

DFS60S-S40A01024

DFS60S Pro

INCREMENTAL ENCODERS





Ordering information

| Туре | Part no. |
|------------------|----------|
| DFS60S-S40A01024 | 1069518 |

Other models and accessories → www.sick.com/DFS60S_Pro

Illustration may differ



Detailed technical data

Safety-related parameters

| Carety related parameters | | | |
|--|--|--|--|
| Safety integrity level | SIL 2 (IEC 61508), SILCL2 (IEC 62061) 1) | | |
| Performance level | PL d (EN ISO 13849) 1) | | |
| Category | 3 (EN ISO 13849) | | |
| PFH _D : Probability of dangerous failure per hour | 1.7 x 10 ^{-8 2)} | | |
| T _M (mission time) | 20 years (EN ISO 13849) | | |
| Safety-related measuring step | 0.09°, Quadrature analysis | | |
| Safety-related accuracy | ± 0.09° | | |

¹⁾ For more detailed information on the exact configuration of your machine/unit, please consult your relevant SICK branch office.

Performance

| Sine/cosine periods per revolution | 1,024 |
|------------------------------------|---|
| Measuring step | 0.3 ", For interpolation of the sine/cosine signals with e.g. 12 bit $^{1)}$ |
| Integral non-linearity | Typ. \pm 45 $^{\prime\prime}$ (without mechanical tension of the stator coupling) |
| Differential non-linearity | ± 7 " |

¹⁾ Not safety-related.

Interfaces

| Communication interface | Incremental |
|--------------------------------|---------------------|
| Communication Interface detail | Sin/Cos 1) |
| Initialization time | 50 ms ²⁾ |
| Output frequency | ≤ 153.6 kHz |

^{1) 1.0} V_{SS} (differential).

²⁾ The values displayed apply to a diagnostic degree of coverage of 99%, which must be achieved by the external drive system and 95 °C operating temperature.

 $^{^{\}rm 2)}\,{\rm Valid}$ signals can be read once this time has elapsed.

| Power consumption | ≤ 0.7 W (without load) |
|-------------------|------------------------|
| Load resistance | ≥ 120 Ω |

 $^{^{1)}}$ 1.0 V_{SS} (differential).

Electrical data

| Connection type | Male connector, M23, 12-pin, radial |
|---|---|
| Supply voltage | 4.5 32 V |
| Reference signal, number | 1 |
| Reference signal, position | 90°, electronically, gated with Sinus and Cosinus |
| Reverse polarity protection | ✓ |
| Protection class | III (according to DIN EN 61140) |
| Short-circuit protection of the outputs | ✓ ¹⁾ |

 $^{^{(1)}}$ Short-circuit to another channel or GND permitted for max. 30 s. In the case of U_S \leq 12 V additional short-circuit to U_S permitted for max. 30 s.

Mechanical data

| Mechanical design | Solid shaft, face mount flange |
|--------------------------------|---|
| Shaft diameter | 10 mm With face |
| Shaft length | 19 mm |
| Weight | Approx. 0.3 kg ¹⁾ |
| Shaft material | Stainless steel |
| Flange material | Aluminum |
| Housing material | Aluminum die cast |
| Start up torque | ≤ 0.5 Ncm (+20 °C) |
| Operating torque | ≤ 0.3 Ncm (+20 °C) |
| Permissible shaft loading | 80 N (radial) 40 N (axial) |
| Operating speed | ≤ 9,000 min ^{-1 2)} |
| Moment of inertia of the rotor | 8 gcm ² |
| Bearing lifetime | 3.6 x 10 ⁹ revolutions ³⁾ |
| Angular acceleration | ≤ 500,000 rad/s² |

 $^{^{1)}}$ Based on encoder with male connector.

Ambient data

| EMC | According to EN 61000-6-2, EN 61000-6-3 and IEC 61326-3-1 | | |
|-------------------------------|---|--|--|
| Enclosure rating | IP65 (IEC 60529) ¹⁾ | | |
| Permissible relative humidity | 90 % (Condensation not permitted) | | |
| Operating temperature range | -30 °C +95 °C ²⁾ | | |

 $^{^{1)}}$ With male connector and mating connector fitted minimum IP65.

 $^{^{2)}}$ Valid signals can be read once this time has elapsed.

 $^{^{2)}}$ Allow for self-heating of approx. 3.0 K per 1,000 rpm regarding the permissible operating temperature.

 $^{^{}m 3)}$ On maximum operating speed and temperature.

²⁾ Allow for self-heating of approx. 3.0 K per 1,000 rpm regarding the permissible operating temperature.

³⁾ Checked to operation with vector length monitoring.

| Storage temperature range | -30 °C +85 °C, without package |
|---------------------------|---|
| Resistance to shocks | 100 g, 6 ms (EN 60068-2-27) ³⁾ |
| Resistance to vibration | 10 g, 10 Hz 1,000 Hz (EN 60068-2-6) |

 $^{^{1)}\,\}mathrm{With}$ male connector and mating connector fitted minimum IP65.

