

## DFS60E-TEEL02048 DFS60



## Ordering information

| Type | Part no. |
| :---: | :---: |
| DFS60E-TEEL02048 | 1069459 |

Other models and accessories $\rightarrow$ www.sick.com/DFS60

Illustration may differ
( $\in$

## Detailed technical data

## Performance

| Pulses per revolution | $2,048^{1)}$ |
| :--- | :--- |
| Measuring step | $90^{\circ}$, electric/pulses per revolution $^{\text {Measuring step deviation at binary number }}$ |
| $\pm 0.15^{\circ}$ <br> of lines | $\pm 0.3^{\circ}$ |
| Error limits |  |
| 1) See maximum revolution range. | Incremental |
| Interfaces | $\mathrm{HTL} /$ Push pull |
| Communication interface | $6-\mathrm{channel}$ |
| Communication Interface detail | 40 ms |
| Number of signal channels | $\leq 300 \mathrm{kHz}$ |
| Initialization time | $\leq 30 \mathrm{~mA}$ |
| Output frequency | $\leq 0.5 \mathrm{~W}$ (without load) |
| Load current |  |
| Power consumption |  |

## Electrical data

| Connection type | Cable, 8-wire, universal, $3 \mathrm{~m}^{\text {1) }}$ |
| :--- | :--- |
| Supply voltage | $10 \ldots 32 \mathrm{~V}$ |
| Reference signal, number | 1 |
| Reference signal, position | $90^{\circ}$, electric, logically gated with A and B |
| Reverse polarity protection | $\boldsymbol{\checkmark}$ |
| Short-circuit protection of the outputs | $\boldsymbol{J}^{2)}$ |
| MTTFd: mean time to dangerous failure | 300 years (EN ISO 13849-1) ${ }^{\text {2) }}$ |

[^0]Mechanical data

| Mechanical design | Through hollow shaft |
| :---: | :---: |
| Shaft diameter | 12 mm |
| Weight | $+0.2 \mathrm{~kg}$ |
| Shaft material | Stainless steel |
| Flange material | Aluminum |
| Housing material | Aluminum die cast |
| Start up torque | $0.8 \mathrm{Ncm}\left(+20^{\circ} \mathrm{C}\right)$ |
| Operating torque | $0.6 \mathrm{Ncm}\left(+20^{\circ} \mathrm{C}\right)$ |
| Permissible movement static | $\pm 0.3 \mathrm{~mm}$ (radial) <br> $\pm 0.5 \mathrm{~mm}$ (axial) |
| Permissible movement dynamic | $\pm 0.1 \mathrm{~mm}$ (radial) <br> $\pm 0.2 \mathrm{~mm}$ (axial) |
| Operating speed | $\left.\leq 6,000 \mathrm{~min}^{-1} 1\right)$ |
| Moment of inertia of the rotor | $40 \mathrm{gcm}{ }^{2}$ |
| Bearing lifetime | $3.6 \times 10^{\wedge} 10$ revolutions |
| Angular acceleration | $\leq 500,000 \mathrm{rad} / \mathrm{s}^{2}$ |

${ }^{1)}$ Allow for self-heating of 3.3 K per 1,000 rpm when designing the operating temperature range.

## Ambient data

| EMC | According to EN 61000-6-2 and EN 61000-6-4 |
| :--- | :--- |
| Enclosure rating | IP65, housing side, cable connection (IEC 60529) <br> IP65, shaft side (IEC 60529) |
| Permissible relative humidity | $90 \%$ (Condensation not permitted) |
| Operating temperature range | $0^{\circ} \mathrm{C} \ldots+85^{\circ} \mathrm{C}$ |
| Storage temperature range | $-40^{\circ} \mathrm{C} \ldots+100^{\circ} \mathrm{C}$, without package |
| Resistance to shocks | $50 \mathrm{~g}, 6 \mathrm{~ms}(\mathrm{EN} \mathrm{60068-2-27)}$ |
| Resistance to vibration | $20 \mathrm{~g}, 10 \mathrm{~Hz} \ldots 2,000 \mathrm{~Hz}(\mathrm{EN} \mathrm{60068-2-6)}$ |

