

DBS60E-TBZZ00S30

DBS60

**INCREMENTAL ENCODERS** 



Illustration may differ

### Ordering information

| Туре             | Part no. |
|------------------|----------|
| DBS60E-TBZZ00S30 | 1078426  |

Other models and accessories → www.sick.com/DBS60



#### Detailed technical data

#### **Features**

| Special device            | 1   |  |
|---------------------------|---|--|
| Specialty                 | Customized pcb with 16 zero pulse positions Cable, 8-wire, universal, 6 m with USB connector, A-code, customized pin allocation |  |
| Standard reference device | DBS60E-TBEK01000, 1072396   |  |

#### Performance

| Pulses per revolution    | 1,024                                 |  |
|--------------------------|---------------------------------------|--|
| Measuring step           | ≤ 90°, electric/pulses per revolution |  |
| Measuring step deviation | ± 18° / pulses per revolution         |  |
| Error limits             | Measuring step deviation x 3          |  |
| Duty cycle               | ≤ 0.5 ± 5 %                           |  |

#### Interfaces

| Communication interface        | Incremental             |  |
|--------------------------------|-------------------------|--|
| Communication Interface detail | HTL / Push pull         |  |
| Number of signal channels      | 6-channel               |  |
| Initialization time            | < 5 ms <sup>1)</sup>    |  |
| Output frequency               | + 300 kHz <sup>2)</sup> |  |
| Load current                   | ≤ 30 mA, per channel    |  |
| Power consumption              | ≤ 1 W (without load)    |  |

 $<sup>^{1)}</sup>$  Valid signals can be read once this time has elapsed.

#### Electrical data

| Connection type            | Cable, 8-wire, with USB port, universal, 6 m, A-coded <sup>1)</sup> Customer-specific pin assignment |  |
|----------------------------|--|--|
| Supply voltage             | 10 27 V  |  |
| Reference signal, number   | 1  |  |
| Reference signal, position | 180°, electric, logically gated with A and B   |  |

<sup>1)</sup> The universal cable connection is positioned so that it is possible to lay it without bends in a radial or axial direction.

<sup>&</sup>lt;sup>2)</sup> Up to 450 kHz on request.

 $<sup>^{2)}\,\</sup>mbox{Short-circuit opposite to another channel, US or GND permissable for maximum 30 s.$ 

<sup>3)</sup> This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40 °C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

| Reverse polarity protection             | ✓                             |
|---|-------------------------------|
| Short-circuit protection of the outputs | <b>✓</b> <sup>2)</sup>        |
| MTTFd: mean time to dangerous failure   | 500 years (EN ISO 13849-1) 3) |

<sup>1)</sup> The universal cable connection is positioned so that it is possible to lay it without bends in a radial or axial direction.

#### Mechanical data

| Mechanical design              | Through hollow shaft, Front clamp                           |  |
|--------------------------------|---|--|
| Shaft diameter                 | 8 mm  |  |
| Flange type / stator coupling  | 2-sided stator coupling, slot, screw hole circle 63–83 mm   |  |
| Weight                         | + 0.25 kg <sup>1)</sup>                                     |  |
| Shaft material                 | Stainless steel   |  |
| Flange material                | Aluminum  |  |
| Housing material               | Aluminum  |  |
| Material, cable                | PVC   |  |
| Start up torque                | + 0.5 Ncm (+20 °C)  |  |
| Operating torque               | 0.4 Ncm (+20 °C)  |  |
| Permissible movement static    | $\pm$ 0.3 mm (radial)<br>$\pm$ 0.5 mm (axial) <sup>2)</sup> |  |
| Permissible movement dynamic   | $\pm$ 0.1 mm (radial)<br>$\pm$ 0.2 mm (axial) <sup>2)</sup> |  |
| Operating speed                | 6,000 min <sup>-1 3)</sup>                                  |  |
| Maximum operating speed        | 9,000 min <sup>-1 4)</sup>                                  |  |
| Moment of inertia of the rotor | 50 gcm <sup>2</sup>   |  |
| Bearing lifetime               | 3.6 x 10 <sup>9</sup> revolutions                           |  |
| Angular acceleration           | ≤ 500,000 rad/s²  |  |
|                                |   |  |

 $<sup>^{1)}</sup>$  Based on encoder with male connector or cable with male connector.

