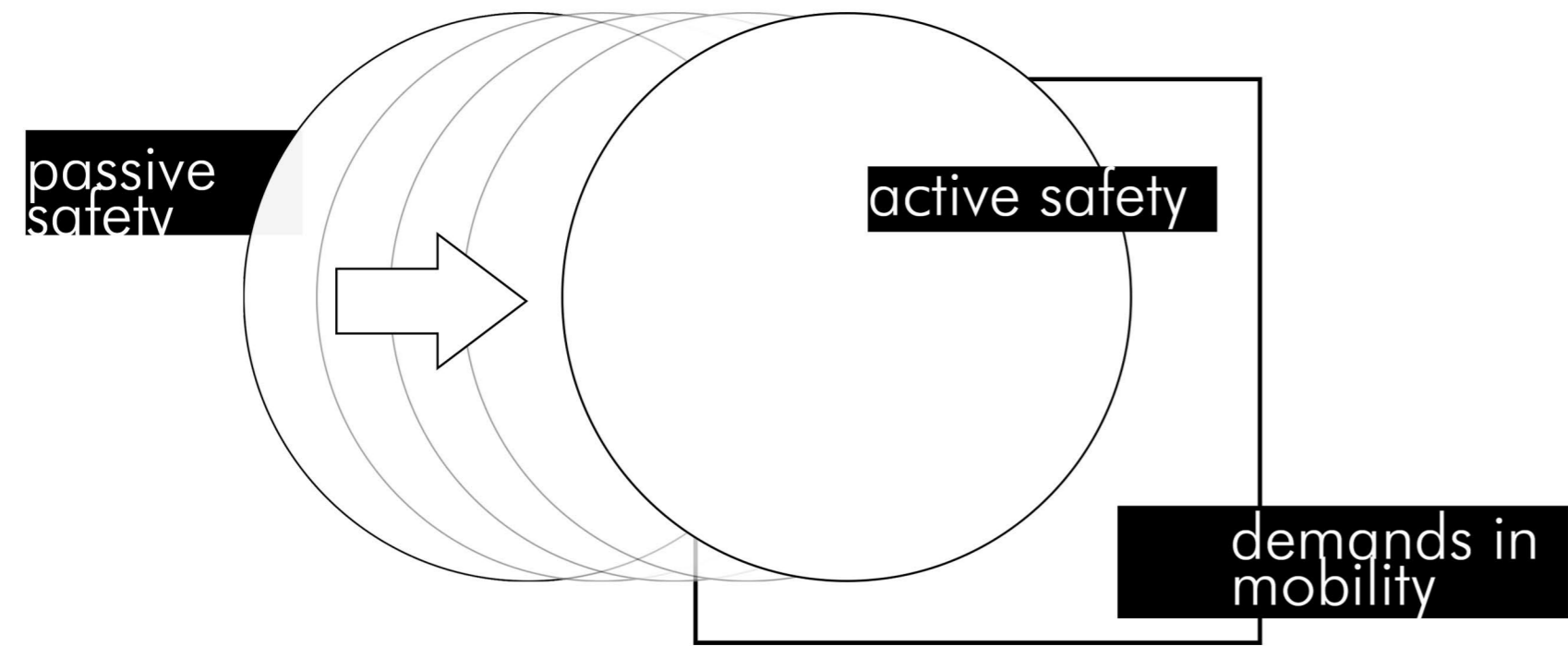


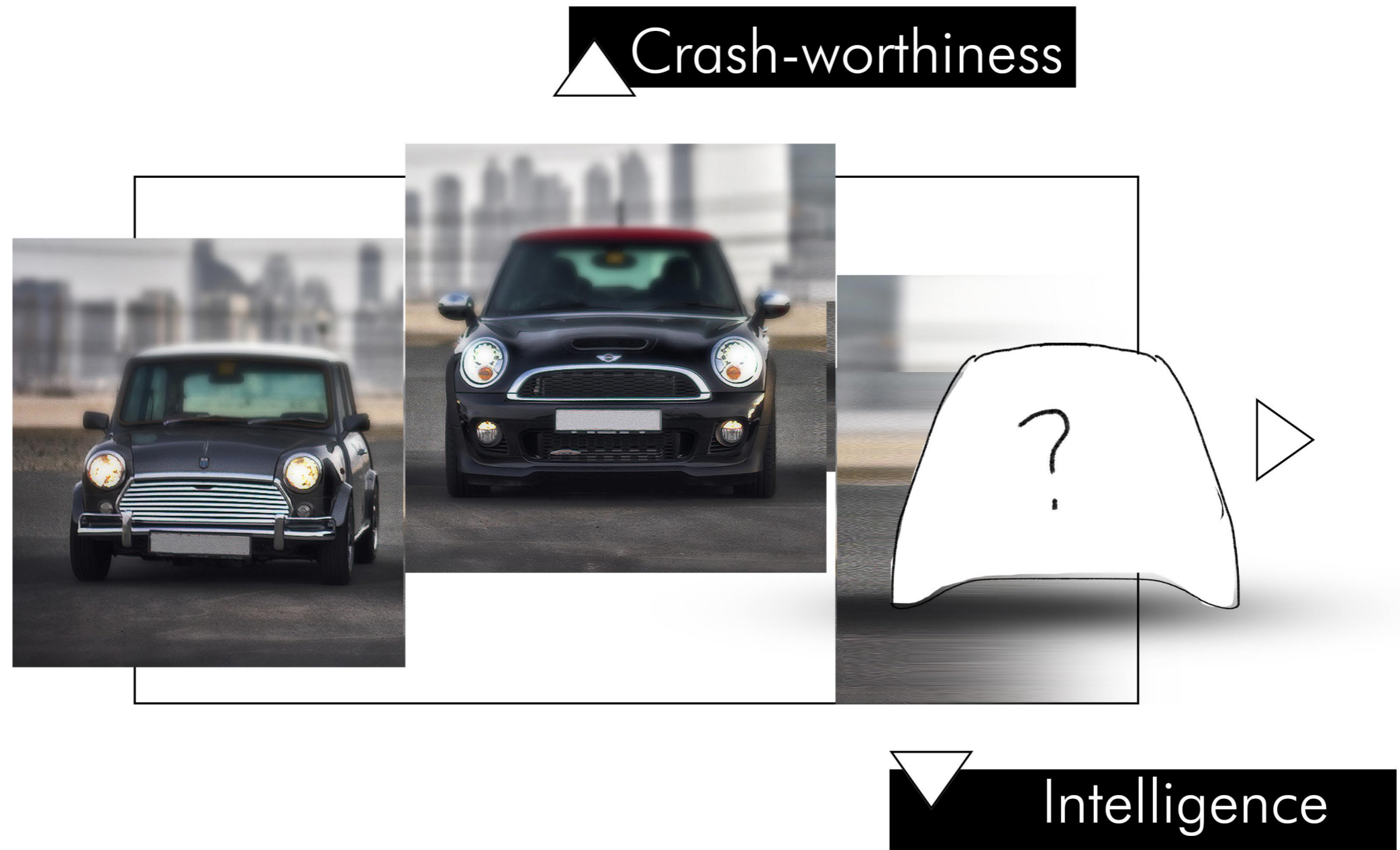
[wip]

Proj. Jellyfish

Safety via Intelligence
Final Major Project

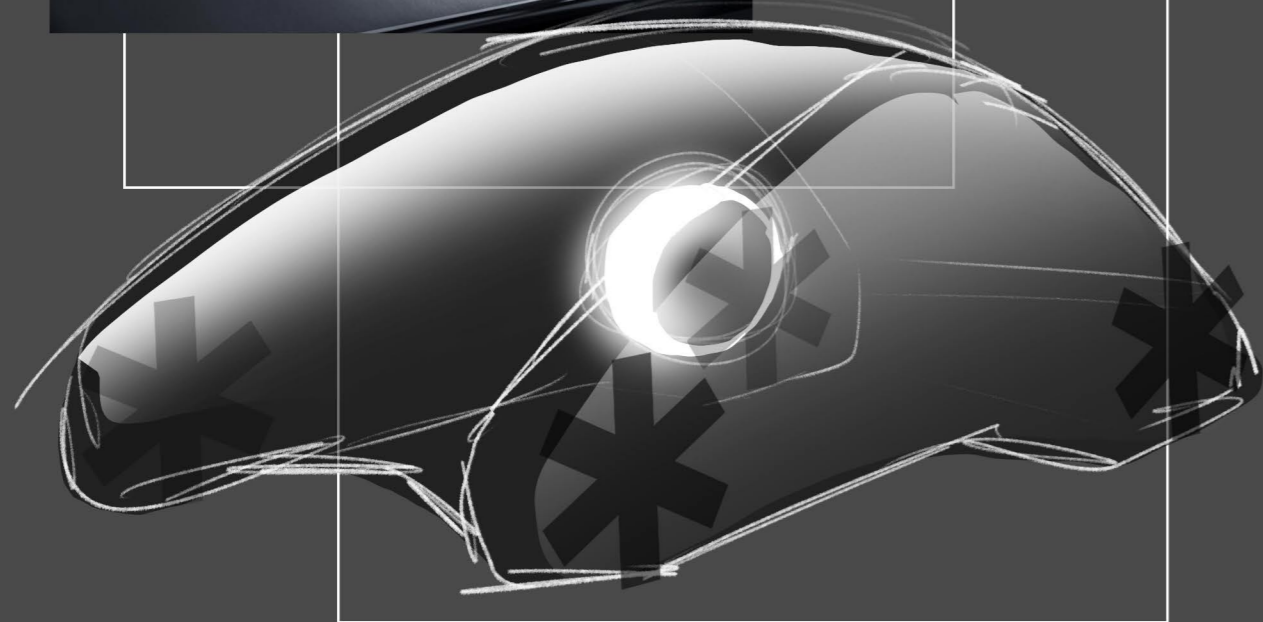


Can we solely rely on Active Safety to provide better efficiency and experience?