## Classifications

| eCI@ss 5.0 | 27270501 |
| :--- | :--- |
| eCI@ss 5.1.4 | 27270501 |
| eCI@ss 6.0 | 27270590 |
| eCI@ss 6.2 | 27270590 |
| eCI@ss 7.0 | 27270501 |
| eCI@ss 8.0 | 27270501 |
| eCI@ss 8.1 | 27270501 |
| eCI@ss 9.0 | 27270501 |
| eCI@ss 10.0 | 27270501 |
| eCI@ss 11.0 | 27270501 |
| eCI@ss 12.0 | 27270501 |
| ETIM 5.0 | EC001486 |
| ETIM 6.0 | EC001486 |
| ETIM 7.0 | EC001486 |


| ETIM 8.0 | EC001486 |
| :--- | :--- |
| UNSPSC $\mathbf{1 6 . 0 9 0 1}$ | 41112113 |

Dimensional drawing (Dimensions in mm (inch))
Through hollow shaft, cable


General tolerances according to DIN ISO 2768-mk
(1) Cable diameter $=5.6 \mathrm{~mm}+/-0.2 \mathrm{~mm}$ bend radius $=30 \mathrm{~mm}$

PIN assignment


| PIN Male connector M12, 8 -pin | PIN <br> Male connector M23, 12-pin | Wire colors (cable connection) | TTL/HTL signal | Sin/Cos 1.0 VPP | Explanation |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | 6 | Brown | ${ }^{-} \mathrm{A}$ | cos- | Signal wire |
| 2 | 5 | White | A | cos+ | Signal wire |
| 3 | 1 | Black | ${ }^{-}$B | SIN- | Signal wire |
| 4 | 8 | Pink | B | SIN+ | Signal wire |


| PIN <br> Male connector M12, 8-pin | PIN <br> Male connector M23, 12-pin | Wire colors (cable connection) | TTL/HTL signal | Sin/Cos 1.0 VPP | Explanation |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 5 | 4 | Yellow | ${ }^{-}$Z | ${ }^{-}$Z | Signal wire |
| 6 | 3 | Purple | Z | Z | Signal wire |
| 7 | 10 | Blue | GND | GND | Ground connection |
| 8 | 12 | Red | $+\mathrm{U}_{S}$ | $+\mathrm{U}_{\mathrm{S}}$ | Supply voltage |
| - | 9 | - | N.c. | N.c. | Not assigned |
| - | 2 | - | N.c. | N.c. | Not assigned |
| - | 11 | - | N.c. | N.c. | Not assigned |
| - | $7^{1)}$ | Orange | O-SET ${ }^{1)}$ | N.c. | Set zero pulse 1) |
| Screen | Screen | Screen | Screen | Screen | Screen connected to housing on encoder side. Connected to ground on control side. |
| 1) |  |  |  |  |  |
| For electrical interfaces only: M, U, V, W with 0-SET function on PIN 7 on M23 plug. The 0-SET input is used to set the zero pulse to the current shaft position. If the 0-SET input is applied to US for longer than 250 ms after it has previously been open or applied to GND for at least $1,000 \mathrm{~ms}$, the current shaft position is assigned zero pulse signal "Z". |  |  |  |  |  |

## Diagrams

Signal outputs


CW with view on the encoder shaft in direction "A", compare dimensional drawing.

