Building & Operating High-Fidelity Data Streams





 In our world today, machine intelligence & personalization drive engaging experiences online



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• In our world today, machine intelligence & personalization drive engaging experiences online









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• In our world today, machine intelligence & personalization drive engaging experiences online





• Disparate data is constantly being connected to drive predictions that keep us engaged!

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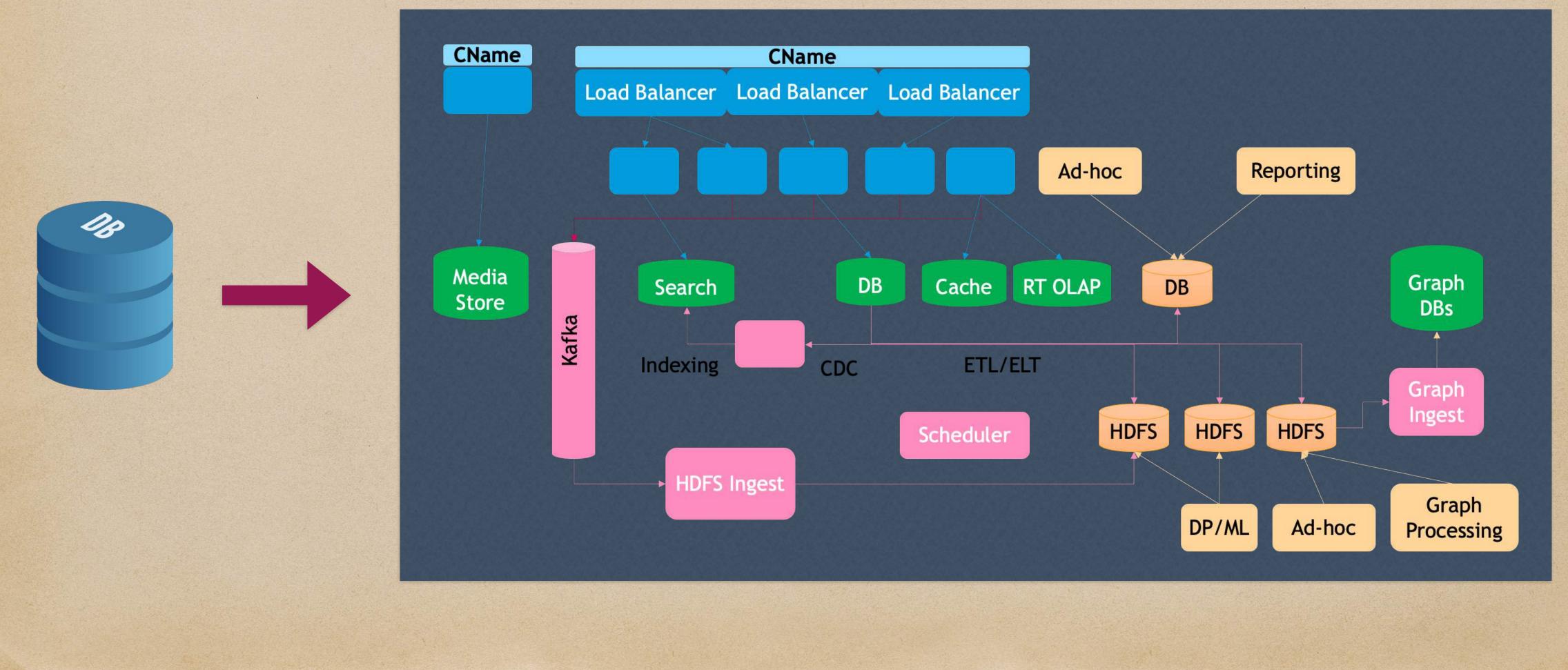


While it may seem that some magical SQL join is powering these connections....



While it may seem that some magical SQL join is powering these connections....
The reality is that data growth has made it impractical to store all of this data in a single DB

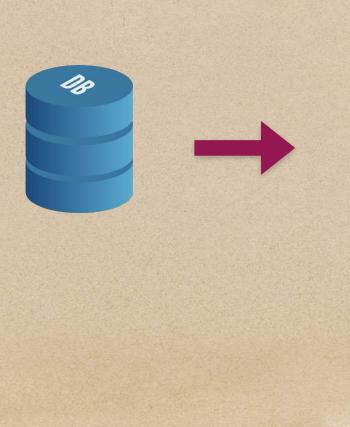


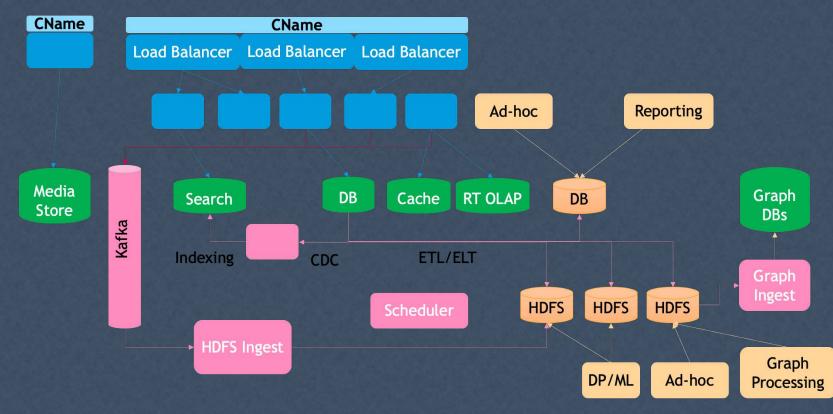




Why Do Streams Matter?

How do companies manage the complexity below?



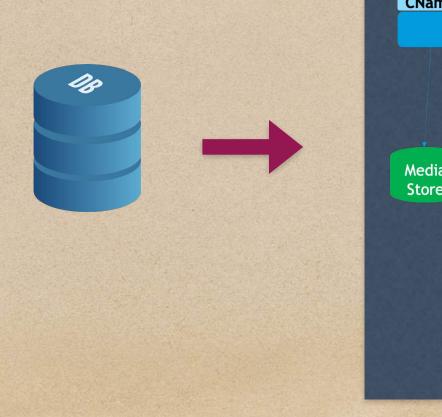


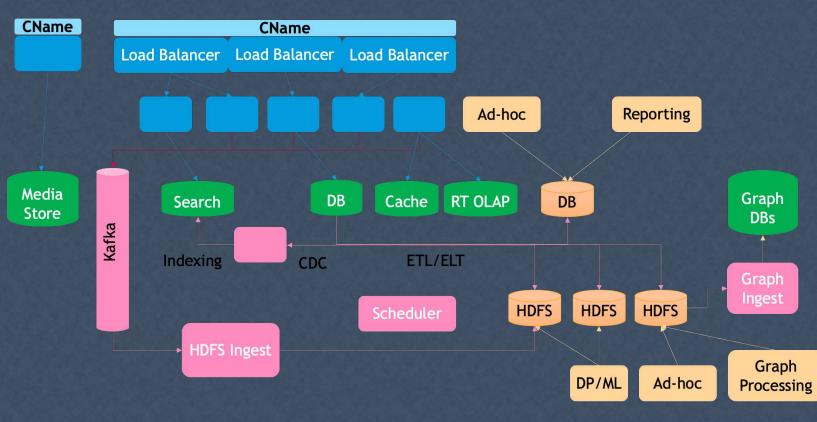


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Why Do Streams Matter?

• A key piece to the puzzle is data movement, which usually comes in 2 forms:







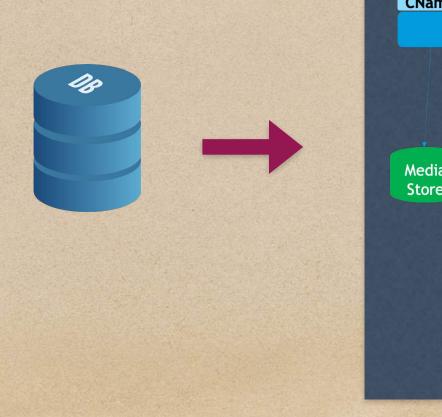
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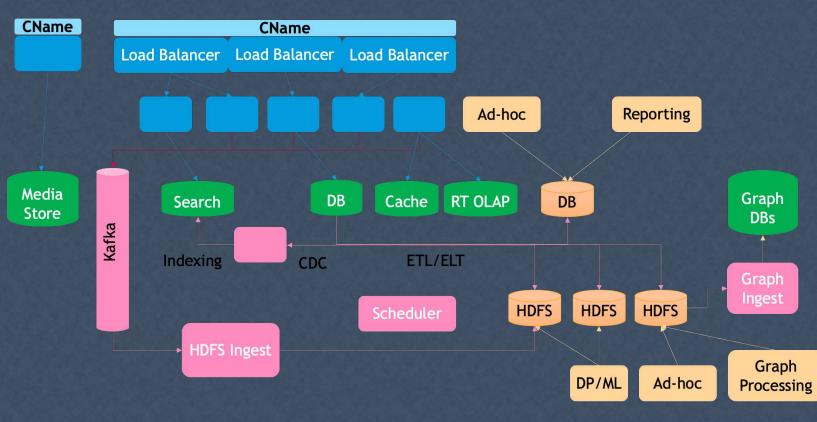
Batch Processing

Stream Processing

Why Do Streams Matter?

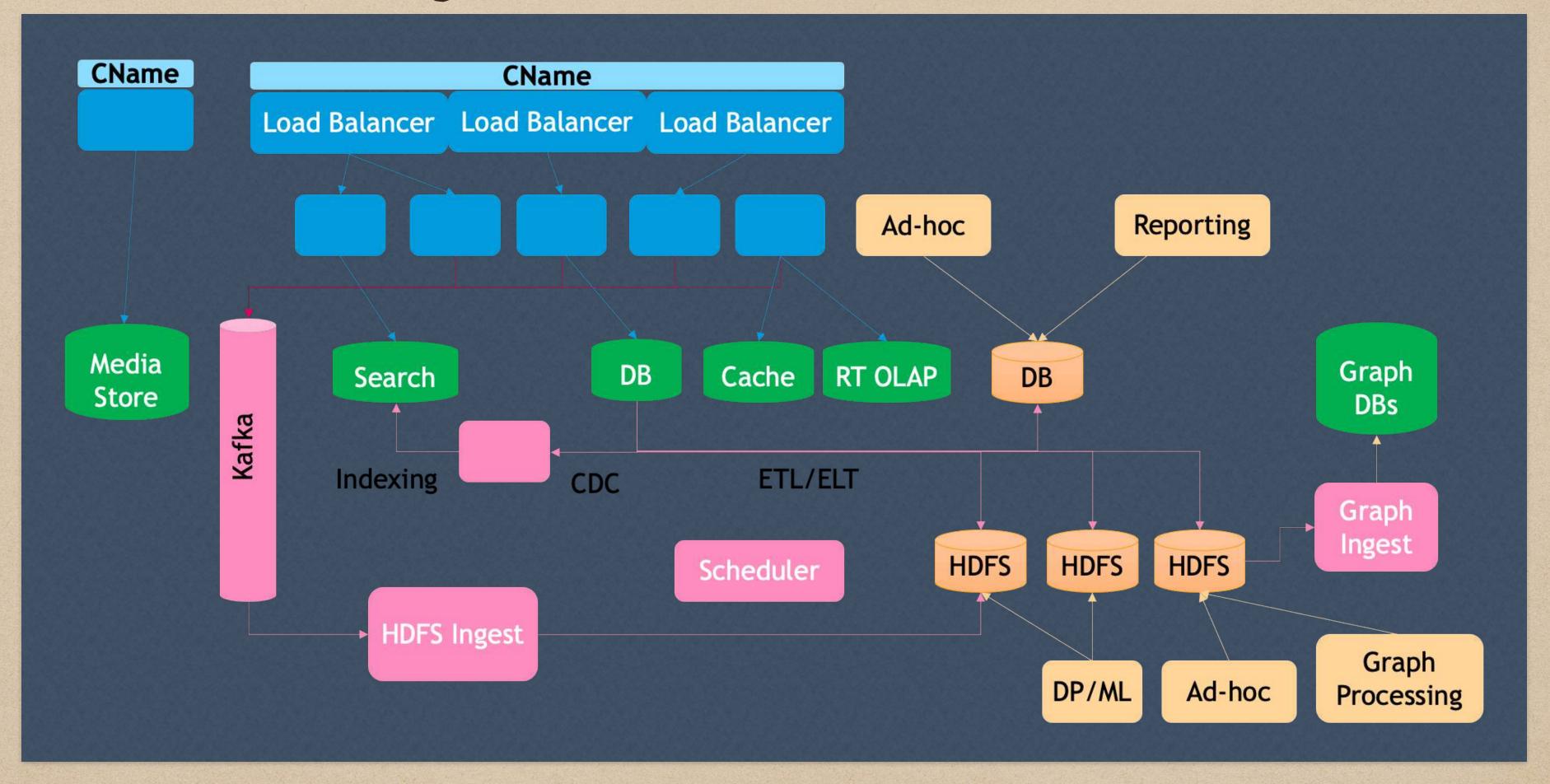
• A key piece to the puzzle is data movement, which usually comes in 2 forms:





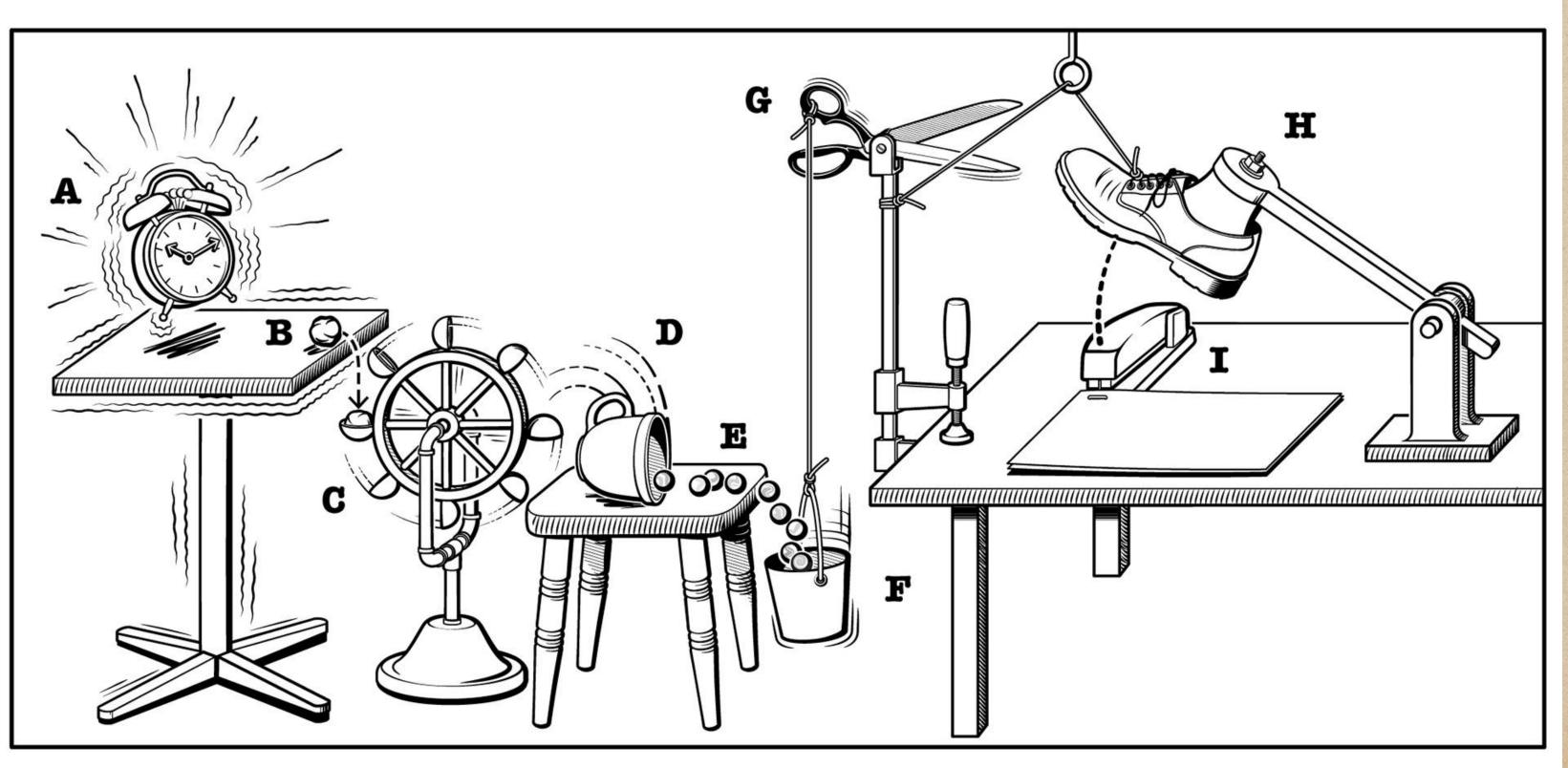








• The answer lies in the image below : complexity, lots of moving parts



Why Are Streams Hard?

© Vernier Software & Technology



Why Are Streams Hard?

• In streaming architectures, any gaps in non-functional requirements can be unforgiving



You end up spending a lot of your time fighting fires & keeping systems up

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Why Are Streams Hard?

• In streaming architectures, any gaps in non-functional requirements can be unforgiving



• In streaming architectures, implementation gaps in non-functional requirements can be unforgiving

You end up spending a lot of your time fighting fires & keeping systems up

• If you don't build your systems with the -ilities as first class citizens, you pay an operational tax

• ... and this translates to unhappy customers and burnt-out team members!





- Data Infrastructure is an iceberg
- Your customers may only see 10% of your effort — those that manifest in features
- The remaining 90% of your work goes unnoticed because it relates to keeping the lights on





- Data Infrastructure is an iceberg
- Your customers may only see 10% of your effort — those that manifest in features
- The remaining 90% of your work goes unnoticed because it relates to keeping the lights on
- In this talk, we will build high-fidelity streams-as-a-service from the ground up!







• Goal : Build a system that can deliver messages from source S to destination D







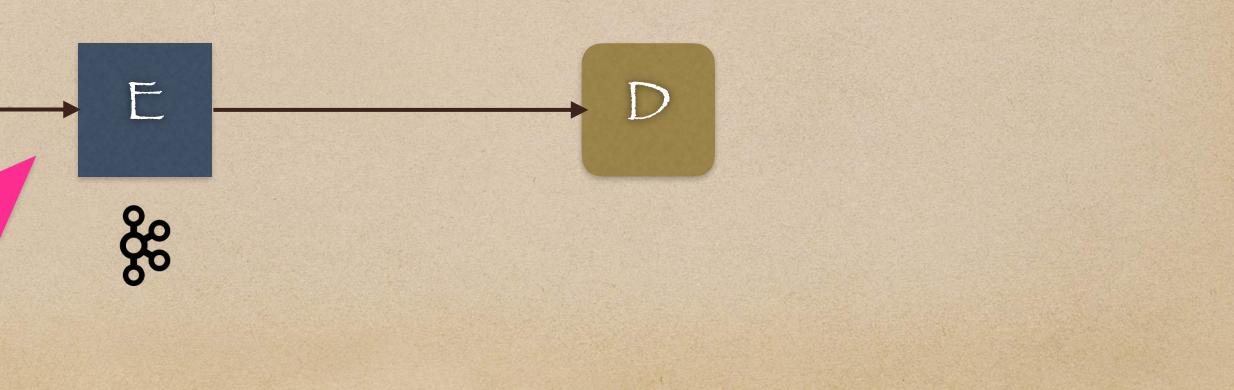
• Goal : Build a system that can deliver messages from source S to destination D

• But first, let's decouple S and D by putting messaging infrastructure between them



S

Events topic







Make a few more implementation decisions about this system

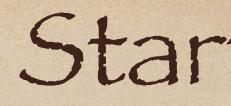
S

Start Simple

E

D





5

 Make a few more implementation decisions about this system • Run our system on a cloud platform (e.g. AWS)

Start Simple

D

E



E

D

Make à few more implementation decisions about this system
Run our system on a cloud platform (e.g. AWS)
Operate at low scale

S



E

D

Make à few more implementation decisions about this system
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Kafka with a single partition

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E

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Make a few more implementation decisions about this system
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S

Kafka across 3 brokers split across AZs with RF=3 (min in-sync replicas =2)



E

 Make a few more implementation decisions about this system • Run our system on a cloud platform (e.g. AWS)

- Operate at low scale
 - Kafka with a single partition

S

- Run S & D on single, separate EC2 Instances

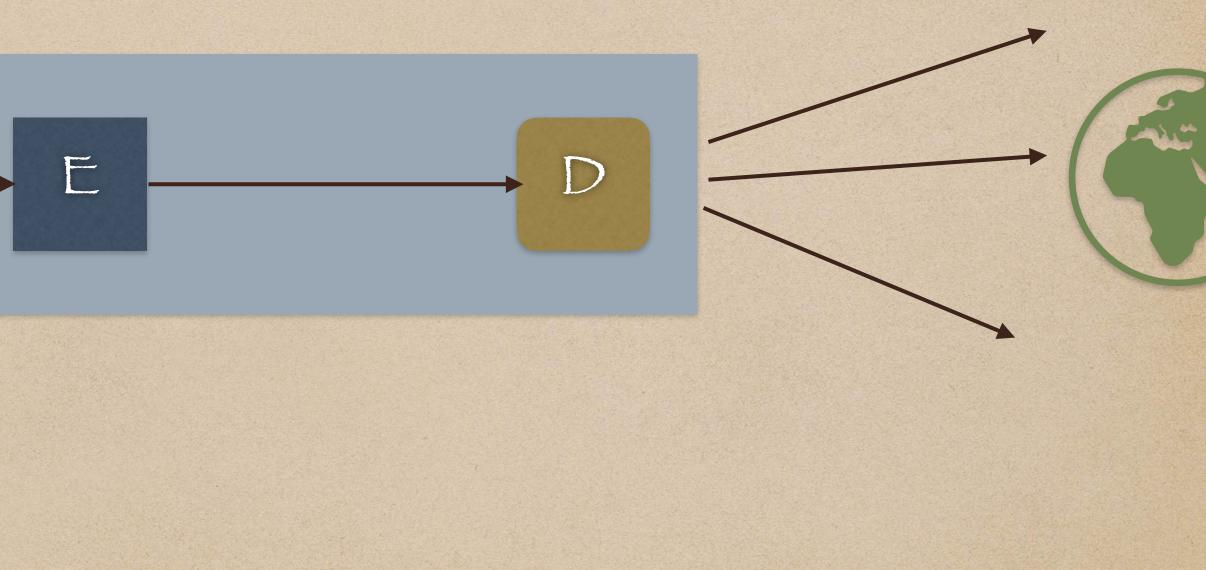
Kafka across 3 brokers split across AZs with RF=3 (min in-sync replicas =2)

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• To make things a bit more interesting, let's provide our stream as a service • We define our system boundary using a blue box as shown below!

S



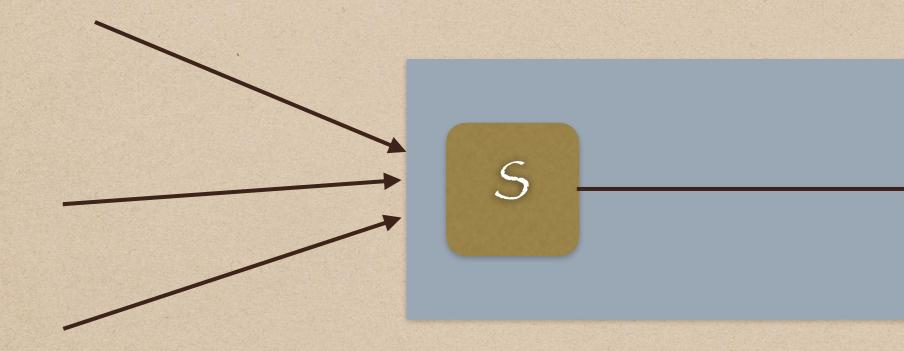


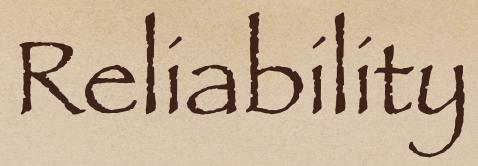


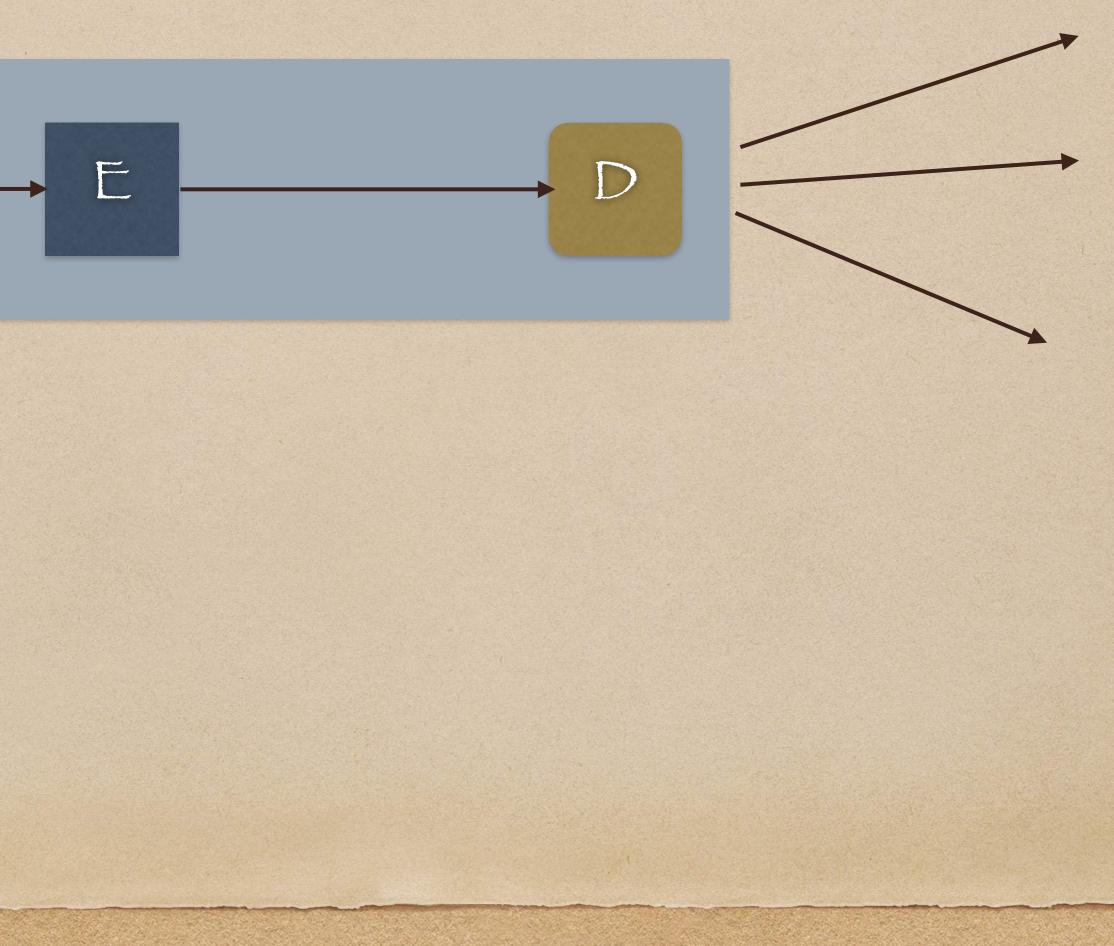
Reliability (Is This System Reliable?)



