



# AFM60A-S1KA262144

AFS/AFM60 SSI

**ABSOLUTE ENCODERS**

**SICK**  
Sensor Intelligence.



Illustration may differ



### Ordering information

Type	Part no.
AFM60A-S1KA262144	1102275

Other models and accessories → [www.sick.com/AFS\\_AFM60\\_SSI](http://www.sick.com/AFS_AFM60_SSI)

### Detailed technical data

#### Performance

<b>Number of steps per revolution (max. resolution)</b>	262,144 (18 bit)
<b>Number of revolutions</b>	4,096 (12 bit)
<b>Max. resolution (number of steps per revolution x number of revolutions)</b>	18 bit x 12 bit (262,144 x 4,096)
<b>Error limits G</b>	0.03° <sup>1)</sup>
<b>Repeatability standard deviation <math>\sigma_r</math></b>	0.002° <sup>2)</sup>

<sup>1)</sup> In accordance with DIN ISO 1319-1, position of the upper and lower error limit depends on the installation situation, specified value refers to a symmetrical position, i.e. deviation in upper and lower direction is the same.

<sup>2)</sup> In accordance with DIN ISO 55350-13; 68.3% of the measured values are inside the specified area.

#### Interfaces

<b>Communication interface</b>	SSI
<b>Communication Interface detail</b>	SSI + Sin/Cos
<b>Initialization time</b>	50 ms <sup>1)</sup>
<b>Position forming time</b>	< 1 $\mu$ s
<b>Code type</b>	Gray
<b>Code sequence parameter adjustable</b>	CW/CCW (V/R) parameter adjustable
<b>Clock frequency</b>	$\leq$ 2 MHz <sup>2)</sup>
<b>Set (electronic adjustment)</b>	H-active (L = 0 - 3 V, H = 4,0 - U <sub>s</sub> V)
<b>CW/CCW (counting sequence when turning)</b>	L-active (L = 0 - 1,5 V, H = 2,0 - U <sub>s</sub> V)
<b>Sine/cosine periods per revolution</b>	1,024
<b>Output frequency</b>	$\leq$ 200 kHz
<b>Load resistance</b>	$\geq$ 120 $\Omega$

<sup>1)</sup> Valid positional data can be read once this time has elapsed.

<sup>2)</sup> Minimum, LOW level (Clock +): 250 ns.

<b>Signal before differential generation</b>	0.5 V <sub>pp</sub> , ± 20 %, 120 Ω
<b>Signal offset before differential generation</b>	2.5 V ± 10 %
<b>Signal after differential generation</b>	1 V <sub>pp</sub> , ± 20 %

<sup>1)</sup> Valid positional data can be read once this time has elapsed.

<sup>2)</sup> Minimum, LOW level (Clock +): 250 ns.

## Electrical data

<b>Connection type</b>	Male connector, M23, 12-pin, radial
<b>Supply voltage</b>	4.5 ... 32 V
<b>Power consumption</b>	≤ 0.7 W (without load)
<b>Reverse polarity protection</b>	✓
<b>MTTFd: mean time to dangerous failure</b>	250 years (EN ISO 13849-1) <sup>1)</sup>

<sup>1)</sup> This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40 °C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

## Mechanical data

<b>Mechanical design</b>	Solid shaft, Servo flange
<b>Shaft diameter</b>	6 mm
<b>Shaft length</b>	10 mm
<b>Weight</b>	0.3 kg <sup>1)</sup>
<b>Shaft material</b>	Stainless steel
<b>Flange material</b>	Aluminum
<b>Housing material</b>	Aluminum die cast
<b>Start up torque</b>	< 0.5 Ncm (+20 °C)
<b>Operating torque</b>	< 0.3 Ncm (+20 °C)
<b>Permissible shaft loading</b>	80 N (radial) 40 N (axial)
<b>Operating speed</b>	≤ 9,000 min <sup>-1</sup> <sup>2)</sup>
<b>Moment of inertia of the rotor</b>	6.2 gcm <sup>2</sup>
<b>Bearing lifetime</b>	3.0 x 10 <sup>9</sup> revolutions
<b>Angular acceleration</b>	≤ 500,000 rad/s <sup>2</sup>

<sup>1)</sup> Based on devices with male connector.

