

INCREMENTAL ENCODERS



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Ordering information

Туре	Part no.
DBS60E-TECCD1024	1112146

Other models and accessories -> www.sick.com/DBS60

Illustration may differ



Detailed technical data

Performance

Pulses per revolution	1,024		
Measuring step	\leq 90°, electric/pulses per revolution		
Measuring step deviation	± 18° / pulses per revolution		
Error limits	Measuring step deviation x 3		
Duty cycle	$\leq 0.5 \pm 5 \%$		
Interfaces			
Communication interface	Incremental		

Communication Interface detail	TTL / RS-422
Number of signal channels	6-channel
Initialization time	< 5 ms ¹⁾
Output frequency	+ 300 kHz ²⁾
Load current	≤ 30 mA, per channel
Power consumption	\leq 0.5 W (without load)

 $^{\mbox{\sc 1})}$ Valid signals can be read once this time has elapsed.

 $^{2)}$ Up to 450 kHz on request.

Electrical data	
Connection type	Male connector, M12, 8-pin, radial
Supply voltage	10 30 V
Reference signal, number	1
Reference signal, position	90°, electric, logically gated with A and B
Reverse polarity protection	✓
Short-circuit protection of the outputs	✓ ¹⁾

 $^{1)}$ Short-circuit opposite to another channel or GND permissible for max. 60 s. No protection signal against U $_{\rm S}$

²⁾ This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40 °C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

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MTTFd: mean time to dangerous failure
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500 years (EN ISO 13849-1) 2)

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Mechanical data

Mechanical design	Through hollow shaft, Front clamp	
Shaft diameter	12 mm	
Flange type / stator coupling	1-sided stator coupling, slot, screw hole circle radius 31.5-48.5 mm	
Weight	+ 0.25 kg ¹⁾	
Shaft material	Stainless steel	
Flange material	Aluminum	
Housing material	Aluminum	
Start up torque	+ 0.5 Ncm (+20 °C)	
Operating torque	0.4 Ncm (+20 °C)	
Permissible movement static	± 0.3 mm (radial) ± 0.5 mm (axial) ²⁾	
Permissible movement dynamic	\pm 0.1 mm (radial) \pm 0.2 mm (axial) ²⁾	
Operating speed	6,000 min ^{-1 3)}	
Maximum operating speed	9,000 min ^{-1 4)}	
Moment of inertia of the rotor	50 gcm ²	
Bearing lifetime	3.6 x 10 ⁹ revolutions	
Angular acceleration	≤ 500,000 rad/s²	

 $^{\left(1\right) }$ Based on encoder with male connector or cable with male connector.

 $^{\rm 2)}$ Not apllicable for stator coupling type C and K.

 $^{\rm 3)}$ Allow for self-heating of 2.6 K per 1,000 rpm when designing the operating temperature range.

⁴⁾ Maximum speed which does not cause mechanical damage to the encoder. Impact on the service life and signal quality is possible. Please note the maximum output frequency.

Ambient data

EMC	According to EN 61000-6-2 and EN 61000-6-3
Enclosure rating	IP65, housing side (IEC 60529) ¹⁾ IP65, shaft side (IEC 60529)
Permissible relative humidity	90 % (Condensation not permitted)
Operating temperature range	-30 °C +100 °C, at maximum 3,000 pulses per revolution ²⁾
Storage temperature range	-40 °C +100 °C, without package
Resistance to shocks	250 g, 3 ms (EN 60068-2-27)
Resistance to vibration	30 g, 10 Hz 2,000 Hz (EN 60068-2-6)

¹⁾ With mating connector fitted.

 $^{2)}$ These values relate to all mechanical versions including recommended accessories unless otherwise noted.

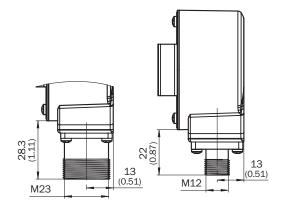
Classifications

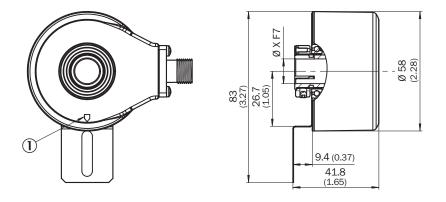
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eCl@ss 5.1.4	27270501

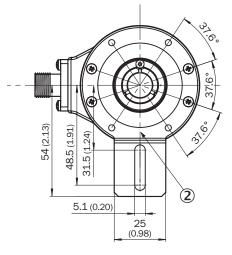
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eCl@ss 6.0	27270590
eCl@ss 6.2	27270590
eCl@ss 7.0	27270501
eCl@ss 8.0	27270501
eCl@ss 8.1	27270501
eCl@ss 9.0	27270501
eCl@ss 10.0	27270501
eCl@ss 11.0	27270501
eCl@ss 12.0	27270501
ETIM 5.0	EC001486
ETIM 6.0	EC001486
ETIM 7.0	EC001486
ETIM 8.0	EC001486
UNSPSC 16.0901	41112113

