



PROPRIO FOOT

Challenges of the user



1



Challenges of the user





Medical Necessity

Reported falls

Fear of falling



n = 435
Majority TT



52% reported ≥1 fall in the past 12 months

Miller, William C., Mark Speechley, and Barry Deathe. "The prevalence and risk factors of falling and fear of falling among lower extremity amputees." Archives of physical medicine and rehabilitation 82.8 (2001): 1031-1037.



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Medical Necessity

Injuries because of falls



• High risk of TF amputees falling



• "1 out of 2 amputees who fall require medical attention"



K. Kaufman, B. Mundell, S. Visscher, H. M. Kremers, D. Larson, and J. Ransom, "Risk factors and costs associated with accidental falls among adults with above-knee amputations: a population-based study," Mayo Clinic, Rochester, MN, Apr. 2015.

Medical Necessity Increased ground clearance Decreased trips and falls



• Changes to Minimum Toe Clearance (MTC) could increase the incidence of trips and fall risk

• MTC ~70% greater



Rosenblatt, Noah J., et al. "Active dorsiflexing prostheses may reduce trip-related fall risk in people with transtibial amputation." J Rehabil Res Dev 51.8 (2014): 1229-1242.

Medical Necessity Increased ground clearance Decreased trips and falls



• Changes to Minimum Toe Clearance (MTC) could increase the incidence of trips and fall risk

• MTC ~70% greater

• Decreased likelihood of tripping (and pursuant likelihood of a fall)

Increased safety

Rosenblatt, Noah J., et al. "Active dorsiflexing prostheses may reduce trip-related fall risk in people with transtibial amputation." J Rehabil Res Dev 51.8 (2014): 1229-1242.

Medical Necessity Increased ground clearance Decreased trips and falls



Improved user mobility



• Fewer stumbles and falls





Ludviksdottir A, Gruben K, Gunnsteinsson K, Ingvarsson Th, Nicholls M. Effects on user mobility and safety when changing from a carbon fiber prosthetic foot to a bionic prosthetic foot. Presented at Orthopadie&Reha-Technik Congress, Leipzig, May 2012.

More natural stair ascent/descent



- 16 TTA + 16 non-amputees
- Neutral ankle angle vs. 4[°] adaptation

Knee flexion is restricted because of limited (ankle) dorsal flexion



Increased knee flexion and increased knee moment

More physiological knee flexion during stair ascent and descent

Alimusaj M, Fradet L, Braatz F, Gerner HJ, Wolf SI. Kinematics and kinetics with an adaptive ankle foot system during stair ambulation of trans-tibial amputees. Gait & Posture. 2009; 30:3:356-363.



• 10 TTA

- Dynamic carbon fiber foot vs. PROPRIO FOOT
- Suspension changed to Seal-In X5
- Final evaluation after 90 days of use



Delussu, Anna Sofia, et al. Assessment of the effects of carbon fiber and bionic foot during overground and treadmill walking in trans-tibial amputees. Gait & posture, 2013, 38. Jg., Nr. 4, S. 876-882.

Medical Necessity – Conclusion



- Increase in reported falls
- Fear of falling
- Falls cause injuries

PROPRIO FOOT

- Increased ground clearance
- Decreased trips and falls
- More natural stair ascent/descent
- Reduced energy consumption





Medical Necessity – Whitepaper





User Profile

- Low to moderate active users
- Unilateral transtibial amputation
- Bilateral transtibial amputation
- Unilateral transfemoral amputation

User Information	
Amputation Level:	Transtibial and Transfemoral
Impact Level:	Low to Moderate
Maximum Patient Weight:	125kg (275lbs)

Case-by-case assessment:

- Bilateral transfemoral amputation
- Limited residual limb control



ÖSSUR DYNAMIC SOLUTIONS

Background



2006

Össur launches the world's first microprocessor-controlled prosthetic ankle-foot system for lower limb amputees.

2016

Pro-Flex[®] is launched introducing carbon technology that provides significantly greater ankle power than conventional carbon feet.

2018

New PROPRIO FOOT[®]:

Innovative design of PROPRIO FOOT ®

+

Pro-Flex[®] LP





PROPRIO FOOT – Review Core functions: • Swing dorsiflexion • Ankle alignment • Stair adaptation Ramp adaptation • Relax/Chair exit



PROPRIO FOOT – What's new





Technical Specifications

- Ankle ROM: 33°
 - Size 27: movement range -19° (dorsi) to $+14^{\circ}$ (plantar) ankle alignment range -2° (dorsi) to $+14^{\circ}$ (plantar) heel height accommodation up to 50 mm / 2"
- Average ROM foot module: approx. 16 degrees
- Unity available for sizes 25-30

CATEGORY SELECTION GUIDE





Weight kg	45-52	53-59	60-68	69-77	78-88	89-100	101-116	117-125
Weight lbs	99-115	116-130	131-150	151-170	171-194	195-220	221-256	257-275
Low Impact Level	1	1	2	3	4	5	6	7
Moderate Impact Level	1	2	3	4	5	6	7	8

Foot Cover



- Beige and brown foot covers
- FSF narrow footcover
 - Used for small sizes, allows room for ankle module
 - No attachment plate
 - Lower opening
- FST standard Pro-Flex family footcover
 - Attachment plate