Maximum revolution range


| Supply voltage |  |
| :---: | :--- |
| $4,5 \mathrm{~V} \ldots 5,5 \mathrm{~V}$ | TTL |
| $10 \mathrm{~V} \ldots 32 \mathrm{~V}$ | TTL |
| $10 \mathrm{~V} \ldots 32 \mathrm{~V}$ | HTL |

## Recommended accessories

Other models and accessories $\rightarrow$ www.sick.com/DFS60

|  | Brief description | Type | Part no . |
| :---: | :---: | :---: | :---: |
| Flanges |  |  |  |
|  | Standard stator coupling | BEF-DSOOXFX | 2056812 |
| Other mounting accessories |  |  |  |
|  | Bearing bracket for hollow shaft encoders, fastening screws included the Bearing Block is intended for very large radial and axial shaft loads. Particularly for application on: Belt pulleys, Chain pinions, Friction wheels. It is designed this way to enable fitting of encoder with blind hollow shaft with ø 12 mm ., fastening screws included | BEF-FA-B12-010 | 2042728 |
|  | Clamping ring for metal hollow shaft ${ }^{\mathrm{R}}$, metal | BEF-KR-M | 2064709 |
| Plug connectors and cables |  |  |  |
| $12$ | Head A: female connector, JST, 8-pin, straight <br> Head B: Flying leads <br> Cable: Incremental, SSI, PUR, halogen-free, shielded, 5 m | DOL-0J08-G05MAA3 | 2046876 |
|  | Head A: female connector, JST, 8-pin, straight <br> Head B: Flying leads <br> Cable: Incremental, SSI, PUR, halogen-free, shielded, 0.5 m | DOL-0J08-G0M5AA3 | 2046873 |


|  | Brief description | Type | Part no . |
| :---: | :---: | :---: | :---: |
| $C^{x}$ | Head A: female connector, JST, 8-pin, straight <br> Head B: Flying leads <br> Cable: Incremental, SSI, PUR, halogen-free, shielded, 10 m | DOL-0J08-G10MAA3 | 2046877 |
|  | Head A: female connector, JST, 8-pin, straight <br> Head B: Flying leads <br> Cable: SSI, Incremental, PUR, halogen-free, shielded, 1.5 m | DOL-0J08-G1M5AA6 | 2048590 |
|  | Head A: female connector, JST, 8-pin, straight <br> Head B: Flying leads <br> Cable: SSI, Incremental, PUR, halogen-free, shielded, 3 m | DOL-OJ08-G3MOAA6 | 2048591 |
|  | Head A: female connector, JST, 8-pin, straight Head B: male connector, M23, 12-pin, straight Cable: Incremental, PUR, halogen-free, shielded, 1 m | STL-2312-G01MAA3 | 2061622 |
|  | Head A: female connector, JST, 8-pin, straight Head B: male connector, M23, 12-pin, straight Cable: Incremental, PUR, halogen-free, shielded, 2 m | STL-2312-G02MAA3 | 2061504 |
|  | Head A: female connector, JST, 8-pin, straight Head B: male connector, M23, 12-pin, straight Cable: Incremental, PUR, halogen-free, shielded, 0.35 m | STL-2312-GM35AA3 | 2061621 |
|  | Head A: male connector, M12, 8-pin, straight, A-coded Cable: Incremental, shielded | STE-1208-GA01 | 6044892 |
|  | Head A: male connector, M23, 12-pin, straight Cable: HIPERFACE ${ }^{\circledR}$, SSI, Incremental, shielded | STE-2312-G01 | 2077273 |
|  |  | STE-2312-GX | 6028548 |

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We have extensive experience in a wide range of industries and understand their processes and requirements. With intelligent sensors, we can deliver exactly what our customers need. In application centers in Europe, Asia and North America, system solutions are tested and optimized in accordance with customer specifications. All this makes us a reliable supplier and development partner.

Comprehensive services complete our offering: SICK LifeTime Services provide support throughout the machine life cycle and ensure safety and productivity.

For us, that is "Sensor Intelligence."

## WORLDWIDE PRESENCE:

Contacts and other locations www.sick.com


[^0]:    ${ }^{1)}$ The universal cable connection is positioned so that it is possible to lay it without bends in a radial or axial direction.
    ${ }^{2)}$ Short-circuit opposite to another channel, US or GND permissable for maximum 30 s .
    ${ }^{3)}$ This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature $40^{\circ} \mathrm{C}$, frequency of use $8760 \mathrm{~h} / \mathrm{a}$. All electronic failures are considered hazardous. For more information, see document no. 8015532.

