pm 1 V_{c}$	25 M $\Omega$ for ranges $\leq \pm 0.5$ V	
Input Capacitance		I	50 pF	
		$\leq \pm 1 \text{ mV}$	< 0.2%	
Intrinsic Noise <sup>3</sup>	± 2	$2.5 \text{ mV to} \pm 10 \text{ mV}$	< 0.1%	
(standard deviation in % of the span)	± 2	5 mV to $\pm$ 500 mV	< 0.05%	
·····		≥±IV	< 0.02%	
		≤ ± 500 mV	> 85 dB	
CMRR		≥±IV	> 70 dB	
Crosstalk		>	-90 dB	
Isolation	C	CH to CH and CH to G	ND, > 100 MΩ at 650 VDC	
Safety		CAT	III 600 V	
Bandwidth and Filter	s			
	≤ ± 2.5 mV		l kHz	
Bandwidth	$\pm 5 \text{ mV to } \pm 25 \text{ mV}$		IO kHz	
(-3 dB)	$\pm 50 \text{ mV to} \pm 500 \text{ mV}$		60 kHz	
	≥ ± 1 V		IOO kHz	
Analog Filter	2nd	Order(-20 dB/dec)	100 Hz, I kHz, 10 kHz	
, and og i neer			0.01 Hz to 10 kHz	
Digital Filter		Туре	Low-pass	
2.5		Filter	Butterworth	
Data Acquisition		- Inter	Butterworth	
ADC		I6 h	it – SAR	
Sampling Interval			/s) each channel	
Temperature (Thermo	ocouple			
Compute Frequency	locupi		4 ms	
compare requercy	1			
Cold Junction	Uncompensated, internal, external (other channel)			
	Accuracy <sup>4</sup> : ± 1.25°C			
	J -210 °C to 1200 °C (-346 °F to 2192 °F)			
	K -250 °C to 1370 °C (-418 °F to 2498 °F)			
	T -200 °C to 400 °C (-328 °F to 752 °F)			
Туре	S		0 °C (-58 °F to 3200 °F)	
		B 200 °C to 1820 °C (392 °F to 3308 °F)		
	E		00 °C (-418 °F to 1832 °F)	
	N		00 °C (-418 °F to 2372 °F)	
	R	R -50°C to 1768°C (-58 °F to 3214 °F)		

Time and Counting			
Threshold	Set by user, auto		
Duty Cycle	10% minimum – (min	imum pulse width, 20 μs)	
Counter	4	8 bits	
	0.1 Hz to 100 kHz		
Frequency	Accuracy: 0.01% reading, 0.1 Hz to 10 Hz 0.05% reading, 10 Hz to 100 kHz		
PWM	Absolute error: 0.1% from 0.1 Hz to 1 kHz 0.5% from 1 kHz to 5 kHz		
TRMS			
Compute Period	Compute on the I Ms/s data flow Each period until 100 Hz 10 ms between 100 Hz and 10 kHz		
Accuracy	10 Hz to 2 kHz	± 0.1% of full range	
(Sine wave $\geq$ 1 V)	2 kHz to 10 kHz	± 0.3% of full range	
Other			
Current	Through shunt or clamp		
Sensor	0 to 10 V, 4 to 20 mA (with external shunt), duty cycle or frequency sensor, other user defined settings		
Calculations	Min – max – avg on $\Delta t$		

High Impedance Module⁵ (D18-HIZ4)			
Voltage			
Input Impedance	10 M $\Omega$ for ranges $\geq \pm$ 1 V,	25 M $\Omega$ for ranges $\leq \pm 0.5$ mV	
	$\leq \pm 1 \text{ mV}$	< 0.2%	
Intrinsic Noise <sup>3</sup>	$\pm$ 2.5 mV to $\pm$ 10 mV	< 0.1%	
(standard deviation in % of the span)	$\pm$ 25 mV to $\pm$ 500 mV	< 0.05%	
	$\ge \pm 1 \text{ V}$	< 0.05%	
Bandwidth and Filters			
	≤ ± 2.5 mV	I kHz	
	$\pm$ 5 mV to $\pm$ 25 mV	I0 kHz	
Bandwidth	$\pm$ 50 mV to $\pm$ 500 mV	60 kHz	
	$\ge \pm 1$ V to $\pm 10$ V	20 kHz	
	≥ ± 25 V	80 kHz	

