EKM36-OKF0B0S02 EKS/EKM36

MOTOR FEEDBACK SYSTEMS ROTARY HIPERFACE DSL®



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Illustration may differ

Ordering information

Туре	Part no.
EKM36-0KF0B0S02	1084837

Other models and accessories -> www.sick.com/EKS_EKM36

CE

Detailed technical data

Features	
Special device	1
Standard reference device	EKM36-0KF0B018A, 1084233
Performance	
Position	
Resolution per revolution	17 bit
System accuracy	± 120 ″
Signal noise (ơ)	\pm 5 " (See "signal noise" and "attenuation" diagrams)
Number of the absolute ascertainable revolu- tions	4,096
Available memory area	8,192 Byte
Measurement step per revolution	131,072
Vibration	
Measurement principle	Optical
Interfaces	
Type of code for the absolute value	Binary
Code sequence	Increasing, when turning the shaft For clockwise rotation, looking in direction "A" (see dimensional drawing)
Communication interface	HIPERFACE DSL [®]
Initialization time	Max. 500 ms ¹⁾
Measurement external temperature resis- tance	32 bit value, without prefix (1 Ω) 0 209.600 Ω At -40 °C +160 °C: NTC +-2K; PTC+-3K

 $^{1)}\ensuremath{\mathsf{From}}$ reaching a permitted operating voltage.

Electrical data

Connection type	Male connector, 4-pin
Supply voltage	7 V 12 V
Warm-up time voltage ramp	Max. 180 ms ¹⁾
Recommended supply voltage	8 V

 $^{1)}$ Duration of voltage ramp between 0 and 7.0 V.

 $^{2)}$ Current rating applies when using interface circuit suggestions as shown in HIPERFACE DSL \circledast manual (8017595).

³⁾ This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 60 °C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

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Current consumption	\leq 150 mA (See current consumption diagram) ²⁾
Output frequency for the digital positionval- ue	0 kHz 75 kHz
MTTF: mean time to dangerous failure	155 years (EN ISO 13849) ³⁾

 $^{1)}$ Duration of voltage ramp between 0 and 7.0 V.

²⁾ Current rating applies when using interface circuit suggestions as shown in HIPERFACE DSL ® manual (8017595).

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Mechanical data

Shaft version	Tapered shaft
Flange type / stator coupling	Stator coupling
Dimensions	See dimensional drawing
Weight	0.1 kg
Moment of inertia of the rotor	4.5 gcm ²
Operating speed	≤ 9,000 min ⁻¹
Angular acceleration	≤ 500,000 rad/s²
Operating torque	0.2 Ncm
Start up torque	0.3 Ncm
Permissible movement static	± 0.1 mm, ± 0.5 mm radial, axial
Permissible movement dynamic	± 0.05 mm radial ± 0.1 mm axial
Life of ball bearings	3.6 x 10^9 revolutions
Ambient data	
Operating temperature range	-20 °C +115 °C ¹⁾
Storage temperature range	-40 °C +125 °C ²⁾
Relative humidity/condensation	90 %. Condensation not permitted

Storage temperature range	-40 °C +125 °C ²⁾
Relative humidity/condensation	90 %, Condensation not permitted
Resistance to shocks	100 g, 6 ms (according to EN 60068-2-27)
Frequency range of resistance to vibrations	50 g, 10 Hz 2,000 Hz (EN 60068-2-6)
EMC	According to EN 61000-6-2, EN 61000-6-4 and IEC 61326-3 $^{\rm 3)}$
Enclosure rating	IP40, with mating connector inserted and closed cover (IEC 60529-1) $^{\rm 4)}$

¹⁾ Given typical thermal connection between motor flange and encoder stator coupling. The max. internal sensor temperature may not exceed 125 °C.

²⁾ Without package.

³⁾ The EMC according to the standards quoted is achieved when the motor feedback system is mounted in an electrically conductive housing, which is connected to the central earthing point of the motor controller via a cable screen. The GND-(0 V) connection of the supply voltage is also grounded here. If other shielding concepts are used, users must perform their own tests.

⁴⁾ With mating connector inserted and closed cover.

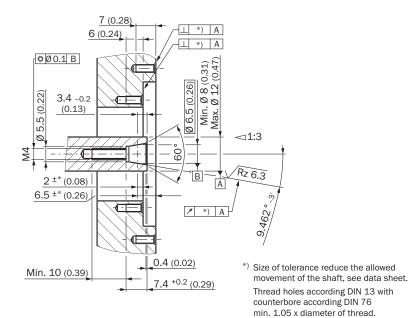
Classifications

ECLASS 5.0	27270590
ECLASS 5.1.4	27270590
ECLASS 6.0	27270590
ECLASS 6.2	27270590
ECLASS 7.0	27270590
ECLASS 8.0	27270590

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ECLASS 8.1	27270590
ECLASS 9.0	27270590
ECLASS 10.0	27273805
ECLASS 11.0	27273901
ECLASS 12.0	27273901
ETIM 5.0	EC001486
ETIM 6.0	EC001486
ETIM 7.0	EC001486
ETIM 8.0	EC001486
UNSPSC 16.0901	41112113

Attachment specifications



① Nominal position

O The size of the tolerance reduces the permissible wave movement, see data sheet

③ Threaded holes in accordance with DIN 13 with recesses in accordance with DIN 76 min. 1.05 x thread diameter

PIN assignment

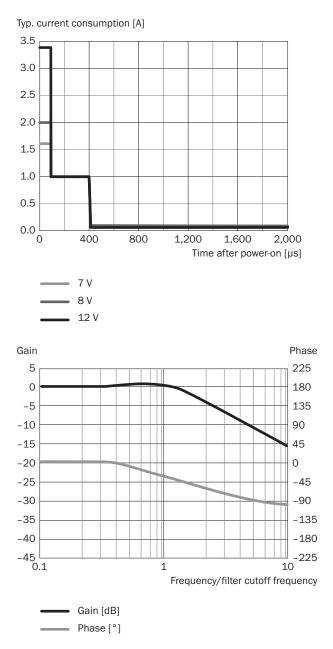
Temperature sensor pin assignment

0 0 2 1		
PIN	Signal	Explanation
1	T+	Thermistor connection
2	Т-	Thermistor connection (to ground)
Recommended outer diameter of set of stranded wires: 2.2 mm \pm 0.1 mm		

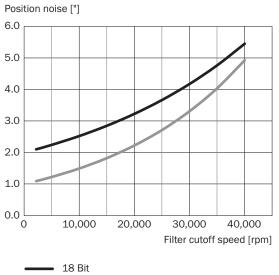
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PIN	Signal	Explanation
	Recommended mating connector: Harwin M8	0-8990205

Diagrams



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_____ 20 Bit

Signal noise is measured as 1 standard deviation (σ) of the value distribution. Position filter cutoff speed is set by ressource 10Ah, see page 11.

Recommended accessories

Other models and accessories -> www.sick.com/EKS_EKM36

	Brief description	Туре	Part no.	
Other mounti	Other mounting accessories			
	Mounting tools	BEF-MW-EKX36	2060224	
Plug connecto	ors and cables			
		DOL-0B02-G0M2XC1	2062083	
		DOL-0B02-G0M3AC2	2108944	
\sim		DOL-0B02-G0M3XC1	2091818	
		DOL-0B02-G0M4XC1	2086286	
		DOL-0B03-G0M4XC1	2087314	

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Online data sheet