Trust issues with Autonomous Vehicles

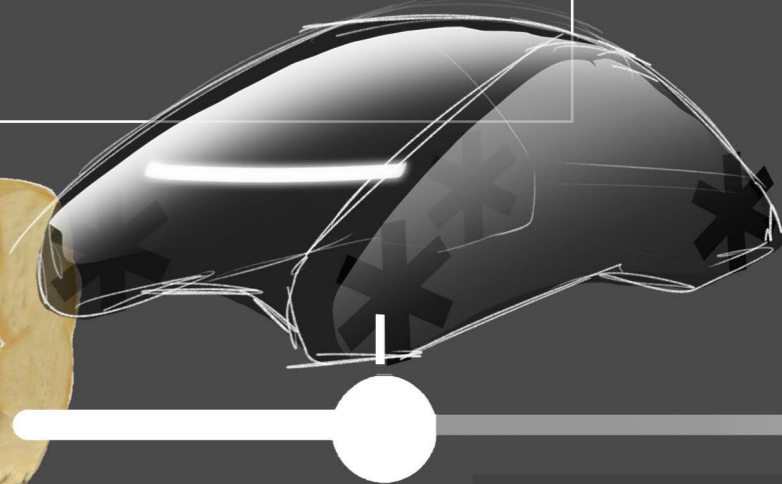
Tangibility



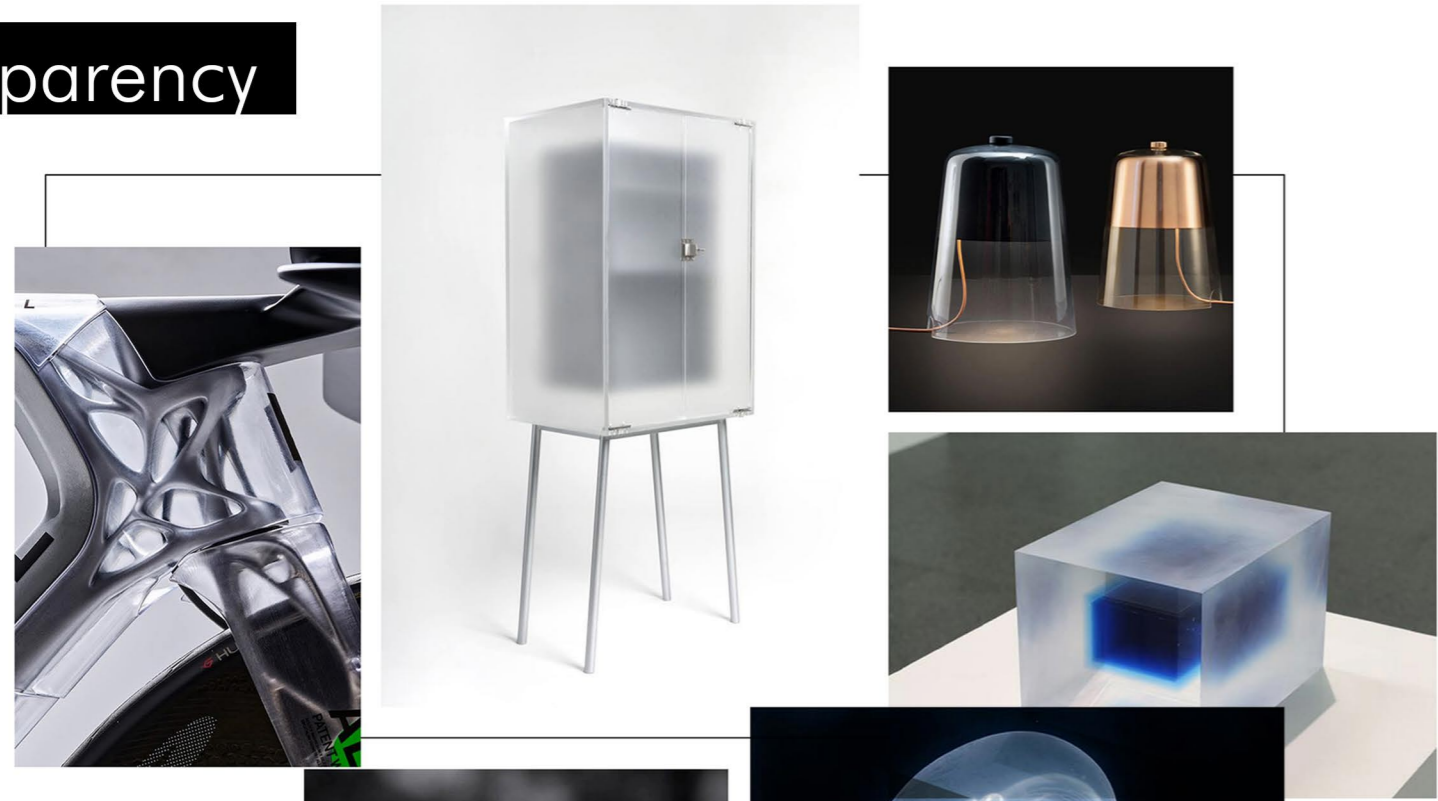
Response



Neutrality



transparency

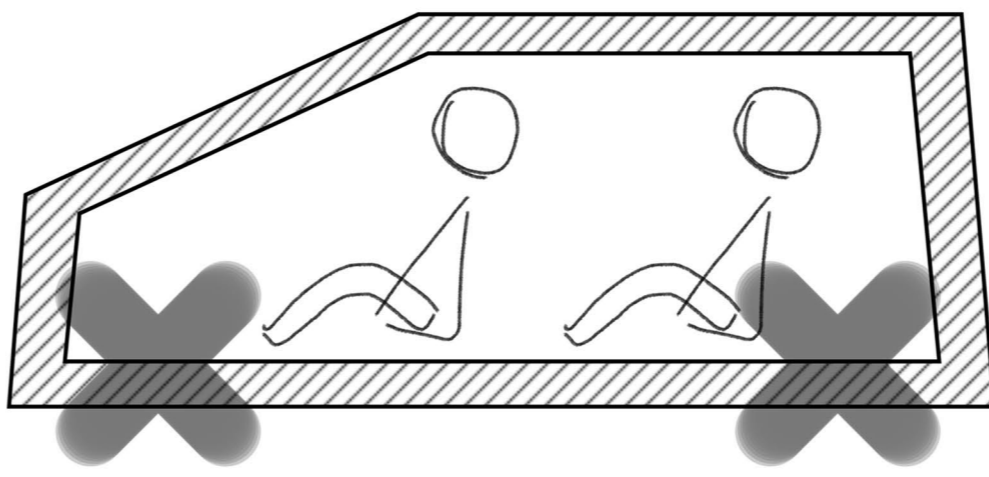


Core

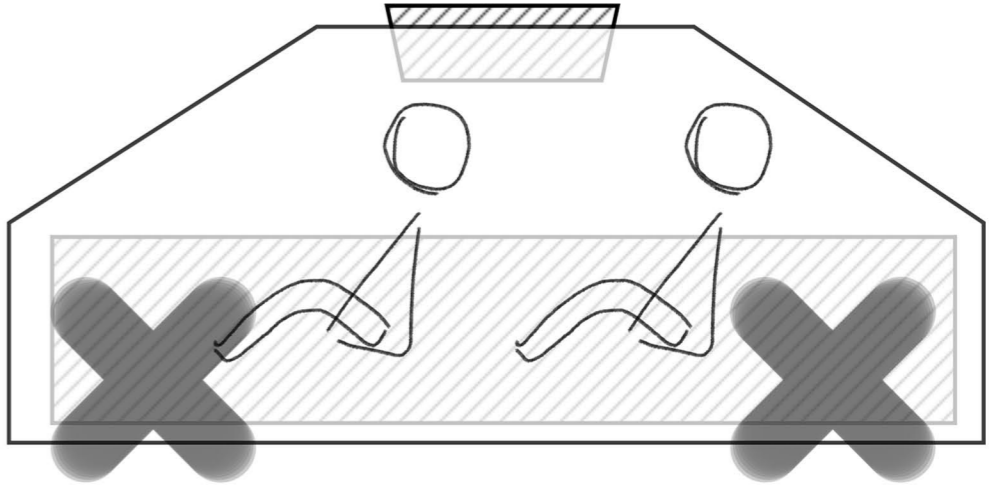


Visual intelligence

A Topology Discussion



Room inside Machine



Room attached to Machine



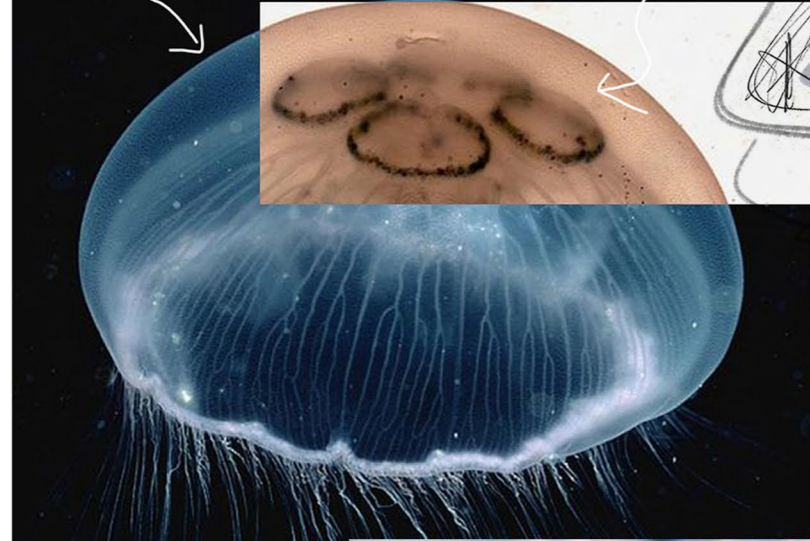
'Room'



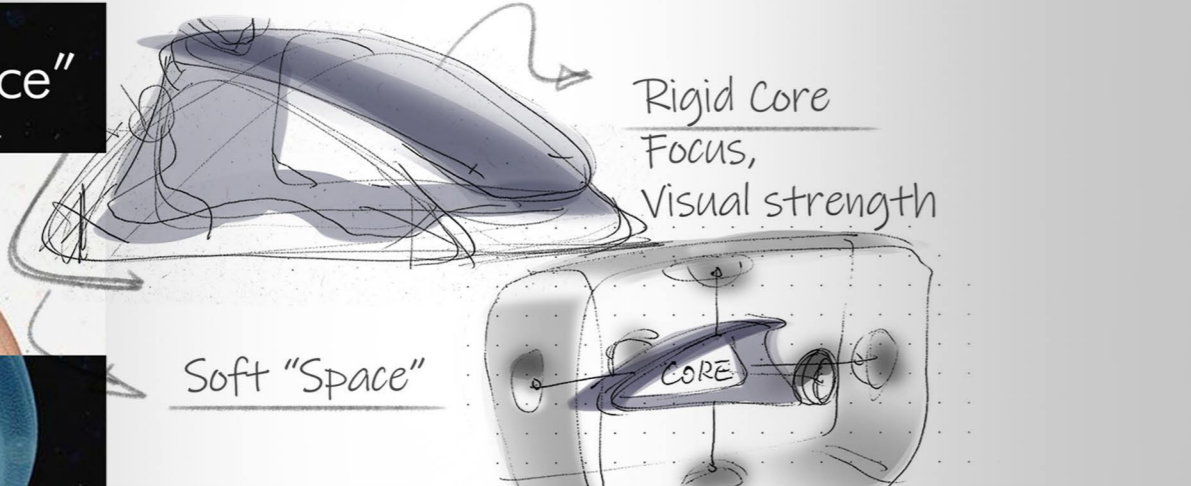
'Machine'

"room"

"Intelligence"