<sup>2)</sup> Allow for self-heating of 3.3 K per 1,000 rpm when designing the operating temperature range.

## Ambient data

<b>EMC</b>	According to EN 61000-6-2 and EN 61000-6-3 <sup>1)</sup>
<b>Enclosure rating</b>	IP65, shaft side (IEC 60529) IP67, housing side (IEC 60529) <sup>2)</sup>
<b>Permissible relative humidity</b>	90 % (Condensation not permitted)
<b>Operating temperature range</b>	-40 °C ... +100 °C <sup>3)</sup>
<b>Storage temperature range</b>	-40 °C ... +100 °C, without package

<sup>1)</sup> EMC according to the standards quoted is achieved if shielded cables are used.

<sup>2)</sup> For devices with male connector: with mounted mating connector.

<sup>3)</sup> Stationary position of the cable.

<b>Resistance to shocks</b>	60 g, 6 ms (EN 60068-2-27)
<b>Resistance to vibration</b>	20 g, 10 Hz ... 2,000 Hz (EN 60068-2-6)

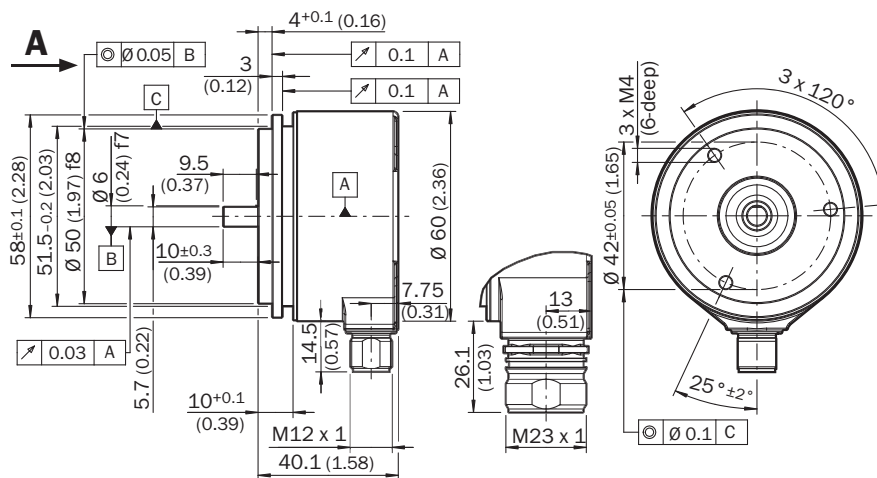
- 1) EMC according to the standards quoted is achieved if shielded cables are used.
- 2) For devices with male connector: with mounted mating connector.
- 3) Stationary position of the cable.

### Classifications

<b>eCl@ss 5.0</b>	27270502
<b>eCl@ss 5.1.4</b>	27270502
<b>eCl@ss 6.0</b>	27270590
<b>eCl@ss 6.2</b>	27270590
<b>eCl@ss 7.0</b>	27270502
<b>eCl@ss 8.0</b>	27270502
<b>eCl@ss 8.1</b>	27270502
<b>eCl@ss 9.0</b>	27270502
<b>eCl@ss 10.0</b>	27270502
<b>eCl@ss 11.0</b>	27270502
<b>eCl@ss 12.0</b>	27270502
<b>ETIM 5.0</b>	EC001486
<b>ETIM 6.0</b>	EC001486
<b>ETIM 7.0</b>	EC001486
<b>ETIM 8.0</b>	EC001486
<b>UNSPSC 16.0901</b>	41112113

