



AFM60B-TETA008192

AFS/AFM60 SSI

ABSOLUTE ENCODERS

SICK
Sensor Intelligence.



Illustration may differ



Ordering information

Type	Part no.
AFM60B-TETA008192	1065574

Other models and accessories → www.sick.com/AFS_AFM60_SSI

Detailed technical data

Performance

Number of steps per revolution (max. resolution)	8,192 (13 bit)
Number of revolutions	4,096 (12 bit)
Max. resolution (number of steps per revolution x number of revolutions)	13 bit x 12 bit (8,192 x 4,096)
Error limits G	0.05° ¹⁾
Repeatability standard deviation σ_r	0.002° ²⁾

¹⁾ In accordance with DIN ISO 1319-1, position of the upper and lower error limit depends on the installation situation, specified value refers to a symmetrical position, i.e. deviation in upper and lower direction is the same.

²⁾ In accordance with DIN ISO 55350-13; 68.3% of the measured values are inside the specified area.

Interfaces

Communication interface	SSI
Communication Interface detail	SSI + incremental / TTL
Initialization time	50 ms ¹⁾
Position forming time	< 1 μ s
Code type	Gray
Code sequence parameter adjustable	CW/CCW (V/R) parameter adjustable
Clock frequency	≤ 2 MHz ²⁾
Set (electronic adjustment)	H-active (L = 0 - 3 V, H = 4,0 - U _s V)
CW/CCW (counting sequence when turning)	L-active (L = 0 - 1,5 V, H = 2,0 - U _s V)
Pulses per revolution	1/4 of number of SSI steps per revolution
Output frequency	≤ 600 kHz
Load current	≤ 30 mA

¹⁾ Valid positional data can be read once this time has elapsed.

²⁾ Minimum, LOW level (Clock +): 250 ns.

Electrical data

Connection type	Male connector, M23, 12-pin, radial
Supply voltage	4.5 ... 32 V
Power consumption	≤ 0.7 W (without load)
Reverse polarity protection	✓
MTTFd: mean time to dangerous failure	250 years (EN ISO 13849-1) ¹⁾

¹⁾ This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40 °C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

Mechanical data

Mechanical design	Through hollow shaft
Shaft diameter	12 mm
Weight	0.2 kg ¹⁾
Shaft material	Stainless steel
Flange material	Aluminum
Housing material	Aluminum die cast
Start up torque	< 0.8 Ncm (+20 °C)
Operating torque	< 0.6 Ncm (+20 °C)
Permissible movement static	± 0.5 mm (axial) ± 0.3 mm (radial)
Permissible movement dynamic	± 0.2 mm (axial) ± 0.1 mm (radial)
Operating speed	≤ 9,000 min ⁻¹ ²⁾
Moment of inertia of the rotor	40 gcm ²
Bearing lifetime	3.0 x 10 ⁹ revolutions
Angular acceleration	≤ 500,000 rad/s ²

¹⁾ Based on devices with male connector.

²⁾ Allow for self-heating of 3.3 K per 1,000 rpm when designing the operating temperature range.

Ambient data

EMC	According to EN 61000-6-2 and EN 61000-6-3 ¹⁾
Enclosure rating	IP65, shaft side (IEC 60529) IP67, housing side (IEC 60529) ²⁾
Permissible relative humidity	90 % (Condensation not permitted)
Operating temperature range	-40 °C ... +100 °C ³⁾
Storage temperature range	-40 °C ... +100 °C, without package
Resistance to shocks	70 g, 6 ms (EN 60068-2-27)
Resistance to vibration	30 g, 10 Hz ... 2,000 Hz (EN 60068-2-6)

¹⁾ EMC according to the standards quoted is achieved if shielded cables are used.

²⁾ For devices with male connector: with mounted mating connector.

³⁾ Stationary position of the cable.

