**MOTOR FEEDBACK SYSTEMS ROTARY HIPERFACE DSL®** 



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Illustration may differ

#### **Ordering information**

Туре	Part no.
EFM50-2KF0A0S03	1077398

Other models and accessories -> www.sick.com/EFS\_EFM50

CE

#### Detailed technical data

Features		
Special device	$\checkmark$	
Specialty	Housing black	
Standard reference device	EFM50-2KF0A023A, 1073504	
Safety-related parameters		
Safety integrity level	SIL 2 (IEC 61508), SILCL2 (EN 62061) $^{1)}$	
Category	20 years	
Test rate	lh	
Maximum demand rate	216 µs	
Performance level	PL d (EN ISO 13849)	
Safety-related resolution	Channel 1 = 23 bit, channel 2 = 12 bit	

1) For more detailed information on the exact configuration of your machine/unit, please consult your relevant SICK branch office.

#### Performance

Position	
Resolution per revolution	20 bit
Signal noise (o)	± 2 ″
Number of the absolute ascertainable revolutions	,
Available memory area	8,192 Byte
Measurement step per revolution	8,388,608
Vibration	
Measurement principle	Optical

#### Interfaces

Code sequence	Increasing, when turning the shaft For clockwise rotation, looking in direction "A" (see dimensional drawing)
Communication interface	HIPERFACE DSL <sup>®</sup>
Initialization time	Max. 500 ms <sup>1)</sup>
Measurement external temperature resis- tance	32-bit value, without prefix (1 $\Omega)$ 0 209.600 $\Omega$ $^{2)}$

<sup>1)</sup> From reaching a permitted operating voltage.

 $^{2)}$  Without sensor tolerance; at -17  $^{\circ}$  C ... +167  $^{\circ}$  C: NTC +-2K (103 GT); PTC+-3K (KTY84/130/PT1000).

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#### Electrical data

Connection type	Male connector, 4-pin
Supply voltage	7 V 12 V
Warm-up time voltage ramp	Max. 180 ms <sup>1)</sup>
Current consumption	$\leq$ 150 mA <sup>2)</sup>
Output frequency for the digital positionval- ue	0 kHz 75 kHz

 $^{(1)}$  Duration of the voltage ramp between 0 and 7.0 V, see diagram "Current consumption" in the diagram section.

<sup>2)</sup> Current rating applies when using interface circuit suggestions as shown in HIPERFACE DSL ® manual (8017595).

#### Mechanical data

Shaft version	Tapered shaft
Dimensions	See dimensional drawing
Weight	0.2 kg
Moment of inertia of the rotor	10 gcm <sup>2</sup>
Operating speed	≤ 9,000 min <sup>-1</sup>
Angular acceleration	≤ 200,000 rad/s²
Start up torque	≤ 0.4 Ncm
Permissible radial shaft movement	± 0.2 mm <sup>1)</sup>
Permissible axial shaft movement	± 0.95 mm
Permissible movement static	± 0.2 mm
Permissible movement dynamic	± 0.1 mm
Life of ball bearings	3.6 x 10^9 revolutions

<sup>1)</sup> Permitted when using the elastomer stator coupling. When the spring plate stator coupling is being used, voltage-free mounting is assumed.

#### Ambient data

Operating temperature range	-30 °C +115 °C <sup>1)</sup>
Storage temperature range	-40 °C +120 °C, without package
Relative humidity/condensation	90 %, Condensation not permitted
Resistance to shocks	100 g, 6 ms (according to EN 60068-2-27)
Frequency range of resistance to vibrations	30 g, 10 Hz 2,000 Hz (EN 60068-2-6)
EMC	According to EN 61000-6-2, EN 61000-6-3 and IEC 61326-3-1 $^{2)}$
Enclosure rating	IP40, with mating connector inserted and closed cover (IEC 60529-1)

<sup>1)</sup> The max. internal sensor temperature may not exceed 125 °C. The defined measuring point on the encoder (see dimensional drawing) must be used for measuring the operating temperature. For typical values for self-heating, see diagram 3 (electrical) and diagram 4 (mechanical).

<sup>2)</sup> EMC according to the listed standards is guaranteed if the motor feedback system with mating plug inserted is connected to the central grounding point of the motor controller via a cable shield. If other screening concepts are used, users must perform their own tests.

