



Össur Touch Solutions: Introducing the i-Limb® Wrist

Rob Hodgson (Clinical Specialist)

Webinar: 12th December 2019



Introduction

- i-Limb range
- Overview of features and benefits
- Control Methods
 - App control
 - Muscle triggers
 - Gesture control
 - Proximity control
- Technical specifications
- Introducing the NEW i-Limb Wrist



Introduction

Overview of i-Limb range



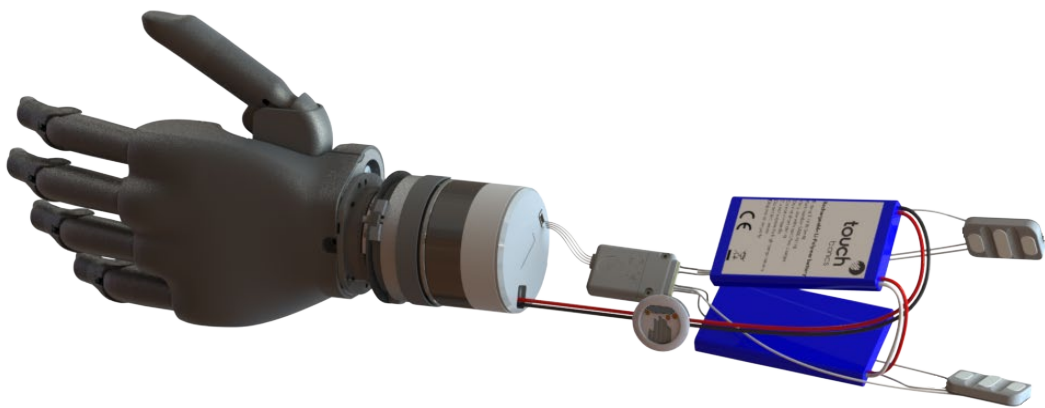
- i-Limb Access
- i-Limb Ultra
- i-Limb Quantum

NEW: i-Limb Wrist



Introduction to i-Limb Wrist

- **i-Limb Wrist** is a powered wrist rotator
- Two main features:
 - Simultaneous Rotation upon grip selection (when fitted in conjunction with the **i-Limb Quantum**)
 - Direct Rotation
- Controlled via 2 **digital electrodes** detecting specific muscle actions from the users residual limb



Basic i-Limb Hand Functions

- Significant advances in multi-articulating myoelectric prosthetic hand technology
 - Individually articulating digits
 - Stall ability
 - Compliant grip
 - Thumb rotation: powered (auto) and manual
 - Proportional control
 - Vari-grip or pulsing
 - Autograsp



Hand Operation

Basic Functions

Open & Close all 5
fingers around objects



Automated Grips

Precision Pinch

Index Point

Tripod Grip

Lateral Grip

And more...



User Profile for i-Limb hands

- Any level of upper limb absence proximal to the wrist:
 - Wrist disarticulation
 - Trans-radial
 - Elbow disarticulation
 - Trans-humeral
 - Shoulder disarticulation
- **Low to moderate usage**
- Clients should:
 - Be motivated
 - Have realistic expectations



Optimum outcomes are achieved when Prosthetist and Therapist work closely together

i-Limb Range

i-Limb Access

- Manual thumb rotation
- 12 grip features
- Auto-grasp
- Pulsing
- App control: quick grips
- Muscle control: triggers



i-Limb Ultra

All features of i-Limb Access plus...

- Powered rotating thumb with manual override
- 18 grip features
- Vari-grip

i-Limb Quantum

All features of i-Limb Ultra plus...

- Gesture control: access 4 grips with single muscle action
- Proximity control: grip chips
- 24 grip features
- 12 custom my grips

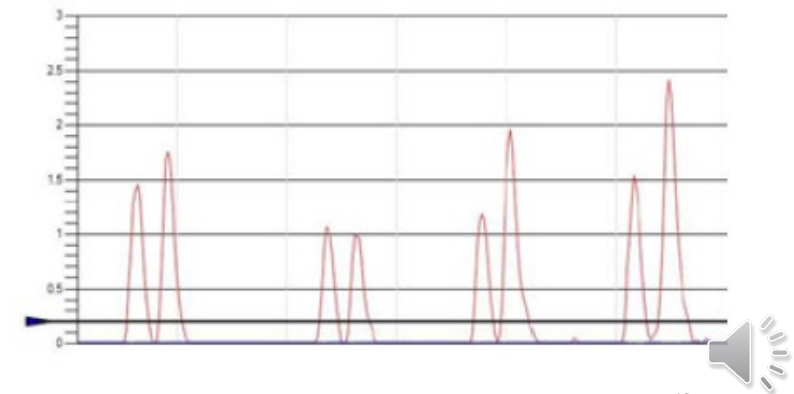
Accessing Multiple Automated Grips: App Control

- App control: quick grips
- Use **Biosim**® (CPO) or **My i-Limb**® (patient) app to connect to hand via Bluetooth
 - iPad
 - iPhone
 - iPod
 - Apple Watch
- Tap icon to choose desired grip
- Useful for infrequently used grips



Accessing Multiple Automated Grips: Muscle Control

- Muscle control: triggers
- Use EMG muscle trigger signals to choose desired grips
 - Hold open
 - Co-contraction
 - Double (open) impulse
 - Triple (open) impulse
- Each trigger is pre-programmed with one grip by the user
- Favorites can be created for groups of commonly used triggers, such as for cooking, office, gym, etc.
- Require more time to learn and more effort to control hand

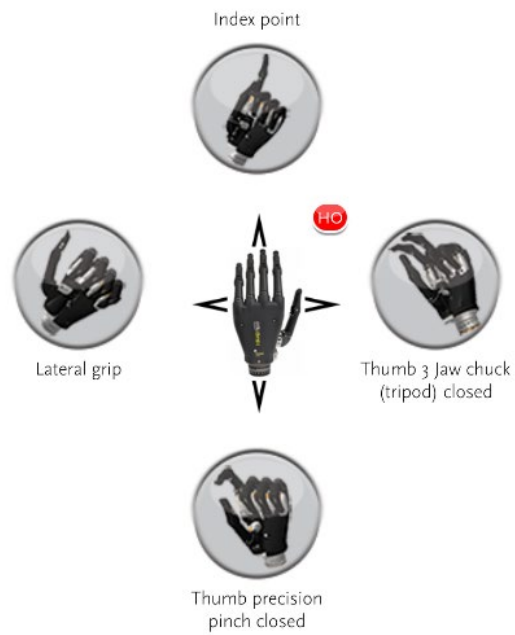


Accessing Multiple Automated Grips: **Gesture Control**

- Gesture control: i-mo intelligent motion
- With multiple automated grips available, the user must learn to access his desired grips consistently
- App, Muscle, and Proximity Control require the user to learn more advanced techniques with their muscles or use additional accessories
- Gesture control uses simple gestures (forward, backward, left, right) to choose desired grips
- Each direction is pre-programmed with one grip by the user
- No need for additional muscle learning nor accessories



Example of changing grips: Gesture Control

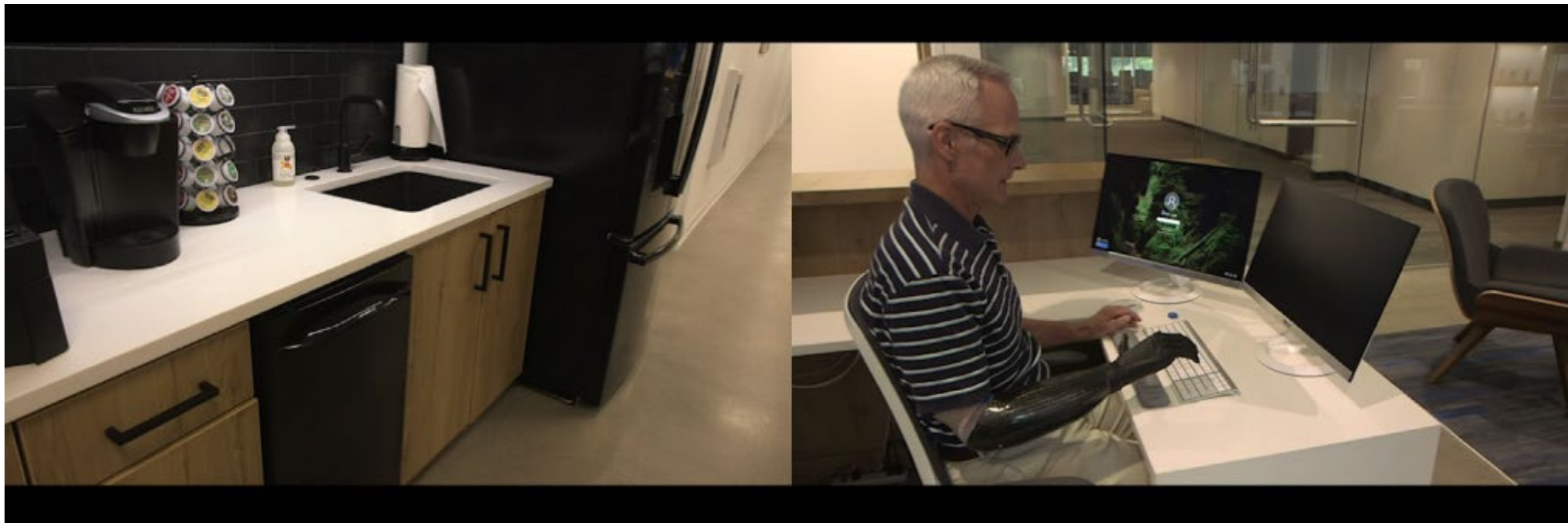


Accessing Multiple Automated Grips: **Proximity Control - Grip Chips**

- Proximity control: grip chips
- Bluetooth device that allows i-Limb to enter grips when nearby the chip (15cm)
- Each grip chip is pre-programmed with one grip or favourite group of grips by the user (Biosim or My i-Limb app)
- Activated by proximity or double tapping



Grip Chips



Technical Details: Titanium Digits

- Titanium material increases the maximum carry load at the proximal segment by 50%
- Improves the protection of the motor from impact forces
- Adds only 28 grams of weight to the i-Limb[®] hand
- Available for i-Limb[®] Quantum, Ultra, and Access hands and for i-Limb[®] hand sizes small, medium, and large



Small



Medium



Large

Stage 1: Opening & Closing

Picking up objects



Stalling digits

Positioning the thumb



Varying the grip force

Stage 1

Training

Stage 2: Accessing Multiple Grips

gesture control



app control

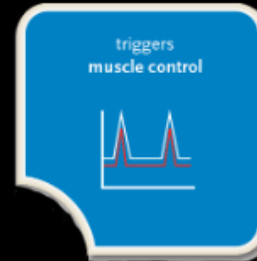


Stage 2

Training progression

Stage 3: Advanced options

muscle control: triggers



proximity control: grip chips



Stage 3

Advanced training

Introduction

Setup

Grips

i-Limb Wrist

Product range

Resources

<https://www.ossur.com.au/prosthetic-solutions/touch-solutions/support-services/training-module>

Stage 1

i-Limb Wrist

Stage 2

i-Limb Wrist

Stage 3

i-Limb Wrist



i-Limb Wrist

- Introduction
- User Profile
- Control Methods
 - Simultaneous Rotation
 - Direct Rotation
- Control Options
 - Smart Control
 - High/Low
 - Co-Contraction
- Features and Benefits
- Setup with Biosim
- Technical Details

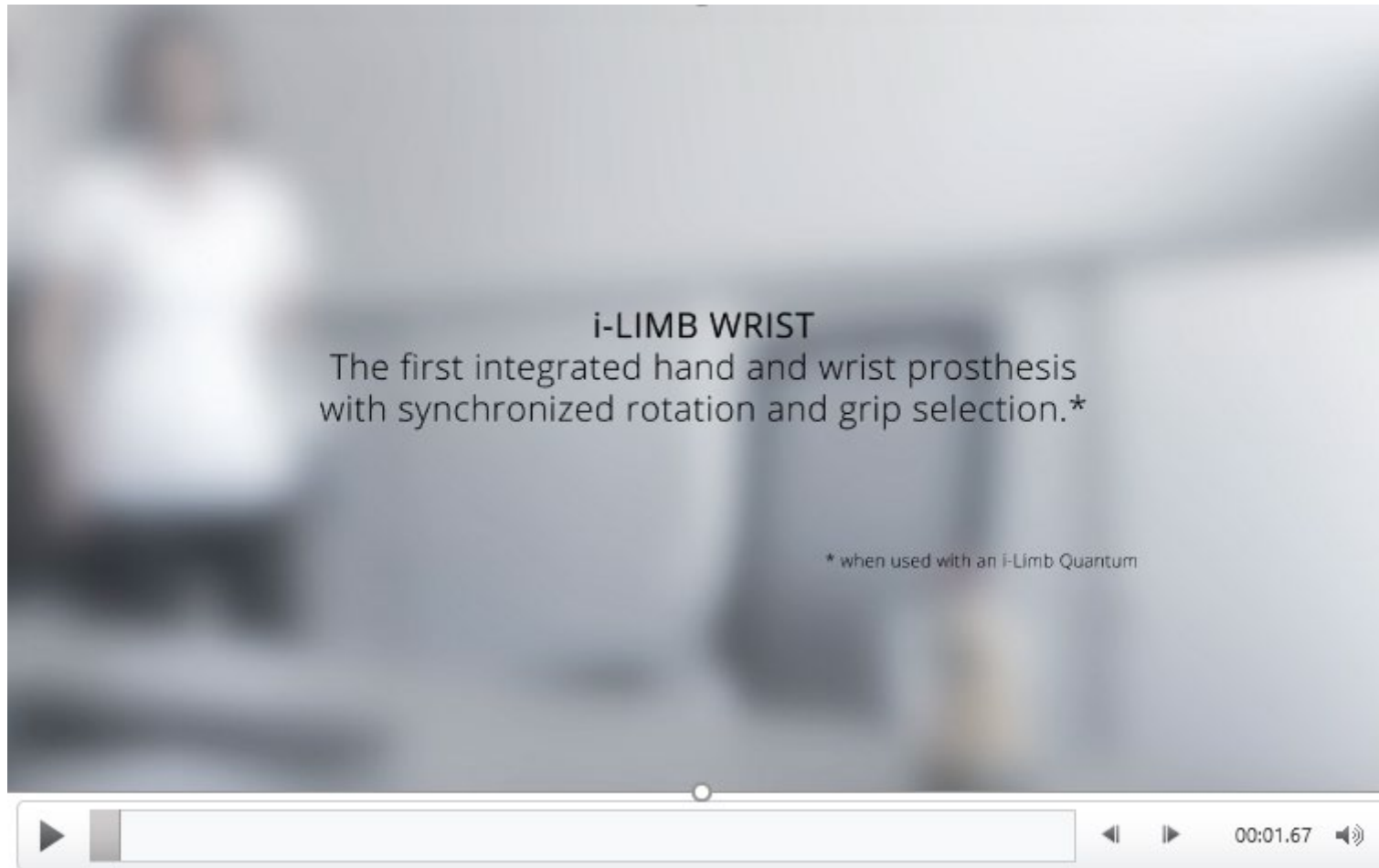


Introduction: i-Limb Wrist

- **i-Limb Wrist** is a powered wrist rotator
- Controlled via 2 digital electrodes detecting specific muscle actions from the user's residual limb
- Two main features:
 - Simultaneous Rotation upon grip selection (only with **i-Limb Quantum**)
 - Direct Rotation
- Direct Rotation control methods:
 - Smart Control
 - High / Low
 - Co-contraction