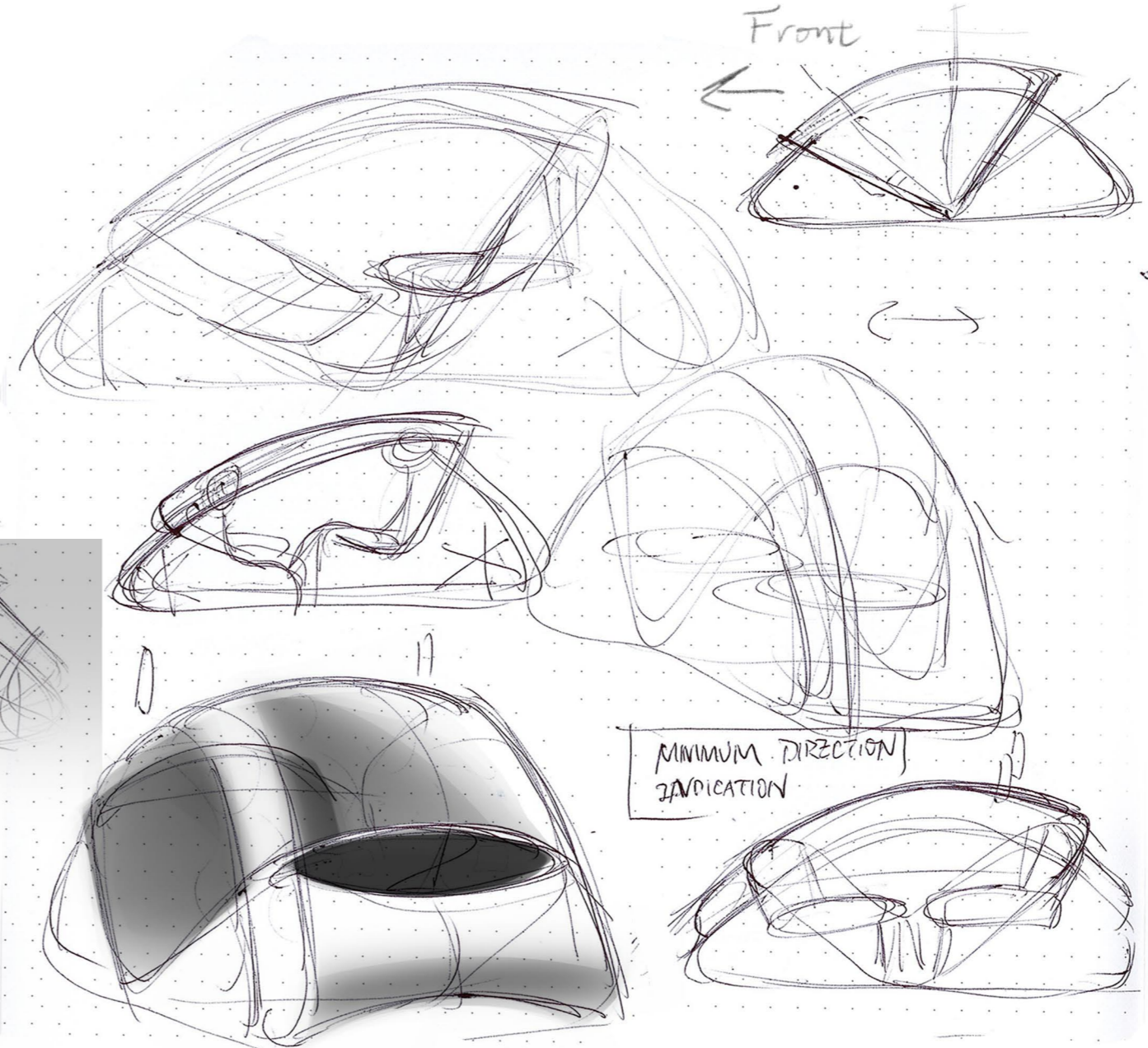
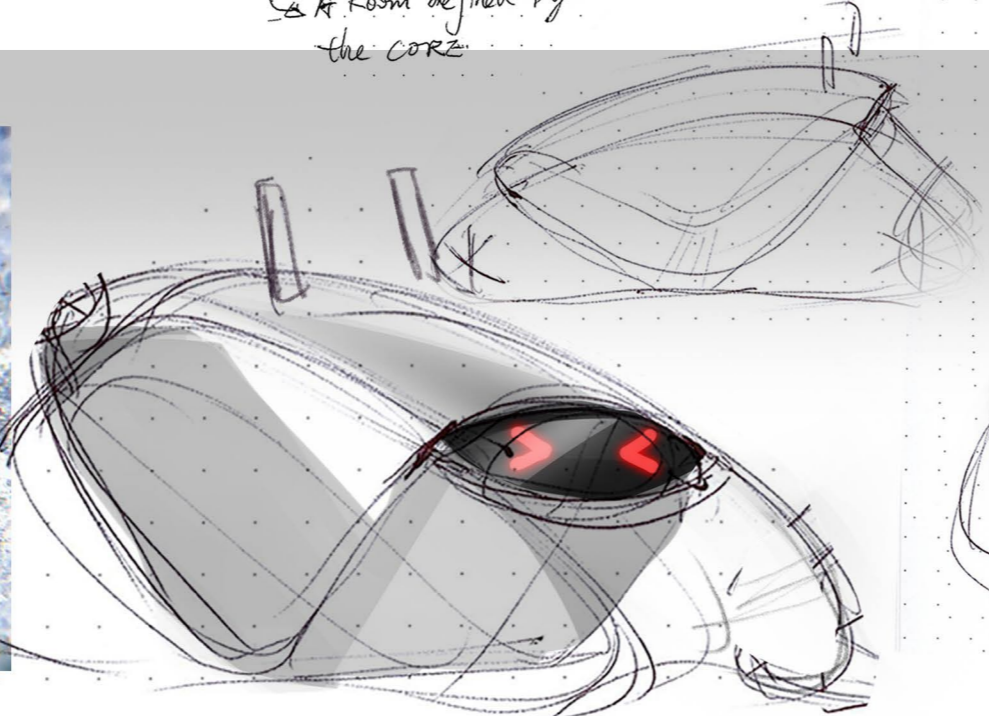
© Getty Images/WaterFrame RM



Rigid Core
Focus,
Visual strength

Soft "Space"

A Room defined by
the core



Front

Minimum directional
indication

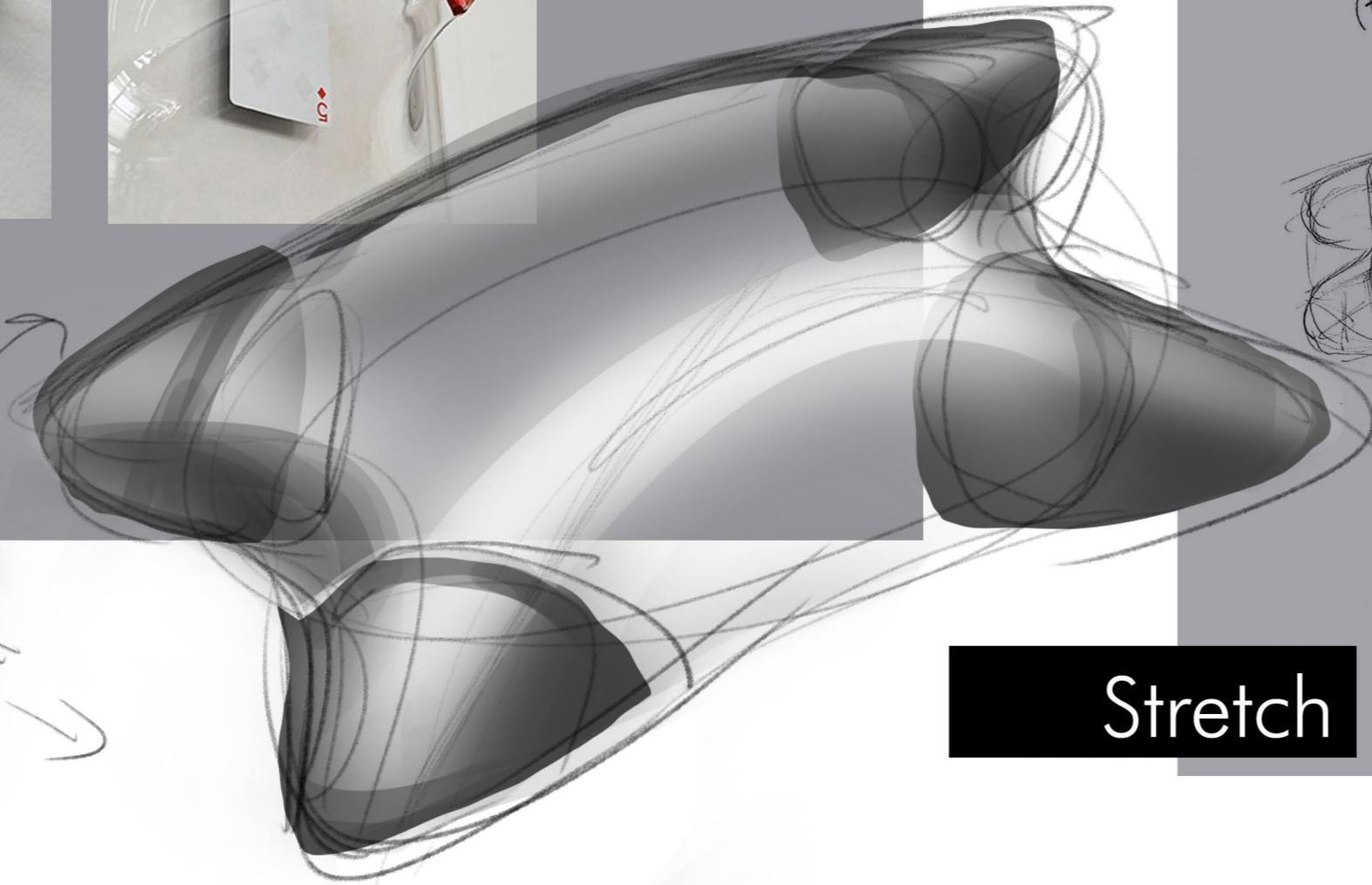
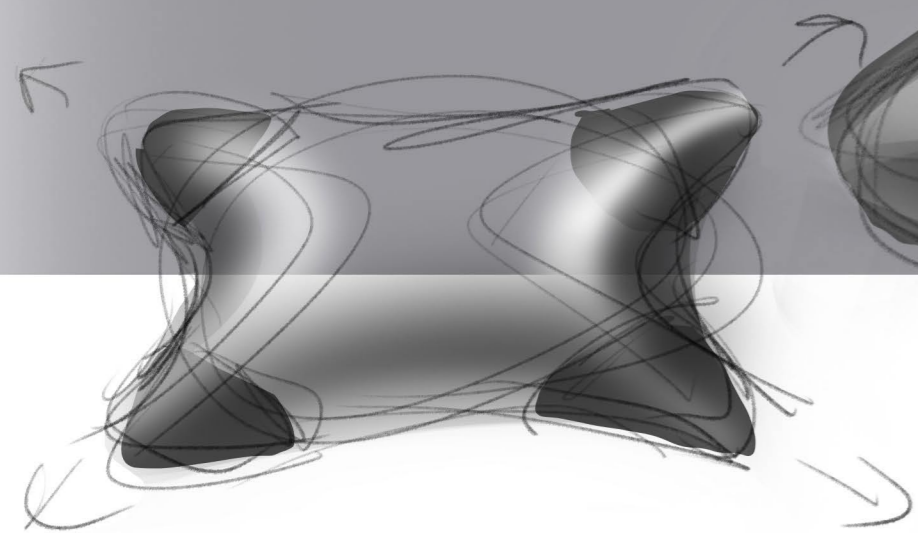
MINIMUM DIRECTION
INDICATION

