



DFS60B-BGEK00512

DFS60

INCREMENTAL ENCODERS

SICK
Sensor Intelligence.



Illustration may differ



Ordering information

| Type | Part no. |
|------------------|----------|
| DFS60B-BGEK00512 | 1094276 |

Other models and accessories → www.sick.com/DFS60

Detailed technical data

Performance

| | |
|---|-------------------------------------|
| Pulses per revolution | 512 ¹⁾ |
| Measuring step | 90°, electric/pulses per revolution |
| Measuring step deviation at binary number of lines | ± 0.008° |
| Error limits | ± 0.05° |

¹⁾ See maximum revolution range.

Interfaces

| | |
|---------------------------------------|------------------------|
| Communication interface | Incremental |
| Communication Interface detail | HTL / Push pull |
| Number of signal channels | 6-channel |
| Initialization time | 40 ms |
| Output frequency | ≤ 600 kHz |
| Load current | ≤ 30 mA |
| Power consumption | ≤ 0.5 W (without load) |

Electrical data

| | |
|--|---|
| Connection type | Cable, 8-wire, universal, 1.5 m ¹⁾ |
| Supply voltage | 10 ... 32 V |
| Reference signal, number | 1 |
| Reference signal, position | 90°, electric, logically gated with A and B |
| Reverse polarity protection | ✓ |
| Short-circuit protection of the outputs | ✓ ²⁾ |
| MTTFd: mean time to dangerous failure | 300 years (EN ISO 13849-1) ³⁾ |

¹⁾ The universal cable connection is positioned so that it is possible to lay it without bends in a radial or axial direction.

²⁾ Short-circuit opposite to another channel, US or GND permissible for maximum 30 s.

³⁾ This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40°C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

Mechanical data

| | |
|---------------------------------------|---|
| Mechanical design | Blind hollow shaft |
| Shaft diameter | 14 mm |
| Weight | + 0.2 kg |
| Shaft material | Stainless steel |
| Flange material | Aluminum |
| Housing material | Aluminum die cast |
| Start up torque | 0.8 Ncm (+20 °C) |
| Operating torque | 0.6 Ncm (+20 °C) |
| Permissible movement static | ± 0.3 mm (radial) ± 0.5 mm (axial) |
| Permissible movement dynamic | ± 0.1 mm (radial) ± 0.2 mm (axial) |
| Operating speed | ≤ 6,000 min ⁻¹ ¹⁾ |
| Moment of inertia of the rotor | 40 gcm ² |
| Bearing lifetime | 3.6 x 10 ¹⁰ revolutions |
| Angular acceleration | ≤ 500,000 rad/s ² |

¹⁾ Allow for self-heating of 3.3 K per 1,000 rpm when designing the operating temperature range.

Ambient data

| | |
|--------------------------------------|--|
| EMC | According to EN 61000-6-2 and EN 61000-6-4 |
| Enclosure rating | IP67, housing side, cable connection (IEC 60529) IP65, shaft side (IEC 60529) |
| Permissible relative humidity | 90 % (Condensation not permitted) |
| Operating temperature range | -40 °C ... +100 °C ¹⁾ -30 °C ... +100 °C ²⁾ |
| Storage temperature range | -40 °C ... +100 °C, without package |
| Resistance to shocks | 70 g, 6 ms (EN 60068-2-27) |
| Resistance to vibration | 30 g, 10 Hz ... 2,000 Hz (EN 60068-2-6) |

¹⁾ Stationary position of the cable.

²⁾ Flexible position of the cable.

Classifications

| | |
|---------------------|----------|
| eCl@ss 5.0 | 27270501 |
| eCl@ss 5.1.4 | 27270501 |
| eCl@ss 6.0 | 27270590 |
| eCl@ss 6.2 | 27270590 |
| eCl@ss 7.0 | 27270501 |
| eCl@ss 8.0 | 27270501 |
| eCl@ss 8.1 | 27270501 |
| eCl@ss 9.0 | 27270501 |
| eCl@ss 10.0 | 27270501 |
| eCl@ss 11.0 | 27270501 |
| eCl@ss 12.0 | 27270501 |

| | |
|-----------------------|----------|
| ETIM 5.0 | EC001486 |
| ETIM 6.0 | EC001486 |
| ETIM 7.0 | EC001486 |
| ETIM 8.0 | EC001486 |
| UNSPSC 16.0901 | 41112113 |

Dimensional drawing (Dimensions in mm (inch))