• Goal : Build a system that can deliver messages reliably from S to D

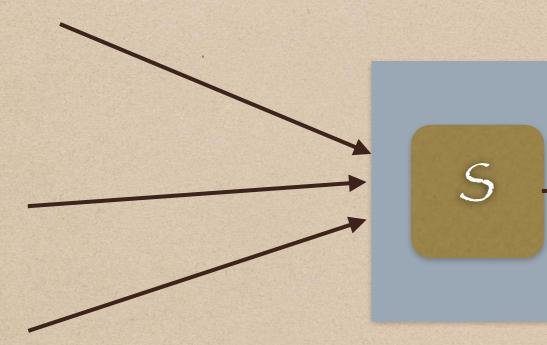




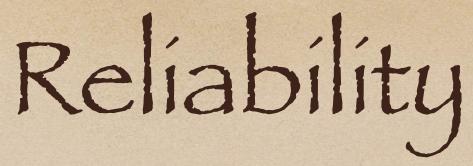


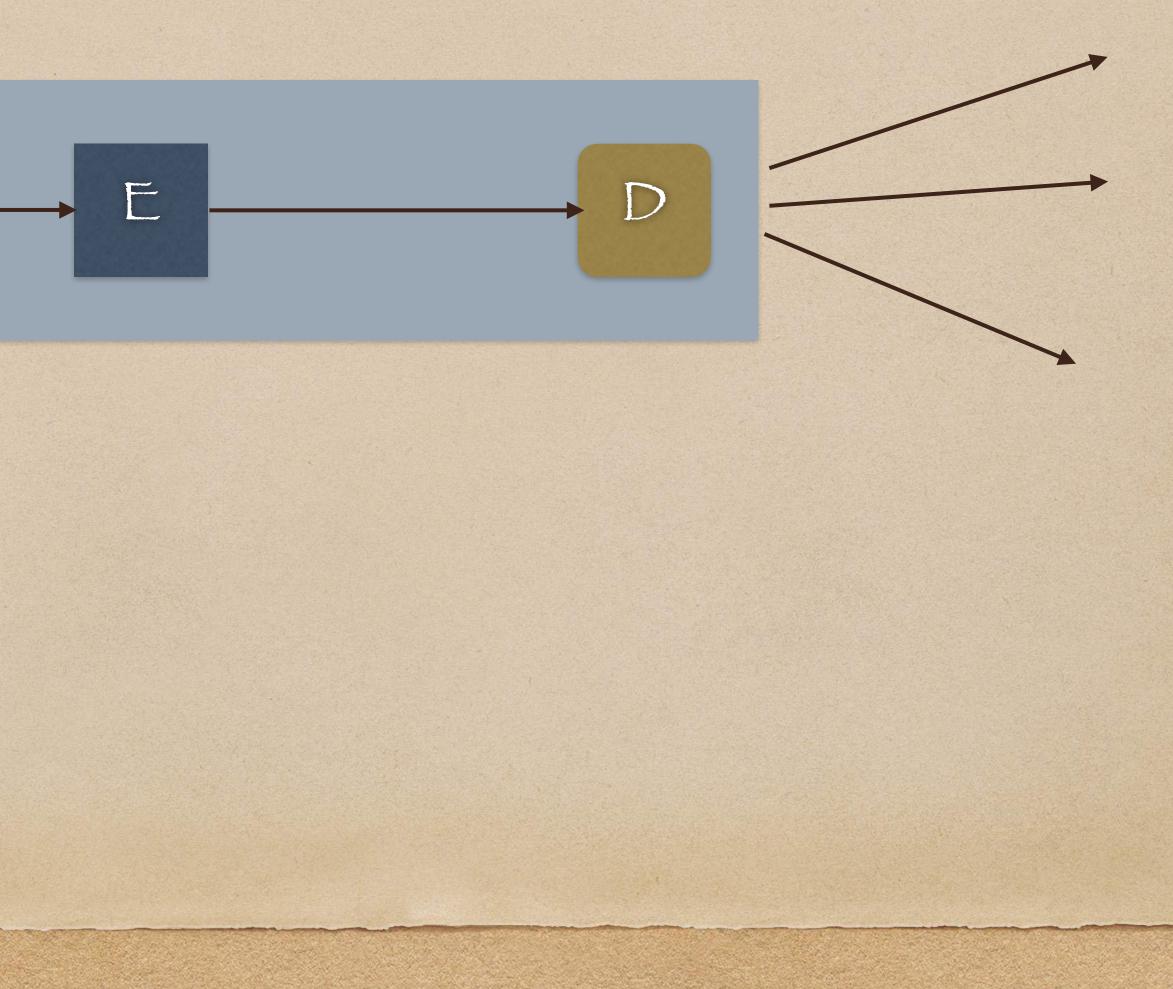


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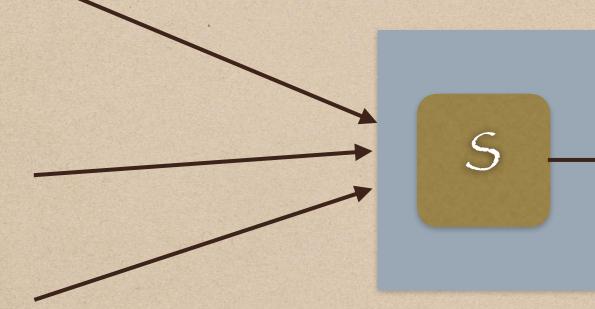
• Concrete Goal : O message loss



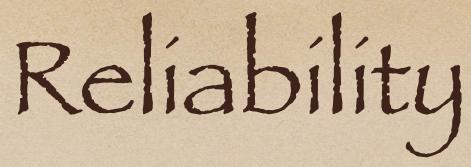


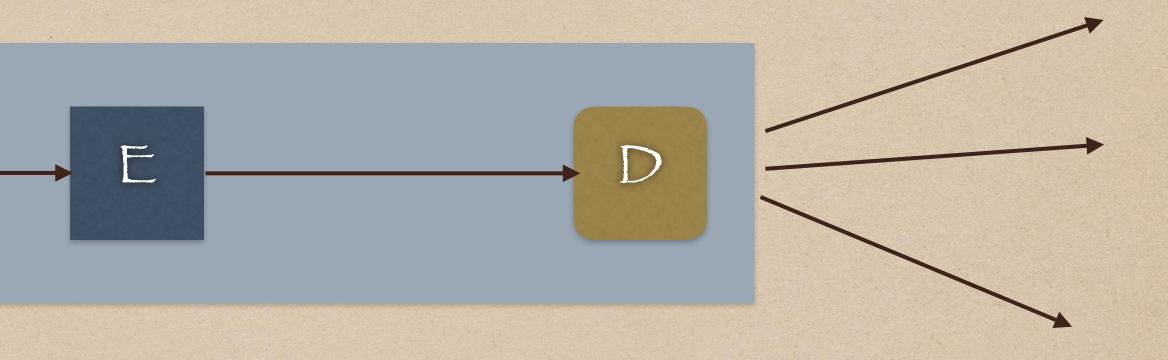


• Goal : Build a system that can deliver messages reliably from S to D



 Concrete Goal : O message loss a remote receiver



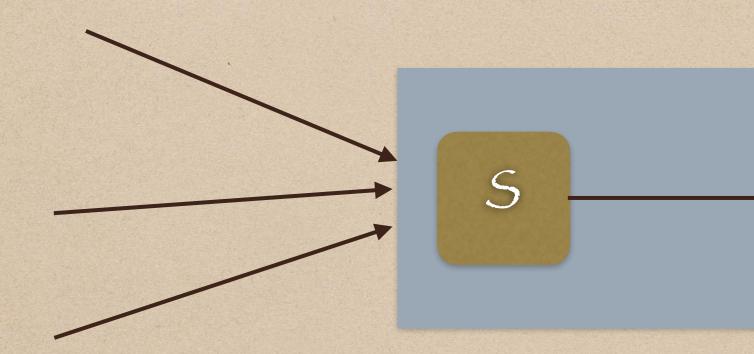


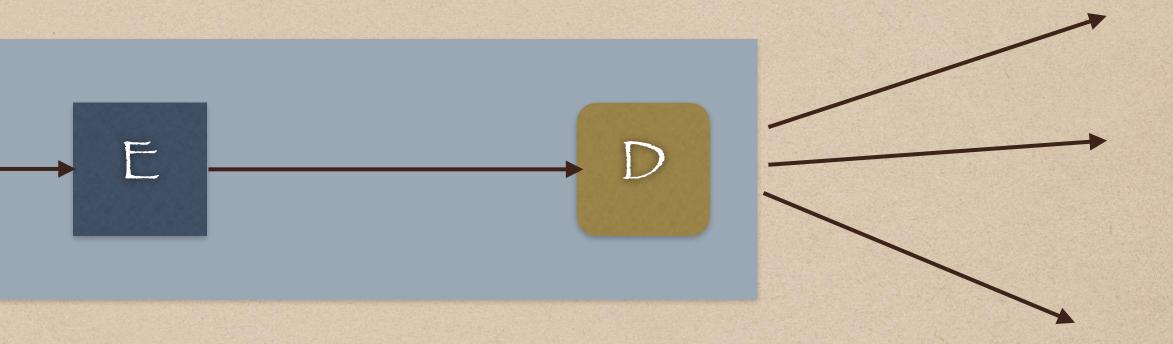
• Once S has ACKd a message to a remote sender, D must deliver that message to



Reliability

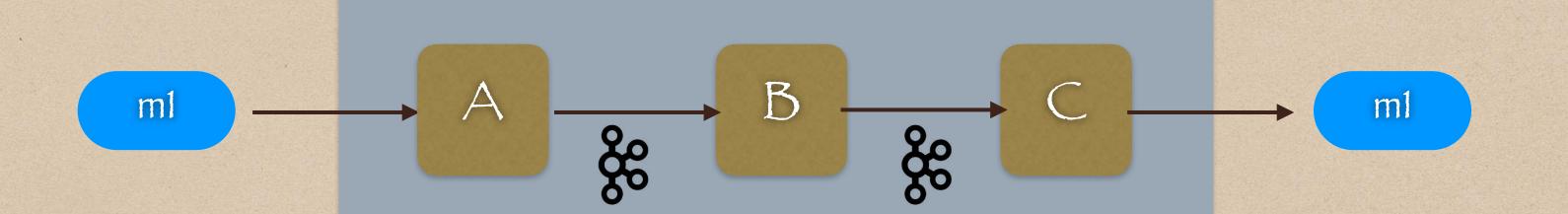
How do we build reliability into our system?





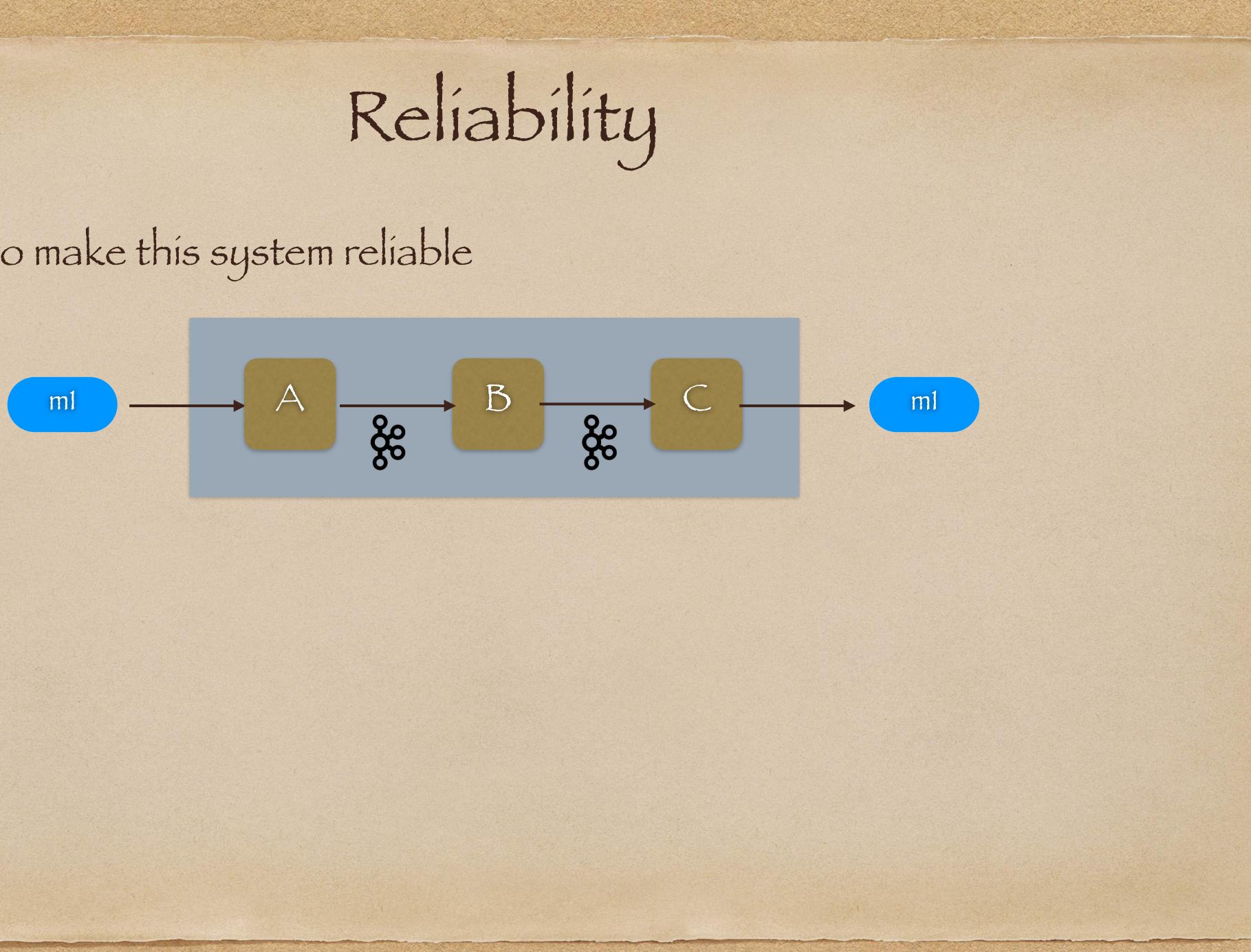


• Let's first generalize our system!



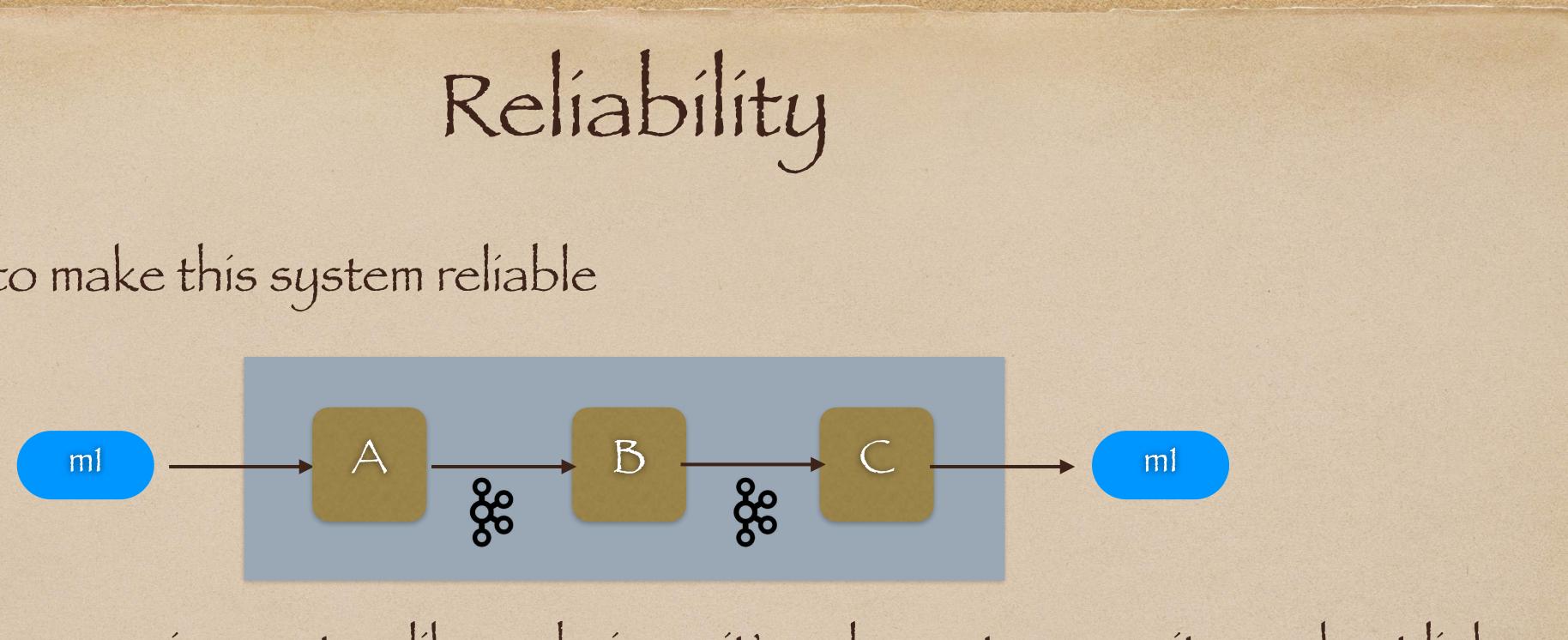


In order to make this system reliable



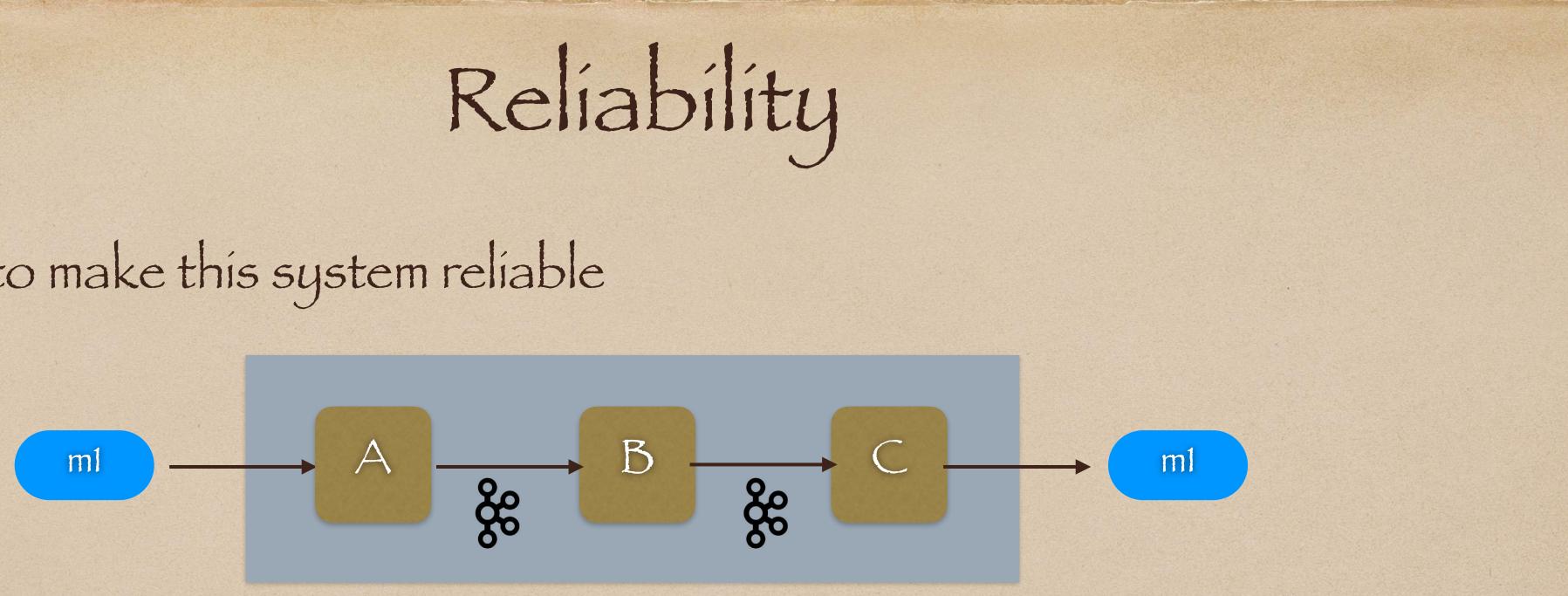


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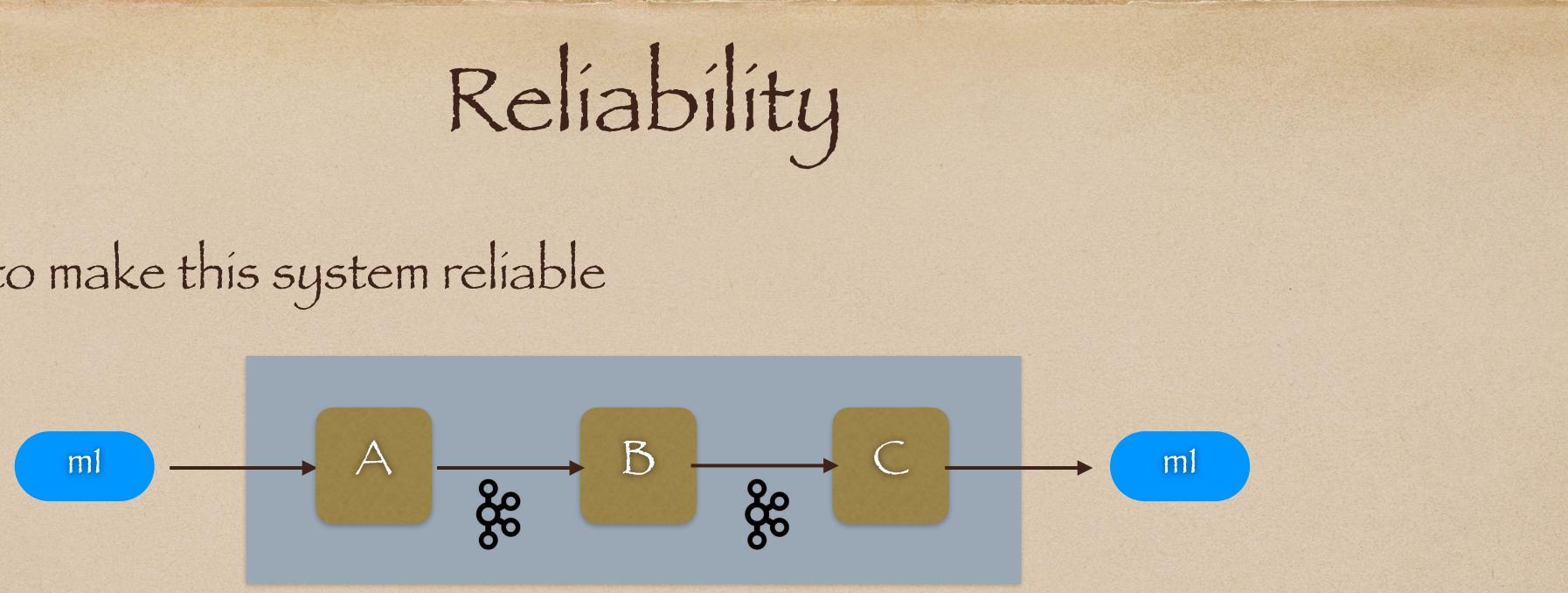
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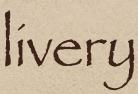
- Insight : If each process/link is transactional in nature, the chain will be transactional!



• In order to make this system reliable

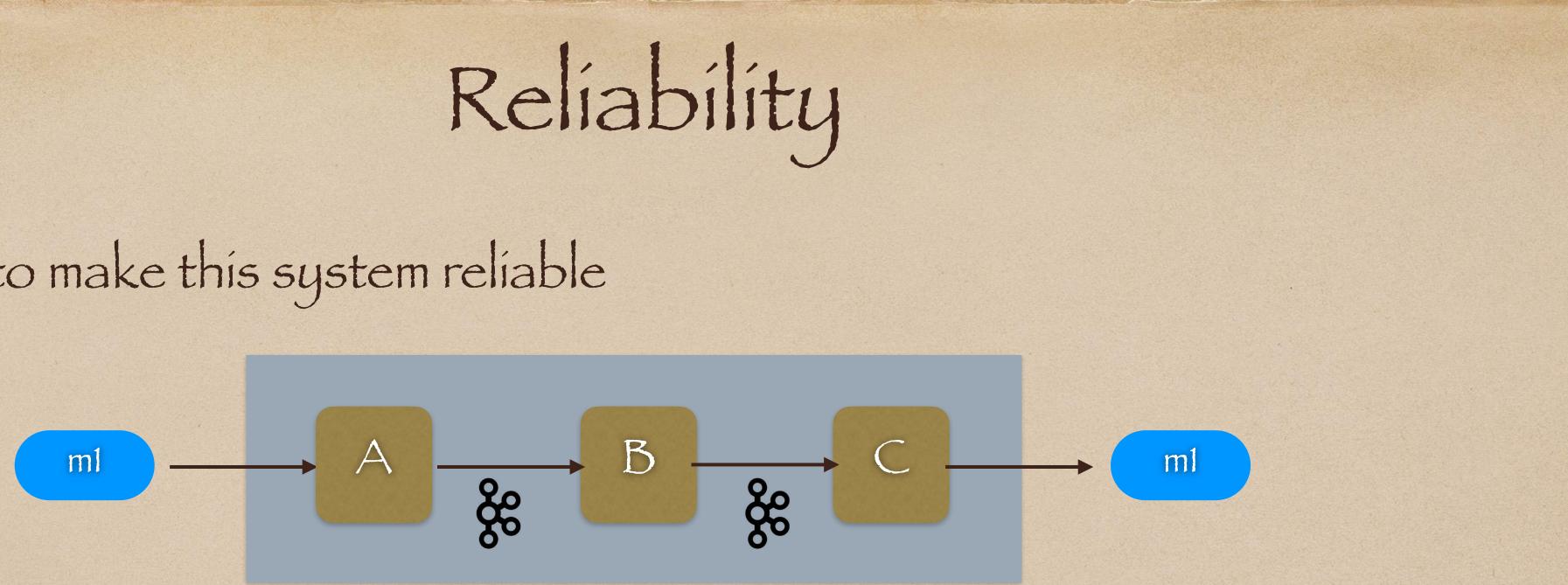


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- Transactionality = At least once delivery





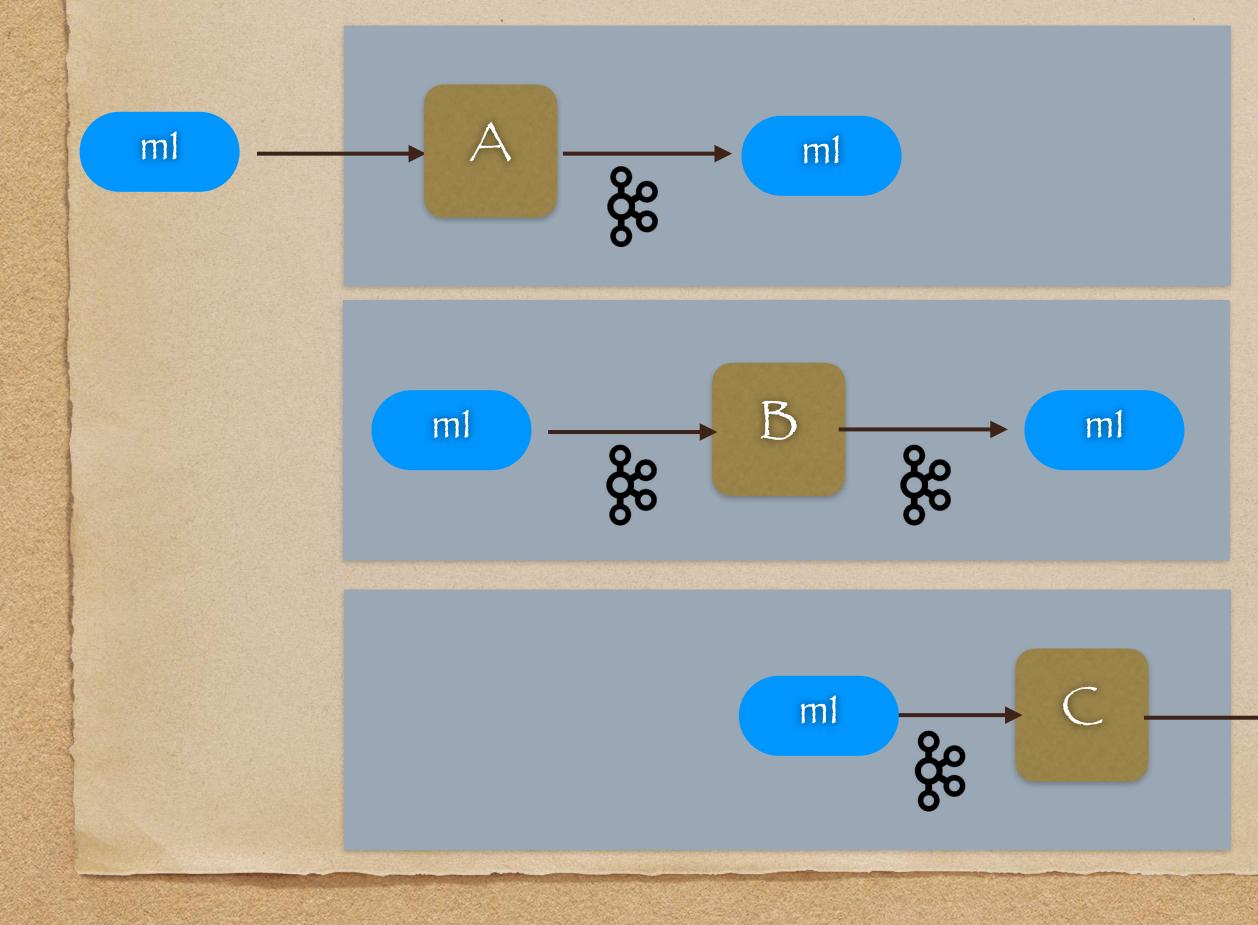
• In order to make this system reliable



- Insight : If each process/link is transactional in nature, the chain will be transactional!
- Transactionality = At least once delivery
- How do we make each link transactional?