(I) Direct measure taken on DMM at I0 (50 Hz) / I2 (60 Hz) NLPC (200 ms) and full bandwidth

(2) Only when offset adjustment has been performed after installing a new module. Otherwise accuracy is  $\pm$  0.1% of full range + 20  $\mu V$ 

(3) Measure  $\pm$  short circuit termination to 50  $\Omega$  on chassis during I sec at the fastest acquisition speed and full bandwidth

(4) Only when cold junction adjustment has been performed after installing a new module. Otherwise accuracy is  $\pm 3$  °C

(5) For all other specs, refer to the universal module specifications

#### **Specifications, measurement Modules**

Note: All specifications apply to the unit after a temperature stabilization time of 30 minutes over an ambient temperature range of 23 °C  $\pm$  5 °C.

Multiplexed Module (D18-MUX8)			
Number of Channels	8		
Input Type	Non-isolated differential input – 4 pin terminal block, Part: Phoenix Contact MC 1.5/ 4-ST-3.5		
Voltage			
Maximum Input Voltage		H to GND and between n a channel	
Range (16 ranges)	50 mV / 100 mV / 250 m	/ / 5 mV / 10 mV / 25 mV / V / 500 mV / 1 V / 2.5 V / / 25 V / 48 V	
Admissible Common	$\leq \pm 1 \text{ V}$	± 3 V	
Mode	≥ ± 2.5 V	± 48 V	
DC Assumed	$\leq \pm 10 \text{ mV}$	$\pm$ 0.1% of full range + 5µV	
DC Accuracy <sup>1</sup>	≥ ± 25 mV	± 0.04% of full range	
Offset Drift	± 50 ppm/° <b>C</b>	C ± 0.5 μV/°C	
Input Impedance	$2 \text{ M}\Omega \text{ for ranges} \ge \pm 1 \text{ V}, 25 \text{ M}\Omega \text{ for ranges} \le \pm 0.5 \text{ V}$		
Input Capacitance	I50 pF		
Intrinsic Noise <sup>2</sup>	≤±ImV	< 0.15%	
(standard deviation in%	$\pm$ 2.5 mV to $\pm$ 10 mV	< 0.05%	
of the span)	≥ ± 25 mV	< 0.01%	
CMRR	> 7	0 dB	
Crosstalk	> -90 dB		
Bandwidth and Filters			
Bandwidth (-3 dB)	I kHz		
	IIR 4th order (-80 dB/dec)	0.01 Hz to 500 Hz	
Digital Filter	Туре	Lowpass	
	Filter	Butterworth	
Data Acquisition			
ADC	18 bit – SAR		
Sampling Interval	200 µs (5 kSa/s) each channel		

Temperature (RTD)			
Compute Frequency	4 ms		
	PtI00	1.0 mA	
Current	Pt200	0.5 mA	
Current	Pt500	0.2 mA	
	Pt1000	0.1 mA	
Temperature Range	-200 °C to +850 °C (-328 °F to 1562 °F )		
Wiring	2 wires	Max. corrective resistance 50 $\Omega$	
	3 wires	Max. 3-wire resistance, 50 $\Omega$	
	4 wires		
Measurement Range (7 Ranges)	± 10 °C, ± 25 °C, ± 65 °C, ± 130 °C, ± 200 °C, [-200 °C, +380 °C], [-200 °C, +850 °C]		
Accuracy	3 wires	0.1% of the range $\pm$ 0.3 °C	
	4 wires	$\pm$ 0.1% of the range $\pm$ 0.2 °C	

(I) Direct measure taken on DMM at I0 (50 Hz) / I2 (60 Hz) NLPC (200 ms) and full bandwidth

(2) Measure  $\pm$  short circuit termination to 50  $\Omega$  on chassis during I sec at the fastest acquisition speed and full bandwidth