Introduction to i-Limb Wrist



User Profile

Indications:

- Transradial-level absence
- Two viable control sites
- New and existing myoelectric users

Contraindications:

- Users unable to use two viable control sites
- More proximal level of absence
- Long transradial without room for a wrist (56mm)



Introduction to i-Limb Wrist: Control

Simultaneous rotation

- i-Limb Quantum

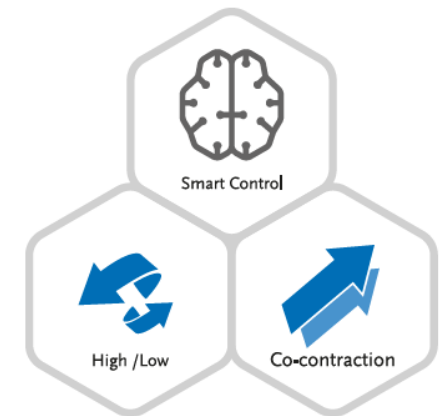


Direct rotation

- i-Limb Access
- i-Limb Ultra
- i-Limb Quantum

Control Methods

- Simultaneous rotation with grip selection
 - Grip is entered using any **i-Limb Quantum** control option (gesture, app, muscle, proximity)
 - Wrist automatically and simultaneously rotates to the optimum position for that grip
- Direct rotation from users muscle actions
 - **Smart Control** identifies intuitive muscle actions from the user during initial set up process with Biosim app
 - Allowing calibration of the prosthesis to the individual user
 - **Alternative direct rotation control methods:**
 - High/Low and Co-contraction offer availability of conventional control methods to also be used for the i-Limb Wrist



Simultaneous Rotation

All methods of control



APP



MUSCLE



GESTURE



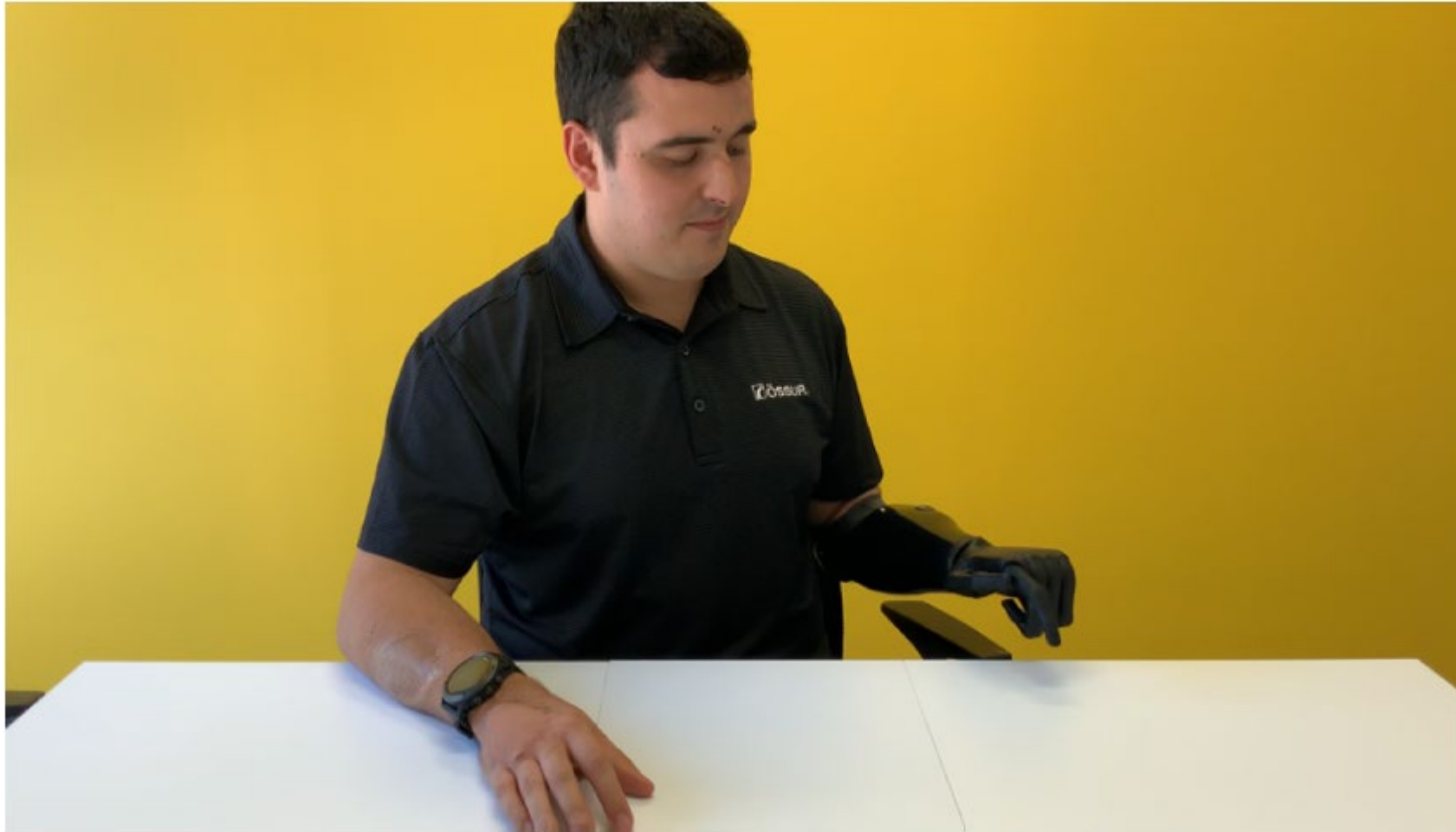
PROXIMITY

Pre-defined positions

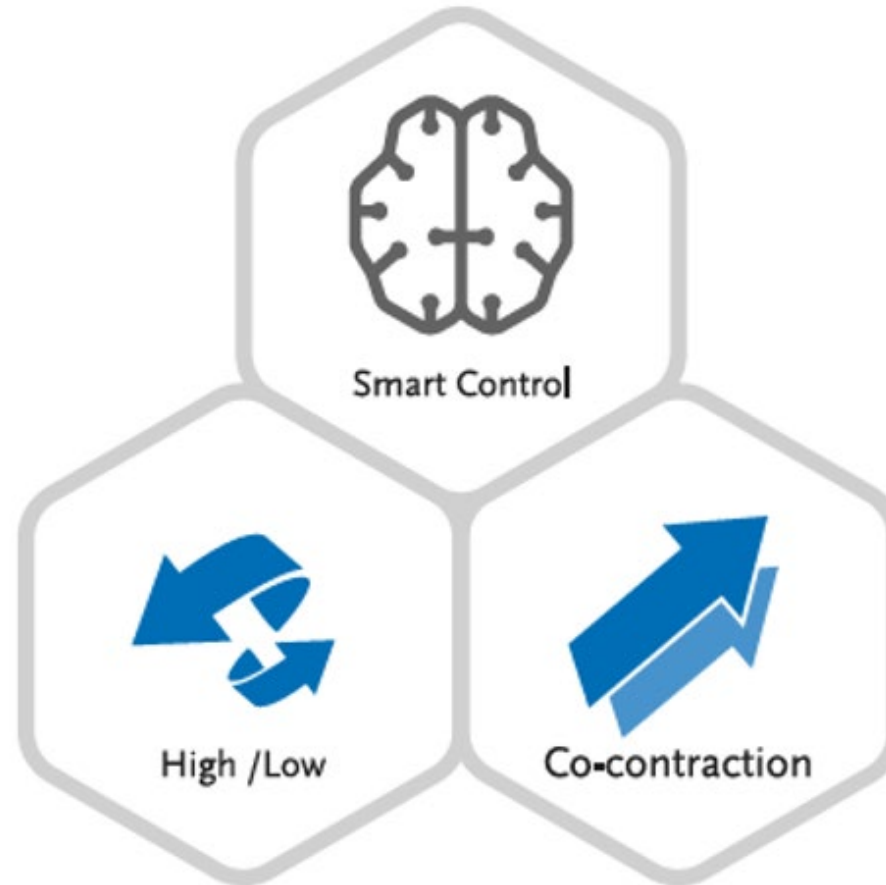
Grip	Wrist rotation
Pinch	45°
Tripod	45°
Thumb park quick	Palm facing inwards
Lateral	Palm facing inwards
Index point	Palm facing downwards
Open palm	Palm facing upwards
Handshake	Palm facing inwards
Grasp	Palm facing downwards
Trigger grips	Palm facing inwards
Cylindrical	Palm facing inwards
Natural hand	No rotation set
My Grips	Full configurable



Simultaneous Rotation

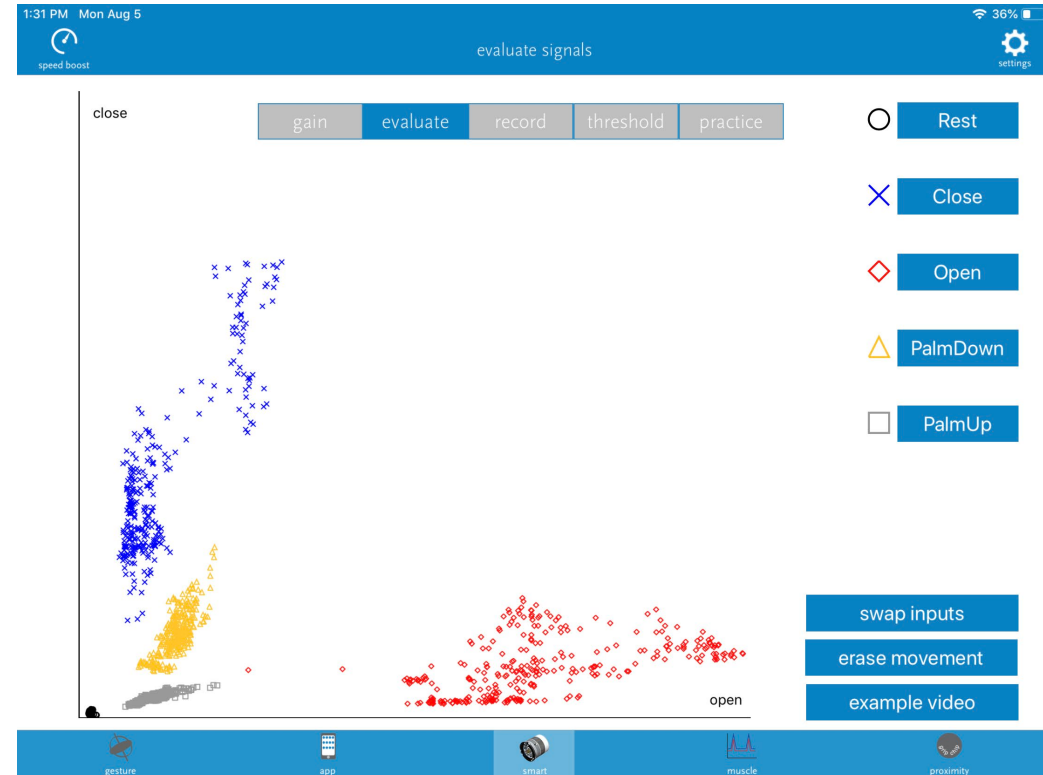
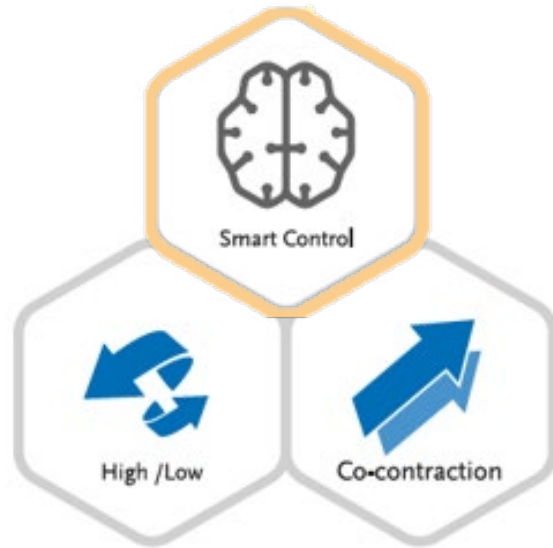


Direct Rotation: 3 Methods of Control



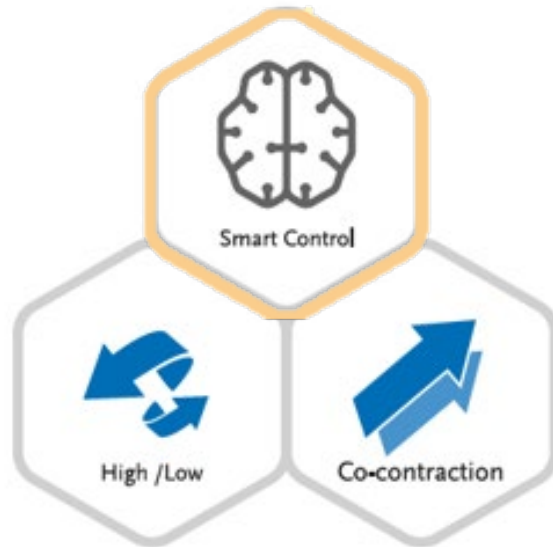
Control strategy is selected based on the users needs, capabilities and preference

