# DFV60B-22EZO-S01 DFV60

**MEASURING WHEEL ENCODERS** 



## DFV60B-22EZ0-S01 | DFV60

MEASURING WHEEL ENCODERS

Illustration may differ

#### Ordering information

Туре	Part no.
DFV60B-22EZ0-S01	1051284

DFV60 spring arm (part number: 2056155) not included with delivery

Other models and accessories → www.sick.com/DFV60

# CE

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#### Detailed technical data

Features	
Special device	✓
Specialty	M12 male connector, 5-pin
Items supplied	DFV60 spring arm (part number: 2056155) not included with delivery
Performance	
Pulses per revolution	30
Resolution in pulses/mm	0.1 Pulses/mm <sup>1)</sup>
Measuring increment (resolution in mm/ pulse)	10 mm/pulse <sup>2)</sup>
Measuring step deviation	± 0.04° <sup>3)</sup>
Error limits	$\pm$ 0.03°, $\pm$ 4 mm/m, subject to measuring wheel (measuring wheel surface + measuring surface + ambient conditions)
Initialization time	30 ms

<sup>1)</sup> Calculation example: Pulses per revolution / measuring wheel circumference = 16,384 pulses per revolution / 200 mm = 81.92 pulses/mm.

<sup>2)</sup> Calculation example: Circumference of wheel / pulses per revolution = 200 mm / 16384 pulses per revolution = 0,012mm/pulse.

 $^{\rm 3)}\,{\rm Value}$  refers to the mounted encoder.

#### Interfaces

Communication interface	Incremental
Communication Interface detail	HTL / Push pull

#### Electrical data

Connection type	Male connector, M12, 5-pin, radial
Power consumption max. without load	≤ 30 mA
Supply voltage	10 V 32 V
Load current max.	30 mA
Maximum output frequency	820 kHz
Reference signal, number	1
Reference signal, position	90°, electric, logically gated with A and B
Reverse polarity protection	✓

<sup>1)</sup> This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40 °C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

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Short-circuit protection of the outputs	1
MTTFd: mean time to dangerous failure	300 years (EN ISO 13849-1) <sup>1)</sup>

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#### Mechanical data

Measuring wheel circumference	300 mm
-	
Measuring wheel surface	O-ring NBR70 <sup>1)</sup>
Mass	+ 420 g
Encoder material	
Shaft	Stainless steel
Flange	Aluminum
Housing	Aluminum
Cable	PUR
Spring arm mechanism material	
Spring element	Not contained in the scope of delivery of the system
Measuring wheel, spring arm	Aluminum
Start up torque	0.8 Ncm (at 20 °C)
Operating torque	0.6 Ncm (at 20 °C)
Operating speed	1,500 min <sup>-1</sup>
Maximum operating speed	3,000 min <sup>-1 2)</sup>
Bearing lifetime	3 x 10^9 revolutions
Maximum travel/deflection of spring arm	40 mm
Recommended pretension	20 Nm
Max. permissible working area for the spring (continuous operation)	± 10 mm
Recommended spring deflection	20 mm 40 mm
Mounting position relative to the measuring object	Preferably from above, from below possible

<sup>1)</sup> The surface of a measuring wheel is subject to wear. This depends on contact pressure, acceleration behavior in the application, traversing speed, measurement surface, mechanical alignment of the measuring wheel, temperature, and ambient conditions. We recommend you regularly check the condition of the measuring wheel and replace as required.

 $^{2)}\,\mbox{Allow}$  for self-heating of 3.3 K per 1,000 rpm when designing the operating temperature range.

#### Ambient data

EMC	According to EN 61000-6-2 and EN 61000-6-4
Enclosure rating	IP65
Permissible relative humidity	90 % (Condensation not permitted)
Operating temperature range	-20 °C +100 °C
Storage temperature range	-40 °C +100 °C, without package

#### Classifications

eCl@ss 5.0	27270501
eCl@ss 5.1.4	27270501
eCl@ss 6.0	27270590

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eCl@ss 6.2	27270590
eCl@ss 7.0	27270501
eCl@ss 8.0	27270501
eCl@ss 8.1	27270501
eCl@ss 9.0	27270501
eCl@ss 10.0	27270790
eCl@ss 11.0	27270707
eCl@ss 12.0	27270504
ETIM 5.0	EC001486
ETIM 6.0	EC001486
ETIM 7.0	EC001486
ETIM 8.0	EC001486
UNSPSC 16.0901	41112113

#### **PIN** assignment



View to the connector M12 fittet to the encoder body

PIN	Signal	Description
1	Us	Supply voltage (potential free to housing)
2	В	Signal line
3	GND	Ground connection of the encoder
4	Α	Signal line
5	Z	Signal line for zero pulse

#### Diagrams



Dual wheel, spring tension, yoke mount



① Recommended pre-tension (20 mm)

2 Maximum deflection (40 mm)
3 Recommended deflection range (10 - 30 mm)

Permissible working area (0 – 30 mm)

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