Dimensional drawing (Dimensions in mm (inch))







XF7 values see shaft diameter table for through hollow shaft, clamping at the front

① Zero pulse mark on housing

② Zero pulse mark on flange under stator coupling

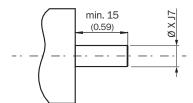
③ Male connector tolerance in relation to hole pattern

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Type Through hollow shaft with front clamping	Shaft diameter XF7
DBS60x-TAxxxxxxxx DBS60x-T1xxxxxxxx	6 mm
DBS60x-TBxxxxxxxx DBS60x-T2xxxxxxxxx	8 mm
DBS60x-TCxxxxxxxx DBS60x-T3xxxxxxxx	3/8″
DBS60x-TDxxxxxxxx DBS60x-T4xxxxxxxx	10 mm
DBS60x-TExxxxxxxx DBS60x-T5xxxxxxxx	12 mm
DBS60x-TFxxxxxxxx DBS60x-T6xxxxxxxx	1/2"
DBS60x-TGxxxxxxxx DBS60x-T7xxxxxxxx	14 mm
DBS60x-THxxxxxxxx DBS60x-T8xxxxxxxxx	15 mm
DBS60x-TJxxxxxxxx	5/8″

Attachment specifications

Through hollow shaft with front clamping



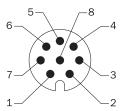
Customer side

Customer side	
Type Through hollow shaft with front clamping	Shaft diameter xj7
DBS60x-TAxxxxxxx DBS60x-T1xxxxxxxx	6 mm
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Type Through hollow shaft with front clamping	Shaft diameter xj7
DBS60x-TJxxxxxxx	5/8″

PIN assignment

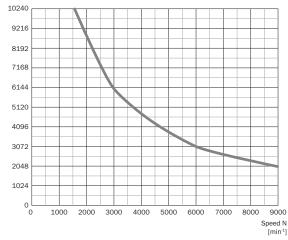


View of M12 male device connector on cable / housing

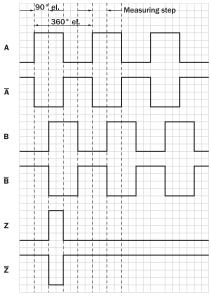
Wire colors (ca- ble connection)	Male connec- tor M12, 8-pin	Male connec- tor M23, 12-pin	TTL/HTL 6- channel signal	Explanation
Brown	1	6	A-	Signal wire
White	2	5	A	Signal wire
Black	3	1	В-	Signal wire
Pink	4	8	В	Signal wire
Yellow	5	4	Z-	Signal wire
Purple	6	3	Z	Signal wire
Blue	7	10	GND	Ground connection
Red	8	12	+U _s	Supply voltage
-	-	9	Not assigned	Not assigned
-	-	2	Not assigned	Not assigned
-	-	11	Not assigned	Not assigned
-	-	7	Not assigned	Not assigned
Screen	Screen	Screen	Screen	Screen connected to en- coder housing

Diagrams

Pulses per revolution



Signal outputs for electrical interfaces TTL and HTL



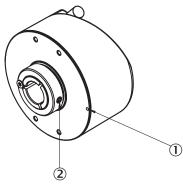
Cw with view on the encoder shaft in direction "A", compare dimensional drawing.

Supply voltage	Output
4,5 V 5,5 V	ΠL
10 V 30 V	TTL
10 V 27 V	HTL
4,5 V 30 V	TTL/HTL universal
4,5 V 30 V	ΠL

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Operation note

Hollow shaft



Attention! If stator coupling is mounted, the zero pulse mark can be hidden by the stator coupling Zero pulse mark on flange

② Zero pulse is active when screw of clamping is inline with zero pulse mark on flange or housing mark