Direct Rotation: Smart Control

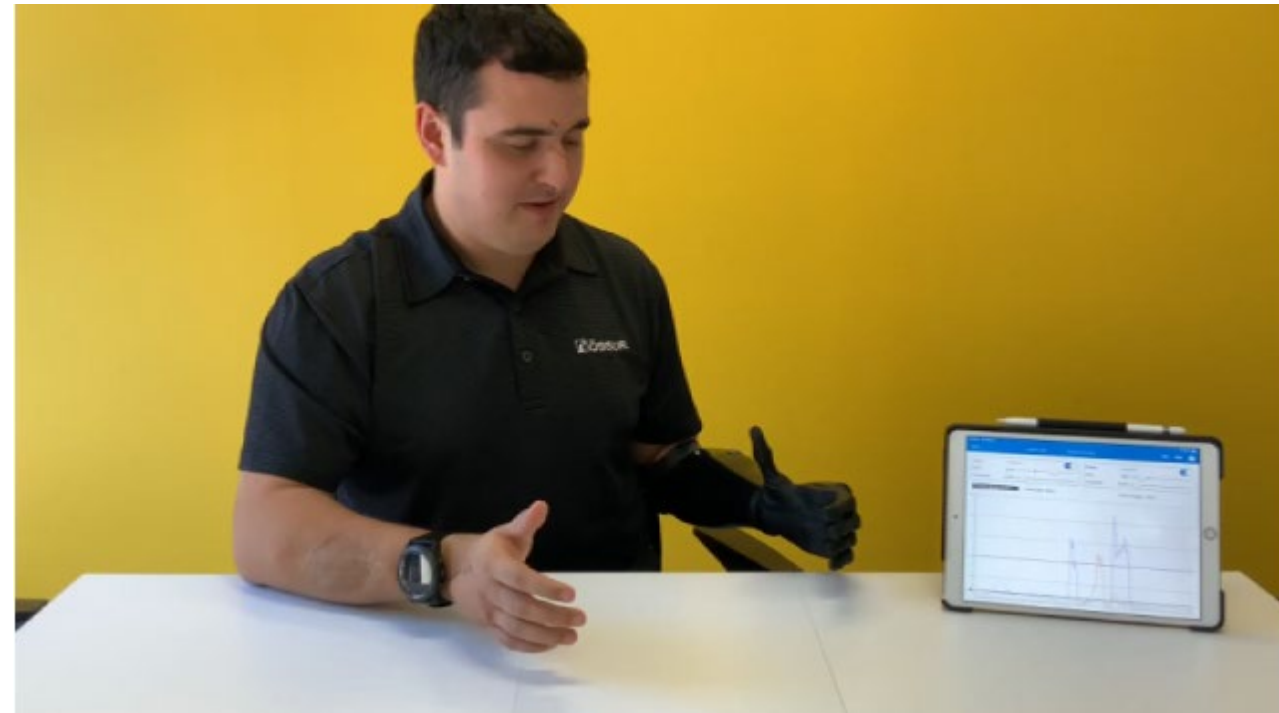
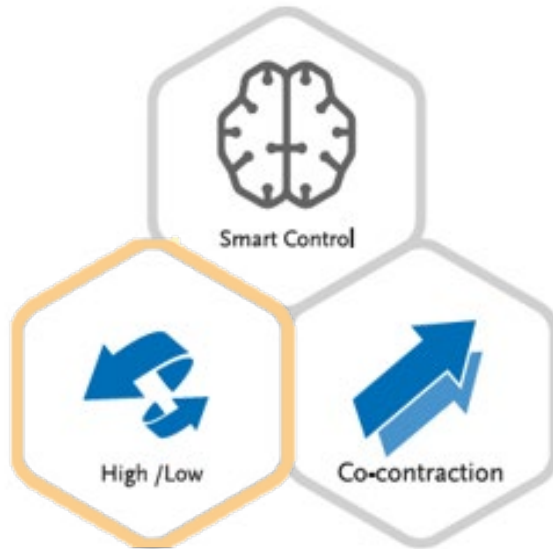


- Identifies muscle actions during initial setup
- Calibration of rest, close, open, palm up, palm down
- Pattern recognition with only 2 electrodes

Smart Control: Example

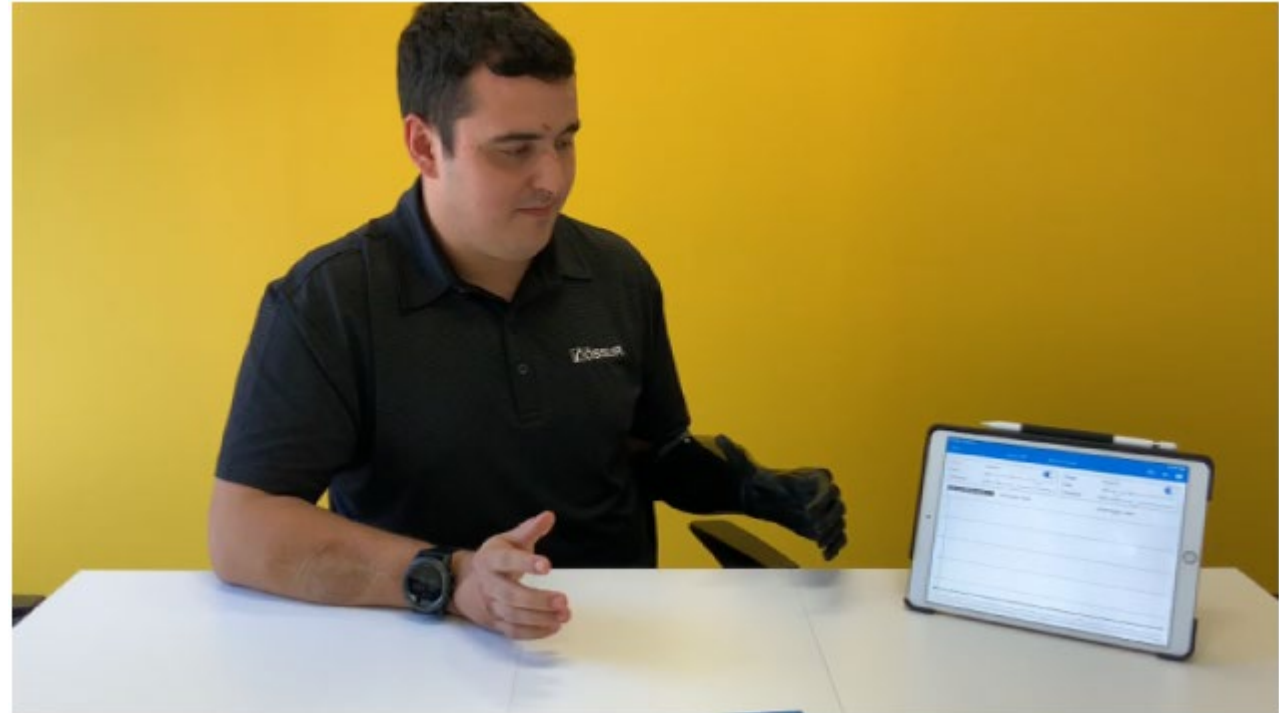
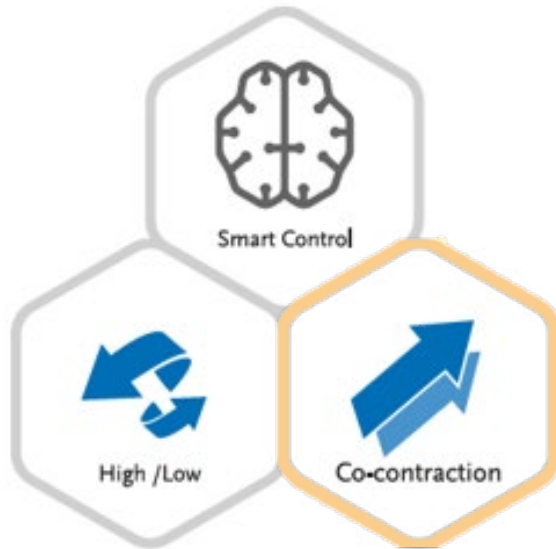


High/Low



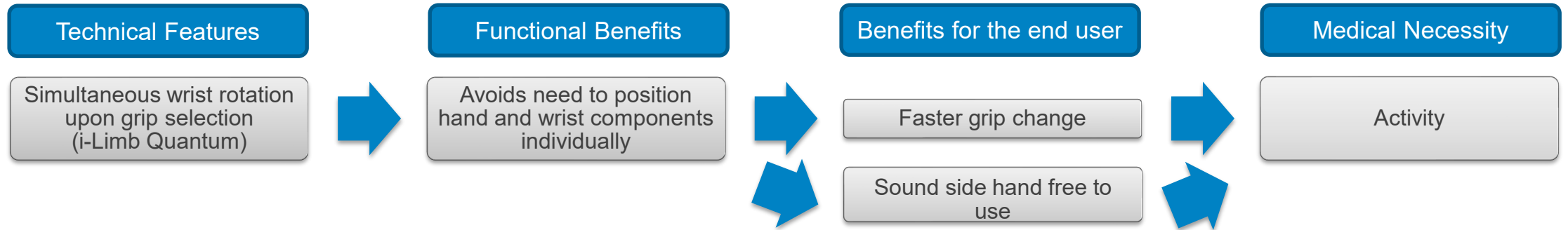
- High (fast and strong) rising signal operates the wrist
- Low (slow and gentle) rising signal operates the hand

Co-Contraction



- Fast rising signal of both muscles at the same time switches control between the hand and wrist

Features & Benefits: Simultaneous Wrist Rotation



Horizontal position



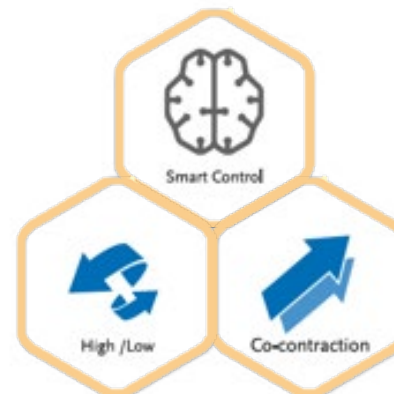
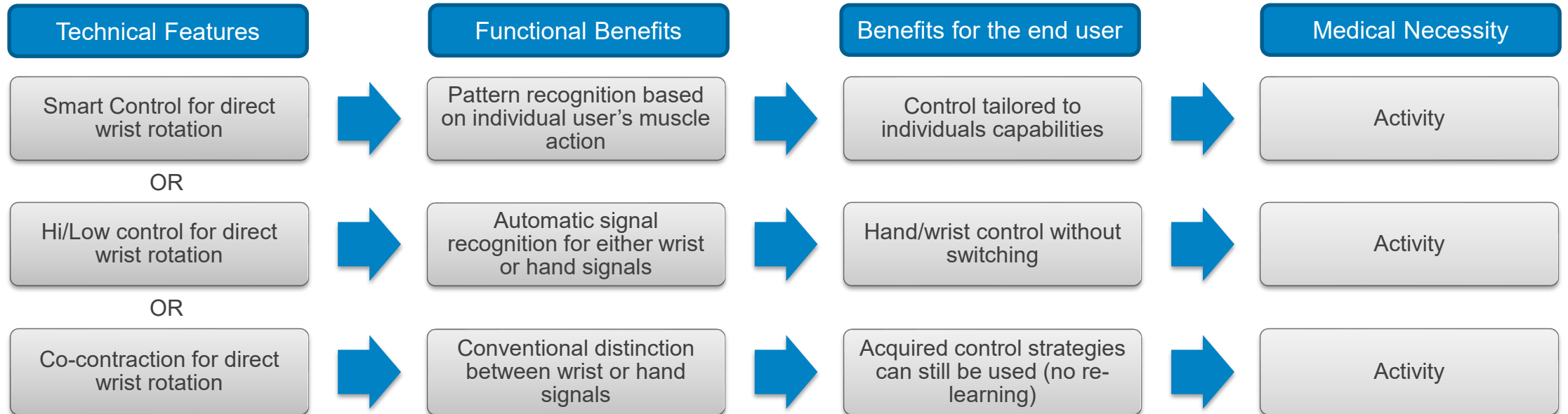
Grip Activation



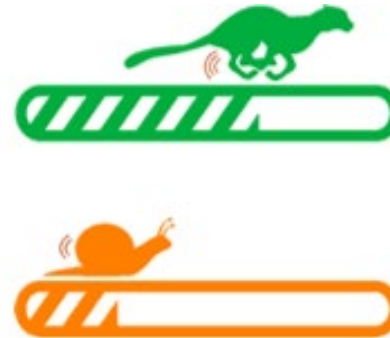
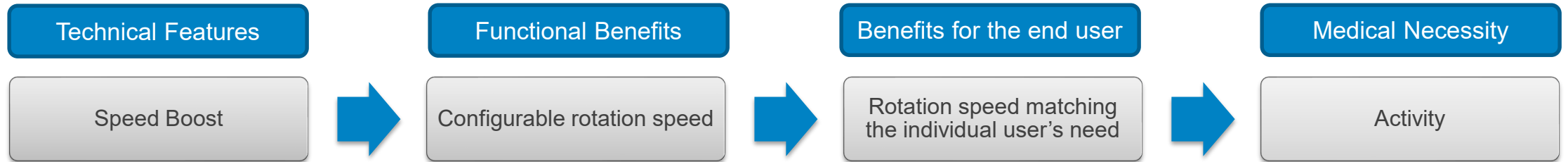
Wrist Rotation to Pre-Defined Position

Grip	Wrist rotation
Pinch	45°
Tripod	45°
Thumb park quick	Palm facing inwards
Lateral	Palm facing inwards
Index point	Palm facing downwards
Open palm	Palm facing upwards
Handshake	Palm facing inwards
Grasp	Palm facing downwards
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Cylindrical	Palm facing inwards
Natural hand	No rotation set
My Grips	Full configurable

