

DBS36E-BBAZ00S69

DBS36/50

INCREMENTAL ENCODERS





Ordering information

Туре	Part no.
DBS36E-BBAZ00S69	1093020

Illustration may differ

Other models and accessories → www.sick.com/DBS36_50



Detailed technical data

Features

Special device	1	
Specialty	Cable, 8-wire with male connector M12, universal, 0.1 m with customized pin assignment Operating temperature range –28 $^{\circ}$ C +85 $^{\circ}$ C	
Standard reference device	DBS36E-BBAJ01024, 1060868	

Performance

Pulses per revolution	1,024	
Measuring step	90°, electric/pulses per revolution	
Measuring step deviation	± 18° / pulses per revolution	
Error limits	± 54° / pulses per revolution	
Duty cycle	≤ 0.5 ± 5 %	

Interfaces

Communication interface	Incremental	
Communication Interface detail	TTL / RS-422	
Number of signal channels	6-channel	
Initialization time	< 3 ms	
Output frequency	≤ 300 kHz	
Load current	≤ 30 mA	
Operating current	≤ 50 mA (without load)	

Electrical data

Connection type	Cable, 8-wire, with male connector, M12, 8-pin, universal, 0.1 m, Customer-specific pin assignment $$
Supply voltage	4.5 5.5 V
Reference signal, number	1
Reference signal, position	90°, electric, logically gated with A and B
Short-circuit protection of the outputs	✓ ¹)
MTTFd: mean time to dangerous failure	600 years (EN ISO 13849-1) ²⁾

 $^{^{1)}\,\}mbox{The short-circuit rating is only given if Us and GND are connected correctly.}$

²⁾ This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40°C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

Mechanical data

Mechanical design	Blind hollow shaft	
Shaft diameter		
Snart diameter	8 mm ¹⁾	
Weight	+ 150 g (with connecting cable)	
Shaft material	Stainless steel	
Flange material	Aluminum	
Housing material	Aluminum	
Material, cable	PVC	
Start up torque	+ 0.5 Ncm (+20 °C)	
Operating torque	0.4 Ncm (+20 °C)	
Permissible movement static	\pm 0.3 mm (radial) \pm 0.5 mm (axial) $^{2)}$	
Permissible movement dynamic	\pm 0.1 mm (radial) \pm 0.2 mm (axial) \pm	
Operating speed	6,000 min ^{-1 3)}	
Maximum operating speed	≤ 8,000 min ^{-1 4)}	
Moment of inertia of the rotor	0.8 gcm ²	
Bearing lifetime	2 x 10^9 revolutions	
Angular acceleration	≤ 500,000 rad/s²	

 $^{^{1)}}$ Order collets for 5 mm, 6 mm and 1/4" mm separately as accessories.

Ambient data

EMC	According to EN 61000-6-2 and EN 61000-6-3 (class A)	
Enclosure rating	IP65	
Permissible relative humidity	90 % (Condensation not permitted)	
Operating temperature range	-28 °C +85 °C, -35 °C +95 °C on request	
Storage temperature range	-40 °C +100 °C, without package	
Resistance to shocks	100 g, 6 ms (EN 60068-2-27)	
Resistance to vibration	20 g, 10 Hz 2,000 Hz (EN 60068-2-6)	

Classifications

eCl@ss 5.0	27270501
eCl@ss 5.1.4	27270501
eCl@ss 6.0	27270590
eCl@ss 6.2	27270590
eCl@ss 7.0	27270501
eCl@ss 8.0	27270501
eCl@ss 8.1	27270501
eCl@ss 9.0	27270501
eCl@ss 10.0	27270501
eCl@ss 11.0	27270501

²⁾ Higher values are possible using limited bearing life.

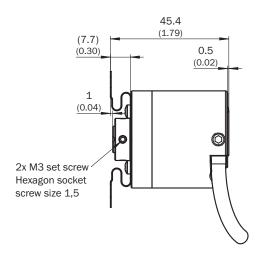
 $^{^{3)}}$ Allow for self-heating of 3.3 K per 1,000 rpm when designing the operating temperature range.

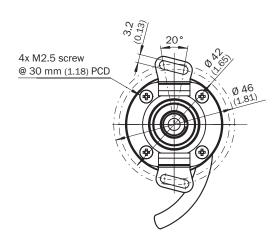
⁴⁾ No permanent operation. Decreasing signal quality.

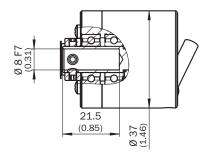
eCl@ss 12.0	27270501
ETIM 5.0	EC001486
ETIM 6.0	EC001486
ETIM 7.0	EC001486
ETIM 8.0	EC001486
UNSPSC 16.0901	41112113

Dimensional drawing (Dimensions in mm (inch))

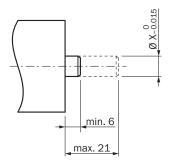
Blind hollow shaft, cable







Attachment specifications



	Encoder	
6 mm	DBS36E-BA	2056390 Premounted
5 mm	DBS36E-BB	2066991
6 mm		2056390
1/4″		On request
8 mm		Not required

PIN assignment



Pin, 8-pin in M12	Signal TTL, HTL	Explanation
1	GND	Ground connection of the encoder
2	+U _s	Supply voltage (volt-free to housing)
3	Α	Signal cable
4	В	Signal cable
5	Z	Signal cable
6	*A	Signal cable
7	'В	Signal cable
8	.S	Signal cable
-	N.C.	Not assigned
-	N.C.	Not assigned
-	N.C.	Not assigned
-	Not connected	Not connected
Shield	Shield	Shield connected to housing on side of encoder.
		Connected to ground on side of control.

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