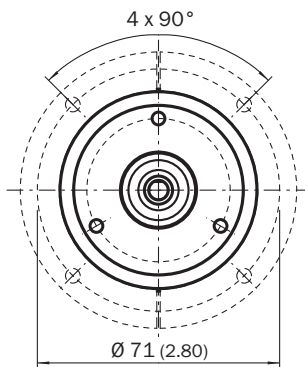
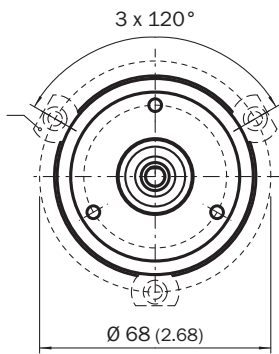
### Dimensional drawing (Dimensions in mm (inch))

Servo flange, M12 and M23 radial male connector



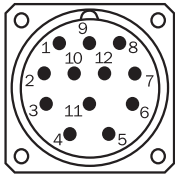
General tolerances according to DIN ISO 2768-mk

Attachment specifications



PIN assignment

M23 male connector, 12-pin and cable, 12-wire, SSI/Gray + SIN/COS

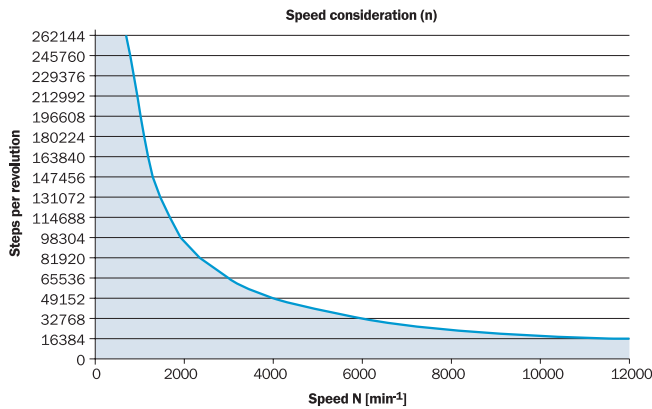


View of M23 male device connector on encoder

PIN	Wire colors (cable connection)	Signal Incremental	Explanation
1	Red	U <sub>S</sub>	Operating voltage
2	Blue	GND	Ground connection
3	Yellow	Clock +	Interface signals
4	White	Data +	Interface signals
5	Orange	SET	Electronic adjustment
6	Brown	Data -	Interface signals
7	Violet	Clock -	Interface signals
8	Black	- SIN	Signal wire
9	Orange-black	CW/CCW (V/R)	Sequence in direction of rotation
10	Green	- COS	Signal wire
11	Gray	+ COS	Signal wire

PIN	Wire colors (cable connection)	Signal Incremental	Explanation
12	Pink	+ SIN	Signal wire
		Screen	Screen connected to housing on encoder side. Connected to ground on control side.



### Diagrams












The maximum speed is also dependent on the shaft type.

### Recommended accessories

Other models and accessories → [www.sick.com/AFS\\_AFM60\\_SSI](http://www.sick.com/AFS_AFM60_SSI)

	Brief description	Type	Part no.
<b>Other mounting accessories</b>			
	Servo clamps, large, for servo flange (clamps, eccentric fastener), 3 pcs, without mounting material, without mounting hardware	BEF-WK-SF	2029166
<b>Plug connectors and cables</b>			
	Head A: female connector, M23, 12-pin, straight Head B: Flying leads Cable: shielded, 3 m	DOL-2312-G03MMD2	2062300
	Head A: female connector, M23, 12-pin, straight Head B: Flying leads Cable: shielded, 5 m	DOL-2312-G05MMD2	2062301
	Head A: female connector, M23, 12-pin, straight Head B: Flying leads Cable: shielded, 10 m	DOL-2312-G10MMD2	2062302
	Head A: female connector, M23, 12-pin, straight Head B: Flying leads Cable: unshielded, 1.5 m	DOL-2312-G1M5MD2	2062284
	Head A: female connector, M23, 12-pin, straight Head B: Flying leads Cable: shielded, 20 m	DOL-2312-G20MMD2	2062303