Features & Benefits: Direct Wrist Rotation



Features & Benefits: Speed Boost

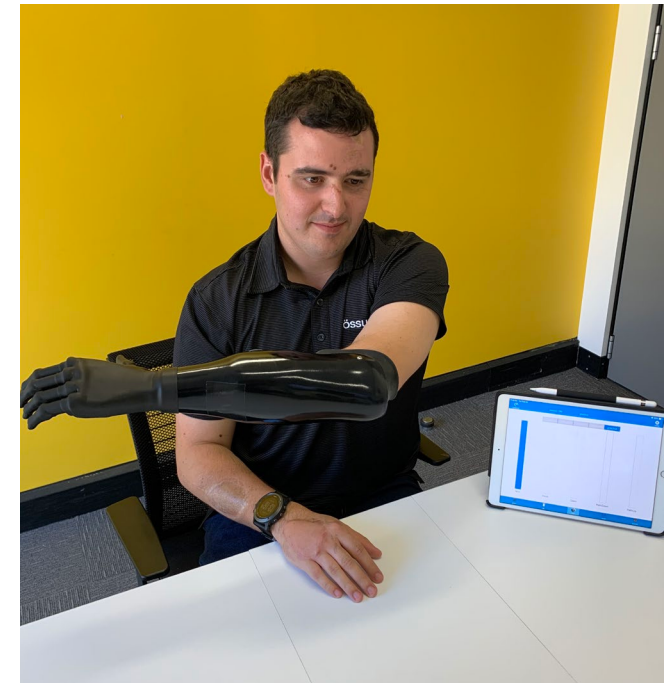
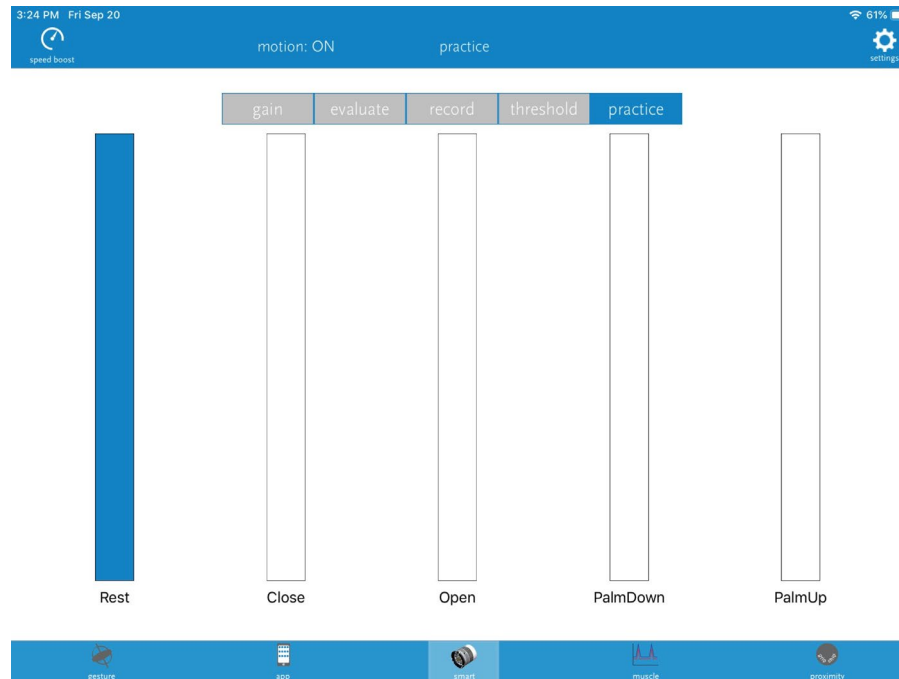




Biosim: with clinician, user can practise and fine tune setup before using prosthesis



My i-Limb: addition of practise mode, for user to practise Smart Control away from clinic



i-Limb Wrist setup via Biosim



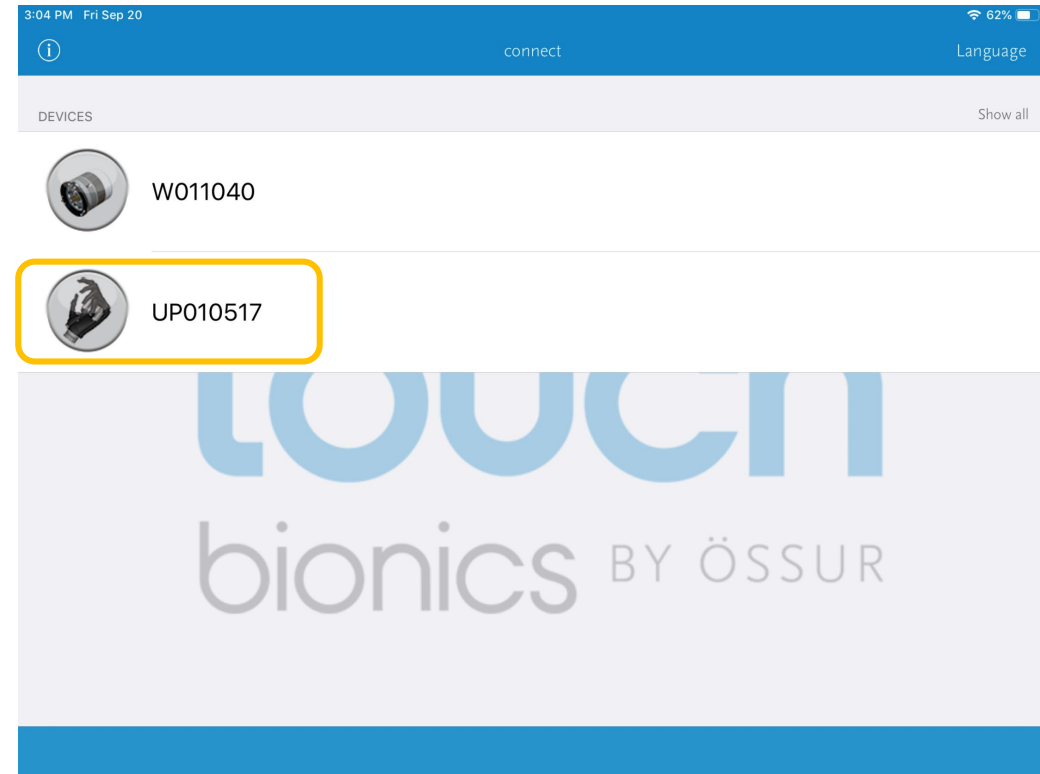
- Set up of the **i-Limb Wrist** and **i-Limb Quantum** hand via **Biosim** on iPad.
- **Digital electrodes** are positioned on the residual limb in the optimum position identified through myo-testing
- User activates muscle actions which feel most intuitive to them for the open/close/palm up/palm down movements.
- A recording process is followed in **Biosim** app with the user repeating each of these actions and also the rest action.
- A successful recording is automatically applied to the **i-Limb Wrist** and **i-Limb Quantum** hand

Smart Control Setup: Connecting

- Connecting with i-Limb Quantum



- Connecting with i-Limb Ultra or Access

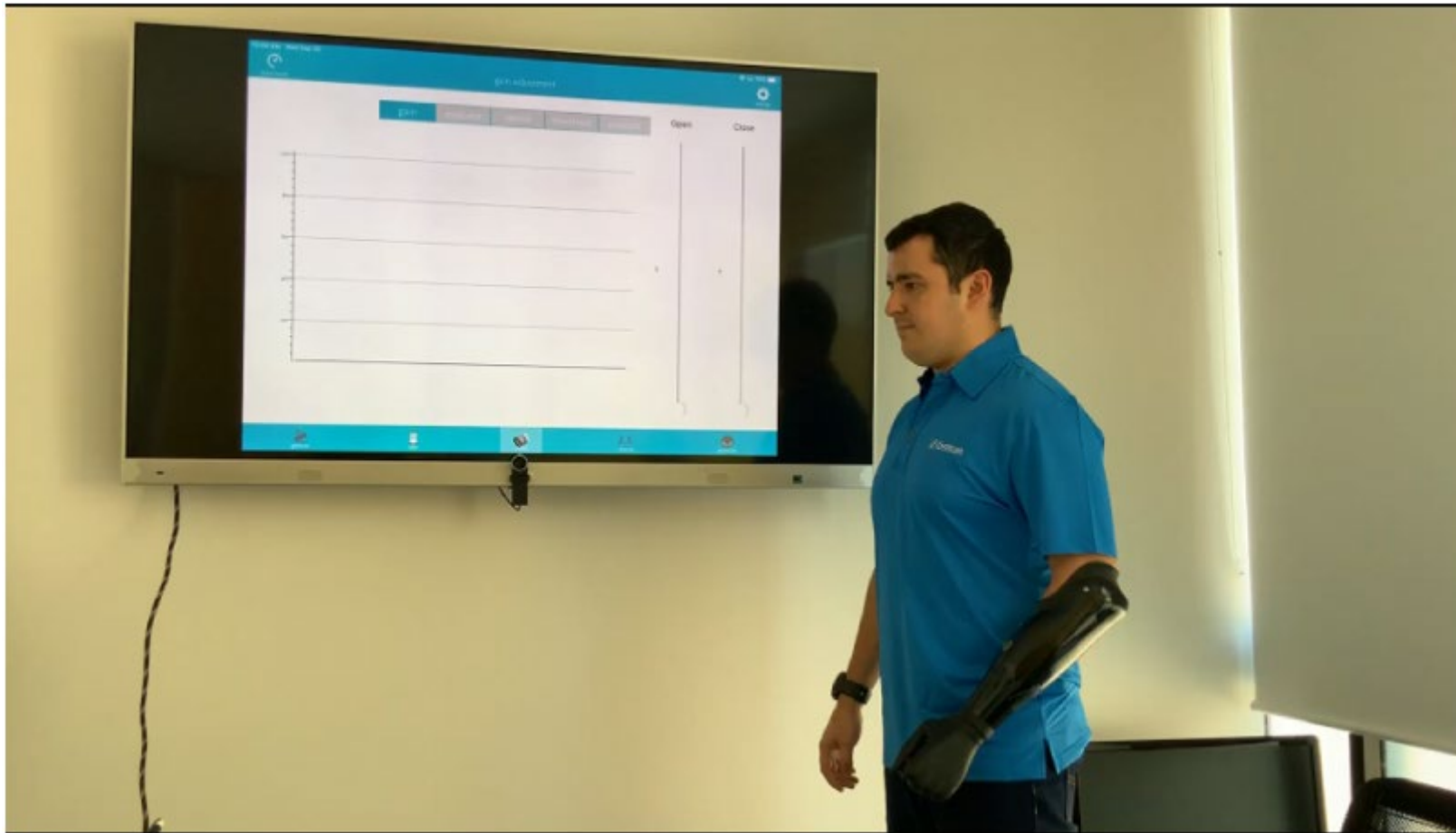


Smart Control Setup: Gain Adjustment

- Myo-testing with myograph using digital electrodes
- Expect different signals due to these electrodes being digital – more interference in graph
- Alter gains so that user can reach 70-80 on graph
 - This allows more signal for palm up/palm down as these movements are weaker

