



# DFS60A-TEPK65536

DFS60

INCREMENTAL ENCODERS

**SICK**  
Sensor Intelligence.



Illustration may differ



### Ordering information

| Type             | Part no. |
|------------------|----------|
| DFS60A-TEPK65536 | 1036964  |

Other models and accessories → [www.sick.com/DFS60](http://www.sick.com/DFS60)

### Detailed technical data

#### Performance

|   |                                     |
|---|-------------------------------------|
| <b>Pulses per revolution</b>                              | 65,536 <sup>1)</sup>                |
| <b>Measuring step</b>                                     | 90°, electric/pulses per revolution |
| <b>Measuring step deviation at binary number of lines</b> | ± 0.0015°                           |
| <b>Error limits</b>                                       | ± 0.03°                             |

<sup>1)</sup> See maximum revolution range.

#### Interfaces

|                                       |                                   |
|---------------------------------------|-----------------------------------|
| <b>Communication interface</b>        | Incremental                       |
| <b>Communication Interface detail</b> | TTL / HTL                         |
| <b>Factory setting</b>                | Factory setting: output level TTL |
| <b>Number of signal channels</b>      | 6-channel                         |
| <b>Programmable/configurable</b>      | ✓                                 |
| <b>Initialization time</b>            | 32 ms <sup>1)</sup><br>30 ms      |
| <b>Output frequency</b>               | ≤ 820 kHz                         |
| <b>Load current</b>                   | ≤ 30 mA                           |
| <b>Power consumption</b>              | ≤ 0.7 W (without load)            |

<sup>1)</sup> With mechanical zero pulse width.

#### Electrical data

|                                 |   |
|---------------------------------|---|
| <b>Connection type</b>          | Cable, 8-wire, universal, 1.5 m <sup>1)</sup> |
| <b>Supply voltage</b>           | 4.5 ... 32 V                                  |
| <b>Reference signal, number</b> | 1   |

<sup>1)</sup> The universal cable connection is positioned so that it is possible to lay it without bends in a radial or axial direction.

<sup>2)</sup> Programming TTL with ≥ 5.5 V: short-circuit opposite to another channel or GND permissible for maximum 30 s.

<sup>3)</sup> Programming HTL or TTL with < 5.5 V: short-circuit opposite to another channel, US or GND permissible for maximum 30 s.

<sup>4)</sup> This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40°C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

|  |   |
|--|---|
| <b>Reference signal, position</b>              | 90°, electric, logically gated with A and B |
| <b>Reverse polarity protection</b>             | ✓   |
| <b>Short-circuit protection of the outputs</b> | ✓ <sup>2) 3)</sup>                          |
| <b>MTTFd: mean time to dangerous failure</b>   | 300 years (EN ISO 13849-1) <sup>4)</sup>    |

<sup>1)</sup> The universal cable connection is positioned so that it is possible to lay it without bends in a radial or axial direction.

<sup>2)</sup> Programming TTL with  $\geq 5.5$  V: short-circuit opposite to another channel or GND permissible for maximum 30 s.

<sup>3)</sup> Programming HTL or TTL with  $< 5.5$  V: short-circuit opposite to another channel, US or GND permissible for maximum 30 s.

<sup>4)</sup> This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40 °C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

## Mechanical data

|                                       |   |
|---------------------------------------|---|
| <b>Mechanical design</b>              | Through hollow shaft                        |
| <b>Shaft diameter</b>                 | 12 mm                                       |
| <b>Weight</b>                         | + 0.2 kg                                    |
| <b>Shaft material</b>                 | Stainless steel                             |
| <b>Flange material</b>                | Aluminum                                    |
| <b>Housing material</b>               | Aluminum die cast                           |
| <b>Start up torque</b>                | 0.8 Ncm (+20 °C)                            |
| <b>Operating torque</b>               | 0.6 Ncm (+20 °C)                            |
| <b>Permissible movement static</b>    | ± 0.3 mm (radial)<br>± 0.5 mm (axial)       |
| <b>Permissible movement dynamic</b>   | ± 0.05 mm (radial)<br>± 0.01 mm (axial)     |
| <b>Operating speed</b>                | $\leq 6,000 \text{ min}^{-1}$ <sup>1)</sup> |
| <b>Moment of inertia of the rotor</b> | 40 gcm <sup>2</sup>                         |
| <b>Bearing lifetime</b>               | $3.6 \times 10^{10}$ revolutions            |
| <b>Angular acceleration</b>           | $\leq 500,000 \text{ rad/s}^2$              |

<sup>1)</sup> Allow for self-heating of 3.3 K per 1,000 rpm when designing the operating temperature range.

