

# EDM35-0VF0A024A

sHub

MOTOR FEEDBACK SYSTEMS ROTARY HIPERFACE DSL®





## **Ordering information**

Туре	Part no.
EDM35-0VF0A024A	1106846

Other models and accessories → www.sick.com/sHub

Illustration may differ



### Detailed technical data

#### Performance

Position	
Resolution per revolution	24 bit
System accuracy	± 25 ″ <sup>1)</sup>
Signal noise (σ)	± 1" <sup>2)</sup>
Number of the absolute ascertainable revolutions	

<sup>1)</sup> In accordance with DIN ISO 1319-1, position of the upper and lower error limit depends on the installation situation, specified value refers to a symmetrical position, i.e. deviation in upper and lower direction is the same.

#### Interfaces

Code sequence	Increasing, when turning the shaft For clockwise rotation, looking in direction "A" (see dimensional drawing)
Communication interface	HIPERFACE DSL®
Initialization time	≤ 500 ms <sup>1)</sup>
Measurement external temperature resistance	32-bit value, without prefix (1 $\Omega$ ) 0 209.600 $\Omega$ $^{2)}$

<sup>&</sup>lt;sup>1)</sup> From reaching a permitted operating voltage.

#### Electrical data

Supply voltage	7 V 12 V
Warm-up time voltage ramp	Max. 180 ms <sup>1)</sup>
Current consumption	$\leq$ 150 mA $^{2)}$
Compatible with sHub®	✓
MTTF: mean time to dangerous failure	150 years (EN ISO 13849) <sup>3)</sup>

 $<sup>^{1)}</sup>$  Duration of voltage ramp between 0 and 7.0 V.

 $<sup>^{2)}</sup>$  Repeatability standard deviation in accordance with DIN 1319-1:1995.

<sup>2)</sup> Without sensor tolerance; at -40 °C ... +160 °C: NTC +-2K; PTC+-3K (KTY84-130/PT1000). For additional conversion function of PT1000 to KTY84/130, see technical description.

 $<sup>^{2)}</sup>$  Current rating applies when using interface circuit suggestions as shown in HIPERFACE DSL  $\circledR$  manual (8017595).

<sup>&</sup>lt;sup>3)</sup> This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 60°C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

### Mechanical data

Shaft version	Tapered shaft
Dimensions	See dimensional drawing
Weight	≤ 100 g
Moment of inertia of the rotor	5 gcm <sup>2</sup>
Operating speed	≤ 9,000 min <sup>-1</sup>
Angular acceleration	$\leq 250,000 \text{ rad/s}^2$
Start up torque	≤ 0.6 Ncm, +20 °C
Permissible movement static	± 1 mm axial <sup>1)</sup>
Permissible movement dynamic	± 0.1 mm radial
Life of ball bearings	50,000 h at 6,000 min <sup>-1</sup> (at a flange temperature of 70 °C)

 $<sup>^{1)}</sup>$  Temperature expansion, mechanical attachment.

### Ambient data

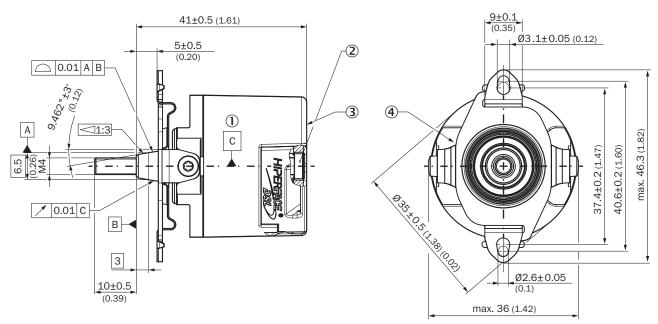
Storage temperature range	-40 °C +125 °C, without package
Relative humidity/condensation	90 %, Condensation not permitted
Resistance to shocks	100 g, 6 ms (according to EN 60068-2-27)
Frequency range of resistance to vibrations	50 g, 10 Hz 2,000 Hz (EN 60068-2-6)
EMC	According to EN 61000-6-2, EN 61000-6-4 and IEC 61326-3 1)
Enclosure rating	IP40, When cover is closed and mating connector is attached (IEC 60529-1)

<sup>1)</sup> According to the listed standards, EMC is guaranteed if the motor feedback system with mating connector inserted is connected to the central grounding point of the motor controller via a cable shield. If other shielding concepts are used, users must perform their own tests. Class A device.

## Classifications

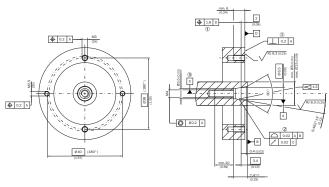
ECLASS 5.0	27270590
ECLASS 5.1.4	27270590
ECLASS 6.0	27270590
ECLASS 6.2	27270590
ECLASS 7.0	27270590
ECLASS 8.0	27270590
ECLASS 8.1	27270590
ECLASS 9.0	27270590
ECLASS 10.0	27273805
ECLASS 11.0	27273901
ECLASS 12.0	27273901
ETIM 5.0	EC001486
ETIM 6.0	EC001486
ETIM 7.0	EC001486
ETIM 8.0	EC001486
UNSPSC 16.0901	41112113

# Dimensional drawing (Dimensions in mm (inch))



- ② Torx 15 cylinder screw
- 3 Measuring point for vibrations
- Measuring point for operating temperature

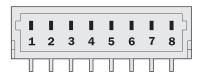
# Attachment specifications



- ① Permanently
- ② Dynamic
- 3 Bearing of the drive shaft

## PIN assignment

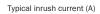
Supply / Communication pin assignment

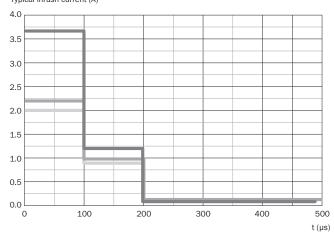


## V connection type

PIN	Signal	Explanation
1	+U <sub>S</sub>	Supply
2	GND	Ground connection
3	DSL-	DSL negative
4	DSL+	DSL positive
5	RxD+	Receiver data positive
6	RxD-	Receiver data negative
7	TxD-	Sender data negative
8	TxD+	Sender data positive
Recommended mating connector: JST (GHR-08V-S)		

# Diagrams





# SICK AT A GLANCE

SICK is one of the leading manufacturers of intelligent sensors and sensor solutions for industrial applications. A unique range of products and services creates the perfect basis for controlling processes securely and efficiently, protecting individuals from accidents and preventing damage to the environment.

We have extensive experience in a wide range of industries and understand their processes and requirements. With intelligent sensors, we can deliver exactly what our customers need. In application centers in Europe, Asia and North America, system solutions are tested and optimized in accordance with customer specifications. All this makes us a reliable supplier and development partner.

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For us, that is "Sensor Intelligence."

# **WORLDWIDE PRESENCE:**

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