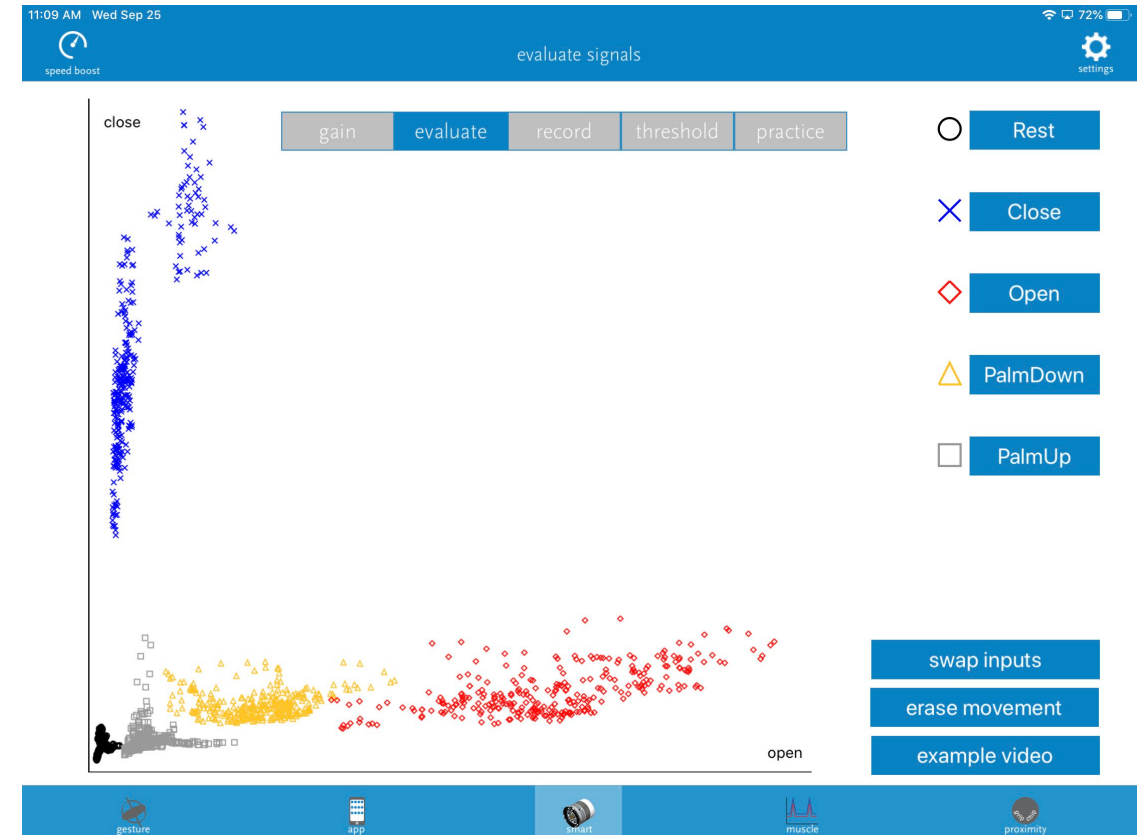


Smart Control Setup: Gain Adjustment

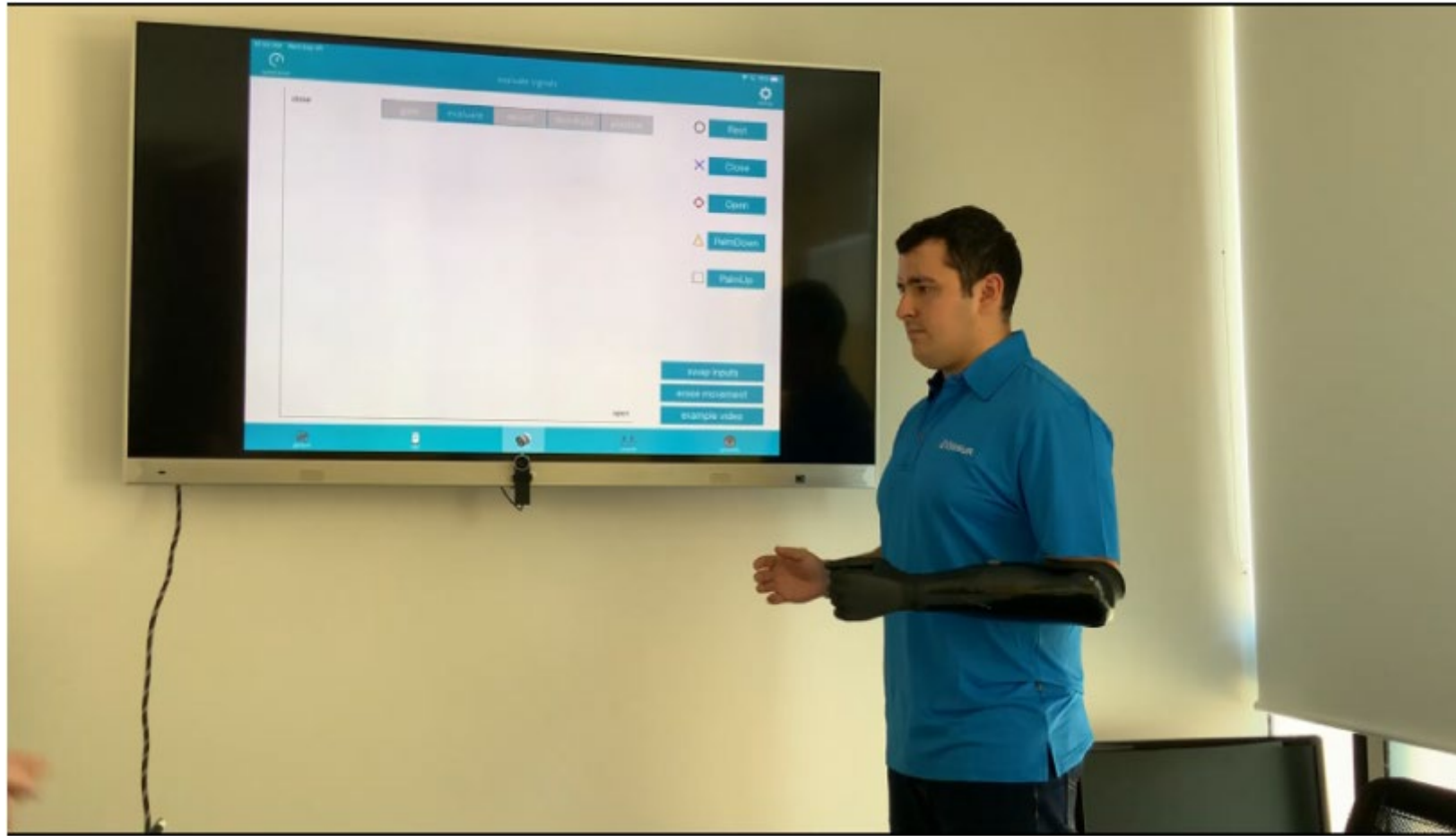


Smart Control Setup: Evaluate

- Spend time practising movements with the user
- Ensure separation of signals before proceeding to the recording process
- Erase all recordings before progressing to next stage

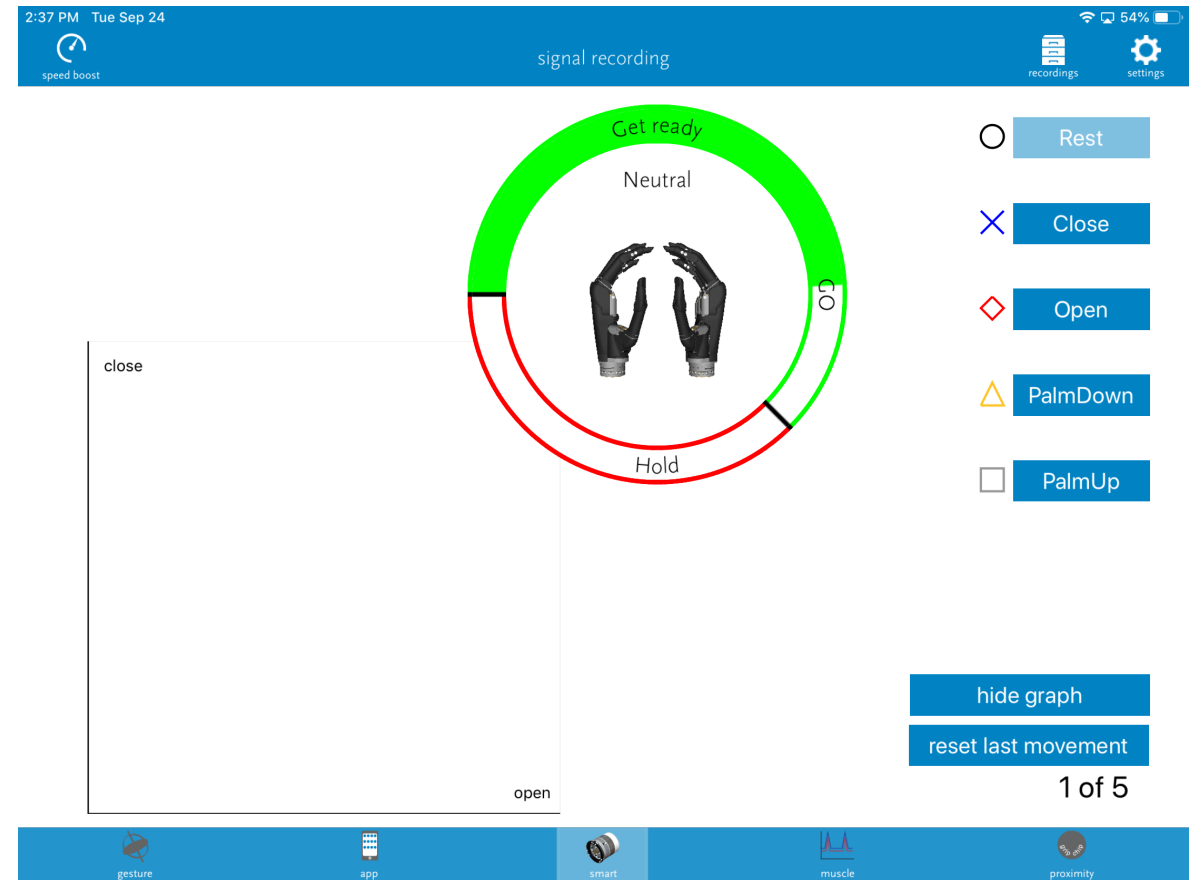


Smart Control Setup: Evaluate

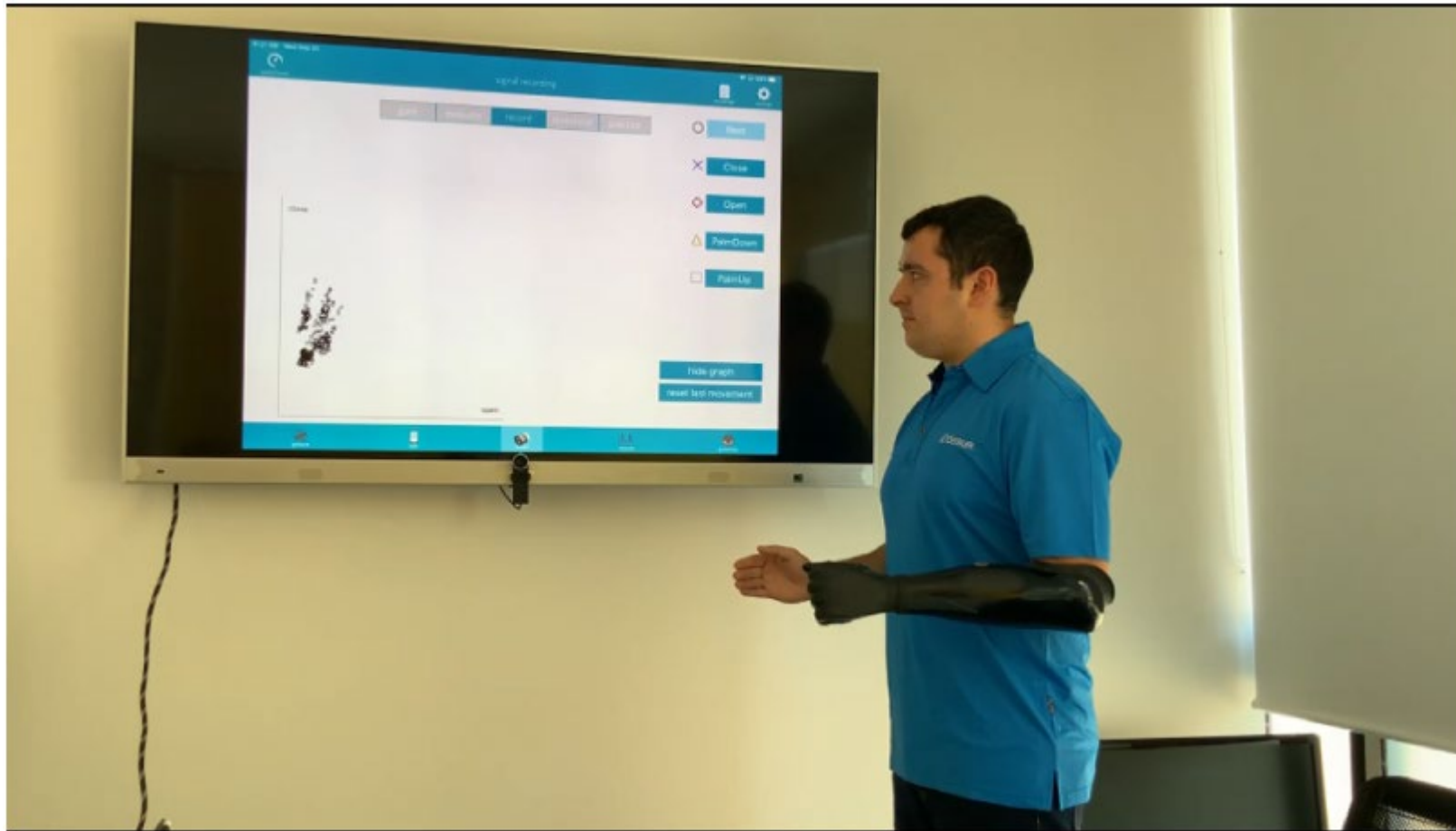


Smart Control Setup: Record

- Record each movement individually
- Having the graph on display can help prompt the user
- Follow the prompts during the recording process
- Last recorded movement can be erased to ensure optimum signals are obtained