Let's first break this chain into its component processing links

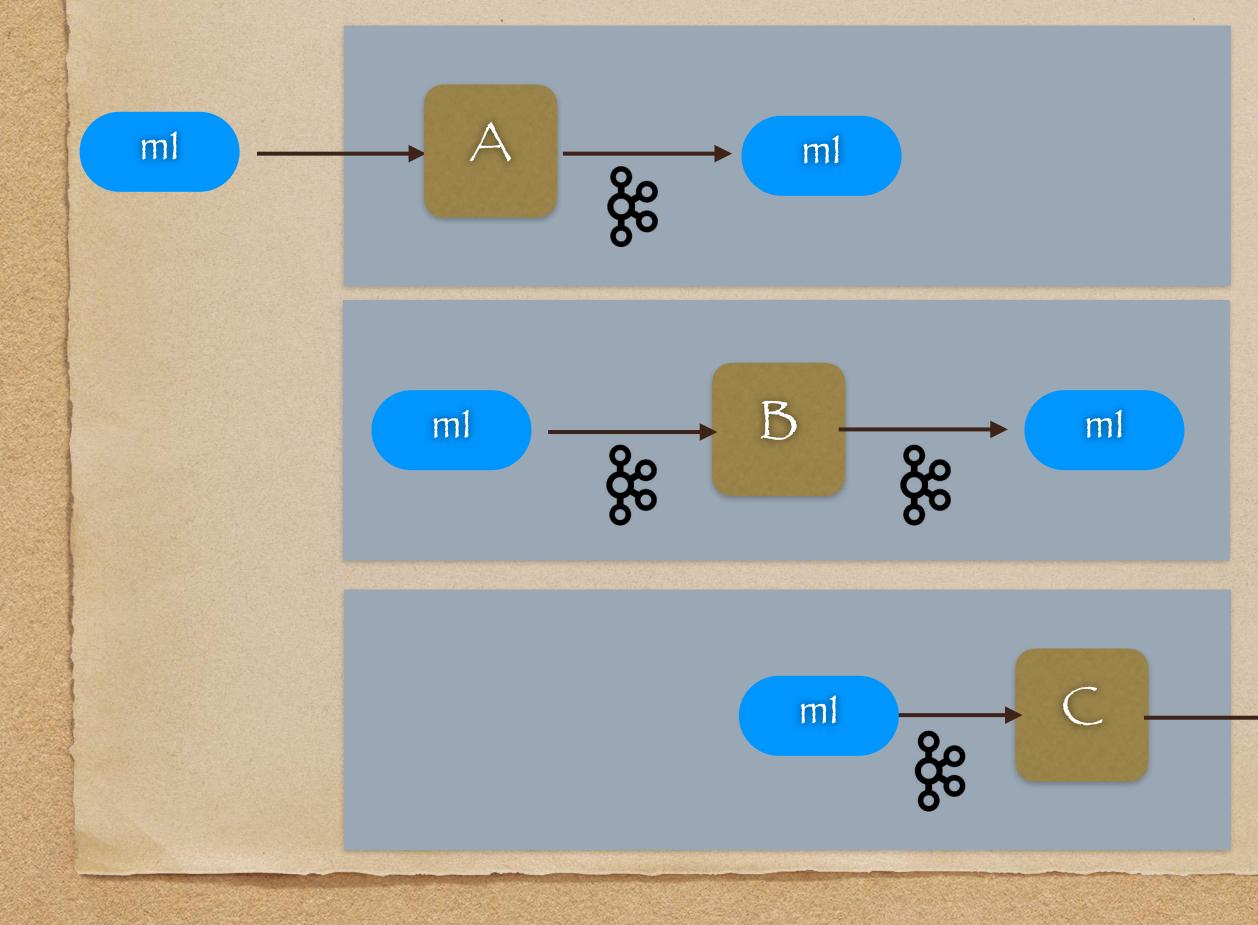


Reliability





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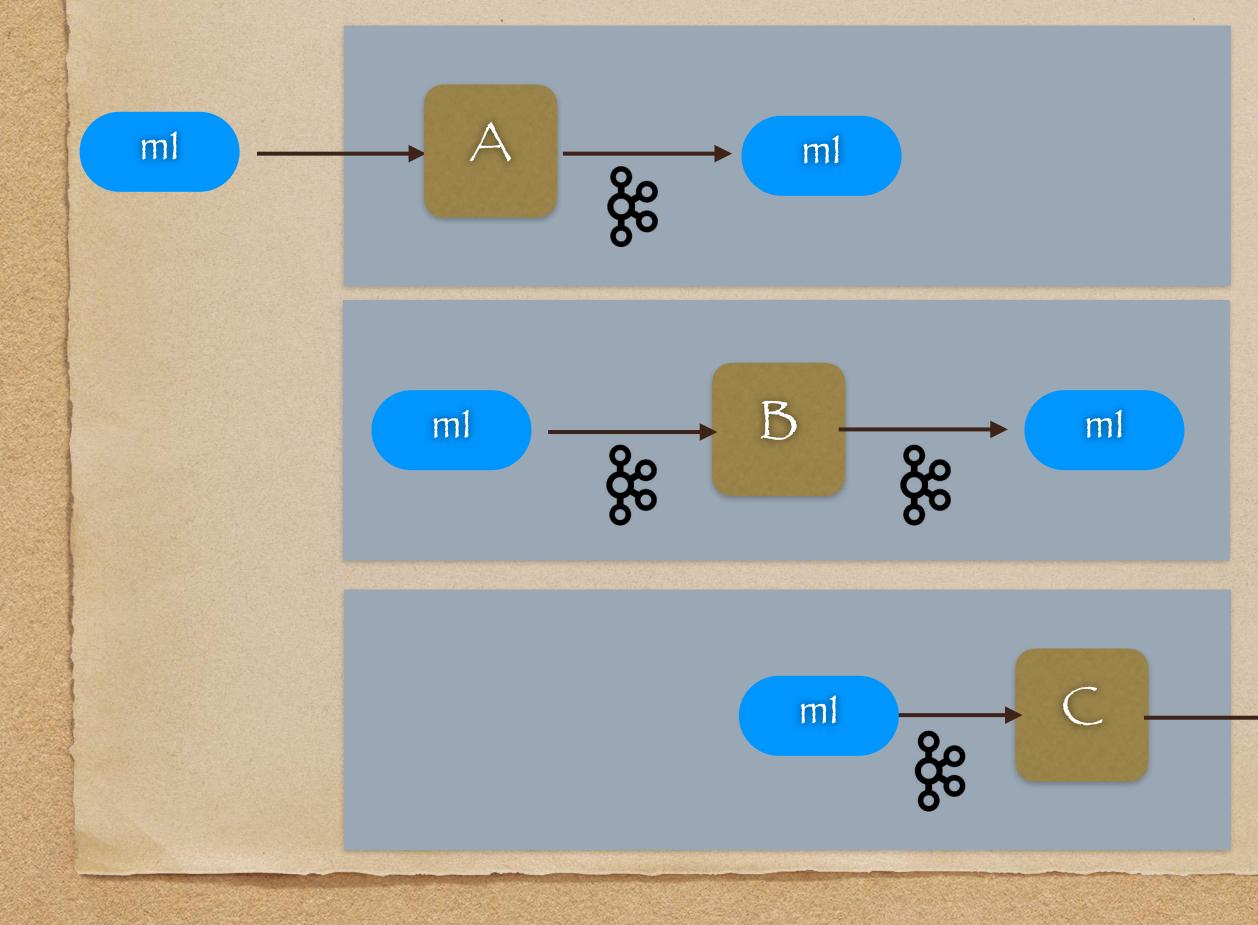
Reliability

A is an ingest node





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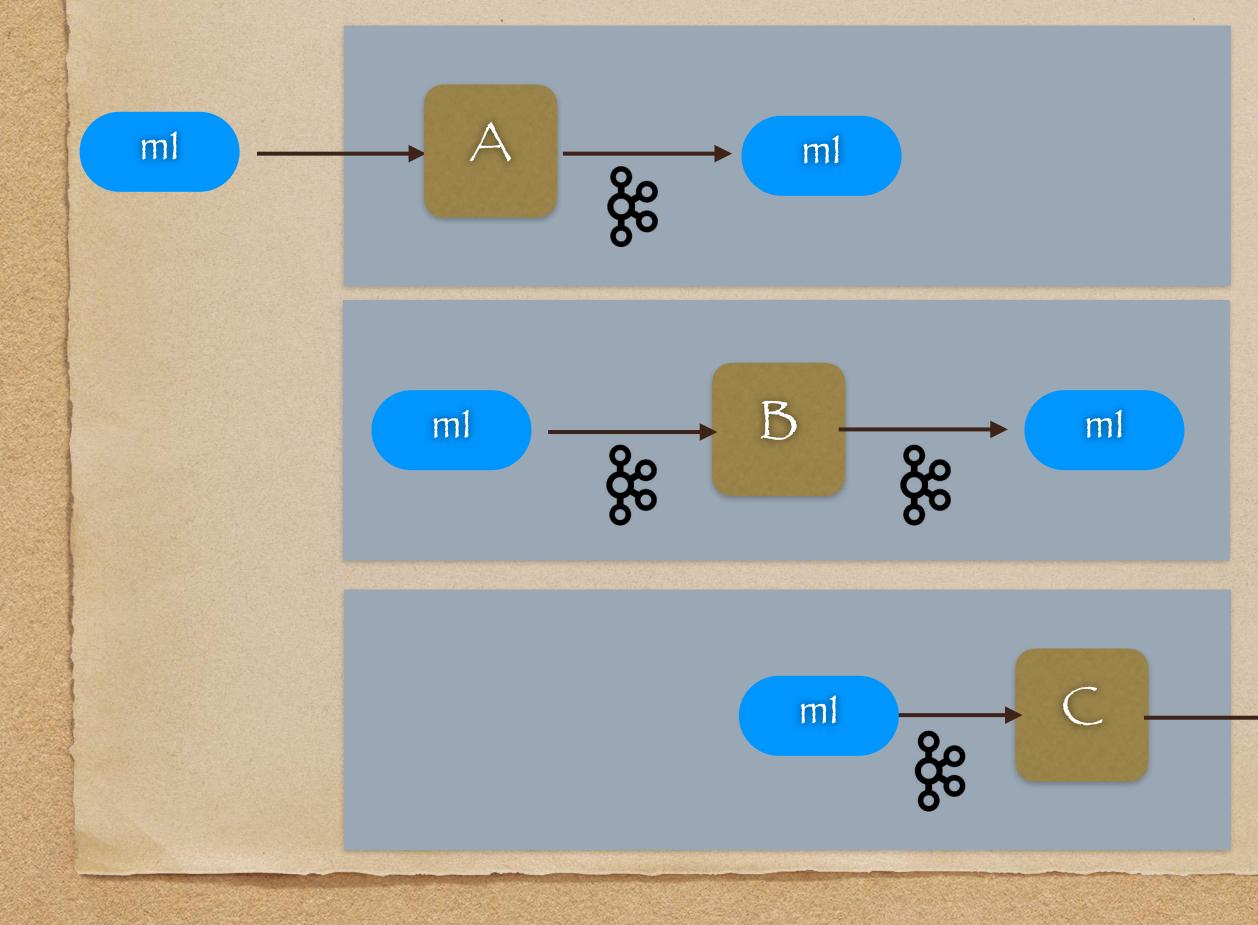
Reliability







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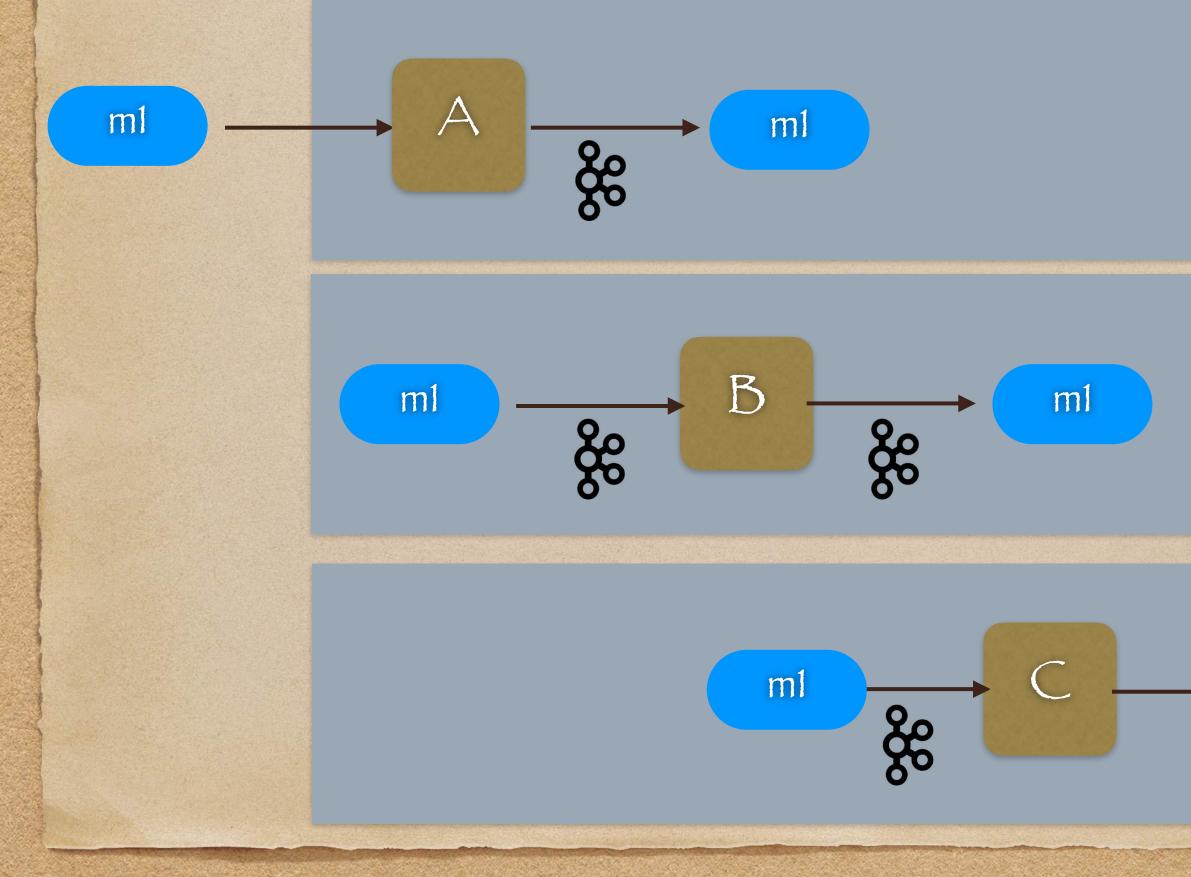
Reliability



C is an expel node



• But, how do we handle edge nodes A & C?



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What does A need to do?

Receive a Request (e.g. REST)

Do some processing

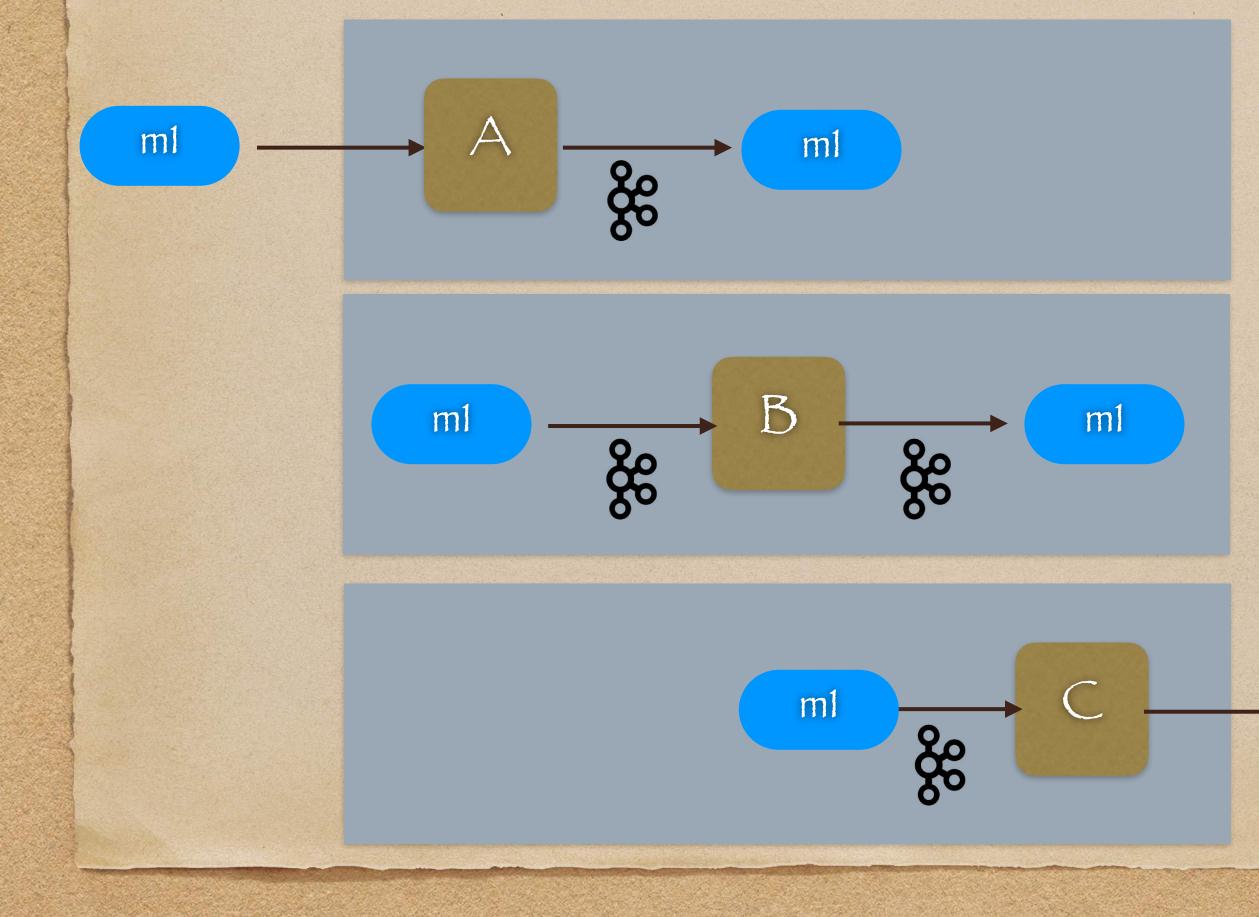
- Reliably send data to Kafka
 - kProducer.send(topíc, message)
 - kProducer.flush()
 - Producer Config
 - acks = all

Send HTTP Response to caller



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• But, how do we handle edge nodes A & C?

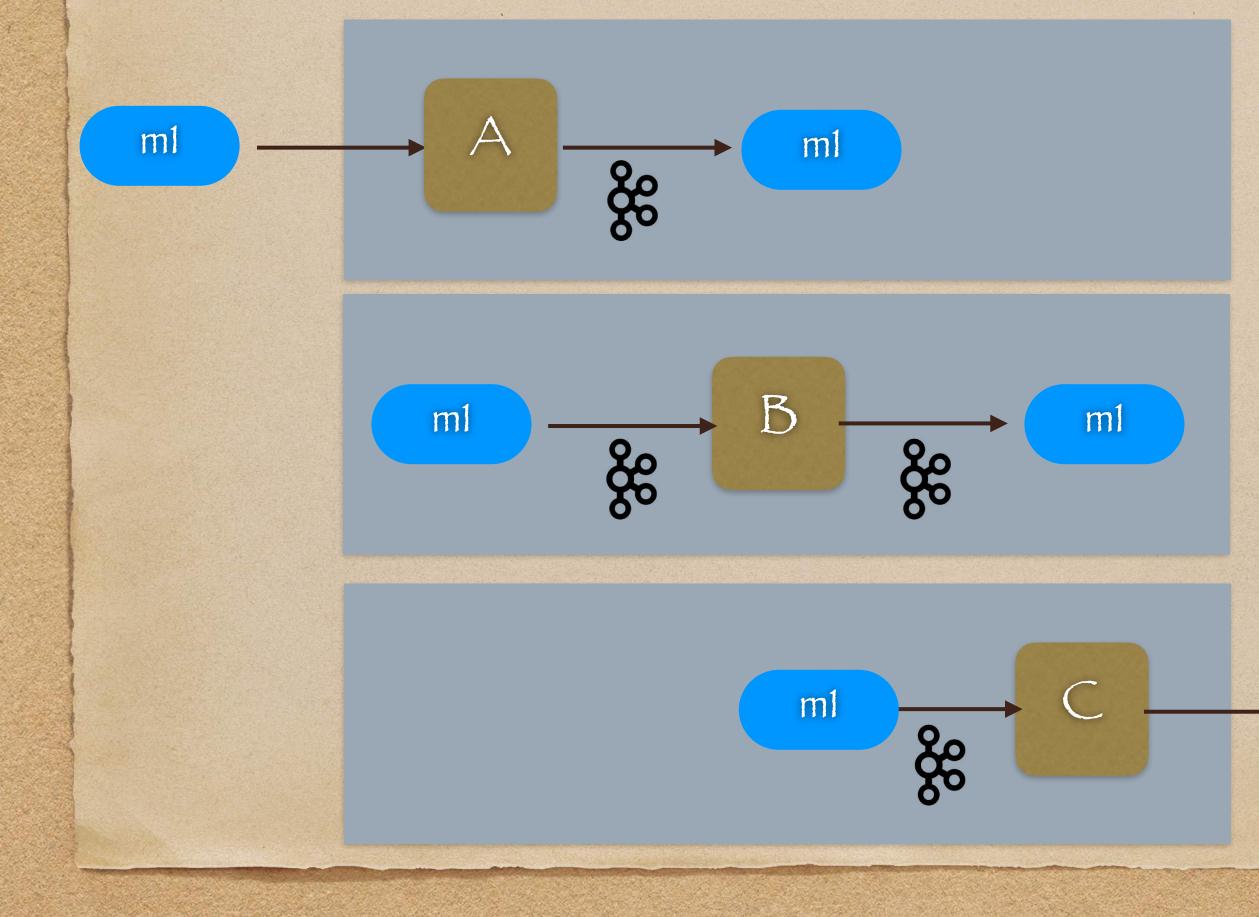


What does C need to do?

- Read data (a batch) from Kafka
- Do some processing
- Reliably send data out
- ACK / NACK Kafka
 - Consumer Config
 - enable.auto.commít = false
 - ACK moves the read checkpoint forward
 - NACK forces a reread of the same data



• But, how do we handle edge nodes A & C?

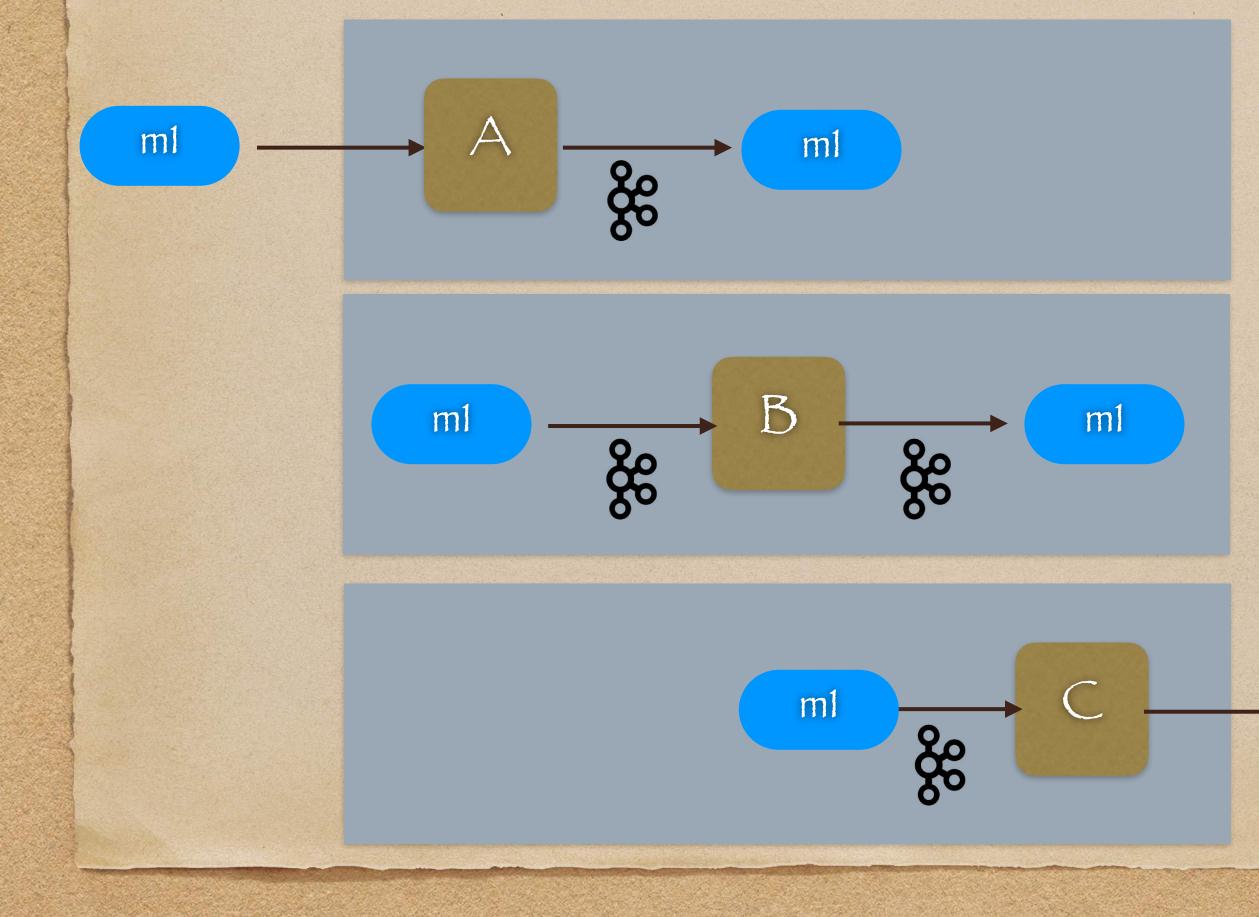


B is a combination of A and C





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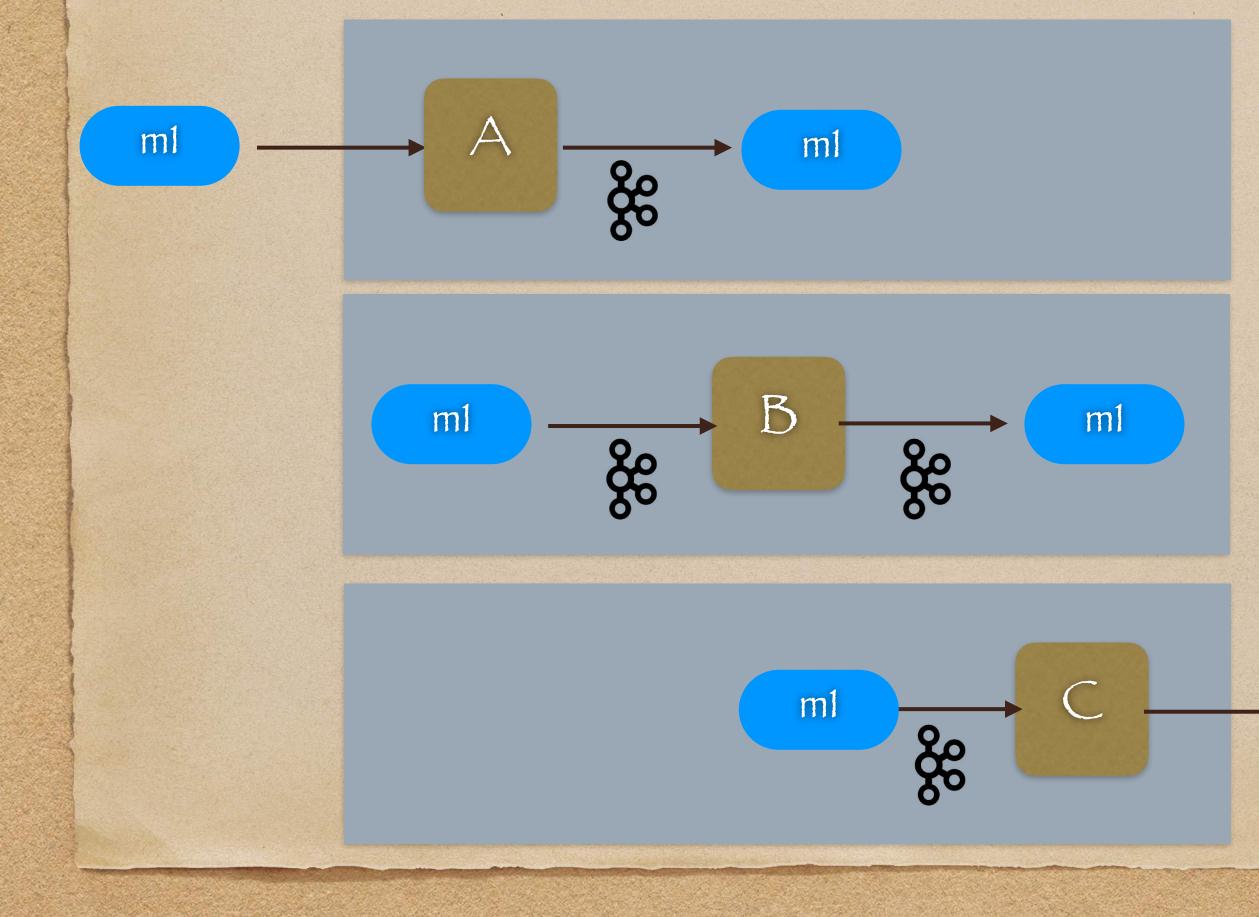
B needs to act like a reliable Kafka Producer

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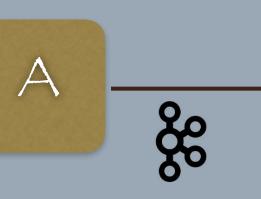
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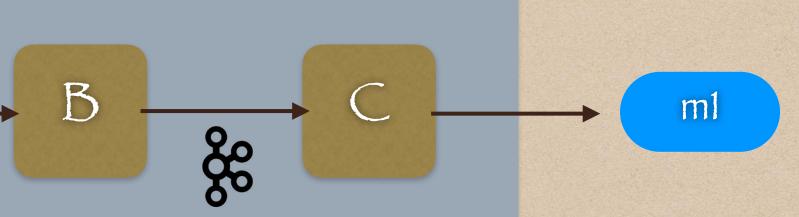
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• How reliable is our system now?

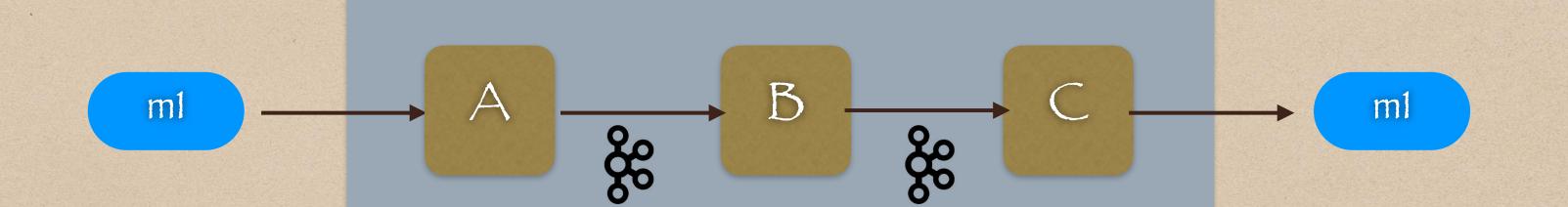








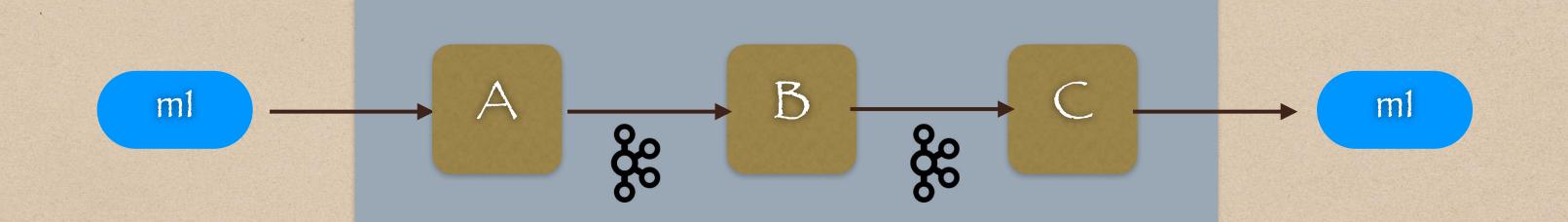
• How reliable is our system now?



• What happens if a process crashes?