Classifications

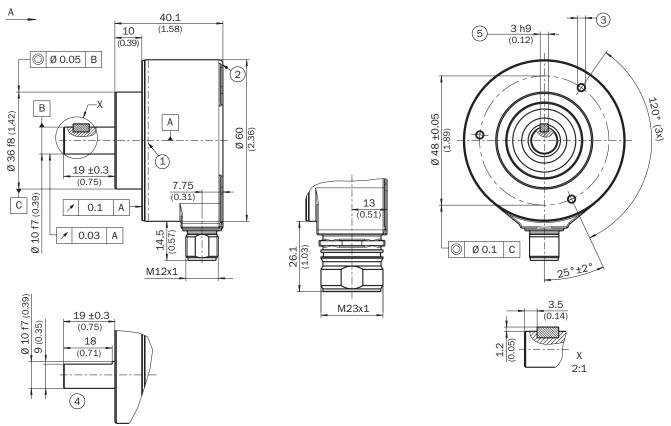
| eCl@ss 5.0 | 27270501 |
|----------------|----------|
| eCl@ss 5.1.4 | 27270501 |
| eCl@ss 6.0 | 27270590 |
| eCl@ss 6.2 | 27270590 |
| eCI@ss 7.0 | 27270501 |
| eCl@ss 8.0 | 27270501 |
| eCl@ss 8.1 | 27270501 |
| eCI@ss 9.0 | 27270501 |
| eCl@ss 10.0 | 27270501 |
| eCl@ss 11.0 | 27270501 |
| eCl@ss 12.0 | 27270501 |
| ETIM 5.0 | EC001486 |
| ETIM 6.0 | EC001486 |
| ETIM 7.0 | EC001486 |
| ETIM 8.0 | EC001486 |
| UNSPSC 16.0901 | 41112113 |
| | |

²⁾ Allow for self-heating of approx. 3.0 K per 1,000 rpm regarding the permissible operating temperature.

³⁾ Checked to operation with vector length monitoring.

Dimensional drawing (Dimensions in mm (inch))

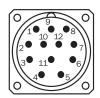
Solid shaft, face mount flange, M12 and M23 radial male connector



General tolerances according to DIN ISO 2768-mk

- ① Operating temperature measuring point (freely selectable, around the housing surface area in each case, approx. 3 mm away from flange)
- ② Measuring point vibration (respectively at the housing face. approx. 3 mm away from the cover edge)
- ③ M3 / M4 (3x) (6 mm deep)
- 4 Shaft with flat
- ⑤ Square key, DIN 6885-A 3x3x6

PIN assignment



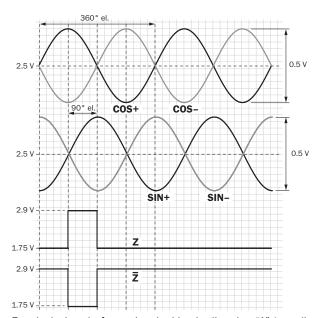
View of M23 male device connector on encoder

| PIN Male connector M12, 8-pin | PIN Male connec- tor M23, 12-pin | Wire colors (ca- ble connection) | Signal | Explanation |
|----------------------------------|--|-------------------------------------|--------|-------------|
| 1 | 6 | Brown | - COS | Signal wire |
| 2 | 5 | White | + COS | Signal wire |
| 3 | 1 | Black | - SIN | Signal wire |
| 4 | 8 | Pink | + SIN | Signal wire |

| PIN Male connector M12, 8-pin | PIN Male connec- tor M23, 12-pin | Wire colors (ca- ble connection) | Signal | Explanation |
|----------------------------------|--|-------------------------------------|----------------|---|
| 5 | 4 | Yellow | | Signal (do not use for safety operating mode) |
| 6 | 3 | Violet | Z | Signal (do not use for safety operating mode) |
| 7 | 10 | Blue | GND | Ground connection |
| 8 | 12 | Red | U _S | Supply voltage (volt-free to housing) |
| - | 9 | - | N.C. | Not assigned |
| - | 2 | - | N.C. | Not assigned |
| - | 11 | - | N.C. | Not assigned |
| - | 7 | - | N.C. | Not assigned |
| Screen | Screen | Screen | Screen | Screen connected to encoder housing Screen connected to housing on encoder side. Connected to ground on control side. |

Diagrams

Signal SIN/COS before differential generation

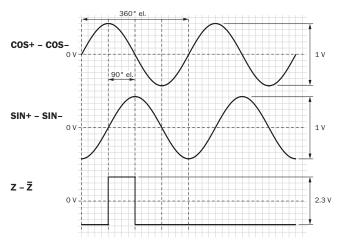


For clockwise shaft rotation, looking in direction "A" (see dimensional drawing)

| Signal | Interface signals | Signal before differ- ential generation At load 120 Ω | Signal offset |
|----------------------------------|----------------------|---|---------------|
| + SIN - SIN + COS - COS | Analog, differential | $0.5 V_{SS} \pm 20 \%$ | 2,5 V ± 10 % |

| Signal | Interface signals | Signal before differ- ential generation At load 120 Ω | Signal offset |
|---------|----------------------|---|---------------|
| Z Z_ | Digital differential | Low: 1,75 V \pm 15 %, High: 2,90 V \pm 15 % | |

Signal SIN/COS after differential generation



For clockwise shaft rotation, looking in direction "A" (see dimensional drawing)

| Supply voltage | Output |
|----------------|-----------------------------|
| 4,5 V 5,5 V | Sin/Cos 1.0 V _{PP} |

SICK AT A GLANCE

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