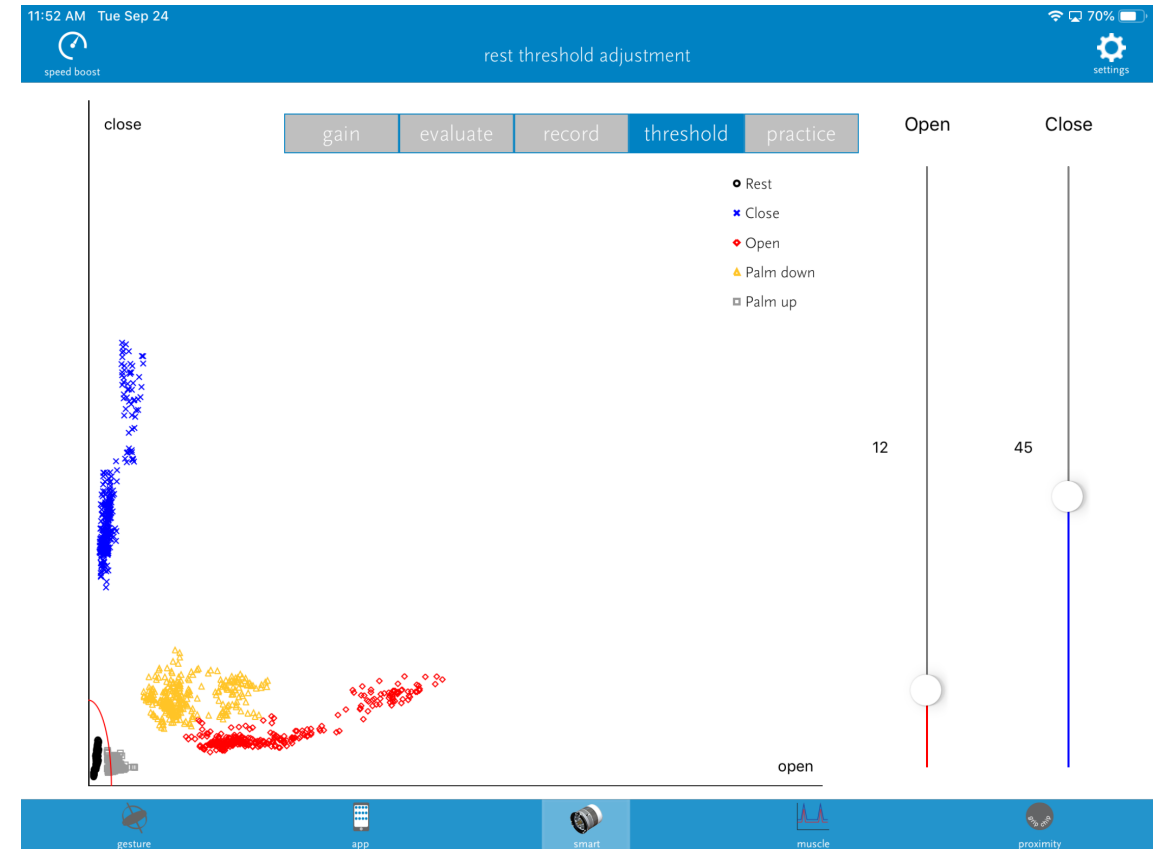


Smart Control Setup: Record

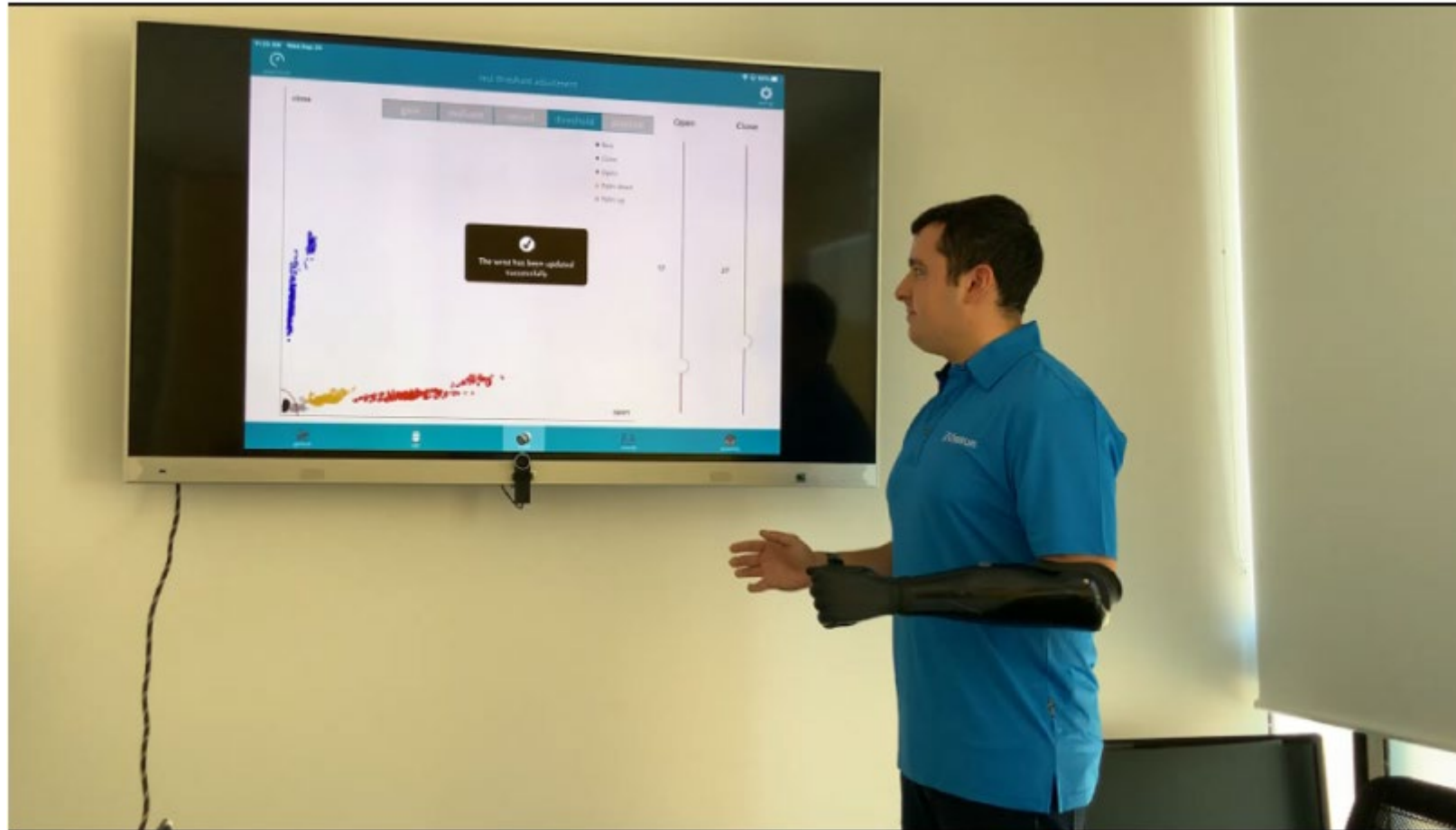


Smart Control Setup: Rest Threshold

- Capture Rest signal using arc
 - This helps wrist separate functional movement
- Change arc size by using open and close sliders
 - Capture all of rest (black)
 - Turns all additional captured movements into rest (closest to rest)
 - Eliminates palm up/palm down movements when weight is added to limb e.g. shopping bag

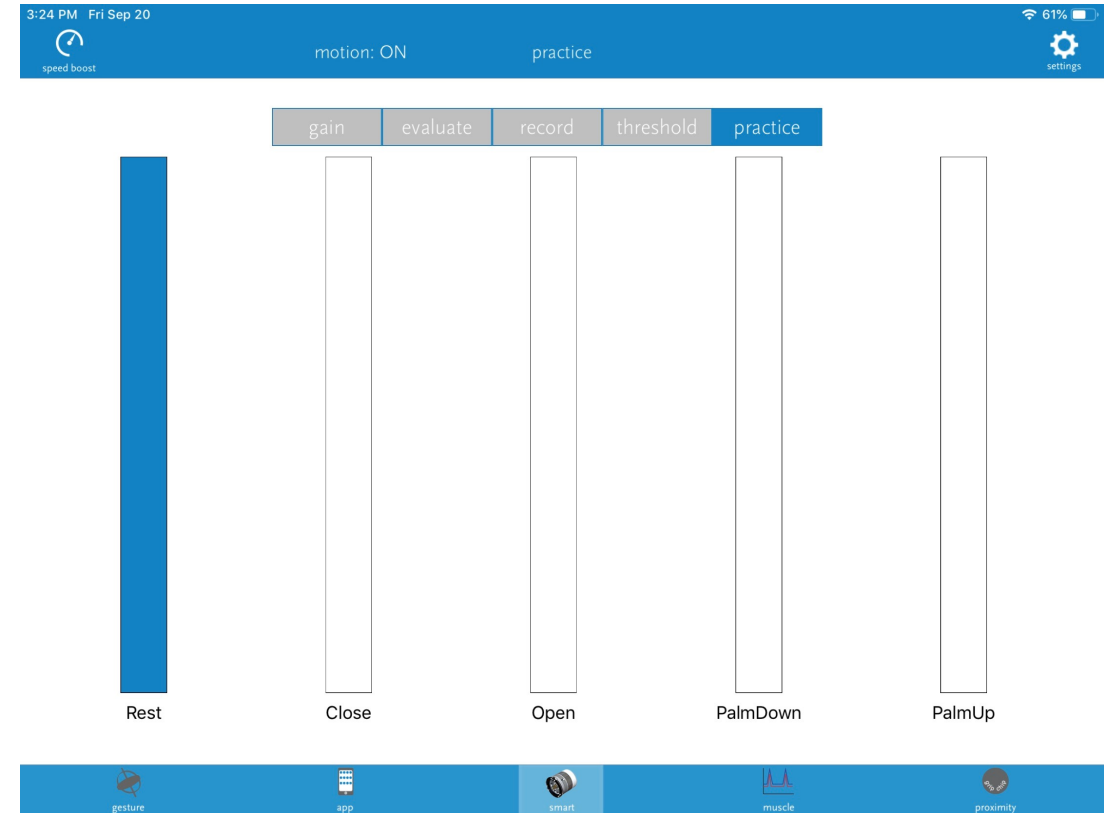


Smart Control Setup: Rest Threshold Adjustment



Smart Control Setup: Practise

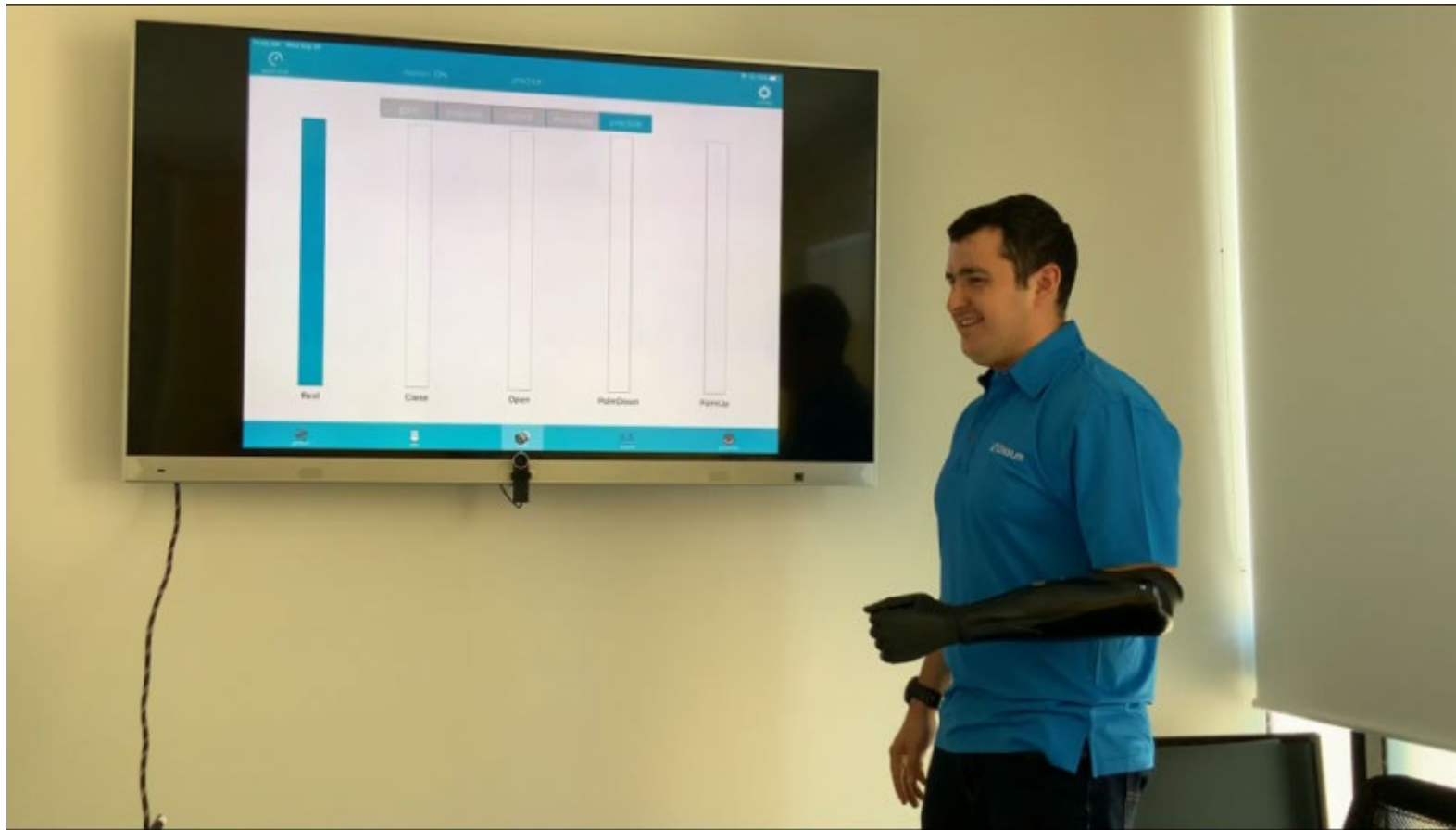
- Each bar represents a movement and will light up to identify which movement is being performed by the user
- Provides a visual feedback to demonstrate what user is doing
- Practise signal separation in various body positions (arms wide, above head, forwards and down)
- Practise purposeful rest in-between movements



Smart Control Setup: Practise



Smart Control Setup: Practise Control



Setup: High / Low and Co-contraction

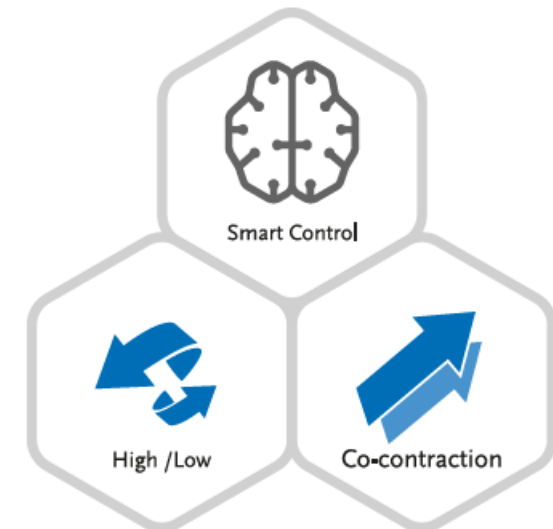
If the user is unable to utilise Smart Control initially, there are alternative control methods available:

- **High / Low**

- A slow (low) rising signal operates the hand
- A fast (high) rising signal operates the wrist:
 - A fast (high) rising **OPEN = Palm up**
 - A fast (high) rising **CLOSE = Palm down**

- **Co-contraction**

- A fast-rising contraction of both muscles at the same time switches control between hand and wrist
- If using co-contraction to switch between hand and wrist control, then co-contraction will not be available for accessing grips (either for gesture control or a muscle trigger)