Activate

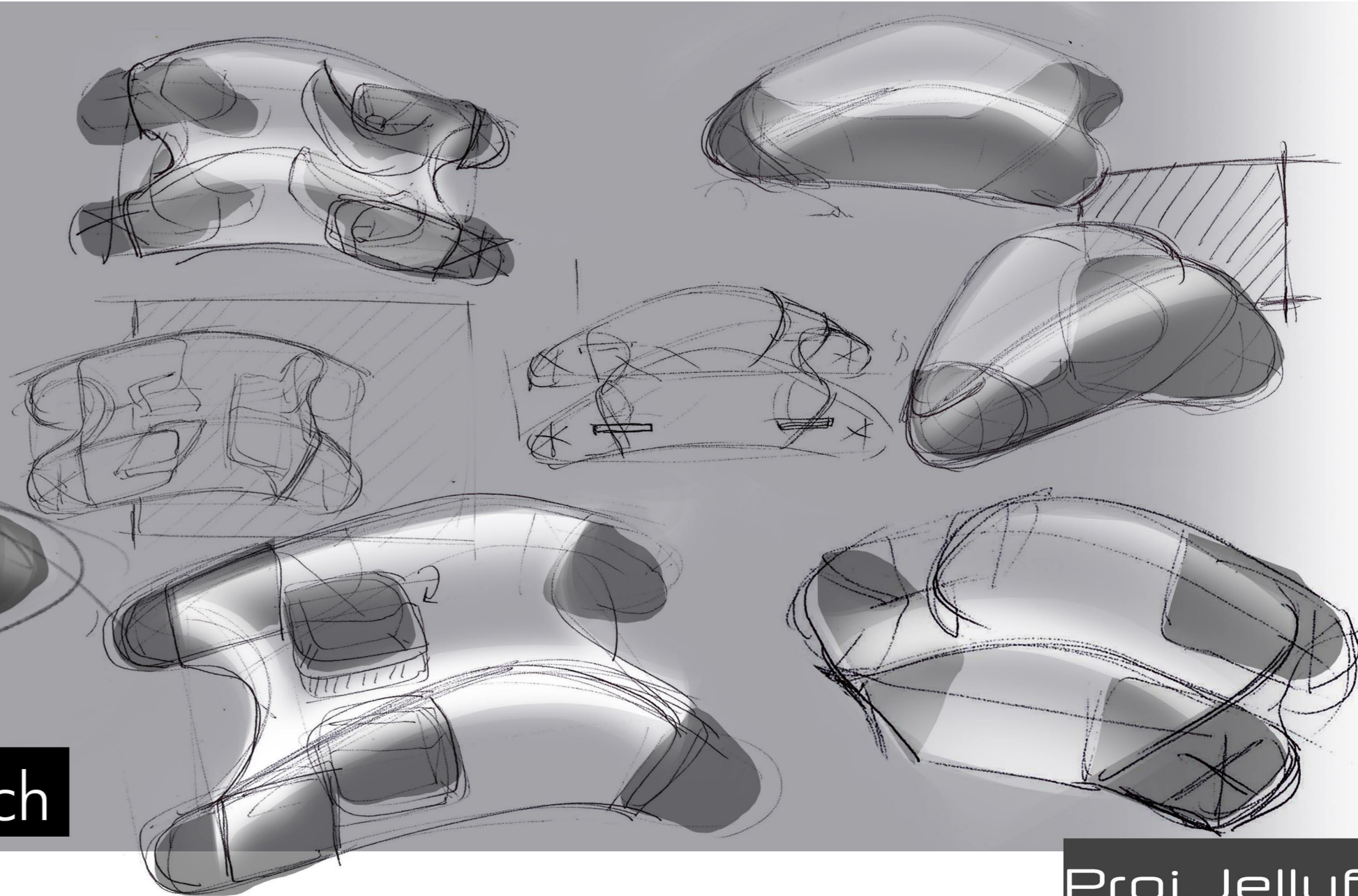
Proj. Jellyfish



Contain / Breach



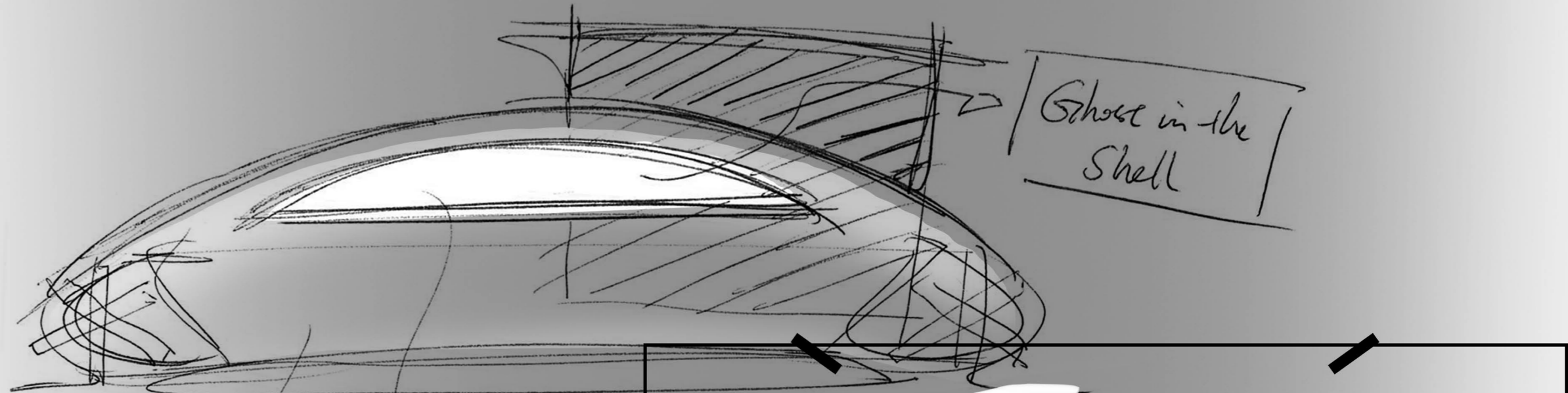
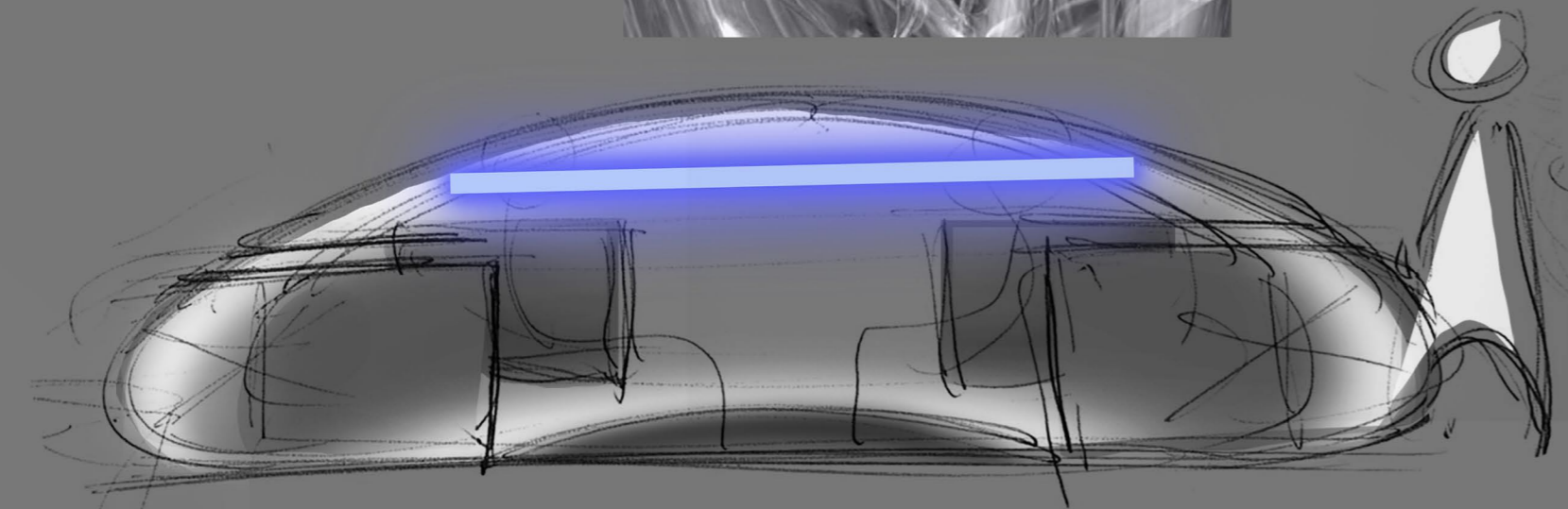
Stretch



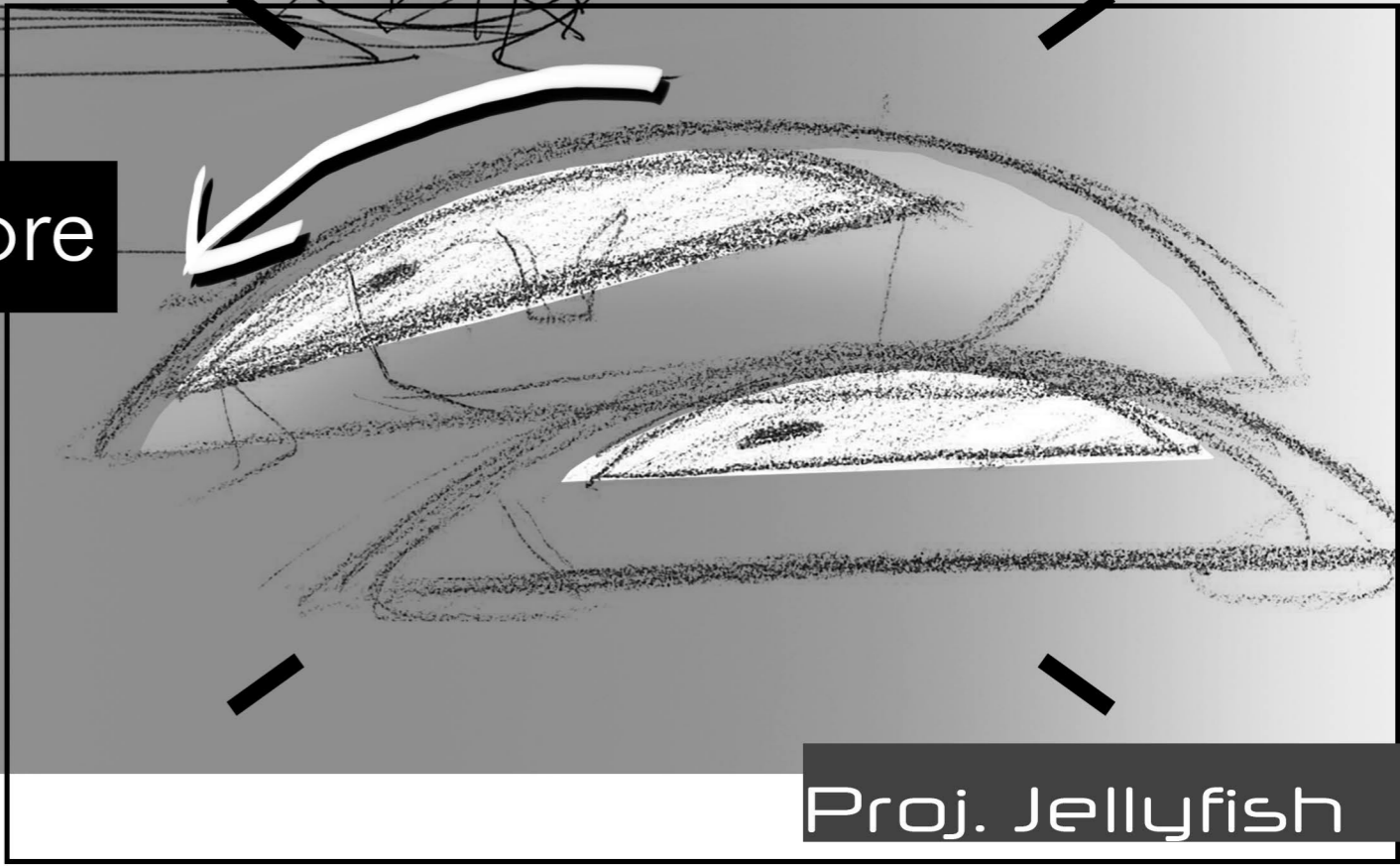
Proj. Jellyfish



"Ghost in the shell"

