

DFS60S-BG0C01024

DFS60S Pro

INCREMENTAL ENCODERS





Ordering information

| Туре | Part no. |
|------------------|----------|
| DFS60S-BG0C01024 | 1069541 |

Other models and accessories → www.sick.com/DFS60S_Pro

Illustration may differ



Detailed technical data

Safety-related parameters

| Carety related parameters | | | |
|--|--|--|--|
| Safety integrity level | SIL 2 (IEC 61508), SILCL2 (IEC 62061) 1) | | |
| Performance level | PL d (EN ISO 13849) 1) | | |
| Category | 3 (EN ISO 13849) | | |
| PFH _D : Probability of dangerous failure per hour | 1.7 x 10 ⁻⁸ ²⁾ | | |
| T _M (mission time) | 20 years (EN ISO 13849) | | |
| Safety-related measuring step | 0.09°, Quadrature analysis | | |
| Safety-related accuracy | ± 0.09° | | |

¹⁾ For more detailed information on the exact configuration of your machine/unit, please consult your relevant SICK branch office.

Performance

| Sine/cosine periods per revolution | 1,024 |
|------------------------------------|---|
| Measuring step | 0.3 $^{\prime\prime}$, For interpolation of the sine/cosine signals with e.g. 12 bit $^{1)}$ |
| Integral non-linearity | Typ. \pm 45 $^{\prime\prime}$ (without mechanical tension of the stator coupling) |
| Differential non-linearity | ± 7 " |

¹⁾ Not safety-related.

Interfaces

| Communication interface | Incremental |
|--------------------------------|------------------------|
| Communication Interface detail | Sin/Cos 1) |
| Initialization time | 50 ms ²⁾ |
| Output frequency | ≤ 153.6 kHz |
| Power consumption | ≤ 0.7 W (without load) |

^{1) 1.0} V_{SS} (differential).

²⁾ The values displayed apply to a diagnostic degree of coverage of 99%, which must be achieved by the external drive system and 95 °C operating temperature.

 $^{^{2)}}$ Valid signals can be read once this time has elapsed.

| Load resistance ≥ 120 Ω |
|--------------------------------|
|--------------------------------|

^{1) 1.0} V_{SS} (differential).

Electrical data

| Connection type | Male connector, M12, 8-pin, radial |
|---|---|
| Supply voltage | 4.5 32 V |
| Reference signal, number | 1 |
| Reference signal, position | 90°, electronically, gated with Sinus and Cosinus |
| Reverse polarity protection | ✓ |
| Protection class | III (according to DIN EN 61140) |
| Short-circuit protection of the outputs | ✓ ¹⁾ |

¹⁾ Short-circuit to another channel or GND permitted for max. 30 s. In the case of $U_S \le 12 \text{ V}$ additional short-circuit to U_S permitted for max. 30 s.

Mechanical data

| Mechanical design | Blind hollow shaft |
|--------------------------------|---|
| Shaft diameter | 14 mm With feather key |
| Weight | Approx. 0.25 kg ¹⁾ |
| Shaft material | Stainless steel |
| Flange material | Die-cast zinc |
| Housing material | Aluminum die cast |
| Start up torque | ≤ 0.8 Ncm (+20 °C) |
| Operating torque | ≤ 0.6 Ncm (+20 °C) |
| Permissible movement static | ± 0.3 mm (radial) ± 0.5 mm (axial) |
| Permissible movement dynamic | ± 0.05 mm (radial) ± 0.1 mm (axial) |
| Operating speed | ≤ 6,000 min ^{-1 2)} |
| Moment of inertia of the rotor | 56 gcm ² |
| Bearing lifetime | 3.6 x 10 ⁹ revolutions ³⁾ |
| Angular acceleration | ≤ 500,000 rad/s² |

 $^{^{1)}}$ Based on encoder with male connector.

Ambient data

| EMC | According to EN 61000-6-2, EN 61000-6-3 and IEC 61326-3-1 |
|-------------------------------|---|
| Enclosure rating | IP65 (IEC 60529) 1) |
| Permissible relative humidity | 90 % (Condensation not permitted) |
| Operating temperature range | −30 °C +95 °C ²⁾ |
| Storage temperature range | -30 °C +85 °C, without package |

 $^{^{1)}}$ With male connector and mating connector fitted minimum IP65.

²⁾ Valid signals can be read once this time has elapsed.

 $^{^{2)}}$ Allow for self-heating of approx. 3.0 K per 1,000 rpm regarding the permissible operating temperature.

 $^{^{}m 3)}$ On maximum operating speed and temperature.

²⁾ Allow for self-heating of approx. 3.0 K per 1,000 rpm regarding the permissible operating temperature.

³⁾ Checked to operation with vector length monitoring.

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| Resistance to shocks | 100 g, 6 ms (EN 60068-2-27) ³⁾ |
|-------------------------|---|
| Resistance to vibration | 30 g, 10 Hz 1,000 Hz (EN 60068-2-6) |

 $^{^{1)}\,\}mathrm{With}$ male connector and mating connector fitted minimum IP65.

