

# AFM60I-S4SK004096

AFS/AFM60 SSI

**ABSOLUTE ENCODERS** 





# Ordering information

Туре	Part no.
AFM60I-S4SK004096	1114389

Other models and accessories → www.sick.com/AFS\_AFM60\_SSI

Illustration may differ



#### Detailed technical data

#### Performance

Number of steps per revolution (max. resolution)	4,096 (12 bit)
Number of revolutions	4,096 (12 bit)
$\label{eq:max_max} \begin{tabular}{ll} Max. resolution (number of steps per revolution x number of revolutions) \end{tabular}$	12 bit x 12 bit (4,096 x 4,096)
Measuring step deviation	± 0.008° pulses 100 10,000
Error limits G	0.03° <sup>1)</sup>
Repeatability standard deviation $\boldsymbol{\sigma}_{r}$	0.002° <sup>2)</sup>

<sup>1)</sup> In accordance with DIN ISO 1319-1, position of the upper and lower error limit depends on the installation situation, specified value refers to a symmetrical position, i.e. deviation in upper and lower direction is the same.

#### Interfaces

Communication interface	SSI
Communication Interface detail	SSI + Sin/Cos
Initialization time	50 ms <sup>1)</sup>
Position forming time	< 1 µs
Code type	Gray
Code sequence parameter adjustable	CW/CCW (V/R)
Interface signals	Sin+, Sin-, Cos+, Cos-: analog, differential
Clock frequency	2 MHz <sup>2)</sup>
Set (electronic adjustment)	H-active (L = $0 - 3 \text{ V}$ , H = $4,0 - U_s \text{ V}$ )
CW/CCW (counting sequence when turning)	L-active (L = 0 - 1,5 V, H = 2,0 - Us V)
Sine/cosine periods per revolution	1,024

 $<sup>^{1)}\,\</sup>mathrm{Valid}$  positional data can be read once this time has elapsed.

 $<sup>^{2)}</sup>$  In accordance with DIN ISO 55350-13; 68.3% of the measured values are inside the specified area.

 $<sup>^{2)}\,\</sup>mathrm{SSI}$  max. clock frequency 2 MHz, and min. LOW level (Clock+): 500 ns.

Output frequency	≤ 200 kHz
Load resistance	≥ 120 Ω
Signal before differential generation	$0.5 V_{pp}$ , ± 20 %, 120 $\Omega$
Signal offset before differential generation	2.5 V ± 10 %
Signal after differential generation	1 $V_{pp}$ , $\pm$ 20 %, 120 $\Omega$

 $<sup>^{1)}\,\</sup>mathrm{Valid}$  positional data can be read once this time has elapsed.

#### Electrical data

Connection type	Cable, 12-wire, radial, 1.5 m
Supply voltage	4.5 32 V DC
Power consumption	≤ 0.5 W (without load)
Reverse polarity protection	✓
MTTFd: mean time to dangerous failure	250 years (EN ISO 13849-1) <sup>1)</sup>

<sup>1)</sup> This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40°C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

#### Mechanical data

Mechanical design	Solid shaft, face mount flange
Shaft diameter	10 mm
Shaft length	19 mm
Weight	0.5 kg <sup>1)</sup>
Shaft material	Stainless steel V2A
Flange material	Stainless steel V2A
Housing material	Stainless steel V2A
Start up torque	1 Ncm (+20 °C)
Operating torque	0.5 Ncm (+20 °C)
Permissible shaft loading	80 N (radial) 40 N (axial)
Operating speed	9,000 min <sup>-1 2)</sup>
Moment of inertia of the rotor	6.2 gcm <sup>2</sup>
Bearing lifetime	3.0 x 10^9 revolutions
Angular acceleration	≤ 500,000 rad/s²

 $<sup>^{1)}</sup>$  Based on devices with male connector.

#### Ambient data

EMC	According to EN 61000-6-2 and EN 61000-6-3 <sup>1)</sup>
Enclosure rating	IP67, shaft side (IEC 60529) IP67, housing side, cable connection (IEC 60529)
Permissible relative humidity	90 % (Condensation not permitted)

<sup>&</sup>lt;sup>1)</sup> EMC according to the standards quoted is achieved if shielded cables are used.

<sup>&</sup>lt;sup>2)</sup> SSI max. clock frequency 2 MHz, and min. LOW level (Clock+): 500 ns.