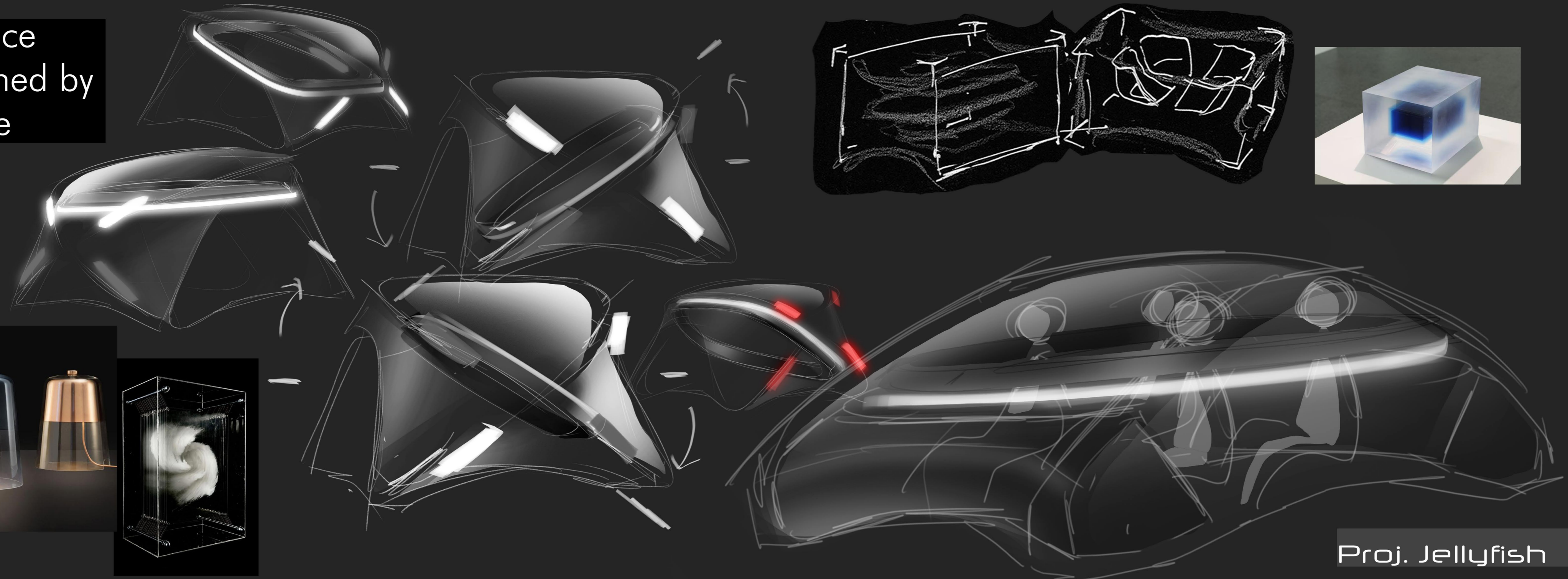


Dynamic Core



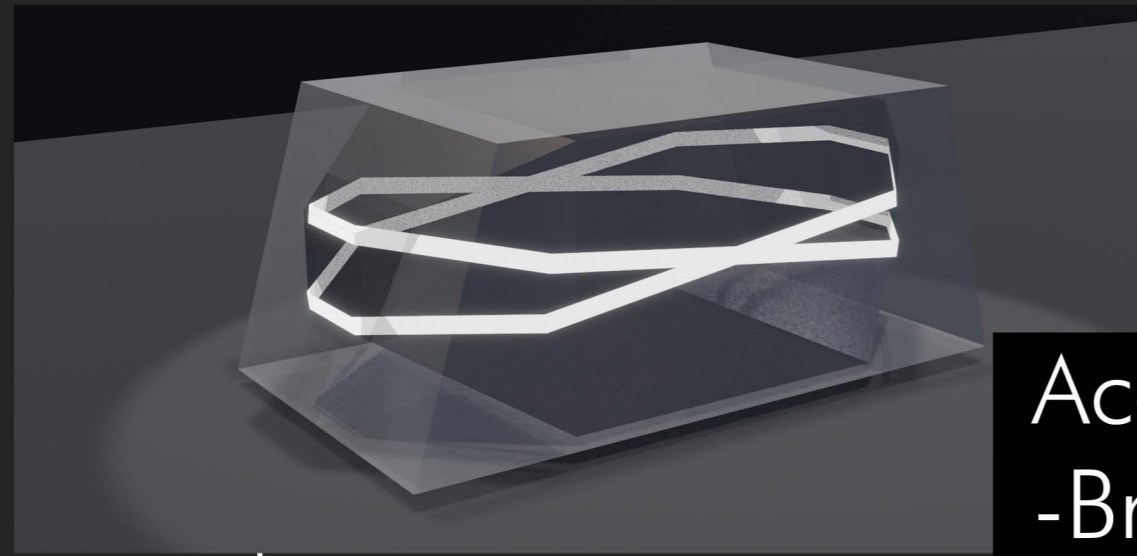
Proj. Jellyfish

Stance
defined by
Core

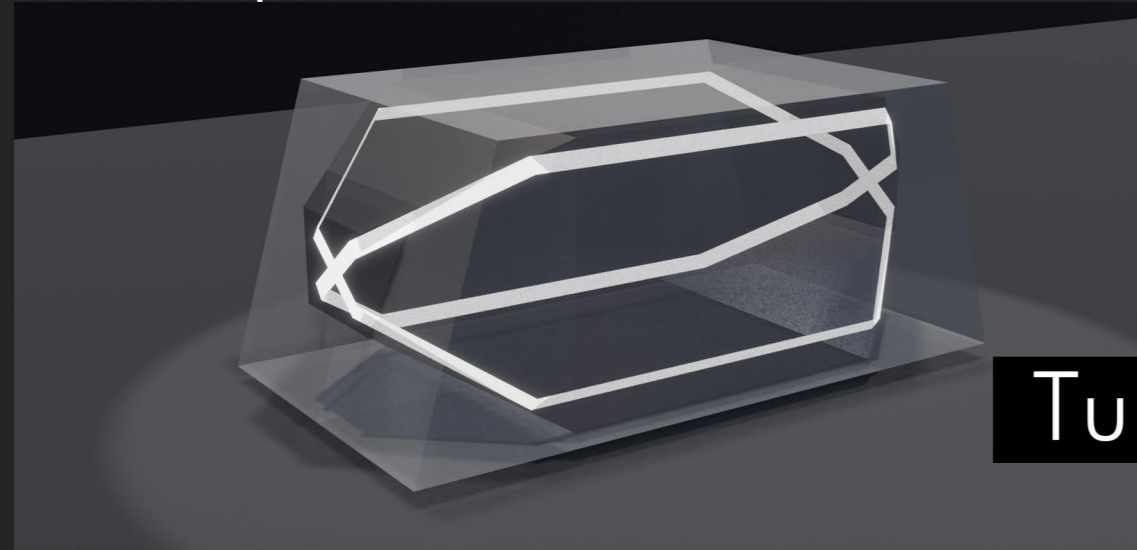


Proj. Jellyfish

Boolean Experiment



