



# DFS60B-TEEC00256

DFS60

INCREMENTAL ENCODERS

**SICK**  
Sensor Intelligence.



Illustration may differ



### Ordering information

Type	Part no.
DFS60B-TEEC00256	1075467

Other models and accessories → [www.sick.com/DFS60](http://www.sick.com/DFS60)

### Detailed technical data

#### Performance

<b>Pulses per revolution</b>	256 <sup>1)</sup>
<b>Measuring step</b>	90°, electric/pulses per revolution
<b>Measuring step deviation at binary number of lines</b>	± 0.008°
<b>Error limits</b>	± 0.05°

<sup>1)</sup> See maximum revolution range.

#### Interfaces

<b>Communication interface</b>	Incremental
<b>Communication Interface detail</b>	HTL / Push pull
<b>Number of signal channels</b>	6-channel
<b>Initialization time</b>	40 ms
<b>Output frequency</b>	≤ 600 kHz
<b>Load current</b>	≤ 30 mA
<b>Power consumption</b>	≤ 0.5 W (without load)

#### Electrical data

<b>Connection type</b>	Male connector, M12, 8-pin, radial
<b>Supply voltage</b>	10 ... 32 V
<b>Reference signal, number</b>	1
<b>Reference signal, position</b>	90°, electric, logically gated with A and B
<b>Reverse polarity protection</b>	✓
<b>Short-circuit protection of the outputs</b>	✓ <sup>1)</sup>
<b>MTTFd: mean time to dangerous failure</b>	300 years (EN ISO 13849-1) <sup>2)</sup>

<sup>1)</sup> Short-circuit opposite to another channel, US or GND permissible for maximum 30 s.

<sup>2)</sup> This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40 °C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

## Mechanical data

<b>Mechanical design</b>	Through hollow shaft
<b>Shaft diameter</b>	12 mm
<b>Weight</b>	+ 0.2 kg
<b>Shaft material</b>	Stainless steel
<b>Flange material</b>	Aluminum
<b>Housing material</b>	Aluminum die cast
<b>Start up torque</b>	0.8 Ncm (+20 °C)
<b>Operating torque</b>	0.6 Ncm (+20 °C)
<b>Permissible movement static</b>	± 0.3 mm (radial) ± 0.5 mm (axial)
<b>Permissible movement dynamic</b>	± 0.1 mm (radial) ± 0.2 mm (axial)
<b>Operating speed</b>	≤ 6,000 min <sup>-1</sup> <sup>1)</sup>
<b>Moment of inertia of the rotor</b>	40 gcm <sup>2</sup>
<b>Bearing lifetime</b>	3.6 x 10 <sup>10</sup> revolutions
<b>Angular acceleration</b>	≤ 500,000 rad/s <sup>2</sup>

<sup>1)</sup> Allow for self-heating of 3.3 K per 1,000 rpm when designing the operating temperature range.

## Ambient data

<b>EMC</b>	According to EN 61000-6-2 and EN 61000-6-4
<b>Enclosure rating</b>	IP65, Housing side, male connector (IEC 60529) <sup>1)</sup> IP65, shaft side (IEC 60529)
<b>Permissible relative humidity</b>	90 % (Condensation not permitted)
<b>Operating temperature range</b>	-40 °C ... +100 °C <sup>2)</sup> -30 °C ... +100 °C <sup>3)</sup>
<b>Storage temperature range</b>	-40 °C ... +100 °C, without package
<b>Resistance to shocks</b>	70 g, 6 ms (EN 60068-2-27)
<b>Resistance to vibration</b>	30 g, 10 Hz ... 2,000 Hz (EN 60068-2-6)

<sup>1)</sup> With mating connector fitted.

<sup>2)</sup> Stationary position of the cable.

<sup>3)</sup> Flexible position of the cable.

## Classifications

<b>eCl@ss 5.0</b>	27270501
<b>eCl@ss 5.1.4</b>	27270501
<b>eCl@ss 6.0</b>	27270590
<b>eCl@ss 6.2</b>	27270590
<b>eCl@ss 7.0</b>	27270501
<b>eCl@ss 8.0</b>	27270501
<b>eCl@ss 8.1</b>	27270501
<b>eCl@ss 9.0</b>	27270501
<b>eCl@ss 10.0</b>	27270501
<b>eCl@ss 11.0</b>	27270501

<b>eCI@ss 12.0</b>	27270501
<b>ETIM 5.0</b>	EC001486
<b>ETIM 6.0</b>	EC001486
<b>ETIM 7.0</b>	EC001486
<b>ETIM 8.0</b>	EC001486
<b>UNSPSC 16.0901</b>	41112113