Temperature (Thermocouple)			
Compute Frequency	4 ms		
Cold hundling	Uncompensated, internal, external (other channel)		
Cold Junction		Accuracy <sup>3</sup> : ± 1.25 °C	
	J	-210 °C to 1200 °C (-346 °F to 2192 °F)	
	К	-250 °C to 1370 °C (-418 °F to 2498 °F)	
	Т	-200 °C to 400 °C (-328 °F to 752 °F)	
Torra	S	-50 °C to 1760 °C (-58 °F to 3200 °F)	
Туре	В	200 °C to 1820 °C (392 °F to 3308 °F)	
	E	-250 °C to 1000 °C (-418 °F to 1832 °F)	
	N	-250 °C to 1300 °C (-418 °F to 2372 °F)	
	R	-50°C to 1768°C (-58 °F to 3214 °F)	
Resistance			
Compute Frequency		4 ms	
	2 wires	Max. corrective resistance 50 $\boldsymbol{\Omega}$	
Wiring	3 wires	Max. 3-wire resistance, 50 $\Omega$	
		4 wires	
Measurement Range (4 Ranges)	300 Ω (I mA), I500 Ω ( 0.5 mA), 5k Ω (0.2 mA), I0 kΩ (0.1 mA)		
Accuracy	$\pm$ 0.1% of the range $\pm$ 0.1 $\Omega$		
Time and Counting			
Threshold	Set by user, auto		
Minimum Pulse Width	l ms		
Counter	32 bits		
Other			
Current	Through shunt or clamp		
Sensor	0 to 10 V, 4 to 20 mA (with external shunt), other user defined settings		

(3) Only when cold junction adjustment has been performed after installing a new module. Otherwise accuracy is ±3 °C

## Chapter 9

# Metrology

## 9.1 | Calibration

You are in possession of a measuring instrument for which the metrological conditions of measurement are defined in the specifications of this manual. Climatic and environmental conditions limit the specifications of your instrument. SEFRAM checks the characteristics of each instrument individually on an automatic rack during manufacture. Adjustment and verification are guaranteed within the framework of ISO9001 certification by measuring instruments connected to COFRAC (or equivalent in ILAC reciprocity). The advertised characteristics are deemed stable for a period of 12 months from first use, under normal conditions of use. We recommend checking after 12 months, without exceeding 24 months of use. Then every 12 months beyond 24 months. When checking characteristics, it is advisable to respect average climatic conditions ( $23^{\circ}C + 3^{\circ}C - 50(+20)^{\circ}RH$ ) and to operate your equipment for 30 minutes beforehand. We advise you to have this verification carried out by our After-Sales Service to ensure the best possible service and preserve the measurement quality of your instrument. When a product returns to SEFRAM or B&K Precision, a full service is provided, including an internal upgrade to keep pace with the latest developments, and a software upgrade. In the event of any deviation from specifications, your instrument will be adjusted to regain its original characteristics.

-Chapter 10-

## Servicing

## 10.1 | For users not based in America

#### 10.1.1 Warranty

Your instrument is guaranteed for three years (36 months) parts and labor against any manufacturing defect or operating hazard. This warranty begins on the date of delivery and ends 1095 calendar days later. If the device is covered by a warranty contract, the latter supersedes or replaces the warranty conditions listed above. The warranty conditions applicable by SEFRAM are available on the website www.sefram.com, the general warranty conditions prevail over the present one which is a summary. This warranty does not cover defects resulting from abnormal use, handling errors or storage conditions outside the defined range.

In the event of a warranty claim, the user must return the device concerned to our factory at his or her own expense following the return procedure indicated on our website: https://www.sefram.com/services.html

SEFRAM Instruments SAS

Service Après-vente

32, Rue Edouard MARTEL

BP 55

#### 42009 SAINT-ETIENNE CEDEX 2

For customers in North America, please return the device to the address mentionned below and follow the instructions given on our website https://www.bkprecision.com/support

**B&K Precision Corp.** 

: 22820 Savi Ranch Parkway

Yorba Linda,CA 92887

bkprecision.com

#### 714-921-9095

The device must be accompanied by a detailed description of the fault, and must be returned with all standard accessories (cords, plugs, etc.). Consumables (batteries, etc.) and optional accessories (case, bag, etc.) are guaranteed for 3 months against manufacturing defects. Components such as LCD screens and touch panels are only guaranteed for normal use. Wear and tear, accidental breakage due to impact or abnormal use are not guaranteed\*. \*See the conditions for acceptance of a touch screen below. Factory-installed options are guaranteed for the same duration as the device. The ssd hard disk is guaranteed for 2000 complete write cycles. The battery (if the battery option is present) is guaranteed for 200 charge/discharge cycles. The remaining warranty period in the event of product replacement or repair is:

- · Time remaining to cover warranty period
- If the device warranty < 90 days, the replaced part is guaranteed for 90 days.