 $<sup>^{2)}</sup>$  Allow for self-heating of 3.3 K per 1,000 rpm when designing the operating temperature range.

<sup>&</sup>lt;sup>2)</sup> Stationary position of the cable.

 $<sup>^{</sup>m 3)}$  Flexible position of the cable.

Operating temperature range	-40 °C +100 °C <sup>2)</sup> -30 °C +100 °C <sup>3)</sup>
Storage temperature range	-40 °C +100 °C, without package
Resistance to shocks	100 g, 6 ms (EN 60068-2-27)
Resistance to vibration	10 g, 10 Hz 2,000 Hz (EN 60068-2-6)

 $<sup>^{1)}</sup>$  EMC according to the standards quoted is achieved if shielded cables are used.  $^{2)}$  Stationary position of the cable.

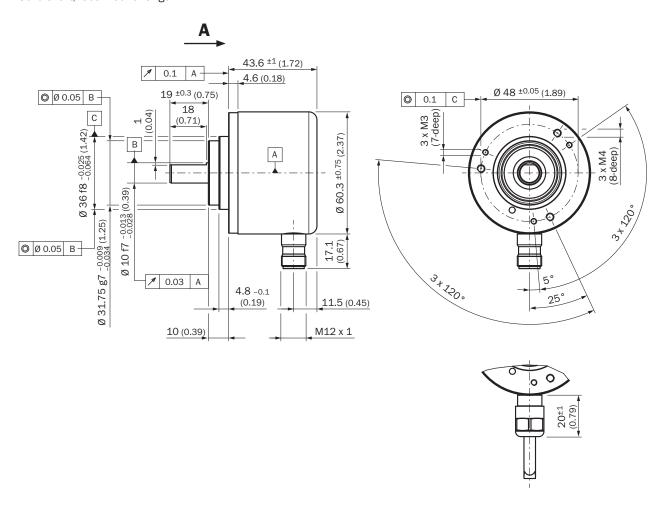
# Classifications

eCl@ss 5.0	27270502
eCl@ss 5.1.4	27270502
eCl@ss 6.0	27270590
eCl@ss 6.2	27270590
eCl@ss 7.0	27270502
eCl@ss 8.0	27270502
eCl@ss 8.1	27270502
eCl@ss 9.0	27270502
eCl@ss 10.0	27270502
eCl@ss 11.0	27270502
eCl@ss 12.0	27270502
ETIM 5.0	EC001486
ETIM 6.0	EC001486
ETIM 7.0	EC001486
ETIM 8.0	EC001486
UNSPSC 16.0901	41112113

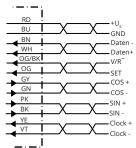
<sup>3)</sup> Flexible position of the cable.

# Dimensional drawing (Dimensions in mm (inch))

Solid shaft, face mount flange



# PIN assignment



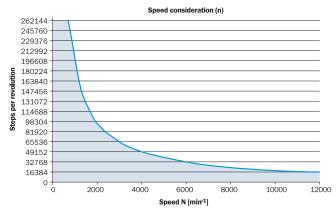
Male connector M12, 8-pin	Connector M12, 12-pin	Wire colors (ca- ble connection)	Signal Incremental	Signal Sin/Cos	Explanation
3	1	Orange/black	V/R	V/R	Sequence in direction of rotation
2	2	White	Data +	Data +	Interface signals
1	3	Brown	Data -	Data -	Interface signals
6	4	Violet	Clock -	Clock -	Interface signals

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Male connector M12, 8-pin	Connector M12, 12-pin	Wire colors (ca- ble connection)	Signal Incremental	Signal Sin/Cos	Explanation
8	5	Red	+U <sub>S</sub>	+U <sub>S</sub>	Operating voltage
-	6	Gray	A	+ COS	Signal cable
-	7	Green	A <sup>-</sup>	- COS	Signal cable
4	8	Pink	В	+ SIN	Signal cable
-	9	Black	В	- SIN	Signal cable
-	10	Orange	SET	SET	Electronic adjust- ment
5	11	Yellow	Clock +	Clock +	Interface signals
7	12	Blue	GND	GND	Ground connection
			Screen	Screen	Screen connected to housing on encoder side. Connected to ground on control side.

# Diagrams



The maximum speed is also dependent on the shaft type.  $% \label{eq:continuous} % \begin{subarray}{ll} \end{subarray} % \begin{subarray}{ll} \end$ 

# SICK AT A GLANCE

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