Classifications

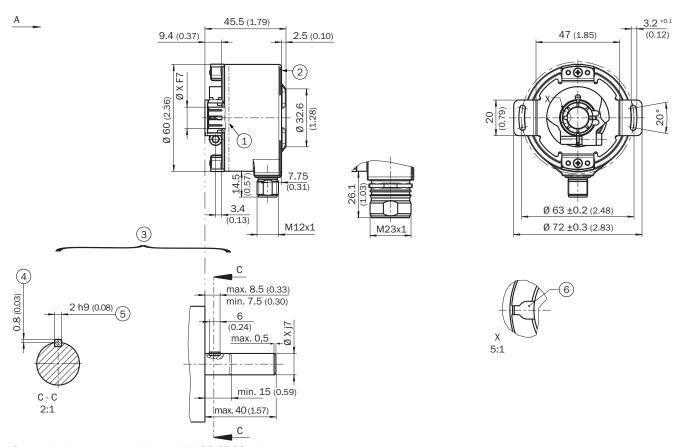
| eCl@ss 5.0 | 27270501 |
|----------------|----------|
| eCl@ss 5.1.4 | 27270501 |
| eCl@ss 6.0 | 27270590 |
| eCl@ss 6.2 | 27270590 |
| eCl@ss 7.0 | 27270501 |
| eCl@ss 8.0 | 27270501 |
| eCl@ss 8.1 | 27270501 |
| eCl@ss 9.0 | 27270501 |
| eCl@ss 10.0 | 27270501 |
| eCl@ss 11.0 | 27270501 |
| eCl@ss 12.0 | 27270501 |
| ETIM 5.0 | EC001486 |
| ETIM 6.0 | EC001486 |
| ETIM 7.0 | EC001486 |
| ETIM 8.0 | EC001486 |
| UNSPSC 16.0901 | 41112113 |

²⁾ Allow for self-heating of approx. 3.0 K per 1,000 rpm regarding the permissible operating temperature.

³⁾ Checked to operation with vector length monitoring.

Dimensional drawing (Dimensions in mm (inch))

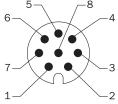
Blind hollow shaft, radial male connector M12 and M23



General tolerances according to DIN ISO 2768-mk

- ① Operating temperature measuring point (freely selectable, around the housing surface area in each case, approx. 3 mm away from flange)
- ② Measuring point vibration (respectively at the housing face, approx. 3 mm away from the cover edge)
- 3 Attachment specifications
- 4 Max. 0.4 at Ø 5/8"
- ⑤ Feather key DIN 6885-A 2x2x6
- 6 Feather key groove

PIN assignment



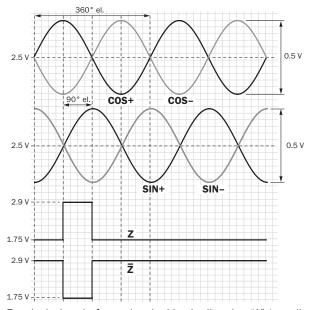
View of M12 male device connector on encoder

| PIN Male connector M12, 8-pin | PIN Male connec- tor M23, 12-pin | Wire colors (ca- ble connection) | Signal | Explanation |
|----------------------------------|--|-------------------------------------|--------|-------------|
| 1 | 6 | Brown | - COS | Signal wire |
| 2 | 5 | White | + COS | Signal wire |
| 3 | 1 | Black | - SIN | Signal wire |

| PIN Male connector M12, 8-pin | PIN Male connec- tor M23, 12-pin | Wire colors (ca- ble connection) | Signal | Explanation |
|----------------------------------|--|-------------------------------------|----------------|---|
| 4 | 8 | Pink | + SIN | Signal wire |
| 5 | 4 | Yellow | | Signal (do not use for safety operating mode) |
| 6 | 3 | Violet | Z | Signal (do not use for safety operating mode) |
| 7 | 10 | Blue | GND | Ground connection |
| 8 | 12 | Red | U _S | Supply voltage (volt-free to housing) |
| - | 9 | - | N.C. | Not assigned |
| - | 2 | - | N.C. | Not assigned |
| - | 11 | - | N.C. | Not assigned |
| - | 7 | - | N.C. | Not assigned |
| Screen | Screen | Screen | Screen | Screen connected to encoder housing Screen connected to housing on encoder side. Connected to ground on control side. |

Diagrams

Signal SIN/COS before differential generation

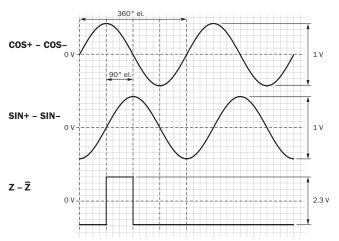


For clockwise shaft rotation, looking in direction "A" (see dimensional drawing)

| Signal | Interface signals | Signal before differ- ential generation At load 120 Ω | Signal offset |
|----------------------------------|----------------------|---|---------------|
| + SIN - SIN + COS - COS | Analog, differential | $0.5 V_{SS} \pm 20 \%$ | 2,5 V ± 10 % |

| Signal | Interface signals | Signal before differ- ential generation At load 120 Ω | Signal offset |
|---------|----------------------|---|---------------|
| Z Z_ | Digital differential | Low: 1,75 V \pm 15 %, High: 2,90 V \pm 15 % | |

Signal SIN/COS after differential generation



For clockwise shaft rotation, looking in direction "A" (see dimensional drawing)

| Supply voltage | Output |
|----------------|-----------------------------|
| 4,5 V 5,5 V | Sin/Cos 1.0 V _{PP} |

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