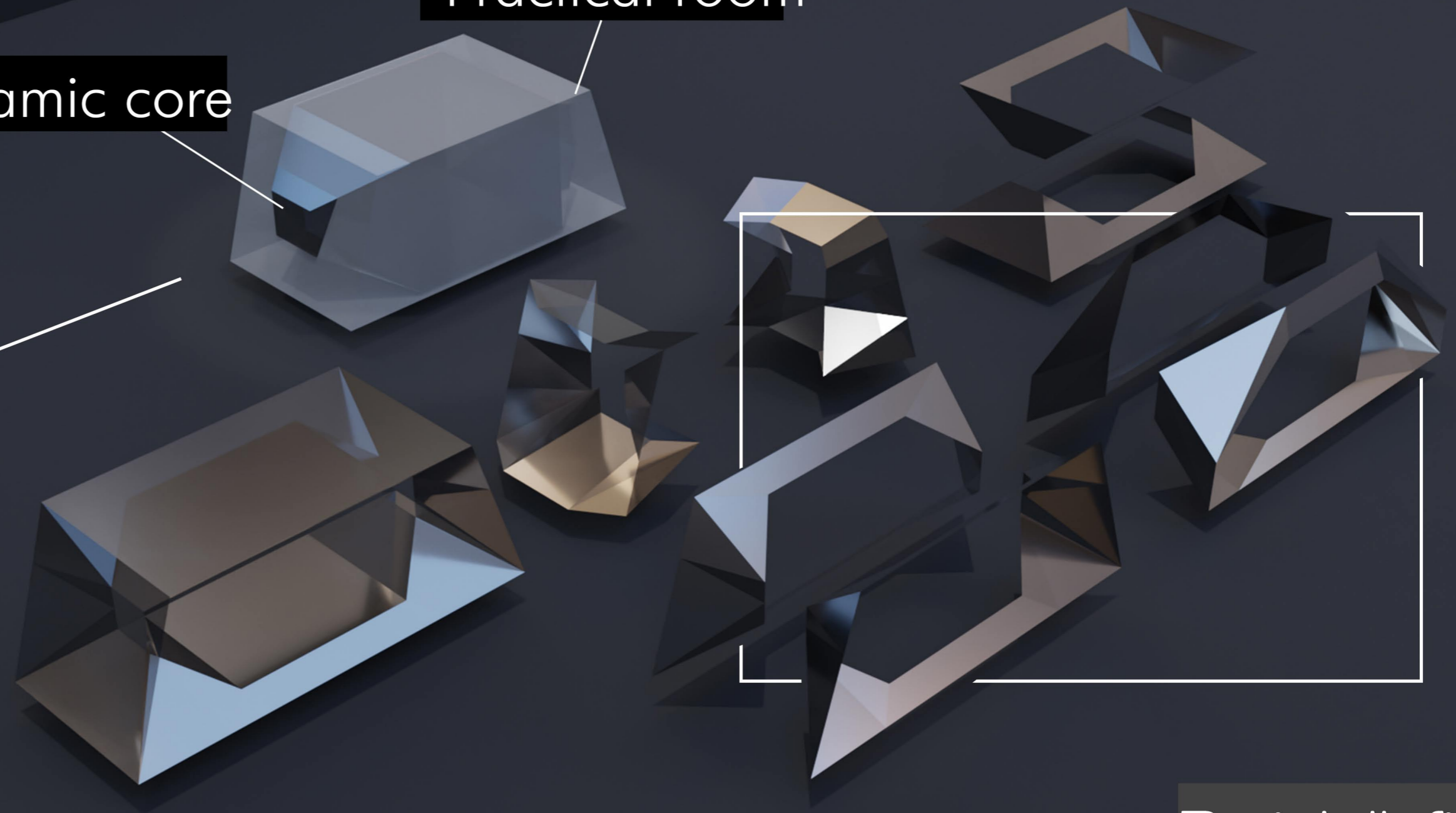
Accelerate
-Break

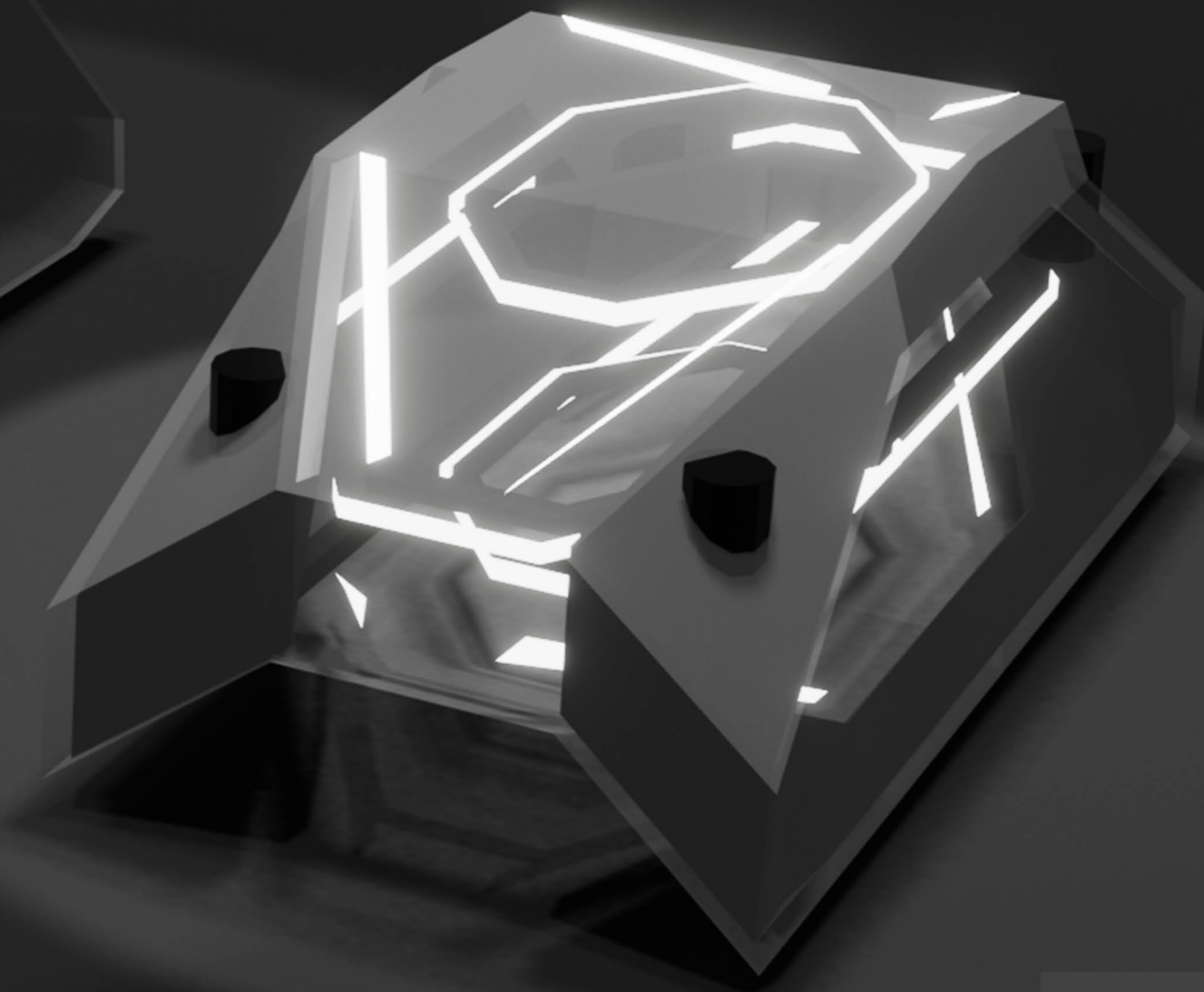
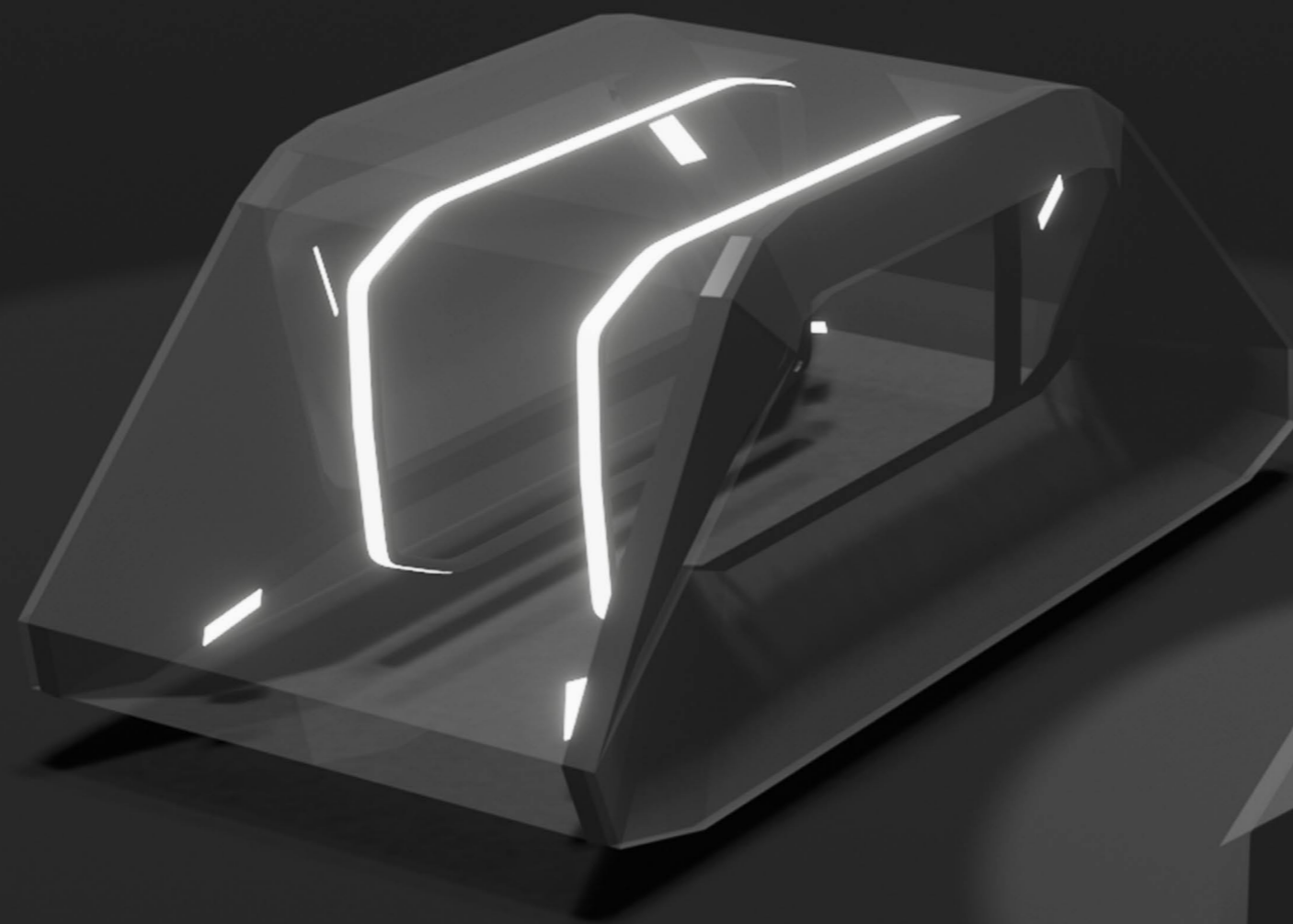
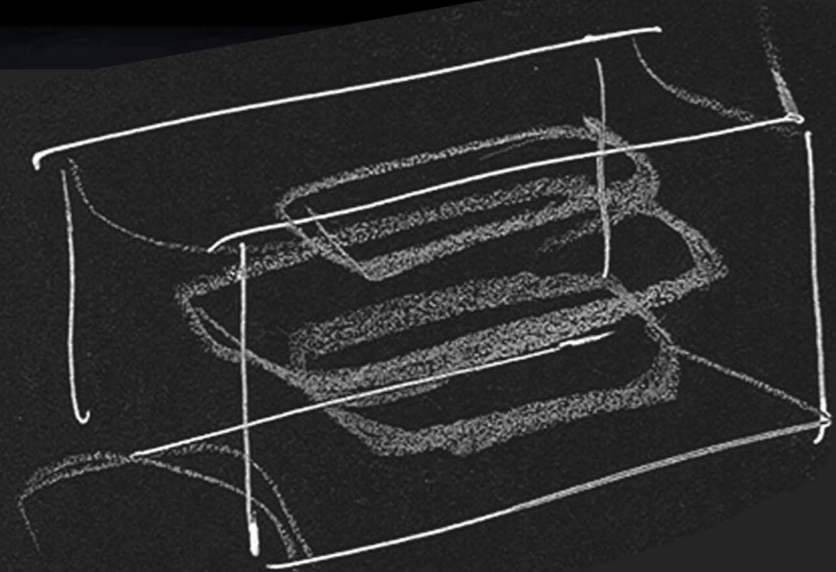
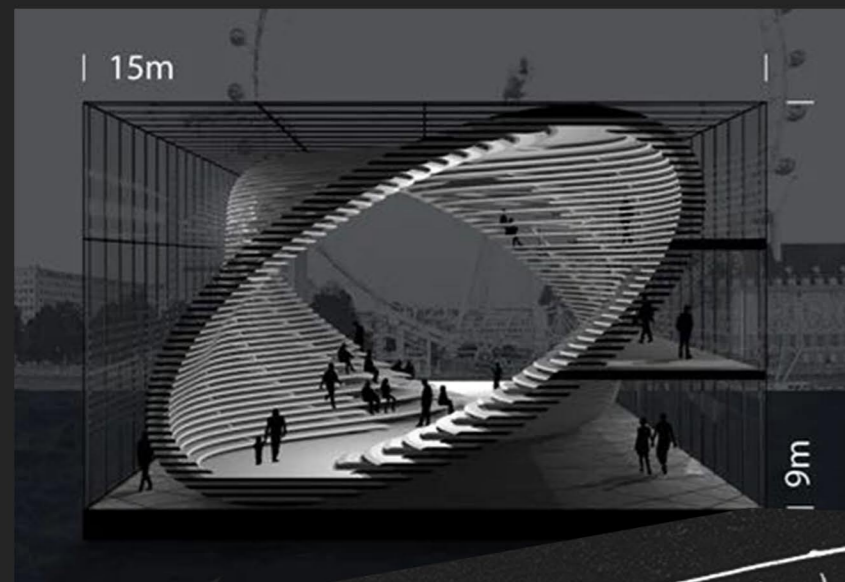