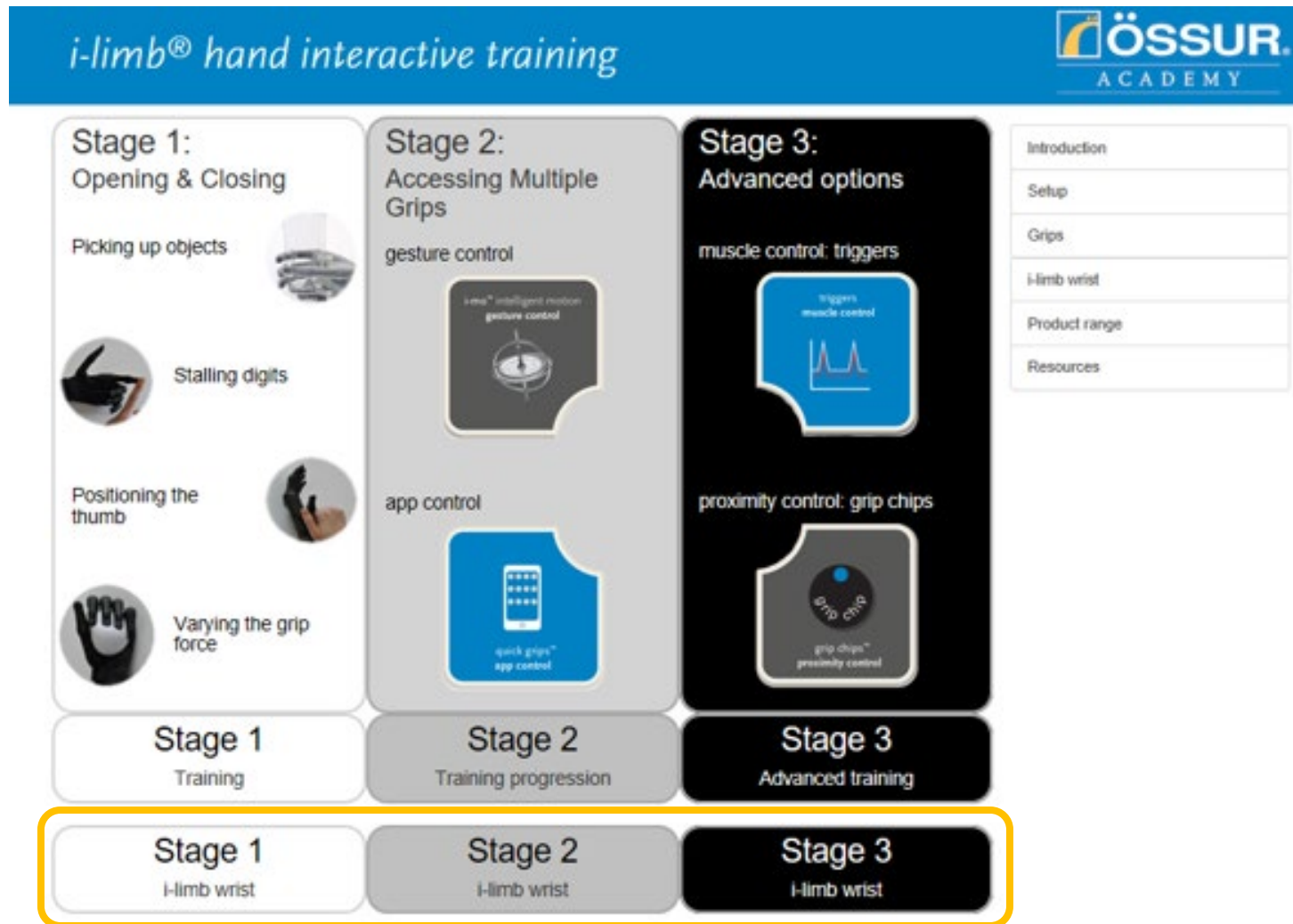


Setup: High / Low and Co-contraction

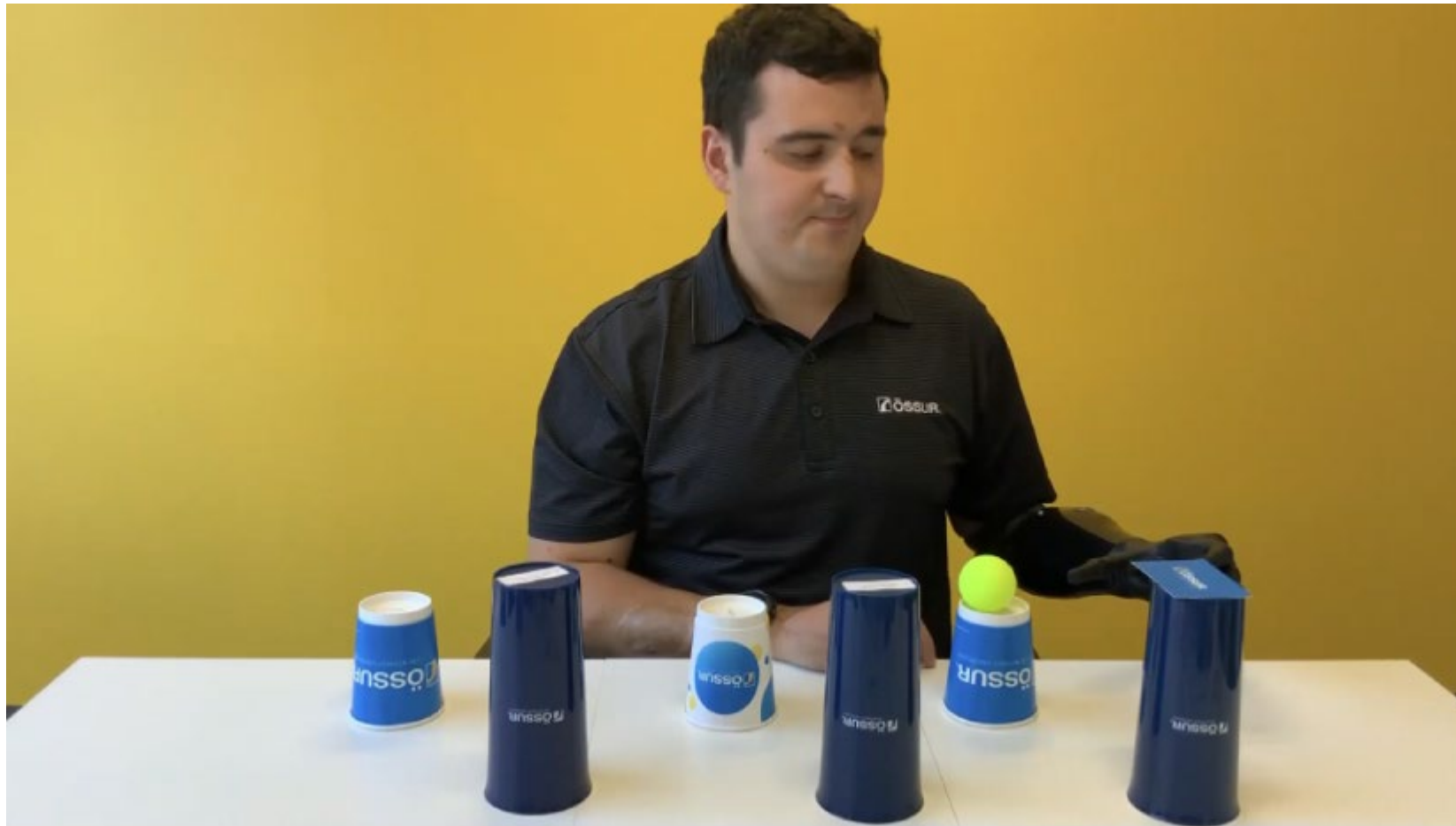


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Done Settings		General	
Setup	DEVICE INFO		
Grip settings	Hand name	M011643	
Global features	Wrist name	W011039	
i-limb wrist options	Load device settings from backup	>	
Control strategy	Reset device to factory defaults	>	
Health check			
Hand usage data			
Wrist usage data			
Language			
About			