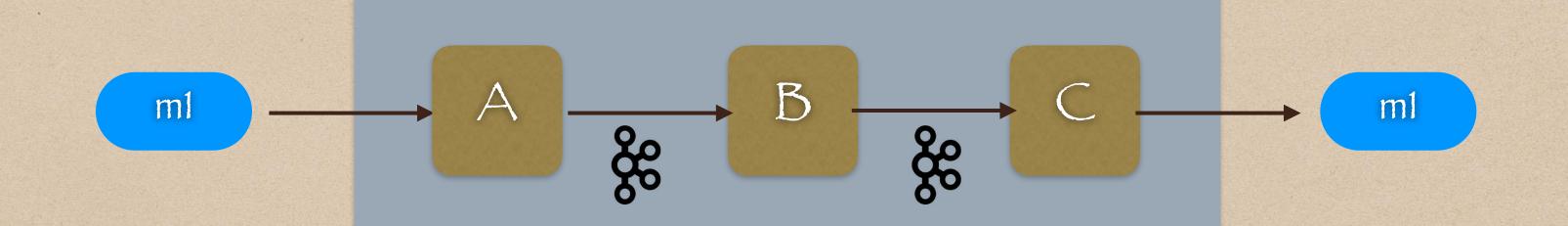
• How reliable is our system now?



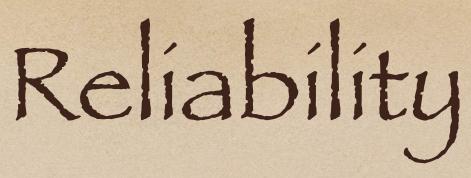
• What happens if a process crashes? • If A crashes, we will have a complete outage at ingestion!



• How reliable is our system now?

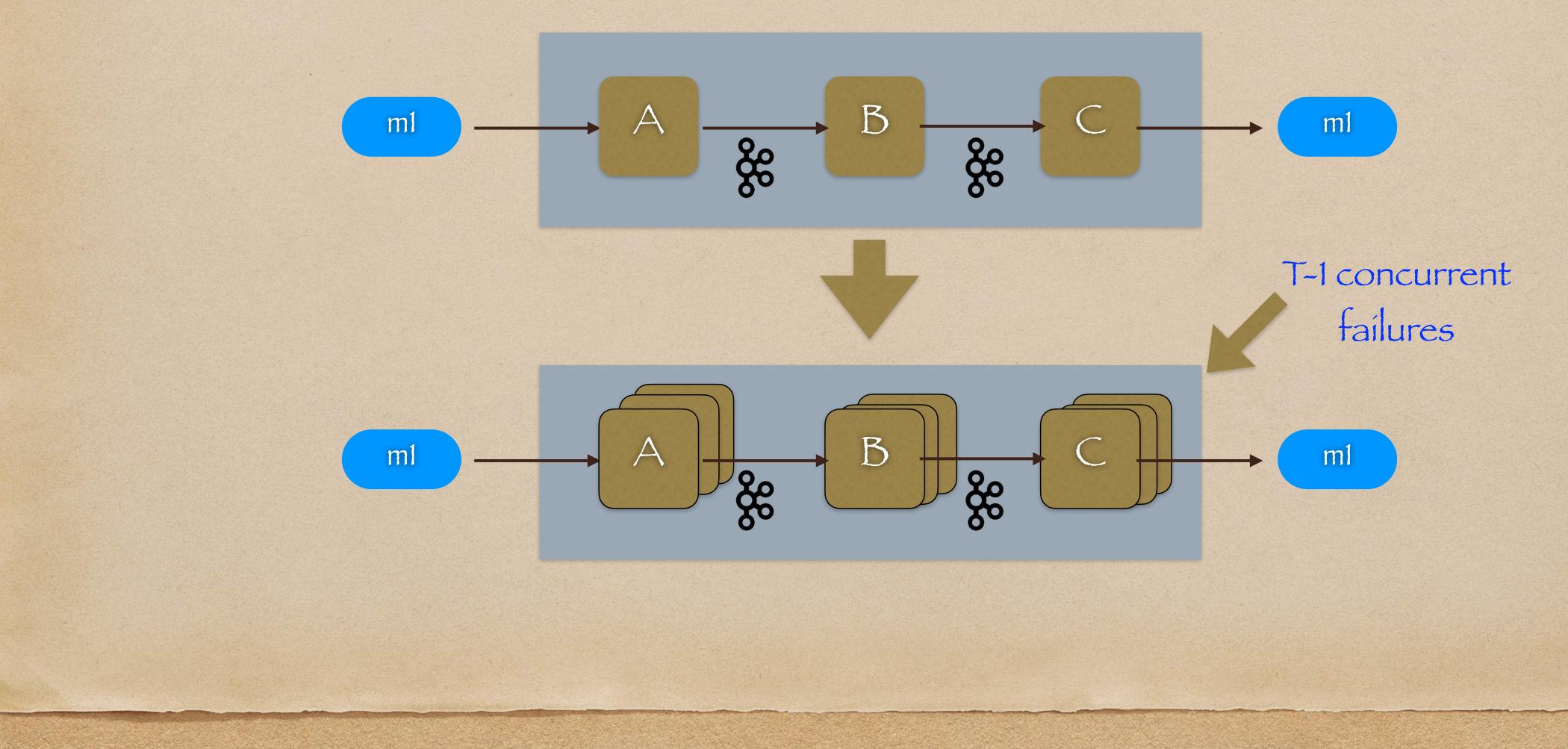


• What happens if a process crashes? • If A crashes, we will have a complete outage at ingestion! • If C crashes, we will stop delivering messages to external consumers!





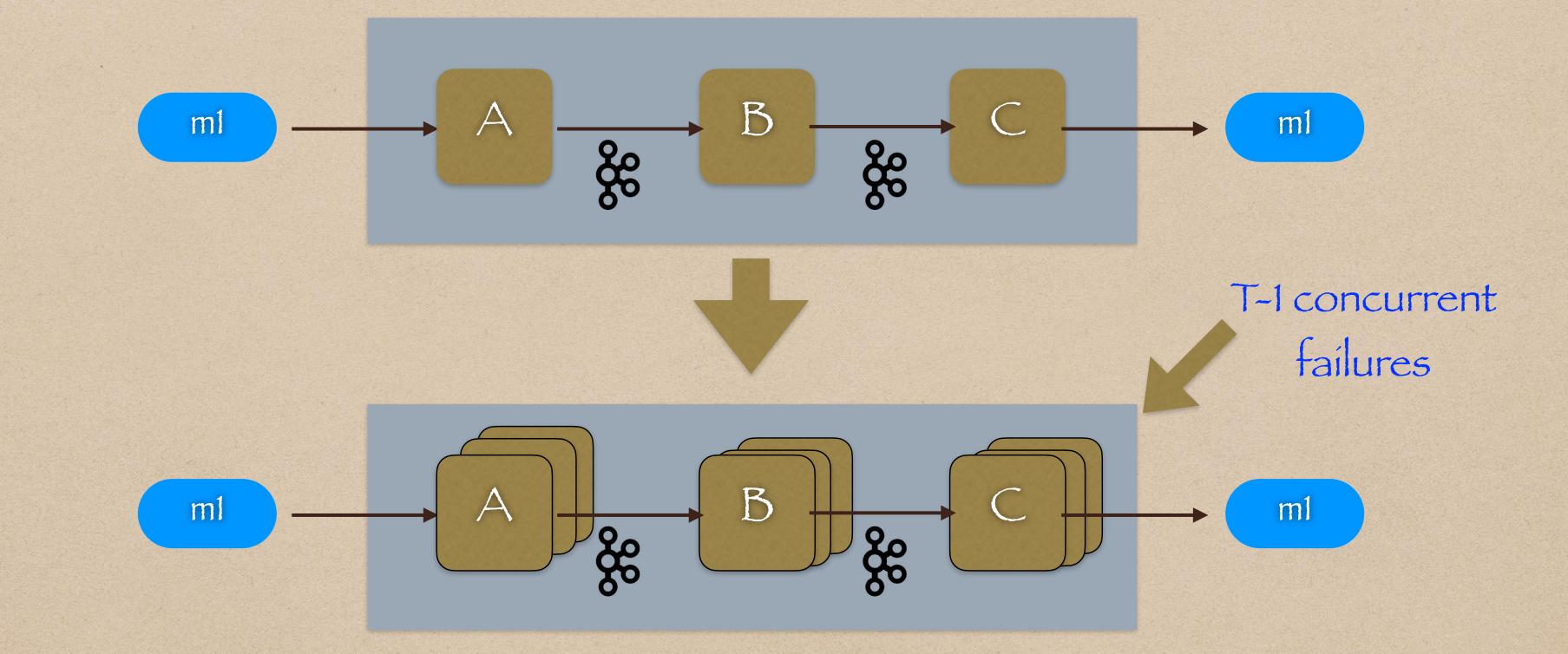
Solution : Place each service in an autoscaling group of size T



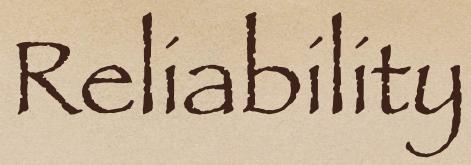




Solution : Place each service in an autoscaling group of size T



• For now, we appear to have a pretty reliable data stream





But how do we measure its reliability?





(This brings us to ...)

Observability (A story about Lag & Loss Metrics)









• Lag is simply a measure of message delay in a system





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• The longer a message takes to transit a system, the greater its lag





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• Lag is simply a measure of message delay in a system • The longer a message takes to transit a system, the greater its lag • The greater the lag, the greater the impact to the business



Lag: What is it?

• Hence, our goal is to minimize lag in order to deliver insights as quickly as possible



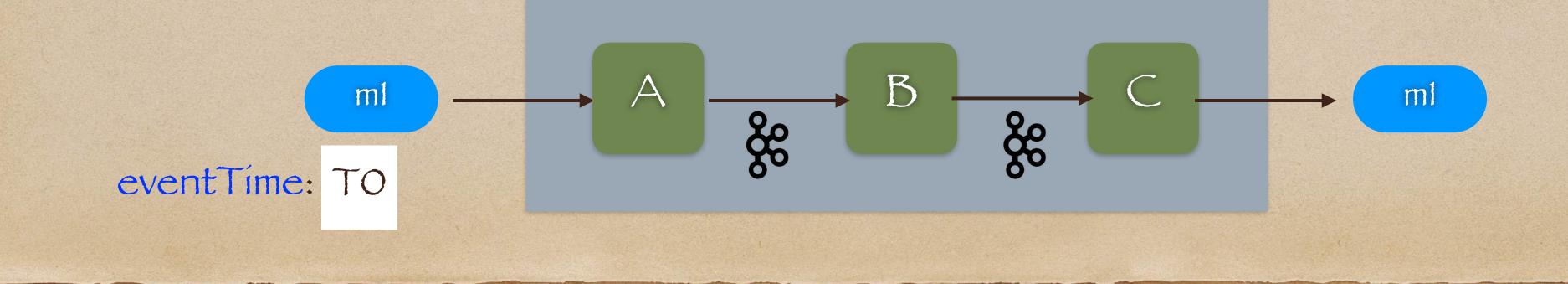




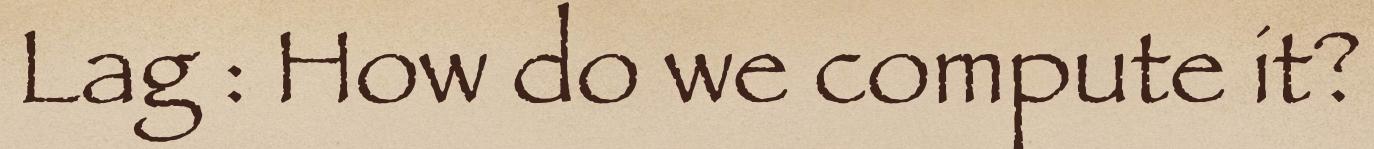


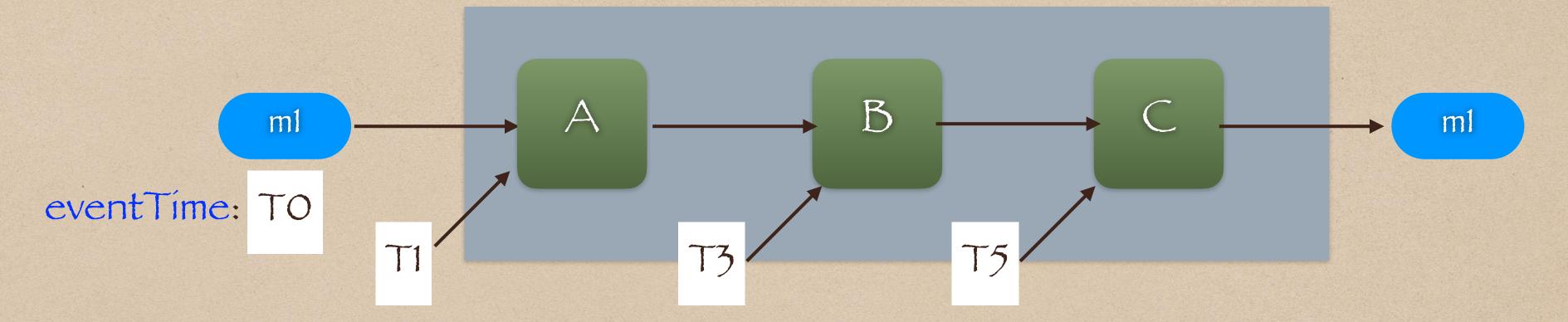
eventTime : the creation time of an event message
Lag can be calculated for any message m1 at any node N in the system as

lag(m1, N) = current_time(m1, N) - eventTime(m1)







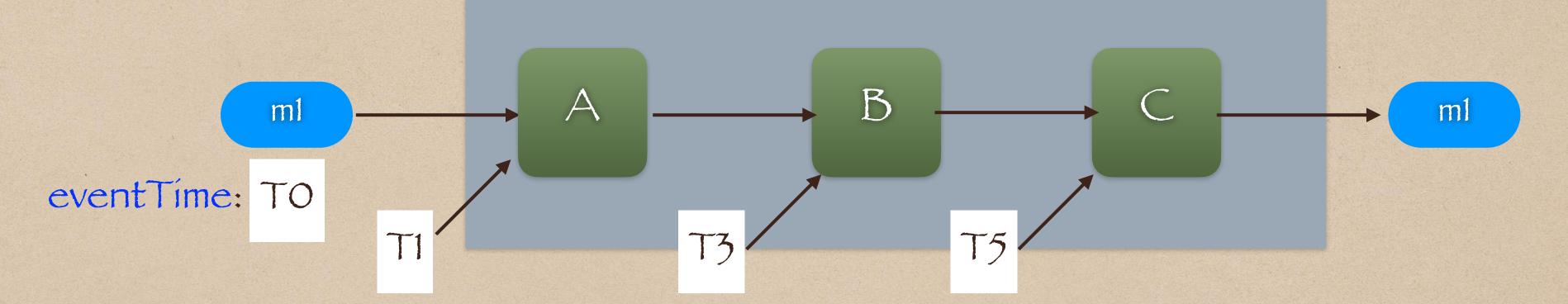


Arriva Lag (Lag-in): time message arrives - event Time



- A = T1 TO (e.g 1 ms)
- $B = T_3 TO(e.g.5 ms)$
- C = T5 T0 (e.g. 10 ms)





Arriva Lag (Lag-in): time message arrives - event Time

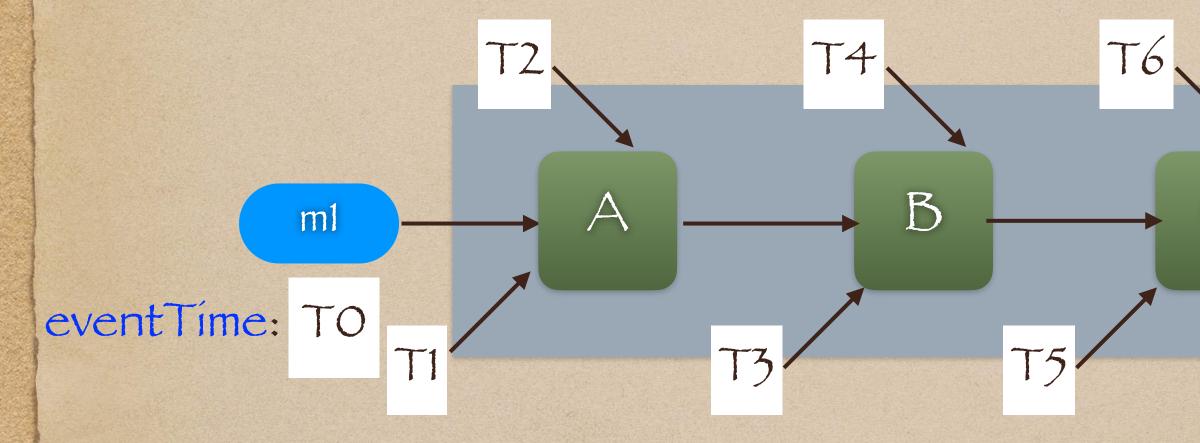


- A = T1 TO (e.g 1 ms)
- $B = T_3 TO(e.g.5 ms)$
- C = T5 T0 (e.g. 10 ms)

Cumulative Lag



Departure Lag (Lag-out): time message leaves - event Time



Arrival Lag (Lag-in): time message arrives - event Time

Lag-out @

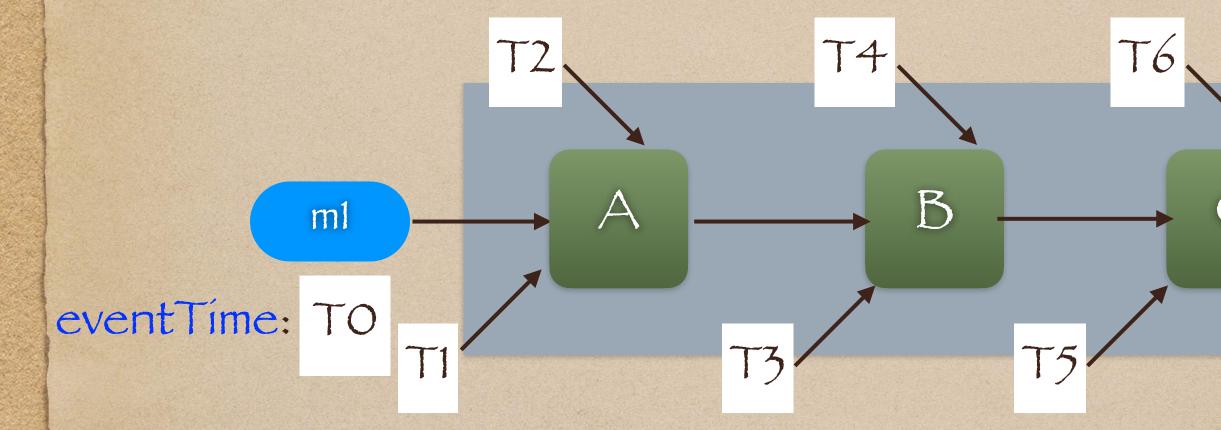
- A = T2 T0 (e.g. 3 ms)
- B = T4 T0 (e.g 8 ms)
- C = T6 T0 (e.g 12 ms)

Lag-in @

A = T1 - TO (e.g 1 ms)
B = T3 - TO (e.g 5 ms)
C = T5 - TO (e.g 10 ms)



Departure Lag (Lag-out): time message leaves - event Time



Arriva Lag (Lag-in): time message arrives - eventTime

E2E Lag is the total time a message spent in the system $\bullet C = T5 - T0$ (e.g. 10 ms)

Lag-out @

- A = T2 T0 (e.g 3 ms)
- B = T4 T0 (e.g 8 ms)
- C = T6 T0 (e.g 12 ms) E2E Lag

Lag-in@

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 While it is interesting to know the lag for a particular message m1, it is of little use since we typically deal with millions of messages



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Instead, we prefer statistics (e.g. P95) to capture population behavior



Lag: How do we compute it?

• Some useful Lag statistics are:

• E2E Lag (p95) : 95th percentile time of messages spent in the system

Lag_[inlout] (N, p95): P95 Lag_in or Lag_out at any Node N

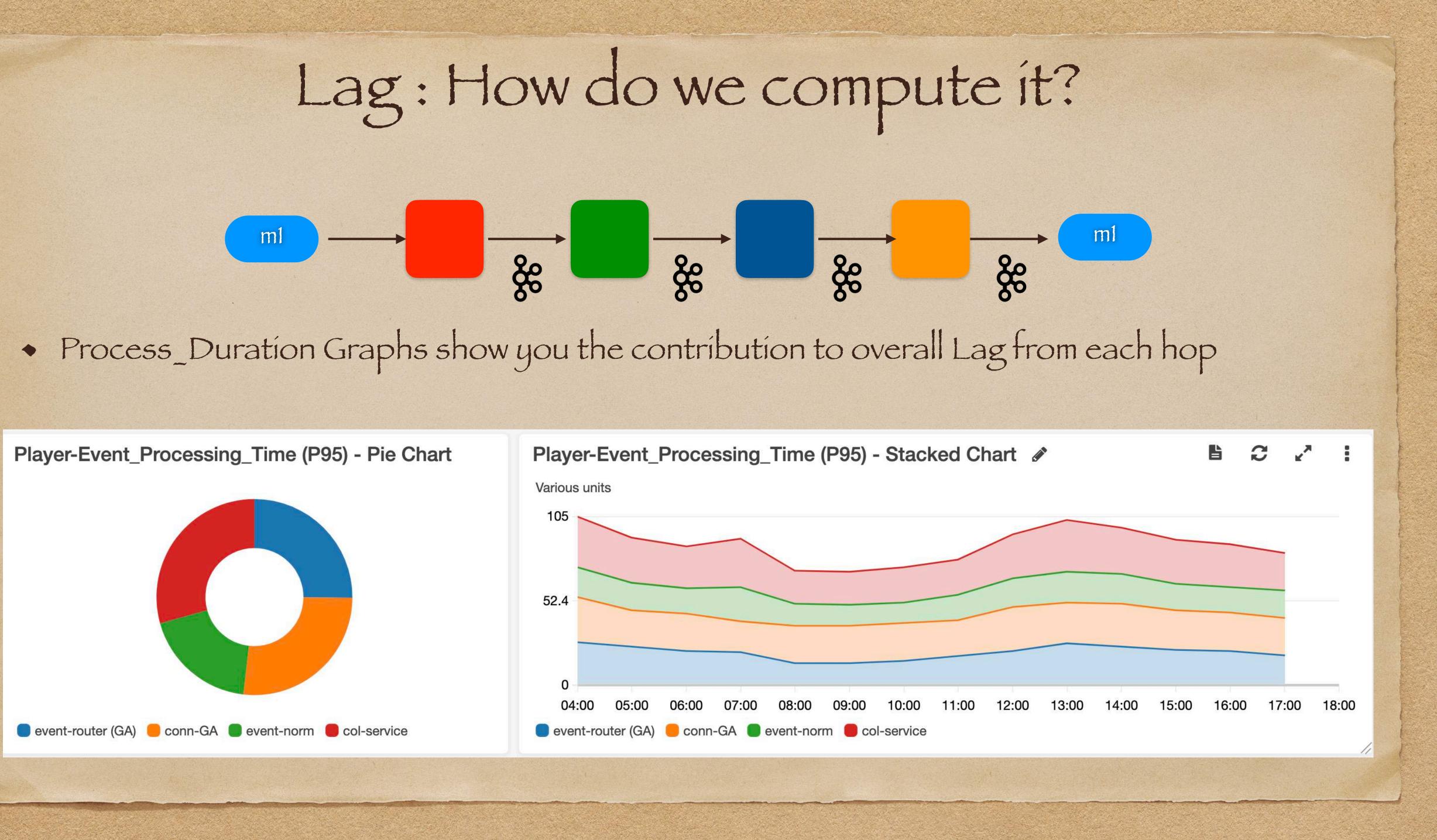


Lag: How do we compute it?

• Some useful Lag statistics are:

• E2E Lag (p95) : 95th percentile time of messages spent in the system Lag_[in|out](N, p95): P95 Lag_in or Lag_out at any Node N Process_Duration(N, p95) : Lag_out(N, p95) - Lag_in(N, p95)









• Loss is simply a measure of messages lost while transiting the system



Loss: What is it?



• Messages can be lost for various reasons, most of which we can mitigate!



Loss: What is it?

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• Loss is simply a measure of messages lost while transiting the system • Messages can be lost for various reasons, most of which we can mitigate! • The greater the loss, the lower the data quality

Loss: What is it?

- Hence, our goal is to minimize loss in order to deliver high quality insights



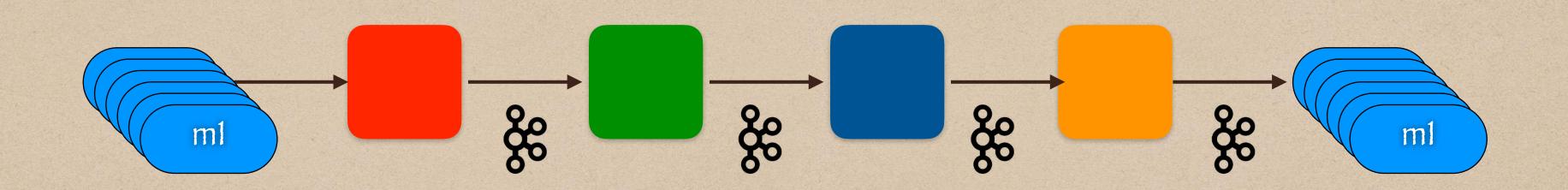
Loss: How do we compute it?



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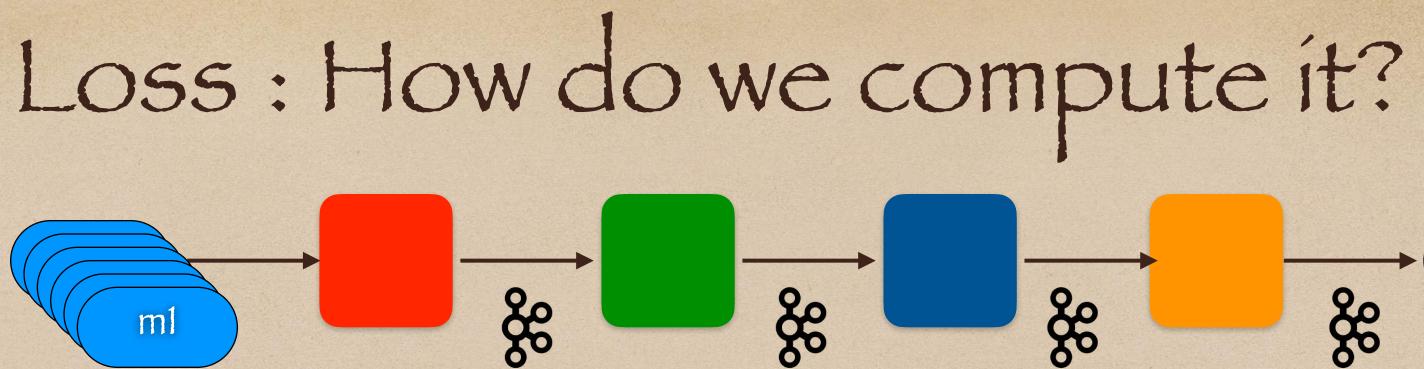
• Concepts : Loss

 Loss can be computed as the se points in the system

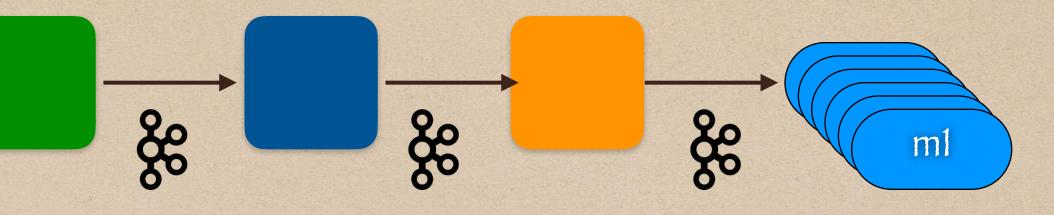


• Loss can be computed as the set difference of messages between any 2

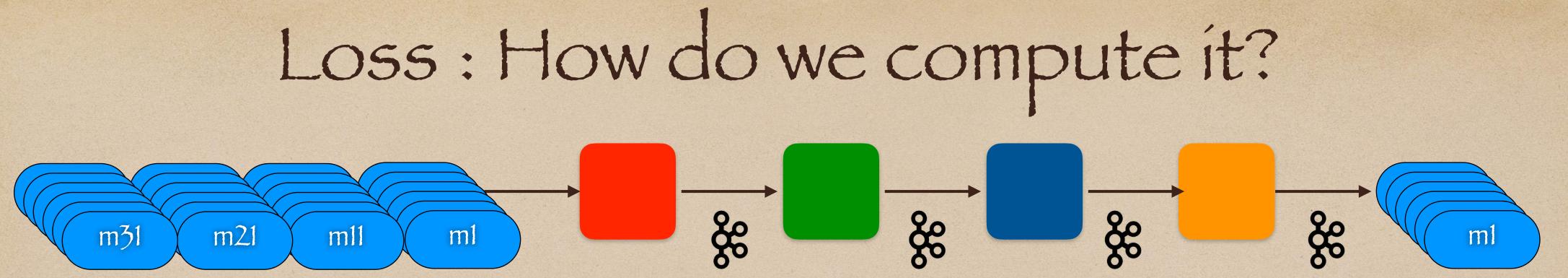




Message Id					E2E Loss E2E Loss
m1	1	1	1	1	
m2	1	1	1	1	
m3	1	0	0	0	
•••	• • •	• • •	• • •	• • •	
m10	1	1	0	0	Image: Section of the section of t
Count	10	9	7	5	
Per Node Loss(N)	0	1	2	2	5 50



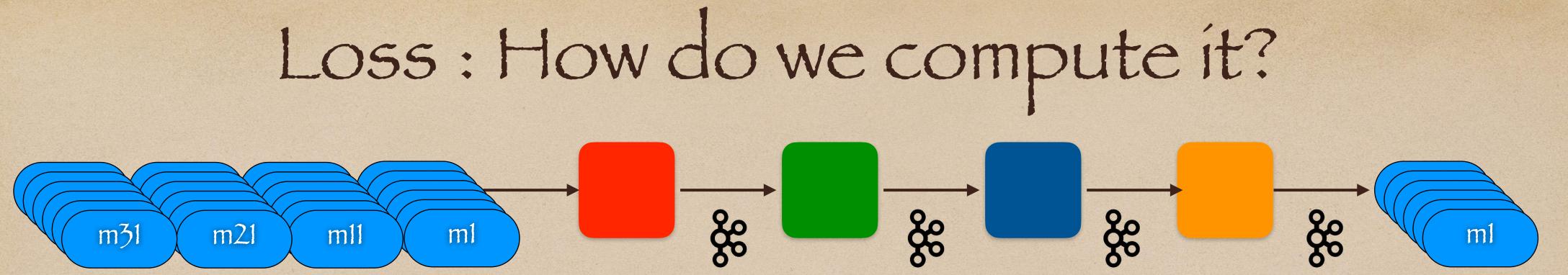




to count?