Turning

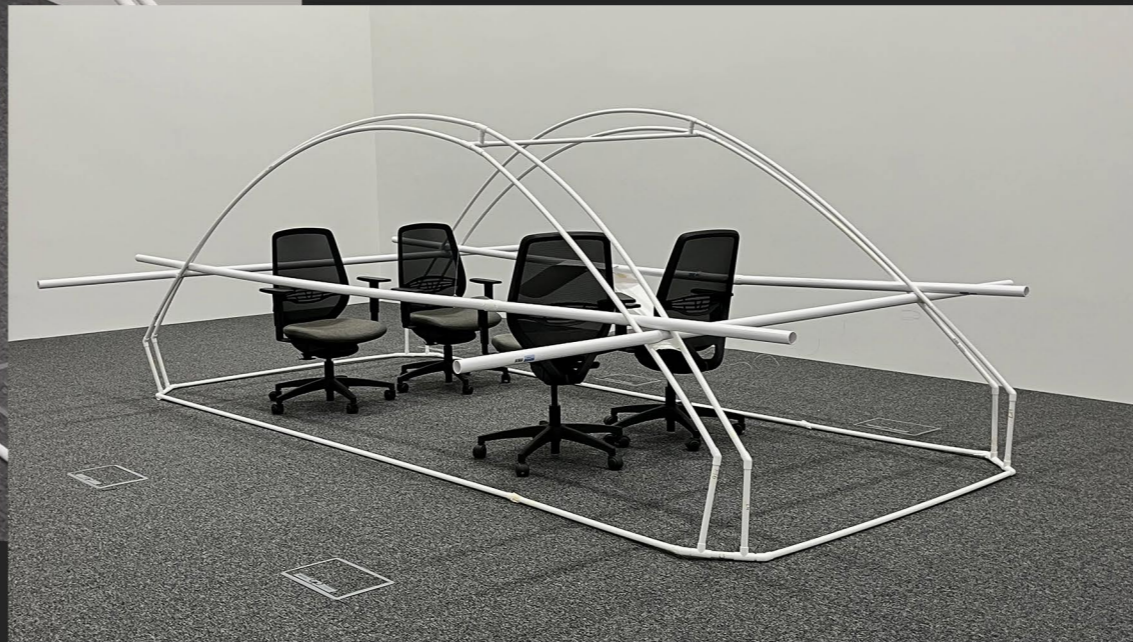
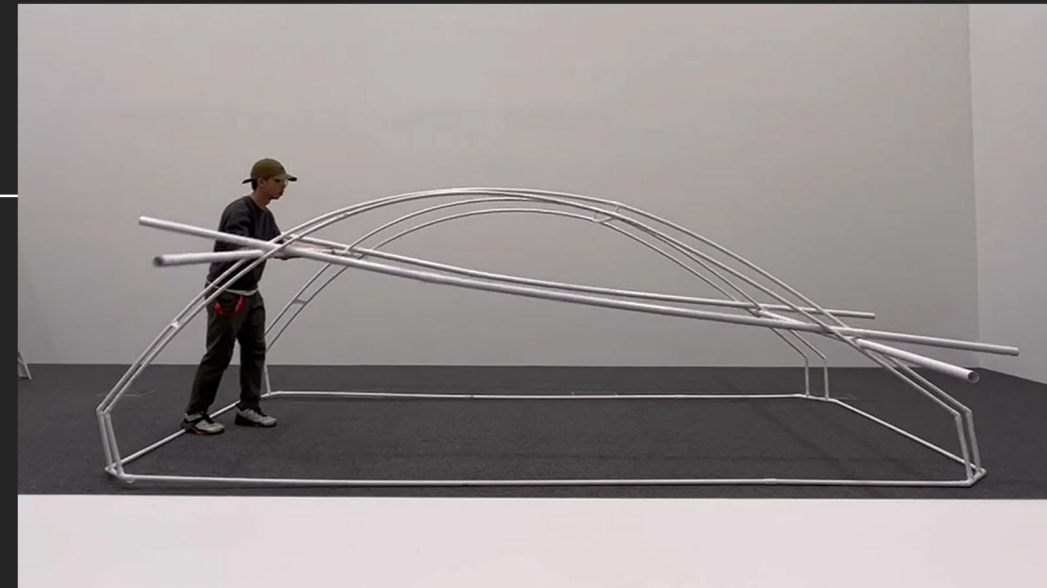
Dynamic core

Practical room



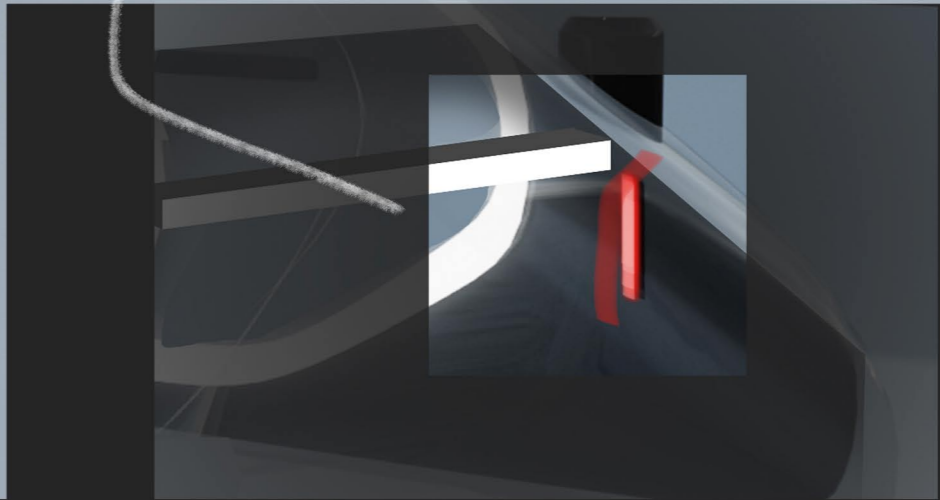
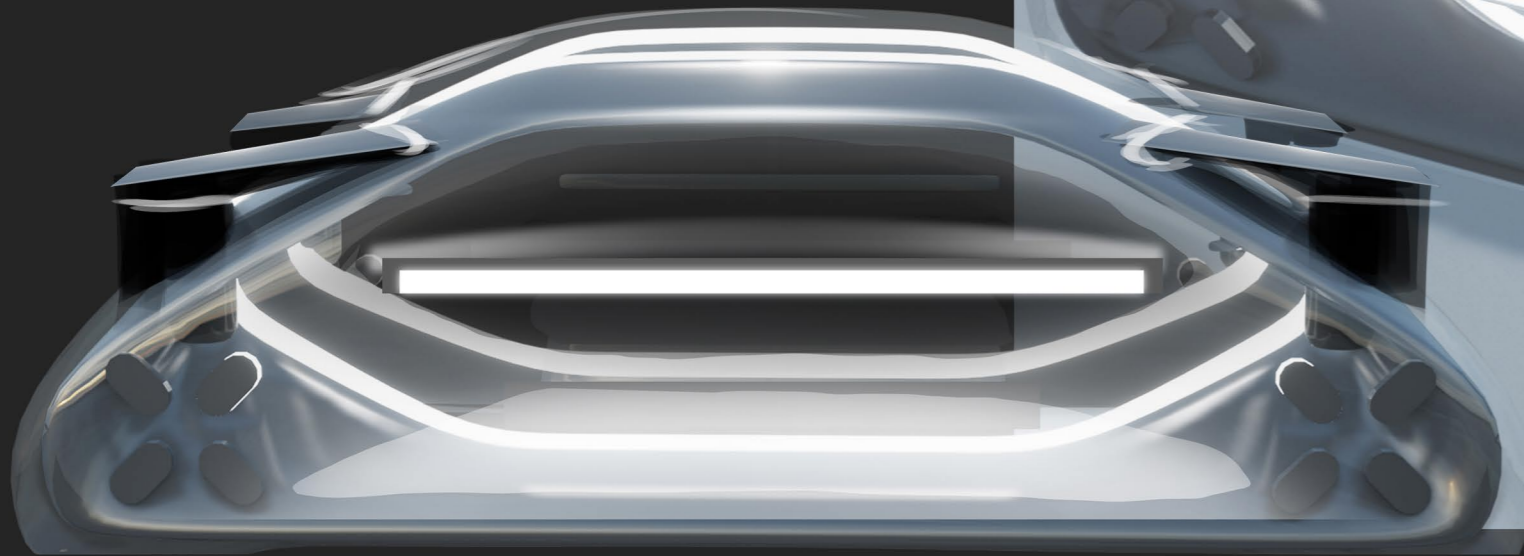
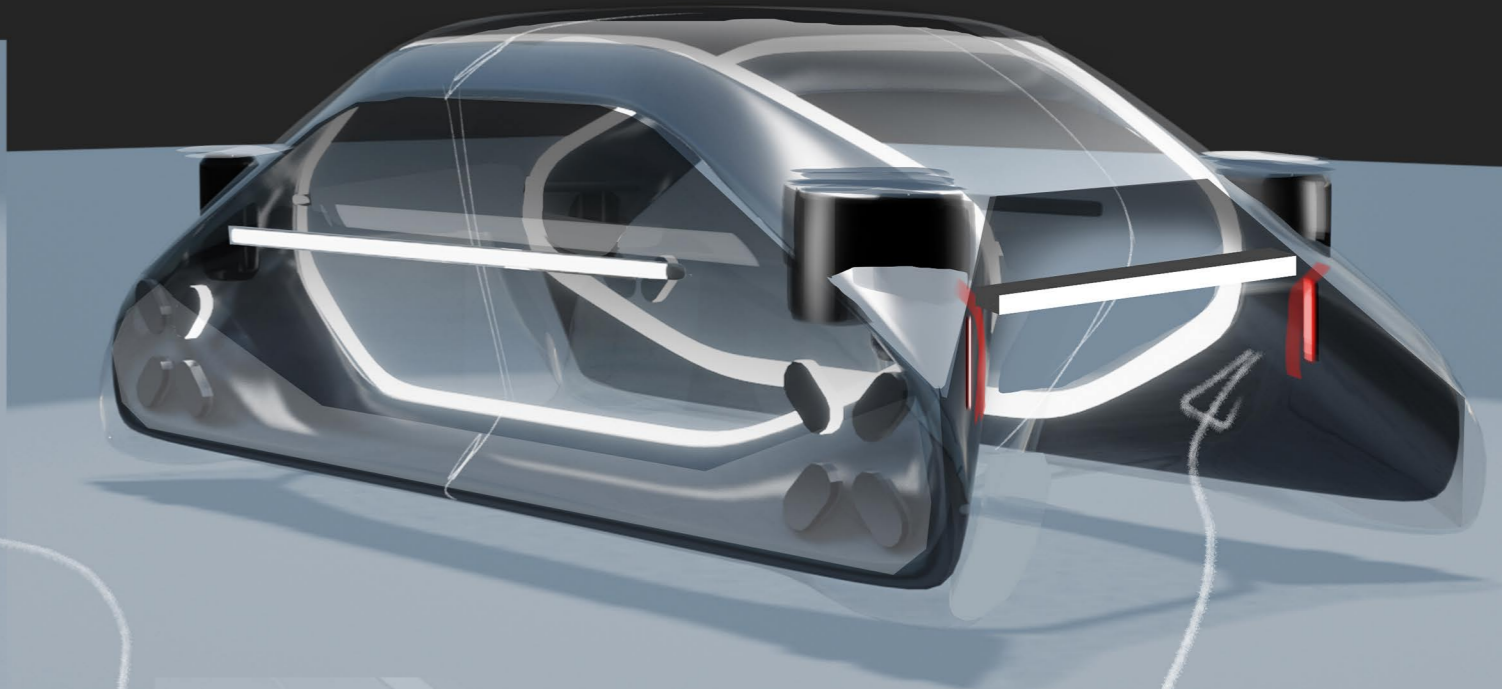
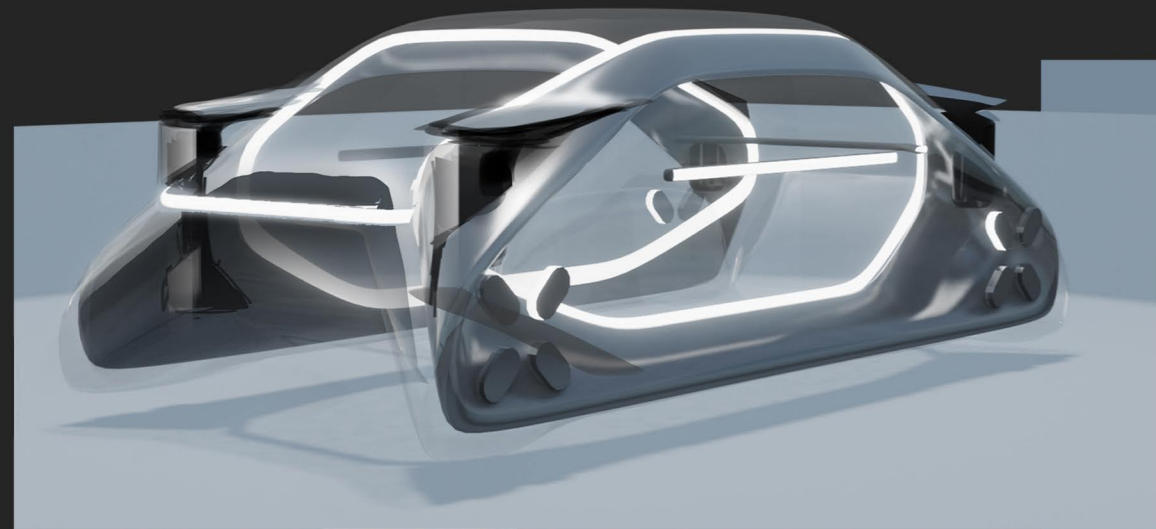


