

# DFS60B-S1EZ00S02

DFS60

**INCREMENTAL ENCODERS**

**SICK**  
Sensor Intelligence.

Illustration may differ

### Ordering information

Type	Part no.
DFS60B-S1EZ00S02	1104944

Other models and accessories → [www.sick.com/DFS60](http://www.sick.com/DFS60)



### Detailed technical data

#### Features

<b>Special device</b>	✓
<b>Specialty</b>	Number of lines 10,000 Male connector, M23 (6027537), 12-pin on cable end
<b>Standard reference device</b>	DFS60B-S1EK10000, 1056192

#### Performance

<b>Pulses per revolution</b>	10,000 <sup>1)</sup>
<b>Measuring step</b>	90°, electric/pulses per revolution
<b>Measuring step deviation at non binary number of lines</b>	± 0.01°
<b>Error limits</b>	± 0.05°

<sup>1)</sup> See maximum revolution range.

#### Interfaces

<b>Communication interface</b>	Incremental
<b>Communication Interface detail</b>	HTL / Push pull
<b>Number of signal channels</b>	6-channel
<b>Initialization time</b>	40 ms
<b>Output frequency</b>	≤ 600 kHz
<b>Load current</b>	≤ 30 mA
<b>Power consumption</b>	≤ 0.5 W (without load)

#### Electrical data

<b>Connection type</b>	Cable, 8-wire, with male connector, M23, 12-pin, universal, 1.5 m <sup>1)</sup>
<b>Supply voltage</b>	10 ... 32 V
<b>Reference signal, number</b>	1
<b>Reference signal, position</b>	90°, electric, logically gated with A and B
<b>Reverse polarity protection</b>	✓
<b>Short-circuit protection of the outputs</b>	✓ <sup>2)</sup>

<sup>1)</sup> The universal cable connection is positioned so that it is possible to lay it without bends in a radial or axial direction.

<sup>2)</sup> Short-circuit opposite to another channel, US or GND permissible for maximum 30 s.

<sup>3)</sup> This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40°C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

<b>MTTFd: mean time to dangerous failure</b>	300 years (EN ISO 13849-1) <sup>3)</sup>
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### Mechanical data

<b>Mechanical design</b>	Solid shaft, Servo flange
<b>Shaft diameter</b>	6 mm
<b>Shaft length</b>	10 mm
<b>Weight</b>	+ 0.3 kg
<b>Shaft material</b>	Stainless steel
<b>Flange material</b>	Aluminum
<b>Housing material</b>	Aluminum die cast
<b>Start up torque</b>	0.5 Ncm (+20 °C)
<b>Operating torque</b>	0.3 Ncm (+20 °C)
<b>Permissible shaft loading</b>	80 N (radial) 40 N (axial)
<b>Operating speed</b>	≤ 9,000 min <sup>-1</sup> <sup>1)</sup>
<b>Moment of inertia of the rotor</b>	6.2 gcm <sup>2</sup>
<b>Bearing lifetime</b>	3.6 x 10 <sup>10</sup> revolutions
<b>Angular acceleration</b>	≤ 500,000 rad/s <sup>2</sup>

<sup>1)</sup> Allow for self-heating of 3.3 K per 1,000 rpm when designing the operating temperature range.

### Ambient data

<b>EMC</b>	According to EN 61000-6-2 and EN 61000-6-4
<b>Enclosure rating</b>	IP67, Housing side, male connector (IEC 60529) <sup>1)</sup> IP65, shaft side (IEC 60529)
<b>Permissible relative humidity</b>	90 % (Condensation not permitted)
<b>Operating temperature range</b>	-40 °C ... +100 °C <sup>2)</sup> -30 °C ... +100 °C <sup>3)</sup>
<b>Storage temperature range</b>	-40 °C ... +100 °C, without package
<b>Resistance to shocks</b>	70 g, 6 ms (EN 60068-2-27)
<b>Resistance to vibration</b>	30 g, 10 Hz ... 2,000 Hz (EN 60068-2-6)

<sup>1)</sup> With mating connector fitted.

<sup>2)</sup> Stationary position of the cable.