## Ambient data

|                                      |  |
|--------------------------------------|--|
| <b>EMC</b>                           | According to EN 61000-6-2 and EN 61000-6-3                                       |
| <b>Enclosure rating</b>              | IP65, housing side, cable connection (IEC 60529)<br>IP65, shaft side (IEC 60529) |
| <b>Permissible relative humidity</b> | 90 % (Condensation not permitted)  |
| <b>Operating temperature range</b>   | -40 °C ... +100 °C <sup>1)</sup><br>-30 °C ... +100 °C <sup>2)</sup>             |
| <b>Storage temperature range</b>     | -40 °C ... +100 °C, without package  |
| <b>Resistance to shocks</b>          | 100 g, 6 ms (EN 60068-2-27)  |
| <b>Resistance to vibration</b>       | 30 g, 10 Hz ... 2,000 Hz (EN 60068-2-6)  |

<sup>1)</sup> Stationary position of the cable.

<sup>2)</sup> Flexible position of the cable.

## Classifications

|                     |          |
|---------------------|----------|
| <b>eCI@ss 5.0</b>   | 27270501 |
| <b>eCI@ss 5.1.4</b> | 27270501 |

|                       |          |
|-----------------------|----------|
| <b>eCl@ss 6.0</b>     | 27270590 |
| <b>eCl@ss 6.2</b>     | 27270590 |
| <b>eCl@ss 7.0</b>     | 27270501 |
| <b>eCl@ss 8.0</b>     | 27270501 |
| <b>eCl@ss 8.1</b>     | 27270501 |
| <b>eCl@ss 9.0</b>     | 27270501 |
| <b>eCl@ss 10.0</b>    | 27270501 |
| <b>eCl@ss 11.0</b>    | 27270501 |
| <b>eCl@ss 12.0</b>    | 27270501 |
| <b>ETIM 5.0</b>       | EC001486 |
| <b>ETIM 6.0</b>       | EC001486 |
| <b>ETIM 7.0</b>       | EC001486 |
| <b>ETIM 8.0</b>       | EC001486 |
| <b>UNSPSC 16.0901</b> | 41112113 |

### Dimensional drawing (Dimensions in mm (inch))

Through hollow shaft, cable



General tolerances according to DIN ISO 2768-mk

① Cable diameter = 5.6 mm +/- 0.2 mm bend radius = 30 mm

PIN assignment



| PIN<br>Male connector M12, 8-pin | PIN<br>Male connector M23, 12-pin | Wire colors (cable connection) | TTL/HTL signal      | Sin/Cos 1.0 V <sub>pp</sub> | Explanation   |
|----------------------------------|-----------------------------------|--------------------------------|---------------------|-----------------------------|---|
| 1                                | 6                                 | Brown                          | $\bar{A}$           | COS-                        | Signal wire   |
| 2                                | 5                                 | White                          | A                   | COS+                        | Signal wire   |
| 3                                | 1                                 | Black                          | $\bar{B}$           | SIN-                        | Signal wire   |
| 4                                | 8                                 | Pink                           | B                   | SIN+                        | Signal wire   |
| 5                                | 4                                 | Yellow                         | $\bar{Z}$           | $\bar{Z}$                   | Signal wire   |
| 6                                | 3                                 | Purple                         | Z                   | Z                           | Signal wire   |
| 7                                | 10                                | Blue                           | GND                 | GND                         | Ground connection   |
| 8                                | 12                                | Red                            | +U <sub>S</sub>     | +U <sub>S</sub>             | Supply voltage  |
| -                                | 9                                 | -                              | N.c.                | N.c.                        | Not assigned  |
| -                                | 2                                 | -                              | N.c.                | N.c.                        | Not assigned  |
| -                                | 11                                | -                              | N.c.                | N.c.                        | Not assigned  |
| -                                | 7 <sup>1)</sup>                   | Orange                         | 0-SET <sup>1)</sup> | N.c.                        | Set zero pulse <sup>1)</sup>  |
| Screen                           | Screen                            | Screen                         | Screen              | Screen                      | Screen connected to housing on encoder side. Connected to ground on control side. |

1)

For electrical interfaces only: M, U, V, W with 0-SET function on PIN 7 on M23 plug. The 0-SET input is used to set the zero pulse to the current shaft position. If the 0-SET input is applied to US for longer than 250 ms after it has previously been open or applied to GND for at least 1,000 ms, the current shaft position is assigned zero pulse signal "Z".

### Diagrams

Mechanical zero pulse width 1° to 359° programmable. Width of the zero pulse in relation to a mechanical revolution of the shaft.



| Supply voltage | Output               |
|----------------|----------------------|
| 4,5 V ... 32 V | TTL/HTL programmable |

Electrical zero pulse width can be configured to 90°, 180°, or 270°. Width of the zero pulse in relation to a pulse period.