Recommended accessories

Other models and accessories -> www.sick.com/DBS60

	Brief description	Туре	Part no.		
Other mounting accessories					
	Bearing bracket for hollow shaft encoders, fastening screws included the Bearing Block is intended for very large radial and axial shaft loads. Particularly for application on: Belt pulleys, Chain pinions, Friction wheels. It is designed this way to enable fitting of encoder with blind hollow shaft with ø 12 mm., fastening screws included	BEF-FA-B12-010	2042728		
Plug connectors and cables					
	Head A: cable Head B: Flying leads Cable: SSI, Incremental, HIPERFACE [®] , PUR, halogen-free, shielded	LTG-2308-MWENC	6027529		
	Head A: cable Head B: Flying leads Cable: SSI, Incremental, PUR, shielded	LTG-2411-MW	6027530		
/	Head A: cable Head B: Flying leads Cable: SSI, Incremental, PUR, halogen-free, shielded	LTG-2512-MW	6027531		
	Head A: cable Head B: Flying leads Cable: SSI, TTL, HTL, Incremental, PUR, halogen-free, shielded	LTG-2612-MW	6028516		
	Head A: female connector, M12, 8-pin, straight Head B: Flying leads Cable: Incremental, SSI, PUR, halogen-free, shielded, 2 m	DOL-1208-G02MAC1	6032866		
	Head A: female connector, M12, 8-pin, straight Head B: Flying leads Cable: Incremental, SSI, PUR, halogen-free, shielded, 5 m	DOL-1208-G05MAC1	6032867		
	Head A: female connector, M12, 8-pin, straight Head B: Flying leads Cable: Incremental, SSI, PUR, halogen-free, shielded, 10 m	DOL-1208-G10MAC1	6032868		

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	Brief description	Туре	Part no.
	Head A: female connector, M12, 8-pin, straight Head B: Flying leads Cable: Incremental, SSI, PUR, halogen-free, shielded, 20 m	DOL-1208-G20MAC1	6032869
	Head A: female connector, M12, 8-pin, straight Head B: Flying leads Cable: Incremental, SSI, PUR, halogen-free, shielded, 25 m	DOL-1208-G25MAC1	6067859
	Head A: female connector, M12, 8-pin, angled Head B: Flying leads Cable: PVC, shielded, 2 m	DOL-1208-W02MA	6020992
	Head A: female connector, M12, 8-pin, angled Head B: Flying leads Cable: HIPERFACE [®] , Incremental, PUR, halogen-free, shielded, 2 m	DOL-1208-W02MAC1	6037724
	Head A: female connector, M12, 8-pin, angled Head B: Flying leads Cable: Sensor/actuator cable, PUR, halogen-free, shielded, 2 m	DOL-1208- W02MAS01	6029224
	Head A: female connector, M12, 8-pin, angled Head B: Flying leads Cable: PUR, halogen-free, unshielded, 2 m	DOL-1208-W02MC	6035623
	Head A: female connector, M12, 8-pin, angled Head B: Flying leads Cable: PVC, shielded, 5 m	DOL-1208-W05MA	6021033
	Head A: female connector, M12, 8-pin, angled Head B: Flying leads Cable: HIPERFACE [®] , Incremental, PUR, halogen-free, shielded, 5 m	DOL-1208-W05MAC1	6037725
6	Head A: female connector, M12, 8-pin, angled Head B: Flying leads Cable: PUR, unshielded, 5 m	DOL-1208-W05MC	6035624
	Head A: female connector, M12, 8-pin, angled Head B: Flying leads Cable: HIPERFACE [®] , Incremental, PUR, halogen-free, shielded, 10 m	DOL-1208-W10MAC1	6037726
	Head A: female connector, M12, 8-pin, angled Head B: Flying leads Cable: PUR, halogen-free, unshielded, 10 m	DOL-1208-W10MC	6035625
	Head A: female connector, M12, 8-pin, angled Head B: Flying leads Cable: HIPERFACE [®] , Incremental, PUR, shielded, 20 m	DOL-1208-W20MAC1	6037727
- Colored	Head A: female connector, M12, 8-pin, straight, A-coded Head B: male connector, M12, 8-pin, straight, A-coded Cable: PUR, halogen-free, shielded, 2 m Drag chain use	YF2AA8- 020S01MKA18	2099207
	Head A: female connector, M12, 8-pin, straight, A-coded Head B: male connector, M12, 8-pin, straight, A-coded Cable: PUR, halogen-free, shielded, 5 m Drag chain use	YF2AA8- 050S01MKA18	2099209
	Head A: female connector, M12, 8-pin, straight, A-coded Head B: male connector, M12, 8-pin, straight, A-coded Cable: PUR, halogen-free, shielded, 10 m Drag chain use	YF2AA8- 100S01MKA18	2099210
	Head A: female connector, M12, 8-pin, straight, A-coded Head B: male connector, M12, 8-pin, straight, A-coded Cable: PUR, halogen-free, shielded, 20 m Drag chain use	YF2AA8- 200S01MKA18	2099208
	Head A: female connector, M12, 8-pin, straight, A-coded Cable: Incremental, SSI, shielded	DOS-1208-GA01	6045001

SICK AT A GLANCE

SICK is one of the leading manufacturers of intelligent sensors and sensor solutions for industrial applications. A unique range of products and services creates the perfect basis for controlling processes securely and efficiently, protecting individuals from accidents and preventing damage to the environment.

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