The warranty period for after-sales service outside the appliance warranty period is 3 months. All spare parts become the property of the user, and replaced parts become the property of SEFRAM. In the event of insurance coverage, the product becomes the property of the insurance company at its exclusive request. Otherwise it remains the property of the user. The warranty applies only to equipment manufactured and supplied by SEFRAM. Any intervention or modification carried out by the user or by a third party without prior authorization from the company will invalidate the warranty. The user is responsible for returning the device to our premises. He must therefore ensure that the packaging provides adequate protection during transport. We recommend using the original packaging. The customer is responsible for taking out the necessary transport insurance. SEFRAM reserves the right to refuse poorly-packaged products, and not to offer repairs if the breakage is due to transport. Particular case of the battery: if a Li-ion battery is fitted to this device. It must not be transported outside the unit. Under no circumstances should it be replaced by the user. It must be replaced at the factory, so that the charging system and protective devices can be checked. This equipment must be transported in accordance with international guidelines for the carriage of equipment containing hazardous materials.

#### 10.1.2 After-sales contact

Help with operation and malfunctions:

In the event of a malfunction, please check the software version of your device first, or contact our technical support if you have problems using it.

Or send an e-mail to:

support@sefram.com or support@bkprecision.com (For North America customers)

#### 10.1.3 In case of breakdown

In the event of a breakdown, please return your equipment together with the RMA document previously registered on our website to https://www.sefram.com/services.html or https://www.bkprecision.com/support

You can call our customer service department at:

+33 (0)4 77 59 36 91 or 800-462-9832 (US & CAN toll free)

Or contact:

services@sefram.com or https://www.bkprecision.com/support/request/technician

#### 10.1.4 Packaging

The packaging for this product is entirely recyclable. Thanks to its design, it enables your instrument to be transported in the best possible conditions. We draw your attention to the fact that the original packaging must be over-packed, if it is to be used for transport by air, road or post. We recommend keeping the original packaging for all transport.

#### 10.1.5 LCD Display Defects

Your SEFRAM device is equipped with an active matrix color LCD display. This screen is sourced from reputable manufacturers. Under current technical manufacturing conditions, these manufacturers are unable to guarantee 100% correct operation of the pixels in the display area. They specify a number of defective pixels on the screen surface. SEFRAM's quality department has made installation of your instrument's display conditional on compliance with the manufacturers' acceptance conditions.

ZONE B		
	ZONE A (Diagonal 60% B)	

Figure 10.1: Display areas

Acceptance criteria:

- Zone A (central zone): fewer than 5 defective pixels in total and fewer than 3 contiguous pixels.
- Zone B (total screen area): less than 9 defective pixels over the entire screen area, with Zone A conditions met.

Defective pixels are defined as a point on the screen that remains unlit or lights up in a color other than the one expected. The contractual warranty only applies to the device in your possession if the above criteria are not met. This applies both at the time of delivery and during the warranty period.

## 10.2 | For users based in America

### 10.2.1 Warranty

Please go to the support and service section on our website at bkprecision.com to obtain an RMA #. Return the product in the original packaging with proof of purchase to the address below. Clearly state on the RMA the performance problem and return any leads, probes, connectors and accessories that you are using with the device. Non-Warranty Service: Please go to the support and service section on our website at bkprecision.com to obtain an RMA #. Return the product in the original packaging to the address below. Clearly state on the RMA the performance problem and return any leads, probes, connectors and accessories that you are using with the device. Customers not on an open account must include payment in the form of a money order or credit card. For the most current repair charges please refer to the service and support section on our website. Return all merchandise to B&K Precision Corp. with prepaid shipping. The flat-rate repair charge for Non-Warranty Service does not include return shipping. Return shipping to locations in North America is included for Warranty Service. For overnight shipments and non-North American shipping fees please contact B&K Precision Corp. Include with the returned instrument your complete return shipping address, contact name, phone number and description of problem.