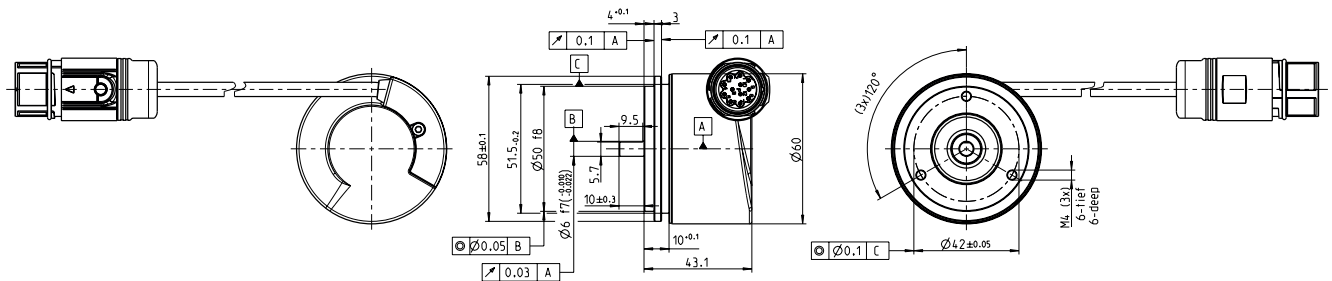
<sup>3)</sup> Flexible position of the cable.

### Classifications

<b>eCI@ss 5.0</b>	27270501
<b>eCI@ss 5.1.4</b>	27270501
<b>eCI@ss 6.0</b>	27270590
<b>eCI@ss 6.2</b>	27270590
<b>eCI@ss 7.0</b>	27270501
<b>eCI@ss 8.0</b>	27270501

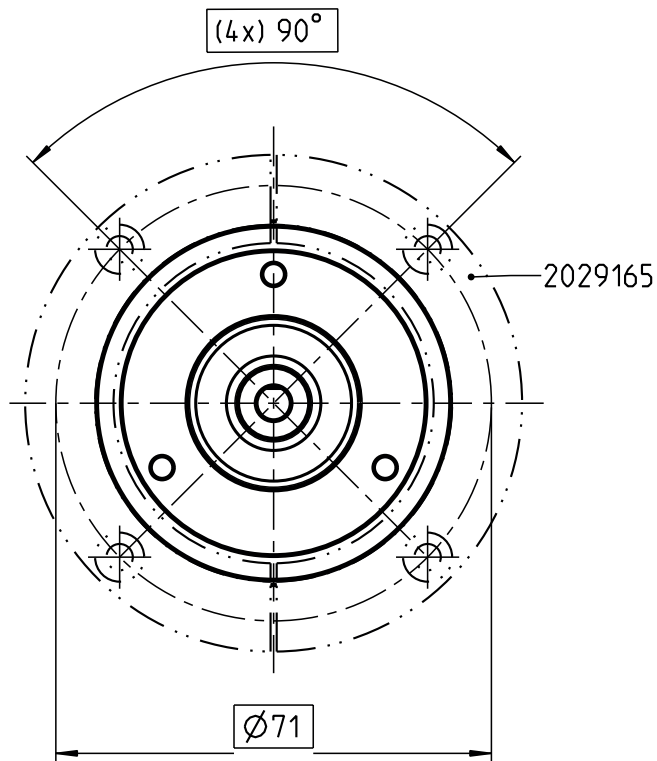
<b>eCl@ss 8.1</b>	27270501
<b>eCl@ss 9.0</b>	27270501
<b>eCl@ss 10.0</b>	27270501
<b>eCl@ss 11.0</b>	27270501
<b>eCl@ss 12.0</b>	27270501
<b>ETIM 5.0</b>	EC001486
<b>ETIM 6.0</b>	EC001486
<b>ETIM 7.0</b>	EC001486
<b>ETIM 8.0</b>	EC001486
<b>UNSPSC 16.0901</b>	41112113