#### Ambient data

| EMC                           | According to EN 61000-6-2 and EN 61000-6-3                                |  |
|-------------------------------|---|--|
| Enclosure rating              | IP65, housing side (IEC 60529) <sup>1)</sup> IP65, shaft side (IEC 60529) |  |
| Permissible relative humidity | 90 % (Condensation not permitted)   |  |
| Operating temperature range   | -20 °C +85 °C <sup>2)</sup>   |  |
| Storage temperature range     | -40 °C +100 °C, without package   |  |
| Resistance to shocks          | 250 g, 3 ms (EN 60068-2-27)   |  |

<sup>1)</sup> With mating connector fitted

 $<sup>^{2)}\,\</sup>mbox{Short-circuit}$  opposite to another channel, US or GND permissable for maximum 30 s.

<sup>3)</sup> This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40°C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

 $<sup>^{2)}\,\</sup>mathrm{Not}$  apllicable for stator coupling type C and K.

 $<sup>^{3)}</sup>$  Allow for self-heating of 2.6 K per 1,000 rpm when designing the operating temperature range.

<sup>&</sup>lt;sup>4)</sup> Maximum speed which does not cause mechanical damage to the encoder. Impact on the service life and signal quality is possible. Please note the maximum output frequency.

<sup>&</sup>lt;sup>2)</sup> These values relate to all mechanical versions including recommended accessories unless otherwise noted.

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| Resistance to vibration | 30 g, 10 Hz 2,000 Hz (EN 60068-2-6) |
|-------------------------|-------------------------------------|

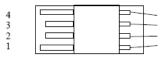
 $<sup>^{1)}</sup>$  With mating connector fitted.

#### Classifications

| eCl@ss 5.0     | 27270501 |
|----------------|----------|
| eCl@ss 5.1.4   | 27270501 |
| eCl@ss 6.0     | 27270590 |
| eCl@ss 6.2     | 27270590 |
| eCl@ss 7.0     | 27270501 |
| eCl@ss 8.0     | 27270501 |
| eCl@ss 8.1     | 27270501 |
| eCl@ss 9.0     | 27270501 |
| eCl@ss 10.0    | 27270501 |
| eCl@ss 11.0    | 27270501 |
| eCl@ss 12.0    | 27270501 |
| ETIM 5.0       | EC001486 |
| ETIM 6.0       | EC001486 |
| ETIM 7.0       | EC001486 |
| ETIM 8.0       | EC001486 |
| UNSPSC 16.0901 | 41112113 |
|                |          |

## PIN assignment



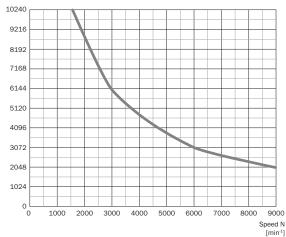


| USB connector | TTI/HTL signal  | Explanation                           |
|---------------|-----------------|---------------------------------------|
| 1             | +U <sub>S</sub> | Supply voltage (volt-free to housing) |
| 2             | В               | Signal cable                          |
| 3             | Z               | Signal cable                          |
| 4             | GND             | Ground connection of the encoder      |
|               |                 | Shield connected to housing on side   |
|               |                 | of encoder. Connected to ground on    |
| Shield        | Shield          | side of control.                      |

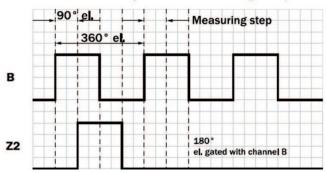
<sup>2)</sup> These values relate to all mechanical versions including recommended accessories unless otherwise noted.

## Diagrams

Pulses per revolution



Width of the zero pulse in relation to a pulse period.



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