	Brief description	Type	Part no.
	Head A: female connector, M23, 12-pin, straight Head B: Flying leads Cable: shielded, 30 m	DOL-2312-G30MMD2	2062304
	Head A: female connector, M23, 9-pin, straight Cable: HIPERFACE <sup>®</sup> , SSI, Incremental, shielded	DOS-2309-G	6028533
	Head A: female connector, M23, 12-pin, straight Cable: HIPERFACE <sup>®</sup> , SSI, Incremental, shielded	DOS-2312-G DOS-2312-G02	6027538 2077057
	Head A: female connector, M23, 12-pin, angled Cable: HIPERFACE <sup>®</sup> , SSI, Incremental, shielded	DOS-2312-W01	2072580
<b>Shaft adaptation</b>			
	Bellows coupling, shaft diameter 6 mm / 6 mm, maximum shaft offset: radial $\pm$ 0.25 mm, axial $\pm$ 0.4 mm, angular $\pm$ 4°; max. speed 10,000 rpm, -30 °C to +120 °C, max. torque 120 Ncm; material: stainless steel bellows, aluminum hub	KUP-0606-B	5312981
	Cross-slotted coupling, shaft diameter 6 mm / 6 mm, maximum shaft offset: radial $\pm$ 0.3 mm, axial $\pm$ 0.2 mm, angle $\pm$ 3°; max. speed 10,000 rpm, -10° to +80 °C, max. torque 80 Ncm; material: fiber-glass reinforced polyamide, aluminum hub	KUP-0606-S	2056406
	Bar coupling, shaft diameter 6 mm / 8 mm, maximum shaft offset radial $\pm$ 0.3 mm, axial $\pm$ 0.2 mm, angle $\pm$ 3°, max. speed 10,000 rpm, torsion spring rigidity 38 Nm/wheel; material: fiber-glass reinforced polyamide, aluminum hub	KUP-0608-S	5314179
	Bellows coupling, shaft diameter 6 mm / 10 mm, maximum shaft offset: radial $\pm$ 0.25 mm, axial $\pm$ 0.4 mm, angular $\pm$ 4°; max. speed 10,000 rpm, -30 °C to +120 °C, max. torque 120 Ncm; material: stainless steel bellows, aluminum hub	KUP-0610-B	5312982
	Double loop coupling, shaft diameter 6 mm / 10 mm, max. shaft offset: radially $\pm$ 2,5 mm, axially $\pm$ 3 mm, angle $\pm$ 10 degrees; max. speed 3.000 rpm, -30 to +80 degrees Celsius, torsional spring stiffness of 25 Nm/rad	KUP-0610-D	5326697
	Spring washer coupling, shaft diameter 6 mm / 10 mm, Maximum shaft offset: radial $\pm$ 0.3 mm, axial $\pm$ 0.4 mm, angular $\pm$ 2.5°; max. speed 12,000 rpm, -10° to +80 °C, max. torque 60 Ncm; material: aluminum flange, glass fiber-reinforced polyamide membrane and hardened steel coupling pin	KUP-0610-F	5312985
	Claw coupling, shaft diameter 6 mm / 10 mm, damping element 80 shore blue, maximum shaft offset: radial $\pm$ 0.22 mm, axial $\pm$ 1 mm angular $\pm$ 1.3°, max. speed 19,000 rpm, angle of twist max. 10°, -30 °C to +80 °C, max. torque 800 Ncm, tightening torque of screws: ISO 4029 150 Ncm, material: aluminum flange, damping element: polyurethane	KUP-0610-J	2127056
	Bar coupling, shaft diameter 6 mm / 10 mm, max. shaft offset: radial $\pm$ 0,3 mm, axial $\pm$ 0,3 mm, angular $\pm$ 3°; max. speed 10.000 rpm, -10° to +80 °C, max. torque: 80 Ncm, material: fiber-glass reinforced polyamide, aluminum hub	KUP-0610-S	2056407

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