B&K Precision Corp. : 22820 Savi Ranch Parkway Yorba Linda,CA 92887 bkprecision.com

714-921-9095

The device must be accompanied by a detailed description of the fault, and must be returned with all standard accessories (cords, plugs, etc.). Consumables (batteries, etc.) and optional accessories (case, bag, etc.) are guaranteed for 3 months against manufacturing defects. Components such as LCD screens and touch panels are only guaranteed for normal use. Wear and tear, accidental breakage due to impact or abnormal use are not guaranteed\*. \*See the conditions for acceptance of a touch screen below. Factory-installed options are guaranteed for the same duration as the device. The ssd hard disk is guaranteed for 2000 complete write cycles. The battery (if the battery option is present) is guaranteed for 200 charge/discharge cycles. The remaining warranty period in the event of product replacement or repair is:

- Time remaining to cover warranty period
- If the device warranty < 90 days, the replaced part is guaranteed for 90 days.

The warranty period for after-sales service outside the appliance warranty period is 3 months. All spare parts become the property of the user, and replaced parts become the property of B&K Precision. In the event of insurance coverage, the product becomes the property of the insurance company at its exclusive request. Otherwise it remains the property of the user. The warranty applies only to equipment manufactured and supplied by B&K Precision. Any intervention or modification carried out by the user or by a third party without prior authorization from the company will invalidate the warranty. The user is responsible for returning the device to our premises. He must therefore ensure that the packaging provides adequate protection during transport. We recommend using the original packaging. The customer is responsible for taking out the necessary transport insurance. B&K Precision reserves the right to refuse poorly-packaged products, and not to offer repairs if the breakage is due to transport. Particular case of the battery: if a Li-ion battery is fitted to this device. It must not be transported outside the unit. Under no circumstances should it be replaced by the user. It must be replaced at the factory, so that the charging system and protective devices can be checked. This equipment must be transported in accordance with international guidelines for the carriage of equipment containing hazardous materials.

#### 10.2.2 Packaging

The packaging for this product is entirely recyclable. Thanks to its design, it enables your instrument to be transported in the best possible conditions. We draw your attention to the fact that the original packaging must be over-packed, if it is to be used for transport by air, road or post. We recommend keeping the original packaging for all transport.

#### 10.2.3 After-sales contact

Help with operation and malfunctions or breakdown :

In the event of a malfunction, please check the software version of your device first, or contact our technical support if you have problems using it.

#### support@bkprecision.com

#### 10.2.4 Elements of tactile acceptance

Your SEFRAM device is equipped with an active matrix color LCD display. This screen is sourced from reputable manufacturers. Under current technical manufacturing conditions, these manufacturers are unable to guarantee 100% correct operation of the pixels in the display area. They specify a number of defective pixels on the screen

surface. SEFRAM's quality department has made installation of your instrument's display conditional on compliance with the manufacturers' acceptance conditions.

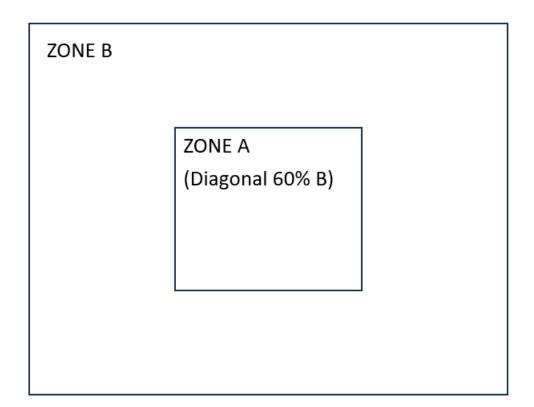


Figure 10.2: Display areas

Acceptance criteria:

- Zone A (central zone): fewer than 5 defective pixels in total and fewer than 3 contiguous pixels.
- Zone B (total screen area): less than 9 defective pixels over the entire screen area, with Zone A conditions met.

Defective pixels are defined as a point on the screen that remains unlit or lights up in a color other than the one expected. The contractual warranty only applies to the device in your possession if the above criteria are not met. This applies both at the time of delivery and during the warranty period.

## -Chapitre 11-

## Annexes

## 11.1 | Revisions

Version and date	Firmware version associated	Modified chapters	Modification type
1.0 / October 2023	1.0.x	All	Document creation