SELECTION CHART FOR PRODUCT VARIANTS									
Category	1	2	3	4	5	6	7	8	
Size 22									
Size 23		FSF Foot Cover No Unity available			N/A				
Size 24									
Size 25									
Size 26		FST Foot Cover Unity available							
Size 27									
Size 28									
Size 29	N	N/A							
Size 30									







Specification	OLD	NEW
Ankle range of motion	29°	33°
Stair Adaptation	Ascent: After the second prosthetic step Descent: After the second prosthetic step	Ascent: After the first prosthetic step Descent: After the first prosthetic step
Ramp Adaptation	8 prosthetic steps to 85% of surface	3 prosthetic steps to 85% of surface
Relax	Yes	Yes
Chair Exit	Yes	Yes, faster detection
Auto-Adjustment	16 prosthetic steps	15 prosthetic steps
Minimum walking speed	2,3 km/h	1,4 km/h
Build Height (27 Cat 5)	169 mm / 6 5/8"	180mm / 7 1/8"
Weight (27 Cat 5)	1.4kg / 3.1lbs (incl. battery)	1.5kg / 3.3lbs (incl. battery)
App Connectivity	N/A	Össur Logic

PROPRIO FOOT – How does it work

ACADEMY

- Swing Dorsiflexion
- Ankle Alignment
- Stair adaptation
- Ramp adaptation
- Relax/ Chair Exit



Swing Dorsiflexion



- After 2 prosthetic steps
- 4° toe-lift
- Stair descent
 - No toe-lift



	Minimum speed	Minimum swing phase duration
Level ground / ramps	1.4 km/h / 0.9 mph	0.4 seconds
Stair ascent	1.2 km/h / 0.8 mph	0.4 seconds

Alignment

- Ankle Alignment
 - User interface or Össur Logic app
 - Barefoot to 5 cm heel height
 - Performed by the user

C Device settings	+
Ankle Alignment	>
Auto Adjustment	>
USER PREFERENCES	
Auto connect	\bigcirc
Display name	HF203069
Relax Mode off	>
Chair Exit Mode on	>
Standby off	>
ADVANCED SETTINGS	
Stair Adaptation Descent Angle: 4 °, Ascent Angle: 4 °	>
Ramp Adaptation Decline Adaptation: 50 %, Incline Adaptation: 95 %	>



Adjustment

- Auto Adjustment
 - Recognition of user's specific gait parameters
 - Calibrates to user's gait parameters
 - Essential for accurate and consistent terrain detection

<	Device settings	+
	Ankle Alignment	>
	Auto Adjustment	>
	USER PREFERENCES	
	Auto connect	
	Display name	HF203069
	Relax Mode off	>
	Chair Exit Mode on	>
	Standby off	>
	ADVANCED SETTINGS	
	Stair Adaptation Descent Angle: 4 °, Ascent Angle: 4 °	>
	Ramp Adaptation Decline Adaptation: 50 %, Incline Adaptation: 95 %	>



• Adjustable adaptation on ramps

	Min	Default	Max
Ramp Ascent	0%	70%	150%
Ramp Descent	0%	65%	100%

- Near full adaptation after three prosthetic steps
- Maximum ramp angle approx. 15°
- Tips:
 - Very active users consider lowering descent value (to about 30%)
 - Insecure users consider increasing the descent value slightly



ÖSSUR

ACADEMY







- Ramp Adaptation setting
 - Controls adaptation as percentage of surface angle
- Example:
 - Setting 100%
 - Surface angle 10°
 - \rightarrow Ankle Angle 10°





- Ramp Adaptation setting
 - Controls adaptation as percentage of surface angle
- Example:
 - Setting 65%
 - Surface angle 10°
 - \rightarrow Ankle Angle 6.5°





- Faster adaptation old (grey) vs new (orange)
- User's perception of adapted foot around 50% adaptation



---- New Proprio Foot ----- Old Proprio Foot

Stair Adaptation

ACADEMY

- Adjustable adaptation on stairs
 - Adaptation after the first full prosthetic step in stairs
 - Sound side first is the preferred way

	Min	Max
Stair Ascent	0°	6°
Stair Descent	0°	6°



Profiles

- Transfemoral (default profile)
 - Stair ascent: 0°
 - Stair descent: 0°
 - Safety:
 - Adaptation in stairs can cause instability for TF users
 - Depends on knee and walking style
- Transtibial
 - Stair ascent: 2°
 - Stair descent: 4°

<	Profiles	+
	CURRENT DEVICE	
	No profiles found Either you haven't created a profile yet or all profiles have been removed	
	FACTORY DEFAULTS	
	Default Profile 2018-11-07 08:25:27 +0000	
	Default TF Profile 2018-11-07 08:25:27 +0000	



Relax and Chair Exit recognition



Relax:

- Detected when sitting and shank is tilted >30°
- Foot still for two seconds
- Foot moves to full plantarflexion
- Also activated when kneeling (over -60°)

Chair Exit:

- Detected while moving the foot backwards or sideways
- Foot moves to 5° dorsiflexion
- Back to neutral in next swing phase





Automatic cycling recognition

- Cyclic movement detected when pedaling
- Motor movements disabled
- Holds neutral position







Benefits for the user





WE IMPROVE PEOPLE'S MOBILITY