In a streaming data system, messages never stop flowing. So, how do we know when





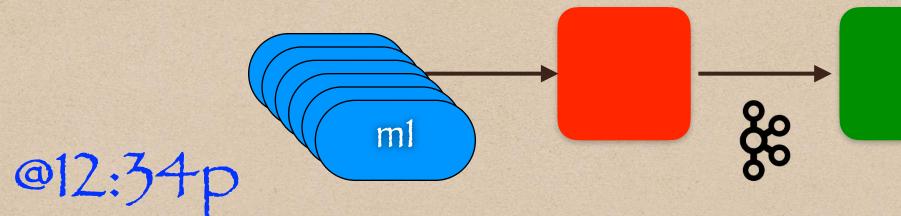
- to count?
- Solution

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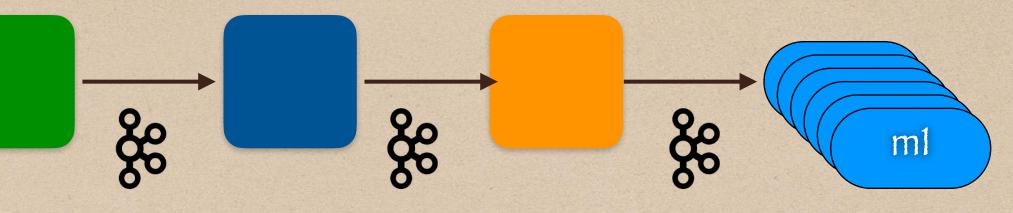
Allocate messages to 1-minute wide time buckets using message event Time



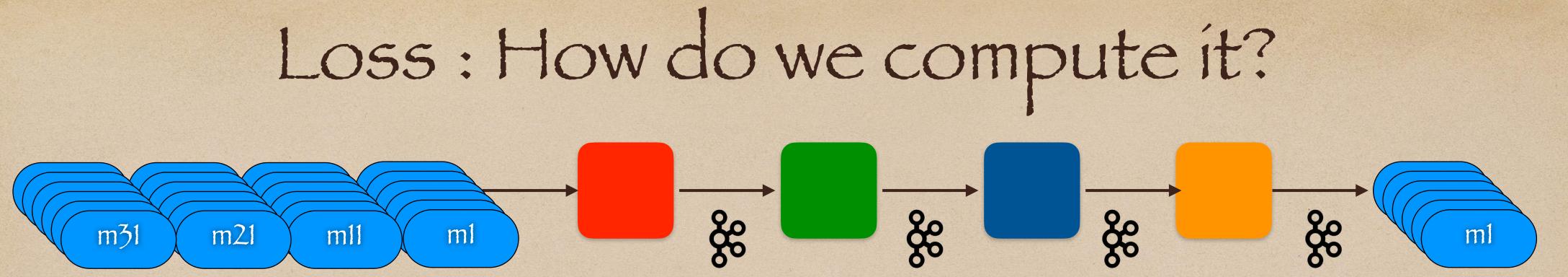
Loss: How do we compute it?



Message Id					E2E Loss	E2E Loss
m1	1	1	1	1		
m2	1	1	1	1		
m3	1	- - 	0	0		
•••	• • •	•••	•••	•••		
m10	1	1	0	0		
Count	10	9	7	5		
Per Node Loss(N)	0	1	2	2	5	50







- to count?
- Solution

 - Wait a few minutes for messages to transit, then compute loss
 - Raíse alarms íf loss occurs over a configured threshold (e.g. > 1%)

• In a streaming data system, messages never stop flowing. So, how do we know when

• Allocate messages to 1-minute wide time buckets using message event Time



Loss: How do we compute it?

 We now have a way to measure the reliability (via Loss metrics) and latency (via Lag metrics) of our system.

• But wait...





Performance (have we tuned our system for performance yet??)

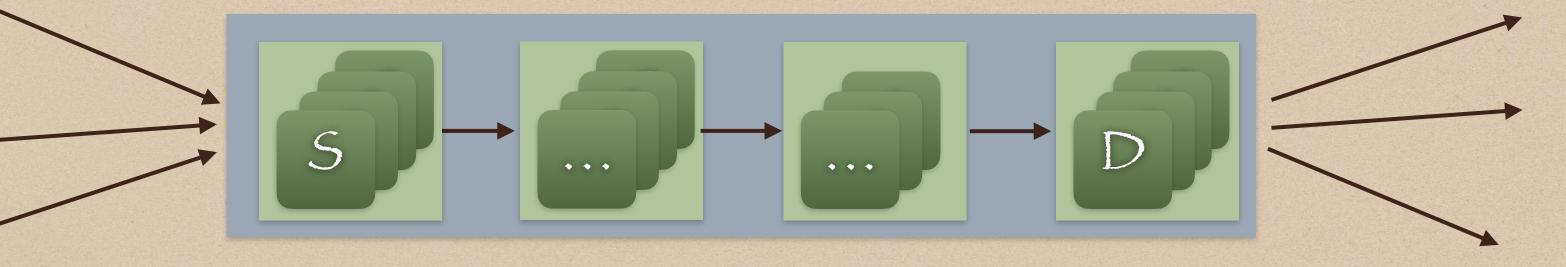








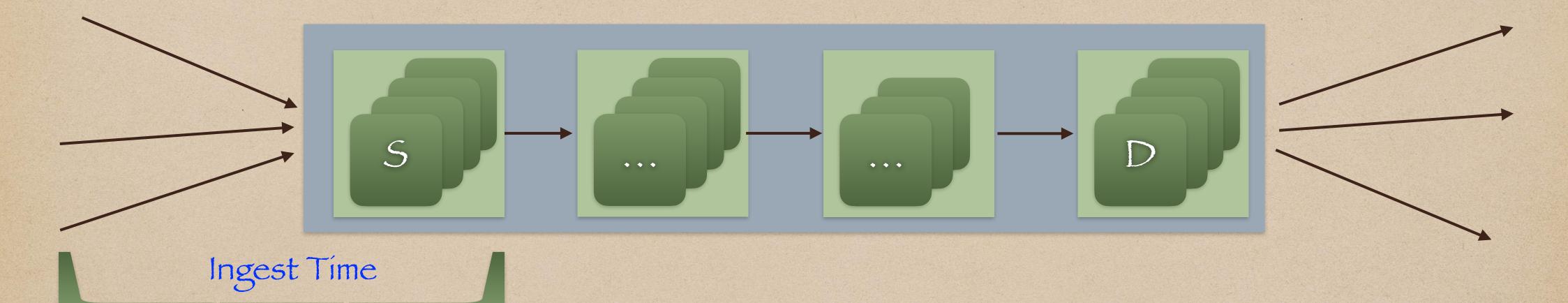
• Goal : Build a system that can deliver messages reliably from S to D with low latency



To understand streaming system performance, let's understand the components of E2E Lag



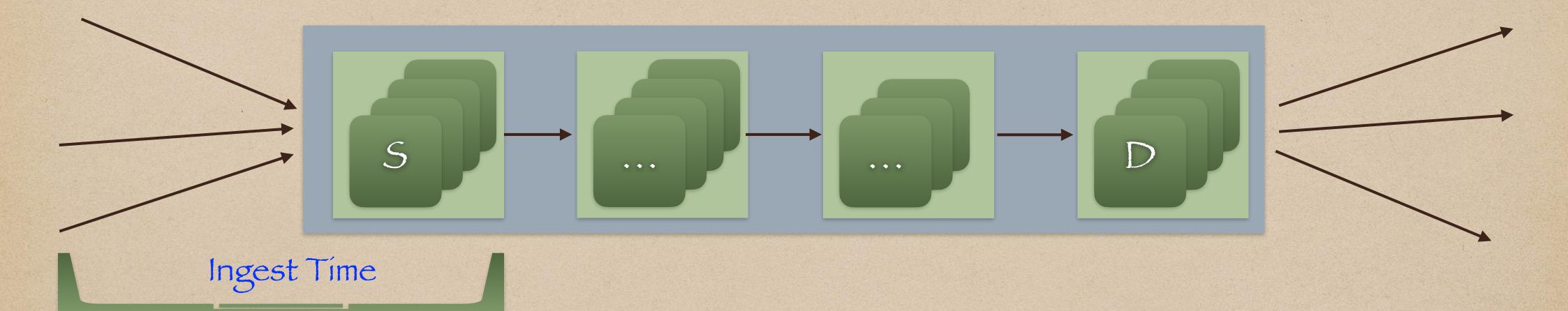




Ingest Time : Time from Last_Byte_In_of_Request to First_Byte_Out_of_Response







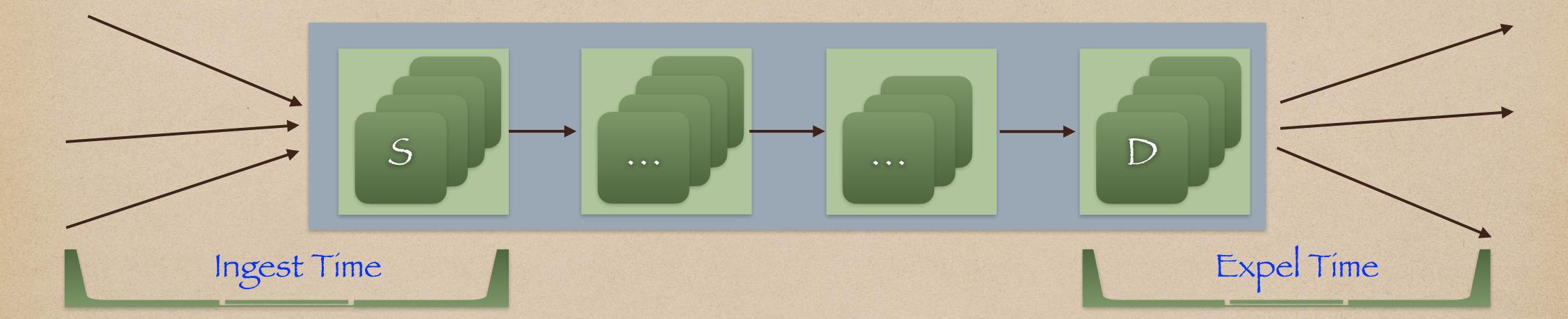
• This time includes overhead of reliably sending messages to Kafka

Performance

Ingest Time : Time from Last_Byte_In_of_Request to First_Byte_Out_of_Response



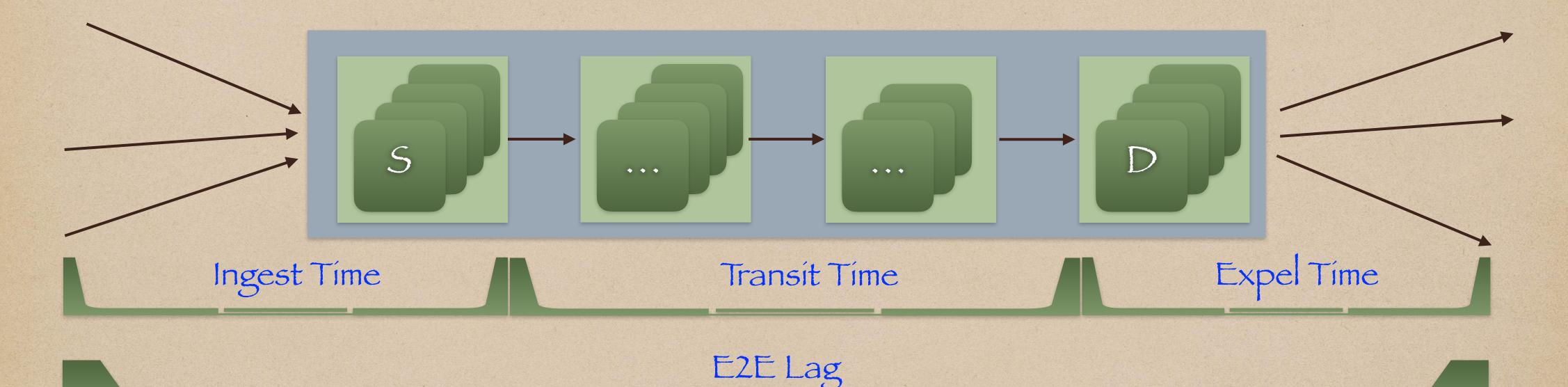




Expel Time : Time to process and egest a message at D.



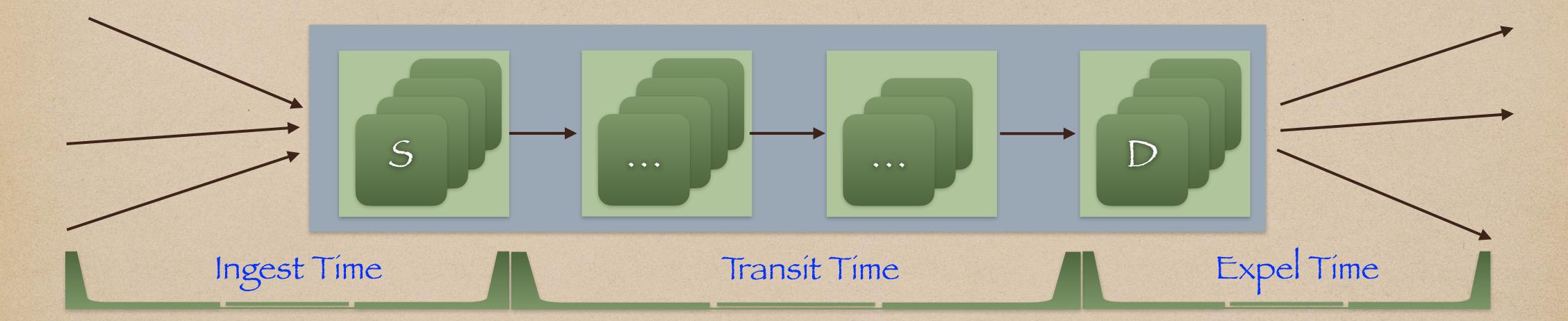




E2E Lag : Total time messages spend in the system from message ingest to expel!







Transit Time : Rest of the time spent in the data pipe (i.e. internal nodes)



Performance Penalties (Trading of Latency for Reliability)



Performance : Penalties

• In order to have stream reliability, we must sacrifice latency!

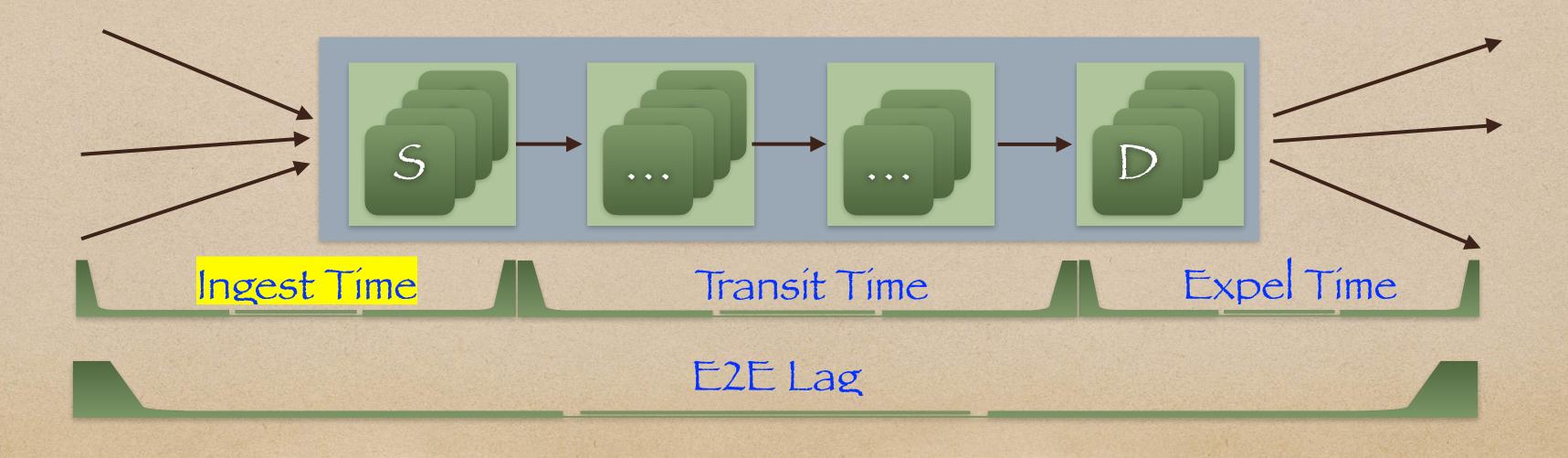
• How can we handle our performance penalties?





Challenge 1 : Ingest Penalty

- request



Performance

• In the name of reliability, S needs to call kProducer.flush() on every inbound API

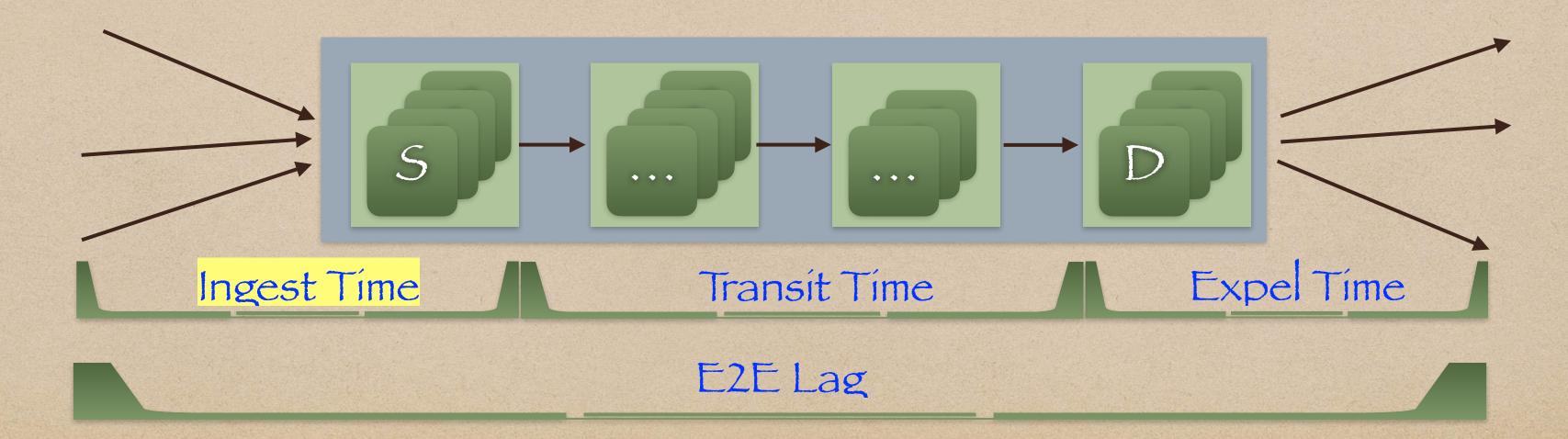
• S also needs to wait for 3 ACKS from Kafka before sending its API response





Challenge 1 : Ingest Penalty

- Approach : Amortization
 - ingest penalty



Performance

• Support Batch APIs (i.e. multiple messages per web request) to amortize the

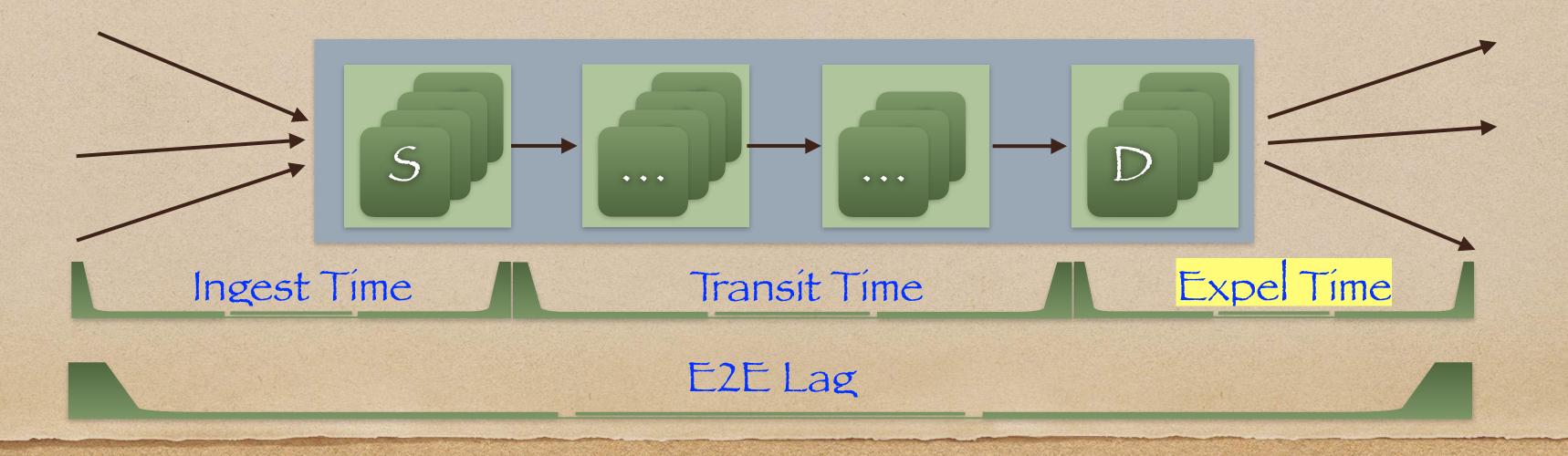




Challenge 2 : Expel Penalty

Observations

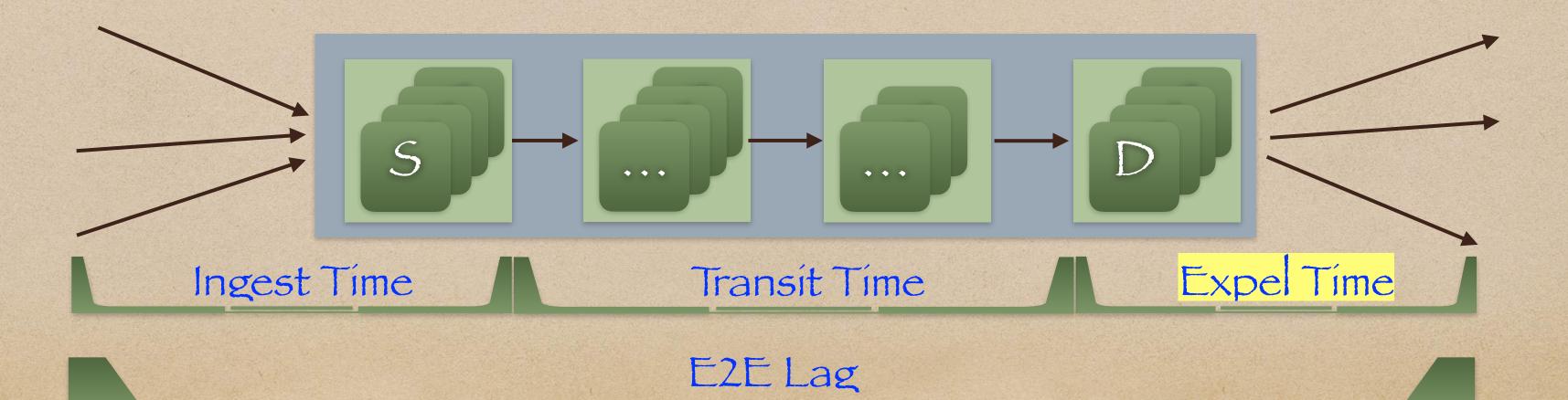
• Kafka is very fast — many orders of magnitude faster than HTTP RTTs • The majority of the expeltime is the HTTP RTT







Challenge 2 : Expel Penalty Approach : Amortization In each D node, add batch + parallelism









Challenge 3 : Retry Penalty (@ D)

Concepts

succeed given enough attempts

Performance

In order to run a zero-loss pipeline, we need to retry messages D that will



Performance

Challenge 3 : Retry Penalty (@ D)

Concepts

In order to run a zero-loss pipeline, we need to retry messages

D that will succeed given enough attempts
We call these Recoverable Failures



- Challenge 3 : Retry Penalty (@ D)
 - Concepts
 - In order to run a zero-loss pipeline, we need to retry messages @ D that will succeed given enough attempts
 We call these Recoverable Failures
 - In contrast, we should never retry a message that has 0 chance of success!
 - We call these Non-Recoverable Failures



- Challenge 3 : Retry Penalty (@ D)
 - Concepts
 - In order to run a zero-loss pipeline, we need to retry messages @ D that will succeed given enough attempts
 We call these Recoverable Failures
 - In contrast, we should never retry a message that has 0 chance of success!
 - We call these Non-Recoverable Failures
 - E.g. Any 4xx HTTP response code, except for 429 (Too Many Requests)





• Challenge 3 : Retry Penalty

- Approach
 - We pay a latency penalty on retry, so we need to smart about
 - What we retry Don't retry any non-recoverable failures

How we retry





Challenge 3 : Retry Penalty

- Approach
 - We pay a latency penalty on retry, so we need to smart about

 - How we retry One Idea : Tiered Retries

Performance

What we retry — Don't retry any non-recoverable failures



Local Retries

 Try to send message a configurable number of times @ D

Performance - Tiered Retries

Global Retries



Local Retries

- Try to send message a configurable number of times @ D
- If we exhaust local retries, D transfers the message to a Global Retrier

Performance - Tiered Retries

Global Retries



Local Retries

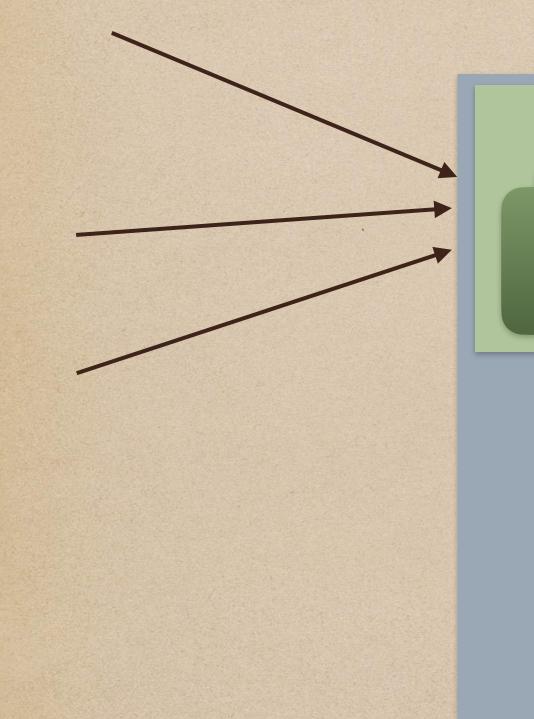
- Try to send message a configurable number of times @ D
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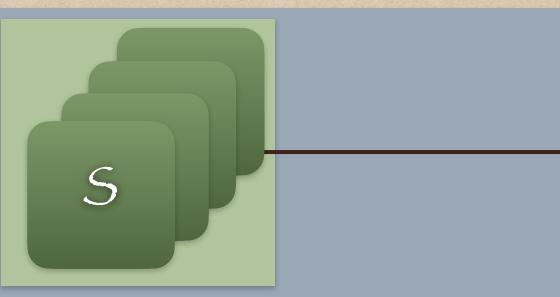
Performance - Tiered Retries

Global Retries

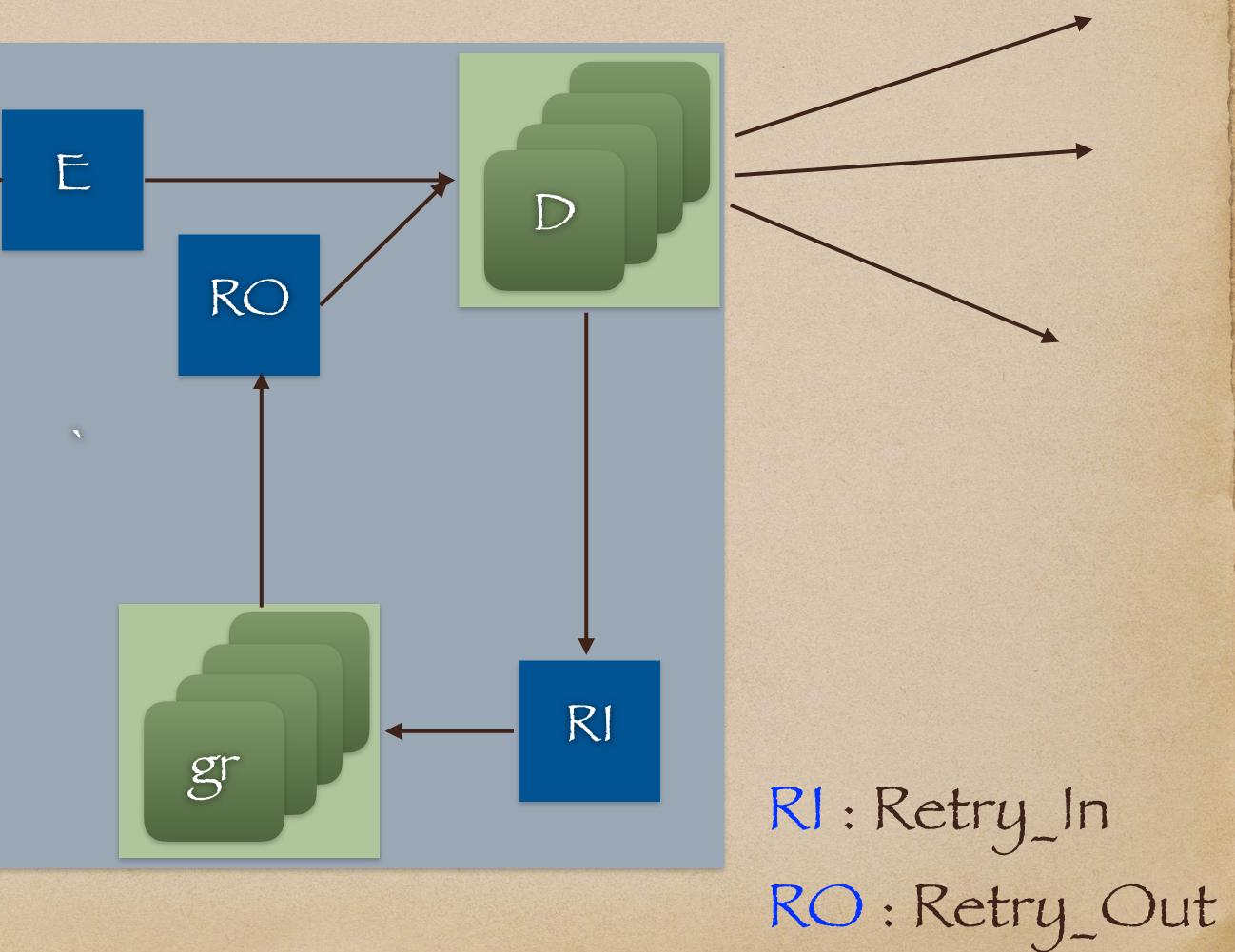
• The Global Retrier than retries the message over a longer span of time







Performance - 2 Tiered Retries







• At this point, we have a system that works well at low scale

Performance









Scalability

• First, Let's dispel a myth!