#### Classifications

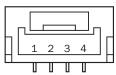
ECLASS 5.0	27270590
ECLASS 5.1.4	27270590
ECLASS 6.0	27270590
ECLASS 6.2	27270590
ECLASS 7.0	27270590

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ECLASS 8.0	27270590
ECLASS 8.1	27270590
ECLASS 9.0	27270590
ECLASS 10.0	27273805
ECLASS 11.0	27273901
ECLASS 12.0	27273901
ETIM 5.0	EC001486
ETIM 6.0	EC001486
ETIM 7.0	EC001486
ETIM 8.0	EC001486
UNSPSC 16.0901	41112113

#### **PIN** assignment

Supply / Communication pin assignment



Integrated in motor cable = J, K

PIN	Signal Explanation	
1		Not connected - no function
2	+U <sub>S</sub> /DSL+	Supply 7 V 12 V
3	GND/DSL-	Ground connection
4		Not connected - no function
Recommended outer diameter of set of stranded wires: 4 mm +0/-0.3 mm		
Recommended mating connector: JST (GHR-04V-S)		

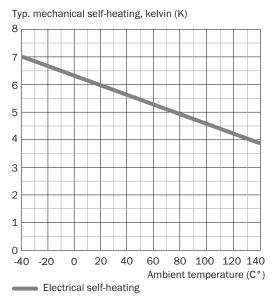
Temperature sensor pin assignment

0 0 2 1		
PIN	Signal	Explanation
1	T+	Thermistor connection
2	Т-	Thermistor connection (to ground)
Recommended outer diameter of set of stranded wires: 2.2 mm $\pm$ 0.1 mm		
Recommended mating connector: Harwin M80-8990205		

#### Diagrams

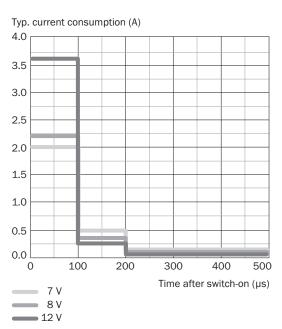
Electrical self-heating

Diagram 3



Power consumption

Diagram 2

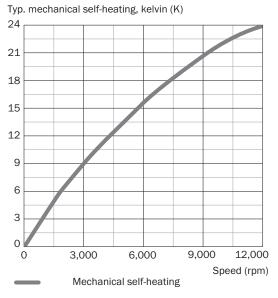


This diagram shows the switch-on current

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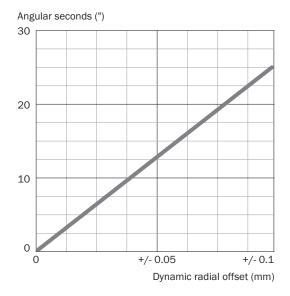
#### Mechanical self-heating

Diagram 4



Error limits

Diagram 1



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#### Recommended accessories

Other models and accessories -> www.sick.com/EFS\_EFM50

	Brief description	Туре	Part no.		
Other mountin	Other mounting accessories				
a a a	Servo clamps, small, for servo flange (clamps, eccentric fastener), 3 pcs, without mount- ing material, without mounting hardware	BEF-WK-RESOL	2039082		
Plug connecto	ors and cables				
	<ul> <li>Connection type head A: Female connector, stranded wire, 4-pin, straight</li> <li>Connection type head B: Flying leads</li> <li>Signal type: HIPERFACE DSL<sup>®</sup></li> <li>Cable: 0.2 m, 2-wire</li> <li>Description: HIPERFACE DSL<sup>®</sup>, unshielded</li> </ul>	DOL-0B02-G0M2XC2	2079920		
$\bigcup$	<ul> <li>Connection type head A: Female connector, stranded wire, 4-pin, straight</li> <li>Connection type head B: Flying leads</li> <li>Signal type: HIPERFACE DSL<sup>®</sup></li> <li>Cable: 0.36 m, 2-wire</li> <li>Description: HIPERFACE DSL<sup>®</sup>, twisted, shielded</li> </ul>	DOL-0B02-GOM3AC2	2108944		

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We have extensive experience in a wide range of industries and understand their processes and requirements. With intelligent sensors, we can deliver exactly what our customers need. In application centers in Europe, Asia and North America, system solutions are tested and optimized in accordance with customer specifications. All this makes us a reliable supplier and development partner.

Comprehensive services complete our offering: SICK LifeTime Services provide support throughout the machine life cycle and ensure safety and productivity.

For us, that is "Sensor Intelligence."

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Online data sheet

