**MOTOR FEEDBACK SYSTEMS ROTARY HIPERFACE®** 



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Illustration may differ

#### Ordering information

Туре	Part no.
SRS50-HZA0-S47	1087377

Other models and accessories → www.sick.com/SRS\_SRM50

CE

### Detailed technical data

Features		
Special device	4	
Specialty	Stator coupling from EFx50 Modified Proposed fitting	
Standard reference device	SRS50-HFA0-K22, 1037068	
Performance		
Sine/cosine periods per revolution	1,024	
Number of the absolute ascertainable revo- lutions	1	
Total number of steps	32,768	
Measuring step	$0.3\ensuremath{^{\prime\prime}}$ For interpolation of the sine/cosine signals with, e. g., 12 bits	
Integral non-linearity	Typ. $\pm$ 45 ", Error limits for evaluating sine/cosine period, without mechanical tension of the stator coupling	
Differential non-linearity	± 7 ", Non-linearity within a sine/cosine period	
Operating speed	$\leq$ 6,000 min <sup>-1</sup> , up to which the absolute position can be reliably produced	
Available memory area	1,792 Byte	
System accuracy	± 52 ″	
Interfaces		
Type of code for the absolute value	Binary	
Code sequence	Increasing, when turning the shaft For clockwise rotation, looking in direction "A" (see dimen- sional drawing), For clockwise shaft rotation, looking in direction "A" (see dimensional drawing)	
Communication interface	HIPERFACE®	
Electrical data		
Connection type	Male connector, 8-pin, radial	
Supply voltage	7 V DC 12 V DC	
Recommended supply voltage	8 V DC	
Current consumption	80 mA <sup>1)</sup>	
Output frequency for sine/cosine signals	≤ 200 kHz	
MTTF: mean time to dangerous failure	235 years (EN ISO 13849) <sup>2)</sup>	

<sup>1)</sup> Without load.

<sup>2)</sup> This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 60°C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

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#### Mechanical data

Shaft version	Tapered shaft
Flange type / stator coupling	Spring mounting plate, Spring mounting plate
Dimensions	See dimensional drawing
Weight	≤ 0.2 kg
Moment of inertia of the rotor	10 gcm <sup>2</sup>
Operating speed	≤ 12,000 min <sup>-1</sup>
Angular acceleration	≤ 200,000 rad/s²
Operating torque	0.2 Ncm
Start up torque	+ 0.4 Ncm
Permissible movement static	± 0.2 mm radial ± 0.75 mm axial <sup>1)</sup>
Permissible movement dynamic	$\pm$ 0.025 mm radial <sup>2)</sup> $\pm$ 0.2 mm axial
Angular motion perpendicular to the rota- tional axis, static	± 0.005 mm/mm
Angular motion perpendicular to the rota- tional axis, dynamic	± 0.0025 mm/mm
Life of ball bearings	3.6 x 10 <sup>9</sup> revolutions

<sup>1)</sup> Based on new proposed fitting.

 $^{2)}\,\mathrm{lt}$  is powered by a voltage-free extension.

#### Ambient data

Operating temperature range	-30 °C +115 °C
Storage temperature range	-40 °C +125 °C, without package
Relative humidity/condensation	90 %, Condensation not permitted
Resistance to shocks	100 g, 10 ms, 10 ms (according to EN 60068-2-27)
Frequency range of resistance to vibrations	20 g, 10 Hz 2,000 Hz (EN 60068-2-6)
EMC	According to EN 61000-6-2 and EN 61000-6-3 $^{1)}$
Enclosure rating	IP40, with mating connector inserted (IEC 60529)

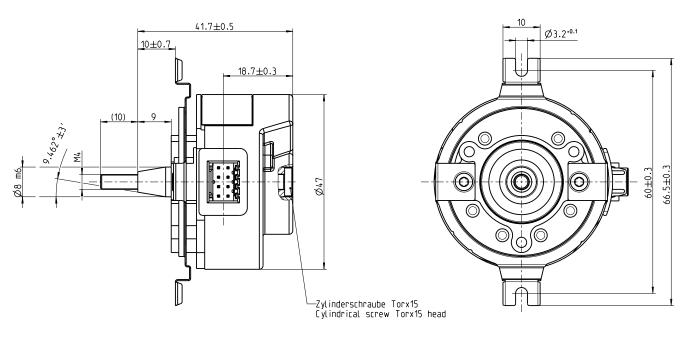
<sup>1)</sup> The EMC according to the standards quoted is achieved when the motor feedback system is mounted in an electrically conductive housing, which is connected to the central earthing point of the motor controller via a cable screen. The GND-(0 V) connection of the supply voltage is also grounded here. If other shielding concepts are used, users must perform their own tests.

Classifications	
ECLASS 5.0	27270590
ECLASS 5.1.4	27270590
ECLASS 6.0	27270590
ECLASS 6.2	27270590
ECLASS 7.0	27270590
ECLASS 8.0	27270590
ECLASS 8.1	27270590
ECLASS 9.0	27270590
ECLASS 10.0	27273805
ECLASS 11.0	27273901

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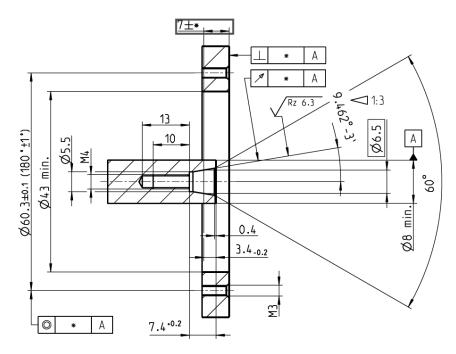
ECLASS 12.0	27273901
ETIM 5.0	EC001486
ETIM 6.0	EC001486
ETIM 7.0	EC001486
ETIM 8.0	EC001486
UNSPSC 16.0901	41112113

Dimensional drawing (Dimensions in mm (inch))



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#### Attachment specifications



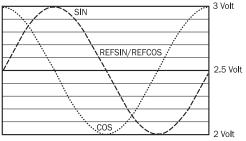
- Größe der Toleranz reduziert die zulössige Wellenbewegung siehe Datenblatt
- Size of tolerance reduce the allowed movement of the shaft see data sheet.

Gewindebohrungen gemäß DIN 13 mit Senkungen gemäß DIN 76 min. 1.05x Gewindedurchmesser

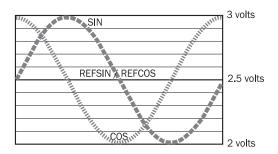
Thread holes according DIN 13 with counterbore according DIN 76 min. 1.05 x diameter of thread

#### Diagrams

Signal specification of the process channel



Signal diagram for clockwise rotation of the shaft looking in direction "A" (see dimensional drawing)1 period =  $360^{\circ}$  : 1024 Signal diagram for clockwise rotation of the shaft looking in direction "A" (see dimensional drawing)1 period =  $360^{\circ}$  : 1024



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Online data sheet