Cw with view on the encoder shaft in direction "A", compare dimensional drawing.

| Supply voltage | Output               |
|----------------|----------------------|
| 4,5 V ... 32 V | TTL/HTL programmable |





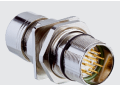
Maximum revolution range



Recommended accessories

Other models and accessories → [www.sick.com/DFS60](http://www.sick.com/DFS60)

|  | Brief description  | Type             | Part no. |
|--|--|------------------|----------|
| <b>Programming and configuration tools</b> |  |                  |          |
|  | USB programming unit, for programmable SICK encoders AFS60, AFM60, DFS60, VFS60, DFV60 and wire draw encoders with programmable encoders   | PGT-08-S         | 1036616  |
|  | Programming unit display for programmable SICK DFS60, DFV60, AFS/AFM60, AHS/AHM36 encoders, and wire draw encoder with DFS60, AFS/AFM60 and AHS/AHM36. Compact dimensions, low weight, and intuitive operation.  | PGT-10-Pro       | 1072254  |
| <b>Flanges</b>                             |  |                  |          |
|  | Standard stator coupling   | BEF-DS00XFX      | 2056812  |
| <b>Other mounting accessories</b>          |  |                  |          |
|  | Bearing bracket for hollow shaft encoders, fastening screws included the Bearing Block is intended for very large radial and axial shaft loads. Particularly for application on: Belt pulleys, Chain pinions, Friction wheels. It is designed this way to enable fitting of encoder with blind hollow shaft with ø 12 mm., fastening screws included | BEF-FA-B12-010   | 2042728  |
|  | Clamping ring for metal hollow shaft <sup>1)</sup> , metal   | BEF-KR-M         | 2064709  |
| <b>Plug connectors and cables</b>          |  |                  |          |
|  | Head A: female connector, JST, 8-pin, straight<br>Head B: Flying leads<br>Cable: Incremental, SSI, PUR, halogen-free, shielded, 5 m  | DOL-0J08-G05MAA3 | 2046876  |

|   | Brief description   | Type             | Part no. |
|---|---|------------------|----------|
|   | Head A: female connector, JST, 8-pin, straight<br>Head B: Flying leads<br>Cable: Incremental, SSI, PUR, halogen-free, shielded, 0.5 m   | DOL-0J08-G0M5AA3 | 2046873  |
|   | Head A: female connector, JST, 8-pin, straight<br>Head B: Flying leads<br>Cable: Incremental, SSI, PUR, halogen-free, shielded, 10 m  | DOL-0J08-G10MAA3 | 2046877  |
|   | Head A: female connector, JST, 8-pin, straight<br>Head B: Flying leads<br>Cable: SSI, Incremental, PUR, halogen-free, shielded, 1.5 m   | DOL-0J08-G1M5AA6 | 2048590  |
|   | Head A: female connector, JST, 8-pin, straight<br>Head B: Flying leads<br>Cable: SSI, Incremental, PUR, halogen-free, shielded, 3 m   | DOL-0J08-G3M0AA6 | 2048591  |
|    | Head A: female connector, terminal box, 8-pin, straight<br>Head B: male connector, D-Sub, 9-pin, straight<br>Cable: SSI + incremental, PVC, shielded, 0.5 m<br>Programming adapter cable for programming tool PGT-10-Pro and PGT-08-S | DSL-0D08-G0M5AC3 | 2061739  |
|    | Head A: female connector, JST, 8-pin, straight<br>Head B: male connector, M23, 12-pin, straight<br>Cable: Incremental, PUR, halogen-free, shielded, 1 m   | STL-2312-G01MAA3 | 2061622  |
|   | Head A: female connector, JST, 8-pin, straight<br>Head B: male connector, M23, 12-pin, straight<br>Cable: Incremental, PUR, halogen-free, shielded, 2 m   | STL-2312-G02MAA3 | 2061504  |
|   | Head A: female connector, JST, 8-pin, straight<br>Head B: male connector, M23, 12-pin, straight<br>Cable: Incremental, PUR, halogen-free, shielded, 0.35 m  | STL-2312-GM35AA3 | 2061621  |
|   | Head A: male connector, M12, 8-pin, straight, A-coded<br>Cable: Incremental, shielded   | STE-1208-GA01    | 6044892  |
|  | Head A: male connector, M23, 12-pin, straight<br>Cable: HIPERFACE®, SSI, Incremental, shielded  | STE-2312-G01     | 2077273  |
|  |   | STE-2312-GX      | 6028548  |



## SICK AT A GLANCE

SICK is one of the leading manufacturers of intelligent sensors and sensor solutions for industrial applications. A unique range of products and services creates the perfect basis for controlling processes securely and efficiently, protecting individuals from accidents and preventing damage to the environment.

We have extensive experience in a wide range of industries and understand their processes and requirements. With intelligent sensors, we can deliver exactly what our customers need. In application centers in Europe, Asia and North America, system solutions are tested and optimized in accordance with customer specifications. All this makes us a reliable supplier and development partner.

Comprehensive services complete our offering: SICK LifeTime Services provide support throughout the machine life cycle and ensure safety and productivity.

For us, that is “Sensor Intelligence.”

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