### Dimensional drawing (Dimensions in mm (inch))

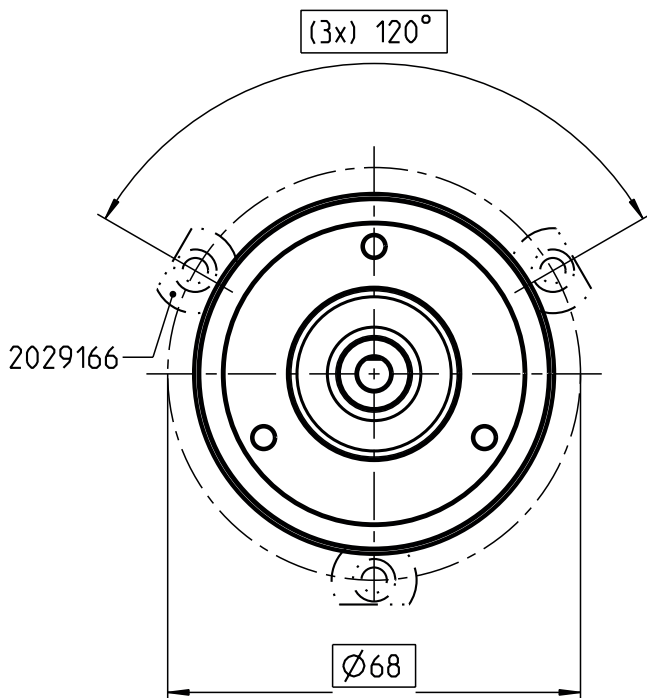


### Attachment specifications

Mounting requirements for half-shell servo clamp



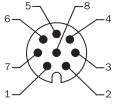
Mounting requirements for small servo clamp



### PIN assignment

#### Cable, 8-wire

View of M12 male device connector on encoder



View of M23 male device connector

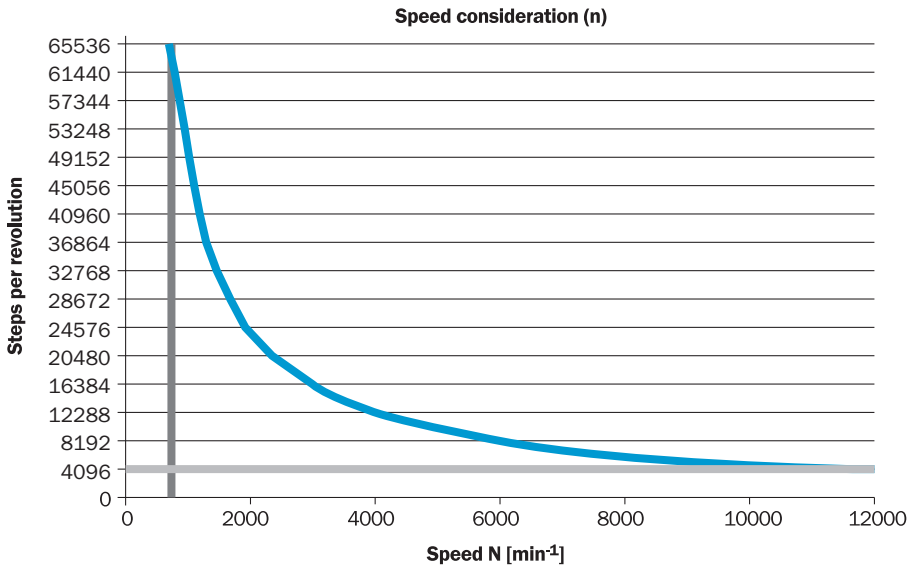


PIN, 8-pin, M12 male connector	PIN, 12-pin, M23 male connector	Color of the wires for encoders with cable outlet	TTL/HTL signal	Sin/cos 1.0 V <sub>ss</sub>	Explanation
1	6	Brown	A	COS-	Signal wire
2	5	White	A	COS+	Signal wire
3	1	Black	B	SIN-	Signal wire
4	8	Pink	B	SIN+	Signal wire
5	4	Yellow	Z	Z	Signal wire
6	3	Violet	Z	Z	Signal wire
7	10	Blue	GND	GND	Ground connection of the encoder
8	12	Red	+U <sub>1</sub>	+U <sub>s</sub>	Supply voltage (volt-free to housing)
-	9	-	n.c.	n.c.	Not assigned
-	2	-	n.c.	n.c.	Not assigned
-	11	-	n.c.	n.c.	Not assigned
-	7 <sup>1)</sup>	-	O-SET <sup>1)</sup>	n.c.	Set zero pulse <sup>1)</sup>
Screen	Screen	Screen	Screen	Screen	Screen connected to housing on encoder side. Connected to ground on control side.

<sup>1)</sup> For electrical interfaces only: M, U, V with O-SET function on PIN 7 on M23 male connector. The O-SET input is used to set the zero pulse on the current shaft position. If the O-SET input is connected to U<sub>s</sub> for longer than 250 ms after it had previously been unassigned for at least 1.000 ms or had been connected to the GND, the current position of the shaft is assigned to the zero pulse signal "Z".

### Diagrams

#### Maximum revolution range



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