### Dimensional drawing (Dimensions in mm (inch))

Through hollow shaft, M12 and M23 radial male connector



General tolerances according to DIN ISO 2768-mk

① Cable diameter = 5.6 mm +/- 0.2 mm bend radius = 30 mm

### PIN assignment



View of M12 male device connector on encoder

PIN Male connector M12, 8-pin	PIN Male connector M23, 12-pin	Wire colors (cable connection)	TTL/HTL signal	Sin/Cos 1.0 V <sub>pp</sub>	Explanation
1	6	Brown	$\bar{A}$	COS-	Signal wire
2	5	White	A	COS+	Signal wire
3	1	Black	$\bar{B}$	SIN-	Signal wire
4	8	Pink	B	SIN+	Signal wire
5	4	Yellow	$\bar{Z}$	$\bar{Z}$	Signal wire
6	3	Purple	Z	Z	Signal wire
7	10	Blue	GND	GND	Ground connection
8	12	Red	+U <sub>S</sub>	+U <sub>S</sub>	Supply voltage
-	9	-	N.c.	N.c.	Not assigned
-	2	-	N.c.	N.c.	Not assigned
-	11	-	N.c.	N.c.	Not assigned
-	7 <sup>1)</sup>	Orange	O-SET <sup>1)</sup>	N.c.	Set zero pulse <sup>1)</sup>
Screen	Screen	Screen	Screen	Screen	Screen connected to housing on encoder side. Connected to ground on control side.

1)

For electrical interfaces only: M, U, V, W with 0-SET function on PIN 7 on M23 plug. The 0-SET input is used to set the zero pulse to the current shaft position. If the 0-SET input is applied to US for longer than 250 ms after it has previously been open or applied to GND for at least 1,000 ms, the current shaft position is assigned zero pulse signal "Z".

## Diagrams

### Signal outputs



CW with view on the encoder shaft in direction "A", compare dimensional drawing.

Maximum revolution range



Supply voltage	Output
4,5 V ... 5,5 V	TTL
10 V ... 32 V	TTL
10 V ... 32 V	HTL

### Recommended accessories

Other models and accessories → [www.sick.com/DFS60](http://www.sick.com/DFS60)

	Brief description	Type	Part no.
<b>Flanges</b>			
	Standard stator coupling	BEF-DS00XFX	2056812
<b>Other mounting accessories</b>			
	Bearing bracket for hollow shaft encoders, fastening screws included the Bearing Block is intended for very large radial and axial shaft loads. Particularly for application on: Belt pulleys, Chain pinions, Friction wheels. It is designed this way to enable fitting of encoder with blind hollow shaft with ø 12 mm., fastening screws included	BEF-FA-B12-010	2042728
	Clamping ring for metal hollow shaft <sup>ts</sup> , metal	BEF-KR-M	2064709
<b>Plug connectors and cables</b>			
	Head A: female connector, M12, 8-pin, straight Head B: Flying leads Cable: Incremental, SSI, PUR, halogen-free, shielded, 2 m	DOL-1208-G02MAC1	6032866
	Head A: female connector, M12, 8-pin, straight Head B: Flying leads Cable: Incremental, SSI, PUR, halogen-free, shielded, 5 m	DOL-1208-G05MAC1	6032867

	Brief description	Type	Part no.
	Head A: female connector, M12, 8-pin, straight Head B: Flying leads Cable: Incremental, SSI, PUR, halogen-free, shielded, 10 m	DOL-1208-G10MAC1	6032868
	Head A: female connector, M12, 8-pin, straight Head B: Flying leads Cable: Incremental, SSI, PUR, halogen-free, shielded, 20 m	DOL-1208-G20MAC1	6032869
	Head A: female connector, M12, 8-pin, angled Head B: Flying leads Cable: PVC, shielded, 2 m	DOL-1208-W02MA	6020992
	Head A: female connector, M12, 8-pin, angled Head B: Flying leads Cable: HIPERFACE <sup>®</sup> , Incremental, PUR, halogen-free, shielded, 2 m	DOL-1208-W02MAC1	6037724
	Head A: female connector, M12, 8-pin, angled Head B: Flying leads Cable: Sensor/actuator cable, PUR, halogen-free, shielded, 2 m	DOL-1208-W02MAS01	6029224
	Head A: female connector, M12, 8-pin, angled Head B: Flying leads Cable: PUR, halogen-free, unshielded, 2 m	DOL-1208-W02MC	6035623
	Head A: female connector, M12, 8-pin, angled Head B: Flying leads Cable: PVC, shielded, 5 m	DOL-1208-W05MA	6021033
	Head A: female connector, M12, 8-pin, angled Head B: Flying leads Cable: HIPERFACE <sup>®</sup> , Incremental, PUR, halogen-free, shielded, 5 m	DOL-1208-W05MAC1	6037725
	Head A: female connector, M12, 8-pin, angled Head B: Flying leads Cable: PUR, unshielded, 5 m	DOL-1208-W05MC	6035624
	Head A: female connector, M12, 8-pin, angled Head B: Flying leads Cable: HIPERFACE <sup>®</sup> , Incremental, PUR, halogen-free, shielded, 10 m	DOL-1208-W10MAC1	6037726
	Head A: female connector, M12, 8-pin, angled Head B: Flying leads Cable: PUR, halogen-free, unshielded, 10 m	DOL-1208-W10MC	6035625
	Head A: female connector, M12, 8-pin, angled Head B: Flying leads Cable: HIPERFACE <sup>®</sup> , Incremental, PUR, shielded, 20 m	DOL-1208-W20MAC1	6037727
		Head A: female connector, M12, 8-pin, straight, A-coded Cable: Incremental, SSI, shielded	DOS-1208-GA01

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