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 - There is no such thing as a system that can handle infinite scale

- Each system is traffic-rated
- The traffic rating comes from running load tests





Scalability

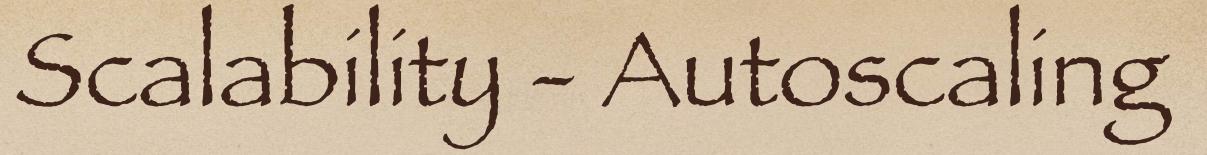
- First, Let's dispel a myth!
 - There is no such thing as a system that can handle infinite scale

- Each system is traffic-rated
- The traffic rating comes from running load tests

• We only achieve higher scale by iteratively running load tests & removing bottlenecks

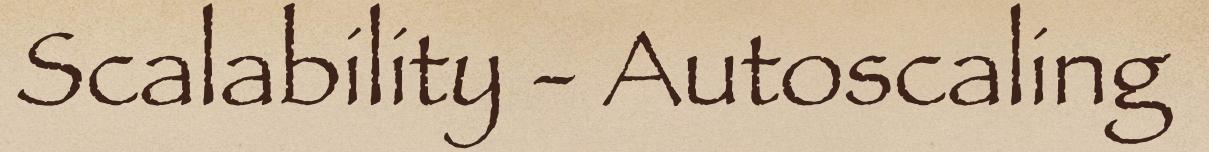


- Goal 1: Automatically scale out to maintain low latency (e.g. E2E Lag)
- Goal 2: Automatically scale in to minimize cost





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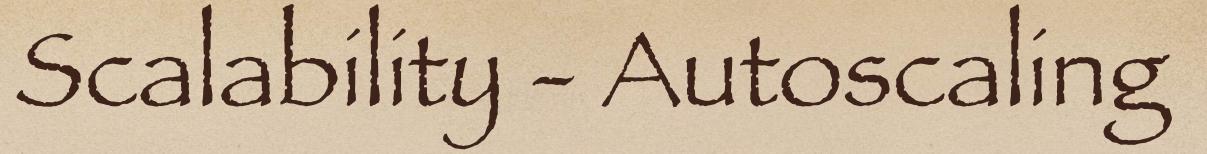




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Autoscaling Considerations

What can autoscale?



What can't autoscale?

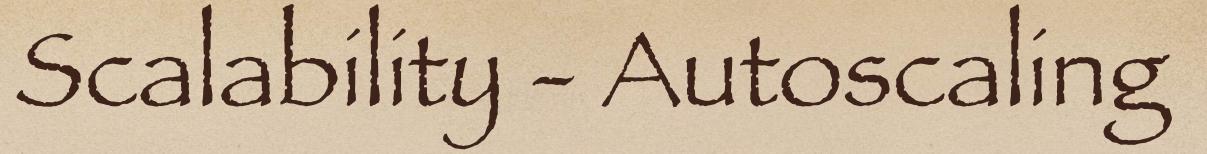




- Goal 1: Automatically scale out to maintain low latency (e.g. E2E Lag)
- Goal 2: Automatically scale in to minimize cost

Autoscaling Considerations

What can autoscale?



What can't autoscale?





The most important part of autoscaling is picking the right metric to trigger autoscaling actions

Scalability - Autoscaling EC2



Scalability - Autoscaling EC2

Píck a metríc that

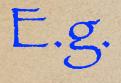
- Preserves low latency
- Goes up as traffic increases
- Goes down as the microservice scales out

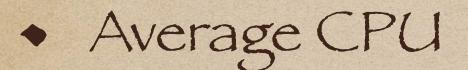


Scalability - Autoscaling EC2

Píck a metríc that

- Preserves low latency
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Scalability - Autoscaling EC2

Píck a metríc that

E.g.

- Preserves low latency
- Goes up as traffic increases
- Goes down as the microservice scales out
 - What to be wary of
- Average CPU

Any locks/code synchronization & IO Waits

• Otherwise ... As traffic increases, CPU will plateau, autoscale-out will stop, and latency (i.e. E2E Lag) will increase





We now have a system with the Non-functional Requirements (NFRs) that we desire!

What Next?





What if we want to handle

- Dífferent types of messages
- More complex processing (i.e. more processing stages)
- More complex stream topologíes (e.g. 1-1, 1-many, many-many)

What Next?

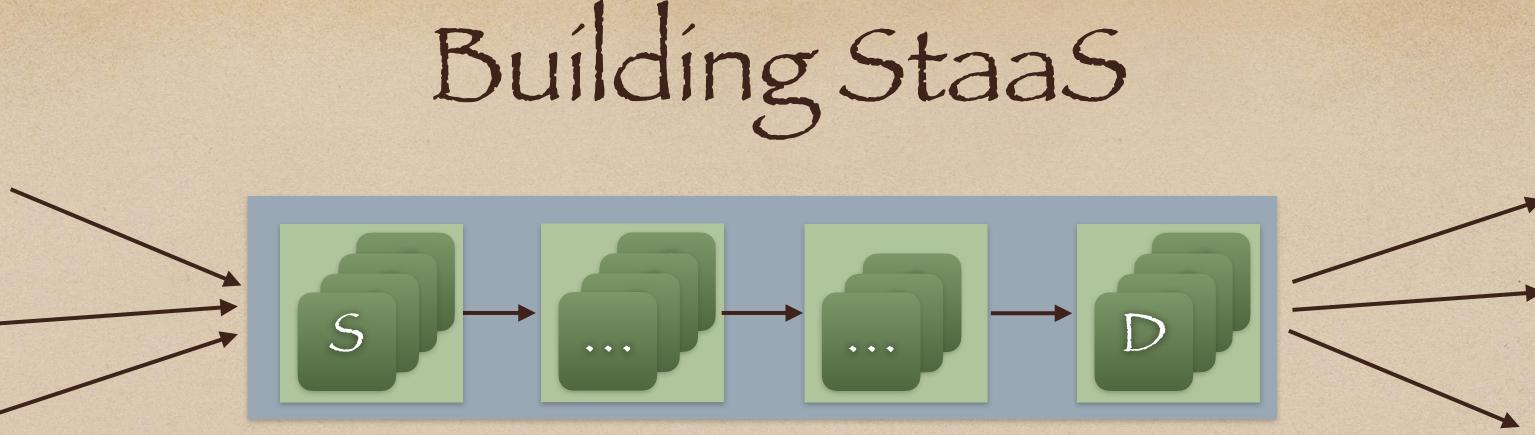


It will take a lot of work to rebuild our data pipe for each variation of customers' needs!

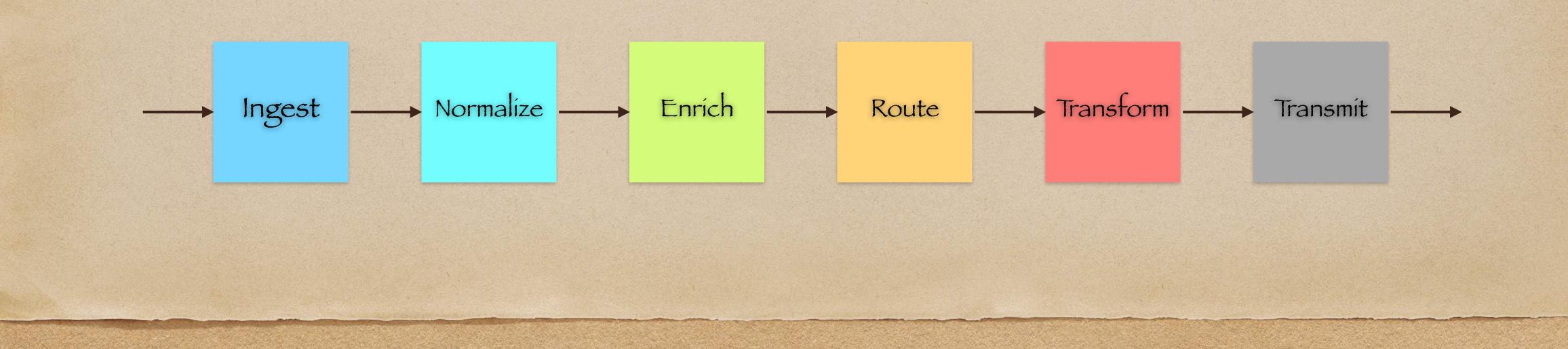
What we need to do is build a more generic Streams-as-a-Service (STaaS) platform!

What Next?



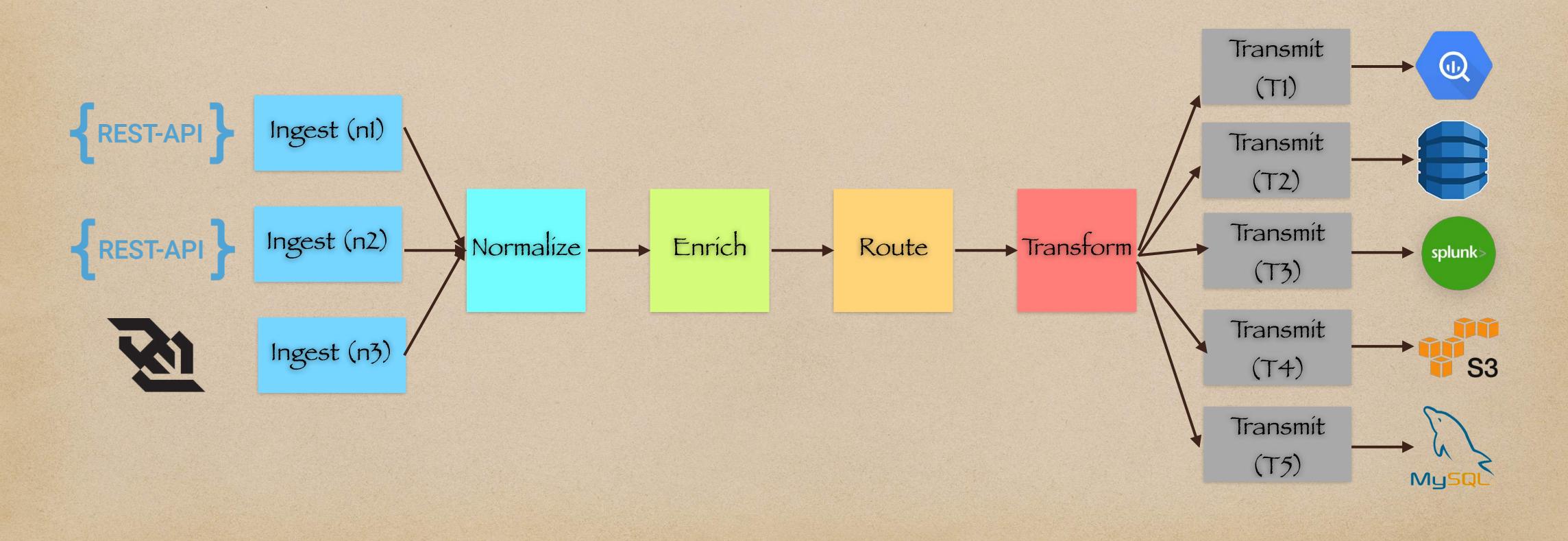


• Firstly, let's make our pipeline a bit more realistic by adding more processing stages



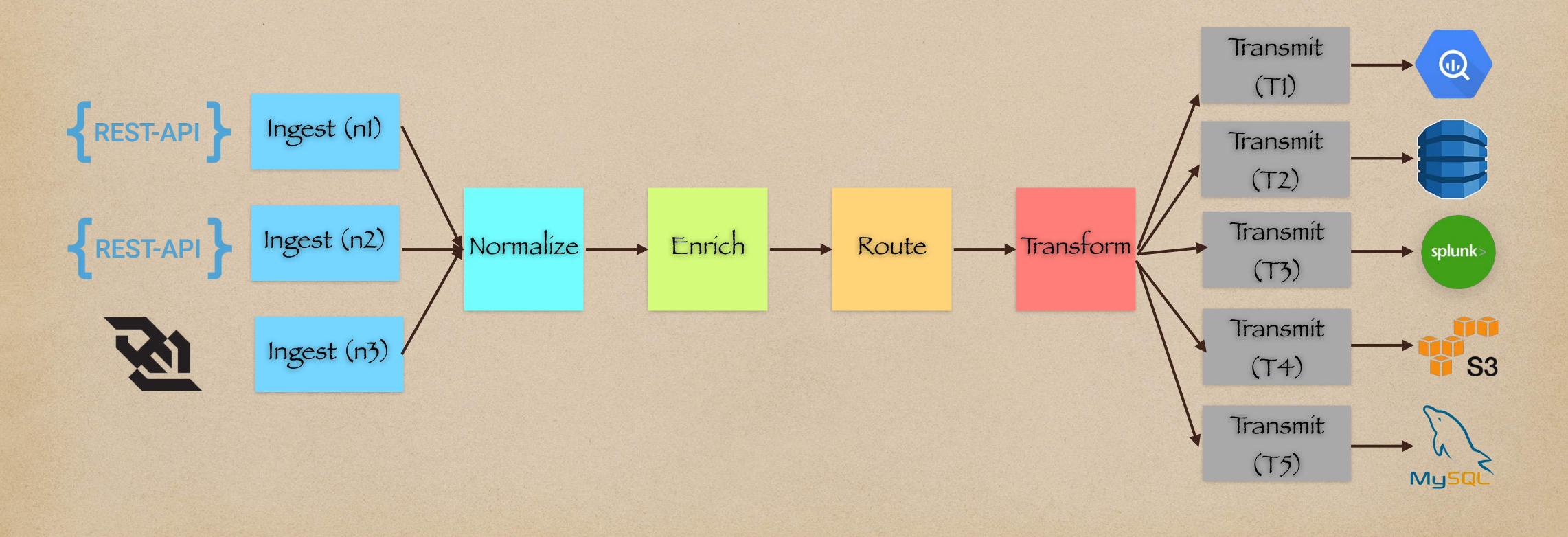


And by handling more complex topologies (e.g. many-to-many)





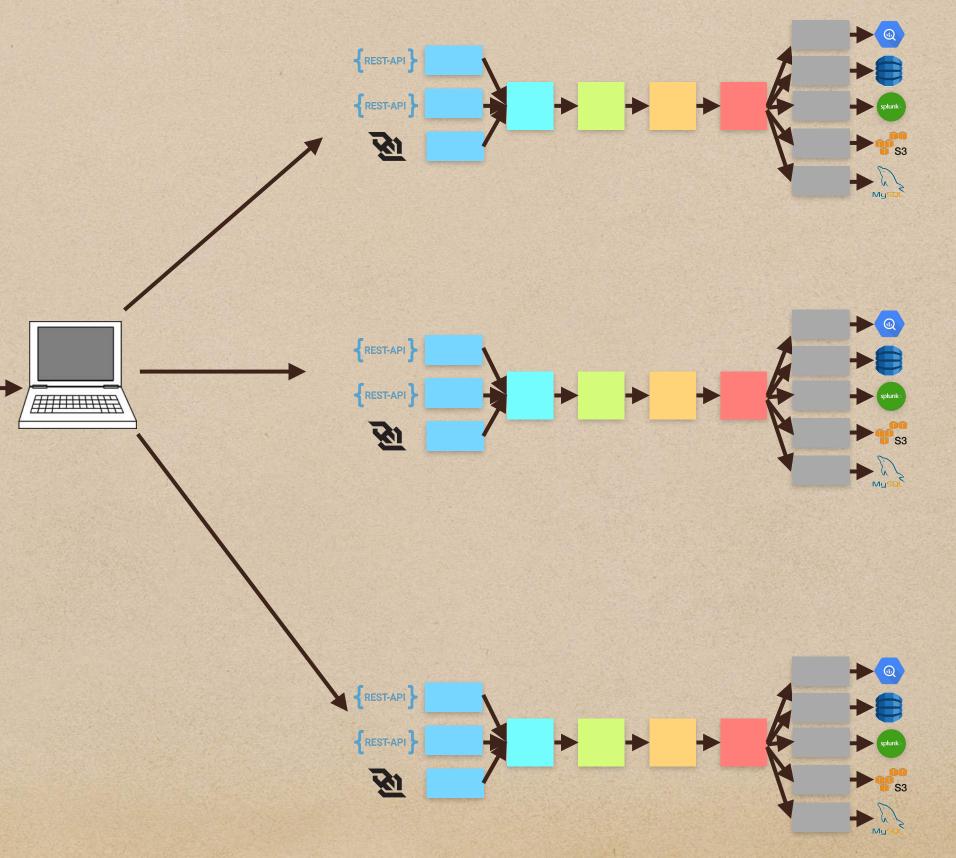
This our data plane — it send messages from multiple sources to multiple destinations





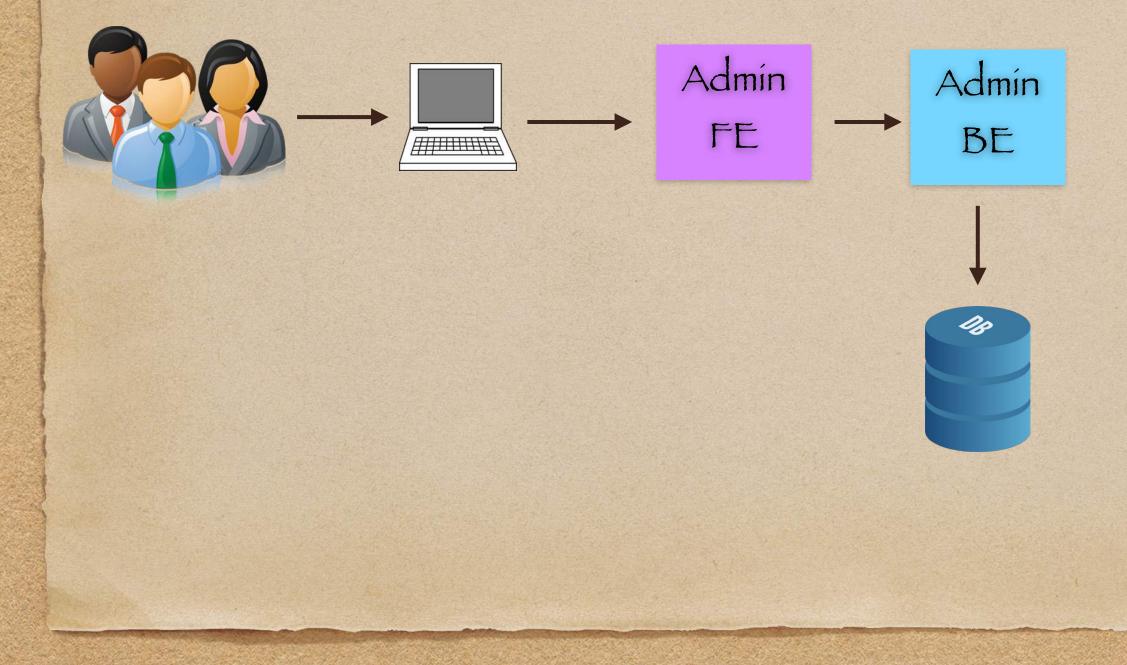
But, we also want to allow users the ability to define their own data pipes in this data plane