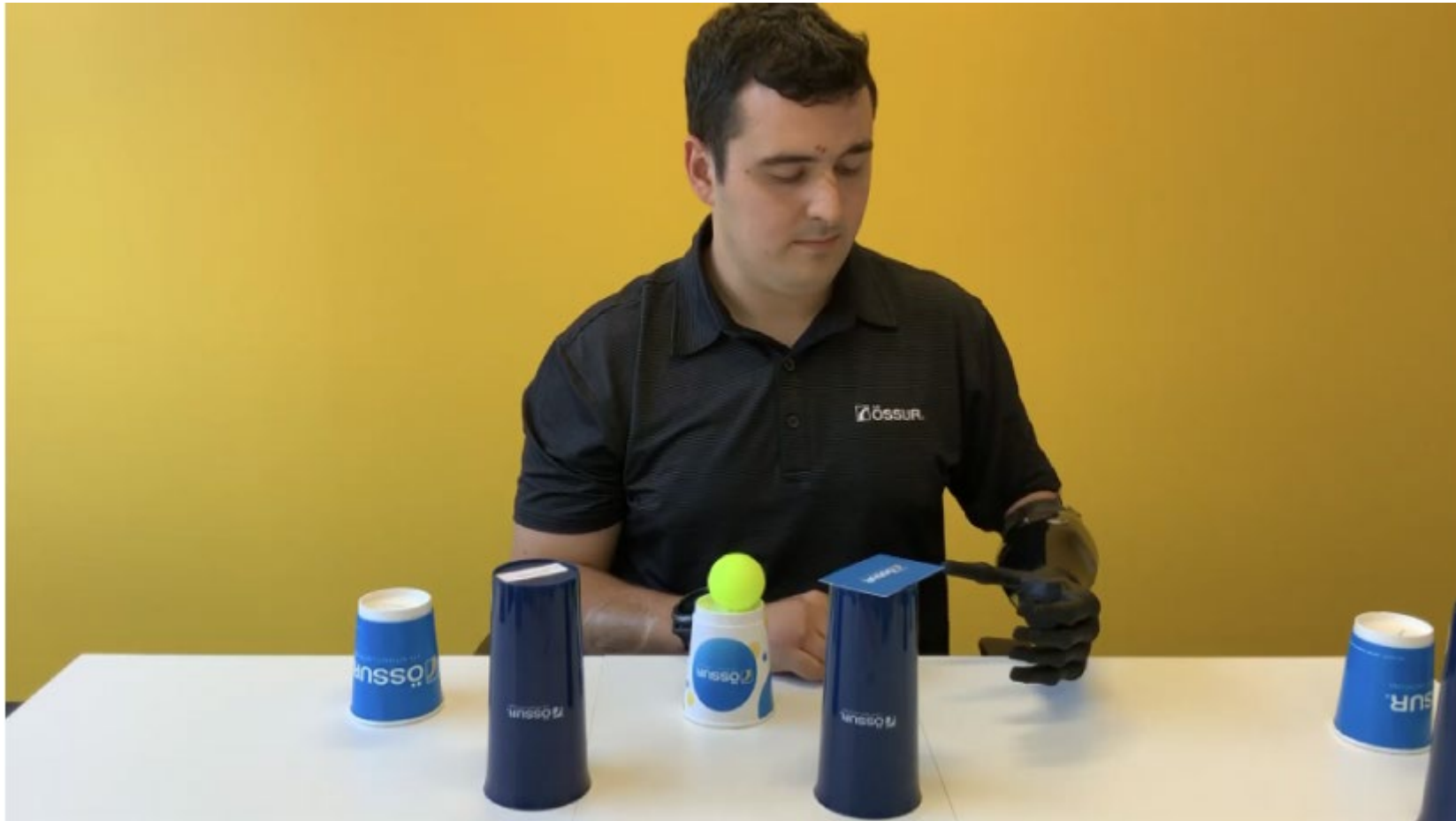
Staged Training Approach



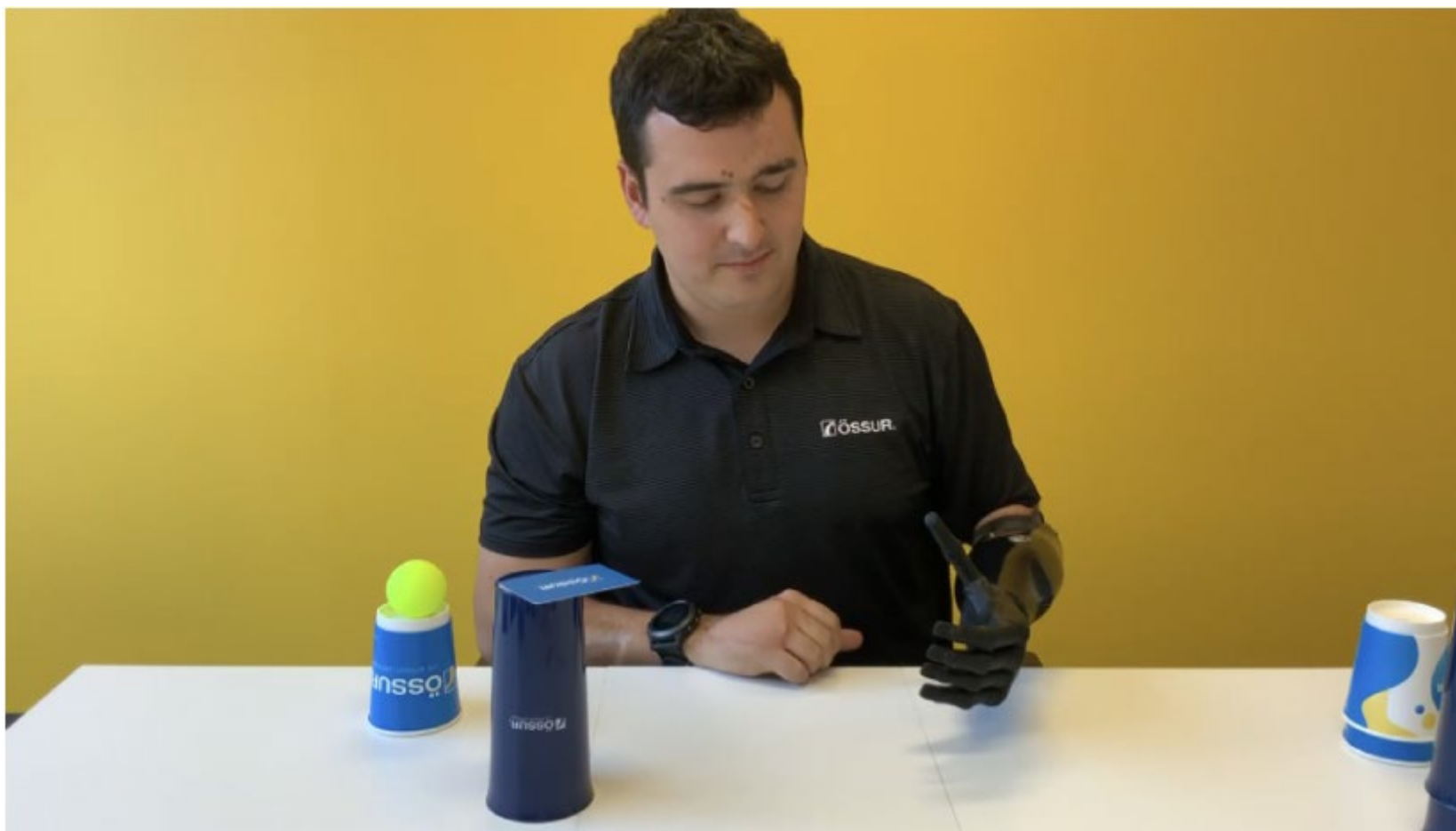
Stage 1 Training



Stage 2 Training



Stage 3 Training

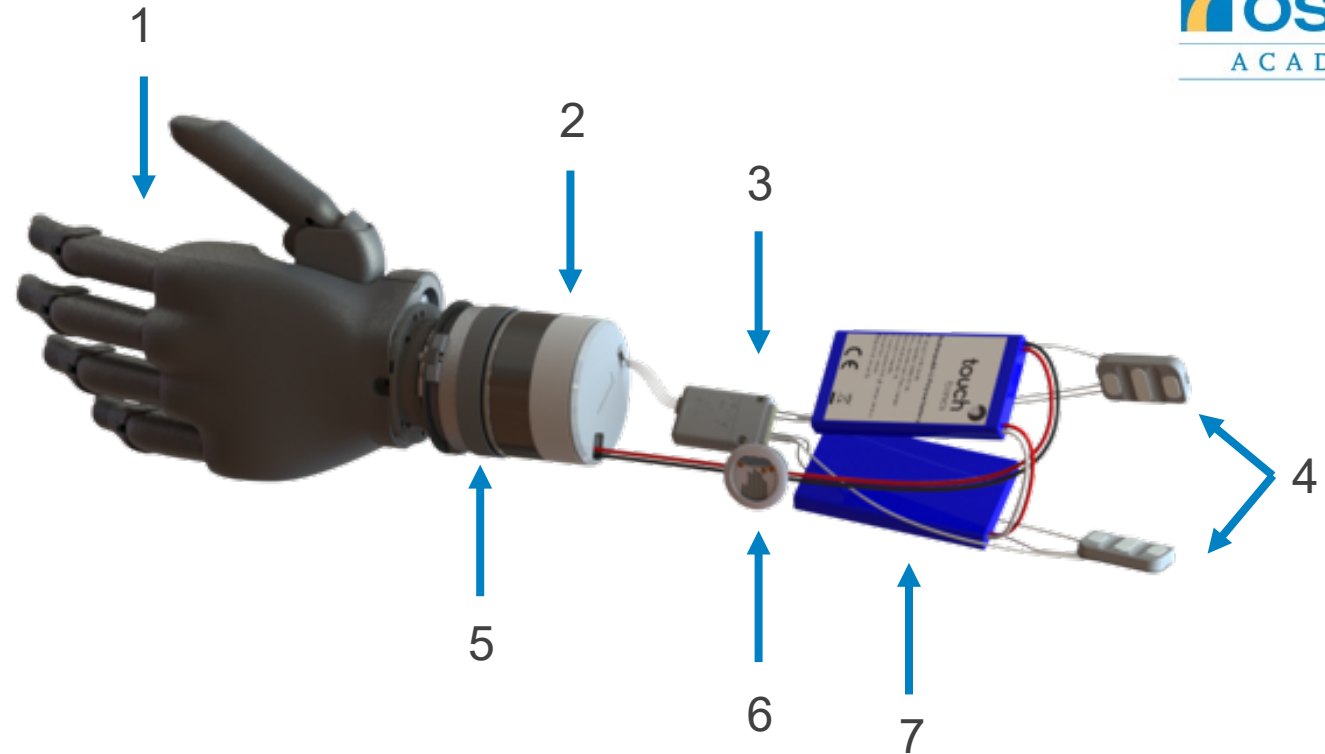


Technical Specifications

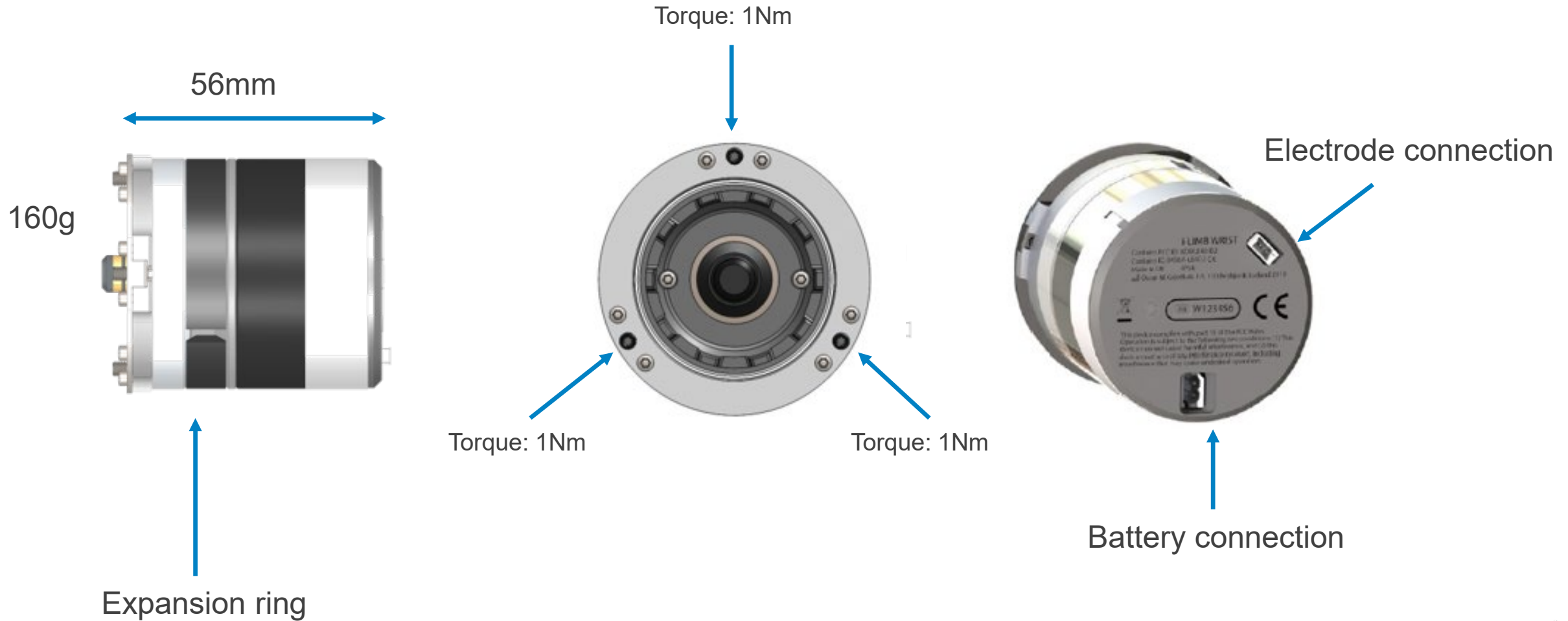


System Components

1. i-Limb (Quantum) hand
2. i-Limb Wrist
3. Digital electrode unit
4. Compact electrode contacts
5. Expansion ring
6. Magnetic charge port
7. Battery



Wrist Technical Specifications

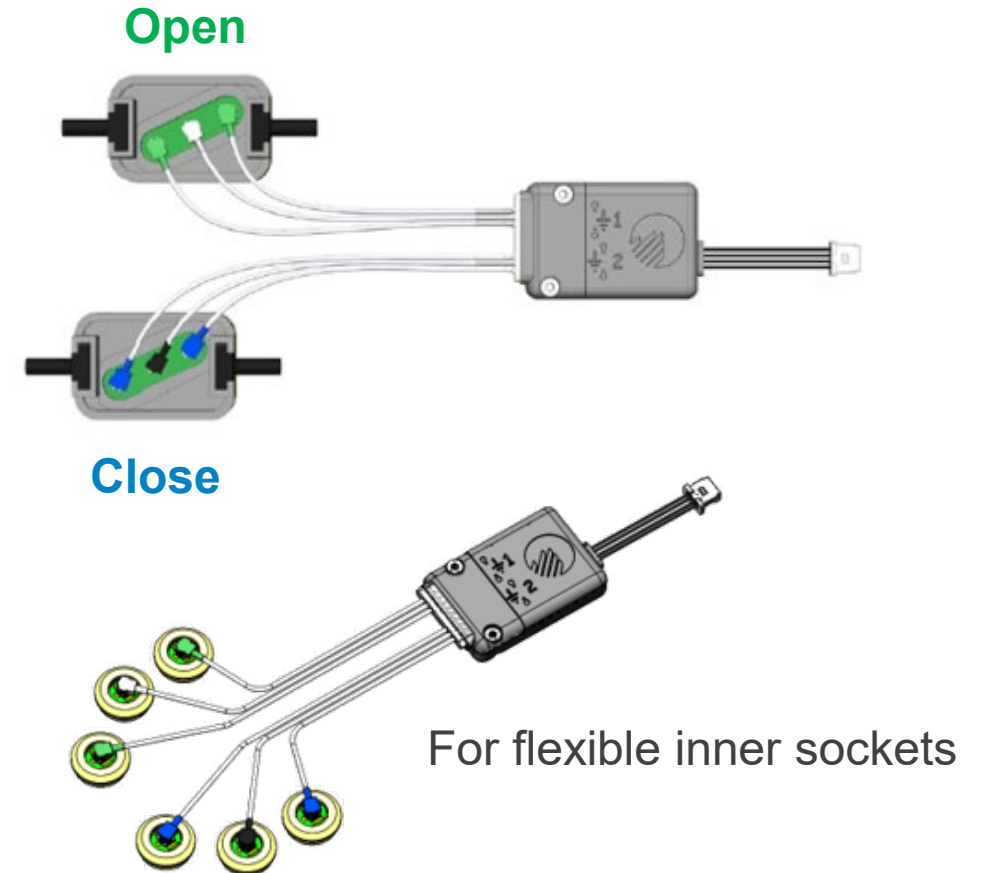


Digital Electrodes

- New digital electrodes control wrist and hand
- Compact and remote available
- More information gathered for wrist and hand to communicate
- Microprocessor within electrode for quick EMG signal processing

Green with white ground = **Open**

Blue with black ground = **Close**



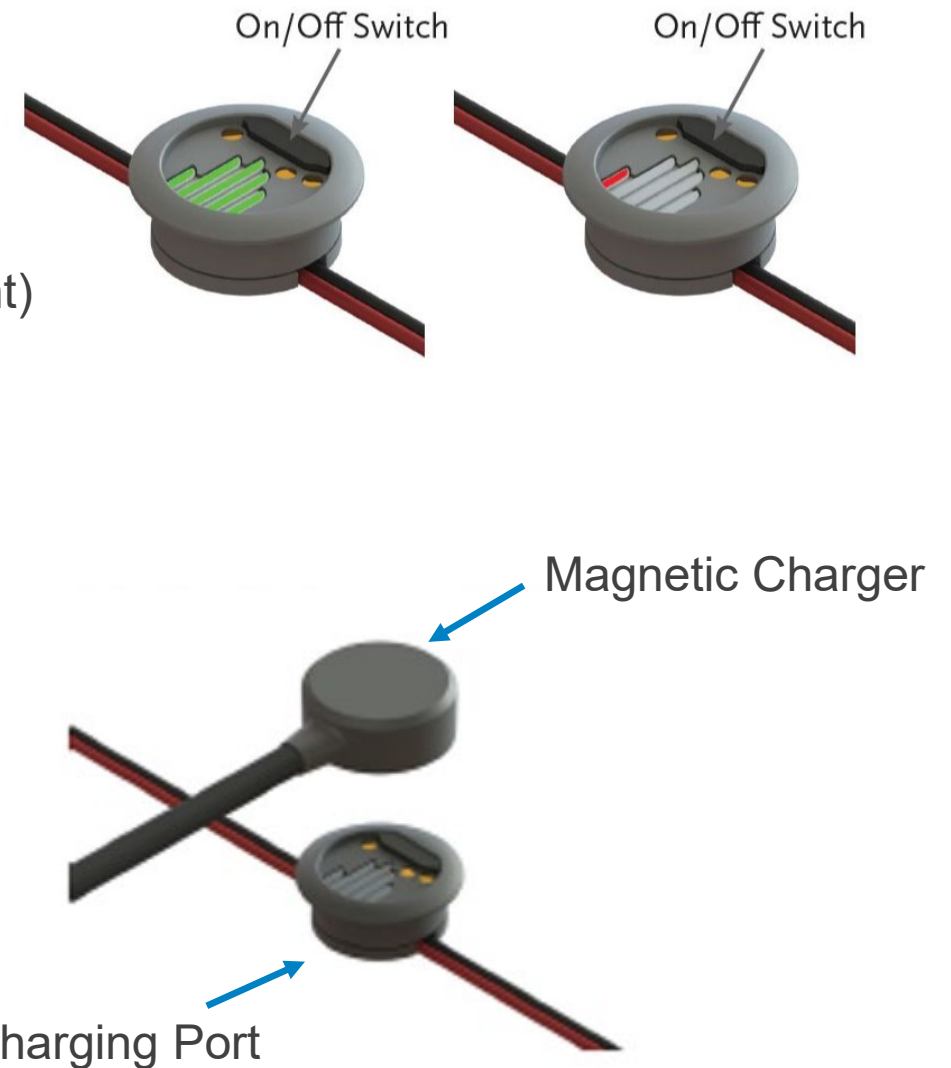
Note: digital electrodes must be plugged in prior to powering on the prosthesis.

Magnetic Charging Port

- Magnetic charging connection
- Powered through on/off switch on face
- Battery level monitored through LED lights (20% per light)
- Power reserve for emergency release (fail safe)



Car charger also available



i-Limb Compatibility

- **i-Limb Quantum** hands built since February 2018 are compatible with the **i-Limb Wrist**.
 - Device serial M9618 and above
- **i-Limb Quantum** hands built since November 2016 can be upgraded to be made compatible.
 - From device serial number M7695 for S/M/L hands and M7653 for XS hands



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