

DFS60B-S4EZ00S80

DFS60

**INCREMENTAL ENCODERS** 



Illustration may differ

### Ordering information

Туре	Part no.
DFS60B-S4EZ00S80	1082933

Other models and accessories → www.sick.com/DFS60



#### Detailed technical data

#### **Features**

Special device	✓
Specialty	Cable, 8-wire, with universal M12 8-pin male connector  Total length including connector 130 mm. M12 connector must be protected by an additional strain relief
Standard reference device	DFS60B-S4EA00006, 1037261

### Performance

Pulses per revolution	6 <sup>1)</sup>
Measuring step	90°, electric/pulses per revolution
Measuring step deviation at non binary number of lines	± 0.08°
Error limits	± 0.05°

 $<sup>^{1)}</sup>$  See maximum revolution range.

#### Interfaces

Communication interface	Incremental
Communication Interface detail	HTL / Push pull
Number of signal channels	6-channel
Initialization time	40 ms
Output frequency	≤ 600 kHz
Load current	≤ 30 mA
Power consumption	≤ 0.5 W (without load)

### Electrical data

Connection type	Cable, 8-wire, with male connector, M12, 8-pin, universal 1)
Supply voltage	10 32 V
Reference signal, number	1
Reference signal, position	90°, electric, logically gated with A and B
Reverse polarity protection	✓

<sup>1)</sup> The universal cable connection is positioned so that it is possible to lay it without bends in a radial or axial direction.

 $<sup>^{2)}\,\</sup>mbox{Short-circuit opposite to another channel, US or GND permissable for maximum 30 s.$ 

<sup>3)</sup> This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40 °C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

Short-circuit protection of the outputs	<b>√</b> <sup>2)</sup>
MTTFd: mean time to dangerous failure	300 years (EN ISO 13849-1) 3)

 $<sup>^{1)}</sup>$  The universal cable connection is positioned so that it is possible to lay it without bends in a radial or axial direction.

### Mechanical data

Mechanical design       Solid shaft, face mount flange         Shaft diameter       10 mm         Shaft length       19 mm         Weight       + 0.3 kg         Shaft material       Stainless steel         Flange material       Aluminum         Housing material       Aluminum die cast         Start up torque       0.5 Ncm (+20 °C)         Operating torque       0.3 Ncm (+20 °C)         Permissible shaft loading       80 N (radial) 40 N (axial)         40 N (axial)       40 N (axial)         Moment of inertia of the rotor       6.2 gcm²         Bearing lifetime       3.6 x 10^10 revolutions         Angular acceleration       ≤ 500,000 rad/s²		
Shaft length  Weight + 0.3 kg  Shaft material Stainless steel  Flange material Aluminum  Housing material Aluminum die cast  Start up torque 0.5 Ncm (+20 °C)  Operating torque 0.3 Ncm (+20 °C)  Permissible shaft loading 80 N (radial) 40 N (axial)  Operating speed ≤ 9,000 min⁻¹¹)  Moment of inertia of the rotor 6.2 gcm²  Bearing lifetime 3.6 x 10^10 revolutions	Mechanical design	Solid shaft, face mount flange
Weight + 0.3 kg  Shaft material Stainless steel  Flange material Aluminum  Housing material Aluminum die cast  Start up torque 0.5 Ncm (+20 °C)  Operating torque 0.3 Ncm (+20 °C)  Permissible shaft loading 80 N (radial) 40 N (axial)  Operating speed ≤ 9,000 min⁻¹¹  Moment of inertia of the rotor 6.2 gcm²  Bearing lifetime 3.6 x 10^10 revolutions	Shaft diameter	10 mm
Shaft material       Stainless steel         Flange material       Aluminum         Housing material       Aluminum die cast         Start up torque       0.5 Ncm (+20 °C)         Operating torque       0.3 Ncm (+20 °C)         Permissible shaft loading       80 N (radial) 40 N (axial)         Operating speed       ≤ 9,000 min⁻¹ ¹)         Moment of inertia of the rotor       6.2 gcm²         Bearing lifetime       3.6 x 10^10 revolutions	Shaft length	19 mm
Flange material  Housing material  Aluminum die cast  Start up torque  0.5 Ncm (+20 °C)  Operating torque  0.3 Ncm (+20 °C)  Permissible shaft loading  80 N (radial) 40 N (axial)  Operating speed  ≤ 9,000 min⁻¹¹¹)  Moment of inertia of the rotor  Bearing lifetime  3.6 x 10^10 revolutions	Weight	+ 0.3 kg
Housing material  Start up torque  0.5 Ncm (+20 °C)  Operating torque  0.3 Ncm (+20 °C)  Permissible shaft loading  80 N (radial) 40 N (axial)  Operating speed  ≤ 9,000 min <sup>-1</sup> 1)  Moment of inertia of the rotor  6.2 gcm²  Bearing lifetime  Aluminum die cast  0.5 Ncm (+20 °C)  80 N (radial) 40 N (axial)  40 N (axial)  50 Scm²  80 Scm²  80 Scm²  80 Scm²  80 Scm²	Shaft material	Stainless steel
Start up torque       0.5 Ncm (+20 °C)         Operating torque       0.3 Ncm (+20 °C)         Permissible shaft loading       80 N (radial) 40 N (axial)         Operating speed       ≤ 9,000 min⁻¹¹¹         Moment of inertia of the rotor       6.2 gcm²         Bearing lifetime       3.6 x 10^10 revolutions	Flange material	Aluminum
Operating torque       0.3 Ncm (+20 °C)         Permissible shaft loading       80 N (radial) 40 N (axial)         Operating speed       ≤ 9,000 min⁻¹¹)         Moment of inertia of the rotor       6.2 gcm²         Bearing lifetime       3.6 x 10^10 revolutions	Housing material	Aluminum die cast
Permissible shaft loading  80 N (radial) 40 N (axial)  Operating speed  ≤ 9,000 min <sup>-1 1)</sup> Moment of inertia of the rotor  6.2 gcm²  Bearing lifetime  3.6 x 10^10 revolutions	Start up torque	0.5 Ncm (+20 °C)
$40 \text{ N (axial)}$ Operating speed $\leq 9,000 \text{ min}^{-1}$ Moment of inertia of the rotor 6.2 gcm <sup>2</sup> Bearing lifetime 3.6 x 10^10 revolutions	Operating torque	0.3 Ncm (+20 °C)
Moment of inertia of the rotor  6.2 gcm <sup>2</sup> 3.6 x 10^10 revolutions	Permissible shaft loading	
Bearing lifetime 3.6 x 10^10 revolutions	Operating speed	≤ 9,000 min <sup>-1 1)</sup>
	Moment of inertia of the rotor	6.2 gcm <sup>2</sup>
Angular acceleration ≤ 500,000 rad/s²	Bearing lifetime	3.6 x 10^10 revolutions
	Angular acceleration	≤ 500,000 rad/s²