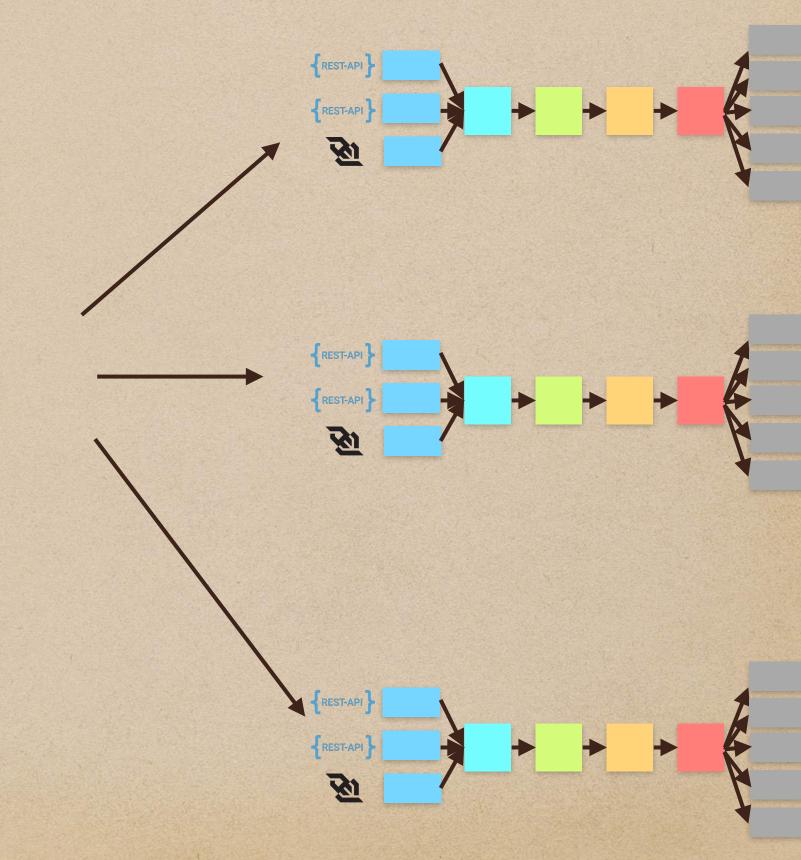






Hence, we need a management plane to capture the intent of the users

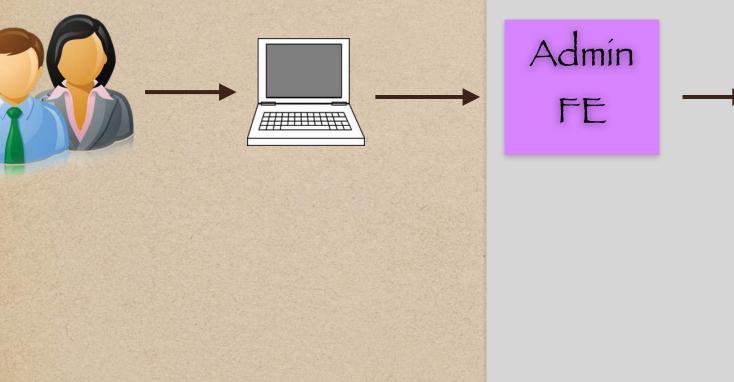




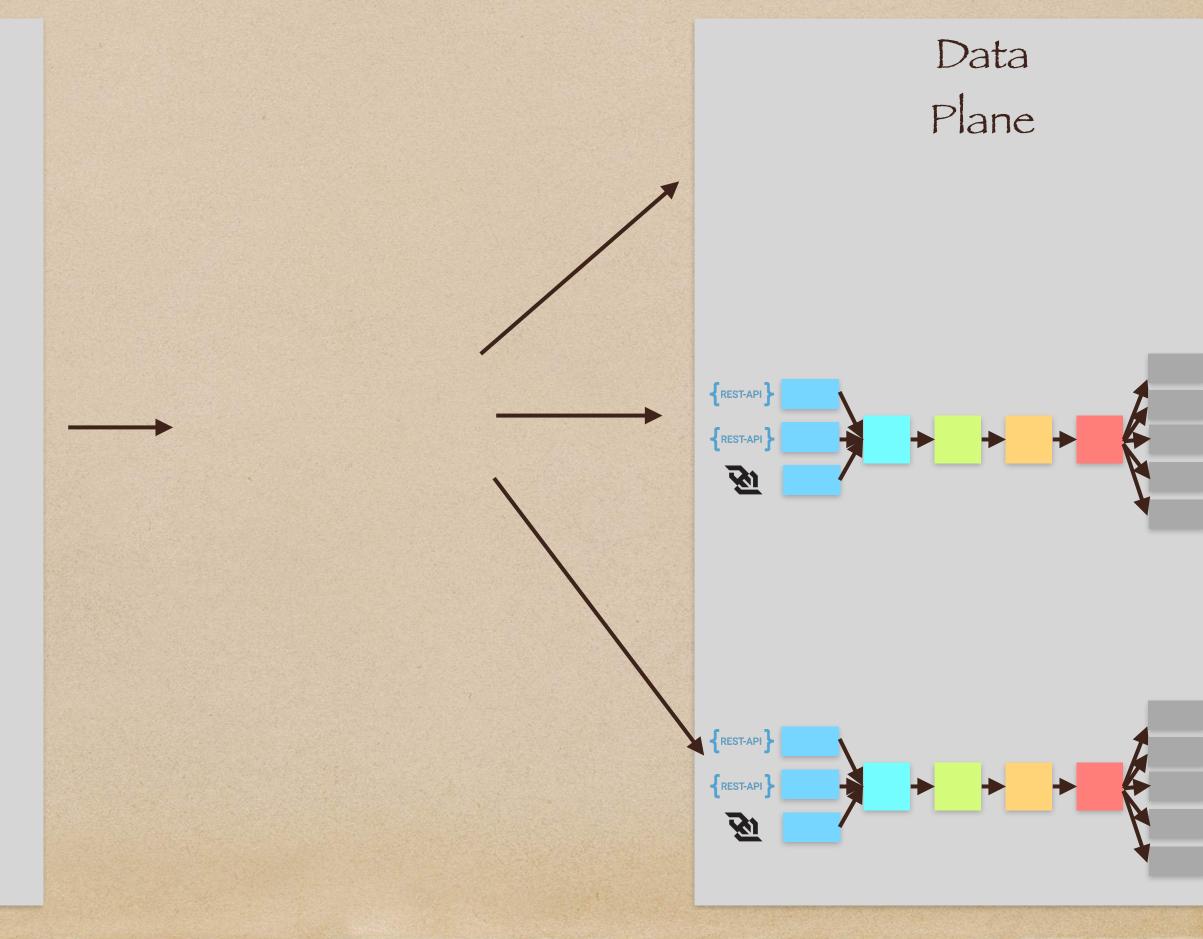


We now have 2 planes: a Management Plane & a Data Plane





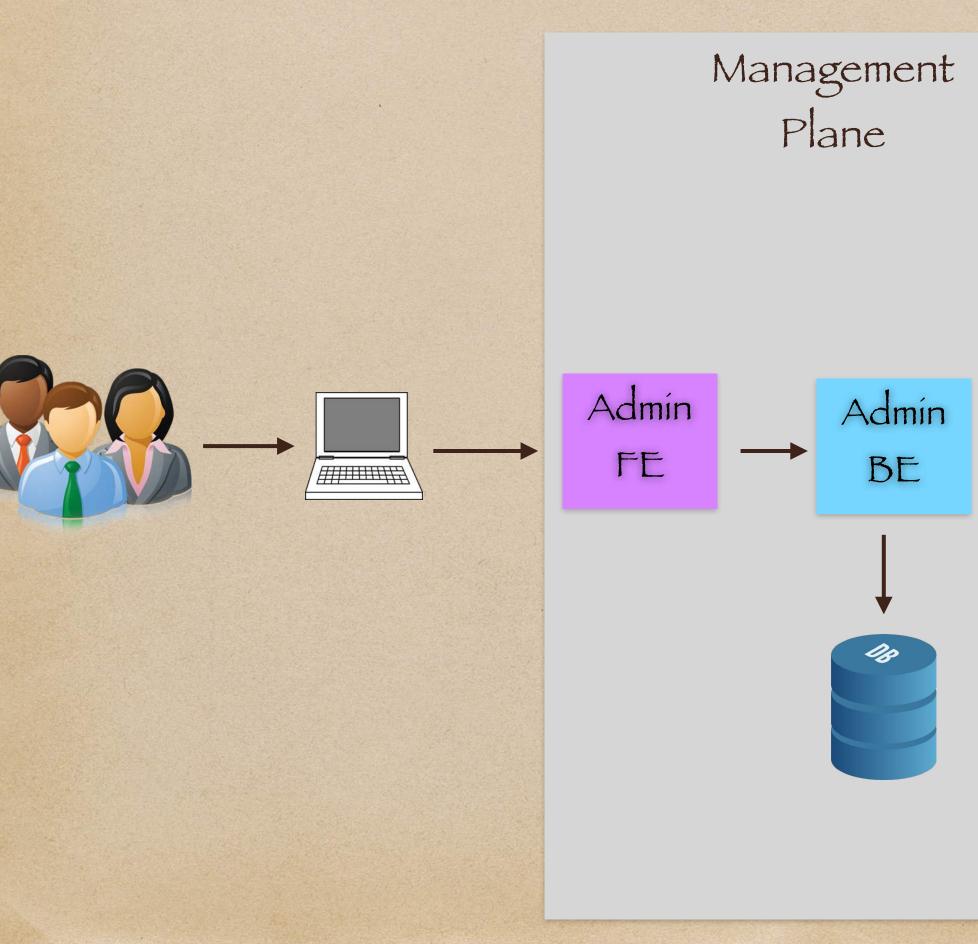


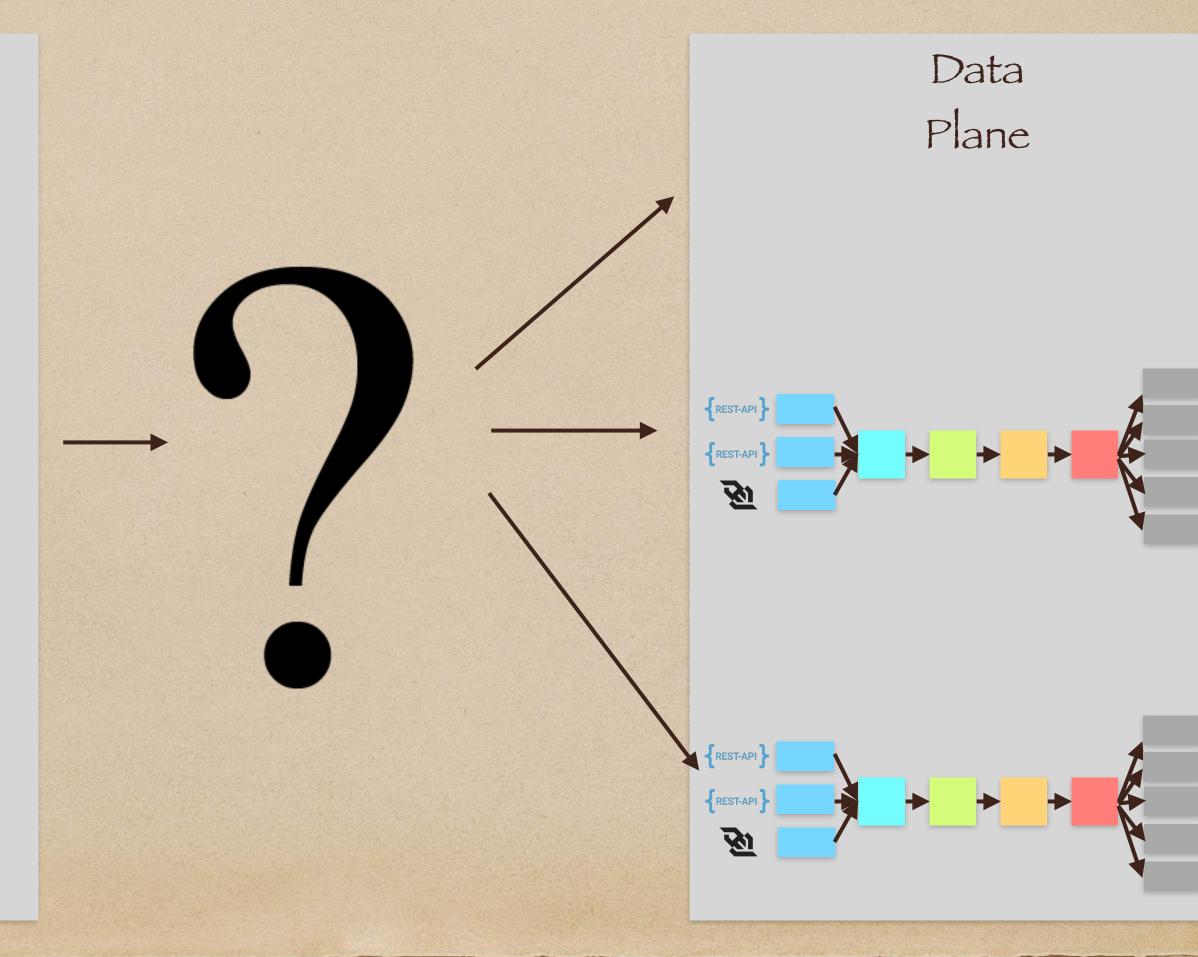






Hence, we need at least 2 planes : Management & Data

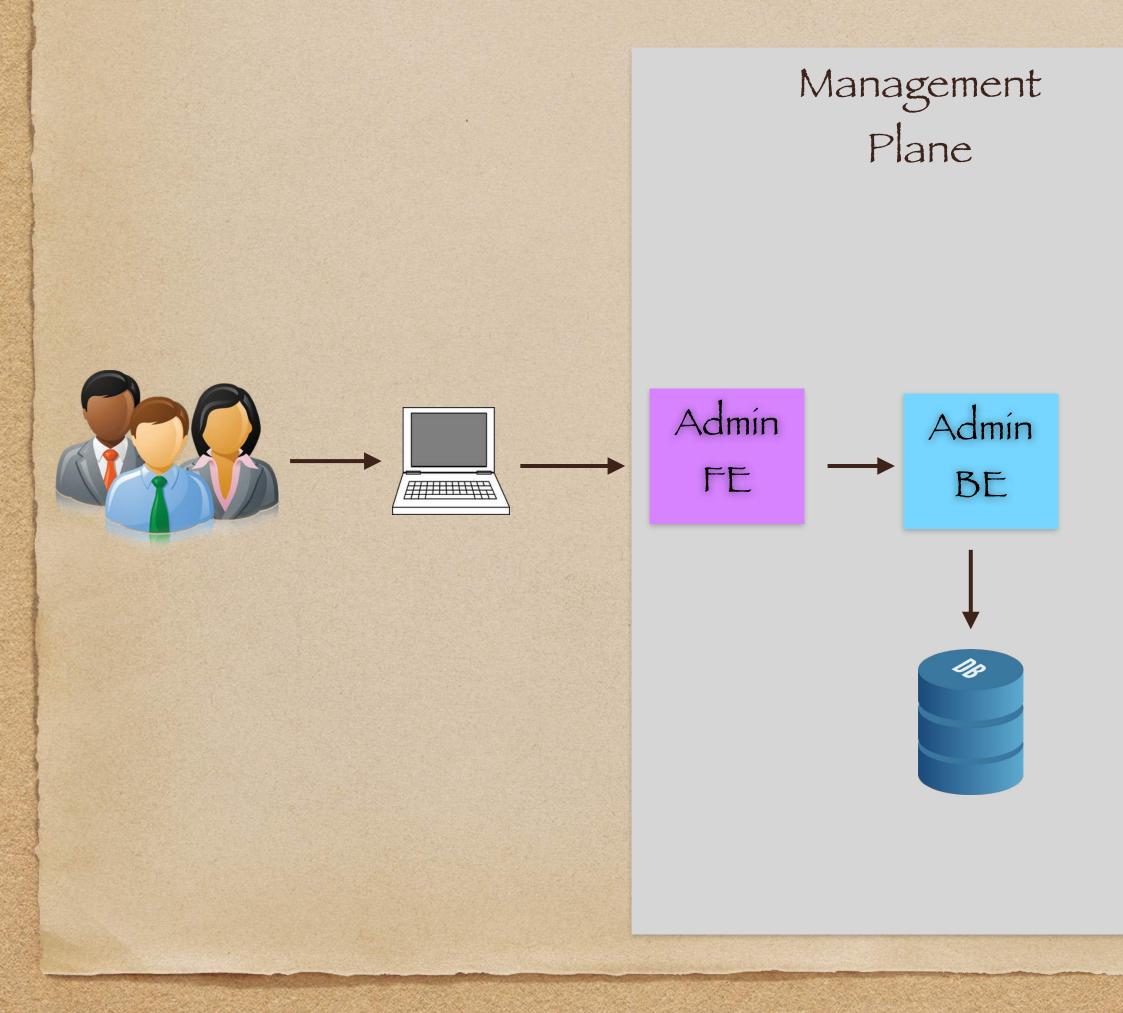


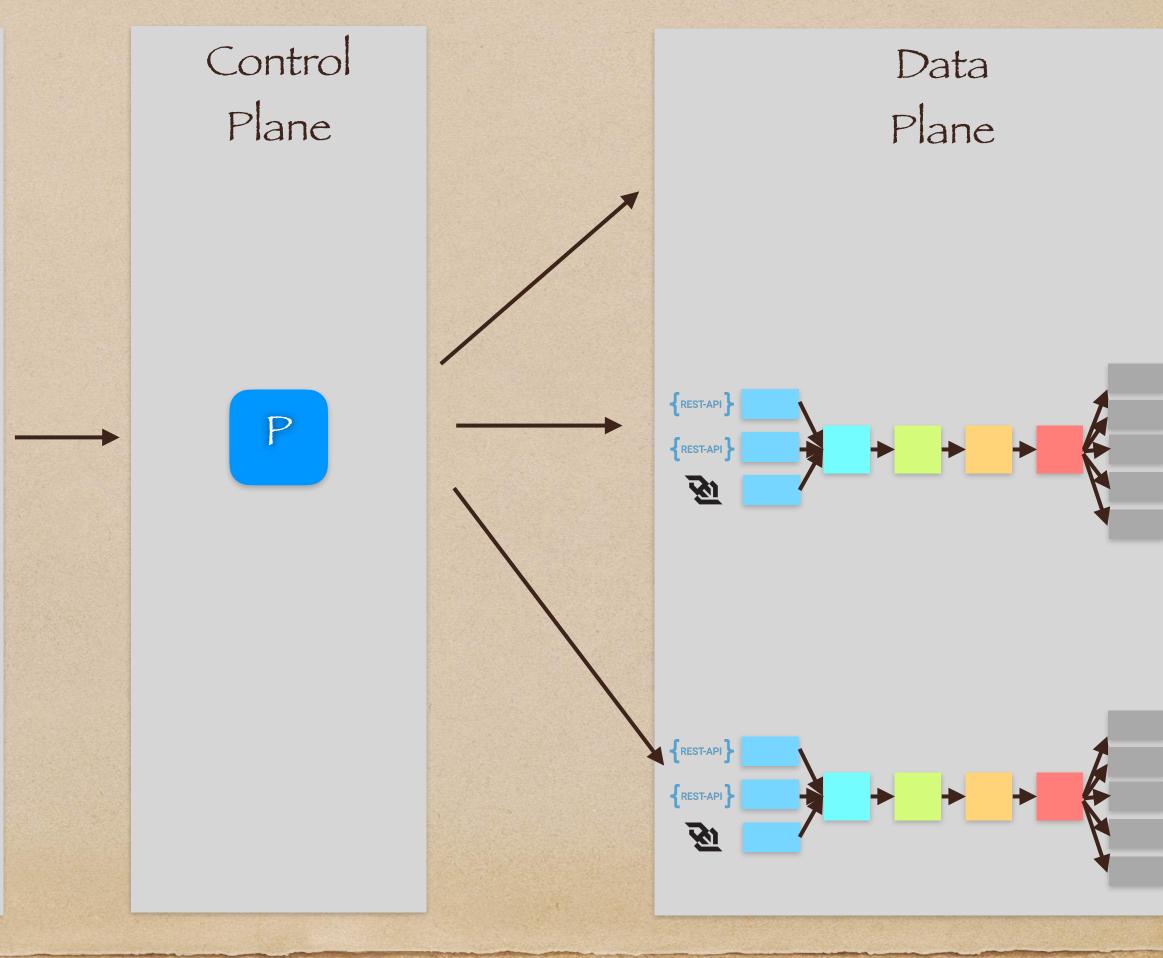






We also need a Provisioner(P)

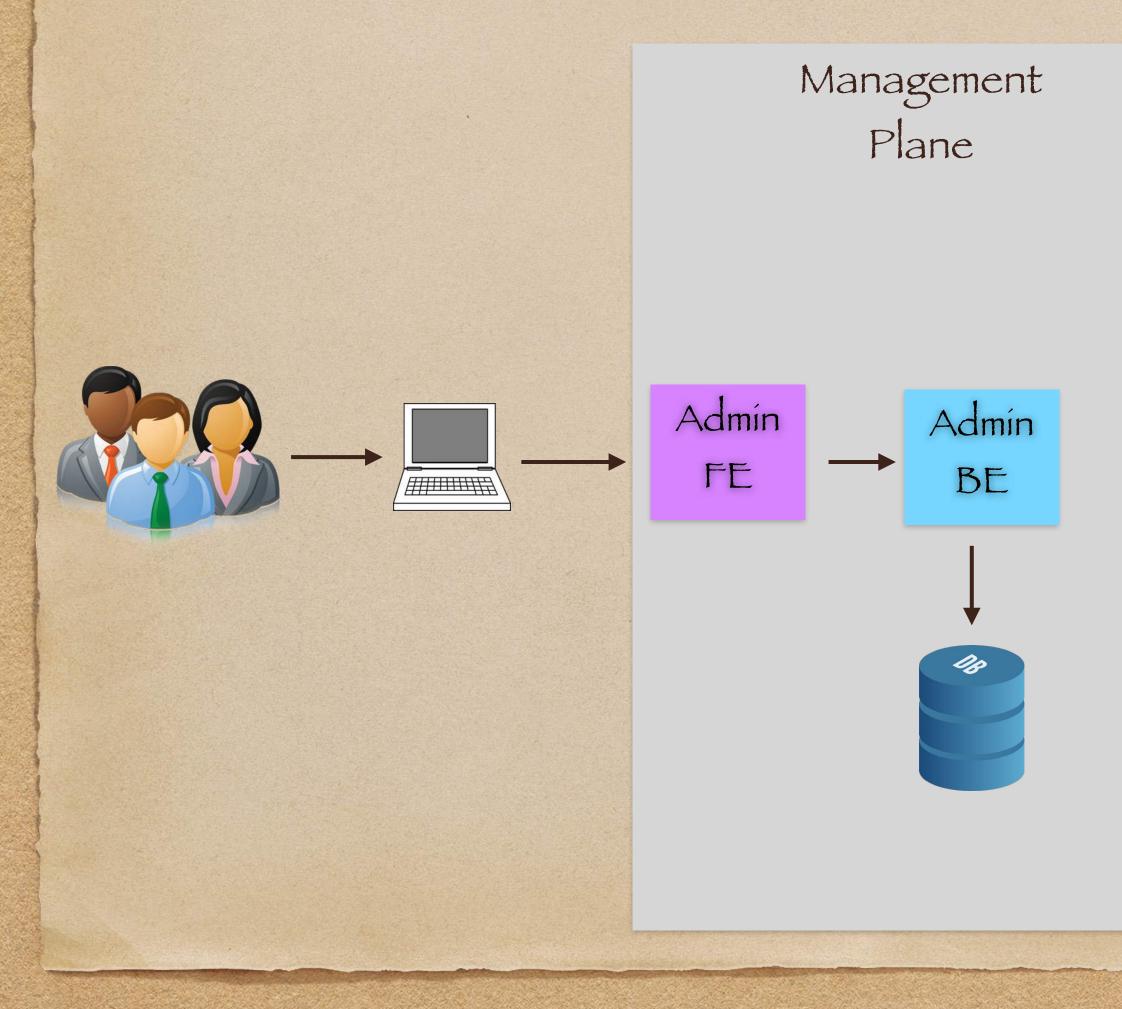


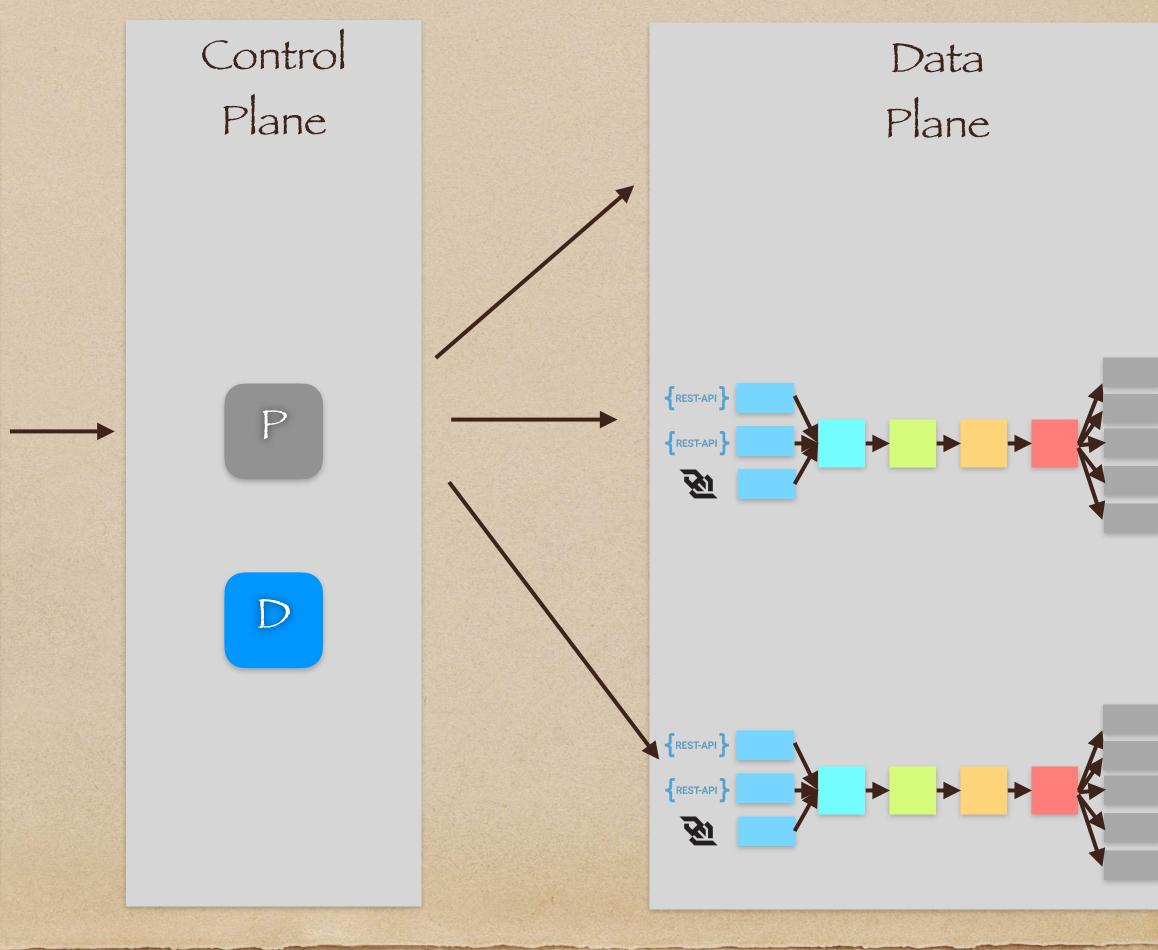






We also need a Deployer(D)

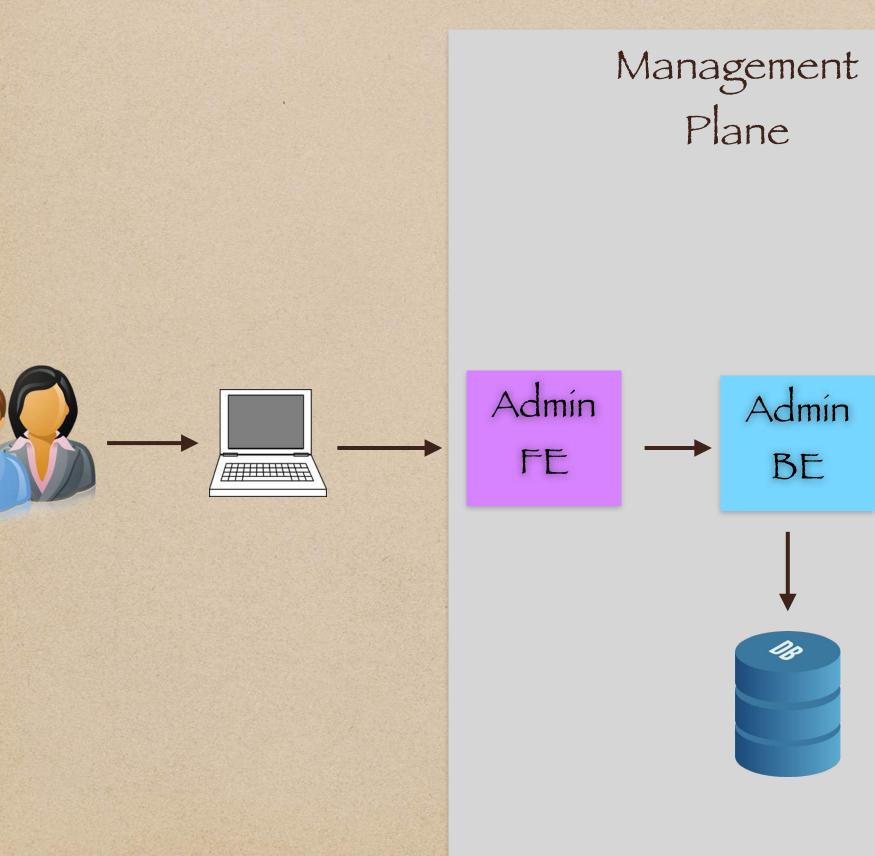


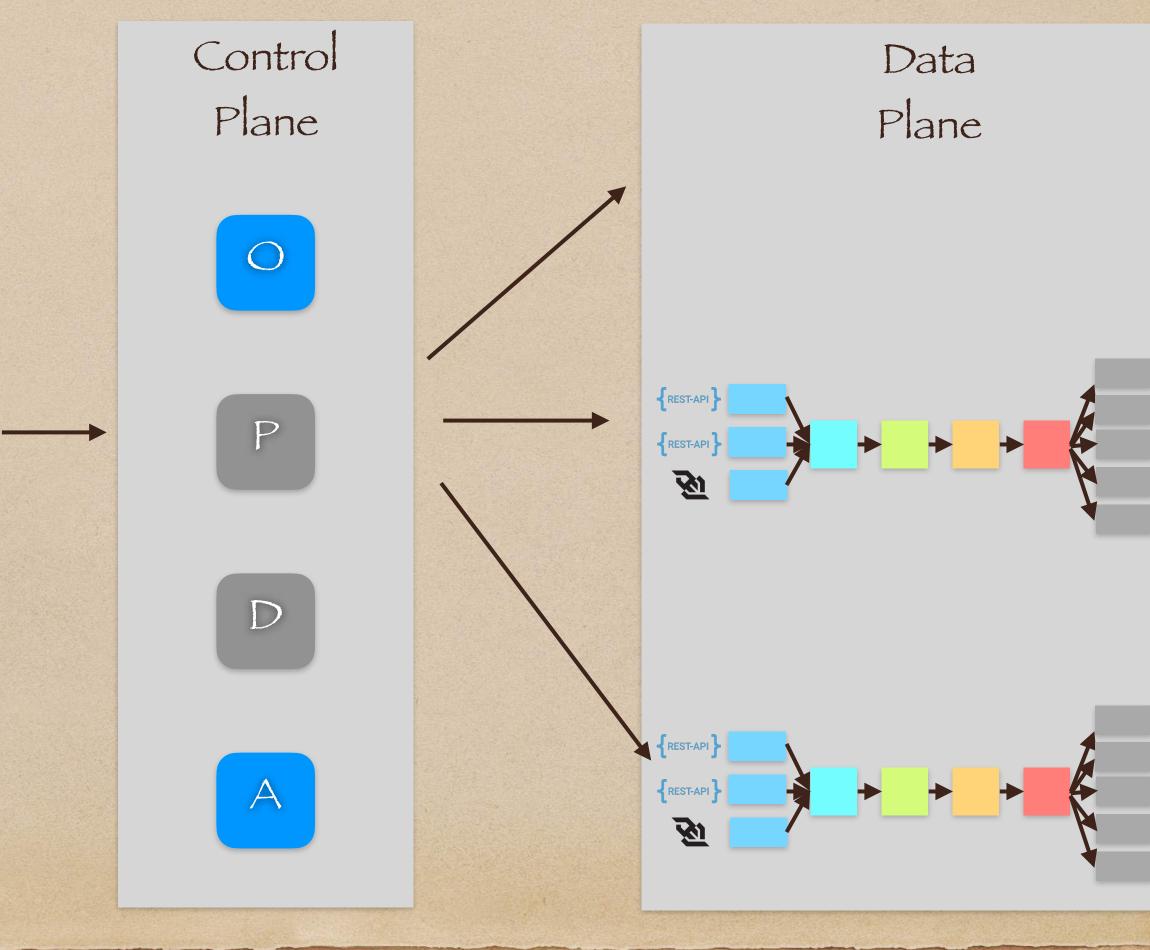






Finally, we can add systems to promote health and stability: Observer(O) & Autoscaler (A)