Proj. Jellyfish

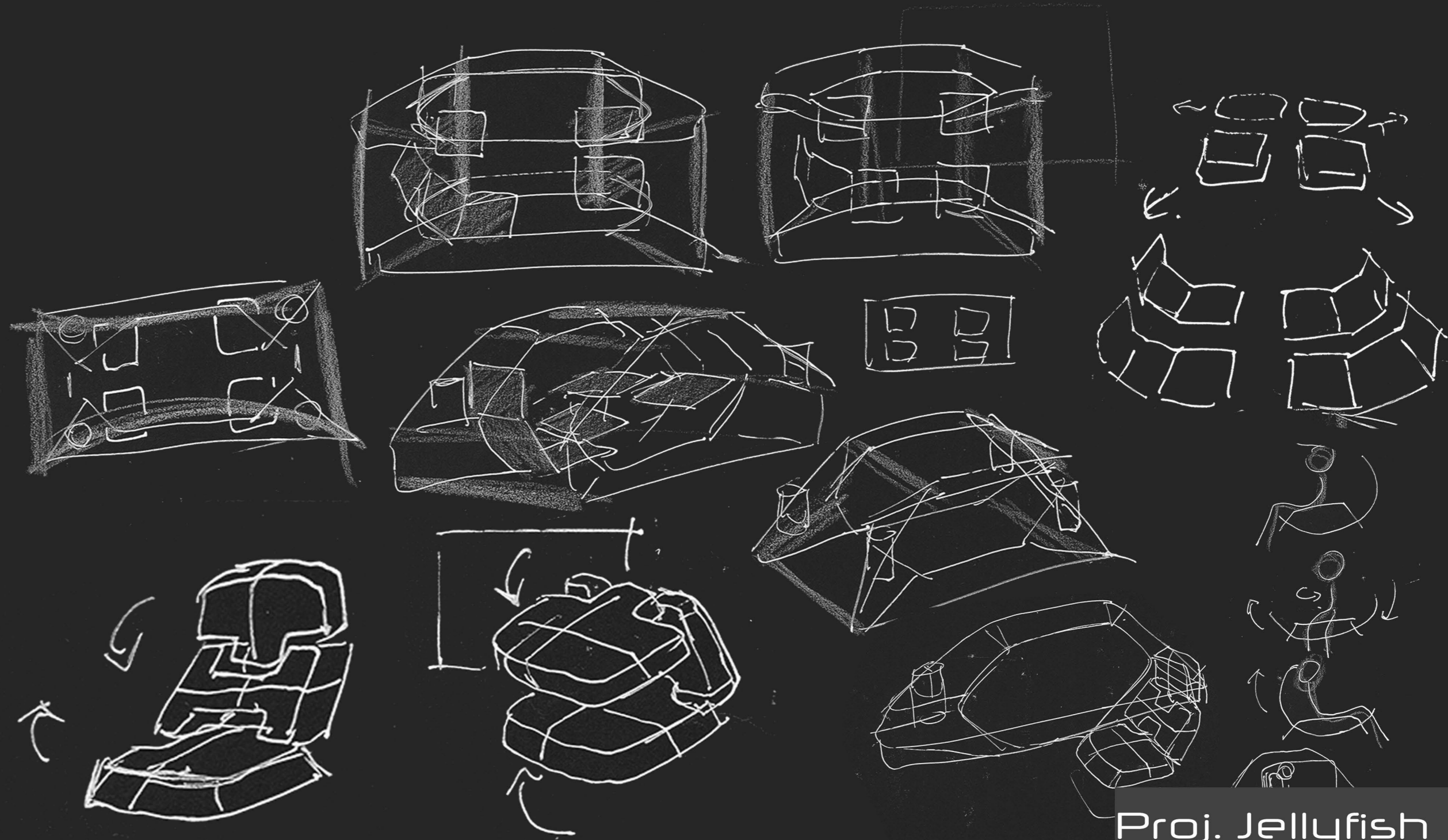
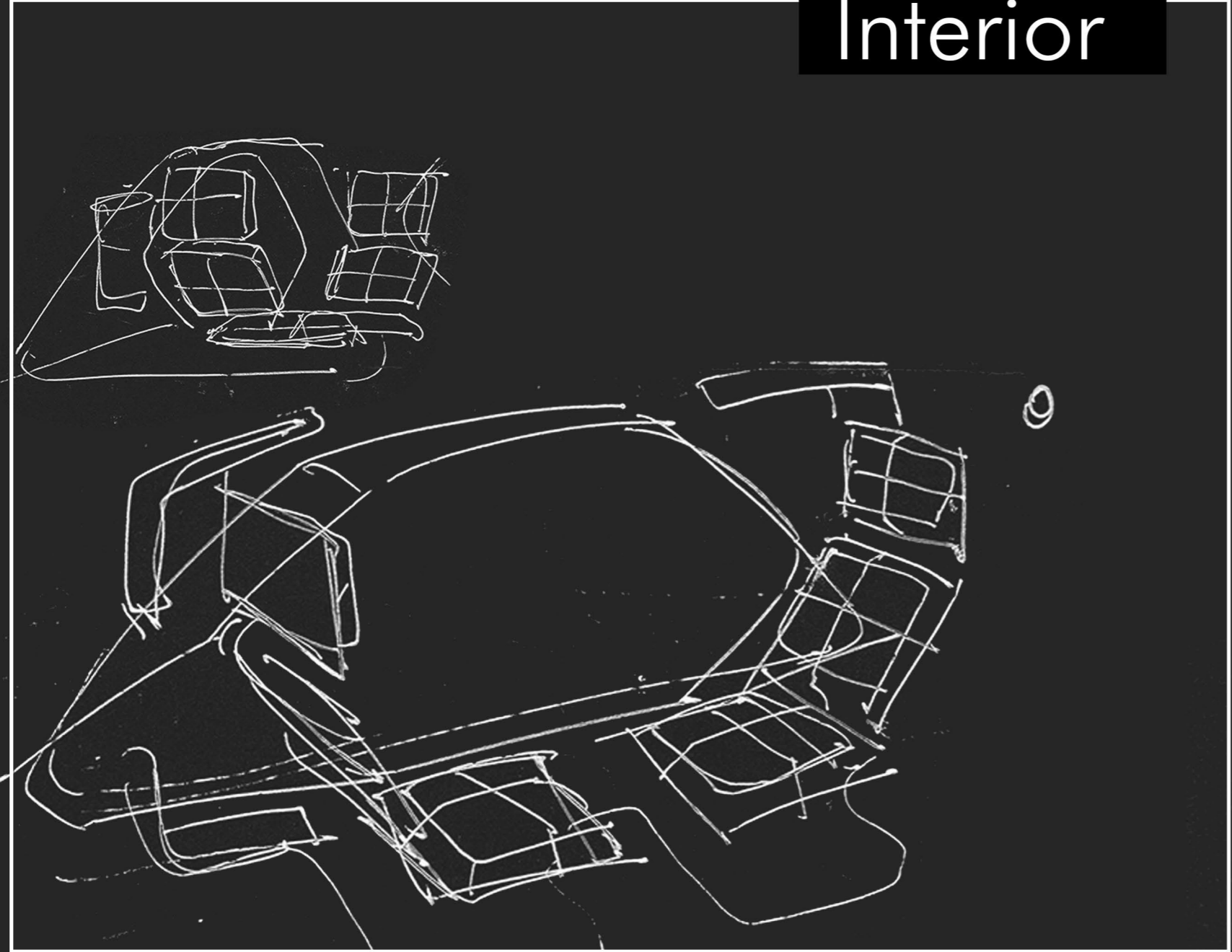


A prototype of the Intelligent Beam system is built, to study how users feel about this system in autonomous journey.

Prototype & Tests



Interior



Interior

