

SFS60S-HLKT0K02

SFS/SFM60

MOTOR FEEDBACK SYSTEMS ROTARY HIPERFACE®





Ordering information

Туре	Part no.
SFS60S-HLKT0K02	1081509

Other models and accessories → www.sick.com/SFS_SFM60

Illustration may differ





Detailed technical data

Safety-related parameters

Safety integrity level	SIL 2 (IEC 61508), SILCL2 (EN 62061) ¹⁾
Category	3 (EN ISO 13849)
Test rate	Not required
Maximum demand rate	Continuous (analog signals)
Performance level	PL d (EN ISO 13849) ²⁾
PFH _D : Probability of dangerous failure per hour	1.7 x 10 ⁻⁸ ²⁾
T _M (mission time)	20 years (EN ISO 13849)
Safety-related accuracy	± 0.09°, For square counting ³⁾
Safety-related measuring step	0.09°, For square counting

¹⁾ For more detailed information on the exact configuration of your machine/unit, please consult your relevant SICK branch office.

Performance

Sine/cosine periods per revolution	1,024
Number of the absolute ascertainable revolutions	1
Total number of steps	32,768
Measuring step	$0.3{\rm ''}$ For interpolation of the sine/cosine signals with, e. g., 12 bits
Integral non-linearity	Typ. \pm 45 $^{\prime\prime}$, Error limits for evaluating sine/cosine period, without mechanical tension of the stator coupling
Differential non-linearity	± 7 ", Non-linearity within a sine/cosine period
Operating speed	\leq 6,000 min ⁻¹ , up to which the absolute position can be reliably produced
Available memory area	1,792 Byte
System accuracy	± 52 "

Interfaces

Type of code for the absolute value	Binary
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²⁾ The enclosure rating (in accordance with IEC 60529) is achieved with attached mating connector and was tested with the shaft in a horizontal position.

³⁾ The values displayed apply to a diagnostic degree of coverage of 90%, which must be achieved by the external drive system. In the event of resonance, suitable tests have to be carried out on the entire drive system.

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Code sequence	Rising, For clockwise shaft rotation, looking in direction "A" (see dimensional drawing)
Communication interface	HIPERFACE [®]

Electrical data

Connection type	Cable, 8-wire (4 x 2 x 0.15 mm²), radial, 1.5 m	
Supply voltage	7 V DC 12 V DC	
Recommended supply voltage	8 V DC	
Current consumption	< 80 mA (without load)	
Output frequency for sine/cosine signals	≤ 200 kHz	

Mechanical data

Shaft version	Through hollow shaft
Shaft diameter	10 mm
Shaft material	Stainless steel
Flange material	Zinc diecast
Housing material	Aluminum die cast
Flange type / stator coupling	Stator coupling
Dimensions	See dimensional drawing
Weight	≤ 0.25 kg
Moment of inertia of the rotor	56 gcm ²
Operating speed	≤ 6,000 min ^{-1 1)}
Angular acceleration	≤ 500,000 rad/s²
Operating torque	0.6 Ncm (+20 °C)
Start up torque	+ 0.8 Ncm (+20 °C)
Permissible radial shaft movement	± 0.35 mm
Permissible axial shaft movement	± 0.6 mm
Permissible movement static	\pm 0.3 mm, \pm 0.5 mm radial, axial
Permissible movement dynamic	± 0.05 mm radial ± 0.1 mm axial
Life of ball bearings	3.6 x 10 ⁹ revolutions

 $^{^{1)}}$ Allow for self-heating of 3.3 K per 1,000 rpm when designing the operating temperature range.

Ambient data

Operating temperature range	−30 °C +85 °C
Storage temperature range	-40 °C +90 °C, without package
Relative humidity/condensation	90 %, Condensation not permitted
Resistance to shocks	100 g, 10 ms, 10 ms (according to EN 60068-2-27)
Frequency range of resistance to vibrations	20 g, 10 Hz 2,000 Hz (EN 60068-2-6)
EMC	According to EN 61000-6-2 and EN 61000-6-3 $^{1)}$
Enclosure rating	IP65, with mating connector inserted (IEC 60529)

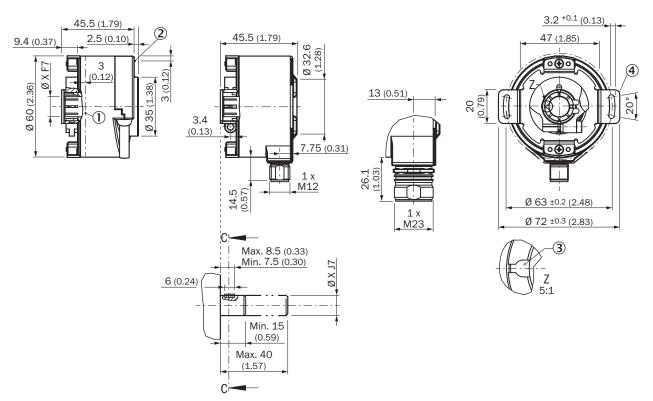
¹⁾ The EMC according to the standards quoted is achieved when the motor feedback system is mounted in an electrically conductive housing, which is connected to the central earthing point of the motor controller via a cable screen. The GND-(0 V) connection of the supply voltage is also grounded here. If other shielding concepts are used, users must perform their own tests.

Classifications

eCl@ss 5.0	27270590
eCl@ss 5.1.4	27270590
eCl@ss 6.0	27270590
eCl@ss 6.2	27270590
eCl@ss 7.0	27270590
eCl@ss 8.0	27270590
eCl@ss 8.1	27270590
eCl@ss 9.0	27270590
eCl@ss 10.0	27273805
eCl@ss 11.0	27273901
eCl@ss 12.0	27273901
ETIM 5.0	EC001486
ETIM 6.0	EC001486
ETIM 7.0	EC001486
ETIM 8.0	EC001486
UNSPSC 16.0901	41112113

Dimensional drawing (Dimensions in mm (inch))

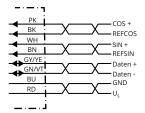
Through hollow shaft - safety system



General tolerances according to DIN ISO 2768-mk

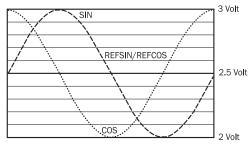
- ① Operating temperature measuring point (freely selectable, in each case circumferential at the housing surface, approx. 3 mm from the flange)
- ② Vibration measuring point (on the housing front face in each case, approx. 3 mm away from edge of housing)
- ③ Feather key groove
- ① Dimensional drawing of the stator coupling may differ depending on the variant. Please also refer to the dimensional drawing of the stator coupling.

PIN assignment



Diagrams

Signal specification of the process channel



Signal diagram for clockwise rotation of the shaft looking in direction "A" (see dimensional drawing)1 period = 360 °: 1024

Recommended accessories

Other models and accessories → www.sick.com/SFS_SFM60

	Brief description	Туре	Part no.
Programming and configuration tools			
[00.10]	SVip® LAN programming tool for all motor feedback systems	PGT-11-S LAN	1057324
Flanges			
	One-sided stator coupling, slot, slot radius 32.25 mm to 141.75 mm, slot width 5.1 mm	BEF-DS02DFS/VFS	2047430
	Stator coupling with hole circle diameter Ø72 mm	BEF-DS07XFX	2059368

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We have extensive experience in a wide range of industries and understand their processes and requirements. With intelligent sensors, we can deliver exactly what our customers need. In application centers in Europe, Asia and North America, system solutions are tested and optimized in accordance with customer specifications. All this makes us a reliable supplier and development partner.

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