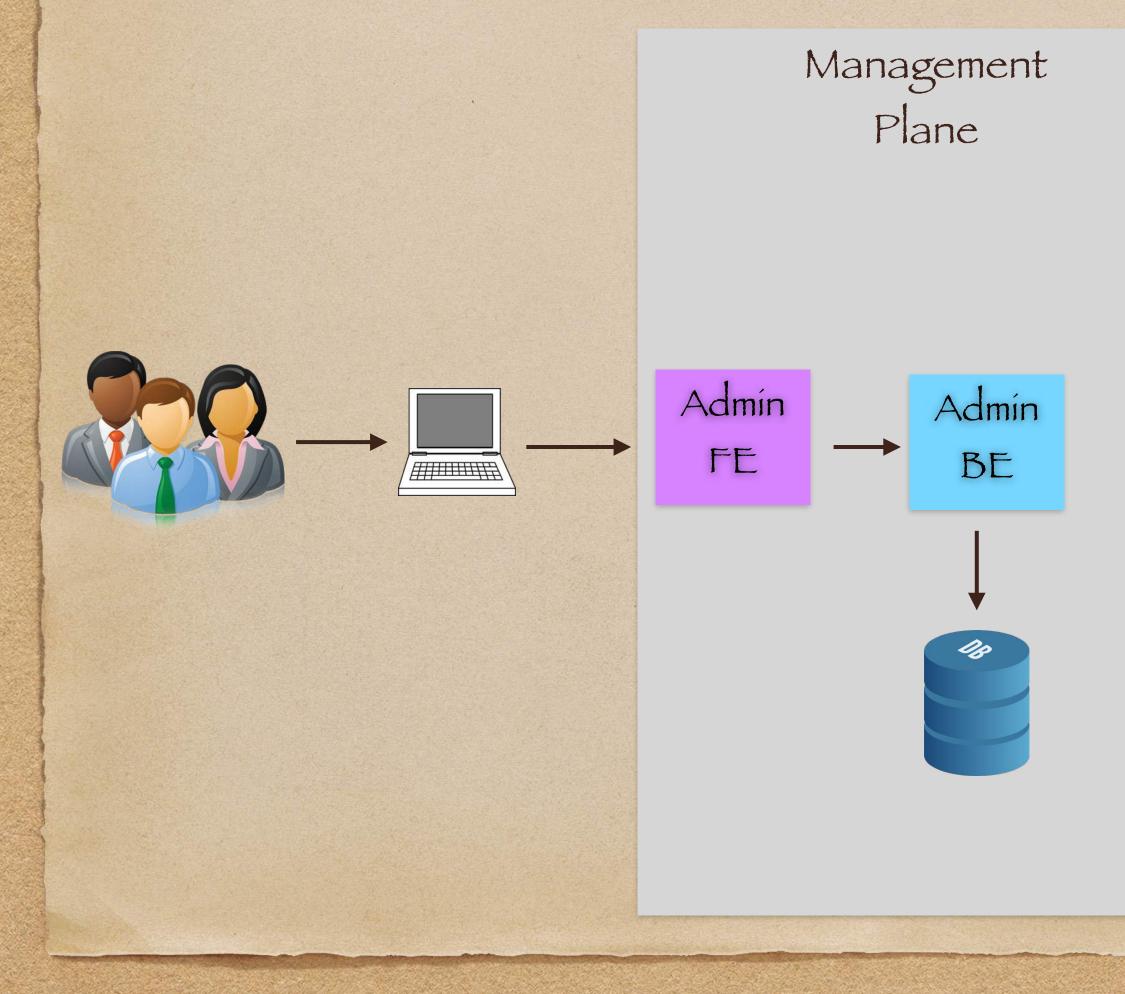


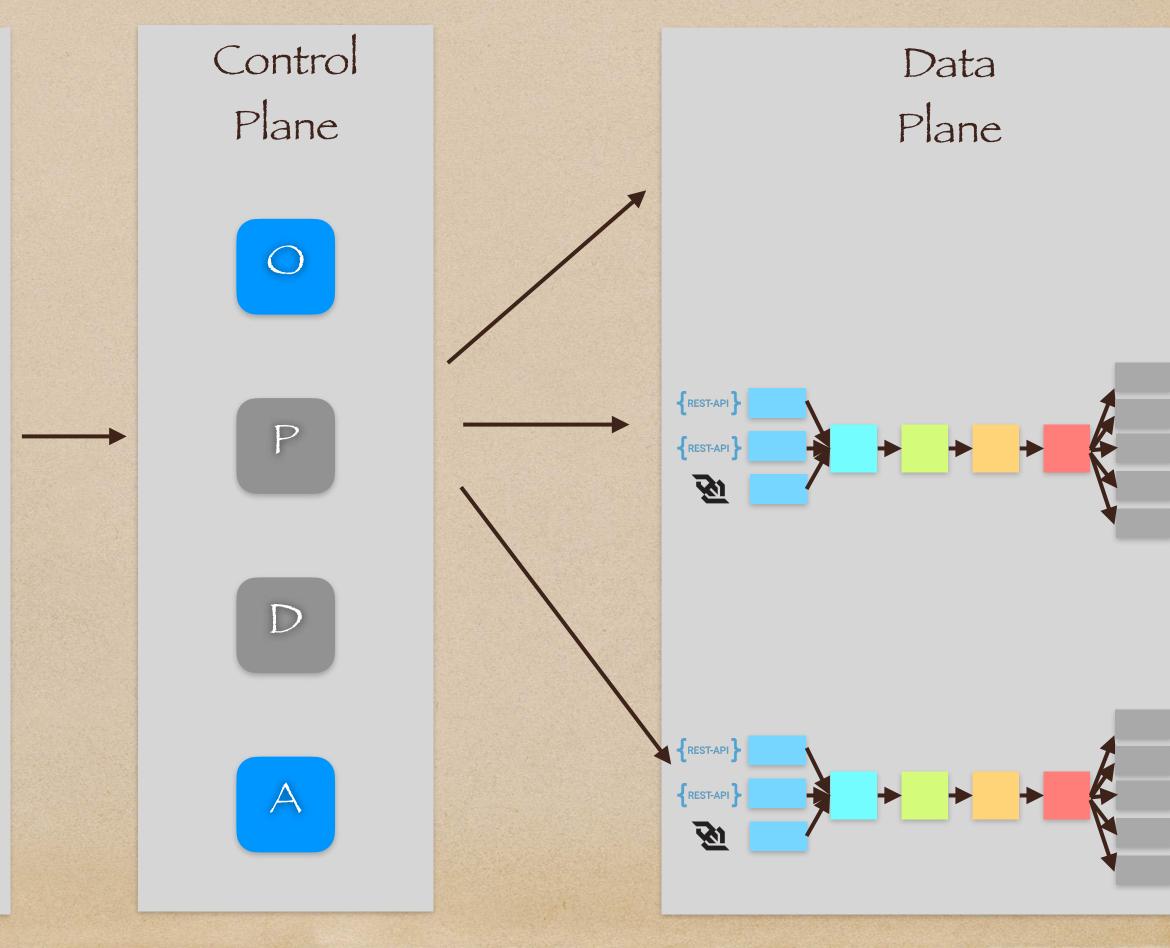




Building StaaS the Control Plane

Together these 4 services form the Control Plane

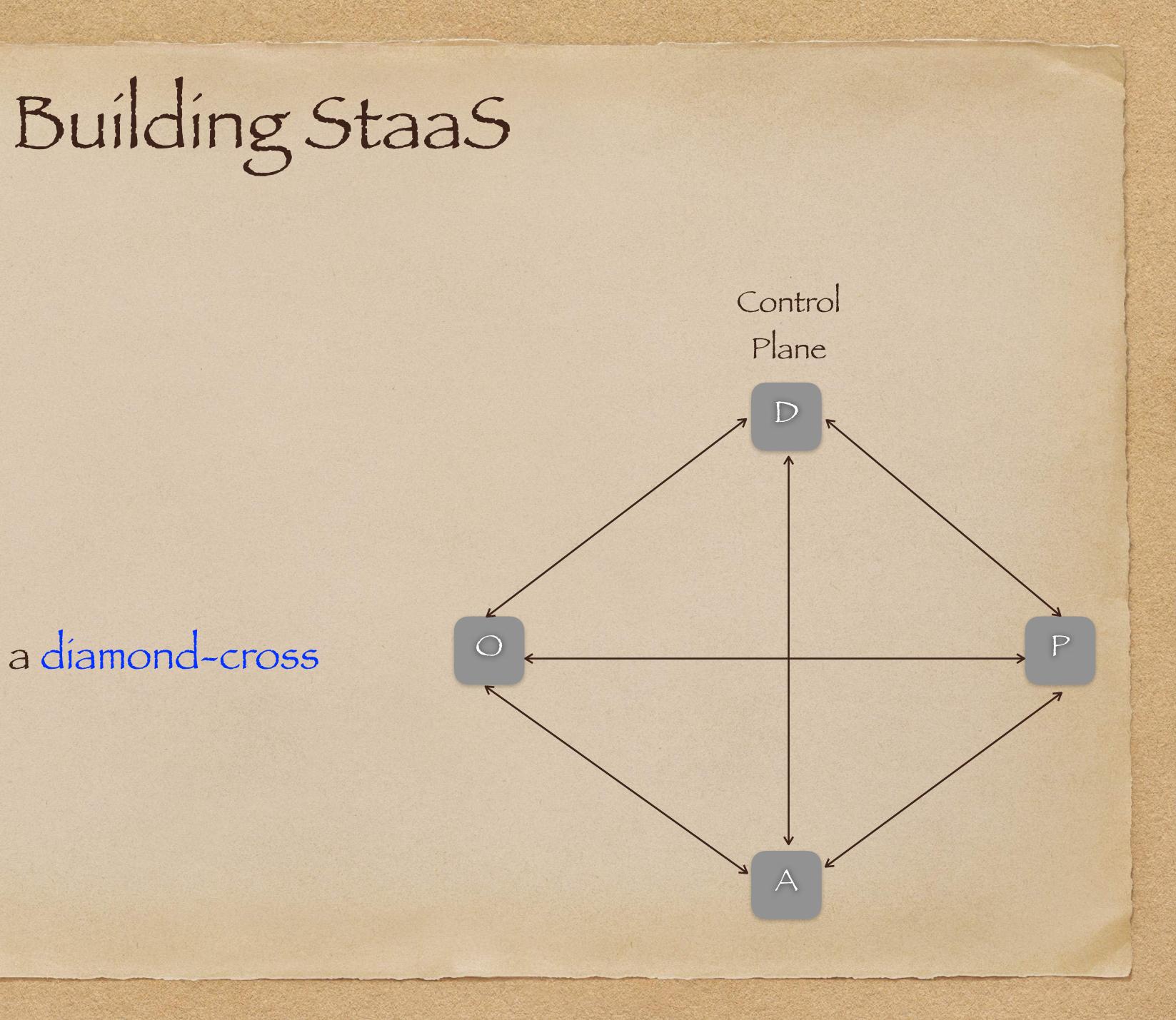






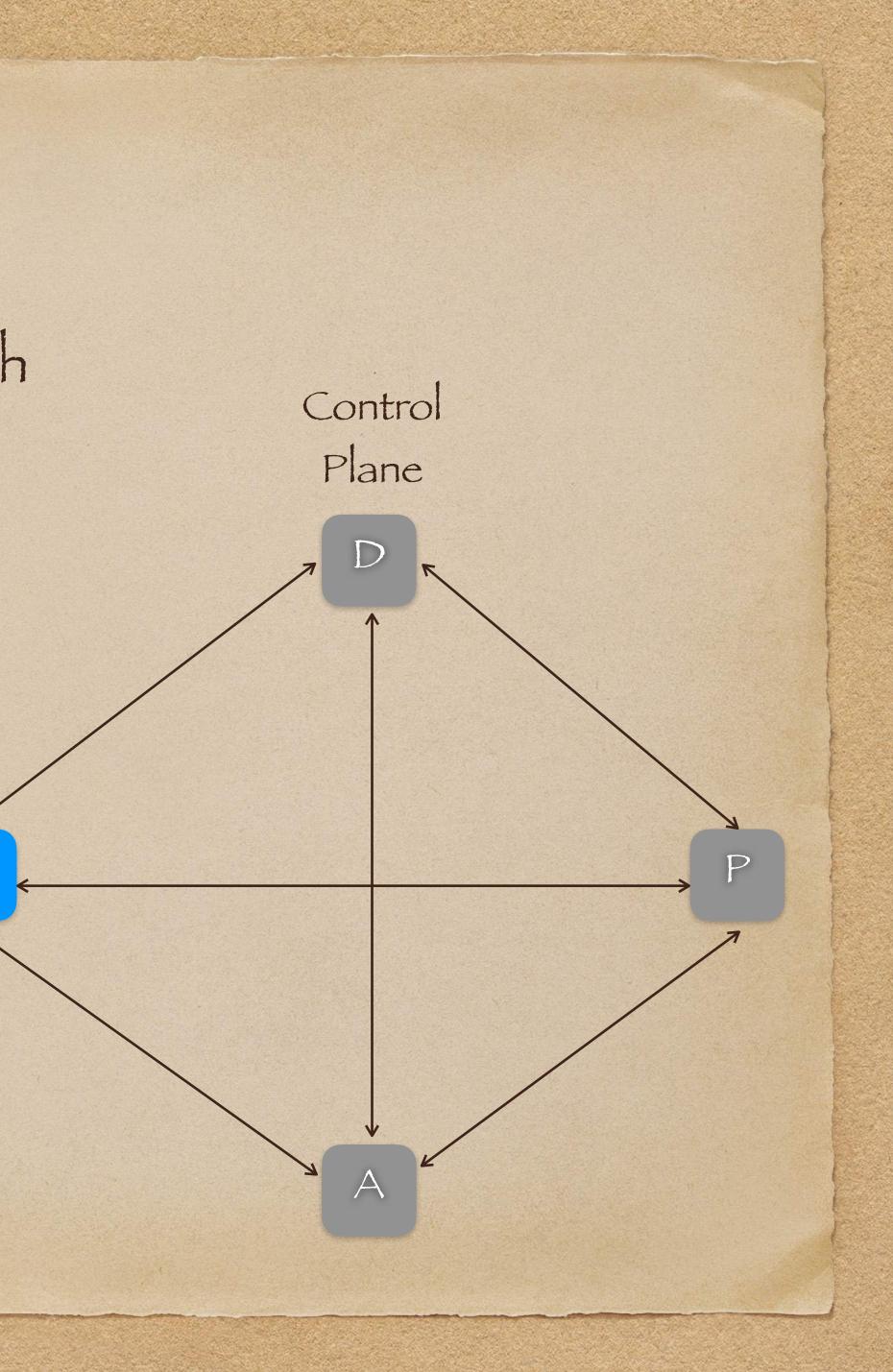


The Control Plane Topology is a diamond-cross

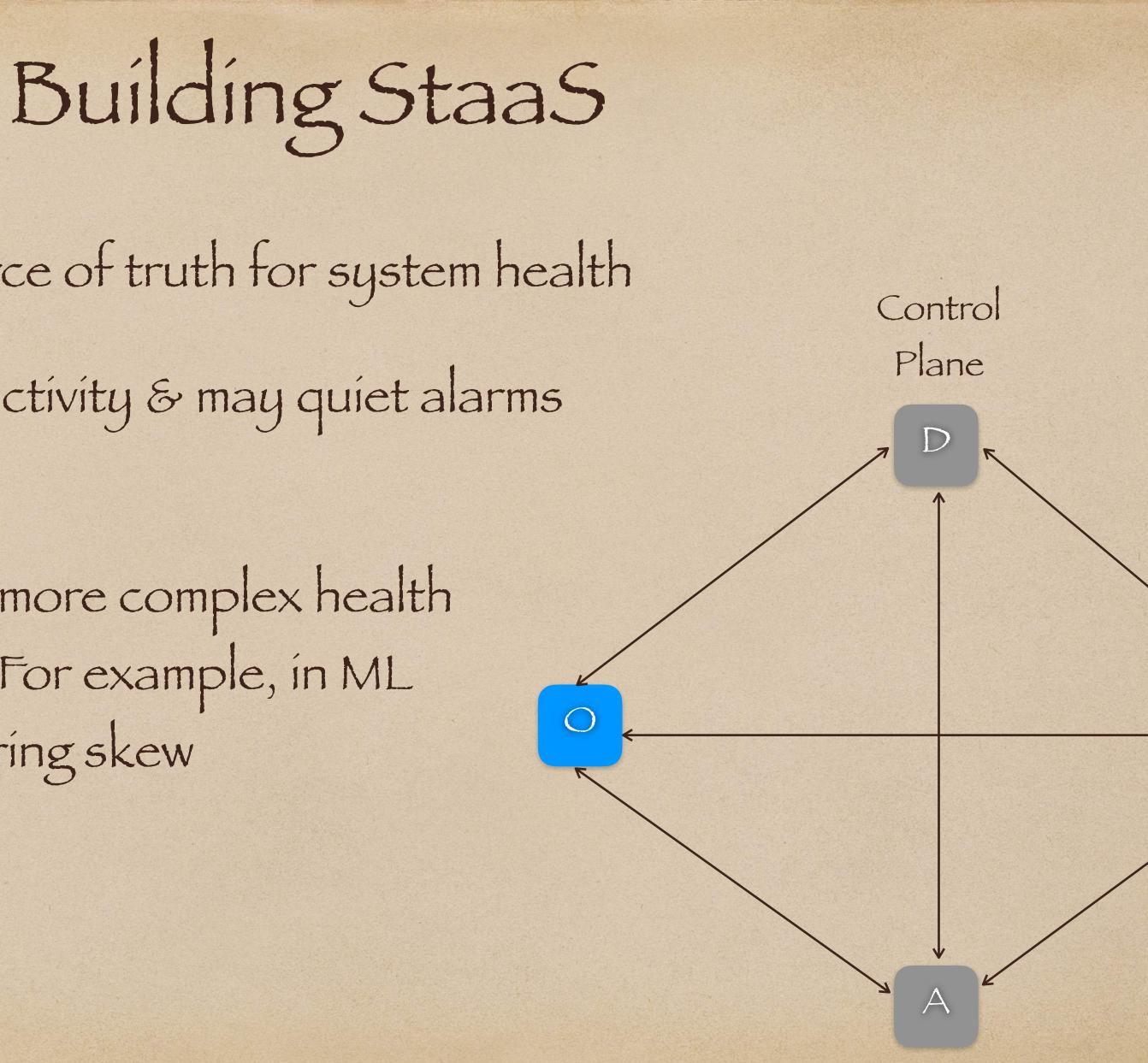


 \bigcirc

- The observer(O) is the source of truth for system health
 - It is aware of D, P, and A activity & may quiet alarms during certain actions

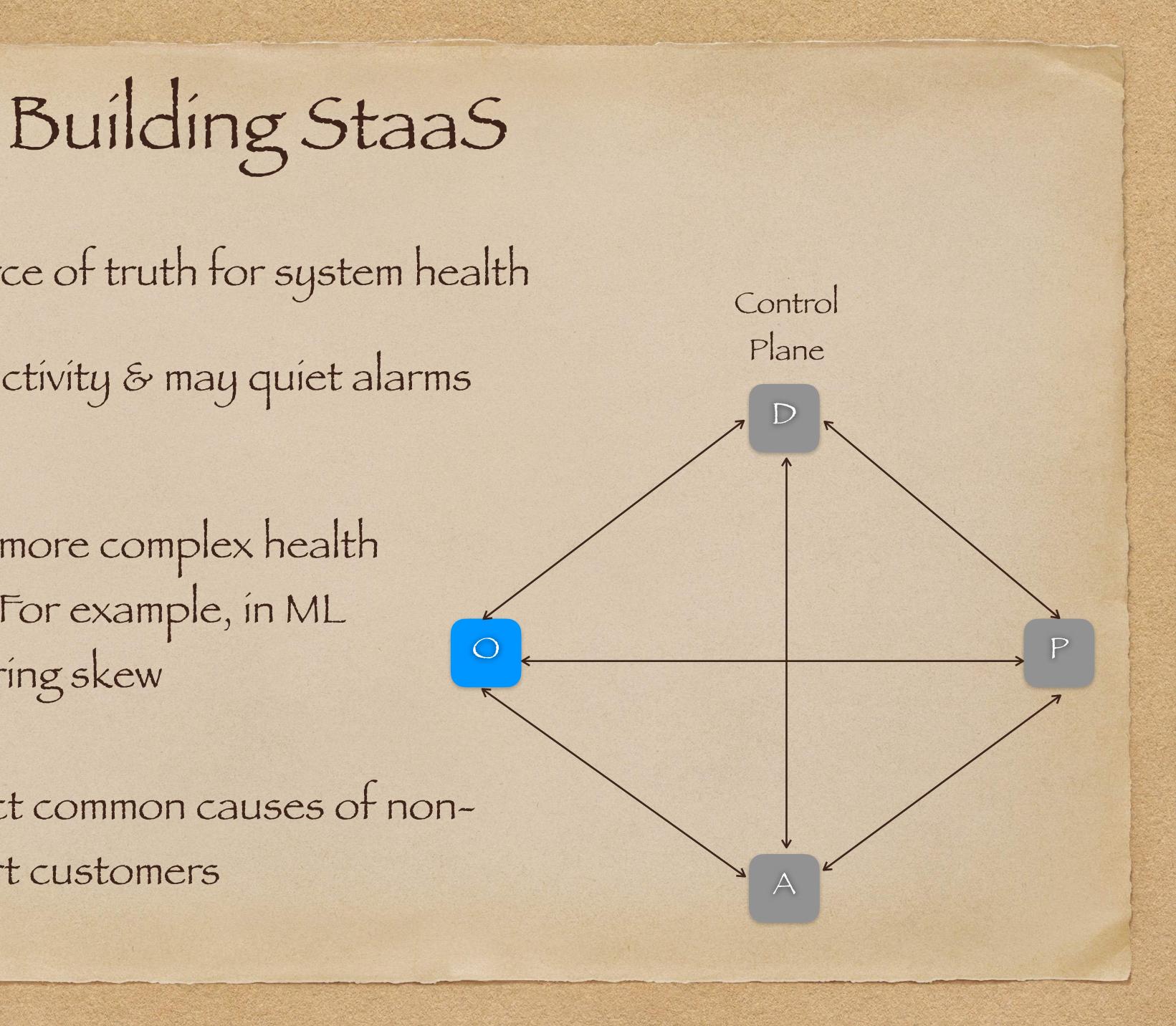


- The observer(O) is the source of truth for system health
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 - It can collect and monitor more complex health metrics than lag and loss. For example, in ML pipelines, it can track scoring skew

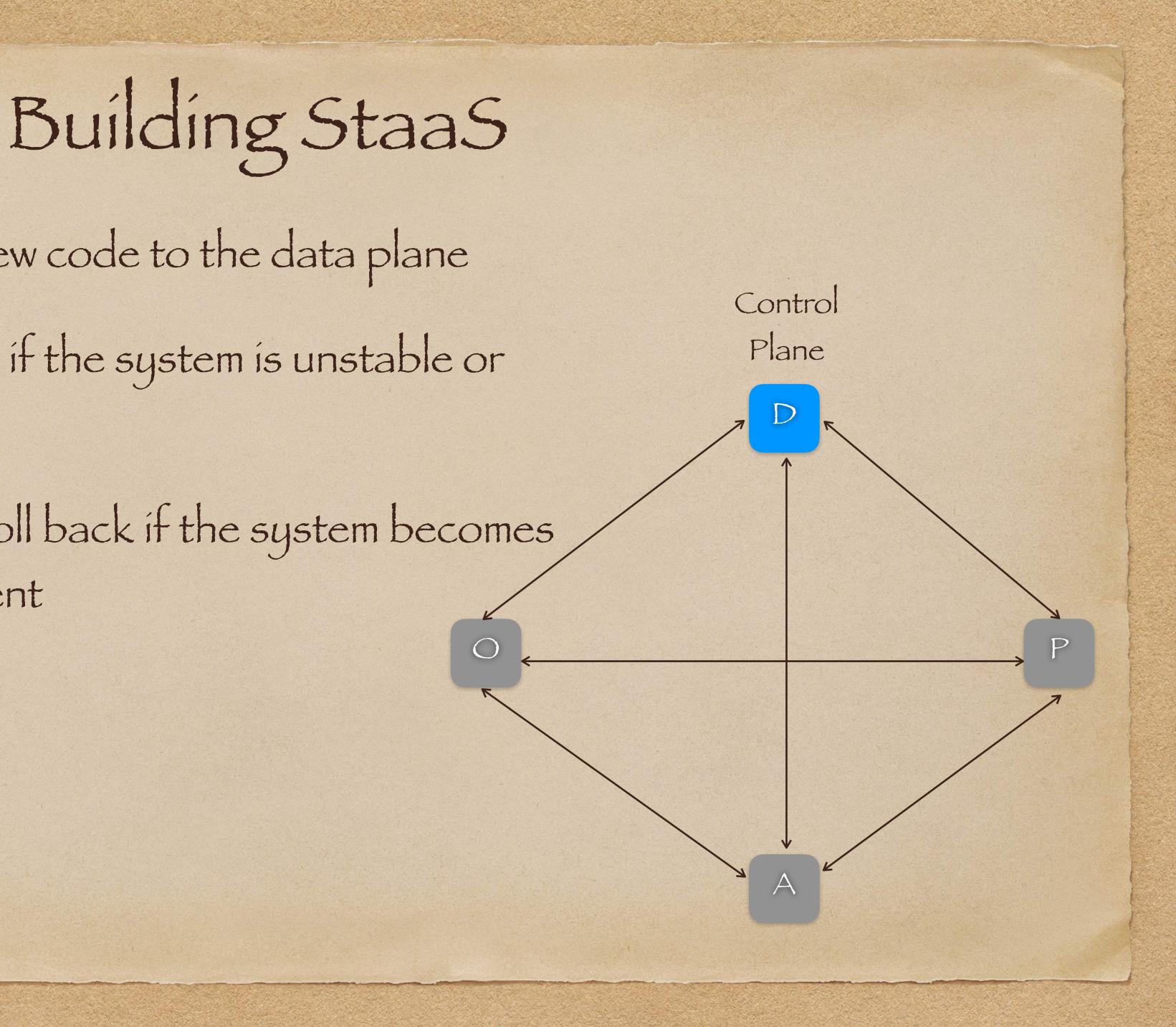




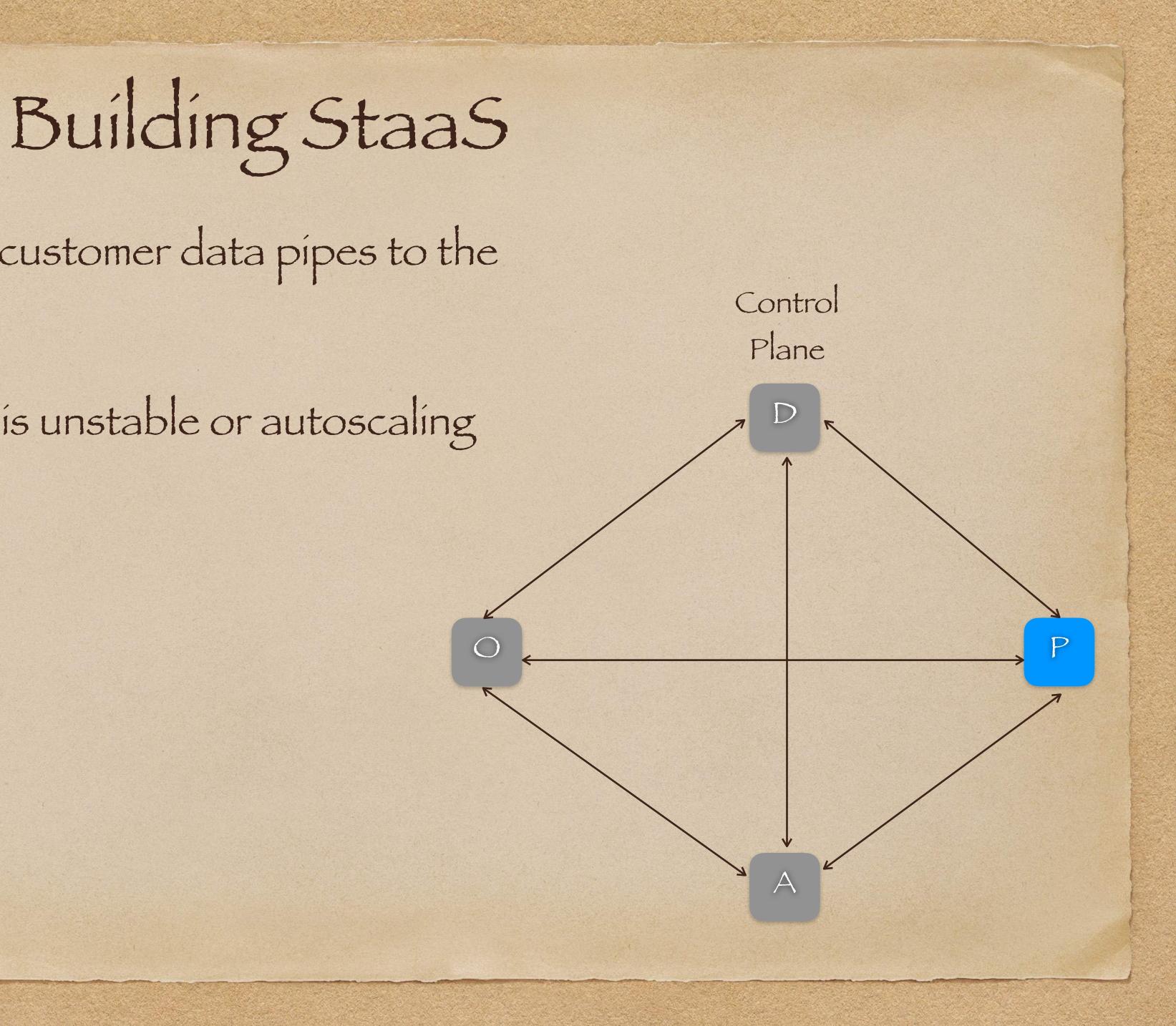
- The observer(O) is the source of truth for system health
 - It is aware of D, P, and A activity & may quiet alarms during certain actions
 - It can collect and monitor more complex health metrics than lag and loss. For example, in ML pipelines, it can track scoring skew
 - The system can also detect common causes of nonrecoverable failures & alert customers



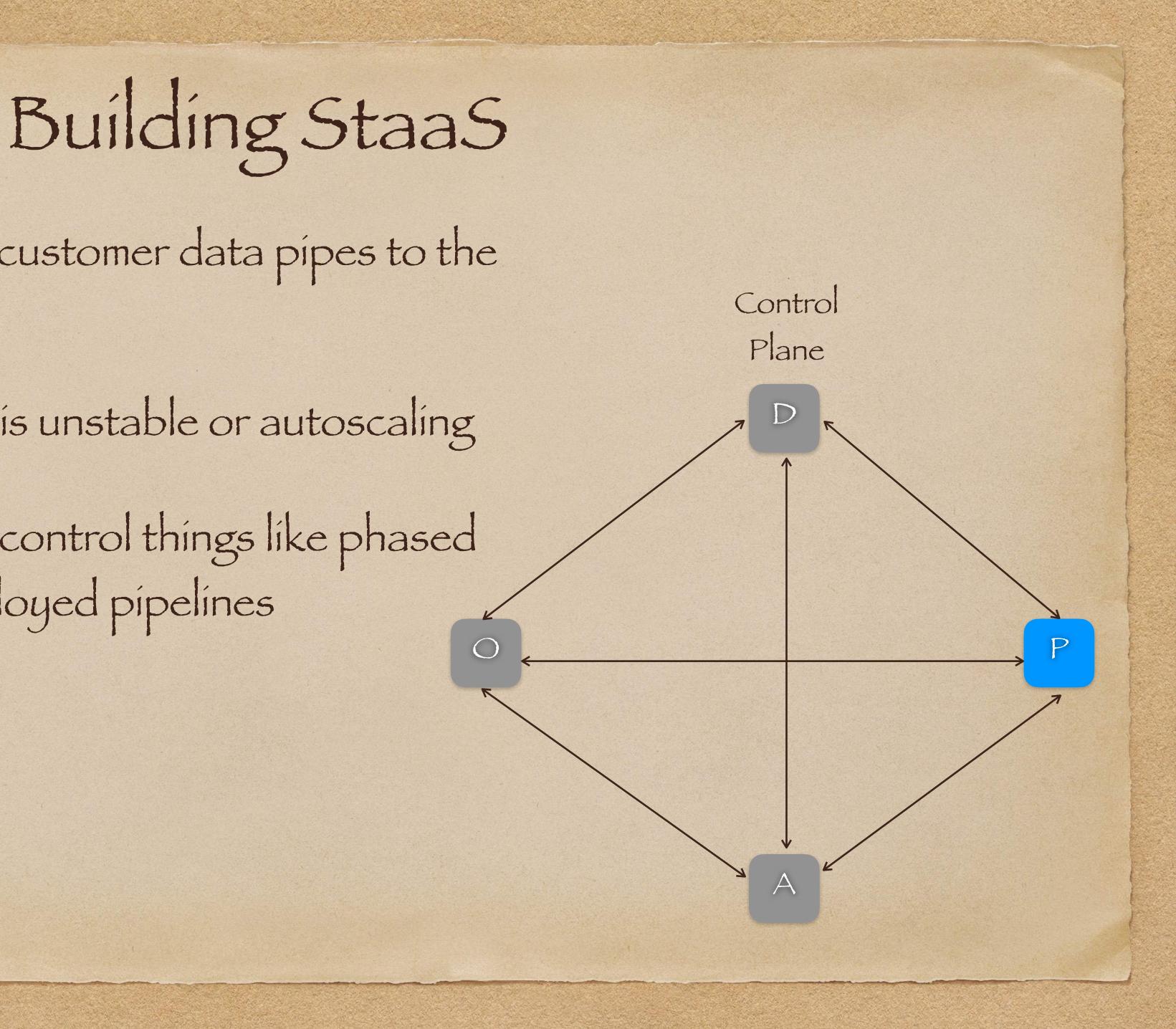
- The deployer (D) deploys new code to the data plane
 - It can however not deploy if the system is unstable or autoscaling
 - It can also automatically roll back if the system becomes unstable due to deployment



- The provisioner (P) deploys customer data pipes to the system.
 - It can pause if the system is unstable or autoscaling



- The provisioner (P) deploys customer data pipes to the system.
 - It can pause if the system is unstable or autoscaling
- The provisioner(P) can also control things like phased traffic ramp ups for new deployed pipelines







Conclusion

citizens

talks (e.g. Isolation, Containerization, Caching)

(@r39132

• We have built a Streams-as-a-Service system with many NFRs as first class

• While we've covered many key elements, a few areas will be covered in future

· Should you have questions, join me for Q&A and follow for more on



Thank You for your Time



- Vincent Chen
- Anísha Naínaní
- Pramod Garre
- Harsh Bhimani
- Nírmalya Ghosh
- Yash Shah
- Aastha Sínha
- Esther Kent
- Dheeraj Rampali

And thanks to the many people who help build these systems with me ..

- Deepak Chandramoulí
- Prasanna Kríshna
- Sandhu Santhakumar
- Maneesh CM & team at Active Lobby
- Shiju & the team at Xminds
- Bob Carlson
- Tony Gentille
- Josh Evans