Blind hollow shaft, cable



General tolerances according to DIN ISO 2768-mk

① Cable diameter = 5.6 mm +/- 0.2 mm bend radius = 30 mm

PIN assignment



| PIN Male connector M12, 8-pin | PIN Male connector M23, 12-pin | Wire colors (cable connection) | TTL/HTL signal | Sin/Cos 1.0 V _{pp} | Explanation |
|----------------------------------|-----------------------------------|--------------------------------|----------------|-----------------------------|-------------|
| 1 | 6 | Brown | A | COS- | Signal wire |

| PIN Male connector M12, 8-pin | PIN Male connector M23, 12-pin | Wire colors (cable connection) | TTL/HTL signal | Sin/Cos 1.0 V _{pp} | Explanation |
|----------------------------------|-----------------------------------|--------------------------------|---------------------|-----------------------------|---|
| 2 | 5 | White | A | COS+ | Signal wire |
| 3 | 1 | Black | \bar{B} | SIN- | Signal wire |
| 4 | 8 | Pink | B | SIN+ | Signal wire |
| 5 | 4 | Yellow | \bar{Z} | \bar{Z} | Signal wire |
| 6 | 3 | Purple | Z | Z | Signal wire |
| 7 | 10 | Blue | GND | GND | Ground connection |
| 8 | 12 | Red | +U _S | +U _S | Supply voltage |
| - | 9 | - | N.c. | N.c. | Not assigned |
| - | 2 | - | N.c. | N.c. | Not assigned |
| - | 11 | - | N.c. | N.c. | Not assigned |
| - | 7 ¹⁾ | Orange | 0-SET ¹⁾ | N.c. | Set zero pulse ¹⁾ |
| Screen | Screen | Screen | Screen | Screen | Screen connected to housing on encoder side. Connected to ground on control side. |

1)

For electrical interfaces only: M, U, V, W with 0-SET function on PIN 7 on M23 plug. The 0-SET input is used to set the zero pulse to the current shaft position. If the 0-SET input is applied to US for longer than 250 ms after it has previously been open or applied to GND for at least 1,000 ms, the current shaft position is assigned zero pulse signal "Z".

Diagrams

Signal outputs



CW with view on the encoder shaft in direction "A", compare dimensional drawing.

Maximum revolution range



| Supply voltage | Output |
|-----------------|--------|
| 4,5 V ... 5,5 V | TTL |
| 10 V ... 32 V | TTL |
| 10 V ... 32 V | HTL |

Recommended accessories

Other models and accessories → www.sick.com/DFS60

| | Brief description | Type | Part no. |
|---|---|------------------|----------|
| Flanges | | | |
|  | Standard stator coupling | BEF-DS00XFX | 2056812 |
| Other mounting accessories | | | |
|  | Clamping ring for metal hollow shaft ⁵ , metal | BEF-KR-M | 2064709 |
| Plug connectors and cables | | | |
|  | Head A: female connector, JST, 8-pin, straight Head B: Flying leads Cable: Incremental, SSI, PUR, halogen-free, shielded, 5 m | DOL-0J08-G05MAA3 | 2046876 |
| | Head A: female connector, JST, 8-pin, straight Head B: Flying leads Cable: Incremental, SSI, PUR, halogen-free, shielded, 0,5 m | DOL-0J08-G0M5AA3 | 2046873 |
| | Head A: female connector, JST, 8-pin, straight Head B: Flying leads Cable: Incremental, SSI, PUR, halogen-free, shielded, 10 m | DOL-0J08-G10MAA3 | 2046877 |

| | Brief description | Type | Part no. |
|--|--|------------------|----------|
|  | Head A: female connector, JST, 8-pin, straight Head B: Flying leads Cable: SSI, Incremental, PUR, halogen-free, shielded, 1.5 m | DOL-0J08-G1M5AA6 | 2048590 |
| | Head A: female connector, JST, 8-pin, straight Head B: Flying leads Cable: SSI, Incremental, PUR, halogen-free, shielded, 3 m | DOL-0J08-G3M0AA6 | 2048591 |
| | Head A: female connector, JST, 8-pin, straight Head B: male connector, M23, 12-pin, straight Cable: Incremental, PUR, halogen-free, shielded, 1 m | STL-2312-G01MAA3 | 2061622 |
| | Head A: female connector, JST, 8-pin, straight Head B: male connector, M23, 12-pin, straight Cable: Incremental, PUR, halogen-free, shielded, 2 m | STL-2312-G02MAA3 | 2061504 |
| | Head A: female connector, JST, 8-pin, straight Head B: male connector, M23, 12-pin, straight Cable: Incremental, PUR, halogen-free, shielded, 0.35 m | STL-2312-GM35AA3 | 2061621 |
|  | Head A: male connector, M12, 8-pin, straight, A-coded Cable: Incremental, shielded | STE-1208-GA01 | 6044892 |
|   | Head A: male connector, M23, 12-pin, straight Cable: HIPERFACE [®] , SSI, Incremental, shielded | STE-2312-G01 | 2077273 |
| | | STE-2312-GX | 6028548 |

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Comprehensive services complete our offering: SICK LifeTime Services provide support throughout the machine life cycle and ensure safety and productivity.

For us, that is “Sensor Intelligence.”

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