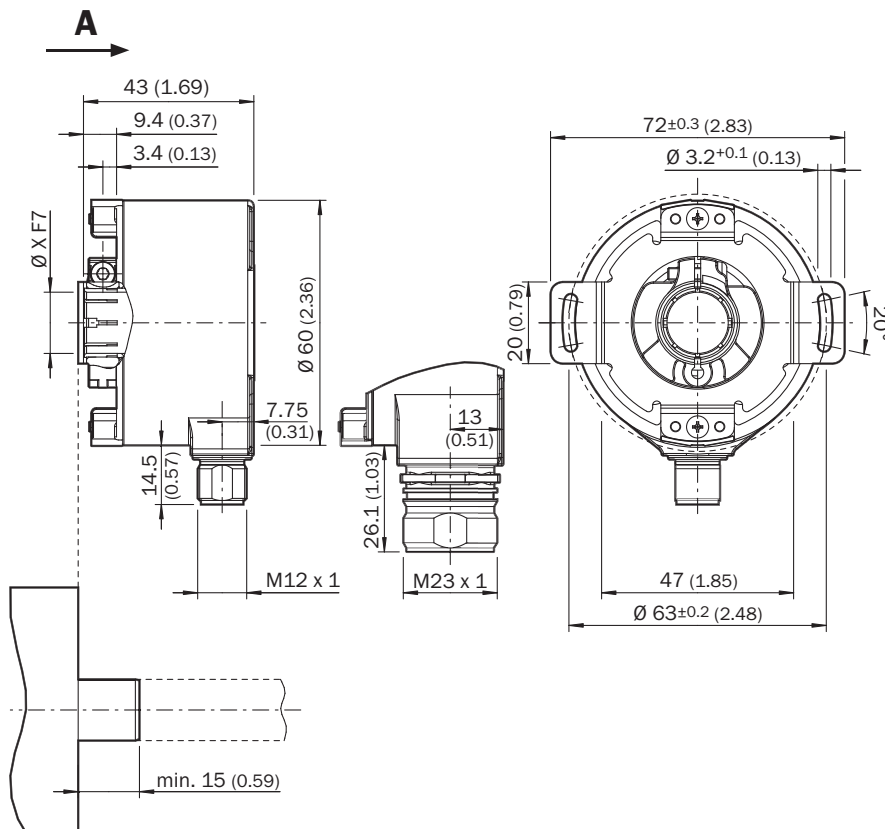
Classifications

eCl@ss 5.0	27270502
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eCl@ss 5.1.4	27270502
eCl@ss 6.0	27270590
eCl@ss 6.2	27270590
eCl@ss 7.0	27270502
eCl@ss 8.0	27270502
eCl@ss 8.1	27270502
eCl@ss 9.0	27270502
eCl@ss 10.0	27270502
eCl@ss 11.0	27270502
eCl@ss 12.0	27270502
ETIM 5.0	EC001486
ETIM 6.0	EC001486
ETIM 7.0	EC001486
ETIM 8.0	EC001486
UNSPSC 16.0901	41112113

Dimensional drawing (Dimensions in mm (inch))

Through hollow shaft, M12 and M23 radial male connector

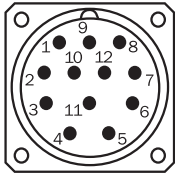


General tolerances according to DIN ISO 2768-mk

① Cable diameter = 5.6 mm +/- 0.2 mm bend radius = 30 mm

PIN assignment

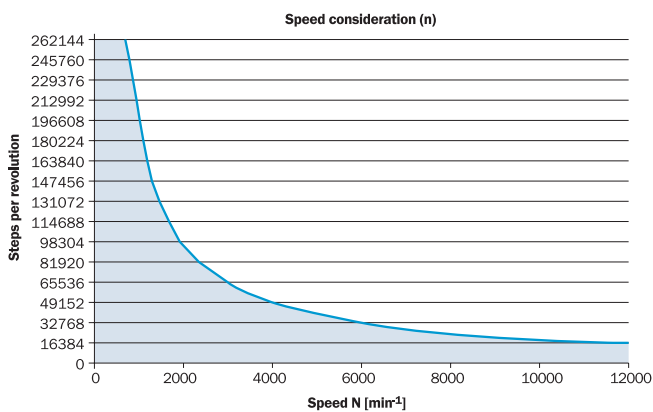
M23 male connector, 12-pin and cable, 12-wire, SSI/Gray + incremental



View of M23 male device connector on encoder

PIN	Wire colors (cable connection)	Signal Sin/Cos	Explanation
1	Red	U _S	Operating voltage
2	Blue	GND	Ground connection
3	Yellow	Clock +	Interface signals
4	White	Data +	Interface signals
5	Orange	SET	Electronic adjustment
6	Brown	Data -	Interface signals
7	Violet	Clock -	Interface signals
8	Black	\bar{B}	Signal wire
9	Orange-black	CW/CCW (V/R)	Sequence in direction of rotation
10	Green	\bar{A}	Signal wire
11	Gray	A	Signal wire
12	Pink	B	Signal wire
		Screen	Screen connected to housing on encoder side. Connected to ground on control side.

Diagrams



The maximum speed is also dependent on the shaft type.

Recommended accessories

Other models and accessories → www.sick.com/AFS_AFM60_SSI

	Brief description	Type	Part no.
Plug connectors and cables			
	Head A: female connector, M23, 12-pin, straight Head B: Flying leads Cable: shielded, 3 m	DOL-2312-G03MMD2	2062300
	Head A: female connector, M23, 12-pin, straight Head B: Flying leads Cable: shielded, 5 m	DOL-2312-G05MMD2	2062301
	Head A: female connector, M23, 12-pin, straight Head B: Flying leads Cable: shielded, 10 m	DOL-2312-G10MMD2	2062302
	Head A: female connector, M23, 12-pin, straight Head B: Flying leads Cable: unshielded, 1.5 m	DOL-2312-G1M5MD2	2062284
	Head A: female connector, M23, 12-pin, straight Head B: Flying leads Cable: shielded, 20 m	DOL-2312-G20MMD2	2062303
	Head A: female connector, M23, 12-pin, straight Head B: Flying leads Cable: shielded, 30 m	DOL-2312-G30MMD2	2062304
	Head A: female connector, M23, 9-pin, straight Cable: HIPERFACE®, SSI, Incremental, shielded	DOS-2309-G	6028533
	Head A: female connector, M23, 12-pin, straight Cable: HIPERFACE®, SSI, Incremental, shielded	DOS-2312-G	6027538
	Head A: female connector, M23, 12-pin, straight Cable: HIPERFACE®, SSI, Incremental, shielded	DOS-2312-G02	2077057
	Head A: female connector, M23, 12-pin, angled Cable: HIPERFACE®, SSI, Incremental, shielded	DOS-2312-W01	2072580

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