 $<sup>^{1)}</sup>$  Allow for self-heating of 3.3 K per 1,000 rpm when designing the operating temperature range.

### Ambient data

ЕМС	According to EN 61000-6-2 and EN 61000-6-4
Enclosure rating	IP67, Housing side, male connector (IEC 60529) <sup>1)</sup> IP65, shaft side (IEC 60529)
Permissible relative humidity	90 % (Condensation not permitted)
Operating temperature range	-40 °C +100 °C <sup>2)</sup> -30 °C +100 °C <sup>3)</sup>
Storage temperature range	-40 °C +100 °C, without package
Resistance to shocks	70 g, 6 ms (EN 60068-2-27)
Resistance to vibration	30 g, 10 Hz 2,000 Hz (EN 60068-2-6)

 $<sup>^{1)}</sup>$  With mating connector fitted.

#### Classifications

eCl@ss 5.0	27270501
eCl@ss 5.1.4	27270501
eCl@ss 6.0	27270590
eCl@ss 6.2	27270590
eCl@ss 7.0	27270501

 $<sup>^{2)}</sup>$  Short-circuit opposite to another channel, US or GND permissable for maximum 30 s.

<sup>&</sup>lt;sup>3)</sup> This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40°C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

<sup>2)</sup> Stationary position of the cable.

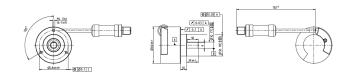
 $<sup>^{</sup>m 3)}$  Flexible position of the cable.

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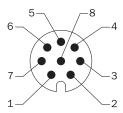
## INCREMENTAL ENCODERS

eCl@ss 8.0	27270501
eCl@ss 8.1	27270501
eCl@ss 9.0	27270501
eCl@ss 10.0	27270501
eCl@ss 11.0	27270501
eCl@ss 12.0	27270501
ETIM 5.0	EC001486
ETIM 6.0	EC001486
ETIM 7.0	EC001486
ETIM 8.0	EC001486
UNSPSC 16.0901	41112113

## Dimensional drawing (Dimensions in mm (inch))



## PIN assignment



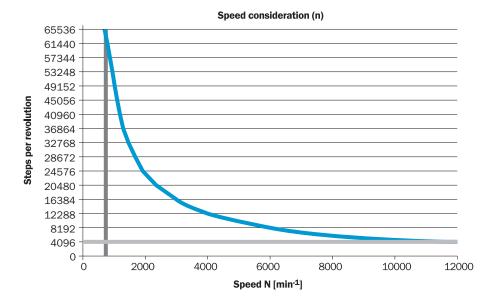
View of M12 male device connector on encoder

PIN Male connector M12, 8-pin	PIN Male connec- tor M23, 12-pin	Wire colors (ca- ble connection)	TTL/HTL signal	Sin/Cos 1.0 V <sub>PP</sub>	Explanation
1	6	Brown	_A	COS-	Signal wire
2	5	White	A	COS+	Signal wire
3	1	Black	-В	SIN-	Signal wire
4	8	Pink	В	SIN+	Signal wire
5	4	Yellow	-Z	-Z	Signal wire
6	3	Purple	Z	Z	Signal wire
7	10	Blue	GND	GND	Ground connection
8	12	Red	+U <sub>S</sub>	+U <sub>S</sub>	Supply voltage
-	9	-	N.c.	N.c.	Not assigned
-	2	-	N.c.	N.c.	Not assigned
-	11	-	N.c.	N.c.	Not assigned

PIN Male connector M12, 8-pin	PIN Male connec- tor M23, 12-pin	Wire colors (ca- ble connection)	TTL/HTL signal	Sin/Cos 1.0 V <sub>PP</sub>	Explanation
-	7 1)	Orange	0-SET 1)	N.c.	Set zero pulse
Screen	Screen	Screen	Screen	Screen	Screen connected to housing on encoder side. Connected to ground on control side.
1)					
For electrical interfaces only: M, U, V, W with 0-SET function on PIN 7 on M23 plug. The 0-SET input is used to set the zero pulse to the current shaft position. If the 0-SET input is applied to US for longer than 250 ms after it has previously been open or applied to GND for at least 1,000 ms, the current shaft position is assigned zero pulse signal "Z".					

## Diagrams

Maximum revolution range



## SICK AT A GLANCE

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For us, that is "Sensor Intelligence."

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